

**! Caution**

- Do not use the unit over the rated current, otherwise the unit may be damaged.
- Please wire the cable in the shortest path to avoid noise.
- Make sure that the unit is turned off when you wire, connect or disconnect the connector, otherwise the unit may be damaged.
- Do not drop or hit, otherwise the unit may be damaged.
- Do not tug the cable while connecting the cable, otherwise the unit may be damaged.

**■ Unit items**

Please check all items are included in the package (See the below table).

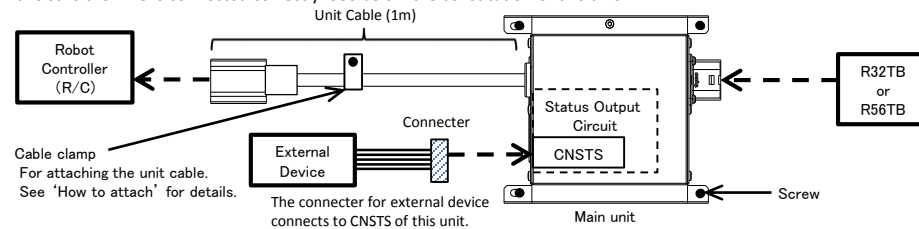
| Item                | Qty. | Remarks   |
|---------------------|------|---|
| 2F-TBSTS-01         | 1    | Main unit   |
| Connector           | 1    | For connecting to external device   |
| Cable clamp         | 1    | For unit cable  |
| Screw               | 5    | For attaching unit (4 pieces), For attaching cable clamp (1piece)                                   |
| Manual              | 1    | This document   |
| Dummy Plug (2D-DP1) | 1    | Connect when T/B is not used. (If you use this unit, it is also required for the CR800 controller.) |

**■ Introduction**

This manual describes the 2F-TBSTS-01 in detail. Teaching pendant Switch Status Output Unit(2F-TBSTS-01) is the unit for outputting the status of the switch on T/B(R32TB, R56TB), such as emergency stop, to external device.

**■ Configuration**

This unit is connected between Robot controller and T/B. Please wire the connector to external equipment yourself. Please make sure the wire is connected correctly. See below the constitution of this unit.



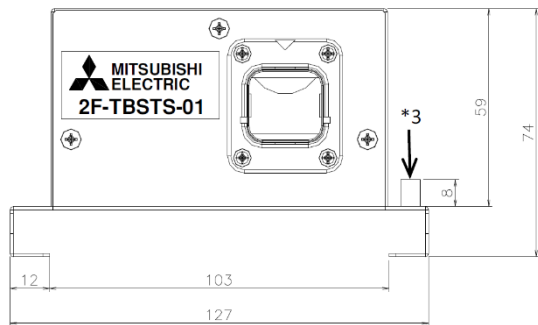
**■ Specification**

| Item                       | Content   | Remarks  |
|----------------------------|---|--|
| Model name                 | 2F-TBSTS-01   |  |
| Supported robot            | RH-F series, RV-F series<br>RH-FR series, RV-FR series<br>RV-CR series, RH-CRH series<br>RV-AS series   |  |
| Supported robot controller | CR750/CR800*1   | Not supported CR751<br>*1 T/B at the time of use of this unit, it is not possible to attach and detach at the time of AUTO mode. |
| Supported T/B              | R32TB, R56TB  | T/B: Teaching Pendant  |
| Cable                      | Type: Cable with shield<br>Conductor size: 0.14~1.5mm <sup>2</sup><br>(AWG28~16)<br>Cable length: Max.10m   | For connecting to the external device.<br>Not included.<br>Please see "Wiring directions" for details.                           |
| Output status              | 1. ON/OFF status of [Emergency stop] switch (channel 1, channel 2)<br>2. ON/OFF status of [Enable] switch (channel 1, channel 2)<br>3. ON/OFF status of [Enable/Disable] switch | Please see "CNSTS connector", "Status output circuit diagram", "Details of circuit operation" for details.                       |
| Maximum current            | 0.2A  | Each status output pin of CNSTS connector<br>Rated current: 0.1A   |
| Protection specification   | IP20  |  |
| Environment                | General environment   | Without inflammable gas or corrosive gas   |
| Ambient temperature        | 0~40°C  |  |
| Ambient humidity           | 45~85%  | Without dew drops  |
| Mass                       | Approx. 1kg   | Unit cable included  |

