



Mitsubishi Electric AC Servo System MELSEC iQ-R Series Motion Module RD78G Simple Motion Mode

e F@ctory



Taking evolution to the next step with Simple Motion mode

GLOBAL IMPACT OF MITSUBISHI ELECTRIC



Through Mitsubishi Electric's vision, "Changes for the Better" are possible for a brighter future.

Changes for the Better

"Changes for the Better" represents the Mitsubishi Electric Group's attitude to "always strive to achieve something better", as we continue to change and grow. Each one of us shares a strong will and passion to continuously aim for change, reinforcing our commitment to creating "an even better tomorrow".

Mitsubishi Electric is involved in many areas including the following:

Energy and Electric Systems

A wide range of power and electrical products from generators to large-scale displays.

Electronic Devices

A wide portfolio of cutting-edge semiconductor devices for systems and products.

Home Appliance

Dependable consumer products like air conditioners and home entertainment systems.

Information and Communication Systems

Commercial and consumer-centric equipment, products and systems.

Industrial Automation Systems

Maximizing productivity and efficiency with cutting-edge automation technology.



Our advances in AI and IoT are adding new value to society in diverse areas from automation to information systems. The creation of game-changing solutions is helping to transform the world, which is why we are honored to be recognized in the 2019 "Forbes Digital 100" as one of world's most influential digital corporations.





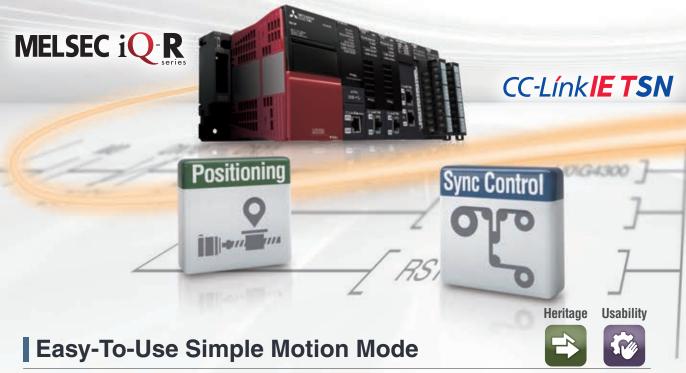
Maximize system performance



OVERVIEW

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Taking evolution to the next step with Simple Motion mode

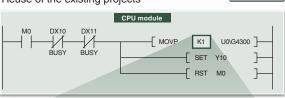


The Simple Motion mode is an easy-to-use function that provides the same usability as the previous models (Simple Motion module RD77MS/QD77MS) when RD78G Motion module is used with MR-J5-G servo amplifier. By selecting the Simple Motion mode on GX Works3, positioning control and synchronous control can be easily executed.

Positioning

[Motion profile table]

- Motion profile table (Same as the Simple Motion module's)
- Reuse of the existing projects

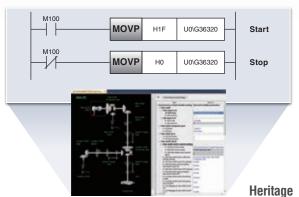


: CONT	0Bh:				
CONT	INC Linear 2	0: 1000	0: 1000	200000.0 μm	20000.0 mm/min
: END	0Bh: INC Linear 2	0: 1000	0: 1000	-200000.0 μm	10000.0 mm/min
	END	END 0Bh:	END OBh: INC Linear 2 0: 1000	END 0Bh: 0: 1000 0: 1000	END 0Bh: 0: 1000 0: 1000 -200000.0

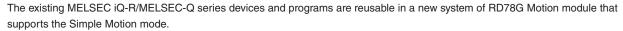
[Synchronous control parameters]

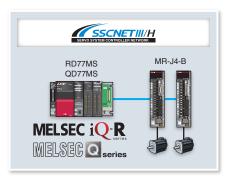
 Easy synchronous control by setting parameters and turning ON a start signal.

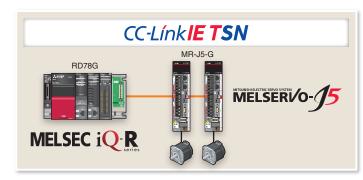




Utilization of Existing Programs









Progressiveness



Improved Performance

- [Compatible with the open integrated network CC-Link IETSN]
- Connects up to 121 stations (including the master station)
 Supports line, start, and line/start mixed topologies
- Connects servo amplifiers and remote I/O modules
- Connects TCP/IP devices (sensors, vision system sensors)
- Synchronizes time among multiple modules





Progressiveness Maintainability

Connecting A High-Performance Servo Amplifier MR-J5-G





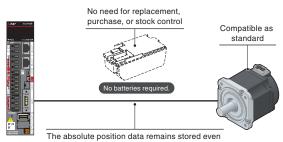
RD78G connects MR-J5-G servo amplifier via CC-Link IE TSN and enables high-speed, high-precision motion control.

- Command communication cycle of ≥ 31.25 µs and speed frequency response of 3.5 kHz enable advanced motion control.
- With use of Maisart, Mitsubishi Electric's AI technology, the servo amplifier monitors age-related deterioration of ball screws, belts, and gears.

The servo amplifier detects signs of failure and outputs a warning, which prevents downtime of machines due to a sudden failure.

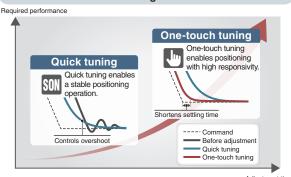
- The HK series rotary servo motors are equipped with a batteryless absolute position encoder as standard, reducing maintenance cost.
- Various servo tuning features, such as quick tuning and one-touch tuning, are available.

Batteryless absolute position encoder as standard



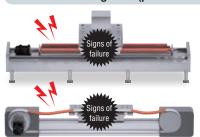
when the servo motors are removed.

Servo tuning function



Adjustment time

Machine diagnosis (predictive maintenance)





The servo amplifiers detect signs of machine failure by monitoring the operation status.

Maisart is Mitsubishi Electric's brand of Al technology. The name stands for "Mitsubishi Electric's Al creates the State-of-the-ART in technology." This means that we are using our proprietary Al technology to make everything smarter.



Combined with a CC-Link IE TSN-compatible servo amplifier, the Motion modules create a high-performance servo system that improves machine capability.

- Executes positioning control with the motion profile table and synchronous control with parameter settings
- Connects remote I/O modules and FR-A800-GN inverters via CC-Link IE TSN. The data of these devices can be read/written by a CPU module.
- Enables safety communication when RD78G is combined with a safety CPU and MR-J5-G-RJ
- Eliminates the redundant wiring required for functional safety, contributing to reduced wiring
- Possible to reuse existing projects of a Simple Motion module for driving MR-J5-G servo amplifier

Product Lines



MELSEC iQ R **RD78G4 RD78G8 RD78G16**

- Maximum number of control axes: 16 axes/module (RD78G16)
- Minimum operation cycle*1: 250 [µs]
- Compatible servo amplifiers

MR-J5-G MR-J5D-G4



MELSEC iQ-F

FX5-40SSC-G NEW



- FX5-80SSC-G
- 4 axes/module (FX5-40SSC-G), 8 axes/module (FX5-80SSC-G)
- Minimum operation cycle^{*1}: 500 [µs]

Maximum number of control axes:

- Maximum number of connected modules*2: 4 modules/system
- Compatible servo amplifiers*3 MR-J5-G
- The operation cycle varies by the number of control axes and the models.
- *2. This refers to the total number of the Motion modules and one FX5-CCLGN-MS (master station).
- *3. MR-J5D-G4 is planned for a future support.

