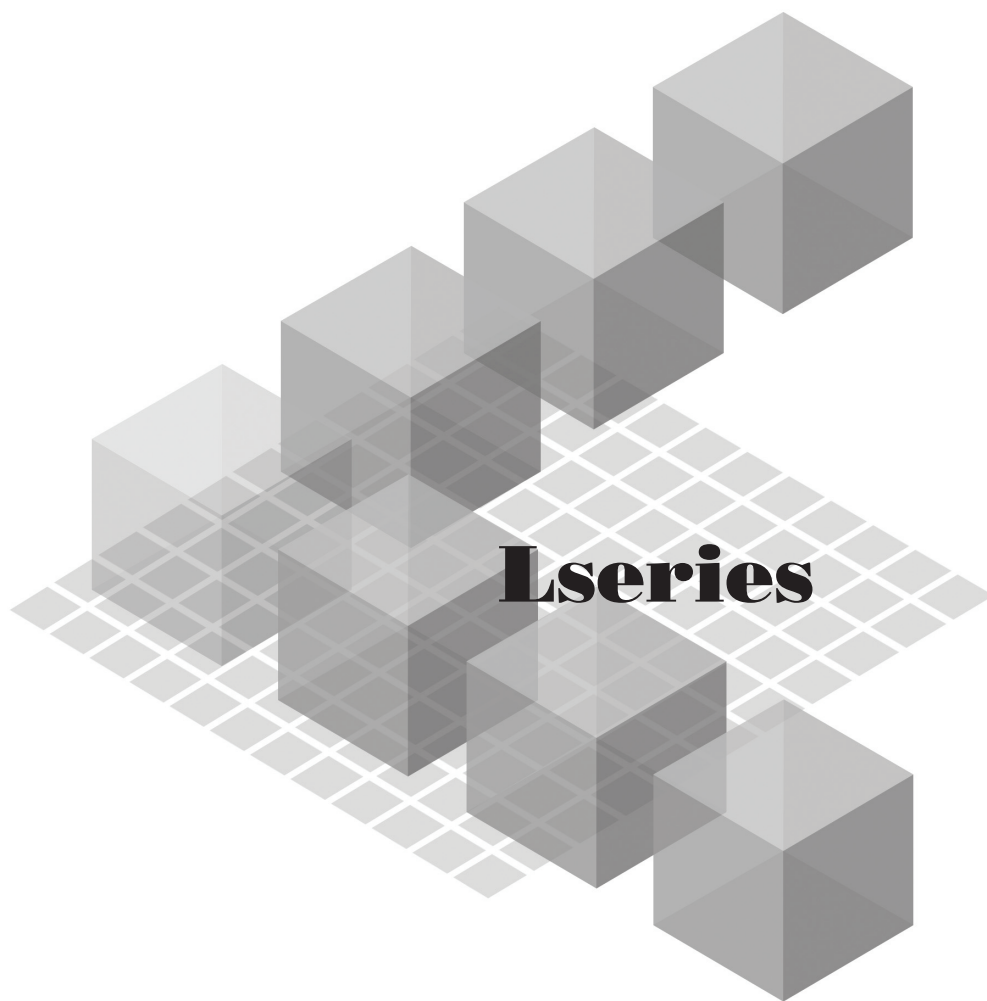


MITSUBISHI

Mitsubishi Programmable Controller

MELSEC *L*_{series}

MELSEC-L Temperature Control Module User's Manual



-L60TCTT4
-L60TCTT4BW
-L60TCRT4
-L60TCRT4BW

MODEL

● SAFETY PRECAUTIONS ●

(Read these precautions before using this product.)

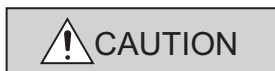
Before using this product, please read this manual and the relevant manuals carefully and pay full attention to safety to handle the product correctly.

The precautions given in this manual are concerned with this product only. For the safety precautions of the programmable controller system, refer to the user's manual for the CPU module used.

In this manual, the safety precautions are classified into two levels: "⚠ CAUTION" and "⚠ WARNING".



Indicates that incorrect handling may cause hazardous conditions, resulting in death or severe injury.



Indicates that incorrect handling may cause hazardous conditions, resulting in minor or moderate injury or property damage.

Under some circumstances, failure to observe the precautions given under "⚠ CAUTION" may lead to serious consequences.

Observe the precautions of both levels because they are important for personal and system safety.

Make sure that the end users read this manual and then keep the manual in a safe place for future reference.

[Design Precautions]

⚠ WARNING

- Do not write any data to the "system area" and "write-protect area" (R) of the buffer memory in the intelligent function module. Also, do not use any "use prohibited" signals as an output signal from the programmable controller CPU to the intelligent function module. Doing so may cause malfunction of the programmable controller system.

[Design Precautions]

⚠ CAUTION

- Do not install the control lines or communication cables together with the main circuit lines or power cables. Keep a distance of 100mm or more between them. Failure to do so may result in malfunction due to noise.

[Installation Precautions]

WARNING

- Shut off the external power supply (all phases) used in the system before mounting or removing a module. Failure to do so may result in electric shock or cause the module to fail or malfunction.

[Installation Precautions]

CAUTION

- Use the programmable controller in an environment that meets the general specifications in the Safety Guidelines provided with the CPU module or head module. Failure to do so may result in electric shock, fire, malfunction, or damage to or deterioration of the product.
- To interconnect modules, engage the respective connectors and securely lock the module joint levers until they click.
- Tighten the screw within the specified torque range. Undertightening can cause drop of the screw, short circuit or malfunction. Overtightening can damage the screw and/or module, resulting in drop, short circuit, or malfunction.
- Do not directly touch any conductive parts and electronic components of the module. Doing so can cause malfunction or failure of the module.

[Wiring Precautions]

WARNING

- After installation and wiring, attach the included terminal cover to the module before turning it on for operation. Failure to do so may result in electric shock.

[Wiring Precautions]

CAUTION

- Individually ground the FG terminal of the programmable controller with a ground resistance of 100Ω or less. Failure to do so may result in electric shock or malfunction.
- Tighten the terminal block screw within the specified torque range. Undertightening can cause short circuit, fire, or malfunction. Overtightening can damage the screw and/or module, resulting in drop, short circuit, fire, or malfunction.
- Prevent foreign matter such as dust or wire chips from entering the module. Such foreign matter can cause a fire, failure, or malfunction.
- A protective film is attached to the top of the module to prevent foreign matter, such as wire chips, from entering the module during wiring. Do not remove the film during wiring. Remove it for heat dissipation before system operation.
- Mitsubishi programmable controllers must be installed in control panels. Connect the main power supply to the power supply module in the control panel through a relay terminal block. Wiring and replacement of a power supply module must be performed by qualified maintenance personnel with knowledge of protection against electric shock. For wiring methods, refer to the MELSEC-L CPU Module User's Manual (Hardware Design, Maintenance and Inspection).

[Startup and Maintenance Precautions]

WARNING

- Do not touch any terminal while power is on. Doing so will cause electric shock or malfunction.
- Shut off the external power supply (all phases) used in the system before cleaning the module or retightening the terminal block screw. Failure to do so may result in electric shock.

[Startup and Maintenance Precautions]

CAUTION

- Do not disassemble or modify the module. Doing so may cause failure, malfunction, injury, or a fire.
- Shut off the external power supply (all phases) used in the system before mounting or removing a module. Failure to do so may cause the module to fail or malfunction.
- Tighten the terminal block screw within the specified torque range. Undertightening can cause drop of the component or wire, short circuit, or malfunction. Overtightening can damage the screw and/or module, resulting in drop, short circuit, or malfunction.
- After the first use of the product (module, display unit, and terminal block), the number of connections/disconnections is limited to 50 times (in accordance with IEC 61131-2). Exceeding the limit may cause malfunction.
- Before handling the module, touch a conducting object such as a grounded metal to discharge the static electricity from the human body. Failure to do so may cause the module to fail or malfunction.

[Disposal Precautions]

CAUTION

- When disposing of this product, treat it as industrial waste.

●CONDITIONS OF USE FOR THE PRODUCT●

- (1) Mitsubishi programmable controller ("the PRODUCT") shall be used in conditions;
- i) where any problem, fault or failure occurring in the PRODUCT, if any, shall not lead to any major or serious accident; and
 - ii) where the backup and fail-safe function are systematically or automatically provided outside of the PRODUCT for the case of any problem, fault or failure occurring in the PRODUCT.
- (2) The PRODUCT has been designed and manufactured for the purpose of being used in general industries.

MITSUBISHI SHALL HAVE NO RESPONSIBILITY OR LIABILITY (INCLUDING, BUT NOT LIMITED TO ANY AND ALL RESPONSIBILITY OR LIABILITY BASED ON CONTRACT, WARRANTY, TORT, PRODUCT LIABILITY) FOR ANY INJURY OR DEATH TO PERSONS OR LOSS OR DAMAGE TO PROPERTY CAUSED BY the PRODUCT THAT ARE OPERATED OR USED IN APPLICATION NOT INTENDED OR EXCLUDED BY INSTRUCTIONS, PRECAUTIONS, OR WARNING CONTAINED IN MITSUBISHI'S USER, INSTRUCTION AND/OR SAFETY MANUALS, TECHNICAL BULLETINS AND GUIDELINES FOR the PRODUCT.

("Prohibited Application")

Prohibited Applications include, but not limited to, the use of the PRODUCT in;

- Nuclear Power Plants and any other power plants operated by Power companies, and/or any other cases in which the public could be affected if any problem or fault occurs in the PRODUCT.
- Railway companies or Public service purposes, and/or any other cases in which establishment of a special quality assurance system is required by the Purchaser or End User.
- Aircraft or Aerospace, Medical applications, Train equipment, transport equipment such as Elevator and Escalator, Incineration and Fuel devices, Vehicles, Manned transportation, Equipment for Recreation and Amusement, and Safety devices, handling of Nuclear or Hazardous Materials or Chemicals, Mining and Drilling, and/or other applications where there is a significant risk of injury to the public or property.

Notwithstanding the above, restrictions Mitsubishi may in its sole discretion, authorize use of the PRODUCT in one or more of the Prohibited Applications, provided that the usage of the PRODUCT is limited only for the specific applications agreed to by Mitsubishi and provided further that no special quality assurance or fail-safe, redundant or other safety features which exceed the general specifications of the PRODUCTS are required. For details, please contact the Mitsubishi representative in your region.

INTRODUCTION

Thank you for purchasing the Mitsubishi MELSEC-L series programmable controllers.

This manual describes the operating procedures, system configuration, parameter settings, functions, programming, and troubleshooting of the L series temperature control module L60TCTT4/L60TCTT4BW/L60TCRT4/L60TCRT4BW (hereafter abbreviated as L60TC4).

Before using this product, please read this manual and the relevant manuals carefully and develop familiarity with the functions and performance of the MELSEC-L series programmable controller to handle the product correctly.

When applying the program examples introduced in this manual to the actual system, ensure the applicability and confirm that it will not cause system control problems.

■Relevant modules: L60TCTT4, L60TCTT4BW, L60TCRT4, L60TCRT4BW

Remark

Operating procedures are explained using GX Works2. When using GX Developer, refer to  Page 430, Appendix 6.

COMPLIANCE WITH EMC AND LOW VOLTAGE DIRECTIVES

(1) Method of ensuring compliance

To ensure that Mitsubishi programmable controllers maintain EMC and Low Voltage Directives when incorporated into other machinery or equipment, certain measures may be necessary. Please refer to one of the following manuals.

- MELSEC-L CPU Module User's Manual (Hardware Design, Maintenance and Inspection)
- MELSEC-L CC-Link IE Field Network Head Module User's Manual
- Safety Guidelines

(This manual is included with the CPU module or head module.)

The CE mark on the side of the programmable controller indicates compliance with EMC and Low Voltage Directives.

(2) Additional measures

To ensure that this product maintains EMC and Low Voltage Directives, please refer to one of the manuals listed under (1).

RELEVANT MANUALS

(1) CPU module user's manual

Manual name <manual number (model code)>	Description
MELSEC-L CPU Module User's Manual (Hardware Design, Maintenance and Inspection) <SH-080890ENG, 13JZ36>	Specifications of the CPU modules, power supply modules, display unit, branch module, extension module, SD memory cards, and batteries, information on how to establish a system, maintenance and inspection, and troubleshooting
MELSEC-L CPU Module User's Manual (Function Explanation, Program Fundamentals) <SH-080889ENG, 13JZ35>	Functions and devices of the CPU module, and programming

(2) Head module user's manual

Manual name <manual number (model code)>	Description
MELSEC-L CC-Link IE Field Network Head Module User's Manual <SH-080919ENG, 13JZ48>	Specifications, procedures before operation, system configuration, installation, wiring, settings, and troubleshooting of the head module

(3) Operating manual

Manual name <manual number (model code)>	Description
GX Works2 Version 1 Operating Manual (Common) <SH-080779ENG, 13JU63>	System configuration, parameter settings, and online operations (common to Simple project and Structured project) of GX Works2
GX Developer Version 8 Operating Manual <SH-080373E, 13JU41>	Operating methods of GX Developer, such as programming, printing, monitoring, and debugging

CONTENTS

SAFETY PRECAUTIONS	1
CONDITIONS OF USE FOR THE PRODUCT	4
INTRODUCTION	5
COMPLIANCE WITH EMC AND LOW VOLTAGE DIRECTIVES	6
RELEVANT MANUALS	7
MANUAL PAGE ORGANIZATION	12
TERMS	14
PACKING LIST	15

CHAPTER 1 WHAT CAN BE DONE WITH A TEMPERATURE CONTROL MODULE 16

1.1 Use	16
1.2 Features	18
1.3 The PID Control System	22
1.4 About the PID Operation	24
1.4.1 Operation method and formula	24
1.4.2 The L60TC4 actions	25
1.4.3 Proportional action (P-action)	26
1.4.4 Integral action (I-action)	27
1.4.5 Derivative action (D-action)	28
1.4.6 PID action	29

CHAPTER 2 PART NAMES 30

CHAPTER 3 SPECIFICATIONS 32

3.1 General Specifications	32
3.2 Performance Specifications	33
3.2.1 Number of parameters to be set	35
3.2.2 Type of usable temperature sensors, temperature measurement range, resolution, and effect from wiring resistance of 1 ohm.	37
3.2.3 Sampling cycle and control output cycle	39
3.3 Function List	40
3.4 I/O Signal List	43
3.5 Buffer Memory List	45

CHAPTER 4 PROCEDURE BEFORE OPERATION 81

CHAPTER 5 SYSTEM CONFIGURATION 83

5.1 Total Configuration	83
5.2 Applicable Systems	84
5.3 Restrictions When Temperature Control Module Is Used with Head Module	84
5.4 Precautions for System Configuration	85

CHAPTER 6 INSTALLATION AND WIRING	86
6.1 Installation Environment and Installation Position	86
6.2 Terminal Block	87
6.3 Wiring precautions	94
6.4 External wiring	95
6.4.1 L60TCTT4	95
6.4.2 L60TCTT4BW	98
6.4.3 L60TCRT4	101
6.4.4 L60TCRT4BW	104
6.5 Heater disconnection detection wiring and setting example for three-phase heater	107
6.6 Unused Channel Setting	108
CHAPTER 7 VARIOUS SETTINGS	109
7.1 Addition of Modules	109
7.2 Switch Setting	110
7.3 Parameter Setting	112
7.4 Auto Refresh	116
7.5 Auto Tuning	118
7.6 Sensor Correction	118
CHAPTER 8 FUNCTIONS	119
8.1 Temperature Input Mode	120
8.1.1 Conversion enable/disable function	121
8.1.2 Temperature conversion method	121
8.1.3 Alert output function	124
8.2 Temperature Control Mode	129
8.2.1 Control Mode Selection Function	130
8.2.2 Control output setting at CPU stop error	132
8.2.3 Control method	133
8.2.4 Manual Reset Function	141
8.2.5 Manual Control	143
8.2.6 Control output cycle unit selection function	144
8.2.7 Auto tuning function	145
8.2.8 Simple Two-degree-of-freedom	157
8.2.9 Derivative Action Selection Function	158
8.2.10 Setting Change Rate Limiter Setting Function	159
8.2.11 Alert Function	161
8.2.12 RFB Limiter Function	175
8.2.13 Input/output (with another analog module) function	176
8.2.14 ON delay output function	178
8.2.15 Self-tuning function	179
8.2.16 Peak current suppression function	189
8.2.17 Simultaneous temperature rise function	194
8.2.18 Forward/reverse action selection function	207
8.2.19 Loop disconnection detection function	208

8.2.20	During AT Loop Disconnection Detection Function	210
8.2.21	Proportional band setting function	212
8.2.22	Cooling method setting function	213
8.2.23	Overlap/dead band function	215
8.2.24	Temperature conversion function (using unused channels)	218
8.2.25	Heater disconnection detection function	221
8.2.26	Output off-time current error detection function	226
8.3	Common Functions	227
8.3.1	Moving Averaging Process to a Temperature Process Value (PV)	227
8.3.2	Temperature process value (PV) scaling function	228
8.3.3	Sensor correction function	230
8.3.4	Auto-setting at input range change	241
8.3.5	Buffer memory data backup function	242
8.3.6	Error history function	244
8.3.7	Module error history collection function	246
8.3.8	Error clear function	247

CHAPTER 9 DISPLAY UNIT	248

9.1	Display Unit	248
9.2	Menu Transition	248
9.3	Setting Value Change Screen List	250
9.4	Checking and Clearing Errors	255

CHAPTER 10 PROGRAMMING	257

10.1	Programming Procedure	257
10.2	When Using the Module in a Standard System Configuration	259
10.2.1	When using the L60TC4 as a temperature input module	259
10.2.2	Standard control (such as auto tuning, self-tuning, and error code read)	270
10.2.3	Standard control (peak current suppression function, simultaneous temperature rise function)	282
10.2.4	When performing the heating-cooling control	297
10.3	When the Module is Connected to the Head Module	307

CHAPTER 11 TROUBLESHOOTING	318

11.1	Before Troubleshooting	318
11.2	Troubleshooting Procedure	318
11.3	Checks Using LEDs	320
11.3.1	When the RUN LED flashes or turns off	320
11.3.2	When the ERR. LED turns on or flashes	320
11.3.3	When the ALM LED turns on or flashes	321
11.4	Checks Using Input Signals	322
11.4.1	When Module READY flag (Xn0) does not turn on	322
11.4.2	When Error occurrence flag (Xn2) is on	322
11.4.3	When Hardware error flag (Xn3) is on	322

11.4.4	When the auto tuning does not start (CH□ Auto tuning status (Xn4 to Xn7) does not turn on)	322
11.4.5	When the auto tuning does not complete (CH□ Auto tuning status (Xn4 to Xn7) stays on and does not turn off)	323
11.4.6	When the self-tuning does not start (CH□ Auto tuning status (Xn4 to Xn7) does not turn on)	323
11.4.7	When Back-up of the set value fail flag (XnA) is on	323
11.4.8	When CH□ Alert occurrence flag (XnC to XnF) is on	323
11.5	Troubleshooting by Symptom	324
11.5.1	When the temperature process value (PV) is abnormal	324
11.6	Error Code List	325
11.7	Alarm Code List	328
11.8	Check the L60TC4 Status	331

APPENDICES	333

Appendix 1	Details of I/O Signals	333
Appendix 1.1	Input signal	333
Appendix 1.2	Output signal	340
Appendix 2	Details of the Buffer Memory	344
Appendix 3	How to Check the Serial Number and Function Version	426
Appendix 4	Addition and Change of Functions	427
Appendix 4.1	Additional function	427
Appendix 4.2	Change of functions	427
Appendix 5	Differences with MELSEC-Q series Modules	428
Appendix 5.1	Differences with temperature control modules	428
Appendix 6	When Using GX Developer	430
Appendix 6.1	I/O assignment and intelligent function module switch setting	430
Appendix 6.2	Initial setting and auto refresh setting	433
Appendix 7	External Dimensions	434

INDEX	436

REVISIONS	442
WARRANTY	443

MANUAL PAGE ORGANIZATION

In this manual, pages are organized and the symbols are used as shown below.

The following illustration is for explanation purpose only, and should not be referred to as an actual documentation.

"" is used for screen names and items.

1. shows operating procedures.

☞ shows mouse operations.*1

[] is used for items in the menu bar and the project window.

Ex. shows setting or operating examples.

📖 shows reference manuals.

📄 shows reference pages.

Point shows notes that requires attention.

Remark shows useful information.

CHAPTER 7 VARIOUS SETTINGS

7.1.1 Setting method

(1) Setting parameters

(a) Operating procedure

1. Open the "PLC Parameter" dialog box.
Project window ⇨ [Parameter] ⇨ [PLC parameter]
2. Select the "I/O Assignment" tab.

Item	Description	Reference
Type	Select the type of the connected module.	Page 74, Section 7.1.2
Model Name	Select the model name of the connected module.	Page 74, Section 7.1.3
Points	Set the number of points assigned to each slot.	Page 74, Section 7.1.4
Start XY	Specify a start I/O number for each slot.	Page 74, Section 7.1.5
Switch Setting	Configure the switch setting of the built-in I/O or intelligent function modules.	Page 74, Section 7.1.6
Detailed Setting	Set the following: - Error Time Output Mode - PLC Operation Mode at HW Error - I/O Response Time	Page 75, Section 7.1.7

Setting "Start XY" enables modification on the start I/O numbers assigned to connected modules.

Ex. When "1000" is specified in "Start XY" to the slot where a 16-point module is connected, the assignment range of an input module is changed to X1000 to X100F.

For details, refer to the following.

📖 MELSEC-L CPU Module User's Manual (Function Explanation, Program Fundamentals)

Point Set the type of the connected module in "Type". Setting a different type results in "SPUNIT LAY ERR". For the intelligent function module, the I/O points must also be the same in addition to the I/O assignment setting. (Page 30, Section 4.2.2)

Remark When an intelligent module is connected, I/O assignment can be omitted by selecting connected modules from "Intelligent Function Module" in the Project window.

73

*1 The mouse operation example is provided below.

Menu bar

Ex. ☞ [Online] ⇨ [Write to PLC...]
Select [Online] on the menu bar, and then select [Write to PLC...].

A window selected in the view selection area is displayed.

Ex. ☞ Project window ⇨ [Parameter] ⇨ [PLC Parameter]
Select [Project] from the view selection area to open the Project window.
In the Project window, expand [Parameter] and select [PLC Parameter].

View selection area

Pages describing buffer memory areas and functions are organized as shown below.

The following illustration is for explanation purpose only, and should not be referred to as an actual documentation.

8.2.4 Manual Reset Function

Standard

Heating-cooling

The position of the stable condition in P control or PD control can be shifted manually using this function. By shifting the proportional band (P), an offset (remaining deviation) is manually reset.

The offset is reset by determining and setting the amount to shift the value of the manipulated value (MV) in a stable condition from the reference value.

The reference value is 50% for standard control, and 0% for heating-cooling control.

Point

This function can be active only in P control and PD control. This function is inactive when integral time (I) is other than 0. CH1 CH2 Manual reset amount setting (Un/G724, Un/G740, Un/G756, Un/G772) is ignored even if it is set. (Note that a write data error (error code: 0003_{HE}) occurs if it is outside the setting range.)

(1) Standard control

The set value (SV) is set where the manipulated value (MV) is 50%. Due to this, as long as the temperature process value (PV) and the set value (SV) is not in equilibrium at 50% of manipulated value, an offset (remaining deviation) generates.

When an offset generates, the proportional band (P) can be manually shifted by the amount of the offset (remaining deviation).

Ex When using the manual reset function in the following conditions

- Control method: P control
- CH1 Manual reset amount setting (Un/G724, Un/G740, Un/G756, Un/G772): 300 (30%)

The Q64TCN shifts the manipulated value (MV) by which the temperature is stabilized at the set value (SV) from 50% to 80%.

137

These icons indicate modes that can be used.

Icon	Meaning
Common to all modes	
Common	This icon means that the buffer memory area or function can be used in both temperature control mode and temperature input mode.
Temperature control mode	This icon means that the buffer memory area or function for temperature control can be used in the standard control.
Standard	The buffer memory area and function can be used in the following control modes and channels: • CH1 to CH4 in the standard control • CH3 and CH4 in the mix control (normal mode) • CH3 and CH4 in the mix control (expanded mode)
Heating-cooling	This icon means that the buffer memory or function for temperature control can be used in the heating-cooling control.
	The buffer memory area and function can be used in the following control modes and channels: • CH1 and CH2 in the heating-cooling control (normal mode) • CH1 to CH4 in the heating-cooling control (expanded mode) • CH1 in the mix control (normal mode) • CH1 and CH2 in the mix control (expanded mode)
Temperature input mode	
Temperature Input	This icon means that the buffer memory area or function can be used in the temperature input mode.

TERMS

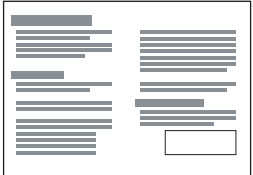
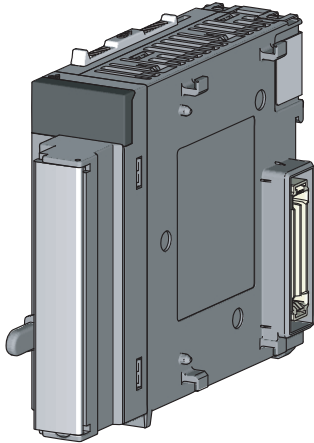
Unless otherwise specified, this manual uses the following terms.

Term	Description
L60TCTT4	The abbreviation for the L60TCTT4 temperature control module
L60TCTT4BW	The abbreviation for the L60TCTT4BW temperature control module with the disconnection detection function
L60TCRT4	The abbreviation for the L60TCRT4 temperature control module
L60TCRT4BW	The abbreviation for the L60TCRT4BW temperature control module with the disconnection detection function
L60TC4	A generic term for the L60TCTT4, L60TCTT4BW, L60TCRT4, and L60TCRT4BW
PID constants	A generic term for the proportional band (P), integral time (I), and derivative time (D)
Temperature sensor	A generic term for thermocouples and platinum resistance thermometers
Control method	A generic term for two-position control, P control, PI control, PD control, and PID control
Temperature input mode	The mode to use the L60TC4 as a temperature input module
Temperature control mode	The mode to use the L60TC4 as a temperature control module
Control mode	A generic term for the standard control, heating-cooling control (normal mode), heating-cooling control (expanded mode), mix control (normal mode), and mix control (expanded mode) when the L60TC4 is used in the temperature control mode
Fixed value action	The operating status of when the set value (SV) is fixed
Full scale	A full input range. For example, when the selected input range is -200.0°C to 400.0°C, the full scale is 600.0.
Ramp action	The operating status of when the set value (SV) is constantly changed
Number of loops	The number of feedback control systems (closed-loop control systems) that can be configured using one module. Under the standard control, one loop consists of one input and one output. Under the heating-cooling control, one loop consists of one input and two outputs.
CPU module	Another term for the MELSEC-L series CPU module
Head module	The abbreviation for the LJ72GF15-T2 CC-Link IE Field Network head module
Display unit	A liquid crystal display to be attached to the CPU module
External input	The abbreviation for input from connectors for external devices
External output	The abbreviation for output to connectors for external devices
Programming tool	A generic term for GX Works2 and GX Developer
GX Works2	The product name of the software package for the MELSEC programmable controllers
GX Developer	
Buffer memory	The memory of an intelligent function module used to store data (such as setting values and monitored values) for communication with a CPU module

PACKING LIST

The following items are included in the package of this product. Before use, check that all the items are included.

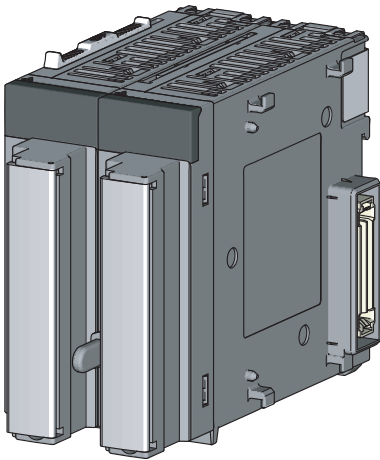
L60TCTT4, L60TCRT4



L60TCTT4, L60TCRT4

Before Using the Product

L60TCTT4BW, L60TCRT4BW



L60TCTT4BW, L60TCRT4BW

Before Using the Product

CHAPTER 1 WHAT CAN BE DONE WITH A TEMPERATURE CONTROL MODULE

1.1 Use

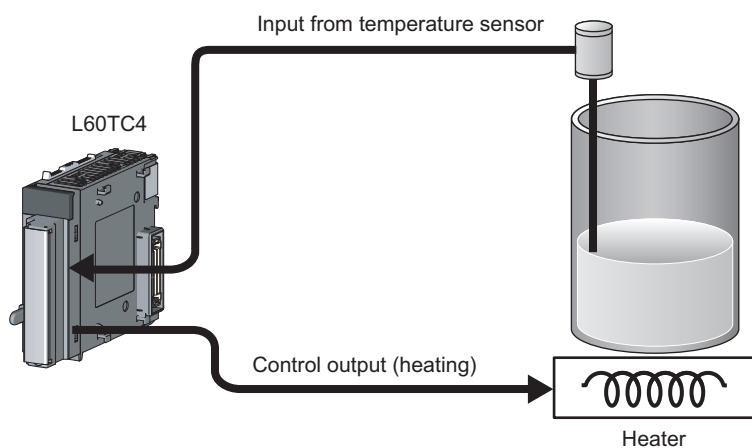
The L60TC4 performs PID operation to reach the target temperature based on input from an external temperature sensor. The module controls temperature by outputting the operation result to a heater or others in transistor output.

Point

The L60TCTT4BW and L60TCRT4BW are L60TCTT4 and L60TCRT4-based modules which possess an additional function to detect heater disconnection using input from external current sensors.

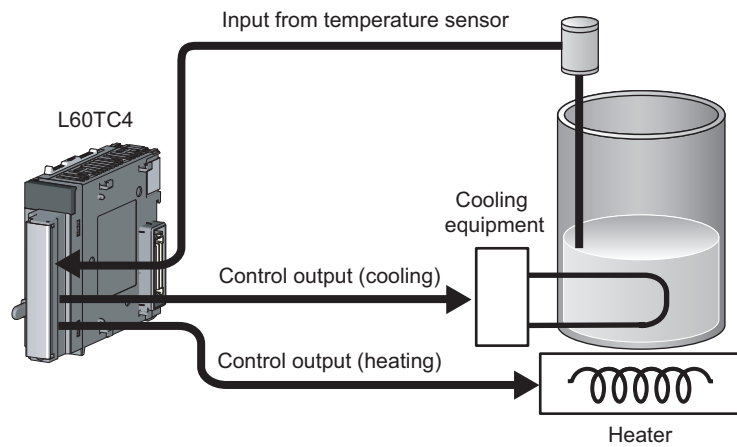
Ex. Standard control (heating)

The input from a temperature sensor is processed with PID operation, and the heater temperature is controlled.

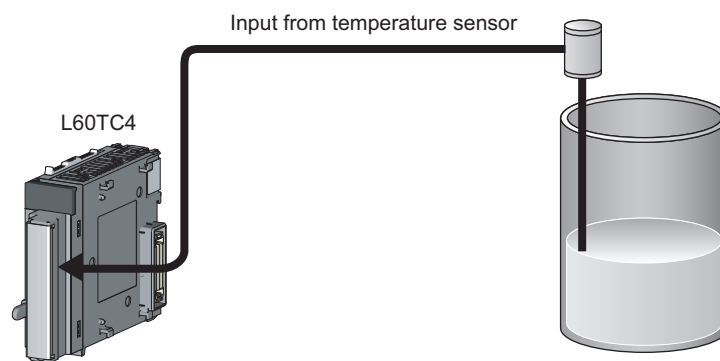


Ex. Heating-cooling control (heating and cooling)

Heating and cooling are processed when the target temperature is lower than the ambient temperature or when the temperature of the target subject is easy to change.

**Ex.** Temperature input (temperature input only)

The L60TC4 can be used as a temperature input module also.



1.2 Features

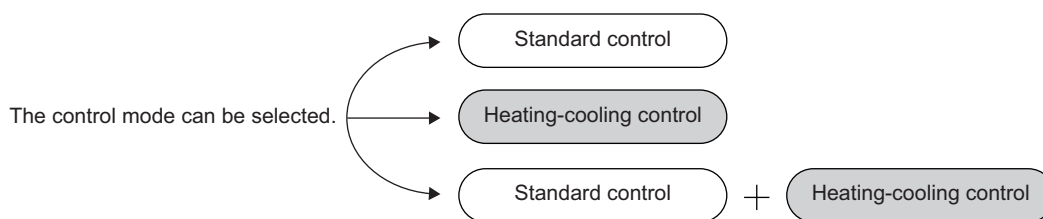
This section describes the L60TC4 features. For functions not described here, refer to the list of functions. (☞ Page 40, Section 3.3)

(1) Optimum temperature adjustment control (PID control)

- The L60TC4 performs temperature adjustment control automatically when the user simply sets PID constants necessary for PID operation: proportional band (P), integral time (I), derivative time (D), and temperature set value (SV). No special instruction is necessary to perform PID control.
- Using the auto tuning function or self-tuning function enables the PID constants to be set automatically by the L60TC4. Complicated PID operational expressions to determine PID constants are not necessary.

(2) Selection of control mode

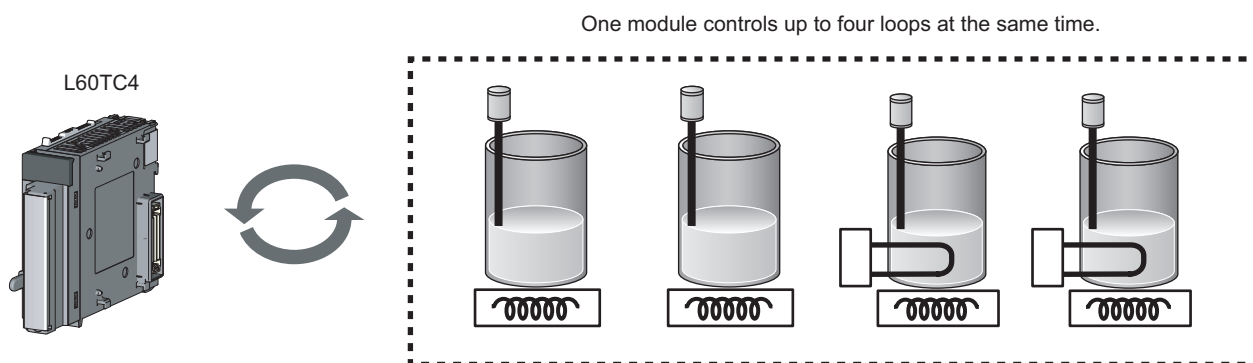
A control mode can be selected from the standard control (heating or cooling), heating-cooling control (heating and cooling), or mix control (combination of the standard control and heating-cooling control).



(3) Four loops on one module

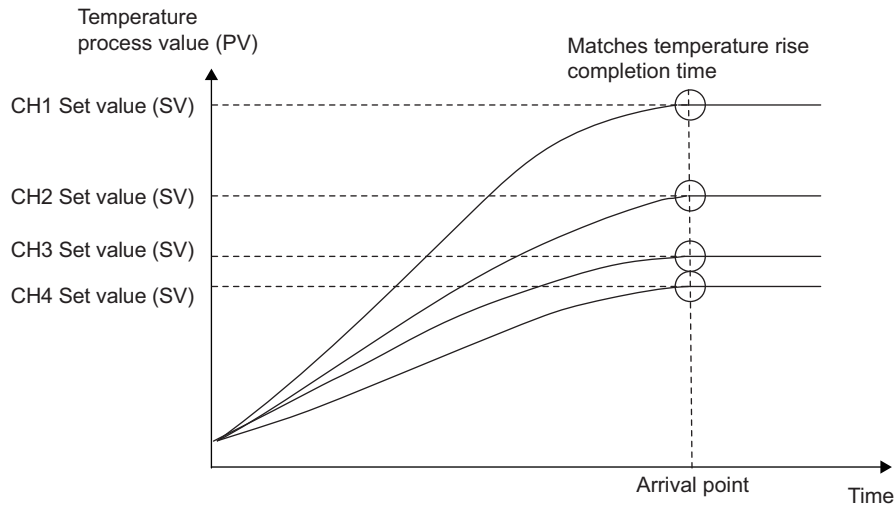
The maximum of four loops of temperature adjustment control can be performed simultaneously.

In addition, loop control can be performed using analog modules in the system; input from an A/D converter module or output to a D/A converter module can be processed.



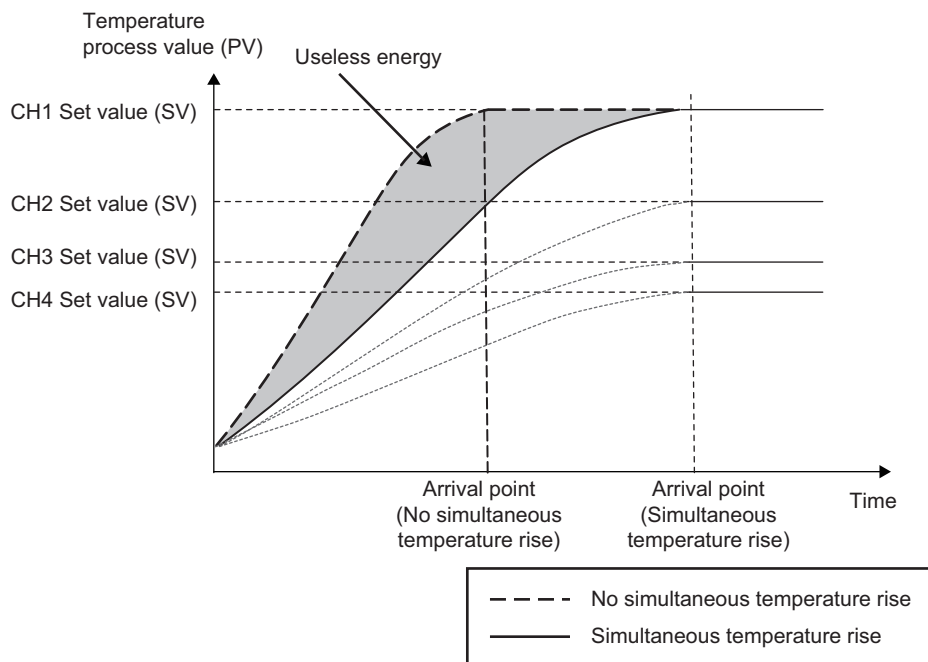
(4) Simultaneous temperature rise of multiple loops

Temperatures of multiple loops can be adjusted to simultaneously reach the set value of each; temperatures are controlled evenly without any partial heat exaggeration.



This function saves energy and cost.