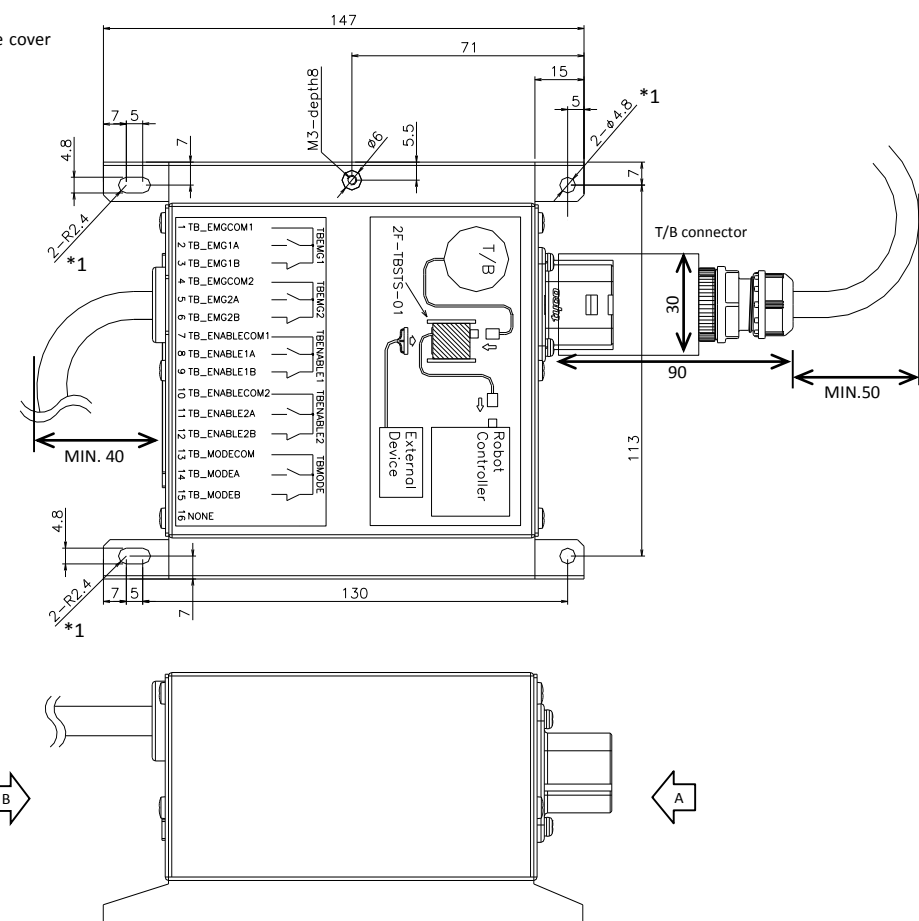
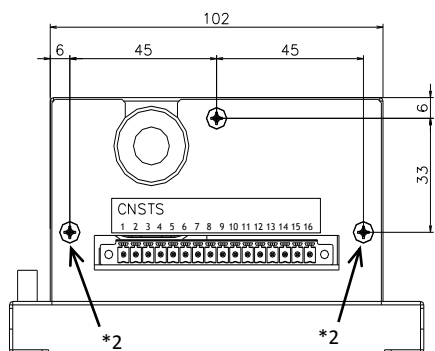
**■ External View**

- \*1: Holes to attach this unit
- \*2: Use when attach ESD countermeasure cover
- \*3: FG terminal

Front view (View from A)