Firmware of RD78G Motion Module

The Simple Motion mode is supported by RD78G with firmware version 16 or later. To obtain the firmware update files, contact your local sales office.



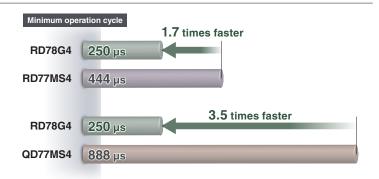


Simple Motion mode

RD78G Motion module firmware version 16 or later

Improved Performance

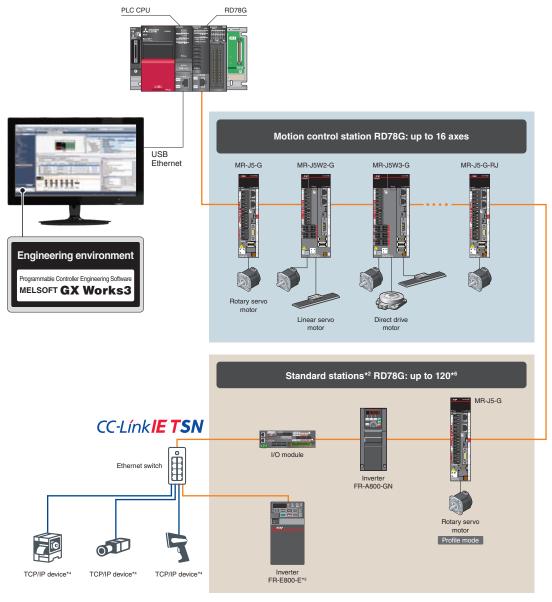
The minimum operation cycle of RD78G in Simple Motion mode is 1.7 to 3.5 times faster than that of the previous models. The data from the servo amplifiers and input/output signals can be received at high speeds, which reduces the cycle time.



System Configuration

The Motion module can function as a master station of CC-Link IE TSN.*1

This feature enables users to create a system more flexibly by connecting various devices, such as servo amplifiers, remote I/O modules, and TCP/IP devices, to the Motion module.*5

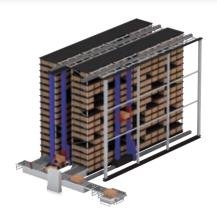


- *1. The Motion modules are not provided with the following functions: sub-master station, local station, multi-master configuration, and backup/restore function.
- *2. Standard stations refer to slave stations other than motion control stations on CC-Link IE TSN.
- *3. When connecting FR-E800-E to RD78G, set the communication speed of CC-Link IE TSN to 100 Mbps.
- *4. TCP/IP devices are not included in the standard stations.
- *5. When Class B and A devices are mixed in the same system, up to eight Class B devices can be connected. Refer to manuals for precautions when Class B and A devices are mixed.
- *6. RD78G can connect up to 120 devices, which is the total number of the motion control stations and standard stations.

Positioning Control

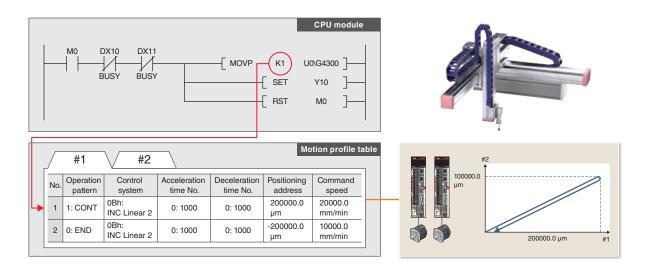
Positioning control is easily executed using a motion profile table.

- To meet various application needs, the Motion module offers various types of positioning control, such as linear interpolation, 2-axis circular interpolation, fixedpitch feed, and continuous path control.
- An automatic operation can be executed easily by setting the positioning address, the speed, and other setting items in a sequence program.
- Powerful sub-functions, such as M-code output, skip, speed change, and target position change functions, are available.



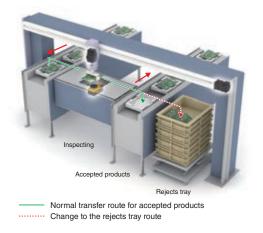
Programming

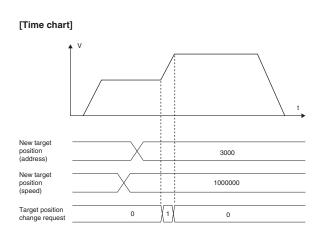
The Motion module easily executes positioning operation with the instruction in a sequence program that starts a positioning data of the motion profile table. To meet various application needs, the Motion module offers various types of control, such as linear interpolation, two-axis circular interpolation, fixed-pitch feed, and continuous path control.



Target Position Change Function

The target position can be changed at any time even when the products are being moved (1-axis linear control). The product is examined with the vision system while being moved to the next line. If a faulty product is found, the target position is changed so that the faulty product is put in a separate tray for those rejected.

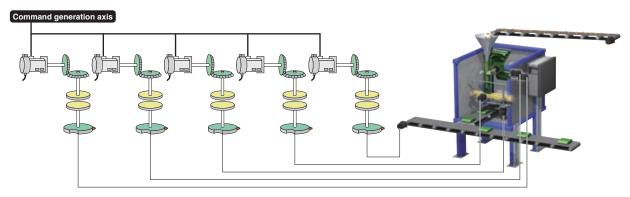




Synchronous Control

Synchronous control can be achieved using software instead of controlling mechanically with gear, shaft, clutch, speed change gear or cam, etc.

- Synchronous control can be flexibly started/ended for each axis, enabling the synchronous control axis and positioning control axis to be used within the same program.
- Command generation axis, servo input axis, or synchronous encoder axis can be set as the input axis.
- The output axis is operated with a cam. The following three operations can be performed with the cam functions: linear operation, two-way operation, and feed operation.
- An incremental synchronous encoder*1 can be connected via MR-J5-G(-RJ)/MR-J5W2-G servo amplifier.



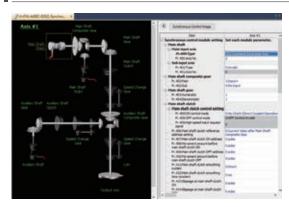
*1. When configuring an absolute position system, use an encoder of HK series servo motors.

[Command generation axis]

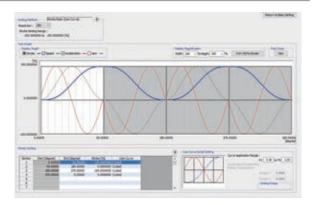
Command generation axis is the axis that performs only the command generation.

It is controlled independently of other axes connected to servo amplifiers. (not counted as a control axis)

Parameter Settings



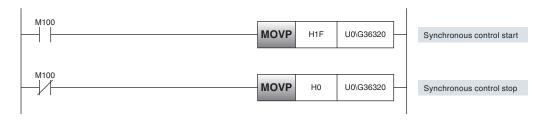
Synchronous control is executed by setting parameters of the input axis, output axis, gear, and clutch for synchronous control and turning on the synchronous control start signal.



The cam graph can be flexibly and easily created through drag & drop. The waveform is changed according to the pointer's movement.

Start/Stop

Synchronous control can be executed after synchronous parameters are set for each output axis. When synchronous control start signal is turned on, the synchronous control parameters are analyzed, and the status is changed to during synchronous control. The output axis is operated by the commands transmitted from the input axis.