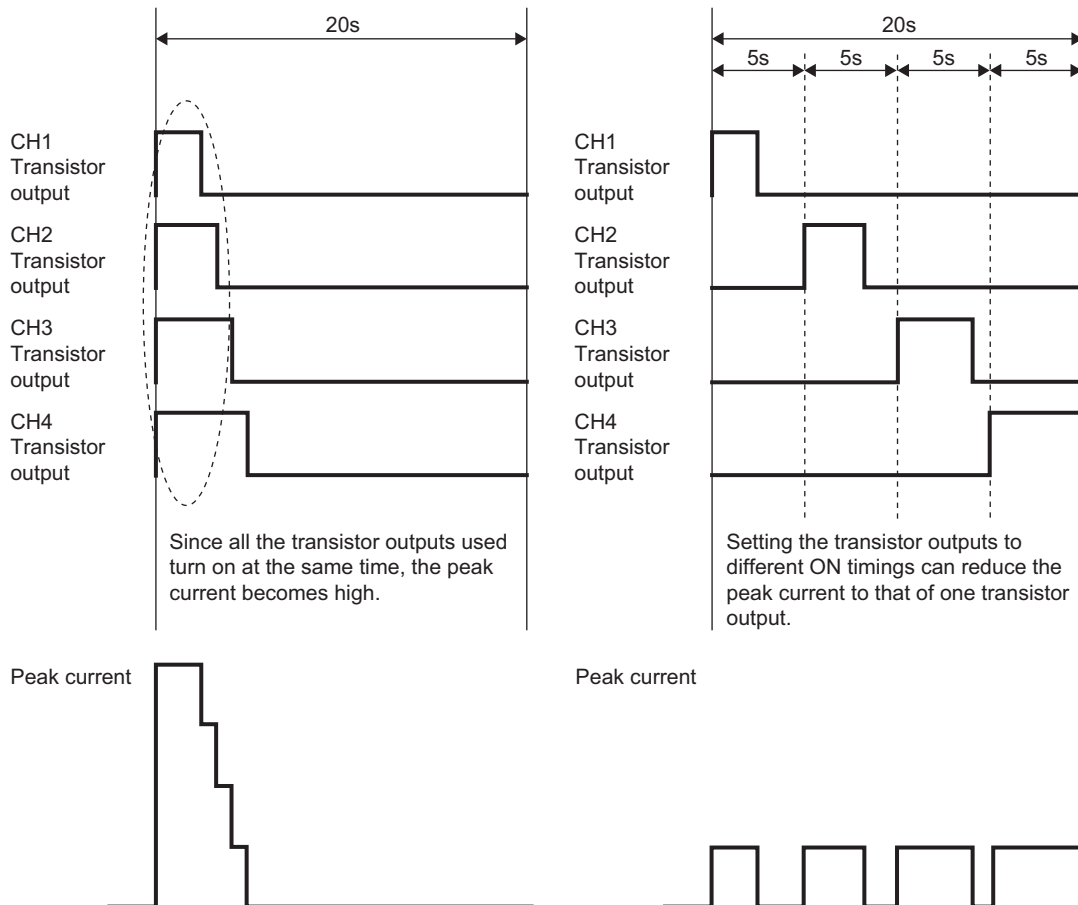
Ex. Comparison of temperature rises on CH1 when using and not using the simultaneous temperature rise function



(5) Suppression of peak current

Current flows into a heater can be suppressed by controlling output so that each channel's output does not turn on at the same time as other channels.

This function saves energy and cost.



(6) RFB limiter function

The RFB (Reset feed back) limiter suppresses overshoot which is liable to occur at a startup or when a temperature process value (PV) is increased.

(7) Correction of temperature process value (PV)

The difference between the temperature process value (PV) and actual temperature can be corrected easily using the following functions.

- Normal sensor correction (one-point correction) function: Corrects the difference by setting the rate of correction value to the full scale of the input range.
- Sensor two-point correction function: Corrects the difference based on the inclination of the line on the two points set in advance.
- Primary delay digital filter setting: Smoothens transient noise, and absorbs drastic change.

(8) Non-volatile memory for backing up set values

The set values in the buffer memory, such as the setting related to PID control, can be stored into a non-volatile memory for data backup. The values do not need to be reset after turning the power on from off or releasing the CPU module from its reset status.

Using the test function of the programming tool to write data directly to the buffer memory, the minimum sequence program required is "LD***" + "OUT Yn1".

(9) Detection of disconnection

Heater disconnection can be detected easily by the loop disconnection detection function.

The L60TCTT4BW and L60TCRT4BW can detect the disconnection of a heater accurately.

(10) Selectable sampling cycle

The module can be applied to wide range of systems since the sampling cycle can be selected from 250ms/4 channels or 500ms/4 channels.

(11) Use as a temperature input module

The L60TC4 can be used not only as a temperature control module, but also as a temperature input module. The mode can be switched easily by a setting.

In addition, The temperature input can be processed through the primary delay digital filter, or output as an alert.

( Page 120, Section 8.1)

(12) Easy setting by GX Works2

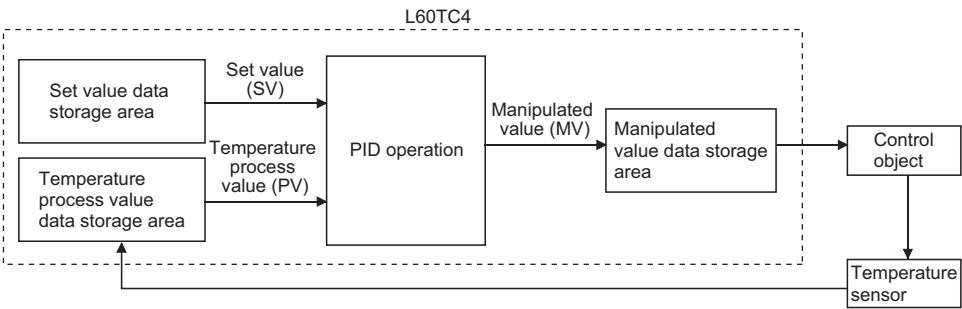
Sequence program can be reduced by configuring the default setting or auto refresh setting on the screen. Also, the setting status or operating status of the module can be checked easily.

1.3 The PID Control System

This section explains the PID control of the L60TC4.

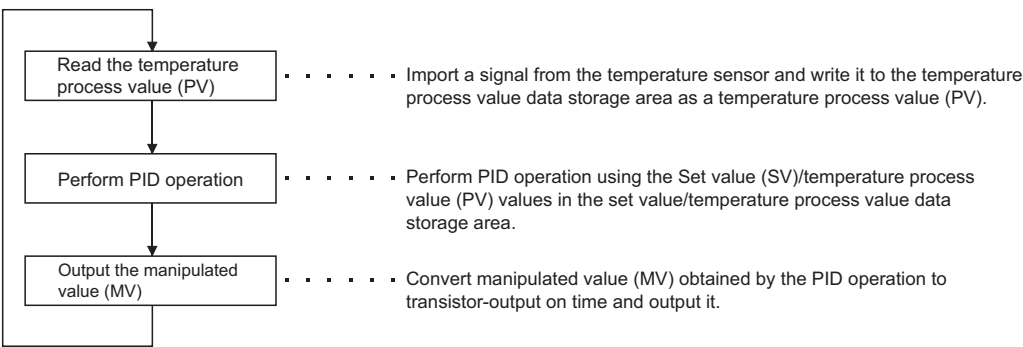
(1) PID control system

The following figure shows a system of when performing the PID control.



(2) PID control procedure

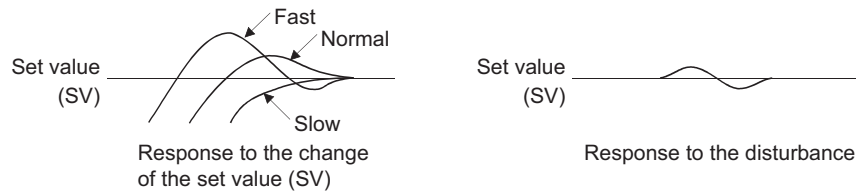
The PID control is performed in the following procedure.



(3) PID control (simple two-degree-of-freedom)

The L60TC4 operates in "simple two-degree-of-freedom". In this form of PID control, parameters are simplified compared to the two-degree-of-freedom PID control.

In the simple two-degree-of-freedom, the module controls the target subject using not only PID constants but also the control response parameter. The parameter can be set to "fast", "normal", or "slow". This setting enables the form of "response to the change of the set value (SV)" to change maintaining "response to the disturbance" in a good condition. (👉 Page 157, Section 8.2.8)



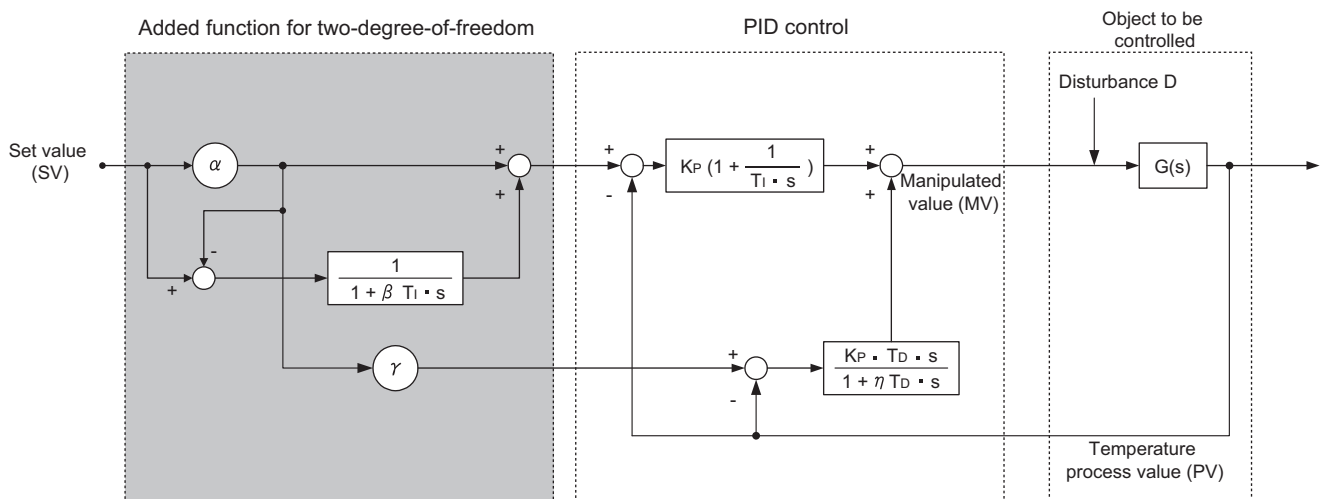
The following explains the difference between the one-degree-of-freedom PID control, two-degree-of-freedom PID control, and simple two-degree-of-freedom PID control.

(a) One-degree-of-freedom PID control and two-degree-of-freedom PID control

- General PID control is called one-degree-of freedom PID control. In the one-degree-of freedom PID control, when PID constants to improve "response to the change of the set value (SV)" are set, "response to the disturbance" degrades. Conversely, when PID constants to improve "response to the disturbance" are set, "response to the change of the set value (SV)" degrades.
- In the two-degree-of-freedom PID control, a manipulated value (MV) is determined considering the set value (SV) or variations. In this form of PID control, "response to the change of the set value (SV)" and "response to the disturbance" can be compatible with each other.

(b) Two-degree-of-freedom PID control and simple two-degree-of-freedom PID control

The following figure is a block diagram of the two-degree-of-freedom PID control.



By setting α , β , and γ above properly, optimum control can be achieved.

Note that required parameter settings increase and PID constants can hardly be auto-set by the auto tuning function for complete two-degree-of-freedom PID control. Therefore, the L60TC4 operates in the simple two-degree-of-freedom PID control for which parameters are simplified.

1.4 About the PID Operation

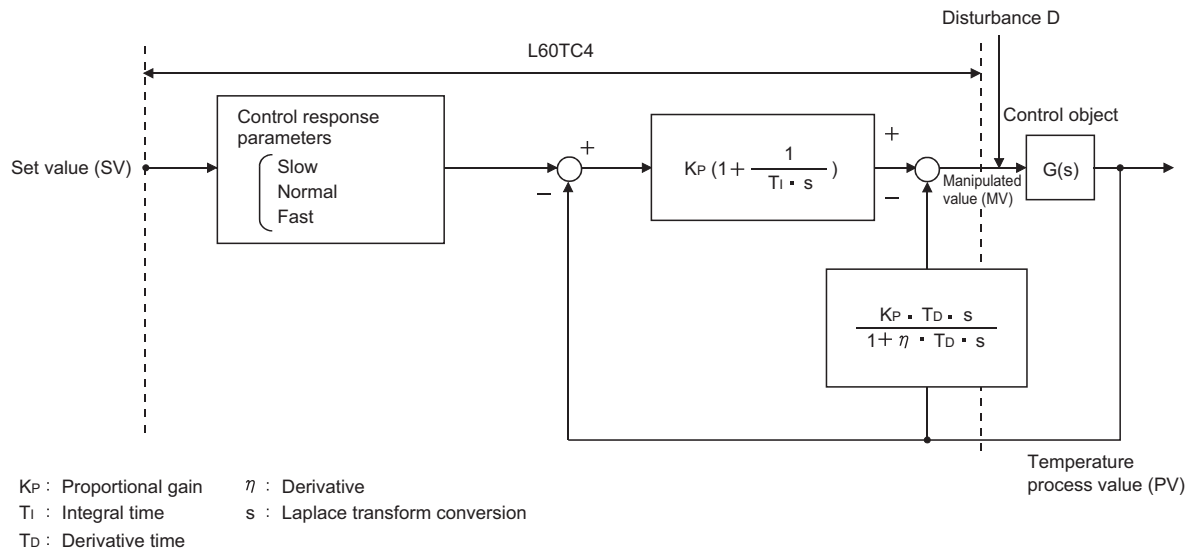
The L60TC4 can perform PID control in process-value incomplete derivation.

1.4.1 Operation method and formula

The PID control in process-value incomplete derivation is an operation method which puts a primary delay filter on input from a derivative action and eliminate high-frequency noise component in order to perform a PID operation on the deviation (E).

(1) Algorithm of PID control in process-value incomplete derivation

The algorithm of PID control in process-value incomplete derivation is shown below.



(2) Formula

The formula used for the L60TC4 is shown below.

$$MV_n = MV_{n-1} + \frac{T_D}{\tau + \eta \cdot T_D} \left\{ (PV_{n-1} - PV_n) - \frac{\tau}{T_D} \cdot MV_{n-1} \right\}$$

τ : Sampling cycle
 MV : Incomplete derivative output
 PV : Temperature process value (PV)
 T_D : Derivative time
 η : Derivative

Remark

The PID control in process-value derivation is an operation method which uses the process value (PV) for the derivation section in order to perform a PID operation. Not using deviation for the derivation section, drastic output change due to a derivative action is reduced when deviation varies along with the setting value change.

1.4.2 The L60TC4 actions

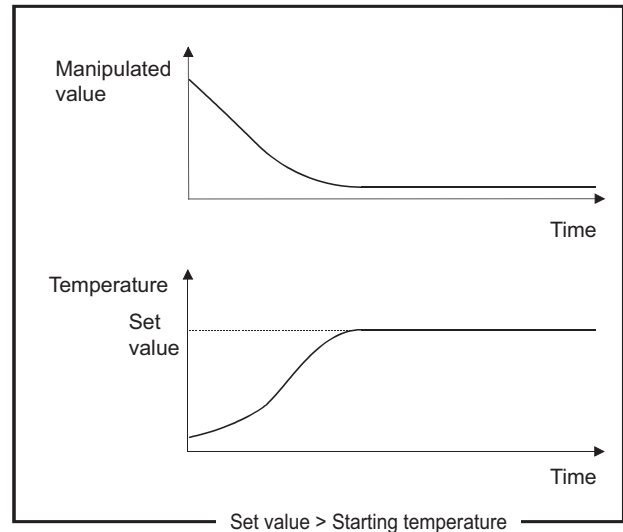
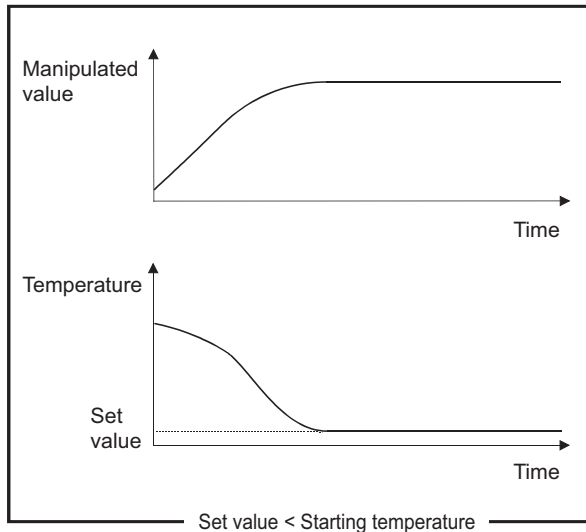
1

The L60TC4 performs PID operations in forward actions and reverse actions.

(1) Forward action

In a forward action, the manipulated value (MV) is increased when the temperature process value (PV) increases from the set value (SV).

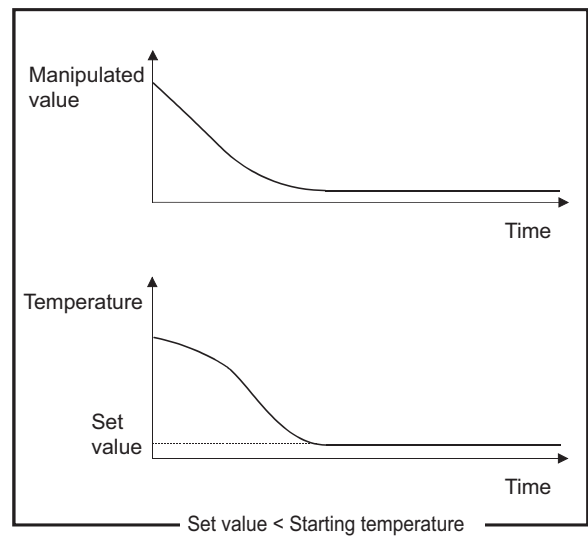
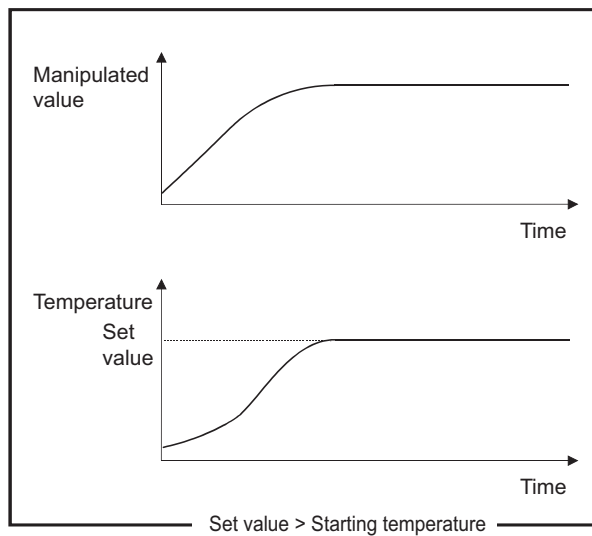
A forward action is used for cooling control.



(2) Reverse action

In a reverse action, the manipulated value is increased when the temperature process value (PV) decreases from the set value (SV).

A reverse action is used for heating control.



1.4.3 Proportional action (P-action)

A proportional action is an action to obtain the manipulated value (MV) proportional to the deviation (difference between the set value (SV) and the process value (PV)).

(1) Proportional gain

In a proportional action, the relationship between changes in the deviation (E) and the manipulated value can be expressed in the following formula:

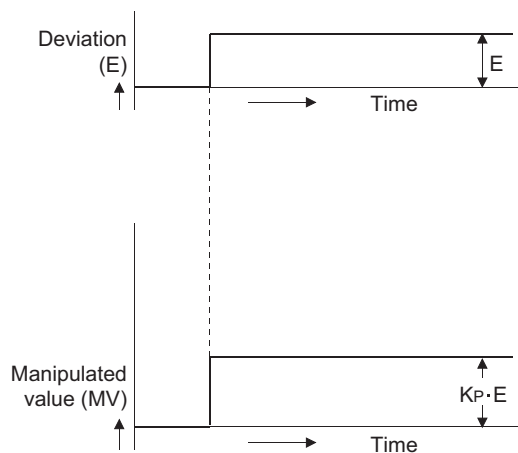
$$MV = K_P \cdot E$$

where K_P is a proportional constant and is called proportional gain. The manipulated value (MV) varies in the range from -5.0% to 105.0%.

The following table describes the difference of actions depending on the value of K_P , proportional gain.

Condition	Proportional action
K_P is a small value	The control action slows down.
K_P is a large value	The control action speeds up, though the temperature process value (PV) tends to fluctuate around the set value.

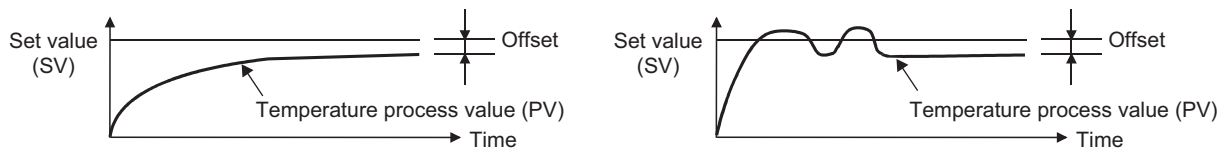
The following figure shows a proportional action of step responses where the deviation (E) is a fixed value.



(2) Offset

The certain amount of difference generates between the temperature process value (PV) and the set value (SV) is called an offset (remaining deviation).

In an proportional action, an offset (remaining deviation) generates.



1.4.4 Integral action (I-action)

1

An integral action is an action which continuously changes the manipulated value (MV) to eliminate the deviation (E) when there is any.

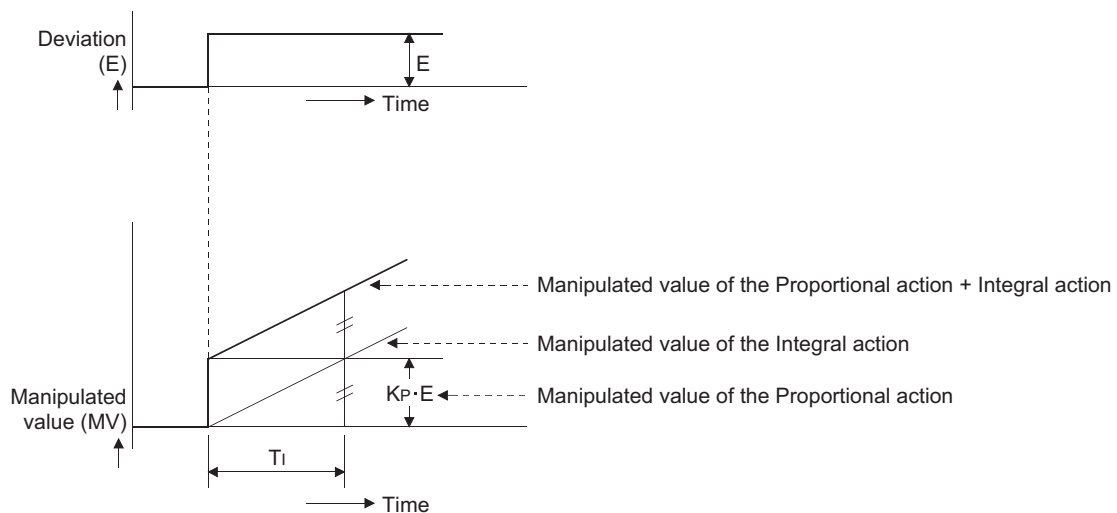
The offset caused by a proportional action can be eliminated.

In an integral action, the time from a deviation occurrence until when the manipulated value (MV) of the integral action becomes equals to that of the proportional action is called integral time, and is indicated as T_I .

The following table describes the difference of actions depending on the value of T_I , integral time.

Condition	Integral action
T_I is a small value	The integral effect gets large, and time to eliminate the offset gets short. Though, the temperature process value (PV) tends to fluctuate around the set value.
T_I is a large value	The integral effect gets small, and time to eliminate the offset gets long.

The following figure shows an integral action of step responses where the deviation (E) is a fixed value.



An integral action is used as a PI action in combination with a proportional action, or PID action in combination with a proportional and derivative actions.

An integral action cannot be used by itself.

1.4.5 Derivative action (D-action)

A derivative action adds the manipulated value (MV) proportional to the rate of change to eliminate the deviation (E) when it occurs.

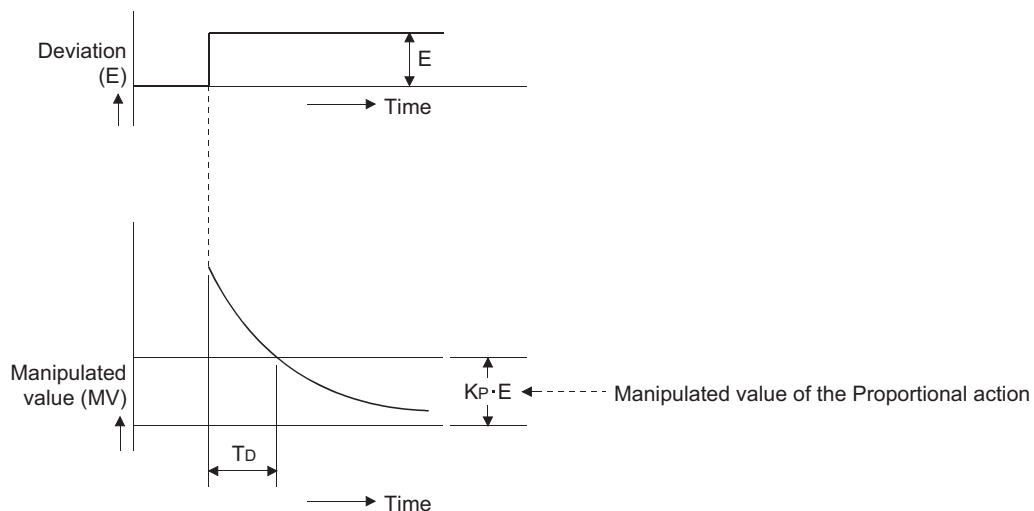
A derivative action can prevent the control target from changing significantly due to disturbance.

In a derivative action, the time from a deviation occurrence until when the manipulated value (MV) of the derivative action becomes equals to that of the proportional action is called derivative time, and is indicated as T_D .

The following table describes the difference of actions depending on the value of T_D , derivative time.

Condition	Derivative action
T_D is a small value	The derivative effect gets small.
T_D is a large value	The derivative effect gets large. Though, the temperature process value (PV) tends to fluctuate around the set value in short cycles.

The following figure shows a derivative action of step responses where the deviation (E) is a fixed value.



A derivative action is used as a PD action in combination with a proportional action, or PID action in combination with a proportional and integral actions.

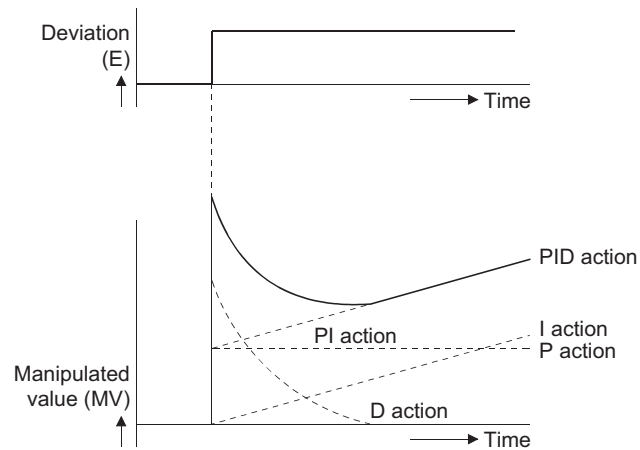
A derivative action cannot be used by itself.

1.4.6 PID action

1

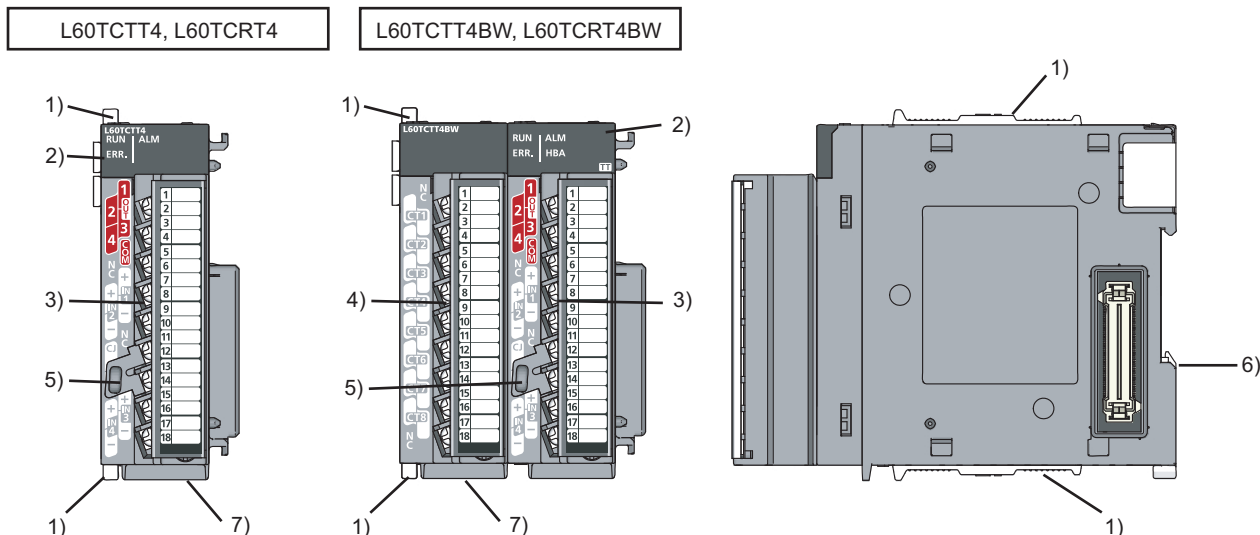
A PID action performs control using the manipulated value (MV) calculated by merging the proportional action, integral action, and derivative action.

The following figure shows a PID action of step responses where the deviation (E) is a fixed value.



CHAPTER 2 PART NAMES

The following table shows part names of the L60TC4.



Number	Name	Description
1)	Module joint levers	Levers for connecting modules
2)	RUN LED	Indicates the operating status of the L60TC4.
		On Operating normally
		Off - The power is not supplied. - The watchdog timer error has occurred. - CPU stop error has occurred when all channels are set to "CLEAR" on Switch Setting. - A value out of the setting range was set on Switch Setting 2 to 5.
	ERR. LED	Indicates the error status of the L60TC4.
		On Hardware fault (Including no connection of a cold junction temperature compensation resistor)
		Flashing Error occurring (☞ Page 344, Appendix 2 (1))
		Off Operating normally
	ALM LED	Indicates the alert status of the L60TC4.
		On Alert is occurring.
		Flashing - Temperature process value (PV) came out of temperature measurement range. - Loop disconnection was detected. - Temperature sensor is not connected.
		Off Alert is not occurring.
	HBA LED (the L60TCTT4BW and L60TCRT4BW only)	Indicates the heater disconnection detection status or the output off-time current error status of the L60TCTT4BW and L60TCRT4BW.
		On Either of the following is detected. - Heater disconnection - Output off-time current error
		Off Neither of the following is detected. - Heater disconnection - Output off-time current error

Number	Name	Description
3)	Terminal block for I/O	Used for temperature sensor input and transistor output. (☞ Page 87, Section 6.2)
4)	Terminal block for CT	Used for current sensor (CT) input.
5)	Cold junction temperature compensation resistor (the L60TCTT4 and L60TCTT4BW only)	Used when cold junction temperature compensation is executed for the L60TCTT4 and L60TCTT4BW.
6)	DIN rail hook	A hook used to mount the module to a DIN rail.
7)	Serial number plate	Displays the serial number printed on the rating plate. For the L60TCTT4BW, L60TCRT4BW, the serial number is displayed on the terminal block for CT.



CHAPTER 3 SPECIFICATIONS

This chapter describes general specifications, performance specifications, the function list, the I/O signal list, and the buffer memory list.

3.1 General Specifications

For the general specifications of the L60TC4, refer to the following.

 "Safety Guidelines", the manual supplied with a CPU module or head module

3.2 Performance Specifications

The following table lists the performance specifications of the L60TC4.

Item			Specifications			
			L60TCTT4	L60TCRT4	L60TCTT4BW	L60TCRT4BW
Control output			Transistor output			
Number of temperature input points			4 channels/module			
Type of usable temperature sensors, the temperature measurement range, the resolution, and the effect from wiring resistance of 1Ω			 Page 37, Section 3.2.2			
Accuracy*1	Indication accuracy	Ambient temperature: 25±5°C	Full scale × (±0.3%)			
		Ambient temperature: 0 to 55°C	Full scale × (±0.7%)			
	Cold junction temperature compensation accuracy: (ambient temperature: 0 to 55°C)	Temperature process value (PV): -100°C or more	Within ±1.0°C	—	Within ±1.0°C	—
		Temperature process value (PV): -150 to -100°C	Within ±2.0°C		Within ±2.0°C	
		Temperature process value (PV): -200 to -150°C	Within ±3.0°C		Within ±3.0°C	
	Sampling cycle			250ms/4 channels 500ms/4 channels		
Control output cycle			0.5 to 100.0s			
Input impedance			1MΩ			
Input filter			0 to 100s (0: Input filter OFF)			
Sensor correction value setting			-50.00 to 50.00%			
Operation at sensor input disconnection			Upscale processing			
Temperature control method			PID ON/OFF pulse or two-position control			
PID constants range		PID constants setting	Can be set by auto tuning.			
		Proportional band (P)	0.0 to 1000.0% (0: Two-position control)			
		Integral time (I)	0 to 3600s (set 0 for P control and PD control.)			
		Derivative time (D)	0 to 3600s (set 0 for P control and PI control.)			
Set value (SV) setting range			Within the temperature range set in the thermocouple/platinum resistance thermometer to be used			
Dead band setting range			0.1 to 10.0%			
Transistor output		Output signal	ON/OFF pulse			
		Rated load voltage	10 to 30VDC			
		Max. load current	0.1A/point, 0.4A/common			
		Max. inrush current	0.4A 10ms			
		Leakage current at OFF	0.1mA or less			
		Max. voltage drop at ON	1.0VDC (TYP) at 0.1A 2.5VDC (MAX) at 0.1A			
		Response time	OFF→ON: 2ms or less, ON→OFF: 2ms or less			
Number of accesses to non-volatile memory			Max. 10 ¹² times			
Insulation method			Between input terminal and programmable controller power supply: Transformer insulation Between input channels: Transformer insulation			

Item		Specifications			
		L60TCTT4	L60TCRT4	L60TCTT4BW	L60TCRT4BW
Dielectric withstand voltage		Between input terminal and programmable controller power supply: 500VAC for 1 minute Between input channels: 500VAC for 1 minute			
Insulation resistance		Between input terminal and programmable controller power supply: 500VDC 20MΩ or more Between input channels: 500VDC 20MΩ or more			
Heater disconnection detection specifications	Current sensor	—		👉 Page 84, Section 5.2 (4)	
	Input accuracy			Full scale × (±1.0%)	
	Number of alert delay			3 to 255	
Number of occupied I/O points		16 points (I/O assignment: 16 intelligent points)			
Number of occupied module		1		2	
Connected terminal		18-point terminal block		Two 18-point terminal blocks	
Applicable wire size		0.3mm ² to 0.75mm ²			
Applicable solderless terminal		R1.25-3 (Solderless terminal with sleeve is unavailable.)			
Internal current consumption		0.30A	0.31A	0.33A	0.35A
Weight		0.18kg		0.33kg	
Outline dimensions		28.5(W)mm × 90(H)mm × 117(D)mm		57.0(W)mm × 90(H)mm × 117(D)mm	

*1 Calculate the accuracy in the following method (only when it is not affected by noise).
Accuracy (°C) = full scale × indication accuracy + cold junction temperature compensation accuracy

Ex. Accuracy at the input range of 38 (−200.0 to 400.0°C), the operating ambient temperature of 35°C, and the temperature process value (PV) of 300°C

$$\begin{aligned}
 & (\text{Full scale}) \times (\text{indication accuracy}) + \text{cold junction temperature compensation accuracy} \\
 & = (400.0^{\circ}\text{C} - (-200.0^{\circ}\text{C})) \times (\pm 0.007) + (\pm 1.0^{\circ}\text{C}) \\
 & = \pm 5.2^{\circ}\text{C}
 \end{aligned}$$

For the noise immunity, dielectric withstand voltage, insulation resistance and others of the programmable controller system which uses the L60TC4, refer to the following.

 MELSEC-L CPU Module User's Manual (Hardware Design, Maintenance and Inspection)

 MELSEC-L CC-Link IE Field Network Head Module User's Manual

3.2.1 Number of parameters to be set

The total number of the parameters of the initial setting and of the auto refresh setting of the L60TC4 must be within the number of parameters which can be set in the CPU module including the number of other intelligent function module parameters.

For the maximum number of parameters which can be set in a CPU module (maximum number of set parameter), refer to the following.

 MELSEC-L CPU Module User's Manual (Hardware Design, Maintenance and Inspection)

 MELSEC-L CC-Link IE Field Network Head Module User's Manual

(1) Number of parameters of the L60TC4

The following table lists the number of parameters that can be set for one L60TC4.

