

# **RV-3S**

# **MELFA Industrial Robots**

# Fast, Compact and Easy to Use





Reduce your cycle time with the fastest Mitsubishi robot in it's class







No need to buy additional software functions as all are supplied with the robot as standard



Move through the point of singularity

# Robots from € 1.65/hr



Robots in a production line

Robots can be a very cost effective way to achieve some automation tasks. The image of a robot as being an expensive luxury is far from the reality. When the cost of a robot is calculated over it's expected lifetime, typically 6-7 years in a general application, it can provide surprising results with costs as low as  $\leqslant$  1.65/hr to purchase and operate.

# Using Mitsubishi robots is easy

Programming a Mitsubishi robot arm, such as the RV-3S, is a lot easier than most people imagine. The programming language of the teach pendent is a simple sentence like structure with commands such a MOV being used to program the robot to move.

Alternatively, users can also benefit from our advanced programming and simulation software packages Cosirop and Cosimir. These two packages can allow a robot application to be built and simulated even before any hardware has been purchased.

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Screenshot Cosimir software

# **Simple integration**

The RV-3S series of robots have been designed to be very simple to integrate into an existing automation cell. Features such as the direct control over 32 local I/Os allows the robot to interact directly with sensors and actuators, speeding up and simplifying system building.

Communicating with other automation plant is an important area of any automation cell. The RV-3S series has been optimised with a choice of three major networking technologies: Ethernet, Profibus/DP and CC-Link.

For complex automation cells where movement is restricted, or there is a large distance between working points, the RV-3S robots can control up to eight additional axes to its standard robot arm configuration. Two of these axis can be interpolated allowing easy and efficient movement around obstructions. The other six axes can be used to control elements such as linear slides to move the robot between work stations.

# **Advanced design**

The RV-3S series has many advanced design features giving users greater and more flexible automation solutions. For example, the IP65 rating means the robot can now not only be located at the machine or workstation but actually IN the machine! This can be of benefit in applications such as cutting machine tools where there can be a lot of cutting liquids.

All Mitsubishi robot controllers are shipped with the full control software as standard, this means that users do not need to buy any additional software modules for special tasks at a later date. In addition Mitsubishi MELFA robot programs are compatible making it easier to upgrade between robots should the need arise.



RV-3S inside an EDM

# New features of the RV-3S series

### ■ Fastest in its class

RV-3S robots are up to 57 % faster than previous Mitsubishi robots in the same class. The maximum travel speed of 5.5 m/s can still be used with a positioning repeatability of  $\pm 0.02$  mm making users cycle times faster without loosing accuracy.

## ■ Move through singularity

Typically robots will stop at an undefined point when the robot arm moves through the point of singularity. However, the new RV-3S series will continue its travel to its final position providing customers with trouble free operation.

### ■ Brakes in all axes

Many robots will have brakes fitted to the major axes but the RV-3S has brakes on all axes. This means the robot will maintain position, protecting the application, even during a power down or emergency situation.

Further more the robots absolute encoders mean that the real position is always known without having to redatum at a special location.

## **■** Operational tolerance

This feature allows the robot arm to be guided into a work piece by external forces, for example, if a hole in the work piece has a certain tolerance on position

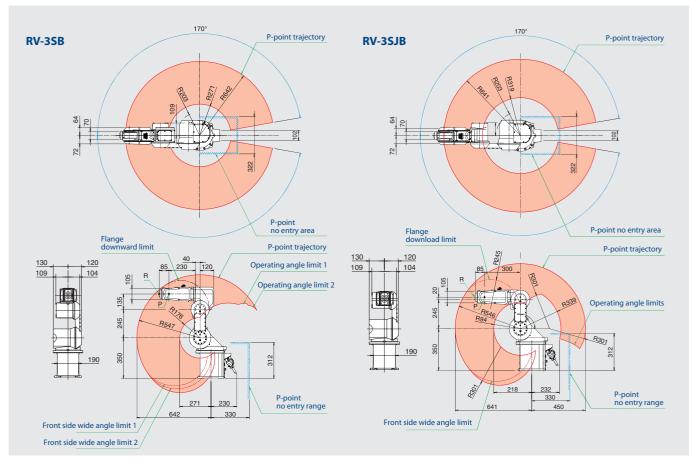
then the robot arm can allow the edges of the hole to guide the robot gripper into the exact location. This ensures 100 % accurate positioning even if the work piece varies.