Rear View (View from B) Unit Cable: Hidden



**■ How to attach**

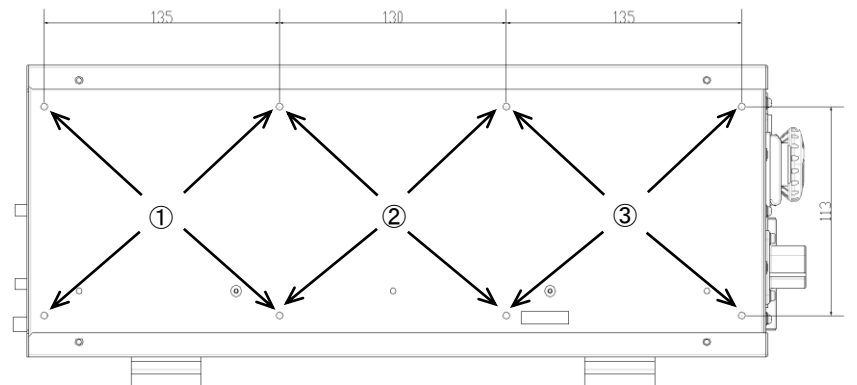
Please attach this unit with M4 screw in the holes provided (\*1 holes in external view). Please use cable clamp for arranging unit cable.

(Case to attach on the side of CR750 controller)

There are 8 holes for M4 screw on the side of the controller (See the side view of robot controller). Please attach it to ①, ②, or ③. Be careful not to interface with surrounding components. The diagram to attach this unit on the side of robot controller is below. Make sure the screw type is correct before attaching.

Screw type

M4 screw length :8mm (4 screws included) NOTE: If the screw type is not correct, the robot controller may be damaged. Tightening torque : 1.5N·m



The side view of CR750 controller

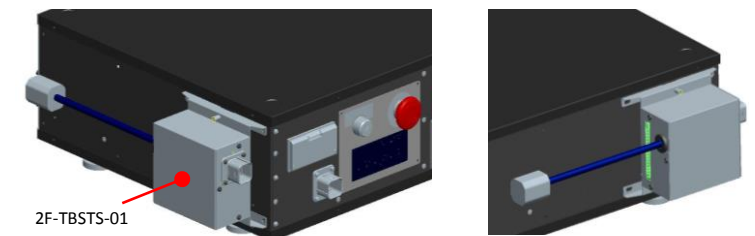


Figure of the diagram to attach the unit

## ■ CNSTS connector

Caution 1: Do not connect the connector for external device to CNUSR connector of CR750 controller.  
2: Take measures for chattering. There are relays in this unit.

You can get the status of three types of T/B switch status from pin status of the CNSTS connector. Here is the details of CNSTS connector. The switch statuses you can get are below.

1. [Emergency stop] switch status (on/off)
2. [Enable] switch status (on/off)
3. [Enable/Disable] switch status (on/off)

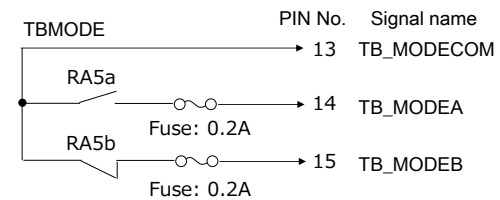
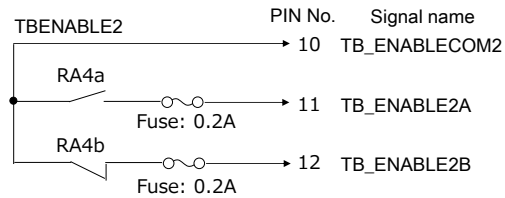
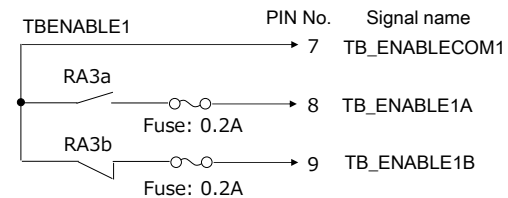
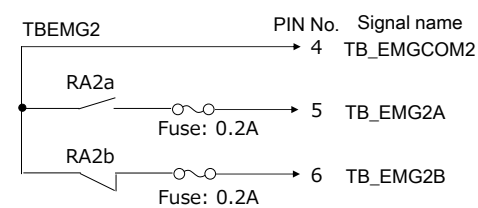
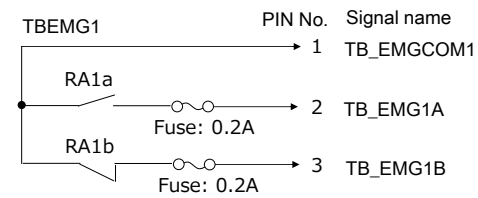
Table 1 shows the pin no., signal name, and the details. Please see “Status output circuit diagram” in this manual for circuit diagrams.