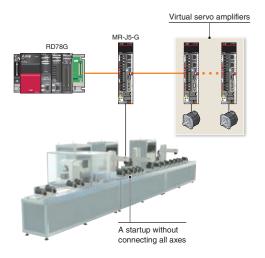


Auxiliary Functions

Virtual Servo Amplifier

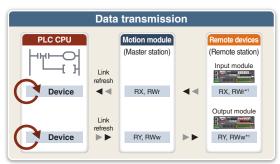
The virtual servo amplifier function enables operations of a virtual servo amplifier as if an actual unit is connected. When the virtual servo amplifier is set as a servo input axis of synchronous control, the Motion module executes synchronous control with virtually generated input commands.

In addition, this function is used to simulate an axis without an actual connection.

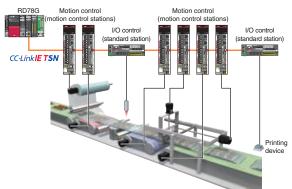


Read/Write Operation of Standard Stations

- The PLC CPU sends/receives link devices to/from standard stations (remote stations other than the motion control stations) through a Motion module.
- One-to-one communication is possible between the master and remote stations.
- The PLC CPU can be programmed using the signals of the remote stations.



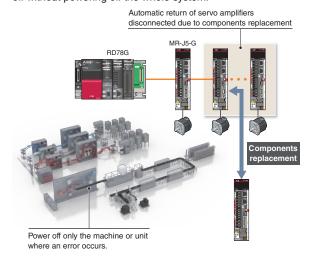
*1. RX and RY are not available for some remote devices



Automatic Return

When slave stations are back to normal status after disconnected due to a data link error, this function automatically returns the disconnected stations to the network and restarts data link.

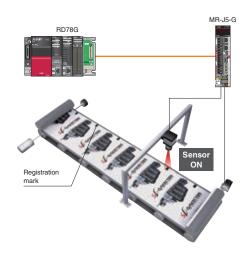
When defective components need to be replaced in one of the machines in a production line or one of the units in a machine, only the machine or the unit can be partly turned off without powering off the whole system.



Mark Detection

This function latches data responding to a trigger signal input to a servo amplifier.

The compensation amount is calculated based on the latched data, and the error is compensated using a compensation axis.



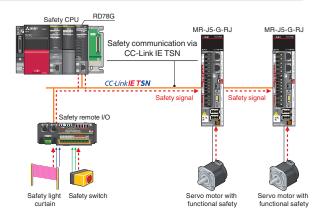
Benefits of Migration to RD78G (Simple Motion Mode)

When migrating to RD78G (Simple Motion mode) from the previous models, the new controller offers improved performance and the ability to connect various devices, such as MELSEC iQ-R series PLC CPUs, the high-performance servo amplifiers, and remote devices via CC-Link IE TSN. The capabilities and improved features of these connected devices can be utilized in the new system.

Servo Amplifier Features

CC-Link IE TSN safety communication function

- RD78G enables safety communication when combined with a safety CPU and MR-J5-G-RJ.
- Wiring the safety signals to the servo amplifiers is not necessary.



Safety sub-functions of servo amplifier

- MR-J5-G-RJ supports safety sub-functions*1, STO/SS1/SS2/SOS/SBC/SLS/SSM/SDI/SLI/SLT.
- The functional safety encoders provide the servo motor positions and speeds necessary for the safety sub-functions at a safety level of Category 4 PL e, SIL 3.

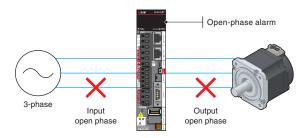
	Servo amplifier		MR-J5-G-RJ						
Servo motor			n functional safety _WS)	Rotary servo motor (HK series), linear servo motor (LM series), direct drive motor (TM series)					
Functional safety category (IEC/EN 61800-5-2)		Cat. 4 PL e, SIL 3	Cat. 3 PL d, SIL 2	Cat. 4 PL e, SIL 3	Cat. 3 PL d, SIL 2				
STO	Safe torque off	•	-	•	-				
SS1-t	Safe stop 1, time controlled	•	-	•	-				
SS1-r *2	Safe stop 1, ramp monitored	•	_	_	•				
SS2-t *2	Safe stop 2, time controlled	•	-	_	-				
SS2-r *2	Safe stop 2, ramp monitored	monitored -	-	-	-				
SOS *2	Safe operating stop	•	-	-	-				
SBC	Safe brake control	•	_	•	-				
SLS *2	Safely-limited speed	•	-	-	•				
SSM *2	Safe speed monitor	•	-	-	•				
SDI *2	Safe direction	•	_	_	•				
SLI *2	Safely-limited increment	•	-	-	-				
SLT	Safely-limited torque	-	•	-	•				

^{*1.} There are some restrictions on the functional safety. Refer to "Safety Sub-Functions" in section 1 of "MELSERVO-J5 catalog (L(NA)03179ENG)" for details.
*2. A fully closed loop system does not support SS1-r, SS2, SOS, SLS, SSM, SDI, and SLI.

Servo Amplifier Features

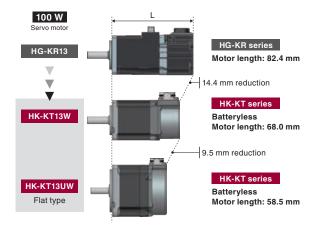
Disconnection detection

The servo amplifiers are equipped with both input openphase detection and output open-phase detection. Input openphase detection detects an open phase of the main circuit power supply of the servo amplifier, and output open-phase detection detects an open phase of the servo motor power supply. The alarm can be distinguished from other alarms such as the overload alarm, reducing the time required to restore the system. MR-J5D-G4 drive units support only output openphase detection.



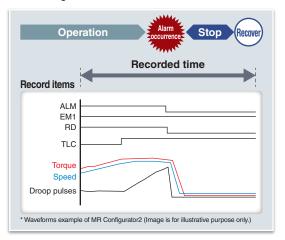
Compact servo motors with a batteryless absolute position encoder

HK-KT series servo motors come equipped with a batteryless absolute position encoder and are more compact than the previous generation HG-KR series. Flat types are also available in the HK-KT product line, contributing to a compact machine design.



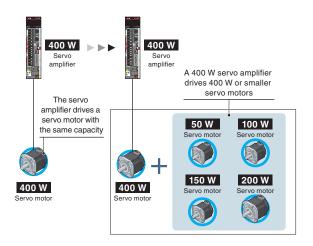
Drive recorder of servo amplifier

The Motion module collects data from the drive recorder of MR-J5-G through TCP/IP communications, which reduces troubleshooting time.



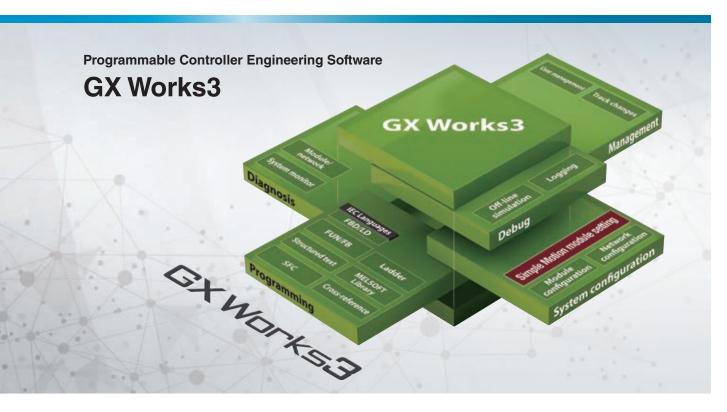
Drives smaller capacity servo motors

Servo amplifiers are able to drive servo motors with a smaller capacity than the servo amplifier being used, reducing the kinds of spare parts that are needed.