### **■** Collision detection

This provides protection for the whole automation investment, sensing and reacting quickly when a crash has occurred.



Vertical articulated robots RV-3SB/RV-3SJB and controller CR2B



# **Specifications** ///

Robot		RV-3SB	RV-3SJB	
Number of axe	es	6	5	
Installation po	sition	Floor mount wall hanging		
Construction t	:ype	Vertical artic	Vertical articulated robot	
Max./rated pay	yload capacity (kg)	3.5 / 3	3.5 / 3	
Position repea	tability (mm)	±0.02	±0.02	
Maximum con	nposite speed (mm/s)	5,500	5,300	
Controller		CR2B	CR2B	
	waist (J1)	340	340	
	shoulder (J2)	225	225	
Operating range	elbow (J3)	191	237	
(degree)	wrist twist (J4)	320	_	
	wrist pitch (J5)	240	240	
	wrist roll (J6)	720	720	
	waist (J1)	250	250	
	shoulder (J2)	187	187	
Maximum speed (degree/s)	elbow (J3)	250	250	
	wrist twist (J4)	412	_	
	wrist pitch (J5)	412	412	
	wrist roll (J6) 660 66	660		
Tolerable	wrist twist (J4) 5.83 —	_		
moment (Nm)	wrist pitch (J5)	5.84	5.84	
	wrist roll (J6)	3.9	3.9	
Tolerable	e wrist twist (J4) 0.137 —	_		
inertia	wrist pitch (J5)	0.137	0.137	
(kgm²)	wrist roll (J6)	0.047	0.047	
Tool pneumatic pipes		ø6 x 2 (primary), ø4 x 8 (secondary as option)		
Pneumatic pre	eassure supply (N/cm²)	0.5 ±10 %		
Roboter weight (kg)		37	33	
Protection /		IP65 / class 1	0**	

Number of axes	controlled	Up to 6 axes simultaneously	
Processor (CPU)		64 Bit RISC + DSP	
Control functions		Palletizing and multi-tasking, optimum acceleration/deceleration control, optimum override control, optimum path connection function, torque limit command, XYZ compliance control, collision detection function	
Programming language		MELFA-Basic IV	
Positioning teaching method		Teaching Box, MDI	
Max. number of programs		88	
Max. number of teaching points		2,500 per program	
Max. number of program steps		5,000 per program	
	general purpose	32 inputs/32 outputs (expandable up to 256 I/Os)	
Number of inputs/outputs	dedicated	User defined	
	for hand open/close	8 inputs/0 outputs (up to 8 hand output signals ca be optionally added)	
Saftey functions	;	Emergency stop and door switch input	
	RS-232C	1 (for a PC, etc.)	
	RS-422	1 (for a teaching unit)	
Interface/	slot for hand	1 (for a pneumatic hand interface)	
extensions	extension slot	3 (for extension options)	
	memory	1 (for an optional memory cassette)	
	I/O link	1 (for a parallel I/O unit)	
Ambient	temperature	0 – 40 °C	
conditions	humidity	45 – 85 % RH	
Power supply		180 – 253 V AC; single phase	
Power capacity		2.0 kVA	
Dimensions (Bx	HxT in mm)	460 x 200 x 400	
Weight		35 kg	

CR2B PTP and CP

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Controller

Control method

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<sup>\*</sup> Wall hanging model with limited range in J1
\*\* Special type