Table 1. Pin assignment

| Circuit name | Pin no. | Signal name   | Signal details   |
|--------------|---------|---------------|--|
| TBEMG1       | 1       | TB_EMGCOM1    | COMMON   |
|              | 2       | TB_EMG1A      | Output of [Emergency stop] switch channel 1 status (on / off). |
|              | 3       | TB_EMG1B      | Signal for relay fault detection.                              |
| TBEMG2       | 4       | TB_EMGCOM2    | COMMON   |
|              | 5       | TB_EMG2A      | Output of [Emergency stop] switch channel 2 status (on / off). |
|              | 6       | TB_EMG2B      | Signal for relay fault detection.                              |
| TBENABLE1    | 7       | TB_ENABLECOM1 | COMMON   |
|              | 8       | TB_ENABLE1A   | Output of [Enable] switch channel 1 status (on / off).         |
|              | 9       | TB_ENABLE1B   | Signal for relay fault detection.                              |
| TBENABLE2    | 10      | TB_ENABLECOM2 | COMMON   |
|              | 11      | TB_ENABLE2A   | Output of [Enable] switch channel 2 status (on / off).         |
|              | 12      | TB_ENABLE2B   | Signal for relay fault detection.                              |
| TBMODE       | 13      | TB_MODECOM    | COMMON   |
|              | 14      | TB_MODEA      | Output of Enable/Disable] switch status (on / off).            |
|              | 15      | TB_MODEB      | Signal for relay fault detection.                              |
|              | 16      |               | No connection  |

## ■ Status output circuit diagram

Schematic diagrams of status output circuits are below.  
The fuses in the circuit are resettable fuse.  
The maximum current of the each pin is 0.2A



## ■ Details of circuit operation

See below for details.

TBEMG1(channel 1), TBEMG2(channel2)

| T/B switch status                                  | Relay status |       | Status of the inside circuit |
|--|--------------|-------|------------------------------|
| [Emergency stop] switch off                        | RA1a         | CLOSE | 1[4] TB_EMGCOM1[2]           |
|  | RA1b         | OPEN  | 2[5] TB_EMG1A[2A]            |
|  | RA2a         | CLOSE | NC — 3[6] TB_EMG1B[2B]       |
|  | RA2b         | OPEN  |                              |
| [Emergency stop] switch on (emergency stop enable) | RA1a         | OPEN  | 1[4] TB_EMGCOM1[2]           |
|  | RA1b         | CLOSE | NC — 2[5] TB_EMG1A[2A]       |
|  | RA2a         | OPEN  |                              |
|  | RA2b         | CLOSE | 3[6] TB_EMG1B[2B]            |

TBENABLE1(channel1), TBENABLE2(channel2)

| T/B switch status  | Relay status |       | Status of the inside circuit |
|--|--------------|-------|------------------------------|
| [Enable] switch off (not push switch / push switch strongly) | RA3a         | OPEN  | 7[10] TB_ENABLECOM1[2]       |
|  | RA3b         | CLOSE | NC — 8[11] TB_ENABLE1A[2A]   |
|  | RA4a         | OPEN  |                              |
|  | RA4b         | CLOSE | 9[12] TB_ENABLE1B[2B]        |
| [Enable] switch on (push switch)                             | RA3a         | CLOSE | 7[10] TB_ENABLECOM1[2]       |
|  | RA3b         | OPEN  | NC — 8[11] TB_ENABLE1A[2A]   |
|  | RA4a         | CLOSE |                              |
|  | RA4b         | OPEN  | 9[12] TB_ENABLE1B[2B]        |