MEMO

One software, many possibilities



MELSOFT GX Works3 has a variety of features which help users create projects and conduct maintenance more flexibly and easily. Our variety of engineering software (GX Works3, sizing software, and model selection software, etc.) fully covers all stages of development processes from parameter settings to maintenance of Motion module, servo amplifier, and servo motors.

GX Works3

This software supports overall development processes for PLC CPUs from system design to maintenance.

Servo Setup Software MR Configurator2

Tuning, monitor display, diagnosis, reading/writing parameters, and test operations are easily performed on a personal computer. This powerful software tool supports a stable machine system and optimum control, and moreover, shortens setup time.

Model Selection Software

Servo amplifiers, servo motors, and indispensable options such as encoder cables can all be selected.

Simple Motion Module Setting

This software covers various development processes for the Motion module from parameter settings, debug, to maintenance.

Drive System Sizing Software "Motorizer"

The most suitable servo motors, servo amplifiers, and regenerative options for your machine can be selected just by setting machine specifications and operation patterns.

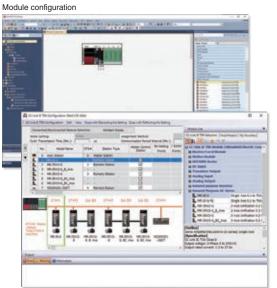


Engineering Environment

Our variety of engineering software (GX Works3, sizing software, model selection software, etc.) fully covers all stages of development processes from parameter settings to maintenance of Motion modules, servo amplifiers, and servo motors.

System Design





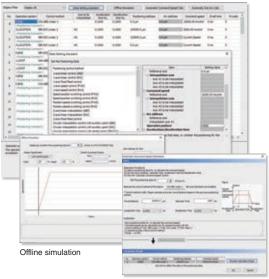
Network configuration

- Module configuration
- Network configuration
- Data settings for servo amplifiers
- Settings for remote I/O

Programming (Positioning)



Positioning data setting



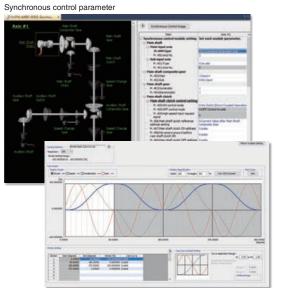
Automatic calculation of command speed

- Programming with Ladder, SFC, FBD/LD
- Positioning data settings
- Offline simulation, automatic calculation of command speed

Programming (Synchronous Control) Programming







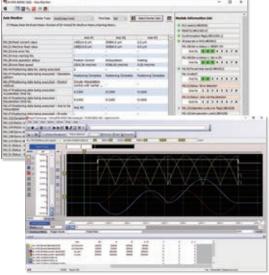
Cam data creation

- Synchronous control parameter
- Cam data creation, cam data list

Debug/Maintenance







Digital oscilloscope

- Event history
- Current value history, start history, axis monitor
- Servo monitor
- Digital oscilloscope

Motion Module (Simple Motion Mode)

Control specifications

Item	Specifications
	RD78G
Maximum number of control axes	4, 8, 16 axes
Operation cycle (operation cycle setting)	250, 500, 1000, 2000, 4000
Interpolation function	Linear interpolation (up to 4 axes), 2-axis circular interpolation, helical interpolation
Control method	Positioning control, path control (linear, arc, and helical), speed control, speed-torque control, synchronous control, continuous operation to torque control
Acceleration/deceleration process Compensation function	Trapezoidal acceleration/deceleration, S-curve acceleration/deceleration Backlash compensation, electronic gear, near pass function
Synchronous control	Synchronous encoder input, command generation axis, cam, phase compensation, cam auto-generation
	256 (depending on the memory capacity, cam resolution, and number of coordinates)
Cam control Cam data	Stroke ratio data format, coordinate data format
Cam auto-generation	Cam auto-generation for rotary knife
Positioning control method Control unit	Motion profile table
Control unit	mm, inch, degree, pulse
Number of positioning data	600 data (positioning data No. 1 to 600)/axis (Can be set with MELSOFT GX Works3 or a sequence program (No. 1 to 600).)
Backup	Parameters, positioning data, and block start data can be saved on flash ROM (batteryless backup)
Home position return	Driver home position return (Note 1)
Positioning control	Linear interpolation control (Up to 4 axes (Note 2) (vector speed, reference axis speed)), fixed-pitch feed control (up to 4 axes), 2-axis circular interpolation (auxiliary point-specified, central point-specified), helical interpolation control, speed control (up to 4 axes), speed-position switching control (INC mode, ABS mode), position-speed switching control (INC mode), current value change (positioning data, start No. for a current value changing) NOP instruction, JUMP instruction (conditional, unconditional), LOOP, LEND, high-level positioning control (block start, condition start, wait start, simultaneous start, repeated start)
Manual control	JOG operation, inching operation, manual pulse generator operation (up to 1 module (incremental) unit magnification (1 to 10000 times), via a CPU (buffer memory))
Speed-torque control	Speed control not including position loop, torque control, continuous operation to torque control
Absolute position system	Provided
Synchronous encoder operation function	Up to the number of axes of the connected servo amplifiers (via a CPU or a servo amplifier)
Speed limit	Speed limit value, JOG speed limit value
Torque limit function	Torque limit value same setting, torque limit value individual setting
Forced stop	Via buffer memory, valid/invalid setting
Software stroke limit function	Movable range check with feed current value or with machine feed value
Hardware stroke limit function	Provided
Speed change	Provided
Override [%	0 to 300
Acceleration/deceleration time change	Provided
Torque limit change	Provided
Target position change	Speed to a target position address and a target position is changeable.
M-code output function	WITH mode/AFTER mode
Other Step function	Deceleration unit step, data No. unit step
functions Skip function	Via a CPU or an external command signal
Parameter initialization function	Provided
External input signal select function	Via a CPU or a servo amplifier
Mark detection function	Continuous detection mode, specified number of detections mode, ring buffer mode
Mark detection signal	Up to the number of axes of the connected servo amplifiers
Mark detection setting	16 settings
Optional data monitor function	Up to 4 points/axis
Automatic return	Provided
Digital oscilloscope function	Bit data: 16 channels, word data: 16 channels (Note 3)

Notes: 1. The home position return method set in a driver (servo amplifier) is used.
2. 4-axis linear interpolation control is enabled only at the reference axis speed.
3. Eight channels of each word data and bit data can be displayed in real time.

Simple Motion module specifications (RD77MS/QD77MS)