Target module	Initial setting	Auto refresh setting	
		Normal mode	Setting item reduction mode
L60TCTT4	45	103 (Max.)	35 (Max.)
L60TCRT4			
L60TCTT4BW		115 (Max.)	36 (Max.)
L60TCRT4BW			

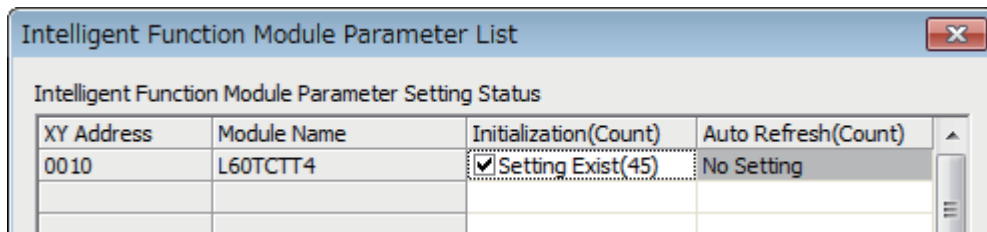
Number of parameters of the auto refresh setting can be reduced by changing the normal mode to the setting item reduction mode. For the setting item reduction mode, refer to the following:

 Page 116, Section 7.4

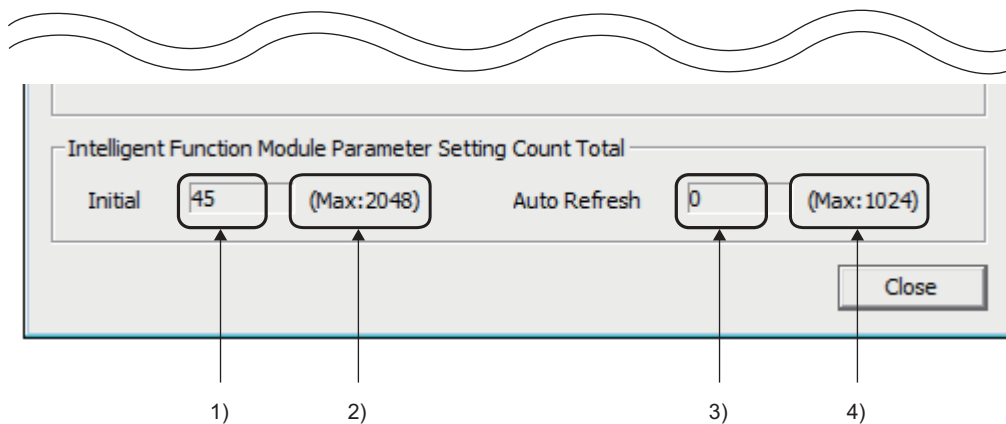
(2) Checking method

The current number and maximum number of the parameters set in the intelligent function module can be checked by the following operation.

- ☞ Project window ⇨ [Intelligent Function Module] ⇨ Right-click
- ⇨ [Intelligent Function Module Parameter List...]



XY Address	Module Name	Initialization(Count)	Auto Refresh(Count)
0010	L60TCTT4	Setting Exist(45)	No Setting



Intelligent Function Module Parameter Setting Count Total

Initial (Max:2048) Auto Refresh (Max:1024)

Close

1) 2) 3) 4)

No.	Description
1)	Total number of the parameters of the initial setting that is checked on the window
2)	Maximum number of parameters of the initial setting
3)	Total number of the parameters of the auto refresh setting that is checked on the window
4)	Maximum number of parameters of the auto refresh setting

3.2.2 Type of usable temperature sensors, temperature measurement range, resolution, and effect from wiring resistance of 1 ohm

This section describes the types of temperature sensors that can be used with the L60TC4, the temperature measurement range, the resolution, and the effect from wiring resistance of 1Ω.

Set the used temperature sensor in the following buffer memory area.

- CH□ Input range (Un\G32, Un\G64, Un\G96, Un\G128) (☞ Page 355, Appendix 2 (12))

(1) L60TCTT4, L60TCTT4BW

The following table lists the types of thermocouples that can be used with the L60TCTT4 and L60TCTT4BW, the temperature measurement range, the resolution, and the effect from wiring resistance of 1Ω.

Thermocouple type	°C			°F		
	Temperature measurement range	Resolution	Effect from wiring resistance of 1Ω (°C/Ω)*1	Temperature measurement range	Resolution	Effect from wiring resistance of 1Ω (°F/Ω)*1
R	0 to 1700	1	0.030	0 to 3000	1	0.054
K	0 to 500 0 to 800 0 to 1300	1	0.005	0 to 1000 0 to 2400	1	0.008
	-200.0 to 1300.0 -200.0 to 400.0 0.0 to 400.0 0.0 to 500.0 0.0 to 800.0	0.1		0.0 to 1000.0	0.1	
J	0 to 500 0 to 800 0 to 1200	1	0.003	0 to 1000 0 to 1600 0 to 2100	1	0.006
	-200.0 to 1000.0 0.0 to 400.0 0.0 to 500.0 0.0 to 800.0	0.1		0.0 to 1000.0	0.1	
T	-200 to 400 -200 to 200 0 to 200 0 to 400	1	0.004	0 to 700 -300 to 400	1	0.008
	-200.0 to 400.0 0.0 to 400.0	0.1		0.0 to 700.0	0.1	
S	0 to 1700	1	0.030	0 to 3000	1	0.054
B	0 to 1800*2	1	0.038	0 to 3000*2	1	0.068
E	0 to 400 0 to 1000	1	0.003	0 to 1800	1	0.005
	-200.0 to 1000.0 0.0 to 700.0	0.1		—	—	—
N	0 to 1300	1	0.006	0 to 2300	1	0.011
	0.0 to 1000.0	0.1		—	—	—
U	0 to 400 -200 to 200	1	0.004	0 to 700 -300 to 400	1	0.009
	0.0 to 600.0	0.1		—	—	—

Thermocouple type	°C			°F		
	Temperature measurement range	Resolution	Effect from wiring resistance of 1Ω (°C/Ω)*1	Temperature measurement range	Resolution	Effect from wiring resistance of 1Ω (°F/Ω)*1
L	0 to 400 0 to 900	1	0.003	0 to 800 0 to 1600	1	0.006
	0.0 to 400.0 0.0 to 900.0	0.1		—	—	—
PLII	0 to 1200	1	0.005	0 to 2300	1	0.010
W5Re/W26Re	0 to 2300	1	0.017	0 to 3000	1	0.021

*1 Means temperature error per Ω of wiring resistance of the thermocouple. The error varies depending on measured temperature or ambient temperature. The temperature error can be corrected by the sensor correction function.

(☞ Page 230, Section 8.3.3)

*2 While temperature can be measured within less than 400°C/800°F, the accuracy cannot be guaranteed.

(2) L60TCRT4, L60TCRT4BW

The following table lists the types of platinum resistance thermometer that can be used with the L60TCRT4 and L60TCRT4BW and temperature measurement range.

Platinum resistance thermometer type	°C		°F	
	Temperature measurement range	Resolution	Temperature measurement range	Resolution
Pt100	-200.0 to 850.0	0.1	-300 to 1100	1
	-200.0 to 600.0		-300.0 to 300.0	0.1
	-200.0 to 200.0			
JPt100	-200.0 to 640.0	0.1	-300 to 900	1
	-200.0 to 500.0		-300.0 to 300.0	0.1
	-200.0 to 200.0			

3.2.3 Sampling cycle and control output cycle

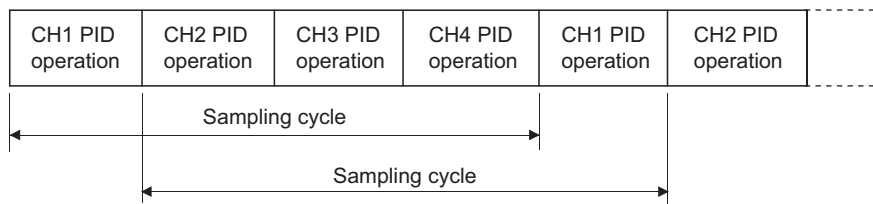
This section describes the sampling cycle and control output cycle of the L60TC4.

(1) Sampling cycle

The L60TC4 performs PID operations in the order of CH1, CH2, CH3, CH4, CH1, CH2

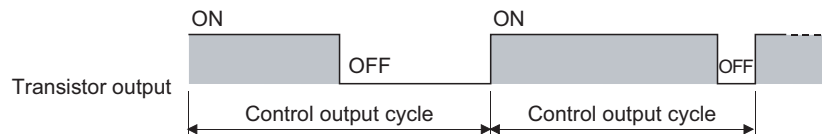
The time from when PID operation is started on the current channel (CHn) until PID operation is restarted on the current channel (CHn) is called a sampling cycle. Select 250ms or 500ms as a sampling cycle. (☞ Page 110, Section 7.2 (1))

The number of used channels and the settings of unused channels do not affect the sampling cycle.



(2) Control output cycle

The control output cycle is the ON/OFF cycle of transistor output.



The manipulated value (MV) represents the ON time of the control output cycle in percentage. (☞ Page 349, Appendix 2 (5))

Set the control output cycle in the following buffer memory areas in the range of 1 to 100s (or 0.5 to 100.0s).

- CH□ Control output cycle setting (Un\G47, Un\G79, Un\G111, Un\G143) (☞ Page 373, Appendix 2 (23))

In the heating-cooling control, the following buffer memory areas are used for the manipulated value (MV) and control output cycle.

Data type	Buffer memory area name	Buffer memory address				Reference
		CH1	CH2	CH3	CH4	
Manipulated value (MV)	Manipulated value for heating (MVh)	Un\G13	Un\G14	Un\G15	Un\G16	Page 349, Appendix 2 (5)
	Manipulated value for cooling (MVc)	Un\G704	Un\G705	Un\G706	Un\G707	
Control output cycle	Heating control output cycle setting	Un\G47	Un\G79	Un\G111	Un\G143	Page 373, Appendix 2 (23)
	Cooling control output cycle setting	Un\G722	Un\G738	Un\G754	Un\G770	

3.3 Function List

This section lists the L60TC4 functions.

(1) When the L60TC4 is used as a temperature input module

Item	Description	Reference
Conversion enable/disable function	Whether to enable or disable the temperature conversion can be set for each channel.	Page 121, Section 8.1.1
Temperature conversion method	The measured temperature by each sampling cycle is stored in the buffer memory. The temperature process values (PV) can be smoothed and sudden changes can be controlled by using the primary delay filter.	Page 121, Section 8.1.2
Alert output function	An alert is output if the temperature process value (PV) meets the condition set in advance. The alert has process alarm and rate alarm.	Page 124, Section 8.1.3

(2) When the L60TC4 is used as a temperature control module

○: Enable, ×: Disable

Item	Description	Enable or disable		Reference
		Standard control	Heating-cooling control	
Control mode selection function	The control mode can be selected from the following modes. • Standard control • Heating-cooling control (normal mode) • Heating-cooling control (expanded mode) • Mix control (normal mode) • Mix control (expanded mode)	○	○	Page 130, Section 8.2.1
Control output setting at CPU stop error	Whether to clear or hold the transistor output status when a CPU stop error occurs or when a CPU module is turned from RUN to STOP can be selected.	○	○	Page 132, Section 8.2.2
Control method	The following control methods can be used with the settings of proportional band (P), integral time (I), and derivative time (D). • Two-position control • P control • PI control • PD control • PID control	○	○	Page 133, Section 8.2.3
Manual reset function	The stable status position in the P control or PD control can be moved manually.	○	○	Page 141, Section 8.2.4
Manual control	The manipulated value (MV) can be set manually by users without automatic calculation by the PID control.	○	○	Page 143, Section 8.2.5
Control output cycle unit selection function	The unit for control output cycle can be selected from 1s or 0.1s and switched between them. Setting the control output cycle to 0.1s allows a more detailed control to be performed.	○	○	Page 144, Section 8.2.6
Auto tuning function	The L60TC4 sets the optimal PID constants automatically.	○	○	Page 145, Section 8.2.7
Simple two-degree-of-freedom	In addition to the PID control, the response speed toward the change of the set value (SV) can be selected from three levels. The simple two-degree-of-freedom PID control can be realized.	○	○	Page 157, Section 8.2.8

Item	Description	Enable or disable		Reference
		Standard control	Heating-cooling control	
Derivative action selection function	Dynamic performance can be improved by selecting the suitable derivative action for the fixed value action and the ramp action.	○	○	Page 158, Section 8.2.9
Setting change rate limiter setting function	Change rate setting of the set value (SV) per set time unit when this value is changed. The batch setting or individual setting can be selected for the temperature rise and drop.	○	○	Page 159, Section 8.2.10
Alert function	The modules goes to the alert status when the temperature process value (PV) or deviation (E) meets the condition set in advance.	○	○	Page 161, Section 8.2.11
RFB limiter function	When the deviation (E) continues for a long time, the PID operation result (manipulated value (MV)) by the integral action can be prevented from exceeding the effective range of the manipulated value (MV).	○	○	Page 175, Section 8.2.12
Input/output (with another analog module) function	Data can be input and output using another analog module (A/D conversion module or D/A converter module) on the system.	○	○	Page 176, Section 8.2.13
ON delay output function	Setting with considering delay time (response/scan time delay) of actual transistor output is possible.	○	○	Page 178, Section 8.2.14
Self-tuning function	The L60TC4 monitors the control status constantly. If the control system oscillates due to a status soon after the control starts, a change of the set value (SV), and property fluctuation of a controlled object, PID constants are changed automatically.	○	×	Page 179, Section 8.2.15
Peak current suppression function	Changing automatically the upper limit output limiter value of each channel and dividing the timing of transistor output can suppress the peak current.	○	×	Page 189, Section 8.2.16
Simultaneous temperature rise function	This function allows several loops to reach the set value (SV) at the same time.	○	×	Page 194, Section 8.2.17
Forward/reverse action selection function	Whether to perform PID operations in the forward action or reverse action can be selected.	○	×	Page 207, Section 8.2.18
Loop disconnection detection function	Errors in the control system (control loop) can be detected.	○	×	Page 208, Section 8.2.19
During AT loop disconnection detection function	A loop disconnection can be detected during auto tuning (AT).	○	×	Page 210, Section 8.2.20
Proportional band setting function	The proportional band (P) can be individually set for heating or cooling.	×	○	Page 212, Section 8.2.21
Cooling method setting function	When the auto tuning is executed, an auto tuning formula is automatically selected according to the selected cooling method and the operation starts.	×	○	Page 213, Section 8.2.22
Overlap/dead band function	By changing the temperature where the cooling transistor output is started, whether control stability is prioritized or energy saving is prioritized can be selected.	×	○	Page 215, Section 8.2.23
Temperature conversion function (using unused channels)	In heating-cooling control (normal mode) and mix control (normal mode), only temperature measurement is allowed by using unused temperature input terminals.	×	○	Page 218, Section 8.2.24
Heater disconnection detection function	The current which flows in the heater main circuit can be measured and disconnections can be detected.	○	○	Page 221, Section 8.2.25
Output off-time current error detection function	An error of when the transistor output is off can be detected.	○	○	Page 226, Section 8.2.26

(3) Common functions

Item	Description	Reference
Moving averaging process to a temperature process value (PV)	Moving averaging process can be set to a temperature process value (PV). With this function, the fluctuation of temperature process values (PV) can be reduced in electrically noisy environments or in the environments where temperature process values (PV) fluctuate greatly. The moving averaging process can be disabled to hasten the response to the change of temperature process values (PV).	Page 227, Section 8.3.1
Temperature process value (PV) scaling function	The temperature process value (PV) can be converted to the set width and this value can be imported into the buffer memory.	Page 228, Section 8.3.2
Sensor correction function	If a difference between a temperature process value (PV) and an actual temperature occurs due to the measurement status, the error can be corrected. Select a correction method from the following two types. • Normal sensor correction (one-point correction) function: The percentage of the full scale of the set input range can be corrected as an error corrected value. • Sensor two-point correction function: An error is corrected by setting any two points (corrected offset value and corrected gain value).	Page 230, Section 8.3.3
Auto-setting at input range change	When the input range is changed, the related buffer memory data is changed automatically so that errors outside the setting range does not occur.	Page 241, Section 8.3.4
Buffer memory data backup function	A set value in a buffer memory area can be backed up in the non-volatile memory. Because the backed up value is restored at the next startup of the module, an initial setting program is not required once this function is executed.	Page 242, Section 8.3.5
Error history function	Up to 16 errors and alarms that occur on the L60TC4 are stored in the buffer memory as history.	Page 244, Section 8.3.6
Module error history collection function	Error contents can be notified to the CPU module when errors and alarms occur on the L60TC4. Error information is held in the memory inside of the CPU module as module error history.	Page 246, Section 8.3.7
Error clear function	When an error occurs, the error can be cleared on the system monitor.	Page 247, Section 8.3.8

3.4 I/O Signal List

This section describes the assignment and applications of the L60TC4 input signals.

(1) Input signal list

Input signal (signal direction: CPU module ← L60TC4)				
Device No.	Temperature input mode	Standard control	Heating-cooling control	Mix control
Xn0	Module READY flag	Module READY flag	Module READY flag	Module READY flag
Xn1	Setting/operation mode status	Setting/operation mode status	Setting/operation mode status	Setting/operation mode status
Xn2	Error occurrence flag	Error occurrence flag	Error occurrence flag	Error occurrence flag
Xn3	Hardware error flag	Hardware error flag	Hardware error flag	Hardware error flag
Xn4	N/A	CH1 Auto tuning status	CH1 Auto tuning status	CH1 Auto tuning status
Xn5	N/A	CH2 Auto tuning status	CH2 Auto tuning status	CH2 Auto tuning status ^{*2}
Xn6	N/A	CH3 Auto tuning status	CH3 Auto tuning status ^{*1}	CH3 Auto tuning status
Xn7	N/A	CH4 Auto tuning status	CH4 Auto tuning status ^{*1}	CH4 Auto tuning status
Xn8	Back-up of the set value completion flag	Back-up of the set value completion flag	Back-up of the set value completion flag	Back-up of the set value completion flag
Xn9	Default value write completion flag	Default value write completion flag	Default value write completion flag	Default value write completion flag
XnA	Back-up of the set value fail flag	Back-up of the set value fail flag	Back-up of the set value fail flag	Back-up of the set value fail flag
XnB	Setting change completion flag	Setting change completion flag	Setting change completion flag	Setting change completion flag
XnC	CH1 Alert occurrence flag	CH1 Alert occurrence flag	CH1 Alert occurrence flag	CH1 Alert occurrence flag
XnD	CH2 Alert occurrence flag	CH2 Alert occurrence flag	CH2 Alert occurrence flag	CH2 Alert occurrence flag
XnE	CH3 Alert occurrence flag	CH3 Alert occurrence flag	CH3 Alert occurrence flag	CH3 Alert occurrence flag
XnF	CH4 Alert occurrence flag	CH4 Alert occurrence flag	CH4 Alert occurrence flag	CH4 Alert occurrence flag

*1 Available only under the heating-cooling control (expanded mode). For details on the expanded mode, refer to  Page 131, Section 8.2.1 (3).

*2 Available only under the mix control (expanded mode). For details on the expanded mode, refer to  Page 131, Section 8.2.1 (3).

(2) Output signal list

Output signal (signal direction: CPU module → L60TC4)				
Device No.	Temperature input mode	Standard control	Heating-cooling control	Mix control
Yn0	N/A	N/A	N/A	N/A
Yn1	Setting/operation mode status	Setting/operation mode instruction	Setting/operation mode instruction	Setting/operation mode instruction
Yn2	Error reset instruction	Error reset instruction	Error reset instruction	Error reset instruction
Yn3	N/A	N/A	N/A	N/A
Yn4	N/A	CH1 Auto tuning instruction	CH1 Auto tuning instruction	CH1 Auto tuning instruction
Yn5	N/A	CH2 Auto tuning instruction	CH2 Auto tuning instruction	CH2 Auto tuning instruction ^{*2}
Yn6	N/A	CH3 Auto tuning instruction	CH3 Auto tuning instruction ^{*1}	CH3 Auto tuning instruction
Yn7	N/A	CH4 Auto tuning instruction	CH4 Auto tuning instruction ^{*1}	CH4 Auto tuning instruction
Yn8	Set value backup instruction	Set value backup instruction	Set value backup instruction	Set value backup instruction
Yn9	Default setting registration instruction	Default setting registration instruction	Default setting registration instruction	Default setting registration instruction
YnA	N/A	N/A	N/A	N/A
YnB	Setting change instruction	Setting change instruction	Setting change instruction	Setting change instruction
YnC	N/A	CH1 PID control forced stop instruction	CH1 PID control forced stop instruction	CH1 PID control forced stop instruction
YnD	N/A	CH2 PID control forced stop instruction	CH2 PID control forced stop instruction	CH2 PID control forced stop instruction ^{*2}
YnE	N/A	CH3 PID control forced stop instruction	CH3 PID control forced stop instruction ^{*1}	CH3 PID control forced stop instruction
YnF	N/A	CH4 PID control forced stop instruction	CH4 PID control forced stop instruction ^{*1}	CH4 PID control forced stop instruction

*1 Available only under the heating-cooling control (expanded mode). For details on the expanded mode, refer to  Page 131, Section 8.2.1 (3).

*2 Available only under the mix control (expanded mode). For details on the expanded mode, refer to  Page 131, Section 8.2.1 (3).

Point

The functions of the L60TC4 cannot be guaranteed if any of the unavailable areas is turned on/off in a program.

3.5 Buffer Memory List

This section lists the L60TC4 buffer memory areas.

For details on the buffer memory, refer to  Page 344, Appendix 2.

Point

Do not write data in the system area or the write-protect area in a program in the buffer memory. Doing so may cause malfunction.

3

(1) Buffer memory address by mode

This section describes the buffer memory assignments by mode.

For details on the modes, refer to  Page 120, Section 8.1, Page 130, Section 8.2.1.

Point

Depending on the control mode, some channels cannot be used for control under the temperature control mode.

The channels which cannot be used for control are the following.

- For heating-cooling control (normal mode): CH3, CH4
- For mix control (normal mode): CH2

The channels which cannot be used for control can be used only for temperature input. For details, refer to

 Page 218, Section 8.2.24.

(a) In the temperature input mode

○: Enable, ×: Disable

Address (decimal (hexadecimal))	Target channel	Setting contents	Default value ^{*1}	Read/Write ^{*2}	Automatic setting ^{*3}	Non-volatile memory write availability ^{*4}	Reference
		Temperature input mode					
0(0 _H)	All CHs	Error code	0	R	×	×	Page 344, Appendix 2 (1)
1(1 _H)	CH1	Decimal point position	0(TT) 1(RT) ^{*5}	R	×	×	Page 344, Appendix 2 (2)
2(2 _H)	CH2	Decimal point position					
3(3 _H)	CH3	Decimal point position					
4(4 _H)	CH4	Decimal point position					
5(5 _H)	CH1	Alert definition	0	R	×	×	Page 346, Appendix 2 (3)
6(6 _H)	CH2	Alert definition					
7(7 _H)	CH3	Alert definition					
8(8 _H)	CH4	Alert definition					
9(9 _H)	CH1	Temperature process value (PV)	0	R	×	×	Page 348, Appendix 2 (4)
10(A _H)	CH2	Temperature process value (PV)					
11(B _H)	CH3	Temperature process value (PV)					
12(C _H)	CH4	Temperature process value (PV)					
13(D _H) to 28(1C _H)	—	System area	—	—	—	—	—
29(1D _H)	All CHs	Cold junction temperature process value ^{*6}	0	R	×	×	Page 352, Appendix 2 (9)
30(1E _H)	All CHs	System area	—	—	—	—	—
31(1F _H)	All CHs	System area	—	—	—	—	—
32(20 _H)	CH1	Input range ^{*7}	2(TT) 7(RT) ^{*5}	R/W	×	○	Page 355, Appendix 2 (12)
33(21 _H) to 44(2C _H)	—	System area	—	—	—	—	—
45(2D _H)	CH1	Sensor correction value setting	0	R/W	×	○	Page 372, Appendix 2 (21)
46(2E _H)	—	System area	—	—	—	—	—
47(2F _H)	—	System area	—	—	—	—	—
48(30 _H)	CH1	Primary delay digital filter setting	0	R/W	×	○	Page 374, Appendix 2 (24)
49(31 _H) to 63(3F _H)	—	System area	—	—	—	—	—
64(40 _H)	CH2	Input range ^{*7}	2(TT) 7(RT) ^{*5}	R/W	×	○	Page 355, Appendix 2 (12)
65(41 _H) to 76(4C _H)	—	System area	—	—	—	—	—

Address (decimal (hexadecimal))	Target channel	Setting contents	Default value ^{*1}	Read/Write ^{*2}	Automatic setting ^{*3}	Non-volatile memory write availability ^{*4}	Reference
		Temperature input mode					
77(4D _H)	CH2	Sensor correction value setting	0	R/W	×	○	Page 372, Appendix 2 (21)
78(4E _H)	CH2	System area	—	—	—	—	—
79(4F _H)	CH2	System area	—	—	—	—	—
80(50 _H)	CH2	Primary delay digital filter setting	0	R/W	×	○	Page 374, Appendix 2 (24)
81(51 _H) to 95(5F _H)	—	System area	—	—	—	—	—
96(60 _H)	CH3	Input range ^{*7}	2(TT) 7(RT) ^{*5}	R/W	×	○	Page 355, Appendix 2 (12)
97(61 _H) to 108(6C _H)	—	System area	—	—	—	—	—
109(6D _H)	CH3	Sensor correction value setting	0	R/W	×	○	Page 372, Appendix 2 (21)
110(6E _H)	CH3	System area	—	—	—	—	—
111(6F _H)	CH3	System area	—	—	—	—	—
112(70 _H)	CH3	Primary delay digital filter setting	0	R/W	×	○	Page 374, Appendix 2 (24)
113(71 _H) to 127(7F _H)	—	System area	—	—	—	—	—
128(80 _H)	CH4	Input range ^{*7}	2(TT) 7(RT) ^{*5}	R/W	×	○	Page 355, Appendix 2 (12)
129(81 _H) to 140(8C _H)	—	System area	—	—	—	—	—
141(8D _H)	CH4	Sensor correction value setting	0	R/W	×	○	Page 372, Appendix 2 (21)
142(8E _H)	CH4	System area	—	—	—	—	—
143(8F _H)	CH4	System area	—	—	—	—	—
144(90 _H)	CH4	Primary delay digital filter setting	0	R/W	×	○	Page 374, Appendix 2 (24)
145(91 _H) to 181(B5 _H)	—	System area	—	—	—	—	—
182(B6 _H)	All	Cold junction temperature compensation selection ^{*6}	0	R/W	×	○	Page 393, Appendix 2 (49)
183(B7 _H)	All	Control switching monitor	0	R	×	×	Page 394, Appendix 2 (50)
184(B8 _H) to 195(C3 _H)	—	System area	—	—	—	—	—
196(C4 _H)	CH1	Process alarm alert output enable/disable setting ^{*7}	1	R/W	×	○	Page 396, Appendix 2 (53)

Address (decimal (hexadecimal))	Target channel	Setting contents	Default value *1	Read/Write *2	Automatic setting *3	Non-volatile memory write availability *4	Reference
		Temperature input mode					
197(C5 _H)	CH1	Process alarm lower lower limit value *7	0(TT) –2000(RT) *5	R/W	○	○	Page 397, Appendix 2 (54)
198(C6 _H)	CH1	Process alarm lower upper limit value *7	0(TT) –2000(RT) *5	R/W	○	○	
199(C7 _H)	CH1	Process alarm upper lower limit value *7	1300(TT) 6000(RT) *5	R/W	○	○	
200(C8 _H)	CH1	Process alarm upper upper limit value *7	1300(TT) 6000(RT) *5	R/W	○	○	
201(C9 _H)	CH1	Rate alarm alert output enable/disable setting *7	1	R/W	×	○	Page 398, Appendix 2 (55)
202(CA _H)	CH1	Rate alarm alert detection cycle *7	1	R/W	×	○	Page 398, Appendix 2 (56)
203(CB _H)	CH1	Rate alarm upper limit value *7	0	R/W	×	○	Page 399, Appendix 2 (57)
204(CC _H)	CH1	Rate alarm lower limit value *7	0	R/W	×	○	
205(CD _H) to 211(D3 _H)	—	System area	—	—	—	—	—
212(D4 _H)	CH2	Process alarm alert output enable/disable setting *7	1	R/W	×	○	Page 396, Appendix 2 (53)
213(D5 _H)	CH2	Process alarm lower lower limit value *7	0(TT) –2000(RT) *5	R/W	○	○	Page 397, Appendix 2 (54)
214(D6 _H)	CH2	Process alarm lower upper limit value *7	0(TT) –2000(RT) *5	R/W	○	○	
215(D7 _H)	CH2	Process alarm upper lower limit value *7	1300(TT) 6000(RT) *5	R/W	○	○	
216(D8 _H)	CH2	Process alarm upper upper limit value *7	1300(TT) 6000(RT) *5	R/W	○	○	
217(D9 _H)	CH2	Rate alarm alert output enable/disable setting *7	1	R/W	×	○	Page 398, Appendix 2 (55)
218(DA _H)	CH2	Rate alarm alert detection cycle *7	1	R/W	×	○	Page 398, Appendix 2 (56)
219(DB _H)	CH2	Rate alarm upper limit value *7	0	R/W	×	○	Page 399, Appendix 2 (57)
220(DC _H)	CH2	Rate alarm lower limit value *7	0	R/W	×	○	
221(DD _H) to 227(E3 _H)	—	System area	—	—	—	—	—
228(E4 _H)	CH3	Process alarm alert output enable/disable setting *7	1	R/W	×	○	Page 396, Appendix 2 (53)

Address (decimal (hexadecimal))	Target channel	Setting contents	Default value *1	Read/Write *2	Automatic setting *3	Non-volatile memory write availability *4	Reference
		Temperature input mode					
229(E5 _H)	CH3	Process alarm lower lower limit value *7	0(TT) –2000(RT) *5	R/W	○	○	Page 397, Appendix 2 (54)
230(E6 _H)	CH3	Process alarm lower upper limit value *7	0(TT) –2000(RT) *5	R/W	○	○	
231(E7 _H)	CH3	Process alarm upper lower limit value *7	1300(TT) 6000(RT) *5	R/W	○	○	
232(E8 _H)	CH3	Process alarm upper upper limit value *7	1300(TT) 6000(RT) *5	R/W	○	○	
233(E9 _H)	CH3	Rate alarm alert output enable/disable setting *7	1	R/W	×	○	Page 398, Appendix 2 (55)
234(EA _H)	CH3	Rate alarm alert detection cycle *7	1	R/W	×	○	Page 398, Appendix 2 (56)
235(EB _H)	CH3	Rate alarm upper limit value *7	0	R/W	×	○	Page 399, Appendix 2 (57)
236(EC _H)	CH3	Rate alarm lower limit value *7	0	R/W	×	○	
237(ED _H) to 243(F3 _H)	—	System area	—	—	—	—	—
244(F4 _H)	CH4	Process alarm alert output enable/disable setting *7	1	R/W	×	○	Page 396, Appendix 2 (53)
245(F5 _H)	CH4	Process alarm lower lower limit value *7	0(TT) –2000(RT) *5	R/W	○	○	Page 397, Appendix 2 (54)
246(F6 _H)	CH4	Process alarm lower upper limit value *7	0(TT) –2000(RT) *5	R/W	○	○	
247(F7 _H)	CH4	Process alarm upper lower limit value *7	1300(TT) 6000(RT) *5	R/W	○	○	
248(F8 _H)	CH4	Process alarm upper upper limit value *7	1300(TT) 6000(RT) *5	R/W	○	○	
249(F9 _H)	CH4	Rate alarm alert output enable/disable setting *7	1	R/W	×	○	Page 398, Appendix 2 (55)
250(FA _H)	CH4	Rate alarm alert detection cycle *7	1	R/W	×	○	Page 398, Appendix 2 (56)
251(FB _H)	CH4	Rate alarm upper limit value *7	0	R/W	×	○	Page 399, Appendix 2 (57)
252(FC _H)	CH4	Rate alarm lower limit value *7	0	R/W	×	○	
253(FD _H) to 543(21F _H)	—	System area	—	—	—	—	—
544(220 _H)	CH1	Sensor two-point correction offset value (measured value) *7	0	R/W	○	○	Page 403, Appendix 2 (63)
545(221 _H)	CH1	Sensor two-point correction offset value (corrected value) *7	0	R/W	○	○	Page 403, Appendix 2 (64)
546(222 _H)	CH1	Sensor two-point correction gain value (measured value) *7	0	R/W	○	○	Page 404, Appendix 2 (65)

Address (decimal (hexadecimal))	Target channel	Setting contents	Default value *1	Read/Write *2	Automatic setting *3	Non-volatile memory write availability *4	Reference
		Temperature input mode					
547(223 _H)	CH1	Sensor two-point correction gain value (corrected value)*7	0	R/W	○	○	Page 404, Appendix 2 (66)
548(224 _H)	CH1	Sensor two-point correction offset latch request*7	0	R/W	×	×	Page 405, Appendix 2 (67)
549(225 _H)	CH1	Sensor two-point correction offset latch completion	0	R	×	×	Page 405, Appendix 2 (68)
550(226 _H)	CH1	Sensor two-point correction gain latch request*7	0	R/W	×	×	Page 406, Appendix 2 (69)
551(227 _H)	CH1	Sensor two-point correction gain latch completion	0	R	×	×	Page 406, Appendix 2 (70)
552(228 _H) to 575(23F _H)	—	System area	—	—	—	—	—
576(240 _H)	CH2	Sensor two-point correction offset value (measured value)*7	0	R/W	○	○	Page 403, Appendix 2 (63)
577(241 _H)	CH2	Sensor two-point correction offset value (corrected value)*7	0	R/W	○	○	Page 403, Appendix 2 (64)
578(242 _H)	CH2	Sensor two-point correction gain value (measured value)*7	0	R/W	○	○	Page 404, Appendix 2 (65)
579(243 _H)	CH2	Sensor two-point correction gain value (corrected value)*7	0	R/W	○	○	Page 404, Appendix 2 (66)
580(244 _H)	CH2	Sensor two-point correction offset latch request*7	0	R/W	×	×	Page 405, Appendix 2 (67)
581(245 _H)	CH2	Sensor two-point correction offset latch completion	0	R	×	×	Page 405, Appendix 2 (68)
582(246 _H)	CH2	Sensor two-point correction gain latch request*7	0	R/W	×	×	Page 406, Appendix 2 (69)
583(247 _H)	CH2	Sensor two-point correction gain latch completion	0	R	×	×	Page 406, Appendix 2 (70)
584(248 _H) to 607(25F _H)	—	System area	—	—	—	—	—
608(260 _H)	CH3	Sensor two-point correction offset value (measured value)*7	0	R/W	○	○	Page 403, Appendix 2 (63)
609(261 _H)	CH3	Sensor two-point correction offset value (corrected value)*7	0	R/W	○	○	Page 403, Appendix 2 (64)
610(262 _H)	CH3	Sensor two-point correction gain value (measured value)*7	0	R/W	○	○	Page 404, Appendix 2 (65)
611(263 _H)	CH3	Sensor two-point correction gain value (corrected value)*7	0	R/W	○	○	Page 404, Appendix 2 (66)
612(264 _H)	CH3	Sensor two-point correction offset latch request*7	0	R/W	×	×	Page 405, Appendix 2 (67)
613(265 _H)	CH3	Sensor two-point correction offset latch completion	0	R	×	×	Page 405, Appendix 2 (68)
614(266 _H)	CH3	Sensor two-point correction gain latch request*7	0	R/W	×	×	Page 406, Appendix 2 (69)
615(267 _H)	CH3	Sensor two-point correction gain latch completion	0	R	×	×	Page 406, Appendix 2 (70)
616(268 _H) to 639(27F _H)	—	System area	—	—	—	—	—

Address (decimal (hexadecimal))	Target channel	Setting contents	Default value *1	Read/Write *2	Automatic setting *3	Non-volatile memory write availability *4	Reference
		Temperature input mode					
640(280 _H)	CH4	Sensor two-point correction offset value (measured value)*7	0	R/W	○	○	Page 403, Appendix 2 (63)
641(281 _H)	CH4	Sensor two-point correction offset value (corrected value)*7	0	R/W	○	○	Page 403, Appendix 2 (64)
642(282 _H)	CH4	Sensor two-point correction gain value (measured value)*7	0	R/W	○	○	Page 404, Appendix 2 (65)
643(283 _H)	CH4	Sensor two-point correction gain value (corrected value)*7	0	R/W	○	○	Page 404, Appendix 2 (66)
644(284 _H)	CH4	Sensor two-point correction offset latch request*7	0	R/W	×	×	Page 405, Appendix 2 (67)
645(285 _H)	CH4	Sensor two-point correction offset latch completion	0	R	×	×	Page 405, Appendix 2 (68)
646(286 _H)	CH4	Sensor two-point correction gain latch request*7	0	R/W	×	×	Page 406, Appendix 2 (69)
647(287 _H)	CH4	Sensor two-point correction gain latch completion	0	R	×	×	Page 406, Appendix 2 (70)
648(288 _H) to 692(2B4 _H)	—	System area	—	—	—	—	—
693(2B5 _H)	All CHs	Conversion enable/disable setting*7	000F _H	R/W	×	○	Page 412, Appendix 2 (76)
694(2B6 _H) to 697(2B9 _H)	—	System area	—	—	—	—	—
698(2BA _H)	CH1	Number of moving averaging	2	R/W	×	○	Page 414, Appendix 2 (78)
699(2BB _H)	CH2	Number of moving averaging	2	R/W	×	○	
700(2BC _H)	CH3	Number of moving averaging	2	R/W	×	○	
701(2BD _H)	CH4	Number of moving averaging	2	R/W	×	○	
702(2BE _H) to 724(2D4 _H)	—	System area	—	—	—	—	—
725(2D5 _H)	CH1	Process value (PV) scaling function enable/disable setting*7	0	R/W	×	○	Page 415, Appendix 2 (82)
726(2D6 _H)	CH1	Process value (PV) scaling lower limit value*7	0	R/W	×	○	Page 416, Appendix 2 (83)
727(2D7 _H)	CH1	Process value (PV) scaling upper limit value*7	0	R/W	×	○	
728(2D8 _H)	CH1	Process value (PV) scaling value	0	R	×	×	Page 416, Appendix 2 (84)
729(2D9 _H) to 740(2E4 _H)	—	System area	—	—	—	—	—
741(2E5 _H)	CH2	Process value (PV) scaling function enable/disable setting *7	0	R/W	×	○	Page 415, Appendix 2 (82)
742(2E6 _H)	CH2	Process value (PV) scaling lower limit value*7	0	R/W	×	○	Page 416, Appendix 2 (83)
743(2E7 _H)	CH2	Process value (PV) scaling upper limit value*7	0	R/W	×	○	

Address (decimal (hexadecimal))	Target channel	Setting contents	Default value *1	Read/Write *2	Automatic setting *3	Non-volatile memory write availability *4	Reference
		Temperature input mode					
744(2E8 _H)	CH2	Process value (PV) scaling value	0	R	×	×	Page 416, Appendix 2 (84)
745(2E9 _H) to 756(2F4 _H)	—	System area	—	—	—	—	—
757(2F5 _H)	CH3	Process value (PV) scaling function enable/disable setting *7	0	R/W	×	○	Page 415, Appendix 2 (82)
758(2F6 _H)	CH3	Process value (PV) scaling lower limit value *7	0	R/W	×	○	Page 416, Appendix 2 (83)
759(2F7 _H)	CH3	Process value (PV) scaling upper limit value *7	0	R/W	×	○	
760(2F8 _H)	CH3	Process value (PV) scaling value	0	R	×	×	Page 416, Appendix 2 (84)
761(2F9 _H) to 772(304 _H)	—	System area	—	—	—	—	—
773(305 _H)	CH4	Process value (PV) scaling function enable/disable setting *7	0	R/W	×	○	Page 415, Appendix 2 (82)
774(306 _H)	CH4	Process value (PV) scaling lower limit value *7	0	R/W	×	○	Page 416, Appendix 2 (83)
775(307 _H)	CH4	Process value (PV) scaling upper limit value *7	0	R/W	×	○	
776(308 _H)	CH4	Process value (PV) scaling value	0	R	×	×	Page 416, Appendix 2 (84)
777(309 _H) to 784(310 _H)	—	System area	—	—	—	—	—
785(311 _H)	All CHs	Sensor correction function selection *7	0	R/W	×	○	Page 423, Appendix 2 (93)
786(312 _H)	All CHs	Temperature conversion completion flag	0	R	×	×	Page 423, Appendix 2 (94)
787(313 _H)	All CHs	Function extension bit monitor	0	R	×	×	Page 424, Appendix 2 (95)
788(314 _H)	All CHs	Sampling cycle monitor	0	R	×	×	Page 424, Appendix 2 (96)
789(315 _H) to 1278(4FE _H)	—	System area	—	—	—	—	—
1279(4FF _H) to 4095(FFF _H)	Buffer memory areas for error history (👉 Page 78, Section 3.5 (2))						
4096(1000 _H) to 53247(CFFF _H)	—	System area	—	—	—	—	—

- *1 This value is stored when Default setting registration instruction (Yn9) is turned on.
- *2 This column indicates whether data can be read from or written to the buffer memory area through sequence programs.
R: Reading enabled
W: Writing enabled
- *3 This column indicates whether the setting in the buffer memory area is automatically changed when the input range is changed. Enable/disable of automatic change can be set on Switch Setting. For details, refer to  Page 241, Section 8.3.4.
- *4 Whether writing to the non-volatile memory by turning off and on Set value backup instruction (Yn8) is enabled in this column. For details, refer to  Page 242, Section 8.3.5.
- *5 (TT) indicates the L60TCTT4 and L60TCTT4BW. (RT) indicates the L60TCRT4 and L60TCRT4BW.
- *6 Available only when the L60TCTT4 or L60TCTT4BW is used. With other models, this area is handled as a system area.
- *7 Available only in the setting mode. To enable the setting contents, turn off, on, and off Setting change instruction (YnB) when Setting/operation mode instruction (Yn1) is off (during setting mode). Note that a write data error (error code: □□□3H) occurs if the setting is changed during the operation mode.