TBMODE

| T/B switch status                           | Relay status |       | Status of the inside circuit |
|---|--------------|-------|------------------------------|
| [ENABLE/DISABLE] switch off / (T/B disable) | RA5a         | OPEN  | 13 TB_MODECOM                |
|   | RA5b         | CLOSE | 14 TB_MODEA                  |
| [ENABLE/DISABLE] switch on / (T/B enable)   | RA5a         | CLOSE | 13 TB_MODECOM                |
|   | RA5b         | OPEN  | 14 TB_MODEA                  |
|   |              |       | 15 TB_MODEB                  |

## ■ Wiring directions

### 1. Tools required (not included)

DIN standard flathead screwdriver (blade thickness:0.4mm blade width:2.5mm)  
Recommended tool: SZS 0-0.4x2.5 (PHOENIX CONTACT), SZF 0-0.4x2.5(PHOENIX CONTACT)

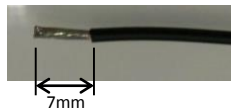


### 2. Cable (not included)

Solid cable / stranded cable :0.14~1.5mm<sup>2</sup> (AWG28~16)  
Stranded with ferrules without plastic sleeve :0.25~1.5mm<sup>2</sup>  
Stranded with ferrules with plastic sleeve :0.25~0.5mm<sup>2</sup>

### 3. Wiring procedure

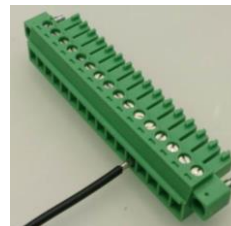
#### (1) Stripe cable(length: 7mm)



#### (2) Loosen the screw



#### (3) Insert the cable to the connection hole



#### (4) Tighten the screw



## ■ Measures against noise / static electricity

### 1. Measures against noise

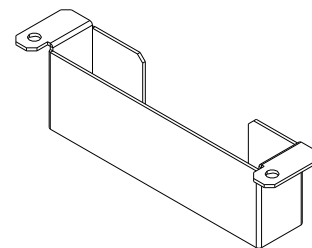
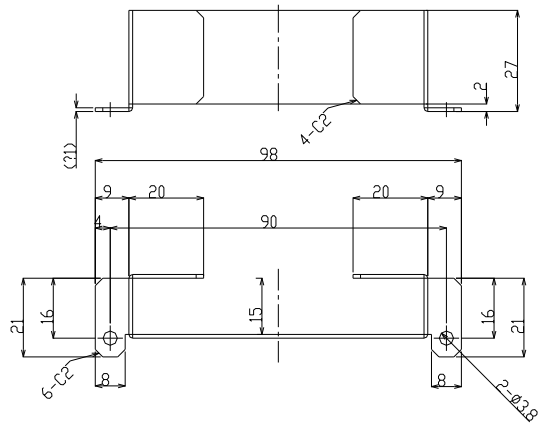
If there are problems due to noise, please connect this unit to ground using \*3 screw hole in outline drawings. Screw and cable are not included.

Screw type : M3  
Screw length : 6mm  
Tightening torque : 0.63N·m

### 2. Measures against static electricity

If there are problems due to static electricity, please connect this unit to ground (see “Measures against noise”) and attach cover. Below figure is an example of the cover. Please \*2 screws in the outline diagram when you attach the cover.