: Items that differ from RD78G

Item		Specifications	ODZZNO	
		RD77MS	QD77MS	
	nber of control axes	2, 4, 8, 16 axes	2, 4, 16 axes (QD77MS2 and QD77MS4 use the buffer memory assignment for 4 axes)	
Operation cycle (operation cycle)		444, 888, 1777, 3555	888, 1777	
nterpolation fu	unction	Linear interpolation (up to 4 axes), 2-axis circular interpolation, helical interpolation	Linear interpolation (up to 4 axes), 2-axis circular interpolation	
Control method	d	Positioning control, path control (linear, arc, and synchronous control, continuous operation to tor	helical), speed control, speed-torque control,	
	eceleration process	Trapezoidal acceleration/deceleration, S-curve a	cceleration/deceleration	
Compensation	tunction	Backlash compensation, electronic gear, near pa		
Synchronous c		Synchronous encoder input, cam, phase compensation, cam auto-generation	Synchronous encoder input, command generatio axis, cam, phase compensation, cam auto-generation	
	Maximum number of cam registrations		solution, and number of coordinates)	
Cam control	Cam data	Stroke ratio data format, coordinate data format		
	Cam auto-generation	Cam auto-generation for rotary knife		
Positioning cor		Motion profile table		
Control unit		mm, inch, degree, pulse		
Number of pos	sitioning data	600 data (positioning data No. 1 to 600)/axis (Can be set with MELSOFT GX Works3 or a sequence program (No. 1 to 100))	600 data (positioning data No. 1 to 600)/axis (Can be set with MELSOFT GX Works2 or a sequence program (QD77MS16 (No. 1 to 100), QD77MS2/QD77MS4 (No. 1 to 600))	
Backup		Parameters, positioning data, and block start data (batteryless backup)		
Home position	return	Proximity dog method, count method 1, count method 2, data set method, scale home position signal detection method, driver home position return (Note 1)	Proximity dog method, count method 1, count method 2, data set method, scale home position signal detection method	
Positioning cor	ntrol	point-specified), helical interpolation control, spe switching control (INC mode, ABS mode), positionally value change (positioning data, start No. for a cunner NoP instruction, JUMP instruction (conditional, upositioning control (block start, condition start, w	on-speed switching control (INC mode), current irrent value changing) unconditional), LOOP, LEND, high-level ait start, simultaneous start, repeated start)	
Manual control	I	JOG operation, inching operation, manual pulse unit magnification (1 to 10000 times), via an inte		
On a a al 4 a u au	control	Speed control not including position loop, torque	control, continuous operation to torque control	
speea-torque (Supported when a battery is mounted on a serv	o amplifier	
	ion system			
Absolute positi	ion system encoder operation function	Up to 4 channels		
Absolute positi Synchronous e		Up to 4 channels Via an internal interface, a CPU (buffer memory	·	
Absolute positi Synchronous e Speed limit	encoder operation function	Up to 4 channels Via an internal interface, a CPU (buffer memory Speed limit value, JOG speed limit value	r), or a servo amplifier	
Absolute positi Synchronous e Speed limit Torque limit fur	encoder operation function	Up to 4 channels Via an internal interface, a CPU (buffer memory Speed limit value, JOG speed limit value Torque limit value same setting, torque limit value	r), or a servo amplifier e individual setting	
Absolute positi Synchronous e Speed limit Torque limit fur Forced stop	encoder operation function	Up to 4 channels Via an internal interface, a CPU (buffer memory Speed limit value, JOG speed limit value Torque limit value same setting, torque limit valu Via an internal interface or a buffer memory, va	e individual setting	
Absolute positi Bynchronous e Speed limit Forque limit fur Forced stop Software stroke	encoder operation function nction le limit function	Up to 4 channels Via an internal interface, a CPU (buffer memory Speed limit value, JOG speed limit value Torque limit value same setting, torque limit value Via an internal interface or a buffer memory, va Movable range check with feed current value or	r), or a servo amplifier e individual setting lid/invalid setting	
Absolute positi Synchronous e Speed limit Torque limit fur Forced stop Software stroke Hardware stroke	encoder operation function nction le limit function ke limit function	Up to 4 channels Via an internal interface, a CPU (buffer memory Speed limit value, JOG speed limit value Torque limit value same setting, torque limit valu Via an internal interface or a buffer memory, va Movable range check with feed current value or Provided	e individual setting	
Absolute positi Synchronous e Speed limit Torque limit fur Torced stop Software stroke Hardware stroke Speed change	encoder operation function nction le limit function ke limit function	Up to 4 channels Via an internal interface, a CPU (buffer memory Speed limit value, JOG speed limit value Torque limit value same setting, torque limit value Via an internal interface or a buffer memory, va Movable range check with feed current value or Provided Provided	r), or a servo amplifier e individual setting lid/invalid setting with machine feed value	
Absolute positi Synchronous e Speed limit Torque limit fur Torced stop Software stroke Hardware stroke Speed change Override	encoder operation function nction le limit function ke limit function [%]	Up to 4 channels Via an internal interface, a CPU (buffer memory Speed limit value, JOG speed limit value Torque limit value same setting, torque limit valu Via an internal interface or a buffer memory, va Movable range check with feed current value or Provided Provided 1 ot 0 300	r), or a servo amplifier e individual setting lid/invalid setting	
Absolute position Synchronous etc. Speed limit for forque limit fur forced stop Software stroked ardware stroked ardware stroked change override Acceleration/de	encoder operation function nction le limit function ke limit function le limit function generation function le limit function generation function	Up to 4 channels Via an internal interface, a CPU (buffer memory Speed limit value, JOG speed limit value Torque limit value same setting, torque limit value Via an internal interface or a buffer memory, va Movable range check with feed current value or Provided Provided 1 0 to 300 Provided	r), or a servo amplifier e individual setting lid/invalid setting with machine feed value	
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Absolute position Synchronous etc. Speed limit Forque limit fur Forced stop Software stroked Hardware stroked Har	encoder operation function netion le limit function ke limit function ke limit function ecceleration time change lange lange lange lange function Step function Skip function signal select function function	Up to 4 channels Via an internal interface, a CPU (buffer memory Speed limit value, JOG speed limit value Torque limit value same setting, torque limit value Via an internal interface or a buffer memory, va Movable range check with feed current value or Provided Provided Provided Provided Provided Speed to a target position address and a target position address and a target position and posit	e individual setting lid/invalid setting with machine feed value 1 to 300 cosition is changeable.	
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Absolute position Synchronous etc. Speed limit Torque limit fur Forced stop Software stroke Hardware stroke	encoder operation function nction le limit function ke limit function ke limit function le celeration time change lange lang	Up to 4 channels Via an internal interface, a CPU (buffer memory Speed limit value, JOG speed limit value Torque limit value same setting, torque limit value Via an internal interface or a buffer memory, va Movable range check with feed current value or Provided Provided Provided Provided Provided Speed to a target position address and a target position address and a target position unit step. Via a CPU or an external command signal Provided Via an internal interface, a CPU (buffer memory Continuous detection mode, specified number of 20 16	e individual setting lid/invalid setting with machine feed value 1 to 300 cosition is changeable. //), or a servo amplifier f detections mode, ring buffer mode 4 (2 points for QD77MS2) 16 (4 settings for QD77MS4/QD77MS2)	

Notes: 1. The home position return method set in a driver (servo amplifier) is used.
2. 4-axis linear interpolation control is enabled only at the reference axis speed.
3. Eight channels of each word data and bit data can be displayed in real time.

Synchronous Control Specifications

Synchronous control

Itom		Number of settable axes			
Item		RD78G4	RD78G8	RD78G16	
Servo input axis	[axes/module]	4	8	16	
Synchronous encoder input axis [axes/module]		4	8	16	
Command generation axis	[axes/module]	4	8	16	
Composite main shaft gear	[module/output axis]				
Main shaft main input axis	[module/output axis]		1		
Main shaft sub input axis	[module/output axis]	1			
Main shaft gear	[module/output axis]		1		
Main shaft clutch	[module/output axis]		1		
Auxiliary shaft	[module/output axis]		1		
Auxiliary shaft gear	[module/output axis]		1		
Auxiliary shaft clutch	[module/output axis]		1		
Auxiliary shaft composite gear	[module/output axis]		1		
Speed change gear	[module/output axis]		1	-	
Output axis (cam axis)	[axes/module]	4	8	16	

Cam control

Item –		Specifications											
		RD78G4		RD78G8			RD78G16						
Memory	Cam storage area		256k bytes										
capacity	Cam working area	1M bytes											
Maximum i	number of registrati	ons	256										
Comment			Up to 32 characte	ers for e	ach c	am d	ata						
	Stroke ratio	Maximum number of	Cam resolution	256	512		1024	2048	4096	8192	2 16	384 3	2768
		cam registrations	RD78G	256	128		64	32	16	8	4	2	
Cam data		Stroke ratio	-214.7483648 to	214.748	3647	[%]							
oum data	Coordinata	Maximum number of	Cam resolution	128	256	512	1024	2048	4096	8192	16384	32768	65535
	Coordinate data type	cam registrations	RD78G	256	128	64	32	16	8	4	2	-	-
		Coordinate data	Input value: 0 to	2147483	647 (Outpu	ıt value:	-2147483	3648 to	214748	33647		
Cam auto-	generation		Cam for rotary kr	nife									

■Products on the Market

Manual Pulse Generator

Mitsubishi Electric has confirmed the operation of the following manual pulse generator. Contact the manufacturer for details.