(b) In the temperature control mode

○: Enable, ×: Disable

Address (decimal (hexadecimal))	Target channel or current sensor (CT)	Setting contents			Default value *1	Read/ Write *2	Automatic setting *3	Non- volatile memory write availability *4	Reference
		Standard control	Heating- cooling control	Mix control					
0(0 _H)	All CHs	Error code			0	R	×	×	Page 344, Appendix 2 (1)
1(1 _H)	CH1	Decimal point position			0(TT) 1(RT) *5	R	×	×	Page 344, Appendix 2 (2)
2(2 _H)	CH2	Decimal point position							
3(3 _H)	CH3	Decimal point position							
4(4 _H)	CH4	Decimal point position							
5(5 _H)	CH1	Alert definition			0	R	×	×	Page 346, Appendix 2 (3)
6(6 _H)	CH2	Alert definition							
7(7 _H)	CH3	Alert definition							
8(8 _H)	CH4	Alert definition							
9(9 _H)	CH1	Temperature process value (PV)			0	R	×	×	Page 348, Appendix 2 (4)
10(A _H)	CH2	Temperature process value (PV)							
11(B _H)	CH3	Temperature process value (PV)							
12(C _H)	CH4	Temperature process value (PV)							
13(D _H)	CH1	Manipulated value (MV)	Manipulated value for heating (MVh)	Manipulated value for heating (MVh)	0	R	×	×	Page 349, Appendix 2 (5)
14(E _H)	CH2	Manipulated value (MV)	Manipulated value for heating (MVh)	Manipulated value for heating (MVh)*7					
15(F _H)	CH3	Manipulated value (MV)	Manipulated value for heating (MVh)*6	Manipulated value (MV)					
16(10 _H)	CH4	Manipulated value (MV)	Manipulated value for heating (MVh)*6	Manipulated value (MV)					
17(11 _H)	CH1	Temperature rise judgment flag	Temperature rise judgment flag	Temperature rise judgment flag	0	R	×	×	Page 350, Appendix 2 (6)
18(12 _H)	CH2	Temperature rise judgment flag	Temperature rise judgment flag	Temperature rise judgment flag*7					
19(13 _H)	CH3	Temperature rise judgment flag	Temperature rise judgment flag *6	Temperature rise judgment flag					
20(14 _H)	CH4	Temperature rise judgment flag	Temperature rise judgment flag *6	Temperature rise judgment flag					

Address (decimal (hexadecimal))	Target channel or current sensor (CT)	Setting contents			Default value *1	Read/ Write *2	Automatic setting *3	Non- volatile memory write availability *4	Reference
		Standard control	Heating- cooling control	Mix control					
21(15 _H)	CH1	Transistor output flag	Heating transistor output flag	Heating transistor output flag	0	R	×	×	Page 351, Appendix 2 (7)
22(16 _H)	CH2	Transistor output flag	Heating transistor output flag	Heating transistor output flag*7					
23(17 _H)	CH3	Transistor output flag	Heating transistor output flag*6	Transistor output flag					
24(18 _H)	CH4	Transistor output flag	Heating transistor output flag*6	Transistor output flag					
25(19 _H)	CH1	Set value (SV) monitor			0	R	×	×	Page 352, Appendix 2 (8)
26(1A _H)	CH2	Set value (SV) monitor	Set value (SV) monitor	Set value (SV) monitor*7					
27(1B _H)	CH3	Set value (SV) monitor	Set value (SV) monitor*6	Set value (SV) monitor					
28(1C _H)	CH4	Set value (SV) monitor	Set value (SV) monitor*6	Set value (SV) monitor					
29(1D _H)	All CHs	Cold junction temperature process value*8			0	R	×	×	Page 352, Appendix 2 (9)
30(1E _H)	All CHs	MAN mode shift completion flag			0	R	×	×	Page 352, Appendix 2 (10)
31(1F _H)	All CHs	Memory's PID constants read/write completion flag			0	R	×	×	Page 353, Appendix 2 (11)
32(20 _H)	CH1	Input range*9			2(TT) 7(RT) *5	R/W	×	○	Page 355, Appendix 2 (12)
33(21 _H)	CH1	Stop mode setting			1	R/W	×	○	Page 362, Appendix 2 (13)
34(22 _H)	CH1	Set value (SV) setting			0	R/W	○	○	Page 363, Appendix 2 (14)
35(23 _H)	CH1	Proportional band (P) setting	Heating proportional band (Ph) setting	Heating proportional band (Ph) setting	30	R/W	×	○	Page 364, Appendix 2 (15)
36(24 _H)	CH1	Integral time (I) setting			240	R/W	×	○	Page 366, Appendix 2 (16)
37(25 _H)	CH1	Derivative time (D) setting			60	R/W	×	○	Page 366, Appendix 2 (17)
38(26 _H)	CH1	Alert set value 1			0	R/W	○	○	Page 367, Appendix 2 (18)
39(27 _H)	CH1	Alert set value 2			0	R/W	○	○	
40(28 _H)	CH1	Alert set value 3			0	R/W	○	○	
41(29 _H)	CH1	Alert set value 4			0	R/W	○	○	

Address (decimal (hexadecimal))	Target channel or current sensor (CT)	Setting contents			Default value *1	Read/ Write *2	Automatic setting *3	Non- volatile memory write availability *4	Reference
		Standard control	Heating- cooling control	Mix control					
42(2A _H)	CH1	Upper limit output limiter	Heating upper limit output limiter	Heating upper limit output limiter	1000	R/W	×	○	Page 369, Appendix 2 (19)
43(2B _H)	CH1	Lower limit output limiter	System area	System area	0	R/W	×	○	
44(2C _H)	CH1	Output variation limiter setting			0	R/W	×	○	Page 371, Appendix 2 (20)
45(2D _H)	CH1	Sensor correction value setting			0	R/W	×	○	Page 372, Appendix 2 (21)
46(2E _H)	CH1	Adjustment sensitivity (dead band) setting			5	R/W	×	○	Page 372, Appendix 2 (22)
47(2F _H)	CH1	Control output cycle setting	Heating control output cycle setting	Heating control output cycle setting	30/300	R/W	×	○	Page 373, Appendix 2 (23)
48(30 _H)	CH1	Primary delay digital filter setting			0	R/W	×	○	Page 374, Appendix 2 (24)
49(31 _H)	CH1	Control response parameters			0	R/W	×	○	Page 375, Appendix 2 (25)
50(32 _H)	CH1	AUTO/MAN mode shift			0	R/W	×	○	Page 376, Appendix 2 (26)
51(33 _H)	CH1	MAN output setting			0	R/W	×	○	Page 377, Appendix 2 (27)
52(34 _H)	CH1	Setting change rate limiter/Setting change rate limiter (temperature rise)*10			0	R/W	×	○	Page 378, Appendix 2 (28)
53(35 _H)	CH1	AT bias			0	R/W	○	○	Page 379, Appendix 2 (29)
54(36 _H)	CH1	Forward/reverse action setting	System area	System area	1	R/W	×	○	Page 380, Appendix 2 (30)
55(37 _H)	CH1	Upper limit setting limiter			1300 (TT) 6000 (RT) *5	R/W	○	○	Page 381, Appendix 2 (31)
56(38 _H)	CH1	Lower limit setting limiter			0(TT) -2000 (RT) *5	R/W	○	○	
57(39 _H)	CH1	System area			—	—	—	—	—
58(3A _H)	CH1	Heater disconnection alert setting*11			0	R/W	×	○	Page 382, Appendix 2 (32)
59(3B _H)	CH1	Loop disconnection detection judgment time	System area	System area	480	R/W	×	○	Page 383, Appendix 2 (33)

Address (decimal (hexadecimal))	Target channel or current sensor (CT)	Setting contents			Default value *1	Read/ Write *2	Automatic setting *3	Non- volatile memory write availability *4	Reference
		Standard control	Heating- cooling control	Mix control					
60(3C _H)	CH1	Loop disconnection detection dead band	System area	System area	0	R/W	○	○	Page 384, Appendix 2 (34)
61(3D _H)	CH1	Unused channel setting			0	R/W	×	○	Page 385, Appendix 2 (35)
62(3E _H)	CH1	Memory's PID constants read instruction			0	R/W	×	×	Page 386, Appendix 2 (36)
63(3F _H)	CH1	Automatic backup setting after auto tuning of PID constants			0	R/W	×	×	Page 387, Appendix 2 (37)
64(40 _H)	CH2	Input range *9			2(TT) 7(RT) *5	R/W	×	○	Page 355, Appendix 2 (12)
65(41 _H)	CH2	Stop mode setting	Stop mode setting	Stop mode setting *7	1	R/W	×	○	Page 362, Appendix 2 (13)
66(42 _H)	CH2	Set value (SV) setting	Set value (SV) setting	Set value (SV) setting *7	0	R/W	○	○	Page 363, Appendix 2 (14)
67(43 _H)	CH2	Proportional band (P) setting	Heating proportional band (Ph) setting	Heating proportional band (Ph) setting *7	30	R/W	×	○	Page 364, Appendix 2 (15)
68(44 _H)	CH2	Integral time (I) setting	Integral time (I) setting	Integral time (I) setting *7	240	R/W	×	○	Page 366, Appendix 2 (16)
69(45 _H)	CH2	Derivative time (D) setting	Derivative time (D) setting	Derivative time (D) setting *7	60	R/W	×	○	Page 366, Appendix 2 (17)
70(46 _H)	CH2	Alert set value 1	Alert set value 1	Alert set value 1 *7	0	R/W	○	○	Page 367, Appendix 2 (18)
71(47 _H)	CH2	Alert set value 2	Alert set value 2	Alert set value 2 *7	0	R/W	○	○	
72(48 _H)	CH2	Alert set value 3	Alert set value 3	Alert set value 3 *7	0	R/W	○	○	
73(49 _H)	CH2	Alert set value 4	Alert set value 4	Alert set value 4 *7	0	R/W	○	○	
74(4A _H)	CH2	Upper limit output limiter	Heating upper limit output limiter	Heating upper limit output limiter *7	1000	R/W	×	○	Page 369, Appendix 2 (19)
75(4B _H)	CH2	Lower limit output limiter	System area	System area	0	R/W	×	○	
76(4C _H)	CH2	Output variation limiter setting	Output variation limiter setting	Output variation limiter setting *7	0	R/W	×	○	Page 371, Appendix 2 (20)
77(4D _H)	CH2	Sensor correction value setting			0	R/W	×	○	Page 372, Appendix 2 (21)
78(4E _H)	CH2	Adjustment sensitivity (dead band) setting	Adjustment sensitivity (dead band) setting	Adjustment sensitivity (dead band) setting *7	5	R/W	×	○	Page 372, Appendix 2 (22)

Address (decimal (hexadecimal))	Target channel or current sensor (CT)	Setting contents			Default value *1	Read/ Write *2	Automatic setting *3	Non- volatile memory write availability *4	Reference
		Standard control	Heating- cooling control	Mix control					
79(4F _H)	CH2	Control output cycle setting	Heating control output cycle setting	Heating control output cycle setting*7	30/300	R/W	×	○	Page 373, Appendix 2 (23)
80(50 _H)	CH2	Primary delay digital filter setting			0	R/W	×	○	Page 374, Appendix 2 (24)
81(51 _H)	CH2	Control response parameters	Control response parameters	Control response parameters*7	0	R/W	×	○	Page 375, Appendix 2 (25)
82(52 _H)	CH2	AUTO/MAN mode shift	AUTO/MAN mode shift	AUTO/MAN mode shift *7	0	R/W	×	○	Page 376, Appendix 2 (26)
83(53 _H)	CH2	MAN output setting	MAN output setting	MAN output setting *7	0	R/W	×	○	Page 377, Appendix 2 (27)
84(54 _H)	CH2	Setting change rate limiter/Setting change rate limiter (temperature rise) *10			0	R/W	×	○	Page 378, Appendix 2 (28)
85(55 _H)	CH2	AT bias	AT bias	AT bias*7	0	R/W	○	○	Page 379, Appendix 2 (29)
86(56 _H)	CH2	Forward/reverse action setting	System area	System area	1	R/W	×	○	Page 380, Appendix 2 (30)
87(57 _H)	CH2	Upper limit setting limiter	Upper limit setting limiter	Upper limit setting limiter*7	1300 (TT) 6000 (RT) *5	R/W	○	○	Page 381, Appendix 2 (31)
88(58 _H)	CH2	Lower limit setting limiter	Lower limit setting limiter	Lower limit setting limiter*7	0 (TT) -2000 (RT) *5	R/W	○	○	
89(59 _H)	CH2	System area			—	—	—	—	—
90(5A _H)	CH2	Heater disconnection alert setting*11	Heater disconnection alert setting*11	Heater disconnection alert setting*7*11	0	R/W	×	○	Page 382, Appendix 2 (32)
91(5B _H)	CH2	Loop disconnection detection judgment time	System area	System area	480	R/W	×	○	Page 383, Appendix 2 (33)
92(5C _H)	CH2	Loop disconnection detection dead band	System area	System area	0	R/W	○	○	Page 384, Appendix 2 (34)
93(5D _H)	CH2	Unused channel setting	Unused channel setting	Unused channel setting*7	0	R/W	×	○	Page 385, Appendix 2 (35)
94(5E _H)	CH2	Memory's PID constants read instruction	Memory's PID constants read instruction	Memory's PID constants read instruction*7	0	R/W	×	×	Page 386, Appendix 2 (36)

Address (decimal (hexadecimal))	Target channel or current sensor (CT)	Setting contents			Default value *1	Read/ Write *2	Automatic setting *3	Non- volatile memory write availability *4	Reference
		Standard control	Heating- cooling control	Mix control					
95(5F _H)	CH2	Automatic backup setting after auto tuning of PID constants	Automatic backup setting after auto tuning of PID constants	Automatic backup setting after auto tuning of PID constants ^{*7}	0	R/W	×	×	Page 387, Appendix 2 (37)
96(60 _H)	CH3	Input range ^{*9}			2(TT) 7(RT) *5	R/W	×	○	Page 355, Appendix 2 (12)
97(61 _H)	CH3	Stop mode setting	Stop mode setting *6	Stop mode setting	1	R/W	×	○	Page 362, Appendix 2 (13)
98(62 _H)	CH3	Set value (SV) setting	Set value (SV) setting ^{*6}	Set value (SV) setting	0	R/W	○	○	Page 363, Appendix 2 (14)
99(63 _H)	CH3	Proportional band (P) setting	Heating proportional band (Ph) setting ^{*6}	Proportional band (P) setting	30	R/W	×	○	Page 364, Appendix 2 (15)
100(64 _H)	CH3	Integral time (I) setting	Integral time (I) setting ^{*6}	Integral time (I) setting	240	R/W	×	○	Page 366, Appendix 2 (16)
101(65 _H)	CH3	Derivative time (D) setting	Derivative time (D) setting ^{*6}	Derivative time (D) setting	60	R/W	×	○	Page 366, Appendix 2 (17)
102(66 _H)	CH3	Alert set value 1	Alert set value 1 ^{*6}	Alert set value 1	0	R/W	○	○	Page 367, Appendix 2 (18)
103(67 _H)	CH3	Alert set value 2	Alert set value 2 ^{*6}	Alert set value 2	0	R/W	○	○	
104(68 _H)	CH3	Alert set value 3	Alert set value 3 ^{*6}	Alert set value 3	0	R/W	○	○	
105(69 _H)	CH3	Alert set value 4	Alert set value 4 ^{*6}	Alert set value 4	0	R/W	○	○	
106(6A _H)	CH3	Upper limit output limiter	Heating upper limit output limiter ^{*6}	Upper limit output limiter	1000	R/W	×	○	Page 369, Appendix 2 (19)
107(6B _H)	CH3	Lower limit output limiter	System area	Lower limit output limiter	0	R/W	×	○	
108(6C _H)	CH3	Output variation limiter setting	Output variation limiter setting ^{*6}	Output variation limiter setting	0	R/W	×	○	Page 371, Appendix 2 (20)
109(6D _H)	CH3	Sensor correction value setting			0	R/W	×	○	Page 372, Appendix 2 (21)
110(6E _H)	CH3	Adjustment sensitivity (dead band) setting	Adjustment sensitivity (dead band) setting ^{*6}	Adjustment sensitivity (dead band) setting	5	R/W	×	○	Page 372, Appendix 2 (22)
111(6F _H)	CH3	Control output cycle setting	Heating control output cycle setting ^{*6}	Control output cycle setting	30/300	R/W	×	○	Page 373, Appendix 2 (23)
112(70 _H)	CH3	Primary delay digital filter setting			0	R/W	×	○	Page 374, Appendix 2 (24)

Address (decimal (hexadecimal))	Target channel or current sensor (CT)	Setting contents			Default value *1	Read/ Write *2	Automatic setting *3	Non- volatile memory write availability *4	Reference
		Standard control	Heating- cooling control	Mix control					
113(71 _H)	CH3	Control response parameters	Control response parameters* ⁶	Control response parameters	0	R/W	×	○	Page 375, Appendix 2 (25)
114(72 _H)	CH3	AUTO/MAN mode shift	AUTO/MAN mode shift* ⁶	AUTO/MAN mode shift	0	R/W	×	○	Page 376, Appendix 2 (26)
115(73 _H)	CH3	MAN output setting	MAN output setting* ⁶	MAN output setting	0	R/W	×	○	Page 377, Appendix 2 (27)
116(74 _H)	CH3	Setting change rate limiter/Setting change rate limiter (temperature rise)* ¹⁰			0	R/W	×	○	Page 378, Appendix 2 (28)
117(75 _H)	CH3	AT bias	AT bias* ⁶	AT bias	0	R/W	○	○	Page 379, Appendix 2 (29)
118(76 _H)	CH3	Forward/reverse action setting	System area	Forward/revers e action setting	1	R/W	×	○	Page 380, Appendix 2 (30)
119(77 _H)	CH3	Upper limit setting limiter	Upper limit setting limiter* ⁶	Upper limit setting limiter	1300 (TT) 6000 (RT) * ⁵	R/W	○	○	Page 381, Appendix 2 (31)
120(78 _H)	CH3	Lower limit setting limiter	Lower limit setting limiter* ⁶	Lower limit setting limiter	0 (TT) -2000 (RT) * ⁵	R/W	○	○	
121(79 _H)	CH3	System area			—	—	—	—	—
122(7A _H)	CH3	Heater disconnection alert setting* ¹¹	Heater disconnection alert setting* ⁶ * ¹¹	Heater disconnection alert setting* ¹¹	0	R/W	×	○	Page 382, Appendix 2 (32)
123(7B _H)	CH3	Loop disconnection detection judgment time	System area	Loop disconnection detection judgment time	480	R/W	×	○	Page 383, Appendix 2 (33)
124(7C _H)	CH3	Loop disconnection detection dead band	System area	Loop disconnection detection dead band	0	R/W	○	○	Page 384, Appendix 2 (34)
125(7D _H)	CH3	Unused channel setting	Unused channel setting* ⁶	Unused channel setting	0	R/W	×	○	Page 385, Appendix 2 (35)
126(7E _H)	CH3	Memory's PID constants read instruction	Memory's PID constants read instruction* ⁶	Memory's PID constants read instruction	0	R/W	×	×	Page 386, Appendix 2 (36)
127(7F _H)	CH3	Automatic backup setting after auto tuning of PID constants	Automatic backup setting after auto tuning of PID constants* ⁶	Automatic backup setting after auto tuning of PID constants	0	R/W	×	×	Page 387, Appendix 2 (37)
128(80 _H)	CH4	Input range* ⁹			2(TT) 7(RT) * ⁵	R/W	×	○	Page 355, Appendix 2 (12)

Address (decimal (hexadecimal))	Target channel or current sensor (CT)	Setting contents			Default value *1	Read/ Write *2	Automatic setting *3	Non- volatile memory write availability *4	Reference
		Standard control	Heating- cooling control	Mix control					
129(81 _H)	CH4	Stop mode setting	Stop mode setting* ⁶	Stop mode setting	1	R/W	×	○	Page 362, Appendix 2 (13)
130(82 _H)	CH4	Set value (SV) setting	Set value (SV) setting* ⁶	Set value (SV) setting	0	R/W	○	○	Page 363, Appendix 2 (14)
131(83 _H)	CH4	Proportional band (P) setting	Heating proportional band (Ph) setting* ⁶	Proportional band (P) setting	30	R/W	×	○	Page 364, Appendix 2 (15)
132(84 _H)	CH4	Integral time (I) setting	Integral time (I) setting* ⁶	Integral time (I) setting	240	R/W	×	○	Page 366, Appendix 2 (16)
133(85 _H)	CH4	Derivative time (D) setting	Derivative time (D) setting* ⁶	Derivative time (D) setting	60	R/W	×	○	Page 366, Appendix 2 (17)
134(86 _H)	CH4	Alert set value 1	Alert set value 1* ⁶	Alert set value 1	0	R/W	○	○	Page 367, Appendix 2 (18)
135(87 _H)	CH4	Alert set value 2	Alert set value 2* ⁶	Alert set value 2	0	R/W	○	○	
136(88 _H)	CH4	Alert set value 3	Alert set value 3* ⁶	Alert set value 3	0	R/W	○	○	
137(89 _H)	CH4	Alert set value 4	Alert set value 4* ⁶	Alert set value 4	0	R/W	○	○	
138(8A _H)	CH4	Upper limit output limiter	Heating upper limit output limiter* ⁶	Upper limit output limiter	1000	R/W	×	○	Page 369, Appendix 2 (19)
139(8B _H)	CH4	Lower limit output limiter	System area	Lower limit output limiter	0	R/W	×	○	
140(8C _H)	CH4	Output variation limiter setting	Output variation limiter setting* ⁶	Output variation limiter setting	0	R/W	×	○	Page 371, Appendix 2 (20)
141(8D _H)	CH4	Sensor correction value setting			0	R/W	×	○	Page 372, Appendix 2 (21)
142(8E _H)	CH4	Adjustment sensitivity (dead band) setting	Adjustment sensitivity (dead band) setting* ⁶	Adjustment sensitivity (dead band) setting	5	R/W	×	○	Page 372, Appendix 2 (22)
143(8F _H)	CH4	Control output cycle setting	Heating control output cycle setting* ⁶	Control output cycle setting	30/300	R/W	×	○	Page 373, Appendix 2 (23)
144(90 _H)	CH4	Primary delay digital filter setting			0	R/W	×	○	Page 374, Appendix 2 (24)
145(91 _H)	CH4	Control response parameters	Control response parameters* ⁶	Control response parameters	0	R/W	×	○	Page 375, Appendix 2 (25)
146(92 _H)	CH4	AUTO/MAN mode shift	AUTO/MAN mode shift * ⁶	AUTO/MAN mode shift	0	R/W	×	○	Page 376, Appendix 2 (26)
147(93 _H)	CH4	MAN output setting	MAN output setting* ⁶	MAN output setting	0	R/W	×	○	Page 377, Appendix 2 (27)

Address (decimal (hexadecimal))	Target channel or current sensor (CT)	Setting contents			Default value *1	Read/ Write *2	Automatic setting *3	Non- volatile memory write availability *4	Reference
		Standard control	Heating- cooling control	Mix control					
148(94 _H)	CH4	Setting change rate limiter/Setting change rate limiter (temperature rise) *10			0	R/W	×	○	Page 378, Appendix 2 (28)
149(95 _H)	CH4	AT bias	AT bias *6	AT bias	0	R/W	○	○	Page 379, Appendix 2 (29)
150(96 _H)	CH4	Forward/reverse action setting	System area	Forward/revers e action setting	1	R/W	×	○	Page 380, Appendix 2 (30)
151(97 _H)	CH4	Upper limit setting limiter	Upper limit setting limiter*6	Upper limit setting limiter	1300 (TT) 6000 (RT) *5	R/W	○	○	Page 381, Appendix 2 (31)
152(98 _H)	CH4	Lower limit setting limiter	Lower limit setting limiter*6	Lower limit setting limiter	0 (TT) -2000 (RT) *5	R/W	○	○	
153(99 _H)	CH4	System area			—	—	—	—	—
154(9A _H)	CH4	Heater disconnection alert setting*11	Heater disconnection alert setting*6*11	Heater disconnection alert setting*11	0	R/W	×	○	Page 382, Appendix 2 (32)
155(9B _H)	CH4	Loop disconnection detection judgment time	System area	Loop disconnection detection judgment time	480	R/W	×	○	Page 383, Appendix 2 (33)
156(9C _H)	CH4	Loop disconnection detection dead band	System area	Loop disconnection detection dead band	0	R/W	○	○	Page 384, Appendix 2 (34)
157(9D _H)	CH4	Unused channel setting	Unused channel setting*6	Unused channel setting	0	R/W	×	○	Page 385, Appendix 2 (35)
158(9E _H)	CH4	Memory's PID constants read instruction	Memory's PID constants read instruction*6	Memory's PID constants read instruction	0	R/W	×	×	Page 386, Appendix 2 (36)
159(9F _H)	CH4	Automatic backup setting after auto tuning of PID constants	Automatic backup setting after auto tuning of PID constants*6	Automatic backup setting after auto tuning of PID constants	0	R/W	×	×	Page 387, Appendix 2 (37)
160(A0 _H) to 163(A3 _H)	—	System area			—	—	—	—	—
164(A4 _H)	All CHs	Alert dead band setting			5	R/W	×	○	Page 388, Appendix 2 (38)
165(A5 _H)	All CHs	Number of alert delay			0	R/W	×	○	Page 388, Appendix 2 (39)
166(A6 _H)	All CHs	Heater disconnection/output off-time current error detection delay count*11			3	R/W	×	○	Page 389, Appendix 2 (40)

Address (decimal (hexadecimal))	Target channel or current sensor (CT)	Setting contents			Default value *1	Read/ Write *2	Automatic setting *3	Non- volatile memory write availability *4	Reference
		Standard control	Heating- cooling control	Mix control					
167(A7 _H)	All CHs	Temperature rise completion range setting			1	R/W	×	○	Page 389, Appendix 2 (41)
168(A8 _H)	All CHs	Temperature rise completion soak time setting			0	R/W	×	○	Page 390, Appendix 2 (42)
169(A9 _H)	All CHs	PID continuation flag			0	R/W	×	○	Page 390, Appendix 2 (43)
170(AA _H)	All CHs	Heater disconnection compensation function selection*11			0	R/W	×	○	Page 390, Appendix 2 (44)
171(AB _H) to 174(AE _H)	—	System area			—	—	—	—	—
175(AF _H)	All CHs	Transistor output monitor ON delay time setting			0	R/W	×	○	Page 391, Appendix 2 (45)
176(B0 _H)	All CHs	CT monitor method switching*11			0	R/W	×	○	Page 391, Appendix 2 (46)
177(B1 _H)	CH1	Manipulated value (MV) for output with another analog module	Manipulated value of heating (MVh) for output with another analog module	Manipulated value of heating (MVh) for output with another analog module	0	R	×	×	Page 392, Appendix 2 (47)
178(B2 _H)	CH2	Manipulated value (MV) for output with another analog module	Manipulated value of heating (MVh) for output with another analog module	Manipulated value of heating (MVh) for output with another analog module*7	0	R	×	×	
179(B3 _H)	CH3	Manipulated value (MV) for output with another analog module	Manipulated value of heating (MVh) for output with another analog module*6	Manipulated value (MV) for output with another analog module	0	R	×	×	
180(B4 _H)	CH4	Manipulated value (MV) for output with another analog module	Manipulated value of heating (MVh) for output with another analog module*6	Manipulated value (MV) for output with another analog module	0	R	×	×	
181(B5 _H)	All CHs	Resolution of the manipulated value for output with another analog module			0	R/W	×	○	Page 393, Appendix 2 (48)
182(B6 _H)	All CHs	Cold junction temperature compensation selection*8			0	R/W	×	○	Page 393, Appendix 2 (49)
183(B7 _H)	All CHs	Control switching monitor			0	R	×	×	Page 394, Appendix 2 (50)

Address (decimal (hexadecimal))	Target channel or current sensor (CT)	Setting contents			Default value *1	Read/ Write *2	Automatic setting *3	Non- volatile memory write availability *4	Reference
		Standard control	Heating- cooling control	Mix control					
184(B8 _H)	CH1	Auto tuning mode selection			0	R/W	×	○	Page 394, Appendix 2 (51)
185(B9 _H)	CH2	Auto tuning mode selection	Auto tuning mode selection	Auto tuning mode selection *7	0	R/W	×	○	
186(BA _H)	CH3	Auto tuning mode selection	Auto tuning mode selection*6	Auto tuning mode selection	0	R/W	×	○	
187(BB _H)	CH4	Auto tuning mode selection	Auto tuning mode selection*6	Auto tuning mode selection	0	R/W	×	○	
188(BC _H) to 191(BF _H)	—	System area			—	—	—	—	—
192(C0 _H)	CH1	Alert 1 mode setting*9			0	R/W	×	○	Page 395, Appendix 2 (52)
193(C1 _H)	CH1	Alert 2 mode setting*9			0	R/W	×	○	
194(C2 _H)	CH1	Alert 3 mode setting*9			0	R/W	×	○	
195(C3 _H)	CH1	Alert 4 mode setting*9			0	R/W	×	○	
196(C4 _H) to 207(CF _H)	—	System area			—	—	—	—	—
208(D0 _H)	CH2	Alert 1 mode setting*9	Alert 1 mode setting*9	Alert 1 mode setting*7*9	0	R/W	×	○	Page 395, Appendix 2 (52)
209(D1 _H)	CH2	Alert 2 mode setting*9	Alert 2 mode setting*9	Alert 2 mode setting*7*9	0	R/W	×	○	
210(D2 _H)	CH2	Alert 3 mode setting*9	Alert 3 mode setting*9	Alert 3 mode setting*7*9	0	R/W	×	○	
211(D3 _H)	CH2	Alert 4 mode setting*9	Alert 4 mode setting*9	Alert 4 mode setting*7*9	0	R/W	×	○	
212(D4 _H) to 223(DF _H)	—	System area			—	—	—	—	—
224(E0 _H)	CH3	Alert 1 mode setting*9	Alert 1 mode setting*6*9	Alert 1 mode setting*9	0	R/W	×	○	Page 395, Appendix 2 (52)
225(E1 _H)	CH3	Alert 2 mode setting*9	Alert 2 mode setting*6*9	Alert 2 mode setting*9	0	R/W	×	○	
226(E2 _H)	CH3	Alert 3 mode setting*9	Alert 3 mode setting*6*9	Alert 3 mode setting*9	0	R/W	×	○	
227(E3 _H)	CH3	Alert 4 mode setting*9	Alert 4 mode setting*6*9	Alert 4 mode setting*9	0	R/W	×	○	
228(E4 _H) to 239(EF _H)	—	System area			—	—	—	—	—

Address (decimal (hexadecimal))	Target channel or current sensor (CT)	Setting contents			Default value *1	Read/ Write *2	Automatic setting *3	Non- volatile memory write availability *4	Reference
		Standard control	Heating- cooling control	Mix control					
240(F0 _H)	CH4	Alert 1 mode setting*9	Alert 1 mode setting*6*9	Alert 1 mode setting*9	0	R/W	×	○	Page 395, Appendix 2 (52)
241(F1 _H)	CH4	Alert 2 mode setting*9	Alert 2 mode setting*6*9	Alert 2 mode setting*9	0	R/W	×	○	
242(F2 _H)	CH4	Alert 3 mode setting*9	Alert 3 mode setting*6*9	Alert 3 mode setting*9	0	R/W	×	○	
243(F3 _H)	CH4	Alert 4 mode setting*9	Alert 4 mode setting*6*9	Alert 4 mode setting*9	0	R/W	×	○	
244(F4 _H) to 255(FF _H)	—	System area			—	—	—	—	—
256(100 _H)	CT1	Heater current process value*11			0	R	×	×	Page 399, Appendix 2 (58)
257(101 _H)	CT2	Heater current process value*11							
258(102 _H)	CT3	Heater current process value*11							
259(103 _H)	CT4	Heater current process value*11							
260(104 _H)	CT5	Heater current process value*11							
261(105 _H)	CT6	Heater current process value*11							
262(106 _H)	CT7	Heater current process value*11							
263(107 _H)	CT8	Heater current process value*11							
264(108 _H)	CT1	CT input channel assignment setting*11			0	R/W	×	○	Page 400, Appendix 2 (59)
265(109 _H)	CT2	CT input channel assignment setting*11							
266(10A _H)	CT3	CT input channel assignment setting*11							
267(10B _H)	CT4	CT input channel assignment setting*11							
268(10C _H)	CT5	CT input channel assignment setting*11							
269(10D _H)	CT6	CT input channel assignment setting*11							
270(10E _H)	CT7	CT input channel assignment setting*11							
271(10F _H)	CT8	CT input channel assignment setting*11							
272(110 _H)	CT1	CT selection*9*11			0	R/W	×	○	Page 401, Appendix 2 (60)
273(111 _H)	CT2	CT selection*9*11							
274(112 _H)	CT3	CT selection*9*11							
275(113 _H)	CT4	CT selection*9*11							
276(114 _H)	CT5	CT selection*9*11							
277(115 _H)	CT6	CT selection*9*11							
278(116 _H)	CT7	CT selection*9*11							
279(117 _H)	CT8	CT selection*9*11							
280(118 _H)	CT1	Reference heater current value*11			0	R/W	×	○	Page 402, Appendix 2 (61)
281(119 _H)	CT2	Reference heater current value*11							
282(11A _H)	CT3	Reference heater current value*11							
283(11B _H)	CT4	Reference heater current value*11							
284(11C _H)	CT5	Reference heater current value*11							
285(11D _H)	CT6	Reference heater current value*11							
286(11E _H)	CT7	Reference heater current value*11							
287(11F _H)	CT8	Reference heater current value*11							

Address (decimal (hexadecimal))	Target channel or current sensor (CT)	Setting contents			Default value *1	Read/ Write *2	Automatic setting *3	Non- volatile memory write availability *4	Reference
		Standard control	Heating- cooling control	Mix control					
288(120 _H)	CT1	CT ratio setting*11			800	R/W	×	○	Page 402, Appendix 2 (62)
289(121 _H)	CT2	CT ratio setting*11							
290(122 _H)	CT3	CT ratio setting*11							
291(123 _H)	CT4	CT ratio setting*11							
292(124 _H)	CT5	CT ratio setting*11							
293(125 _H)	CT6	CT ratio setting*11							
294(126 _H)	CT7	CT ratio setting*11							
295(127 _H)	CT8	CT ratio setting*11							
296(128 _H) to 543(21F _H)	—	System area			—	—	—	—	—
544(220 _H)	CH1	Sensor two-point correction offset value (measured value)*9			0	R/W	○	○	Page 403, Appendix 2 (63)
545(221 _H)	CH1	Sensor two-point correction offset value (corrected value)*9			0	R/W	○	○	Page 403, Appendix 2 (64)
546(222 _H)	CH1	Sensor two-point correction gain value (measured value)*9			0	R/W	○	○	Page 404, Appendix 2 (65)
547(223 _H)	CH1	Sensor two-point correction gain value (corrected value)*9			0	R/W	○	○	Page 404, Appendix 2 (66)
548(224 _H)	CH1	Sensor two-point correction offset latch request*9			0	R/W	×	×	Page 405, Appendix 2 (67)
549(225 _H)	CH1	Sensor two-point correction offset latch completion			0	R	×	×	Page 405, Appendix 2 (68)
550(226 _H)	CH1	Sensor two-point correction gain latch request*9			0	R/W	×	×	Page 406, Appendix 2 (69)
551(227 _H)	CH1	Sensor two-point correction gain latch completion			0	R	×	×	Page 406, Appendix 2 (70)
552(228 _H) to 563(233 _H)	—	System area			—	—	—	—	—
564(234 _H)	CH1	Setting change rate limiter (temperature drop)*12			0	R/W	×	○	Page 378, Appendix 2 (28)
565(235 _H) to 570(23A _H)	—	System area			—	—	—	—	—
571(23B _H)	All CHs	During AT loop disconnection detection function enable/disable setting	System area	During AT loop disconnection detection function enable/disable setting	0	R/W	×	○	Page 407, Appendix 2 (71)
572(23C _H)	—	System area			—	—	—	—	—