Tightening torque : 0.63N·m



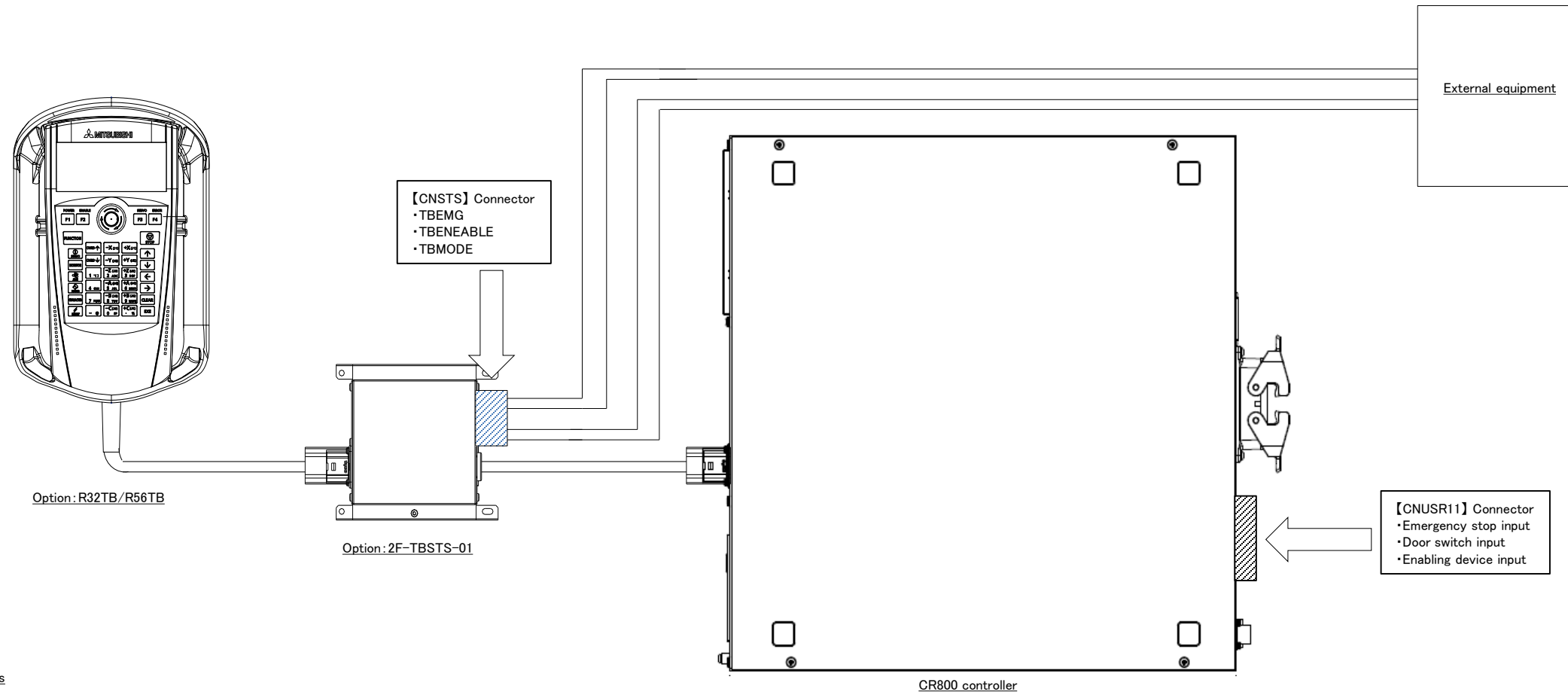
Recommend material: Steel

## ■ Troubleshooting

| Trouble  | Cause        | Measures   |
|--|--------------|--|
| Different from “Details of circuit operation”. | wrong wiring | Please wire the cable properly in reference to “Details of circuit operation”.   |
|  | Relay fault  | Please contact service provider. The unit needs to be replaced. When the output status of the signal for relay fault detection (TB_EMG1B, TB_EMG2B, TB_ENABLE1B, TB_ENABLE2B, TB_MODEB) does not change in accordance with the output status of the signal for T/B switch (TB_EMG1A, TB_EMG2A, TB_ENABLE1A, TB_ENABLE2A, TB_MODEA), the relay is broken. |
|  | Over-current | Maximum current is 0.2 A. Please redesign the circuit configuration to reduce the current.   |

## Example of wiring

The C800 controller provides examples of wiring to monitor the status of the R32TB/R56TB emergency stop button. By monitoring the contacts of A and B of the relay output from the CNSTS connector, it is possible to detect the welding of the relay.



### Wiring details