Product name	Model		Manufacturer
Manual pulse generator (Note 1)	RE46A2CO2B	Number of pulses per revolution: 25 pulses/rev (100 pulses/rev after magnification by 4)	Tokyo Sokuteikizai Co.,Ltd.

Notes: 1. Connect the manual pulse generator to a CPU module or a high-speed pulse input/output module. Refer to user's manuals and each product manual for details.

Motion Module

CC-Link IE TSN

	Motion module
Item	Simple Motion mode
	RD78G
Communications speed [bps]	1 G/100 M (Note 1)
Maximum number of connectable stations per network	121 stations (including the master station)
Connection cable	Ethernet cable (category 5e or higher, double shielded/STP) straight cable
Maximum distance between stations [m]	100
Maximum number of networks	239
Topology (Note 2)	Line, star, line/star mixed topologies
Communications method	Time-sharing method
Maximum transient transmission capacity	1920 bytes
Maximum link points per network	
RX/RY	16K points
RWr/RWw	8K points
Maximum link points per station	
RX/RY	16K points
RWr/RWw	8K points
Safety communications	
Maximum number of safety connectable stations per network	1814 connections
Maximum number of safety connections per station	120 connections
Maximum number of link points per safety connection	8 words (input: 8 words, output: 8 words)

Notes: 1. A 1 Gbps device and a 100 Mbps device cannot be used on the same network.

2. Use a switching hub (certified class: B) for star topology.

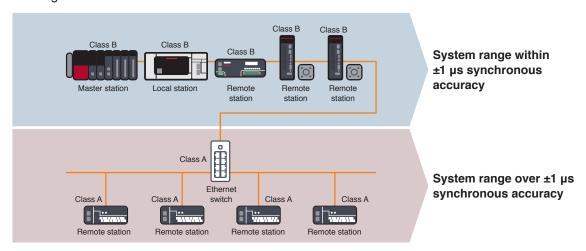
[Note when connecting devices]

Connect class A remote stations after class B remote stations.

Certified Class

CC-Link IE TSN certifies nodes and switches to a specific class level according to its functionality and performance classification. Products can be classified as either class A or B. For the certified classification of each product, please check the CC-Link partner association website or the relevant product catalog or manual. Supported functions and system configuration may differ according to the certified class of products used. For example, products compatible with certified class B are necessary to configure a high-speed motion control system. For details of configuring systems with both class A and class B devices, please refer to relevant master product manual.

System configuration



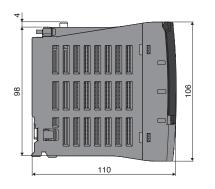
- Synchronous accuracy of a system varies relative to the combination of connected devices and switches certification class
- Use class B Ethernet switch when configuring a star topology with class B devices
- Use class B devices when configuring a system within ±1 μs high-accuracy synchronization, connect class A devices to a separate branch line from class B devices (for details of system configuration, please refer to relevant master product manual)

Motion module

Module specifications RD78G

Item	RD78G
	RD78G4: 4 axes
Maximum number of control axes	RD78G8: 8 axes
	RD78G16: 16 axes
Maximum number of connectable stations	121 stations
Maximum number of connectable stations	(including the master station)
Servo amplifier connection method	CC-Link IE TSN
CC-Link IE TSN certified class	В
Maximum distance between stations [m]	100
PERIPHERAL I/F	Via CPU module (USB, Ethernet)
Extended memory	SD memory card
Number of ports for CC-Link IE TSN	1 port
Number of I/O points occupied	32 points
Number of slots occupied	1 slot
5 V DC internal current consumption [A]	1.93
Mass [kg]	0.26
Dimensions [mm]	106.0 (H) × 27.8 (W) × 110.0 (D)

Dimensions RD78G4/RD78G8/RD78G16





[Unit: mm]

Engineering Software

MELSOFT GX Works3 operating environment (Note 1)

Item	Description
	Microsoft® Windows® 10 (Home, Pro, Enterprise, Education, IoT Enterprise 2016 LTSB (Note 2)) (64 bit/32 bit)
OS	Microsoft® Windows® 8.1 (64 bit/32 bit), Microsoft® Windows® 8.1 (Enterprise, Pro) (64 bit/32 bit)
	Microsoft® Windows® 7 (Enterprise, Ultimate, Professional, Home Premium) (64 bit/32 bit)
Personal computer	Windows® supported personal computer
CPU	Intel® Core™2 Duo Processor 2 GHz or more recommended
Poguired memory	For 64-bit edition: 2 GB or more recommended
Required memory	For 32-bit edition: 1 GB or more recommended
From board dials appear	For installation: 17 GB or more free hard disk capacity
Free hard disk space	For operation: 512 MB or more free virtual memory capacity
Optical drive	DVD-ROM supported disk drive
Monitor	Resolution 1024 × 768 pixels or higher

Notes: 1. Refer to Installation Instructions for precautions and restrictions regarding the operating environment.

Engineering software list

Item	Model	Description	
MELSOFT GX Works3	SW1DND-GXW3-E	•Programmable Controller Engineering Software [MELSOFT GX Works3 (Note 1, 2), GX Works2, GX Developer, PX Developer] •MITSUBISHI ELECTRIC FA Library	DVD-ROM
MELSOFT iQ Works	SW2DND-IQWK-E	FA engineering software (Note 3) • System Management Software [MELSOFT Navigator] • Programmable Controller Engineering Software [MELSOFT GX Works3 (Note 1, 2), GX Works2, GX Developer, PX Developer] • Motion Controller Engineering Software [MELSOFT MT Works2] • Screen Design Software [MELSOFT GT Works3] • Robot Programming Software [MELSOFT RT ToolBox3 (Note 4)] • Inverter Setup Software [MELSOFT FR Configurator2] • MITSUBISHI ELECTRIC FA Library	DVD-ROM

- Notes: 1. MELSOFT GX Works3 with version 1.075D or later and MR Configurator2 with version 1.100E or later are required.
 2. The MELSOFT GX Works3 menu is switchable between Japanese, English, and simplified Chinese.
 3. Refer to each product manual for the software supported by the model.
 4. RT ToolBox3 mini (simplified version) will be installed if iQ Works product ID is used. When RT ToolBox3 (with simulation function) is required, please purchase RT ToolBox3 product ID.

^{2.} The 32-bit edition is not supported.

●Servo system controller

Item	Model	Application	Standard
Motion module (Note 1)	RD78G4	Maximum number of control axes: 4 axes CC-Link IE TSN master station	CE, UL, KC
	RD78G8	Maximum number of control axes: 8 axes CC-Link IE TSN master station	CE, UL, KC
	RD78G16	Maximum number of control axes: 16 axes CC-Link IE TSN master station	CE, UL, KC

Notes: 1. The Simple Motion mode is supported by RD78G with firmware version 16 or later.

To obtain the firmware update files, contact your local sales office.