Address (decimal (hexadecimal))	Target channel or current sensor (CT)	Setting contents			Default value *1	Read/ Write *2	Automatic setting *3	Non- volatile memory write availability *4	Reference
		Standard control	Heating- cooling control	Mix control					
573(23D _H)	CH1	AT simultaneous temperature rise parameter calculation flag	System area	System area	0	R	×	×	Page 407, Appendix 2 (72)
574(23E _H)	CH1	Self-tuning setting	System area	System area	0	R/W	×	○	Page 408, Appendix 2 (73)
575(23F _H)	CH1	Self-tuning flag	System area	System area	0	R	×	×	Page 409, Appendix 2 (74)
576(240 _H)	CH2	Sensor two-point correction offset value (measured value)* ⁹			0	R/W	○	○	Page 403, Appendix 2 (63)
577(241 _H)	CH2	Sensor two-point correction offset value (corrected value)* ⁹			0	R/W	○	○	Page 403, Appendix 2 (64)
578(242 _H)	CH2	Sensor two-point correction gain value (measured value)* ⁹			0	R/W	○	○	Page 404, Appendix 2 (65)
579(243 _H)	CH2	Sensor two-point correction gain value (corrected value)* ⁹			0	R/W	○	○	Page 404, Appendix 2 (66)
580(244 _H)	CH2	Sensor two-point correction offset latch request* ⁹			0	R/W	×	×	Page 405, Appendix 2 (67)
581(245 _H)	CH2	Sensor two-point correction offset latch completion			0	R	×	×	Page 405, Appendix 2 (68)
582(246 _H)	CH2	Sensor two-point correction gain latch request* ⁹			0	R/W	×	×	Page 406, Appendix 2 (69)
583(247 _H)	CH2	Sensor two-point correction gain latch completion			0	R	×	×	Page 406, Appendix 2 (70)
584(248 _H) to 595(253 _H)	—	System area			—	—	—	—	—
596(254 _H)	CH2	Setting change rate limiter (temperature drop)* ¹²			0	R/W	×	○	Page 378, Appendix 2 (28)
597(255 _H) to 604(25C _H)	—	System area			—	—	—	—	—
605(25D _H)	CH2	AT simultaneous temperature rise parameter calculation flag	System area	System area	0	R	×	×	Page 407, Appendix 2 (72)
606(25E _H)	CH2	Self-tuning setting	System area	System area	0	R/W	×	○	Page 408, Appendix 2 (73)
607(25F _H)	CH2	Self-tuning flag	System area	System area	0	R	×	×	Page 409, Appendix 2 (74)

Address (decimal (hexadecimal))	Target channel or current sensor (CT)	Setting contents			Default value *1	Read/ Write *2	Automatic setting *3	Non- volatile memory write availability *4	Reference
		Standard control	Heating- cooling control	Mix control					
608(260 _H)	CH3	Sensor two-point correction offset value (measured value)* ⁹			0	R/W	○	○	Page 403, Appendix 2 (63)
609(261 _H)	CH3	Sensor two-point correction offset value (corrected value)* ⁹			0	R/W	○	○	Page 403, Appendix 2 (64)
610(262 _H)	CH3	Sensor two-point correction gain value (measured value)* ⁹			0	R/W	○	○	Page 404, Appendix 2 (65)
611(263 _H)	CH3	Sensor two-point correction gain value (corrected value)* ⁹			0	R/W	○	○	Page 404, Appendix 2 (66)
612(264 _H)	CH3	Sensor two-point correction offset latch request* ⁹			0	R/W	×	×	Page 405, Appendix 2 (67)
613(265 _H)	CH3	Sensor two-point correction offset latch completion			0	R	×	×	Page 405, Appendix 2 (68)
614(266 _H)	CH3	Sensor two-point correction gain latch request* ⁹			0	R/W	×	×	Page 406, Appendix 2 (69)
615(267 _H)	CH3	Sensor two-point correction gain latch completion			0	R	×	×	Page 406, Appendix 2 (70)
616(268 _H) to 627(273 _H)	—	System area			—	—	—	—	—
628(274 _H)	CH3	Setting change rate limiter (temperature drop)* ¹²			0	R/W	×	○	Page 378, Appendix 2 (28)
629(275 _H) to 636(27C _H)	—	System area			—	—	—	—	—
637(27D _H)	CH3	AT simultaneous temperature rise parameter calculation flag	System area	AT simultaneous temperature rise parameter calculation flag	0	R	×	×	Page 407, Appendix 2 (72)
638(27E _H)	CH3	Self-tuning setting	System area	Self-tuning setting	0	R/W	×	○	Page 408, Appendix 2 (73)
639(27F _H)	CH3	Self-tuning flag	System area	Self-tuning flag	0	R	×	×	Page 409, Appendix 2 (74)
640(280 _H)	CH4	Sensor two-point correction offset value (measured value)* ⁹			0	R/W	○	○	Page 403, Appendix 2 (63)
641(281 _H)	CH4	Sensor two-point correction offset value (corrected value)* ⁹			0	R/W	○	○	Page 403, Appendix 2 (64)
642(282 _H)	CH4	Sensor two-point correction gain value (measured value)* ⁹			0	R/W	○	○	Page 404, Appendix 2 (65)

Address (decimal (hexadecimal))	Target channel or current sensor (CT)	Setting contents			Default value *1	Read/ Write *2	Automatic setting *3	Non- volatile memory write availability *4	Reference
		Standard control	Heating- cooling control	Mix control					
643(283 _H)	CH4	Sensor two-point correction gain value (corrected value)* ⁹			0	R/W	○	○	Page 404, Appendix 2 (66)
644(284 _H)	CH4	Sensor two-point correction offset latch request* ⁹			0	R/W	×	×	Page 405, Appendix 2 (67)
645(285 _H)	CH4	Sensor two-point correction offset latch completion			0	R	×	×	Page 405, Appendix 2 (68)
646(286 _H)	CH4	Sensor two-point correction gain latch request* ⁹			0	R/W	×	×	Page 406, Appendix 2 (69)
647(287 _H)	CH4	Sensor two-point correction gain latch completion			0	R	×	×	Page 406, Appendix 2 (70)
648(288 _H) to 659(293 _H)	—	System area			—	—	—	—	—
660(294 _H)	CH4	Setting change rate limiter (temperature drop)* ¹²			0	R/W	×	○	Page 378, Appendix 2 (28)
661(295 _H) to 668(29C _H)	—	System area			—	—	—	—	—
669(29D _H)	CH4	AT simultaneous temperature rise parameter calculation flag	System area	AT simultaneous temperature rise parameter calculation flag	0	R	×	×	Page 407, Appendix 2 (72)
670(29E _H)	CH4	Self-tuning setting	System area	Self-tuning setting	0	R/W	×	○	Page 408, Appendix 2 (73)
671(29F _H)	CH4	Self-tuning flag	System area	Self-tuning flag	0	R	×	×	Page 409, Appendix 2 (74)
672(2A0 _H) to 688(2B0 _H)	—	System area			—	—	—	—	—

Address (decimal (hexadecimal))	Target channel or current sensor (CT)	Setting contents			Default value *1	Read/ Write *2	Automatic setting *3	Non- volatile memory write availability *4	Reference
		Standard control	Heating- cooling control	Mix control					
689(2B1 _H)	CH1	Temperature process value (PV) for input with another analog module			0	R/W	×	×	Page 412, Appendix 2 (75)
690(2B2 _H)	CH2	Temperature process value (PV) for input with another analog module	Temperature process value (PV) for input with another analog module	Temperature process value (PV) for input with another analog module *7	0	R/W	×	×	
691(2B3 _H)	CH3	Temperature process value (PV) for input with another analog module	Temperature process value (PV) for input with another analog module *6	Temperature process value (PV) for input with another analog module	0	R/W	×	×	
692(2B4 _H)	CH4	Temperature process value (PV) for input with another analog module	Temperature process value (PV) for input with another analog module *6	Temperature process value (PV) for input with another analog module	0	R/W	×	×	
693(2B5 _H)	—	System area			—	—	—	—	—
694(2B6 _H)	—	System area			—	—	—	—	—
695(2B7 _H)	CH2	System area	System area	Temperature conversion setting *14	0	R/W	×	○	Page 413, Appendix 2 (77)
696(2B8 _H)	CH3	System area	Temperature conversion setting *13	System area	0	R/W	×	○	
697(2B9 _H)	CH4	System area	Temperature conversion setting *13	System area	0	R/W	×	○	
698(2BA _H)	CH1	Number of moving averaging			2	R/W	×	○	Page 414, Appendix 2 (78)
699(2BB _H)	CH2	Number of moving averaging			2	R/W	×	○	
700(2BC _H)	CH3	Number of moving averaging			2	R/W	×	○	
701(2BD _H)	CH4	Number of moving averaging			2	R/W	×	○	
702(2BE _H)	—	System area			—	—	—	—	—
703(2BF _H)	—	System area			—	—	—	—	—

Address (decimal (hexadecimal))	Target channel or current sensor (CT)	Setting contents			Default value *1	Read/ Write *2	Automatic setting *3	Non- volatile memory write availability *4	Reference
		Standard control	Heating- cooling control	Mix control					
704(2C0 _H)	CH1	System area	Manipulated value for cooling (MVc)	Manipulated value for cooling (MVc)	0	R	×	×	Page 349, Appendix 2 (5)
705(2C1 _H)	CH2	System area	Manipulated value for cooling (MVc)	Manipulated value for cooling (MVc) *7	0	R	×	×	
706(2C2 _H)	CH3	System area	Manipulated value for cooling (MVc)*6	System area	0	R	×	×	
707(2C3 _H)	CH4	System area	Manipulated value for cooling (MVc)*6	System area	0	R	×	×	
708(2C4 _H)	CH1	System area	Manipulated value of cooling (MVc) for output with another analog module	Manipulated value of cooling (MVc) for output with another analog module	0	R	×	×	Page 392, Appendix 2 (47)
709(2C5 _H)	CH2	System area	Manipulated value of cooling (MVc) for output with another analog module	Manipulated value of cooling (MVc) for output with another analog module*7	0	R	×	×	
710(2C6 _H)	CH3	System area	Manipulated value of cooling (MVc) for output with another analog module*6	System area	0	R	×	×	
711(2C7 _H)	CH4	System area	Manipulated value of cooling (MVc) for output with another analog module*6	System area	0	R	×	×	Page 392, Appendix 2 (47)
712(2C8 _H)	CH1	System area	Cooling transistor output flag	Cooling transistor output flag	0	R	×	×	Page 351, Appendix 2 (7)
713(2C9 _H)	CH2	System area	Cooling transistor output flag	Cooling transistor output flag *7	0	R	×	×	
714(2CA _H)	CH3	System area	Cooling transistor output flag *6	System area	0	R	×	×	
715(2CB _H)	CH4	System area	Cooling transistor output flag *6	System area	0	R	×	×	
716(2CC _H) to 718(2CE _H)	—	System area			—	—	—	—	—

Address (decimal (hexadecimal))	Target channel or current sensor (CT)	Setting contents			Default value *1	Read/ Write *2	Automatic setting *3	Non- volatile memory write availability *4	Reference
		Standard control	Heating- cooling control	Mix control					
719(2CF _H)	All CHs	System area	Cooling method setting *9	Cooling method setting *9	0	R/W	×	○	Page 414, Appendix 2 (79)
720(2D0 _H)	CH1	System area	Cooling proportional band (Pc) setting	Cooling proportional band (Pc) setting	30	R/W	×	○	Page 364, Appendix 2 (15)
721(2D1 _H)	CH1	System area	Cooling upper limit output limiter	Cooling upper limit output limiter	1000	R/W	×	○	Page 369, Appendix 2 (19)
722(2D2 _H)	CH1	System area	Cooling control output cycle setting	Cooling control output cycle setting	30/300	R/W	×	○	Page 373, Appendix 2 (23)
723(2D3 _H)	CH1	System area	Overlap/dead band setting	Overlap/dead band setting	0	R/W	×	○	Page 415, Appendix 2 (80)
724(2D4 _H)	CH1	Manual reset amount setting			0	R/W	×	○	Page 415, Appendix 2 (81)
725(2D5 _H)	CH1	Process value (PV) scaling function enable/disable setting*9			0	R/W	×	○	Page 415, Appendix 2 (82)
726(2D6 _H)	CH1	Process value (PV) scaling lower limit value*9			0	R/W	×	○	Page 416, Appendix 2 (83)
727(2D7 _H)	CH1	Process value (PV) scaling upper limit value*9			0	R/W	×	○	
728(2D8 _H)	CH1	Process value (PV) scaling value			0	R	×	×	Page 416, Appendix 2 (84)
729(2D9 _H)	CH1	Derivative action selection*9			0	R/W	×	○	Page 417, Appendix 2 (85)
730(2DA _H)	CH1	Simultaneous temperature rise group setting*9	System area	System area	0	R/W	×	○	Page 417, Appendix 2 (86)
731(2DB _H)	CH1	Simultaneous temperature rise gradient data	System area	System area	0	R/W	○	○	Page 418, Appendix 2 (87)
732(2DC _H)	CH1	Simultaneous temperature rise dead time	System area	System area	0	R/W	○	○	Page 418, Appendix 2 (88)
733(2DD _H)	CH1	Simultaneous temperature rise AT mode selection	System area	System area	0	R/W	×	○	Page 419, Appendix 2 (89)
734(2DE _H)	CH1	Simultaneous temperature rise status	System area	System area	0	R	×	×	Page 420, Appendix 2 (90)
735(2DF _H)	CH1	Setting change rate limiter unit time setting*9			0	R/W	×	○	Page 421, Appendix 2 (91)
736(2E0 _H)	CH2	System area	Cooling proportional band (Pc) setting	Cooling proportional band (Pc) setting*7	30	R/W	×	○	Page 364, Appendix 2 (15)

Address (decimal (hexadecimal))	Target channel or current sensor (CT)	Setting contents			Default value *1	Read/ Write *2	Automatic setting *3	Non- volatile memory write availability *4	Reference
		Standard control	Heating- cooling control	Mix control					
737(2E1 _H)	CH2	System area	Cooling upper limit output limiter	Cooling upper limit output limiter*7	1000	R/W	×	○	Page 369, Appendix 2 (19)
738(2E2 _H)	CH2	System area	Cooling control output cycle setting	Cooling control output cycle setting*7	30/300	R/W	×	○	Page 373, Appendix 2 (23)
739(2E3 _H)	CH2	System area	Overlap/dead band setting	Overlap/dead band setting*7	0	R/W	×	○	Page 415, Appendix 2 (80)
740(2E4 _H)	CH2	Manual reset amount setting	Manual reset amount setting	Manual reset amount setting*7	0	R/W	×	○	Page 415, Appendix 2 (81)
741(2E5 _H)	CH2	Process value (PV) scaling function enable/disable setting*9	Process value (PV) scaling function enable/disable setting*9	Process value (PV) scaling function enable/disable setting*7*9	0	R/W	×	○	Page 415, Appendix 2 (82)
742(2E6 _H)	CH2	Process value (PV) scaling lower limit value*9	Process value (PV) scaling lower limit value*9	Process value (PV) scaling lower limit value*7*9	0	R/W	×	○	Page 416, Appendix 2 (83)
743(2E7 _H)	CH2	Process value (PV) scaling upper limit value*9	Process value (PV) scaling upper limit value*9	Process value (PV) scaling upper limit value*7*9	0	R/W	×	○	
744(2E8 _H)	CH2	Process value (PV) scaling value	Process value (PV) scaling value	Process value (PV) scaling value *7	0	R	×	×	Page 416, Appendix 2 (84)
745(2E9 _H)	CH2	Derivative action selection *9	Derivative action selection *9	Derivative action selection *7*9	0	R/W	×	○	Page 417, Appendix 2 (85)
746(2EA _H)	CH2	Simultaneous temperature rise group setting*9	System area	System area	0	R/W	×	○	Page 417, Appendix 2 (86)
747(2EB _H)	CH2	Simultaneous temperature rise gradient data	System area	System area	0	R/W	○	○	Page 418, Appendix 2 (87)
748(2EC _H)	CH2	Simultaneous temperature rise dead time	System area	System area	0	R/W	○	○	Page 418, Appendix 2 (88)
749(2ED _H)	CH2	Simultaneous temperature rise AT mode selection	System area	System area	0	R/W	×	○	Page 419, Appendix 2 (89)
750(2EE _H)	CH2	Simultaneous temperature rise status	System area	System area	0	R	×	×	Page 420, Appendix 2 (90)
751(2EF _H)	CH2	Setting change rate limiter unit time setting*9	Setting change rate limiter unit time setting*9	Setting change rate limiter unit time setting*7*9	0	R/W	×	○	Page 421, Appendix 2 (91)
752(2F0 _H)	CH3	System area	Cooling proportional band (Pc) setting*6	System area	30	R/W	×	○	Page 364, Appendix 2 (15)

Address (decimal (hexadecimal))	Target channel or current sensor (CT)	Setting contents			Default value *1	Read/ Write *2	Automatic setting *3	Non- volatile memory write availability *4	Reference
		Standard control	Heating- cooling control	Mix control					
753(2F1 _H)	CH3	System area	Cooling upper limit output limiter* ⁶	System area	1000	R/W	×	○	Page 369, Appendix 2 (19)
754(2F2 _H)	CH3	System area	Cooling control output cycle setting* ⁶	System area	30/300	R/W	×	○	Page 373, Appendix 2 (23)
755(2F3 _H)	CH3	System area	Overlap/dead band setting* ⁶	System area	0	R/W	×	○	Page 415, Appendix 2 (80)
756(2F4 _H)	CH3	Manual reset amount setting	Manual reset amount setting* ⁶	Manual reset amount setting	0	R/W	×	○	Page 415, Appendix 2 (81)
757(2F5 _H)	CH3	Process value (PV) scaling function enable/disable setting* ⁹	Process value (PV) scaling function enable/disable setting* ^{6,9}	Process value (PV) scaling function enable/disable setting* ⁹	0	R/W	×	○	Page 415, Appendix 2 (82)
758(2F6 _H)	CH3	Process value (PV) scaling lower limit value* ⁹	Process value (PV) scaling lower limit value* ^{6,9}	Process value (PV) scaling lower limit value* ⁹	0	R/W	×	○	Page 416, Appendix 2 (83)
759(2F7 _H)	CH3	Process value (PV) scaling upper limit value* ⁹	Process value (PV) scaling upper limit value* ^{6,9}	Process value (PV) scaling upper limit value* ⁹	0	R/W	×	○	
760(2F8 _H)	CH3	Process value (PV) scaling value	Process value (PV) scaling value* ⁶	Process value (PV) scaling value	0	R	×	×	Page 416, Appendix 2 (84)
761(2F9 _H)	CH3	Derivative action selection * ⁹	Derivative action selection * ^{6,9}	Derivative action selection * ⁹	0	R/W	×	○	Page 417, Appendix 2 (85)
762(2FA _H)	CH3	Simultaneous temperature rise group setting* ⁹	System area	Simultaneous temperature rise group setting* ⁹	0	R/W	×	○	Page 417, Appendix 2 (86)
763(2FB _H)	CH3	Simultaneous temperature rise gradient data	System area	Simultaneous temperature rise gradient data	0	R/W	○	○	Page 418, Appendix 2 (87)
764(2FC _H)	CH3	Simultaneous temperature rise dead time	System area	Simultaneous temperature rise dead time	0	R/W	○	○	Page 418, Appendix 2 (88)
765(2FD _H)	CH3	Simultaneous temperature rise AT mode selection	System area	Simultaneous temperature rise AT mode selection	0	R/W	×	○	Page 419, Appendix 2 (89)
766(2FE _H)	CH3	Simultaneous temperature rise status	System area	Simultaneous temperature rise status	0	R	×	×	Page 420, Appendix 2 (90)
767(2FF _H)	CH3	Setting change rate limiter unit time setting* ⁹	Setting change rate limiter unit time setting* ^{6,9}	Setting change rate limiter unit time setting* ⁹	0	R/W	×	○	Page 421, Appendix 2 (91)

Address (decimal (hexadecimal))	Target channel or current sensor (CT)	Setting contents			Default value *1	Read/ Write *2	Automatic setting *3	Non- volatile memory write availability *4	Reference
		Standard control	Heating- cooling control	Mix control					
768(300 _H)	CH4	System area	Cooling proportional band (Pc) setting*6	System area	30	R/W	×	○	Page 364, Appendix 2 (15)
769(301 _H)	CH4	System area	Cooling upper limit output limiter*6	System area	1000	R/W	×	○	Page 369, Appendix 2 (19)
770(302 _H)	CH4	System area	Cooling control output cycle setting*6	System area	30/300	R/W	×	○	Page 373, Appendix 2 (23)
771(303 _H)	CH4	System area	Overlap/dead band setting*6	System area	0	R/W	×	○	Page 415, Appendix 2 (80)
772(304 _H)	CH4	Manual reset amount setting	Manual reset amount setting*6	Manual reset amount setting	0	R/W	×	○	Page 415, Appendix 2 (81)
773(305 _H)	CH4	Process value (PV) scaling function enable/disable setting*9	Process value (PV) scaling function enable/disable setting*6*9	Process value (PV) scaling function enable/disable setting*9	0	R/W	×	○	Page 415, Appendix 2 (82)
774(306 _H)	CH4	Process value (PV) scaling lower limit value*9	Process value (PV) scaling lower limit value*6*9	Process value (PV) scaling lower limit value*9	0	R/W	×	○	Page 416, Appendix 2 (83)
775(307 _H)	CH4	Process value (PV) scaling upper limit value*9	Process value (PV) scaling upper limit value*6*9	Process value (PV) scaling upper limit value*9	0	R/W	×	○	
776(308 _H)	CH4	Process value (PV) scaling value	Process value (PV) scaling value*6	Process value (PV) scaling value	0	R	×	×	Page 416, Appendix 2 (84)
777(309 _H)	CH4	Derivative action selection*9	Derivative action selection*6*9	Derivative action selection*9	0	R/W	×	○	Page 417, Appendix 2 (85)
778(30A _H)	CH4	Simultaneous temperature rise group setting*9	System area	Simultaneous temperature rise group setting*9	0	R/W	×	○	Page 417, Appendix 2 (86)
779(30B _H)	CH4	Simultaneous temperature rise gradient data	System area	Simultaneous temperature rise gradient data	0	R/W	○	○	Page 418, Appendix 2 (87)
780(30C _H)	CH4	Simultaneous temperature rise dead time	System area	Simultaneous temperature rise dead time	0	R/W	○	○	Page 418, Appendix 2 (88)
781(30D _H)	CH4	Simultaneous temperature rise AT mode selection	System area	Simultaneous temperature rise AT mode selection	0	R/W	×	○	Page 419, Appendix 2 (89)
782(30E _H)	CH4	Simultaneous temperature rise status	System area	Simultaneous temperature rise status	0	R	×	×	Page 420, Appendix 2 (90)

Address (decimal (hexadecimal))	Target channel or current sensor (CT)	Setting contents			Default value *1	Read/ Write *2	Automatic setting *3	Non- volatile memory write availability *4	Reference
		Standard control	Heating- cooling control	Mix control					
783(30F _H)	CH4	Setting change rate limiter unit time setting* ⁹	Setting change rate limiter unit time setting* ^{6,9}	Setting change rate limiter unit time setting* ⁹	0	R/W	×	○	Page 421, Appendix 2 (91)
784(310 _H)	All CHs	Peak current suppression control group setting* ⁹	System area	System area	0	R/W	×	○	Page 422, Appendix 2 (92)
785(311 _H)	All CHs	Sensor correction function selection* ⁹			0	R/W	×	○	Page 423, Appendix 2 (93)
786(312 _H)	All CHs	Temperature conversion completion flag			0	R	×	×	Page 423, Appendix 2 (94)
787(313 _H)	All CHs	Function extension bit monitor			0	R	×	×	Page 424, Appendix 2 (95)
788(314 _H)	All CHs	Sampling cycle monitor			0	R	×	×	Page 424, Appendix 2 (96)
789(315 _H) to 1278(4FE _H)	—	System area			—	—	—	—	—
1279(4FF _H) to 4095(FFF _H)	Buffer memory for error history (👉 Page 78, Section 3.5 (2))								
4096(1000 _H) to 53247(CFFF _H)	—	System area			—	—	—	—	—

- *1 This value is stored when Default setting registration instruction (Yn9) is turned on. The default value varies depending on the mode. For details on the default values, refer to the following.
 Page 344, Appendix 2
- *2 This column indicates whether data can be read from or written to the buffer memory area through sequence programs.
R: Reading enabled
W: Writing enabled
- *3 This column indicates whether the setting in the buffer memory area is automatically changed when the input range is changed. Enable/disable of automatic change can be set on Switch Setting. For details, refer to  Page 241, Section 8.3.4.
- *4 Whether writing to the non-volatile memory by turning off and on Set value backup instruction (Yn8) is enabled in this column. For details, refer to  Page 242, Section 8.3.5.
- *5 (TT) indicates the L60TCTT4 and L60TCTT4BW. (RT) indicates the L60TCRT4 and L60TCRT4BW.
- *6 Available only when the heating-cooling control (expanded mode) is set on Switch Setting. With other models, this area is handled as a system area.
- *7 Available only when the mix control (expanded mode) is set on Switch Setting. With other models, this area is handled as a system area.
- *8 Available only when the L60TCTT4 or L60TCTT4BW is used. With other models, this area is handled as a system area.
- *9 Available only in the setting mode. To enable the setting contents, turn off, on, and on Setting change instruction (YnB) when Setting/operation mode instruction (Yn1) is off (during setting mode). Note that a write data error (error code: □□□3H) occurs if the setting is changed during the operation mode.
- *10 By using the setting change rate limiter, whether to set temperature rise/temperature drop in a batch or individually can be selected on Switch Setting. In the batch setting, the target of setting change rate limiter is only this area. In the individual setting, this area is the setting target for the temperature rise. For details, refer to  Page 159, Section 8.2.10.
- *11 Available only when the L60TCTT4BW or L60TCRT4BW is used. With other models, this area is handled as a system area.
- *12 By using the setting change rate limiter, whether to set temperature rise/temperature drop in a batch or individually can be selected on Switch Setting. In the batch setting, this area is handled as a system area. In the individual setting, this area is the setting target for the temperature drop. For details, refer to  Page 159, Section 8.2.10.
- *13 Available only when the heating-cooling control (normal mode) is set on Switch Setting. With other models, this area is handled as a system area.
- *14 Available only when the mix control (normal mode) is set on Switch Setting. With other models, this area is handled as a system area.

(2) Buffer memory address for error history

Address (decimal (hexadecimal))	Target channel	Setting contents				Default value *1	Read/ Write *2	Automatic setting *3	Non- volatile memory write availability *4	Reference
1279(4FF _H)	All CHs	Latest address of error history				0	R	×	×	Page 425, Appendix 2 (97)
1280(500 _H)	All CHs	History 1	Error code			0	R	×	×	Page 425, Appendix 2 (98)
1281(501 _H)			Error occurrence time	Upper 2 digits of year	Lower 2 digits of year					
1282(502 _H)				Month	Day					
1283(503 _H)				Hour	Minute					
1284(504 _H)				Second	Day of the week					
1285(505 _H) to 1287(507 _H)	—	System area				—	—	—	—	—
1288(508 _H) to 1292(50C _H)	All CHs	History 2	Error code, error occurrence time (Data structure is the same as that of History 1.)			0	R	×	×	Page 425, Appendix 2 (98)
1293(50D _H) to 1295(50F _H)	—	System area				—	—	—	—	—
1296(510 _H) to 1300(514 _H)	All CHs	History 3	Error code, error occurrence time (Data structure is the same as that of History 1.)			0	R	×	×	Page 425, Appendix 2 (98)
1301(515 _H) to 1303(517 _H)	—	System area				—	—	—	—	—
1304(518 _H) to 1308(51C _H)	All CHs	History 4	Error code, error occurrence time (Data structure is the same as that of History 1.)			0	R	×	×	Page 425, Appendix 2 (98)
1309(51D _H) to 1311(51F _H)	—	System area				—	—	—	—	—
1312(520 _H) to 1316(524 _H)	All CHs	History 5	Error code, error occurrence time (Data structure is the same as that of History 1.)			0	R	×	×	Page 425, Appendix 2 (98)
1317(525 _H) to 1319(527 _H)	—	System area				—	—	—	—	—
1320(528 _H) to 1324(52C _H)	All CHs	History 6	Error code, error occurrence time (Data structure is the same as that of History 1.)			0	R	×	×	Page 425, Appendix 2 (98)

Address (decimal (hexadecimal))	Target channel	Setting contents		Default value *1	Read/ Write *2	Automatic setting *3	Non- volatile memory write availability *4	Reference
1325(52D _H) to 1327(52F _H)	—	System area		—	—	—	—	—
1328(530 _H) to 1332(534 _H)	All CHs	History 7	Error code, error occurrence time (Data structure is the same as that of History 1.)	0	R	×	×	Page 425, Appendix 2 (98)
1333(535 _H) to 1335(537 _H)	—	System area		—	—	—	—	—
1336(538 _H) to 1340(53C _H)	All CHs	History 8	Error code, error occurrence time (Data structure is the same as that of History 1.)	0	R	×	×	Page 425, Appendix 2 (98)
1341(53D _H) to 1343(53F _H)	—	System area		—	—	—	—	—
1344(540 _H) to 1348(544 _H)	All CHs	History 9	Error code, error occurrence time (Data structure is the same as that of History 1.)	0	R	×	×	Page 425, Appendix 2 (98)
1349(545 _H) to 1351(547 _H)	—	System area		—	—	—	—	—
1352(548 _H) to 1356(54C _H)	All CHs	History 10	Error code, error occurrence time (Data structure is the same as that of History 1.)	0	R	×	×	Page 425, Appendix 2 (98)
1357(54D _H) to 1359(54F _H)	—	System area		—	—	—	—	—
1360(550 _H) to 1364(554 _H)	All CHs	History 11	Error code, error occurrence time (Data structure is the same as that of History 1.)	0	R	×	×	Page 425, Appendix 2 (98)
1365(555 _H) to 1367(557 _H)	—	System area		—	—	—	—	—
1368(558 _H) to 1372(55C _H)	All CHs	History 12	Error code, error occurrence time (Data structure is the same as that of History 1.)	0	R	×	×	Page 425, Appendix 2 (98)
1373(55D _H) to 1375(55F _H)	—	System area		—	—	—	—	—
1376(560 _H) to 1380(564 _H)	All CHs	History 13	Error code, error occurrence time (Data structure is the same as that of History 1.)	0	R	×	×	Page 425, Appendix 2 (98)

Address (decimal (hexadecimal))	Target channel	Setting contents		Default value ^{*1}	Read/ Write ^{*2}	Automatic setting ^{*3}	Non- volatile memory write availability ^{*4}	Reference
1381(565 _H) to 1383(567 _H)	—	System area		—	—	—	—	—
1384(568 _H) to 1388(56C _H)	All CHs	History 14	Error code, error occurrence time (Data structure is the same as that of History 1.)	0	R	×	×	Page 425, Appendix 2 (98)
1389(56D _H) to 1391(56F _H)	—	System area		—	—	—	—	—
1392(570 _H) to 1396(574 _H)	All CHs	History 15	Error code, error occurrence time (Data structure is the same as that of History 1.)	0	R	×	×	Page 425, Appendix 2 (98)
1397(575 _H) to 1399(577 _H)	—	System area		—	—	—	—	—
1400(578 _H) to 1404(57C _H)	All CHs	History 16	Error code, error occurrence time (Data structure is the same as that of History 1.)	0	R	×	×	Page 425, Appendix 2 (98)
1405(57D _H) to 4095(FFF _H)	—	System area		—	—	—	—	—

^{*1} This default value is set after the module is turned off and on or after the CPU module is reset and the reset is cancelled.

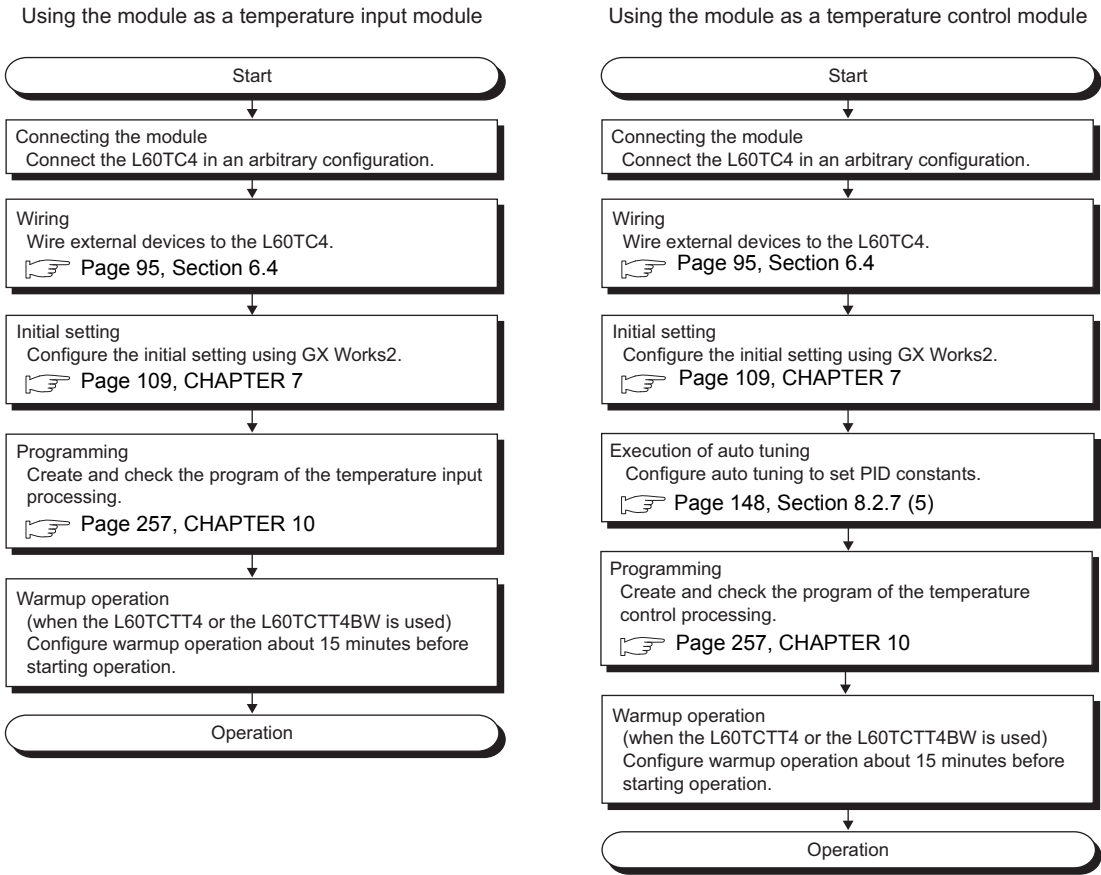
^{*2} This column indicates whether data can be read from or written to the buffer memory area through sequence programs.
R: Reading enabled
W: Writing enabled

^{*3} This column indicates whether the setting in the buffer memory area is automatically changed when the input range is changed. Enable/disable of automatic change can be set on Switch Setting. For details, refer to  Page 241, Section 8.3.4.

^{*4} Whether writing to the non-volatile memory by turning off and on Set value backup instruction (Yn8) is enabled in this column. For details, refer to  Page 242, Section 8.3.5.

CHAPTER 4 PROCEDURE BEFORE OPERATION

This chapter describes the procedure before operating the L60TC4.



Point

When using the L60TCTT4 and the L60TCTT4BW which use the thermocouples as the temperature sensors, temperature compensation must be executed properly. Perform warm-up operation about 15 minutes before starting operation.

Memo

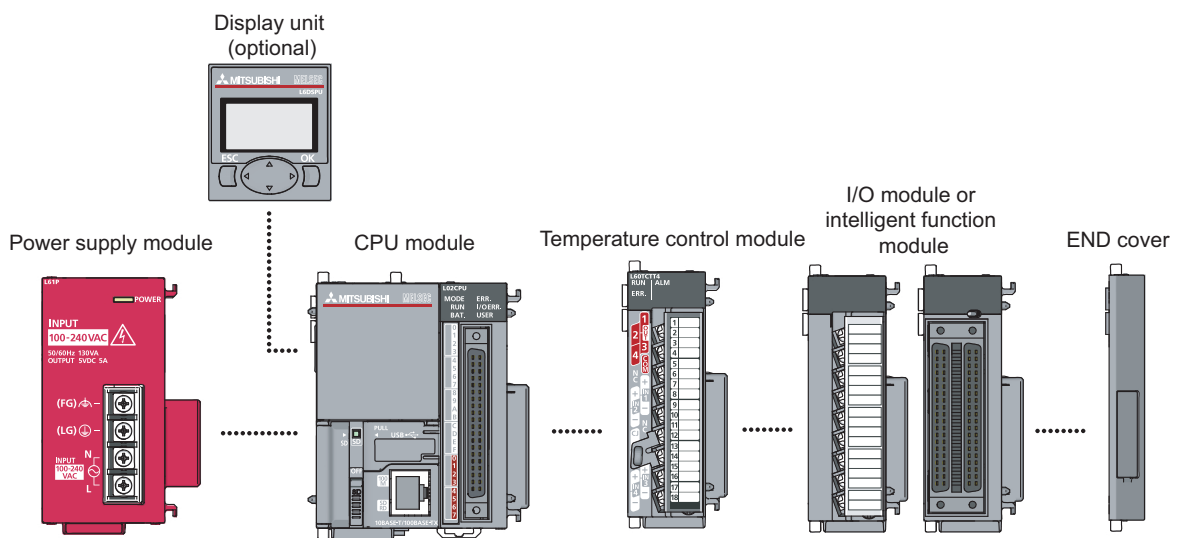
CHAPTER 5 SYSTEM CONFIGURATION

This chapter describes the total configuration of the L60TC4, number of connectable modules, and applicable software version.

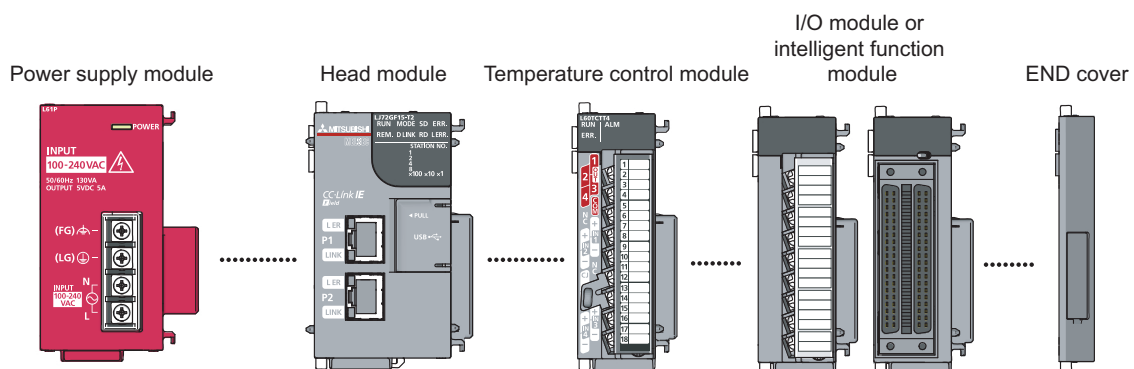
5.1 Total Configuration

This section describes examples of system configurations when using the L60TC4.