●Engineering software

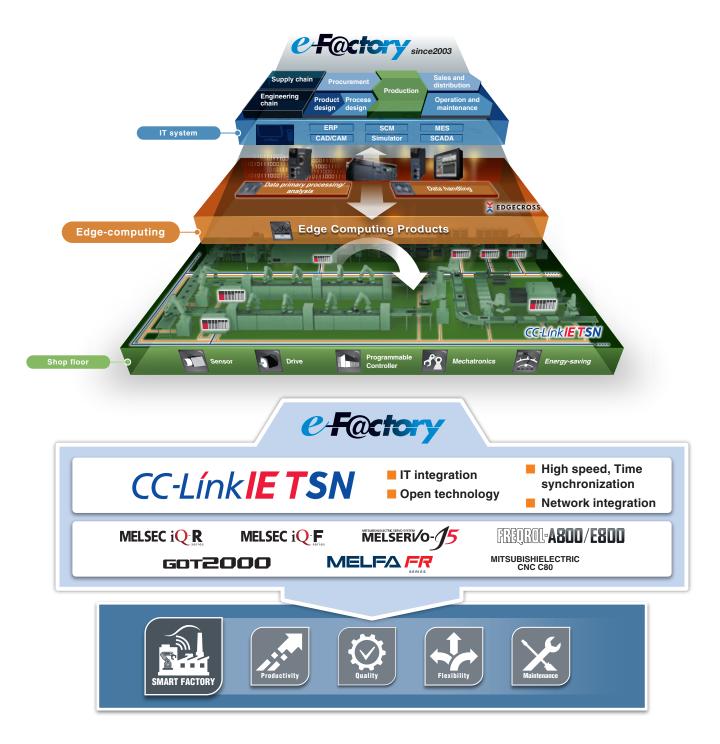
Item	Model	Application
MELSOFT iQ Works	SW2DND-IQWK-E	FA Engineering Software
MELSOFT GX Works3	SW1DND-GXW3-E	Programmable Controller Engineering Software

Mitsubishi Electric Solutions

e-F@ctory

Maximize productivity and reduce costs with an intelligent smart factory solution

Intelligent smart factories utilize high-speed networks with large data bandwidths to meet current manufacturing needs. The combination of CC-Link IE TSN and Mitsubishi Electric's e-F@ctory solution ensures robust integration between IT and factory automation systems, providing an intelligent smart factory solution that reduces total cost while improving operations, production yield, and efficient management of the supply chain. e-F@ctory is the Mitsubishi Electric solution for adding value across the manufacturing enterprise by enhancing productivity, thereby simultaneously reducing maintenance and operating costs, and enabling the seamless flow of information throughout the plant. e-F@ctory uses a combination of factory automation and IT technologies in combination with various best-in-class partner products through its alliance program.



Mitsubishi Electric FA Global Website

Mitsubishi Electric Factory Automation provides a mix of services to support its customers worldwide, through a consolidated global website. It offers a selection of support tools and a window to its local Mitsubishi Electric sales and support network.

Global & Local Websites

Mitsubishi Electric Factory Automation
Global website

www.MitsubishiElectric.com/fa





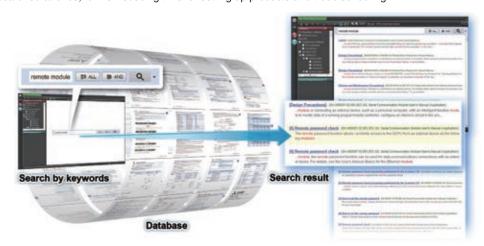


Local websites

Global website

e-Manual Viewer

The e-Manual viewer is a next-generation digital manual offered by Mitsubishi Electric that consolidates factory automation products manuals into an easy-to-use package with various useful features integrated into the viewer. The e-Manual allows multiple manuals to be cross-searched at once, further reducing time for setting up products and troubleshooting.



■ Key features included

- One-stop database containing all required manuals, with local file cache
- Included with GX Works3 engineering software
- Also available in tablet version
- Easily download manuals all at once

- Multiple users can share the latest manuals and knowhow with document sharing function
- Directly port sample programs within manuals to GX Works3
- Downloaded manuals are usable offline













Servo system controller

Warranty

1. Warranty period and coverage

We will repair any failure or defect (hereinafter referred to as "failure") in our FA equipment (hereinafter referred to as the "Product") arisen during warranty period at no charge due to causes for which we are responsible through the distributor from which you purchased the Product or our service provider. However, we will charge the actual cost of dispatching our engineer for an on-site repair work on request by customer in Japan or overseas countries. We are not responsible for any on-site readjustment and/or trial run that may be required after a defective unit is repaired or replaced.

[Term]

For terms of warranty, please contact your original place of purchase.

[Limitations]

- You are requested to conduct an initial failure diagnosis by yourself, as a general rule.
 - It can also be carried out by us or our service company upon your request and the actual cost will be charged.
 - However, it will not be charged if we are responsible for the cause of the failure.
- (2) This limited warranty applies only when the condition, method, environment, etc. of use are in compliance with the terms and conditions and instructions that are set forth in the instruction manual and user manual for the Product and the caution label affixed to the Product.
- (3) Even during the term of warranty, the repair cost will be charged on you in the following cases;
 - a failure caused by your improper storing or handling, carelessness or negligence, etc., and a failure caused by your hardware or software problem
 - a failure caused by any alteration, etc. to the Product made on your side without our approval
 - (iii) a failure which may be regarded as avoidable, if your equipment in which the Product is incorporated is equipped with a safety device required by applicable laws and has any function or structure considered to be indispensable according to a common sense in the industry
 - (iv) a failure which may be regarded as avoidable if consumable parts designated in the instruction manual, etc. are duly maintained and replaced
 - (v) any replacement of consumable parts (battery, fan, smoothing capacitor, etc.)
 - (vi) a failure caused by external factors such as inevitable accidents, including without limitation fire and abnormal fluctuation of voltage, and acts of God, including without limitation earthquake, lightning and natural disasters
 - (vii) a failure generated by an unforeseeable cause with a scientific technology that was not available at the time of the shipment of the Product from our company
 - (viii) any other failures which we are not responsible for or which you acknowledge we are not responsible for

- 2. Term of warranty after the stop of production
 - (1) We may accept the repair at charge for another seven (7) years after the production of the product is discontinued. The announcement of the stop of production for each model can be seen in our Sales and Service, etc.
 - (2) Please note that the Product (including its spare parts) cannot be ordered after its stop of production.

3. Service in overseas countries

Our regional FA Center in overseas countries will accept the repair work of the Product. However, the terms and conditions of the repair work may differ depending on each FA Center. Please ask your local FA Center for details.

 Exclusion of loss in opportunity and secondary loss from warranty liability

Regardless of the gratis warranty term, Mitsubishi shall not be liable for compensation to:

- Damages caused by any cause found not to be the responsibility of Mitsubishi.
- (2) Loss in opportunity, lost profits incurred to the user by Failures of Mitsubishi products.
- (3) Special damages and secondary damages whether foreseeable or not, compensation for accidents, and compensation for damages to products other than Mitsubishi products.
- (4) Replacement by the user, maintenance of on-site equipment, start-up test run and other tasks.

5. Change of Product specifications

Specifications listed in our catalogs, manuals or technical documents may be changed without notice.

- 6. Application and use of the Product
 - (1) For the use of our Motion module, its applications should be those that may not result in a serious damage even if any failure or malfunction occurs in Motion module, and a backup or failsafe function should operate on an external system to Motion controller/Simple Motion module when any failure or malfunction occurs.
 - (2) Our Motion module is designed and manufactured as general purpose product for use at general industries.

Therefore, applications substantially influential on the public interest for such as atomic power plants and other power plants of electric power companies, and also which require a special quality assurance system, including applications for railway companies and government or public offices are not recommended, and we assume no responsibility for any failure caused by these applications when used.

In addition, applications which may be substantially influential to human lives or properties for such as airlines, medical treatments, railway service, incineration and fuel systems, manoperated material handling equipment, entertainment machines, safety machines, etc. are not recommended, and we assume no responsibility for any failure caused by these applications when used.

We will review the acceptability of the abovementioned applications, if you agree not to require a specific quality for a specific application. Please contact us for consultation.

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MEMO

МЕМО

YOUR SOLUTION PARTNER



Mitsubishi Electric offers a wide range of automation equipment from PLCs and HMIs to CNC and EDM machines.



Low voltage: MCCB, MCB, AC



Medium voltage: VCB, VCC



Power monitoring, energy management



Compact and Modular Controllers



Inverters, Servos and Motors



Visualization: HMIs



Numerical Control (NC)



Industrial / Collaborative Robots



Processing machines: EDM, Lasers, IDS



Transformers, Air conditioning, Photovoltaic systems

A NAME TO TRUST

Since its beginnings in 1870, some 45 companies use the Mitsubishi name, covering a spectrum of finance, commerce and industry.

The Mitsubishi brand name is recognized around the world as a symbol of premium quality.

Mitsubishi Electric Corporation, established in 1921, is active in space development, transportation, semi-conductors, energy systems, communications and information processing, audio visual equipment and home electronics, building and energy management and automation systems, and has 183 factories, laboratories and offices worldwide in over 140 countries

This is why you can rely on Mitsubishi Electric automation solution - because we know first hand about the need for reliable, efficient, easy-to-use automation and control in our own factories.

As one of the world's leading companies with a global turnover of over 4 trillion Yen (over \$40 billion), employing over 146,000 people, Mitsubishi Electric has the resource and the commitment to deliver the ultimate in service and support as well as the best products.

^{*} Not all products are available in all countries.

Mitsubishi Electric AC Servo System MELSEC iQ-R series Motion Module Simple Motion Mode

Indonesia

USA Mitsubishi Electric Automation, Inc. Tel: +1-847-478-2100 500 Corporate Woods Parkway, Vernon Hills, IL 60061, U.S.A.

Mitsubishi Electric Automation, Inc. Mexico Branch Tel: +52-55-3067-7512 Mexico

Boulevard Miguel de Cervantes Saavedra 301, Torre Norte Piso 5, Ampliacion Granada, Miguel Hidalgo, Ciudad de Mexico, Mexico, C.P.11520

Brazil Mitsubishi Electric do Brasil Comercio e Servicos Ltda. Tel: +55-11-4689-3000

Avenida Adelino Cardana, 293, 21 andar, Bethaville, Barueri SP, Brazil Mitsubishi Electric Europe B.V. German Branch

Tel: +49-2102-486-0 Germany Mitsubishi-Electric-Platz 1, 40882 Ratingen, Germany

UK Mitsubishi Electric Europe B.V. UK Branch Tel: +44-1707-28-8780 Travellers Lane, UK-Hatfield, Hertfordshire, AL10 8XB, U.K.

Mitsubishi Electric Europe B.V. Italian Branch Tel: +39-039-60531 Italy

Centro Direzionale Colleoni - Palazzo Sirio, Viale Colleoni 7, 20864 Agrate Brianza (MB), Italy

Mitsubishi Electric Europe B.V. Spanish Branch Spain Tel: +34-935-65-3131 Carretera de Rubi, 76-80-Apdo. 420, E-08174 Sant Cugat del Valles (Barcelona), Spain

Mitsubishi Electric Europe B.V. French Branch France Tel: +33-1-55-68-55-68

25, Boulevard des Bouvets, 92741 Nanterre Cedex, France Czech Republic Mitsubishi Electric Europe B.V. Czech Branch, Prague Office Tel: +420-255-719-200

Pekarska 621/7, 155 00 Praha 5, Czech Republic

Mitsubishi Electric Europe B V Polish Branch Poland Tel: +48-12-347-65-00 ul. Krakowska 48. 32-083 Balice. Poland

Mitsubishi Electric (Russia) LLC St. Petersburg Branch Russia Tel: +7-812-449-51-34

Startovaya street, 8, BC "Aeroplaza", office 607; 196210, St. Petersburg, Russia

Mitsubishi Electric Europe B.V. (Scandinavia) Tel: +46-8-625-10-00 Sweden Hedvig Mollersgata 6, 223 55 Lund, Sweden

Turkey Mitsubishi Electric Turkey A.S. Umraniye Branch Tel: +90-216-969-2500

Serifali Mah. Kale Sok. No:41 34775 Umraniye - Istanbul, Turkey UAE Tel: +971-4-3724716

Mitsubishi Electric Europe B.V. Dubai Branch Dubai Silicon Oasis, P.O.BOX 341241, Dubai, U.A.E.

South Africa Tel: +27-11-658-8100 Adroit Technologies

20 Waterford Office Park, 189 Witkoppen Road, Fourways, South Africa China Mitsubishi Electric Automation (China) Ltd. Tel: +86-21-2322-3030

Mitsubishi Electric Automation Center, No.1386 Hongqiao Road, Shanghai, China

SETSUYO ENTERPRISE CO., LTD. Taiwan Tel: +886-2-2299-2499 6F, No.105, Wugong 3rd Road, Wugu District, New Taipei City 24889, Taiwan

Mitsubishi Electric Automation Korea Co., Ltd. Tel: +82-2-3660-9529 Korea 7F to 9F, Gangseo Hangang Xi-tower A, 401, Yangcheon-ro, Gangseo-Gu, Seoul 07528, Korea

Mitsubishi Electric Asia Pte. Ltd. Tel: +65-6473-2486 Singapore

307 Alexandra Road, Mitsubishi Electric Building, Singapore 159943

Thailand Mitsubishi Electric Factory Automation (Thailand) Co., Ltd. Tel: +66-2092-8600

True Digital Park Building Sukhumvit 101 Sukhumvit Road, Bang Chak, Prakanong, Bangkok,

PT. Mitsubishi Electric Indonesia

Gedung Jaya 8th Floor, JL. MH. Thamrin No.12, Jakarta Pusat 10340, Indonesia

Vietnam Mitsubishi Electric Vietnam Company Limited Tel: +84-28-3910-5945

11th & 12th Floor, Viettel Tower B, 285 Cach Mang Thang 8 Street, Ward 12, District 10, Ho Chi Minh City, Vietnam

Mitsubishi Electric India Pvt. Ltd. Pune Branch India

Tel: +91-20-2710-2000 Emerald House, EL-3, J Block, M.I.D.C., Bhosari, Pune - 411026, Maharashtra, India

Australia Mitsubishi Electric Australia Pty. Ltd. Tel: +61-2-9684-7777

348 Victoria Road, P.O. Box 11, Rydalmere, N.S.W 2116, Australia

Mitsubishi Electric Corporation Nagoya Works is a factory certified for ISO14001 (standards for environmental management systems) and ISO9001(standards for quality assurance management systems)





Tel: +62-21-3192-6461



MITSUBISHI ELECTRIC CORPORATION

HEAD OFFICE: TOKYO BUILDING, 2-7-3, MARUNOUCHI, CHIYODA-KU, TOKYO 100-8310, JAPAN NAGOYA WORKS: 1-14, YADA-MINAMI 5, HIGASHI-KU, NAGOYA, JAPAN