(1) Connecting to a CPU module



(2) Connecting to a head module



5.2 Applicable Systems

(1) Number of connectable modules

A CPU module and a head module recognize one L60TCTT4BW or L60TCRT4BW as two modules. Therefore, number of connectable modules reduces to half of other modules.

For the number of connectable modules, refer to the following.

-  MELSEC-L CPU Module User's Manual (Hardware Design, Maintenance and Inspection)
-  MELSEC-L CC-Link IE Field Network Head Module User's Manual

(2) Applicable software version

For applicable software version, refer to the following.

-  MELSEC-L CPU Module User's Manual (Hardware Design, Maintenance and Inspection)
-  MELSEC-L CC-Link IE Field Network Head Module User's Manual

(3) Temperature sensor

For usable temperature sensors, refer to the following.

- Types of usable temperature sensor ( Page 37, Section 3.2.2)

(4) Current sensor for heater disconnection detection

The following table lists current sensors for heater disconnection detection available with the L60TCTT4BW or L60TCRT4BW.

Model name	Remarks	Manufacturer
CTL-12-S36-8 (0.0 to 100.0A)* ¹	—	U.R.D.Co., LTD. www.u-rd.com/english
CTL-12-S36-10 (0.0 to 100.0A)		
CTL-12-S56-10 (0.0 to 100.0A)		
CTL-6-P (0.00 to 20.00A)* ¹		
CTL-6-P-H (0.00 to 20.00A)		

*1 The CTL-12-S36-8 and CTL-6-P can be used although they have been discontinued.

For how to select current sensors for heater disconnection detection, refer to the following.

- Selecting a current sensor for heater disconnection detection ( Page 401, Appendix 2 (60))
- Setting of the number of second-winding of connected current sensor ( Page 402, Appendix 2 (62))

5.3 Restrictions When Temperature Control Module Is Used with Head Module

There is no restrictions when the temperature control module is used with a head module.

5.4 Precautions for System Configuration

The L60TC4 measures temperature based on the temperature of the terminal block. Therefore, depending on the system configuration, temperature distribution of the terminal block can be uneven due to the effect of heat generated from modules, and the measured temperature may differ from actual temperature (especially when two or more L60TC4 modules are connected next to each other or the L60TC4 is mounted next to the power supply module or CPU module).

In this case, the difference between measured value and actual temperature can be reduced by the following methods.

(1) Using the sensor correction function

The measured temperature can be corrected to the actual temperature by this function.

For details on the sensor correction function, refer to the following.

 Page 230, Section 8.3.3

CHAPTER 6 INSTALLATION AND WIRING

This chapter describes the installation and wiring of the L60TC4.

6.1 Installation Environment and Installation Position

For precautions for installation environment and installation position, refer to the following.

-  MELSEC-L CPU Module User's Manual (Hardware Design, Maintenance and Inspection)
-  MELSEC-L CC-Link IE Field Network Head Module User's Manual

6.2 Terminal Block

(1) Precautions

Tighten the terminal block screws within the following specified torque range.

Undertightening can cause drop of the screw, short circuit, or malfunction. Overtightening can damage the screw and/or module, resulting in drop, short circuit, or malfunction.

Screw	Tightening torque range
Terminal screw (M3 screw)	0.42 to 0.58N • m
Terminal block mounting screw (M3.5 screw)	0.66 to 0.89N • m

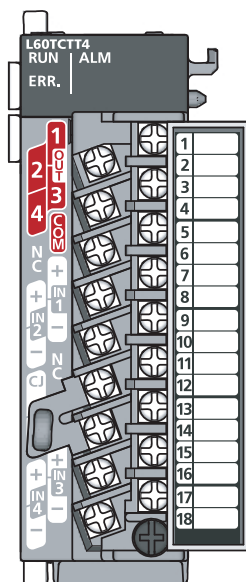
The following table shows the applicable solderless terminal installed to the terminal block. For wiring, use the wire applicable to the following wire and mount with the applicable tightening torque. Use a UL-approved solderless terminal and tools recommended by the manufacturer of the solderless terminal. The sleeve solderless terminal cannot be used.

Solderless terminal		Wire			
Model name	Applicable tightening torque	Wire diameter	Type	Material	Temperature rating
R1.25-3	0.42 to 0.58N • m	22 to 18 AWG	Stranded wire	Copper wire	75°C or more

(2) Signal names of terminal blocks

The following shows signal names of terminal blocks.

(a) L60TCTT4, L60TCTT4BW (terminal block for I/O)



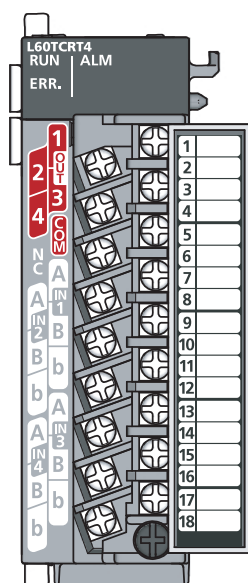
Terminal number	Indication	Temperature input		Standard control	
		Symbol	Name	Symbol	Name
1	OUT1	—	Unused	L1	CH1 Output
2	OUT2	—	Unused	L2	CH2 Output
3	OUT3	—	Unused	L3	CH3 Output
4	OUT4	—	Unused	L4	CH4 Output
5	COM	—	Unused	COM-	Output common
6	NC	NC	Unused	NC	Unused
7	IN1+	MT1+	Monitor 1 thermocouple +	CH1+	CH1 Thermocouple +
8	IN2+	MT2+	Monitor 2 thermocouple +	CH2+	CH2 Thermocouple +
9	IN1-	MT1-	Monitor 1 thermocouple -	CH1-	CH1 Thermocouple -
10	IN2-	MT2-	Monitor 2 thermocouple -	CH2-	CH2 Thermocouple -
11	NC	NC	Unused	NC	Unused
12	CJ	CJ	Cold junction temperature compensation resistor	CJ	Cold junction temperature compensation resistor
13	NC	NC	Unused	NC	Unused
14	CJ	CJ	Cold junction temperature compensation resistor	CJ	Cold junction temperature compensation resistor
15	IN3+	MT3+	Monitor 3 thermocouple +	CH3+	CH3 Thermocouple +
16	IN4+	MT4+	Monitor 4 thermocouple +	CH4+	CH4 Thermocouple +
17	IN3-	MT3-	Monitor 3 thermocouple -	CH3-	CH3 Thermocouple -
18	IN4-	MT4-	Monitor 4 thermocouple -	CH4-	CH4 Thermocouple -

Terminal number	Indication	Heating-cooling control (normal mode)		Heating-cooling control (expanded mode)		Mix control (normal mode)		Mix control (expanded mode)	
		Symbol	Name	Symbol	Name	Symbol	Name	Symbol	Name
1	OUT1	L1H	CH1 Heating output	L1H	CH1 Heating output	L1H	CH1 Heating output	L1H	CH1 Heating output
2	OUT2	L1C	CH1 Cooling output	L1C	CH1 Cooling output	L1C	CH1 Cooling output	L1C	CH1 Cooling output
3	OUT3	L2H	CH2 Heating output	L2H	CH2 Heating output	L3	CH3 Output	L3	CH3 Output
4	OUT4	L2C	CH2 Cooling output	L2C	CH2 Cooling output	L4	CH4 Output	L4	CH4 Output
5	COM	COM-	Output common	COM-	Output common	COM-	Output common	COM-	Output common
6	NC	NC	Unused	NC	Unused	NC	Unused	NC	Unused
7	IN1+	CH1+	CH1 Thermocouple +	CH1+	CH1 Thermocouple +	CH1+	CH1 Thermocouple +	CH1+	CH1 Thermocouple +
8	IN2+	CH2+	CH2 Thermocouple +	CH2+	CH2 Thermocouple +	MT2+	Monitor 2 thermocouple +	CH2+	CH2 Thermocouple +
9	IN1-	CH1-	CH1 Thermocouple -	CH1-	CH1 Thermocouple -	CH1-	CH1 Thermocouple -	CH1-	CH1 Thermocouple -
10	IN2-	CH2-	CH2 Thermocouple -	CH2-	CH2 Thermocouple -	MT2-	Monitor 2 thermocouple -	CH2-	CH2 Thermocouple -
11	NC	NC	Unused	NC	Unused	NC	Unused	NC	Unused
12	CJ	CJ	Cold junction temperature compensation resistor	CJ	Cold junction temperature compensation resistor	CJ	Cold junction temperature compensation resistor	CJ	Cold junction temperature compensation resistor
13	NC	NC	Unused	NC	Unused	NC	Unused	NC	Unused
14	CJ	CJ	Cold junction temperature compensation resistor	CJ	Cold junction temperature compensation resistor	CJ	Cold junction temperature compensation resistor	CJ	Cold junction temperature compensation resistor
15	IN3+	MT3+	Monitor 3 thermocouple +	CH3+	CH3 Thermocouple +	CH3+	CH3 Thermocouple +	CH3+	CH3 Thermocouple +
16	IN4+	MT4+	Monitor 4 thermocouple +	CH4+	CH4 Thermocouple +	CH4+	CH4 Thermocouple +	CH4+	CH4 Thermocouple +
17	IN3-	MT3-	Monitor 3 thermocouple -	CH3-	CH3 Thermocouple -	CH3-	CH3 Thermocouple -	CH3-	CH3 Thermocouple -
18	IN4-	MT4-	Monitor 4 thermocouple -	CH4-	CH4 Thermocouple -	CH4-	CH4 Thermocouple -	CH4-	CH4 Thermocouple -

Point

Do not remove the cold junction temperature compensation resistor from the terminal block.

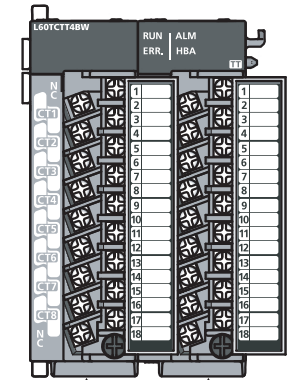
(b) L60TCRT4, L60TCRT4BW (terminal block for I/O)



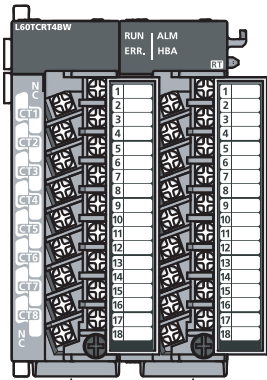
Terminal number	Indication	Temperature input		Standard control	
		Symbol	Name	Symbol	Name
1	OUT1	—	Unused	L1	CH1 Output
2	OUT2	—	Unused	L2	CH2 Output
3	OUT3	—	Unused	L3	CH3 Output
4	OUT4	—	Unused	L4	CH4 Output
5	COM	—	Unused	COM-	Output common
6	NC	NC	Unused	NC	Unused
7	IN1 A	MT1 A	Monitor 1 resistance thermometer A	CH1 A	CH1 Resistance thermometer A
8	IN2 A	MT2 A	Monitor 2 resistance thermometer A	CH2 A	CH2 Resistance thermometer A
9	IN1 B	MT1 B	Monitor 1 resistance thermometer B	CH1 B	CH1 Resistance thermometer B
10	IN2 B	MT2 B	Monitor 2 resistance thermometer B	CH2 B	CH2 Resistance thermometer B
11	IN1 b	MT1 b	Monitor 1 resistance thermometer b	CH1 b	CH1 Resistance thermometer b
12	IN2 b	MT2 b	Monitor 2 resistance thermometer b	CH2 b	CH2 Resistance thermometer b
13	IN3 A	MT3 A	Monitor 3 resistance thermometer A	CH3 A	CH3 Resistance thermometer A
14	IN4 A	MT4 A	Monitor 4 resistance thermometer A	CH4 A	CH4 Resistance thermometer A
15	IN3 B	MT3 B	Monitor 3 resistance thermometer B	CH3 B	CH3 Resistance thermometer B
16	IN4 B	MT4 B	Monitor 4 resistance thermometer B	CH4 B	CH4 Resistance thermometer B
17	IN3 b	MT3 b	Monitor 3 resistance thermometer b	CH3 b	CH3 Resistance thermometer b
18	IN4 b	MT4 b	Monitor 4 resistance thermometer b	CH4 b	CH4 Resistance thermometer b

Terminal number	Indication	Heating-cooling control (normal mode)		Heating-cooling control (expanded mode)		Mix control (normal mode)		Mix control (expanded mode)	
		Symbol	Name	Symbol	Name	Symbol	Name	Symbol	Name
1	OUT1	L1H	CH1 Heating output	L1H	CH1 Heating output	L1H	CH1 Heating output	L1H	CH1 Heating output
2	OUT2	L1C	CH1 Cooling output	L1C	CH1 Cooling output	L1C	CH1 Cooling output	L1C	CH1 Cooling output
3	OUT3	L2H	CH2 Heating output	L2H	CH2 Heating output	L3	CH3 Output	L3	CH3 Output
4	OUT4	L2C	CH2 Cooling output	L2C	CH2 Cooling output	L4	CH4 Output	L4	CH4 Output
5	COM	COM-	Output common	COM-	Output common	COM-	Output common	COM-	Output common
6	NC	NC	Unused	NC	Unused	NC	Unused	NC	Unused
7	IN1 A	CH1 A	CH1 Resistance thermometer A	CH1 A	CH1 Resistance thermometer A	CH1 A	CH1 Resistance thermometer A	CH1 A	CH1 Resistance thermometer A
8	IN2 A	CH2 A	CH2 Resistance thermometer A	CH2 A	CH2 Resistance thermometer A	MT2 A	Monitor 2 resistance thermometer A	CH2 A	CH2 Resistance thermometer A
9	IN1 B	CH1 B	CH1 Resistance thermometer B	CH1 B	CH1 Resistance thermometer B	CH1 B	CH1 Resistance thermometer B	CH1 B	CH1 Resistance thermometer B
10	IN2 B	CH2 B	CH2 Resistance thermometer B	CH2 B	CH2 Resistance thermometer B	MT2 B	Monitor 2 resistance thermometer B	CH2 B	CH2 Resistance thermometer B
11	IN1 b	CH1 b	CH1 Resistance thermometer b	CH1 b	CH1 Resistance thermometer b	CH1 b	CH1 Resistance thermometer b	CH1 b	CH1 Resistance thermometer b
12	IN2 b	CH2 b	CH2 Resistance thermometer b	CH2 b	CH2 Resistance thermometer b	MT2 b	Monitor 2 resistance thermometer b	CH2 b	CH2 Resistance thermometer b
13	IN3 A	MT3 A	Monitor 3 resistance thermometer A	CH3 A	CH3 Resistance thermometer A	CH3 A	CH3 Resistance thermometer A	CH3 A	CH3 Resistance thermometer A
14	IN4 A	MT4 A	Monitor 4 resistance thermometer A	CH4 A	CH4 Resistance thermometer A	CH4 A	CH4 Resistance thermometer A	CH4 A	CH4 Resistance thermometer A
15	IN3 B	MT3 B	Monitor 3 resistance thermometer B	CH3 B	CH3 Resistance thermometer B	CH3 B	CH3 Resistance thermometer B	CH3 B	CH3 Resistance thermometer B
16	IN4 B	MT4 B	Monitor 4 resistance thermometer B	CH4 B	CH4 Resistance thermometer B	CH4 B	CH4 Resistance thermometer B	CH4 B	CH4 Resistance thermometer B
17	IN3 b	MT3 b	Monitor 3 resistance thermometer b	CH3 b	CH3 Resistance thermometer b	CH3 b	CH3 Resistance thermometer b	CH3 b	CH3 Resistance thermometer b
18	IN4 b	MT4 b	Monitor 4 resistance thermometer b	CH4 b	CH4 Resistance thermometer b	CH4 b	CH4 Resistance thermometer b	CH4 b	CH4 Resistance thermometer b

(c) L60TCTT4BW (terminal block for CT), L60TCRT4BW (terminal block for CT)



Terminal block for CT Terminal block for I/O



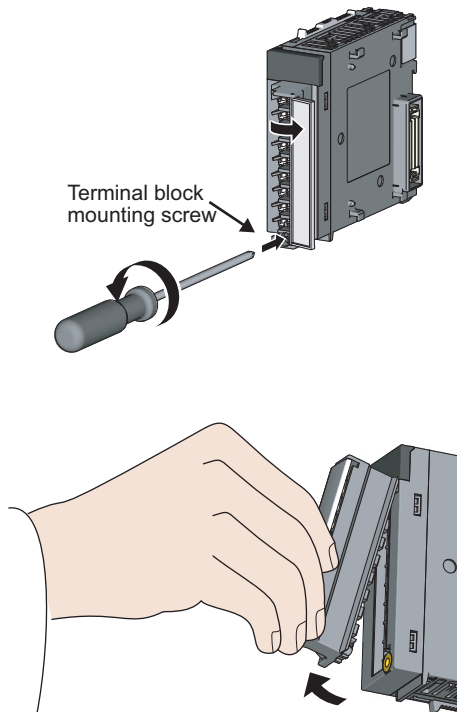
Terminal block for CT Terminal block for I/O

Terminal number	Indication	Standard control	
		Symbol	Name
1	NC	NC	Unused
2	CT1	CT1	CT input 1
3	CT1	CT1	CT input 1
4	CT2	CT2	CT input 2
5	CT2	CT2	CT input 2
6	CT3	CT3	CT input 3
7	CT3	CT3	CT input 3
8	CT4	CT4	CT input 4
9	CT4	CT4	CT input 4
10	CT5	CT5	CT input 5
11	CT5	CT5	CT input 5
12	CT6	CT6	CT input 6
13	CT6	CT6	CT input 6
14	CT7	CT7	CT input 7
15	CT7	CT7	CT input 7
16	CT8	CT8	CT input 8
17	CT8	CT8	CT input 8
18	NC	NC	Unused

(3) Removal and installation of the terminal block

The following shows how to remove and install the terminal block.

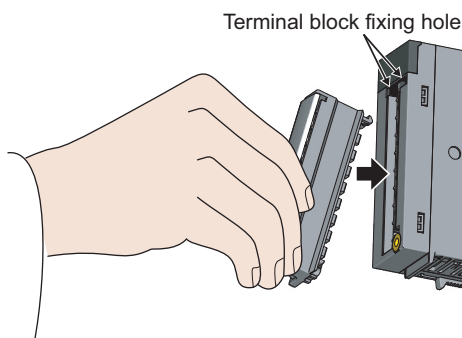
(a) Removal procedure



1. Open the terminal cover and loosen the terminal block mounting screw.

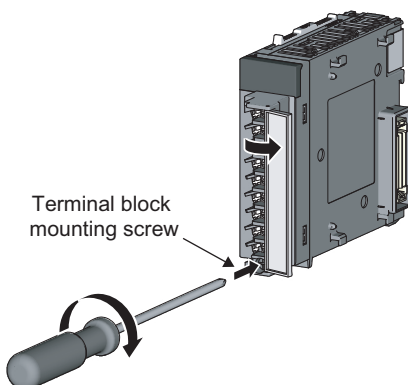
2. Using the terminal block fixing hole as a supporting point, remove the terminal block.

(b) Installation procedure



1. Fully insert the projections on the top of the terminal block into the terminal block fixing holes of the module and press the terminal block until it snaps into place.

2. Open the terminal cover and tighten the terminal block mounting screw.



6.3 Wiring precautions

External wiring that is less likely to be affected by noise is one of the conditions for a highly reliable system that fully utilizes the L60TC4.

This section describes wiring precautions.

- Use separate cables for the AC control circuit and the L60TC4's external I/O signals to avoid influence of AC side surges and induction.
- Do not locate external wires near the main circuit line, high-voltage circuit lines, and load circuit lines of devices other than programmable controllers such as an inverter. Also, do not bunch external wires with these lines. Otherwise, the external wires are more likely to be affected by noise, surges, and induction.
- Ground shielded cables at one end on the programmable controller side. However, depending on the external noise condition, it should be grounded on the other side.
- To ensure that this product maintains EMC and Low Voltage Directives, refer to the following.

 MELSEC-L CPU Module User's Manual (Hardware Design, Maintenance and Inspection)

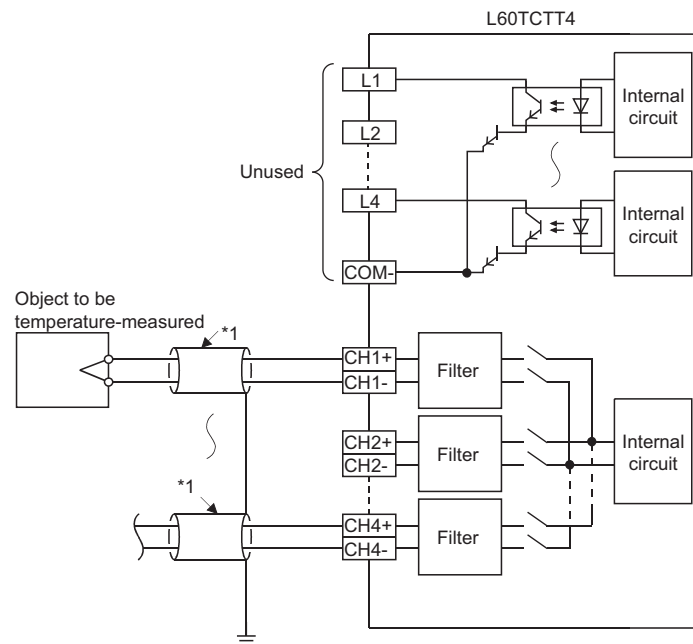
 MELSEC-L CC-Link IE Field Network Head Module User's Manual

6.4 External wiring

The following figure shows the external wiring.

6.4.1 L60TCTT4

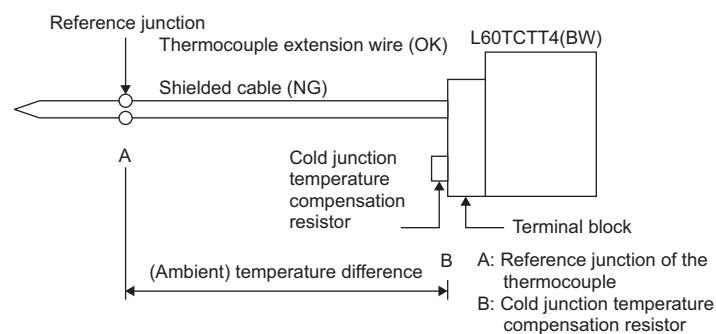
(1) In the temperature input mode



*1 Use the shielded compensation lead wire.

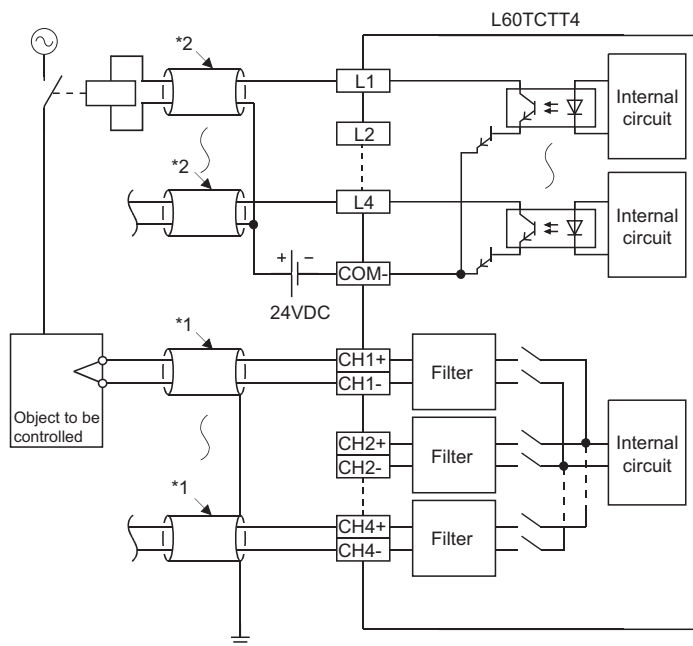
Point

Use the compensation lead wire for the cable of thermocouple. If the compensation lead wire is not used, and when the cold junction temperature compensation resistor is away from the end tip of thermocouple, the (ambient) temperature difference may lead to a faulty temperature process value (PV).



(2) In the temperature control mode

(a) In the standard control

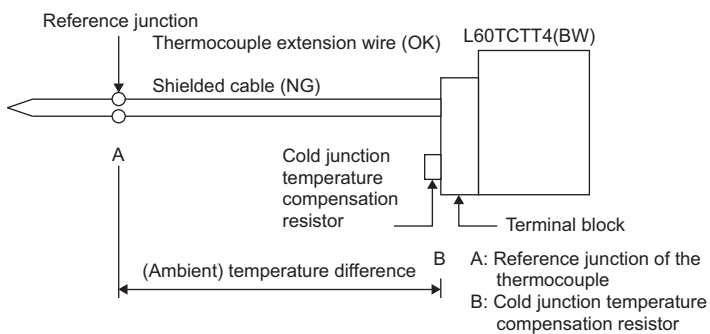


*1 Use the shielded compensation lead wire.

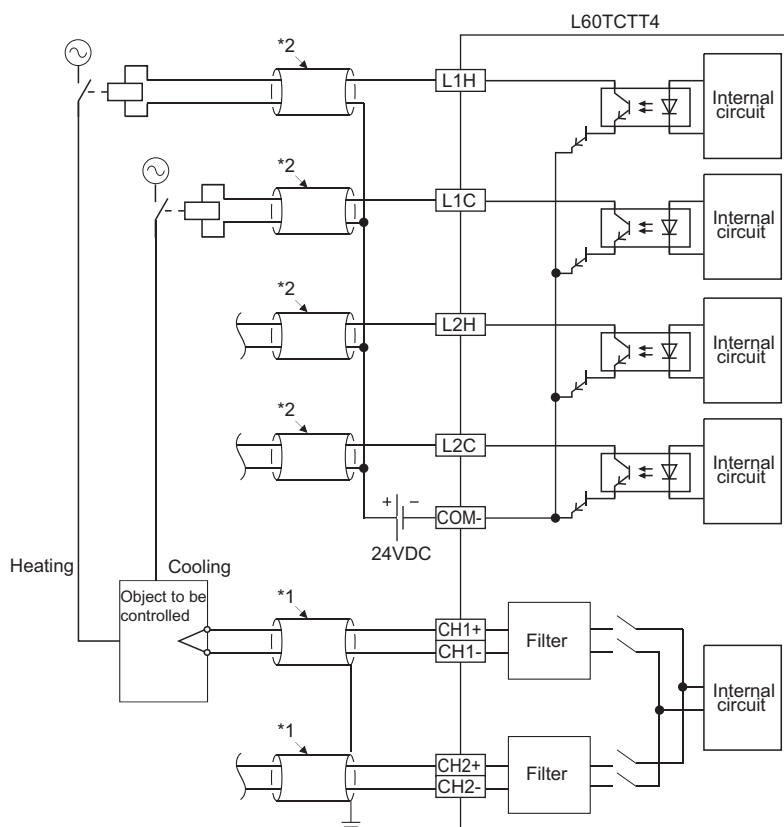
*2 Use the shielded cable.

Point

Use the compensation lead wire for the cable of thermocouple. If the compensation lead wire is not used, and when the cold junction temperature compensation resistor is away from the end tip of thermocouple, the (ambient) temperature difference may lead to a faulty temperature process value (PV).



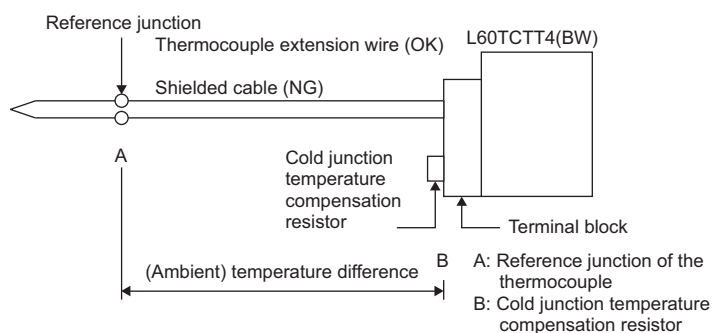
(b) In the heating-cooling control



- *1 Use the shielded compensation lead wire.
- *2 Use the shielded cable.

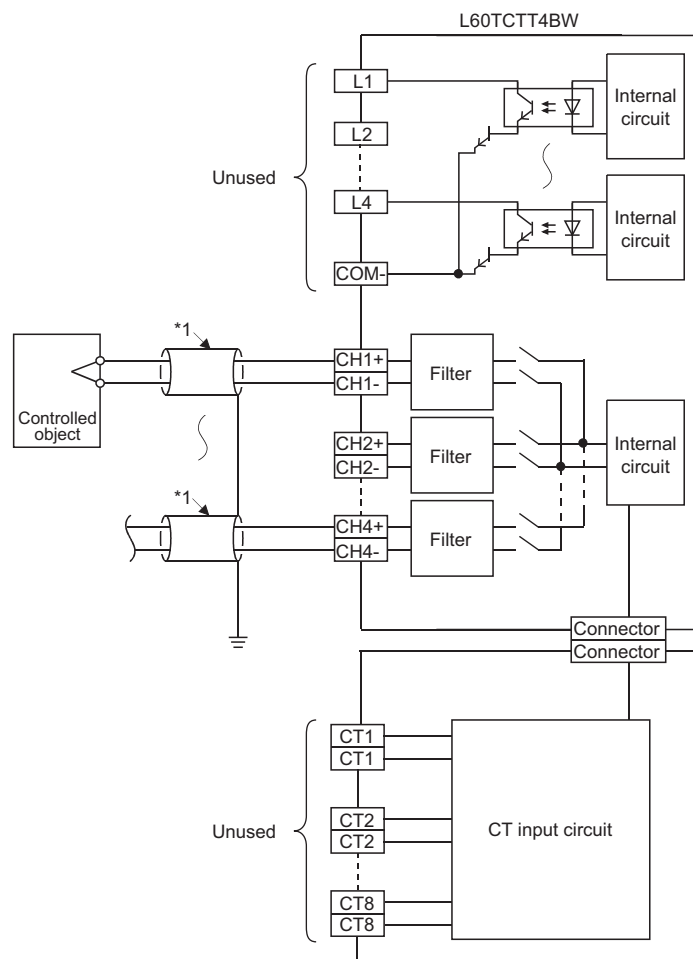
Point

Use the compensation lead wire for the cable of thermocouple. If the compensation lead wire is not used, and when the cold junction temperature compensation resistor is away from the end tip of thermocouple, the (ambient) temperature difference may lead to a faulty temperature process value (PV).



6.4.2 L60TCTT4BW

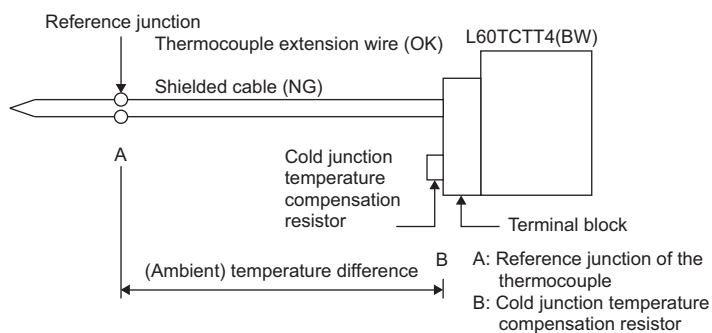
(1) In the temperature input mode

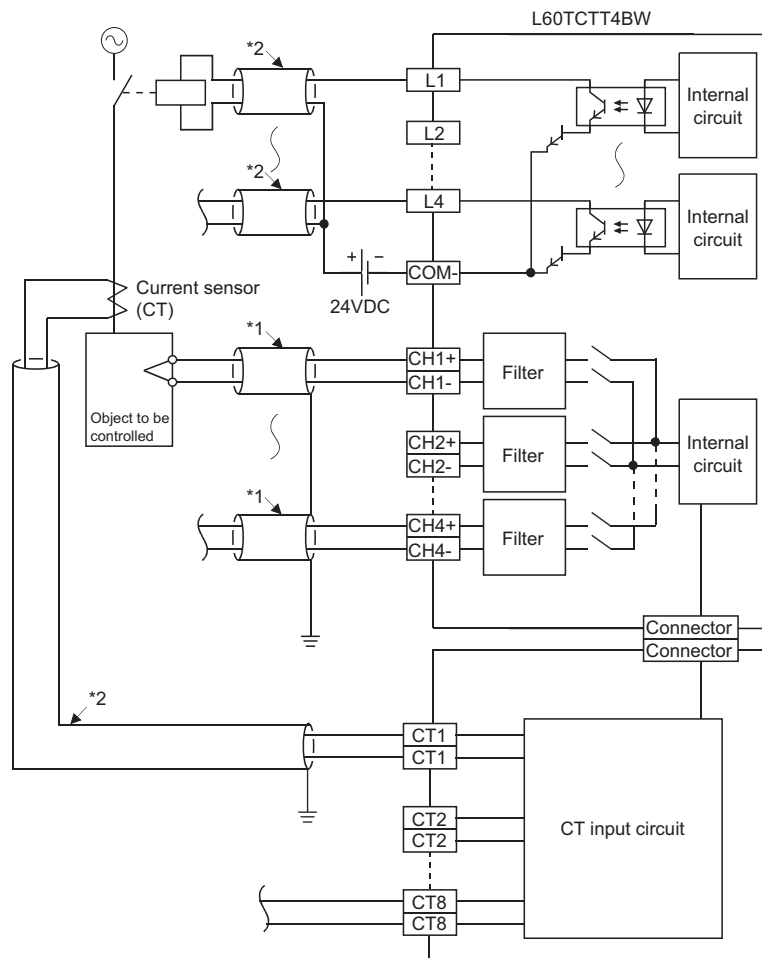


*1 Use the shielded compensation lead wire.

Point

Use the compensation lead wire for the cable of thermocouple. If the compensation lead wire is not used, and when the cold junction temperature compensation resistor is away from the end tip of thermocouple, the (ambient) temperature difference may lead to a faulty temperature process value (PV).



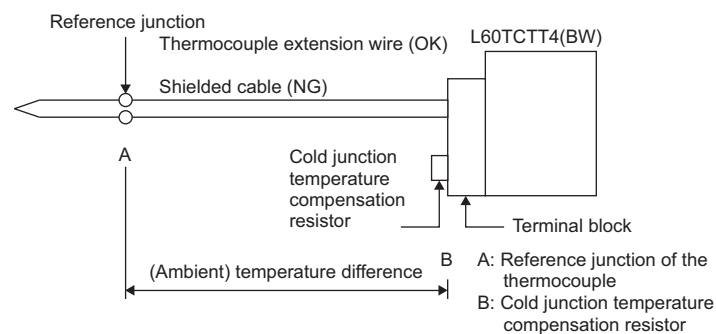
(2) In the temperature control mode**(a) In the standard control**

*1 Use the shielded compensation lead wire.

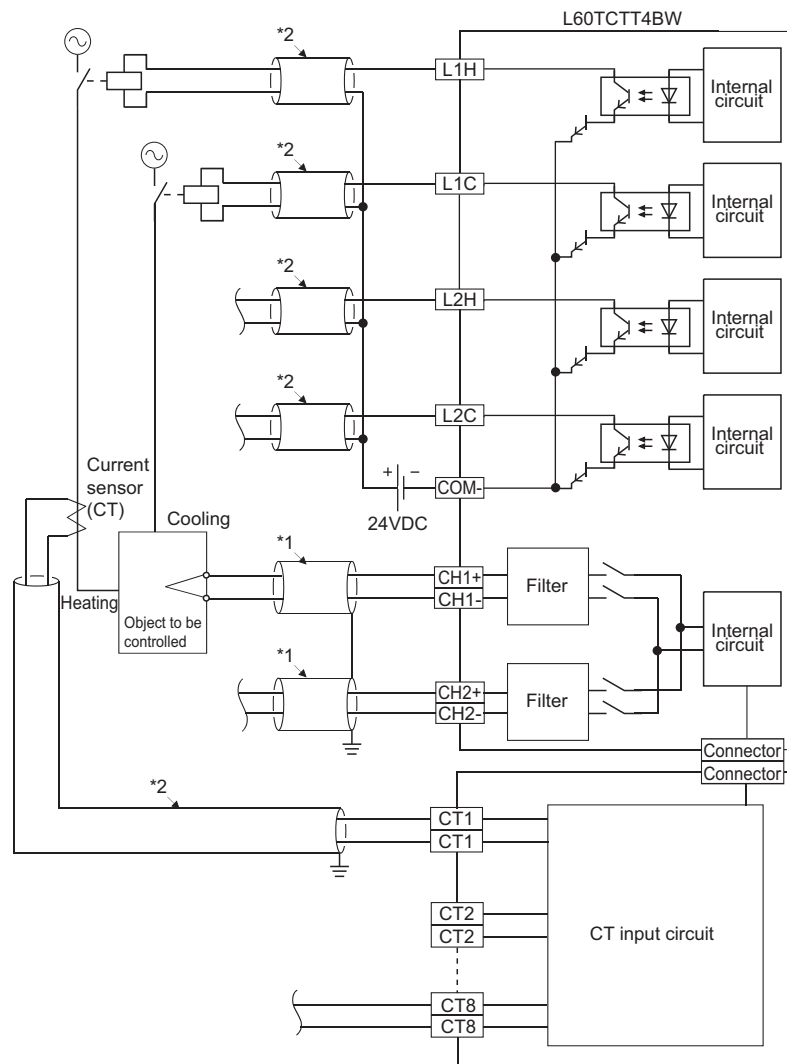
*2 Use the shielded cable.

Point

- To use the heater disconnection detection function, the CT input channel assignment must be set. Since the CT1 is used in the loop of CH1 in the above wiring example, set CH1(1) to CT1 CT input channel assignment setting (Un\G264).
- Use the compensation lead wire for the cable of thermocouple. If the compensation lead wire is not used, and when the cold junction temperature compensation resistor is away from the end tip of thermocouple, the (ambient) temperature difference may lead to a faulty temperature process value (PV).



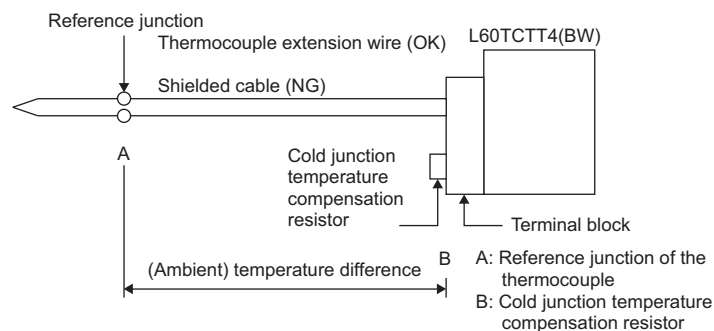
(b) In the heating-cooling control



- *1 Use the shielded compensation lead wire.
- *2 Use the shielded cable.

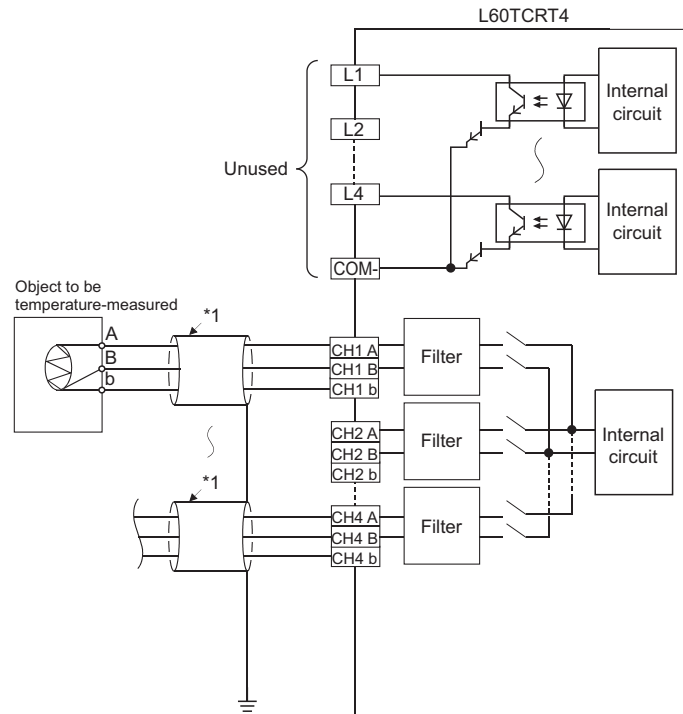
Point

- To use the heater disconnection detection function, the CT input channel assignment must be set. Since the CT1 is used in the loop of CH1 in the above wiring example, set CH1(1) to CT1 CT input channel assignment setting (Un\G264).
- Use the compensation lead wire for the cable of thermocouple. If the compensation lead wire is not used, and when the cold junction temperature compensation resistor is away from the end tip of thermocouple, the (ambient) temperature difference may lead to a faulty temperature process value (PV).



6.4.3 L60TCRT4

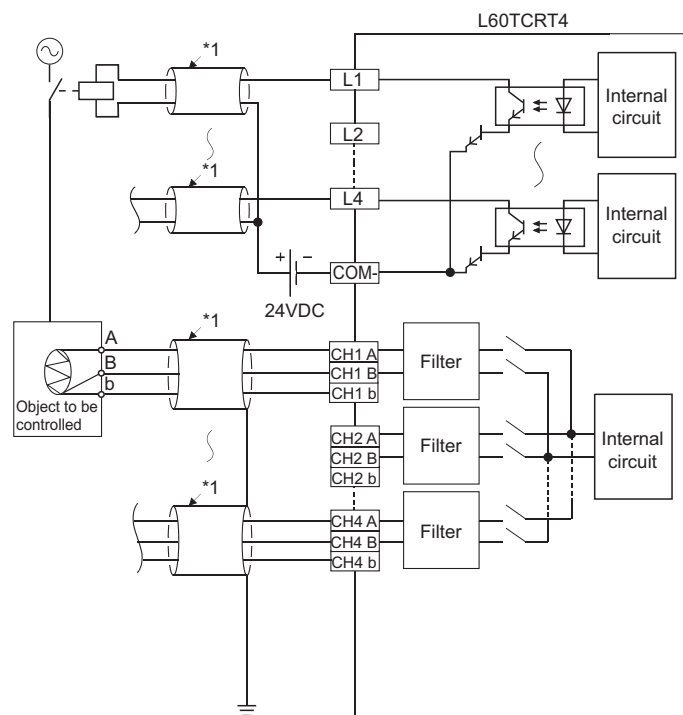
(1) In the temperature input mode



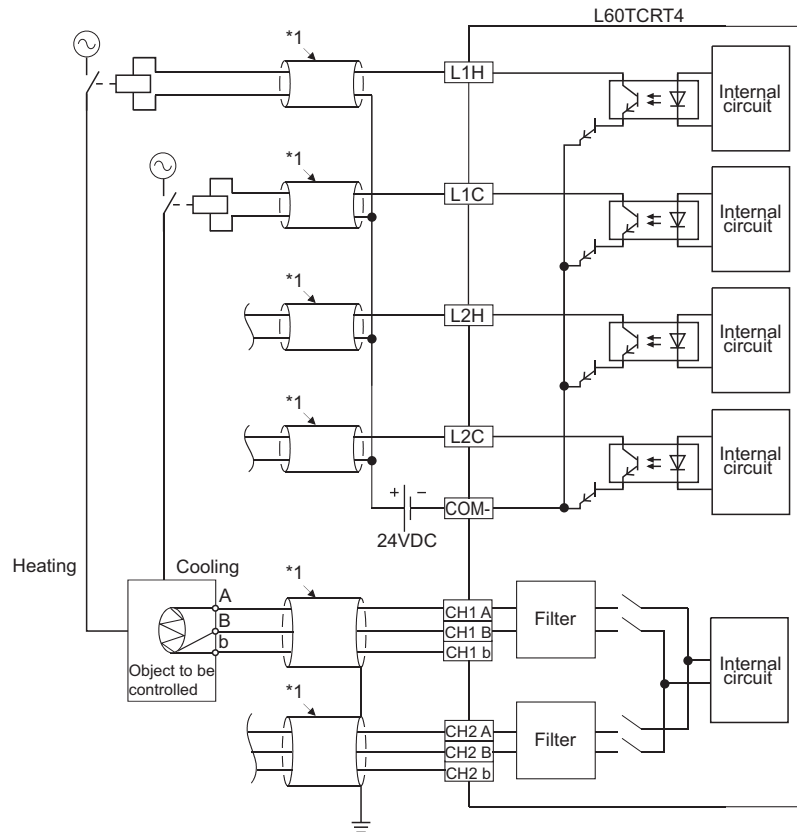
*1 Use the shielded cable.

(2) In the temperature control mode

(a) In the standard control



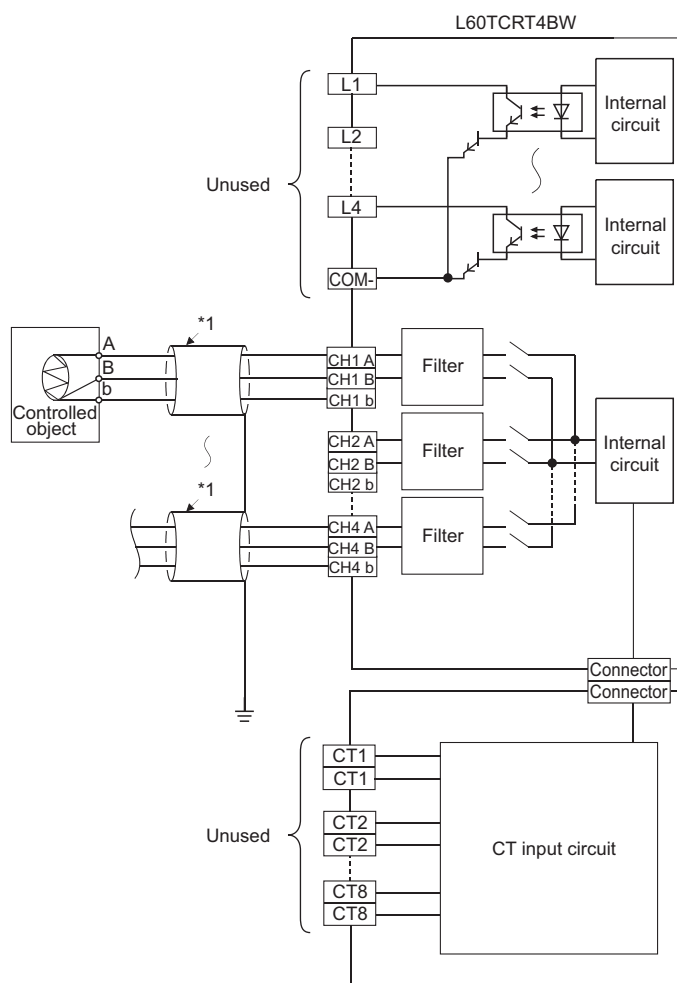
*1 Use the shielded cable.

(b) In the heating-cooling control

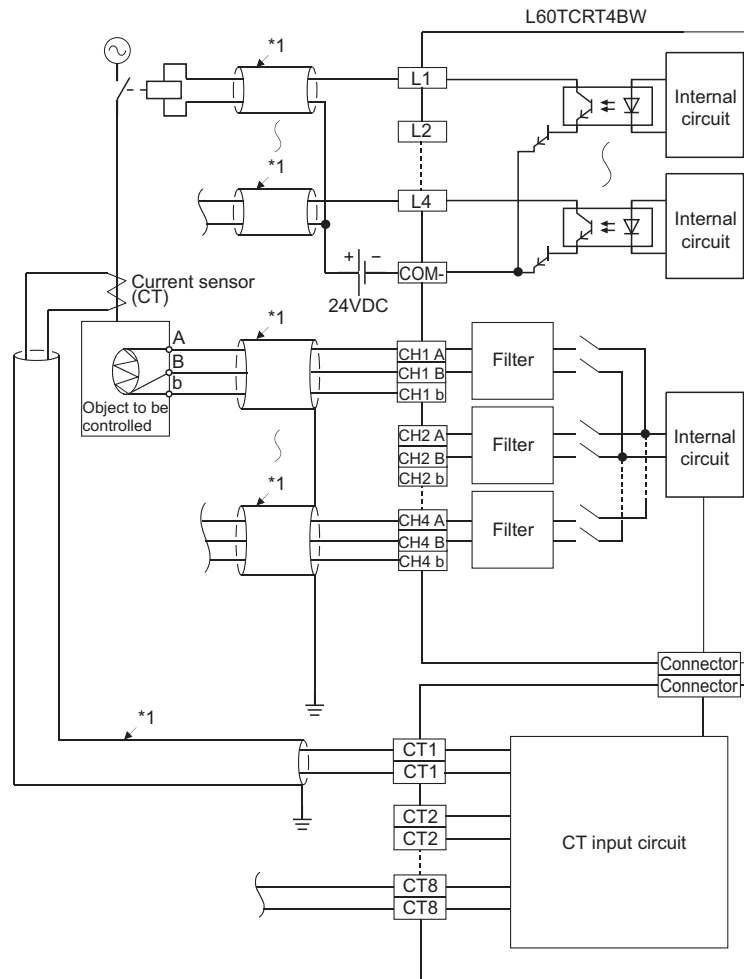
*1 Use the shielded cable.

6.4.4 L60TCRT4BW

(1) In the temperature input mode



*1 Use the shielded cable.

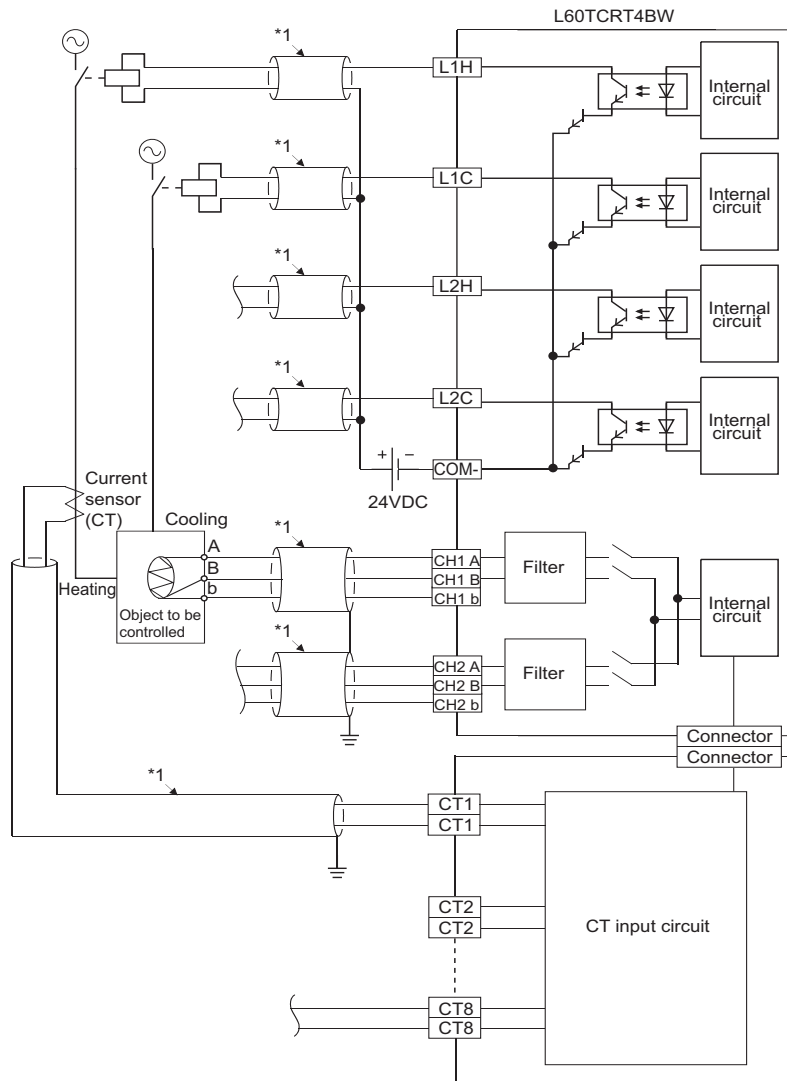
(2) In the temperature control mode**(a) In the standard control**

*1 Use the shielded cable.

Point

To use the heater disconnection detection function, the CT input channel assignment must be set. Since the CT1 is used in the loop of CH1 in the above wiring example, set CH1(1) to CT1 CT input channel assignment setting (Un\G264).

(b) In the heating-cooling control



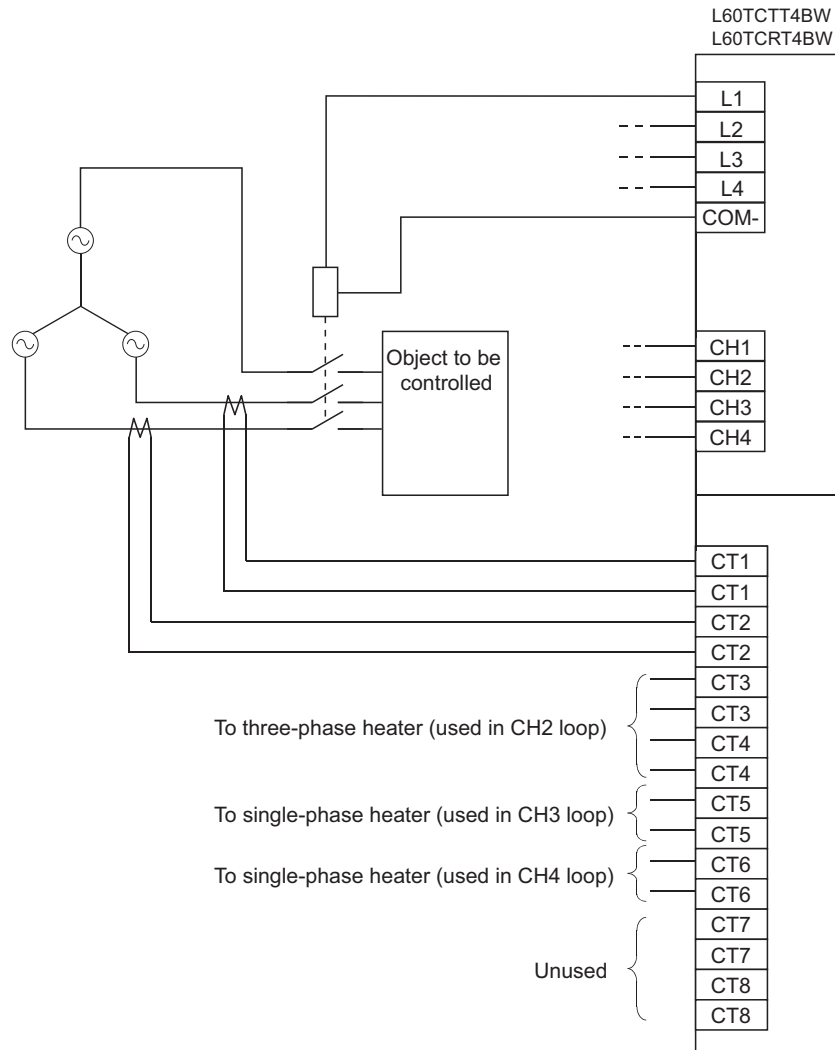
*1 Use the shielded cable.

Point

To use the heater disconnection detection function, the CT input channel assignment must be set. Since the CT1 is used in the loop of CH1 in the above wiring example, set CH1(1) to CT1 CT input channel assignment setting (Un\G264).

6.5 Heater disconnection detection wiring and setting example for three-phase heater

The following figure shows a wiring and setting example to detect a three-phase heater disconnection by using the heater disconnection detection function.



Three-phase heater disconnection detection is executed by measuring the currents of two of the three cables. In the above wiring example, set CT□ CT input channel assignment setting (Un\G264 to Un\G271) as indicated below.

CT input	Buffer memory address	Set value
CT1	Un\G264	1
CT2	Un\G265	1
CT3	Un\G266	2
CT4	Un\G267	2
CT5	Un\G268	3
CT6	Un\G269	4
CT7	Un\G270	0
CT8	Un\G271	0

6.6 Unused Channel Setting

When no temperature sensor is connected to a channel, the L60TC4 performs upscale processing for the channel. Therefore, when a temperature sensor is not connected to a channel where no temperature control is performed, the module determines that the temperature process value (PV) has exceeded the temperature measurement range for the input range, and the ALM LED blinks.

Once the unused channel setting is configured, no alert will occur for a channel where a temperature sensor is not connected. To prevent faulty alert detection, configure the unused channel setting.

(1) Setting method

Set a value in CH□ unused channel setting (Un\G61, Un\G93, Un\G125, Un\G157).

For details on the setting, refer to the following.

 Page 385, Appendix 2 (35)

The following table shows the relationship between the setting value and control status.

Set value	Control status		
	PID control	Temperature judgment	Alert judgment
0: Use	The controls are performed. (However, it depends on other setting status.)		
1: Unused	The controls are not performed.		

Remark

Even if the unused channel setting is configured, the sampling cycle does not change.

CHAPTER 7 VARIOUS SETTINGS

This chapter describes the setting procedures of the L60TC4.

Point

- To enable the contents of the new module, parameter setting, and auto refresh setting, reset the CPU module, switch STOP → RUN → STOP → RUN, or turn off and on the power after writing the contents into the CPU module.
- To enable the contents of the switch setting, reset the CPU module, or turn off and on the power after writing the contents into the CPU module.

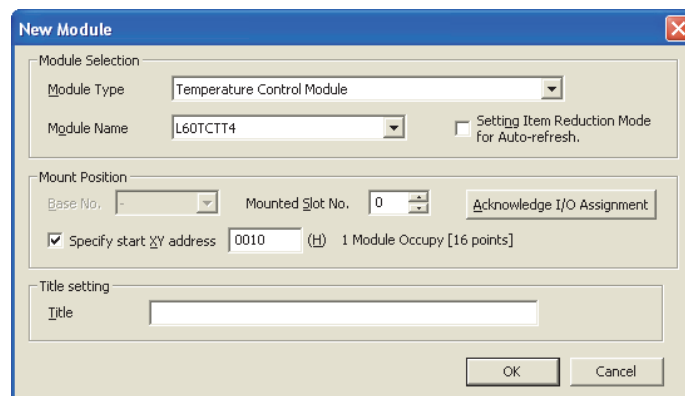
7.1 Addition of Modules

Add the model name of the L60TC4 to use on the project.

(1) Addition procedure

Open the "New Module..." window.

 Project window ⇨ [Intelligent Function Module] ⇨ Right-click ⇨ [New Module...]



	Item	Description
Module Selection	Module Type	Set "Temperature Control Module".
	Module Name	Select the module name to connect.
	Setting Item Reduction Mode for Auto-refresh	Select it to reduce the number of setting items for auto refresh. ( Page 116, Section 7.4)
Mount Position	Mounted Slot No.	Set the slot No. where the module is connected.
	Specify start XY address	The start I/O number (hexadecimal) of the target module is set according to the mounted slot No. An arbitrary start I/O number can be also set.
Title setting	Title	Set an arbitrary title.

7.2 Switch Setting

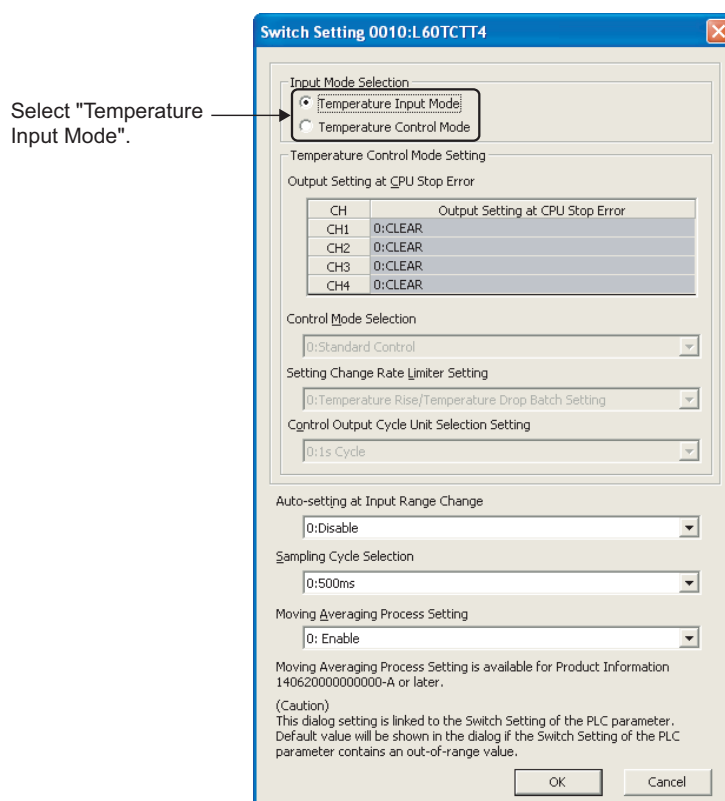
Configure settings such as the output setting at CPU stop error and the control mode selection which are used in each channel.

(1) Setting method

Open the "Switch Setting" window.

 Project window ⇨ [Intelligent Function Module] ⇨ Module name ⇨ [Switch Setting]

(a) When using the L60TC4 as a temperature input module



Item	Description	Set value	Reference
Auto-setting at Input Range Change	Set this item to change data of the related buffer memory automatically when the input range is changed so that an error outside the setting range does not occur.	• 0: Disable • 1: Enable	Page 241, Section 8.3.4
Sampling Cycle Selection ^{*1}	Select the sampling cycle.	• 0: 500ms (default value) • 1: 250ms	Page 121, Section 8.1.2
Moving Averaging Process Setting	Set whether to enable or disable the moving averaging process.	• 0: Enable • 1: Disable	Page 227, Section 8.3.1

^{*1} Immediately after the setting is changed, a set value discrepancy error (error code: 0□□E_H) occurs. To clear the set value discrepancy error, turn off, on, and off Set value backup instruction (Yn8).

(b) When using the L60TC4 as a temperature control module

Select "Temperature Control Mode".

Item	Description	Set value	Reference
Output Setting at CPU Stop Error	Set whether to hold or clear the transistor output status when a CPU stop error occurs or when a CPU module is switched from RUN to STOP.	• 0: CLEAR (default value) • 1: HOLD	Page 132, Section 8.2.2
Control Mode Selection ^{*1}	Set the control mode.	• 0: Standard Control • 1: Heating/Cooling Control (Normal Mode) • 2: Heating/Cooling Control (Expanded Mode) • 3: Mix Control (Normal Mode) • 4: Mix Control (Expanded Mode)	Page 130, Section 8.2.1
Setting Change Rate Limiter Setting	Select "batch" setting or "individual" setting for the variation limiter set value at temperature rise and drop when setting the variation of the set value (SV).	• 0: Temperature Rise/Temperature Drop Batch setting • 1: Temperature Rise/Temperature Drop Individual setting	Page 159, Section 8.2.10
Control Output Cycle Unit Selection Setting ^{*1}	Select 0.1s or 1s as a unit for the cycle of turning on and off the transistor output.	• 0: 1s Cycle (default value) • 1: 0.1s Cycle	Page 144, Section 8.2.6
Auto-setting at Input Range Change	Set this item to change data of the related buffer memory automatically when the input range is changed so that an error which is out of the setting does not occur.	• 0: Disable • 1: Enable	Page 241, Section 8.3.4
Sampling Cycle Selection ^{*1}	Select the sampling cycle.	• 0: 500ms (default value) • 1: 250ms	—
Moving Averaging Process Setting	Set whether to enable or disable the moving averaging process.	• 0: Enable • 1: Disable	Page 227, Section 8.3.1

^{*1} Immediately after the setting is changed, a set value discrepancy error (error code: 0□□E_H) occurs. To clear the set value discrepancy error, turn off, on, and off Set value backup instruction (Yn8).

7.3 Parameter Setting

Set the parameter for each channel.

By setting parameters here, the parameter setting is not required on a program.

(1) Setting method

Open the "Parameter" window.

1. Start up "Parameter" on the Project window.

Project window ⇨ [Intelligent Function Module] ⇨ Module name ⇨ [Parameter]

Clear Value for Gray Cells button

Pull-down list type

Text box type

Item	CH1	CH2	CH3	CH4
Basic setting				
Input range	Set the temperature conversion system.			
Set value (SV) setting	2:Thermocouple Measured Temperature Range(0 to 1300 C)	2:Thermocouple Measured Temperature Range(0 to 1300 C)	2:Thermocouple Measured Temperature Range(0 to 1300 C)	2:Thermocouple Measured Temperature Range(0 to 1300 C)
Unused channel setting	0:Used 0:Used 1:Unused	0:Used 0:Disable 1:Unused	0:Used 0:Used 1:Disable	0:Used 0:Used 1:Disable
Conversion enable/disable setting	0:Used 0:Used 1:Unused	0:Used 0:Disable 1:Unused	0:Used 0:Used 1:Disable	0:Used 0:Used 1:Disable
Control basic parameter setting	Proportional band (P), integral time (I), derivative time (D) and temperature set value (set			
Proportional band (P) setting/Heating control	3.0 %	3.0 %	3.0 %	3.0 %
proportional band setting (Ph)	3.0 %	3.0 %	3.0 %	3.0 %
Cooling proportional band (Pc) setting	3.0 %	3.0 %	3.0 %	3.0 %
Integral time (I) setting	240 s	240 s	240 s	240 s
Derivative time (D) setting	60 s	60 s	60 s	60 s
Control output cycle setting/Heating control output cycle setting.	30 s	30 s	30 s	30 s
Control response parameter	0:Slow	0:Slow	0:Slow	0:Slow
Stop Mode Setting	1:Monitor	1:Monitor	1:Monitor	1:Monitor
PID continuation flag	0:Stop	0:Stop	0:Stop	0:Stop
Control detail parameter setting				
Forward/reverse action setting	1:Reverse Action	1:Reverse Action	1:Reverse Action	1:Reverse Action
Upper limit setting limiter	1300 C	1300 C	1300 C	1300 C
Lower limit setting limiter	0 C	0 C	0 C	0 C
Setting change rate limiter or Setting change rate limiter (Temperature rise)	0.0 %	0.0 %	0.0 %	0.0 %
Setting change rate limiter (Temperature drop)	0.0 %	0.0 %	0.0 %	0.0 %
Sensor correction value setting	0.00 %	0.00 %	0.00 %	0.00 %
Number of moving averaging (Available for Product Information 14062000000000-A or later)	2 Times	2 Times	2 Times	2 Times

Used to specify as unused the channels where temperature control will not be performed and temperature sensors will not be connected.

2. Click **Clear Value for Gray Cells** to set items unnecessary for the mode set on Switch Setting to 0.

3. Double-click the item to change the setting, and enter the setting value.

- Items to select from a pull-down list

Double-click the item to set to display the pull-down list. Select the item.

- Items to enter in a text box

Double-click the item to set, and enter the value.

Remark

If writing is performed without setting unnecessary items for the mode set on Switch Setting to 0, a write data error (error code: □□□2_H) may occur.

For details on setting values, refer to the following.

Input mode selection	Setting item	Reference
Temperature Input Mode	Input range	Page 355, Appendix 2 (12)
	Conversion enable/disable setting	Page 412, Appendix 2 (76)
	Sensor correction value setting	Page 372, Appendix 2 (21)
	Number of moving averaging	Page 414, Appendix 2 (78)
	Primary delay digital filter setting	Page 374, Appendix 2 (24)
	Process value (PV) scaling function enable/disable setting	Page 415, Appendix 2 (82)
	Process value (PV) scaling lower limit value	Page 416, Appendix 2 (83)
	Process value (PV) scaling upper limit value	
	Cold junction temperature compensation selection	Page 393, Appendix 2 (49)
	Process alarm alert output enable/disable setting	Page 396, Appendix 2 (53)
	Process alarm lower lower limit value	Page 397, Appendix 2 (54)
	Process alarm lower upper limit value	
	Process alarm upper lower limit value	
	Process alarm upper upper limit value	
	Rate alarm alert output enable/disable setting	Page 398, Appendix 2 (55)
	Rate alarm alert detection cycle	Page 398, Appendix 2 (56)
	Rate alarm upper limit value	Page 399, Appendix 2 (57)
	Rate alarm lower limit value	

Input mode selection	Setting item	Reference
Temperature control mode	Input range	Page 355, Appendix 2 (12)
	Set value (SV) setting	Page 363, Appendix 2 (14)
	Unused channel setting	Page 385, Appendix 2 (35)
	Proportional band (P) setting/Heating control proportional band setting (Ph)	Page 364, Appendix 2 (15)
	Cooling proportional band (Pc) setting	
	Integral time (I) setting	Page 366, Appendix 2 (16)
	Derivative time (D) setting	Page 366, Appendix 2 (17)
	Control output cycle setting/Heating control output cycle setting	Page 373, Appendix 2 (23)
	Control response parameter	Page 375, Appendix 2 (25)
	Stop Mode Setting	Page 362, Appendix 2 (13)
	PID continuation flag	Page 390, Appendix 2 (43)
	Forward/reverse action setting	Page 380, Appendix 2 (30)
	Upper limit setting limiter	Page 381, Appendix 2 (31)
	Lower limit setting limiter	
	Setting change rate limiter or Setting change rate limiter (Temperature rise)	Page 378, Appendix 2 (28)
	Setting change rate limiter (Temperature drop)	
	Sensor correction value setting	Page 372, Appendix 2 (21)
	Number of moving averaging	Page 414, Appendix 2 (78)
	Primary delay digital filter setting	Page 374, Appendix 2 (24)
	Upper limit output limiter/Heating upper limit output limiter	Page 369, Appendix 2 (19)
	Lower limit output limiter	
	Output variation limiter	Page 371, Appendix 2 (20)
	Adjustment sensitivity (dead band) setting	Page 372, Appendix 2 (22)
	Self-tuning setting	Page 408, Appendix 2 (73)
	Temperature conversion setting	Page 413, Appendix 2 (77)
	Cooling method setting	Page 414, Appendix 2 (79)
	Cooling upper limit output limiter	Page 369, Appendix 2 (19)
	Cooling control output cycle setting	Page 373, Appendix 2 (23)
	Overlap/dead band setting	Page 415, Appendix 2 (80)
	Process value (PV) scaling function enable/disable setting	Page 415, Appendix 2 (82)
	Process value (PV) scaling lower limit value	Page 416, Appendix 2 (83)
	Process value (PV) scaling upper limit value	
	Derivative action selection	Page 417, Appendix 2 (85)

Input mode selection	Setting item	Reference
Temperature Control Mode	Simultaneous temperature rise group setting	Page 417, Appendix 2 (86)
	Simultaneous temperature rise AT mode selection	Page 419, Appendix 2 (89)
	Setting change rate limiter Unit time setting	Page 421, Appendix 2 (91)
	Peak current suppression control group setting	Page 422, Appendix 2 (92)
	Automatic backup setting after auto tuning of PID constants	Page 387, Appendix 2 (37)
	Cold junction temperature compensation selection	Page 393, Appendix 2 (49)
	Alert 1 mode setting to Alert 4 mode setting	Page 395, Appendix 2 (52)
	Alert set value 1 to Alert set value 4	Page 367, Appendix 2 (18)
	Alert dead band setting	Page 388, Appendix 2 (38)
	Number of alert delay	Page 388, Appendix 2 (39)
	Loop disconnection detection judgment time	Page 383, Appendix 2 (33)
	Loop disconnection detection dead band	Page 384, Appendix 2 (34)
	Heater disconnection alert setting	Page 382, Appendix 2 (32)
	Heater disconnection/output off-time current error detection delay count	Page 389, Appendix 2 (40)
	Heater disconnection compensation function selection	Page 390, Appendix 2 (44)
	AT Bias	Page 379, Appendix 2 (29)
	Auto tuning mode selection	Page 394, Appendix 2 (51)
	During AT loop disconnection detection function enable/disable setting	Page 407, Appendix 2 (71)
	Temperature rise completion range setting	Page 389, Appendix 2 (41)
	Temperature rise completion soak time setting	Page 390, Appendix 2 (42)
	Transistor output monitor ON delay time setting	Page 391, Appendix 2 (45)
	Resolution of the manipulated value for output with another analog module	Page 393, Appendix 2 (48)
	CT monitor method switching	Page 391, Appendix 2 (46)
	CT□ CT input channel assignment setting	Page 400, Appendix 2 (59)
	CT□ CT selection	Page 401, Appendix 2 (60)
	CT□ Reference heater current value	Page 402, Appendix 2 (61)
	CT□ CT Ratio setting	Page 402, Appendix 2 (62)

4. When using CH2 to CH4, follow the step 3 described earlier.

7.4 Auto Refresh

Buffer memory data can be transferred to specified devices using this function.

By using this auto refresh setting, reading or writing is not required on a program.

For the L60TC4, number of parameters of the auto refresh setting can be reduced by changing the normal mode to the setting item reduction mode.

(1) Setting item reduction mode

In the setting item reduction mode, setting items can be grouped so that the device setting is required only for the start item of the group and the number of parameters of the auto refresh setting can be saved compared with the normal mode.

For the number of parameters of the auto refresh setting, refer to the following:

(☞ Page 35, Section 3.2.1)

(a) GX Works2 version supporting this function

GX Works2 with version 1.73B or later supports this function.

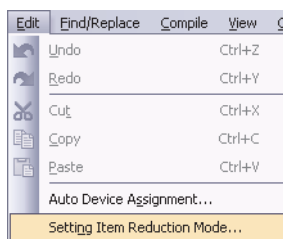
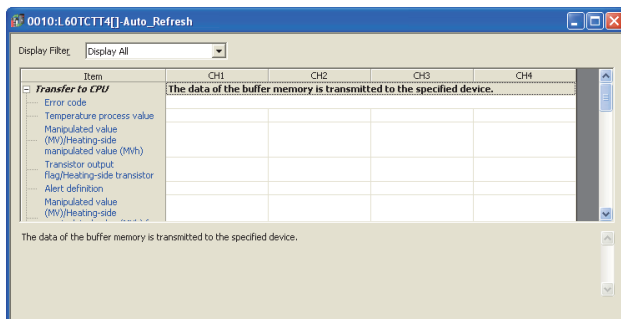
(2) Setting method

(a) In the setting item reduction mode

Configure settings from "Auto_Refresh" window.

The mode change to the setting item reduction mode can be performed from "New Module" window as well.

(☞ Page 109, Section 7.1)



(To the next page)

1. Open "Auto_Refresh" window.

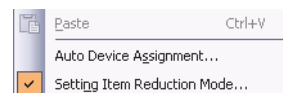
☞ Project window ⇒ [Intelligent Function Module]
⇒ Module name ⇒ [Auto_Refresh]

2. Change from the normal mode to the setting item reduction mode.

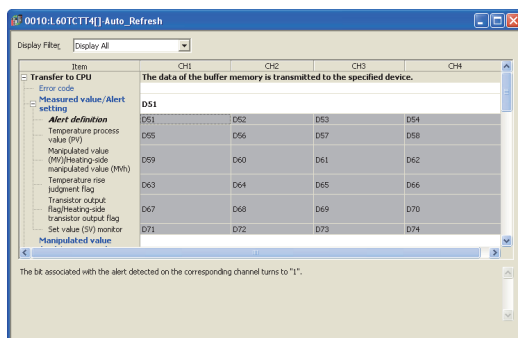
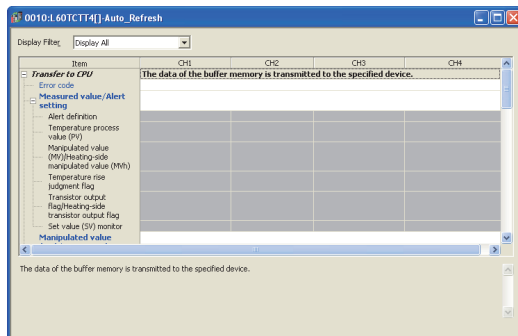
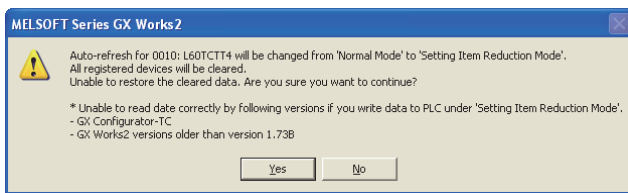
If the setting item reduction mode is already set, the following operation is not required.

☞ [Edit] ⇒ [Setting Item Reduction Mode]

If the mode is changed to the setting item reduction mode, the box to the left of [Setting Item Reduction Mode] is checked.



(From the previous page)



End

3. Click the  button.

4. Click the item to be set and enter the auto refresh target device.

5. To set the device for a grouped setting items (gray part), set the device to the start item (white part). When the device is set to the start item, the consecutive devices are automatically set to the grouped setting items. (The left side window is the example when "D51" is set to "Measured value/Alert setting".)

Point

- To change the mode back to the normal mode, perform [Edit] ⇔ [Setting Item Reduction Mode] again and uncheck the box to the left of [Setting Item Reduction Mode].
- By changing the mode (normal mode → setting item reduction mode, setting item reduction mode → normal mode), the settings before the change are all cleared.

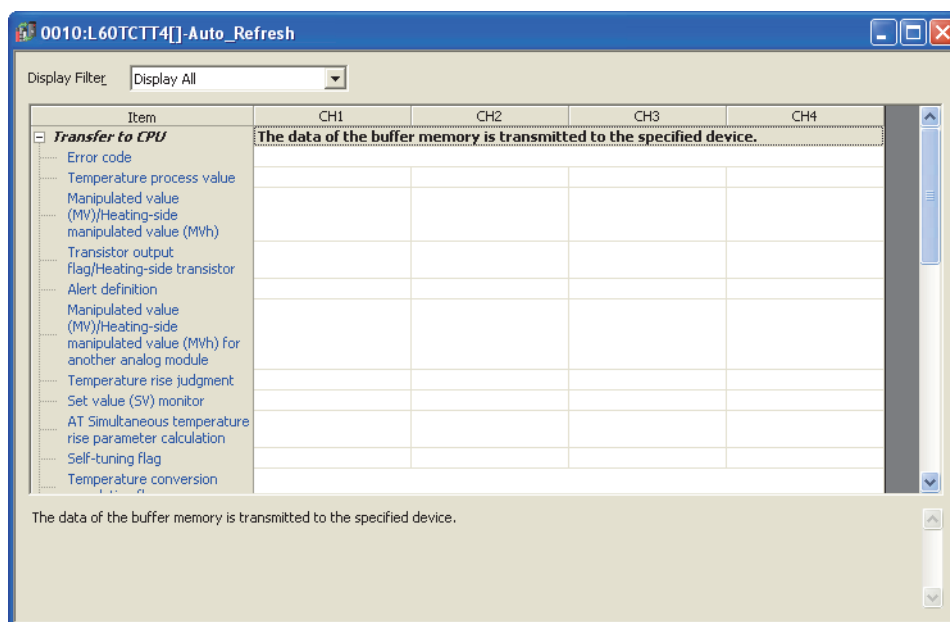
(b) In the normal mode

Open the "Auto_Refresh" window.

1. Start "Auto_Refresh" on the Project window.

Project window ⇒ [Intelligent Function Module] ⇒ Module name ⇒ [Auto_Refresh]

2. Click the item to set, and enter the auto refresh target device.



7.5 Auto Tuning

For how to execute auto tuning, refer to the following.

☞ Page 148, Section 8.2.7 (5)

7.6 Sensor Correction

For how to execute sensor correction, refer to the following.

☞ Page 230, Section 8.3.3

CHAPTER 8 FUNCTIONS

This chapter explains the details of the L60TC4 functions and how to set each function.

For details on I/O signals and the buffer memory, refer to the following.

- Details of I/O signals (☞ Page 333, Appendix 1)
- Details of the buffer memory (☞ Page 344, Appendix 2)

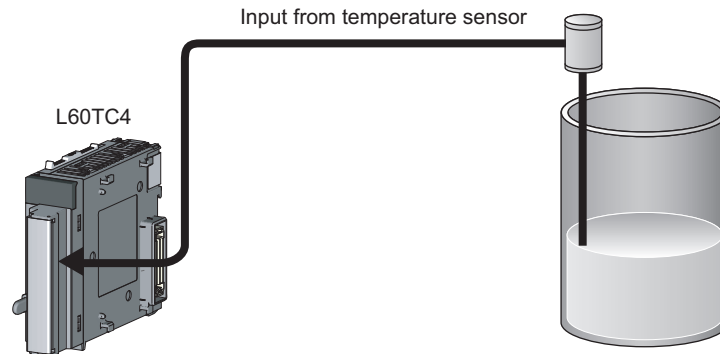
Point

For the functions indicated with the icons **Standard** and **Heating-cooling**, or with **Common**, the following terms are used, unless otherwise specified.

- Proportional band (P): includes heating proportional band (Ph) and cooling proportional band (Pc)
 - Manipulated value (MV): includes manipulated value for heating (MVh) and manipulated value for cooling (MVc)
 - Manipulated value (MV) for output with another analog module: includes manipulated value of heating (MVh) for output with another analog module and manipulated value of cooling (MVc) for output with another analog module
 - Transistor output: includes heating transistor output and cooling transistor output
 - Upper limit output limiter value: includes heating upper limit output limiter value and cooling upper limit output limiter value
 - Control output cycle: includes heating control output cycle and cooling control output cycle
-

8.1 Temperature Input Mode

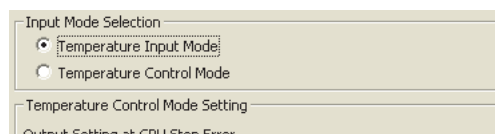
The L60TC4 can be used as a temperature input module using this function.



(1) Setting method

Set the L60TC4 to the temperature input mode on Switch Setting. (☞ Page 110, Section 7.2)

☞ Project window ⇒ [Intelligent Function Module] ⇒ Module name ⇒ [Switch Setting]



(2) Precaution

When resolution is "1", the temperature process value (PV) of the L60TC4 is rounded off from the actual temperature.

- Ex.** When the actual temperature is 1299.5°C, the temperature process value (PV) of the L60TC4 is 1300°C.
To measure temperature by every 0.1°C, set resolution to "0.1". (☞ Page 355, Appendix 2 (12))
Note that the temperature process value (PV) is not rounded off for the process alarm and rate alarm.
(☞ Page 125, Section 8.1.3 (1) (d), Page 127, Section 8.1.3 (2) (d))

8.1.1 Conversion enable/disable function

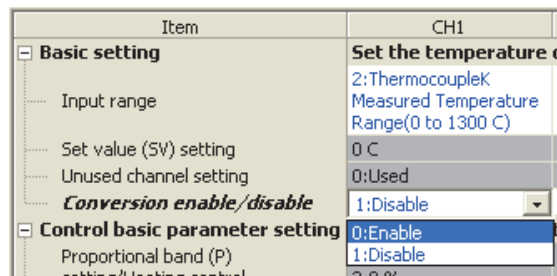
Temperature
Input

Temperature conversion can be enabled or disabled for each channel using this function. By disabling unused channels, unnecessary disconnection detection or alert output can be prevented.

(1) Setting method

Set "Conversion enable/disable setting" to "0: Enable".

 Project window ⇨ [Intelligent Function Module] ⇨ Module name ⇨ [Parameter]



8.1.2 Temperature conversion method

Temperature
Input

8

In the L60TC4, a measured value is stored into CH□ Temperature process value (PV) (Un\G9 to Un\G12) in every sampling cycle. In addition, the use of the primary delay digital filter smoothens the temperature process value (PV), and its drastic change can be absorbed.

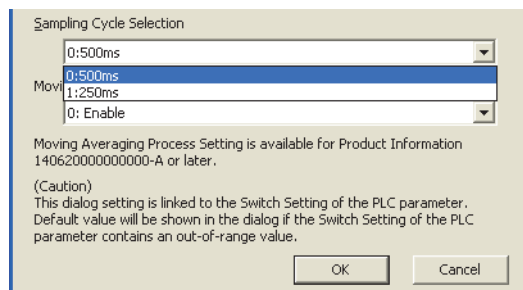
(1) Sampling cycle

A sampling cycle can be selected from 250ms or 500ms.

(a) How to set the sampling cycle

Select a sampling cycle on "Sampling Cycle Selection".

 Project window ⇨ [Intelligent Function Module] ⇨ Module name ⇨ [Switch Setting]

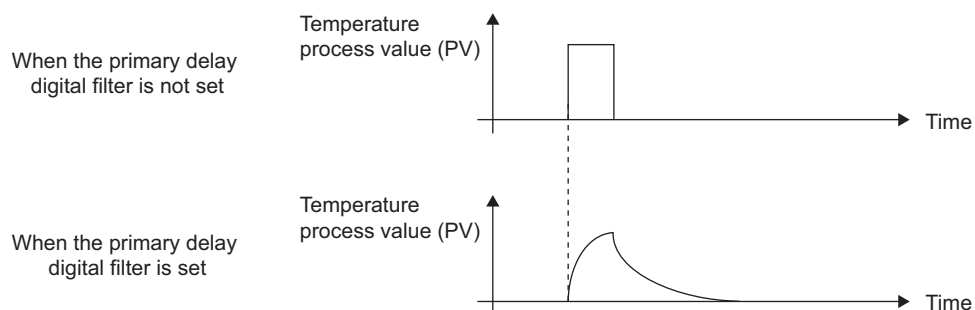


(b) How to check the sampling cycle

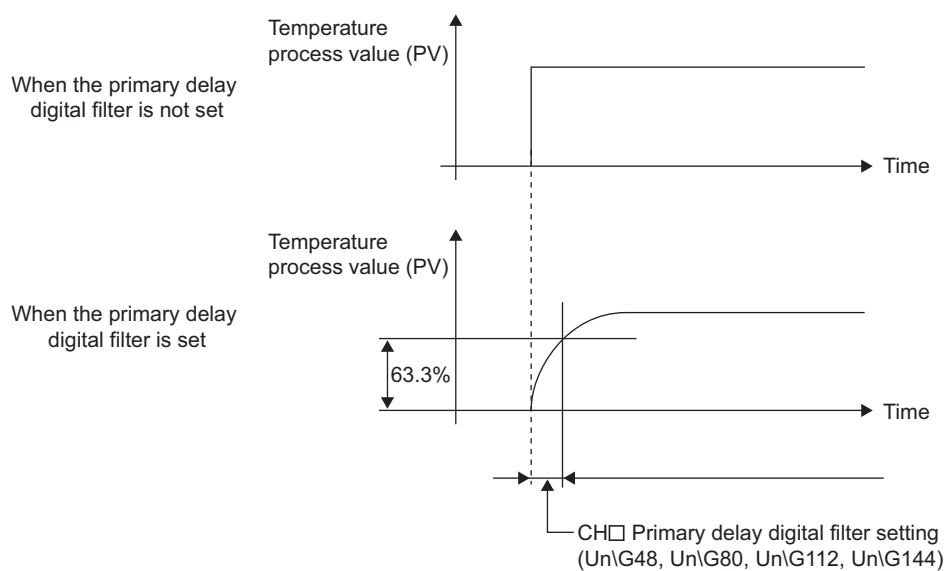
A running sampling cycle can be checked in Sampling cycle monitor (Un\G788).

(2) Primary delay digital filter

A setting of the primary delay digital filter outputs the temperature process value (PV) whose transient noise is smoothened.



For the primary delay digital filter, set the time until the temperature process value (PV) changes by 63.3% (time constant).



(a) How to set the primary delay digital filter

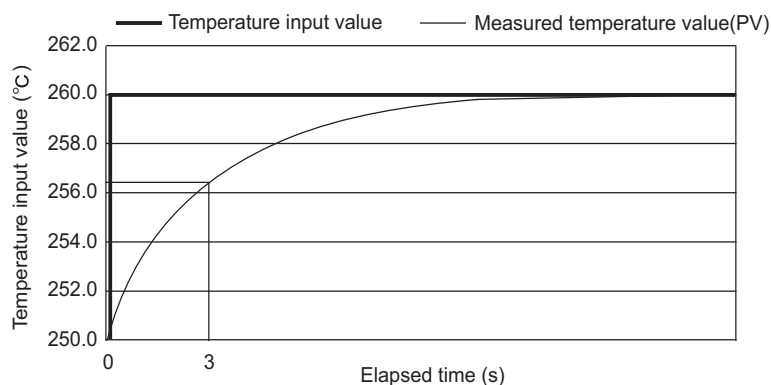
In "Primary delay digital filter setting", set the time until the temperature process value (PV) changes by 63.3% (time constant).

 Project window ⇨ [Intelligent Function Module] ⇨ Module name ⇨ [Parameter]

Control detail parameter setting	Set temperature measurement
Forward/reverse action setting	1:Reverse Action
Upper limit setting limiter	1300 C
Lower limit setting limiter	0 C
Setting change rate limiter or Setting change rate limiter (Temperature rise)	0.0 %
Setting change rate limiter (Temperature drop)	0.0 %
Sensor correction value setting	0.00 %
Number of moving averaging (Available for Product Information 14062000000000-A or later)	2 Times
Primary delay digital filter	3 s
Upper limit output limiter/Heating upper limit output limiter	100.0 %

Ex. When 3(3s) is set in "Primary delay digital filter setting"

The change shown below will happen if the Temperature process value (PV) changes from 250°C to 260°C under the condition where 3(3s) is set in "Primary delay digital filter setting".



The temperature reaches 256.3°C which is 63.3% of the temperature process value (PV) three seconds after the temperature input value has reached 250.0°C.

8.1.3 Alert output function

Temperature
Input

An alert can be output when the temperature process value (PV) meets the condition set in advance using this function. Use this function to activate danger signals of devices or safety devices.

There are two types of alert: process alarm and rate alarm.

(1) Process alarm

An alert occurs when the temperature process value (PV) reaches the process alarm upper upper limit value or more, or the process alarm lower lower limit value or less.

The alert is cleared when the process value reaches a value less than the process alarm upper lower limit value, or a value more than the process alarm lower upper limit value. An alert is not cleared even by resetting the error or switching to the setting mode.

(a) Checking the alert occurrence

When an alert occurs, CH□ Alert occurrence flag (XnC to XnF) turns on, and the ALM LED turns on.

In CH□ Alert definition (Un\G5 to Un\G8), whether it is an upper limit alert or lower limit alert can be checked.

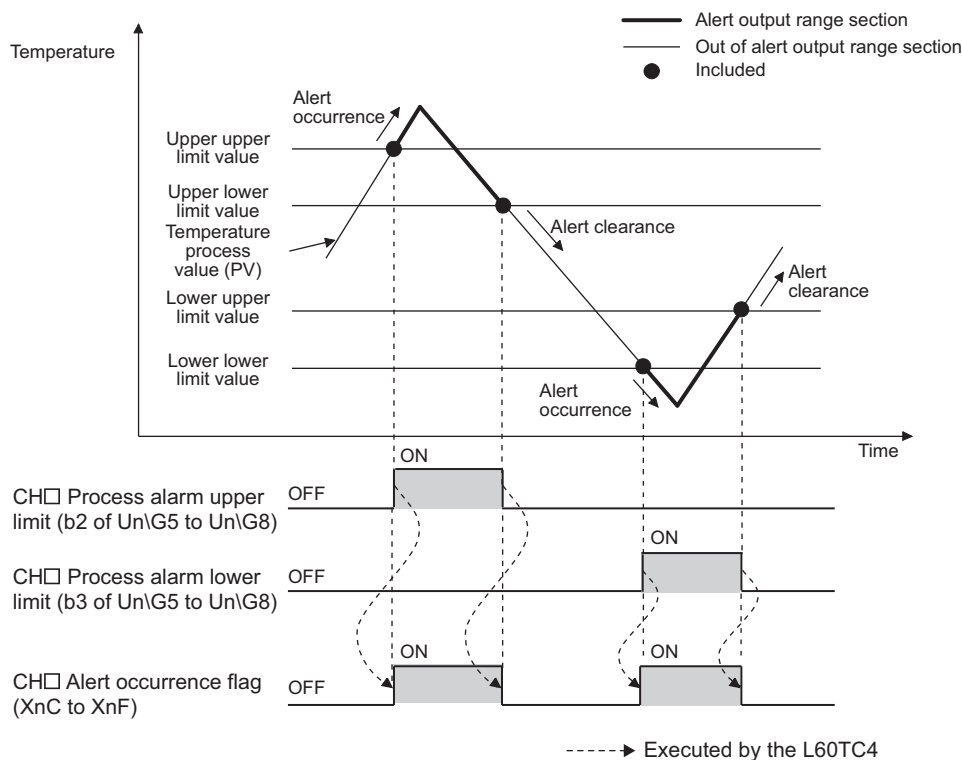
( Page 346, Appendix 2 (3))

(b) Checking the alert clearance

CH□ Process alarm upper limit (b2 of Un\G5 to Un\G8) or CH□ Process alarm lower limit (b3 of Un\G5 to Un\G8) becomes 0 (OFF). Also, CH□ Alert occurrence flag (XnC to XnF) turns off, and the ALM LED turns off.

Point

In CH□ Alert occurrence flag (XnC to XnF) and on the ALM LED, the alert is not cleared when an alert other than the process alarm is occurring.



(c) How to set process alarm

Set "Process alarm alert output enable/disable setting" to "0: Enable". Then, set the lower lower limit value, lower upper limit value, upper lower limit value, and upper upper limit value of the process alarm.

 Project window ⇨ [Intelligent Function Module] ⇨ Module name ⇨ [Parameter]

Item	CH1	
Process alarm alert output enable/disable setting	0:Enable	0
Process alarm lower lower limit value	0 C	0
Process alarm lower upper limit value	100 C	1
Process alarm upper lower limit value	900 C	9
Process alarm upper upper limit value	1000 C	1

(d) Precaution

When resolution is "1", the temperature process value (PV) of the L60TC4 is rounded off from the actual temperature. For the process alarm also, the temperature process value (PV) rounded off from the actual temperature determines the alert occurrence.

(2) Rate alarm

The temperature process value (PV) is monitored every rate alarm alert detection cycle. An alert occurs when the change from the previous monitoring is greater than the rate alarm upper limit value, or smaller than the rate alarm lower limit value. The rate alarm is helpful to monitor the change of the temperature process value (PV) in a limited range.

$$\begin{aligned} \text{PV Present value} - \text{PV Previous value} &\geq \text{Rate alarm upper limit value} \\ \text{PV Present value} - \text{PV Previous value} &\leq \text{Rate alarm lower limit value} \end{aligned}$$

The alert is cleared when the temperature process value reaches within the range of the formulas above. An alert is not cleared even by resetting the error or switching to the setting mode.

(a) Checking the alert occurrence

While the rate alarm is occurring, CH□ Alert occurrence flag (XnC to XnF) turns on, and the ALM LED turns on.^{*1}

In CH□ Alert definition (Un\G5 to Un\G8), whether it is an upper limit alert or lower limit alert can be checked.

( Page 346, Appendix 2 (3))

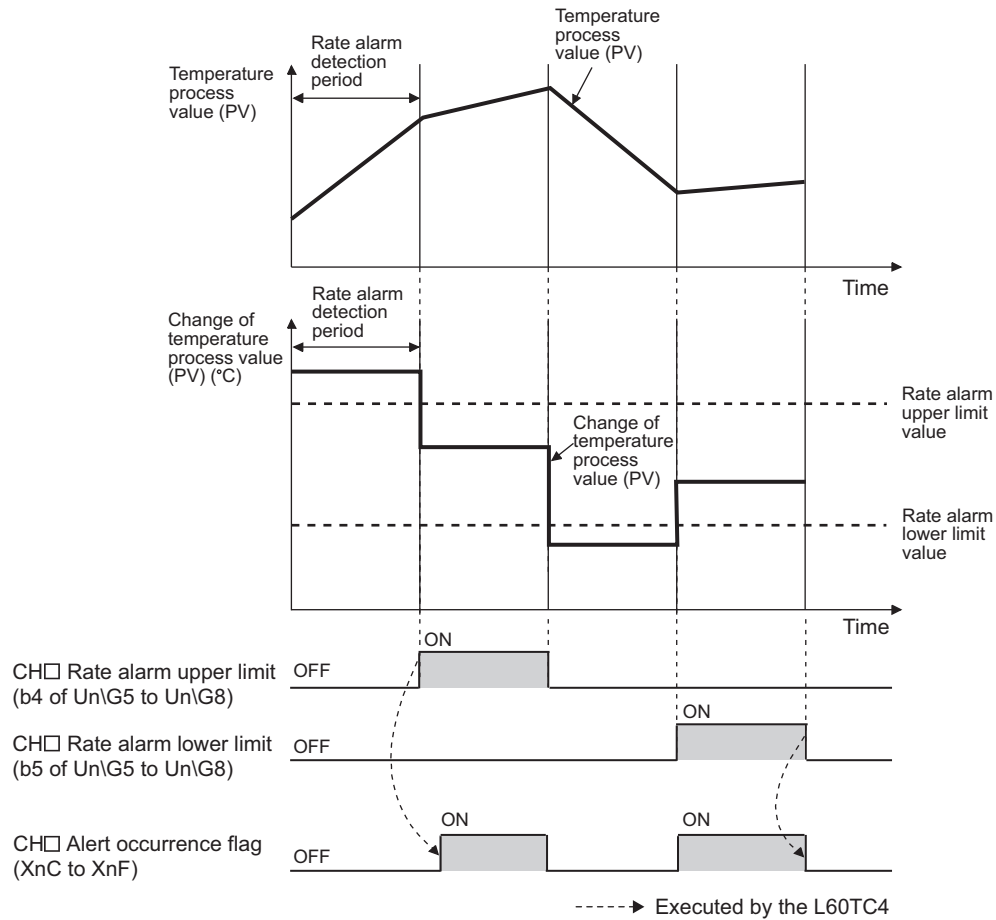
^{*1} The ALM LED prioritizes the detection of other errors for which the ALM LED flashes (such as the detection of loop disconnection).

(b) Checking the alert clearance

CH□ Rate alarm upper limit (b4 of Un\G5 to Un\G8) or CH□ Rate alarm lower limit (b5 of Un\G5 to Un\G8) becomes 0 (OFF). Also, CH□ Alert occurrence flag (XnC to XnF) turns off, and the ALM LED turns off.

Point

In CH□ Alert occurrence flag (XnC to XnF) and on the ALM LED, the alert is not cleared when an alert other than the rate alarm is occurring.



(c) How to set rate alarm

Set "Rate alarm alert output enable/disable setting" to "0: Enable". Then, set the alert detection cycle, upper limit value, and lower limit value of the rate alarm.

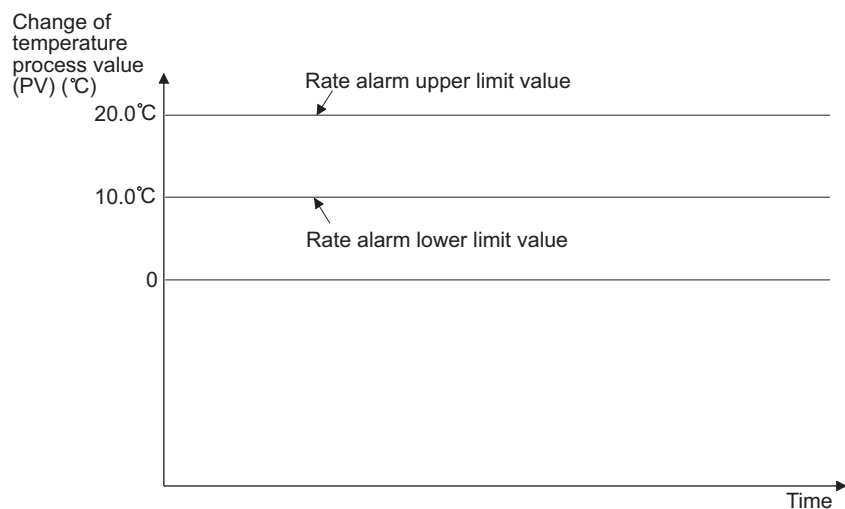
Project window ⇨ [Intelligent Function Module] ⇨ Module name ⇨ [Parameter]

Item	CH1
Rate alarm alert output enable/disable setting	0:Enable
Rate alarm alert detection cycle	1 Times
Rate alarm upper limit value	200 C
Rate alarm lower limit value	10 C

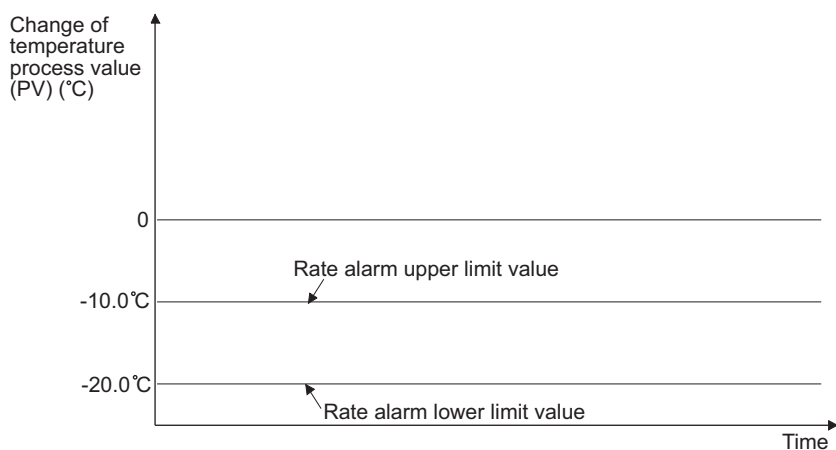
(d) Precaution

When resolution is "1", the temperature process value (PV) of the L60TC4 is rounded off from the actual temperature. For the rate alarm also, the temperature process value (PV) rounded off from the actual temperature determines the alert occurrence.

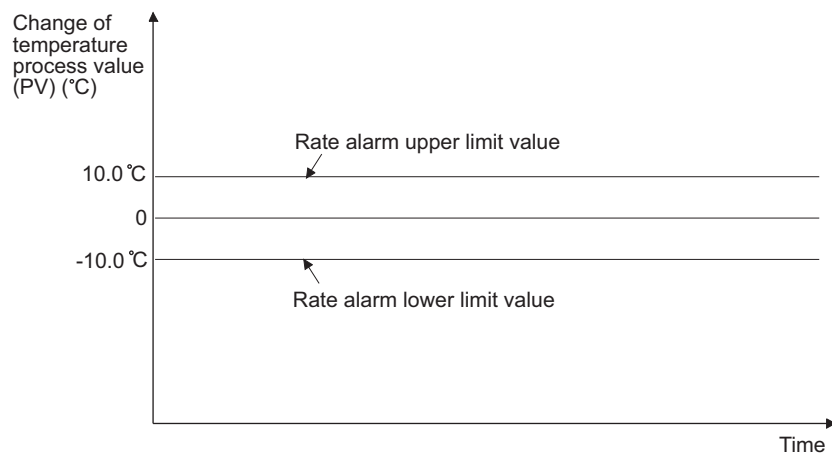
- Ex.** A setting example of the rate alarm upper limit value and lower limit value to monitor that the temperature process value (PV) is rising within the specified range



- Ex.** A setting example of the rate alarm upper limit value and lower limit value to monitor that the temperature process value (PV) is falling within the specified range



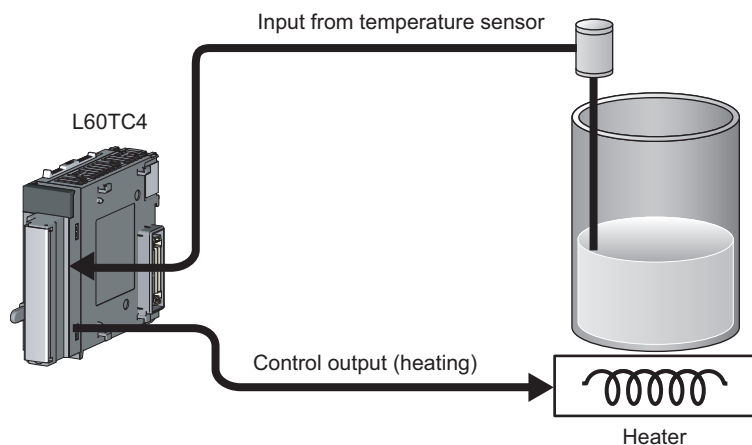
- Ex.** A setting example of the rate alarm upper limit value and lower limit value to monitor that the temperature process value (PV) is changing within the specified range



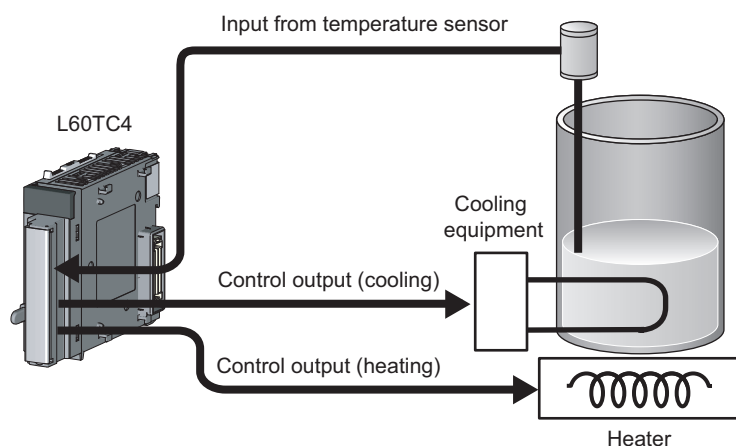
8.2 Temperature Control Mode

The L60TC4 can be used as a temperature control module using this function.

- Standard control (heating)



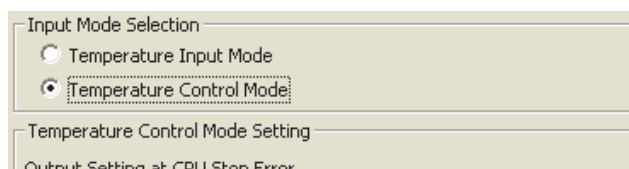
- Heating-cooling control (heating and cooling)



(1) Setting method

Set the L60TC4 to the temperature control mode on Switch Setting. (☞ Page 110, Section 7.2)

☞ Project window ☞ [Intelligent Function Module] ☞ Module name ☞ [Switch Setting]



8.2.1 Control Mode Selection Function

Standard Heating-cooling

A control mode can be selected using this function.

This section explains selectable control modes of the L60TC4.

(1) Standard control and heating-cooling control

There are two types of control modes in the L60TC4: standard control and heating-cooling control.

(a) Standard control

The control method is either one of heating (reverse action) or cooling (forward action). When the control method is heating, of a heater for example, cooling is controlled by simply turning off the heating. When the control method is cooling, of cold water for example, heating is controlled by simply turning off the cooling.

(b) Heating-cooling control

The control method is both heating and cooling. To heat up the target subject, its heating mean is turned on, and its cooling mean is turned off. To cool down the target subject, its heating mean is turned off, and its cooling mean is turned on.

(2) Selectable control mode

A control mode can be selected from five modes.

Select the control mode on Switch Setting.

For details on the setting method, refer to the following.

 Page 110, Section 7.2

Control mode	Contents	Number of controllable loops
Standard control	Performs the standard control of four channels	Standard control 4 loops
Heating-cooling control (normal mode)	Performs the heating-cooling control. CH3 and CH4 cannot be used.	Heating-cooling control 2 loops
Heating-cooling control (expanded mode)	Performs the heating-cooling control. The number of loops is expanded using an output module and others in the system.	Heating-cooling control 4 loops
Mix control (normal mode)	Performs the standard control and the heating-cooling control. CH2 cannot be used.	Standard control 2 loops Heating-cooling control 1 loop
Mix control (expanded mode)	Performs the standard control and the heating-cooling control. The number of loops is expanded using an output module and others in the system.	Standard control 2 loops Heating-cooling control 2 loops

Control for each channel is as follows.

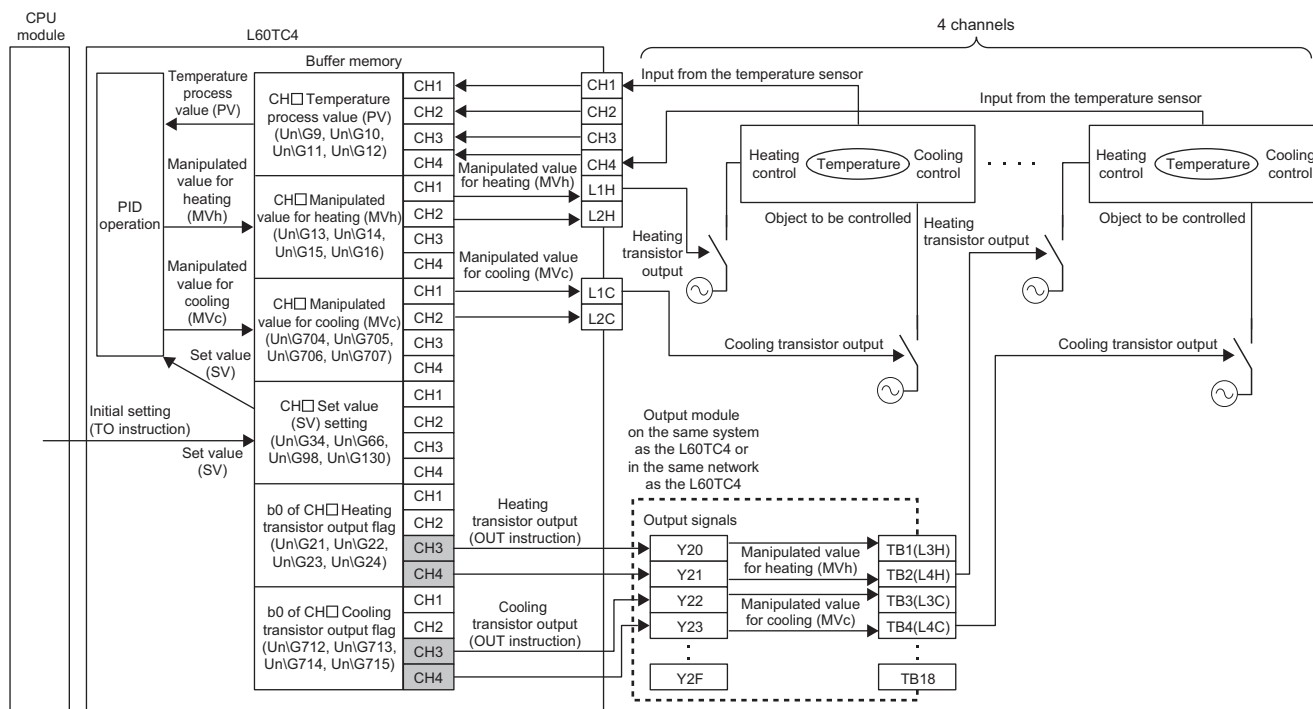
Channel	Standard control	Heating-cooling control		Mix control	
		Normal mode	Expanded mode	Normal mode	Expanded mode
CH1	Standard control	Heating-cooling control	Heating-cooling control	Heating-cooling control	Heating-cooling control
CH2	Standard control	Heating-cooling control	Heating-cooling control	—*1	Heating-cooling control*2
CH3	Standard control	—*1	Heating-cooling control*2	Standard control	Standard control
CH4	Standard control	—*1	Heating-cooling control*2	Standard control	Standard control

*1 Only temperature measurement using a temperature input terminal can be performed. ( Page 218, Section 8.2.24)

*2 Heating-cooling control is performed using an output module in the system. ( Page 131, Section 8.2.1 (3))

(3) Expanded mode

In the heating-cooling control (expanded mode) or the mix control (expanded mode), the number of loops for heating-cooling control can be expanded using an output module and others in the system. To use an expanded mode, construct a system such as the one shown below.



Point

When the heating-cooling control (expanded mode) is selected, heating/cooling transistor output of CH3 and CH4 are activated. Also, when the mix control (expanded mode) is selected, heating/cooling transistor output of CH2 is activated. These areas are activated only when an expanded mode is selected. When a normal mode is selected, these areas are used for the system. If data is written into these areas when it is used by the system, a write data error occurs. (error code: □□□2_H)

The following is an example of using an expanded mode.

Ex. A program in which CH3 Heating transistor output flag (b0 of Un\G23) is assigned to Y20 of an output module (The start I/O number of the L60TC4 is set to 10 in the following program example.)



8.2.2 Control output setting at CPU stop error

Standard Heating-cooling

When a stop error occurs on the CPU module or when CPU's status is changed from RUN to STOP, whether to hold or clear the status of transistor output can be selected using this function.

Configure "Output Setting at CPU Stop Error" on Switch Setting.

For details on the setting method, refer to the following.

 Page 110, Section 7.2

Processing for each status is describes in the following table.

Status		Processing				Reference
Output Setting at CPU Stop Error		CLEAR		HOLD		Page 110, Section 7.2
Setting of PID continuation flag (Un\G169)		Stop	Continue	Stop	Continue	Page 390, Appendix 2 (43)
Error	L60TC4 Write data error	Follow the operation of when an error occurs				Page 325, Section 11.6
	L60TC4 Hardware error	Depends on the symptom of the hardware				—
	CPU Stop error	Stops the operation and turns off external output		Follows the stop mode setting ^{*1}	Stops the operation and performs external output	—
CPU operation	RUN → STOP	Follows the stop mode setting ^{*1}	Stops the operation and performs external output	Follows the stop mode setting ^{*1}	Stops the operation and performs external output	—
	Resetting	The module is incapable to operate, and not performs external output				—

^{*1} CH□ Stop mode setting (Un\G33, Un\G65, Un\G97, Un\G129) ( Page 362, Appendix 2 (13))

Important

- Fully pay attention to the setting of PID continuation flag (Un\G169) which controls external output.
- By the failure of an output element or internal circuit, an abnormal output may occur. Construct a circuit to monitor output signals that could cause a serious accident.

8.2.3 Control method

Standard Heating-cooling

The following control methods can be applied by setting the proportional band (P), integral time, and derivative time(D).

- Two-position control (☞ Page 133, Section 8.2.3 (1))
- P control (☞ Page 135, Section 8.2.3 (2))
- PI control (☞ Page 136, Section 8.2.3 (3))
- PD control (☞ Page 137, Section 8.2.3 (4))
- PID control (☞ Page 137, Section 8.2.3 (5))

Remark

For P control and PD control, the manual reset function is activated. (☞ Page 141, Section 8.2.4)

(1) Two-position control

Two-position control is a control method that uses 0% manipulated value (MV) and 100% manipulated value (MV). Turning on and off the manipulated value (MV) repeatedly, the temperature process value comes close to the set value (SV), then is kept constant.

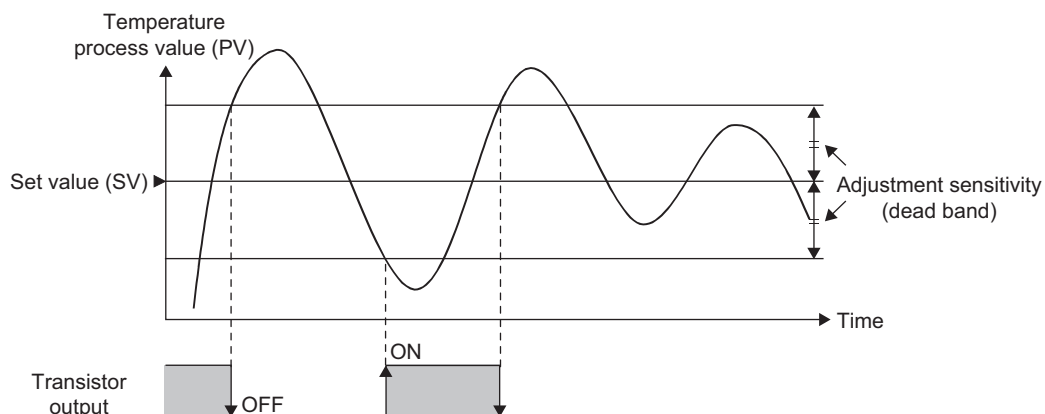
Point

By the setting in CH□ Adjustment sensitivity (dead band) setting (Un\G46, Un\G78, Un\G110, Un\G142) the chattering of transistor output under two-position control can be prevented. Set a dead band toward the set value (SV) in CH□ Adjustment sensitivity (dead band) setting (Un\G46, Un\G78, Un\G110, Un\G142). (☞ Page 372, Appendix 2 (22))

(a) Standard control

The module operates as follows outside the range of CH□ Adjustment sensitivity (dead band) setting (Un\G46, Un\G78, Un\G110, Un\G142).

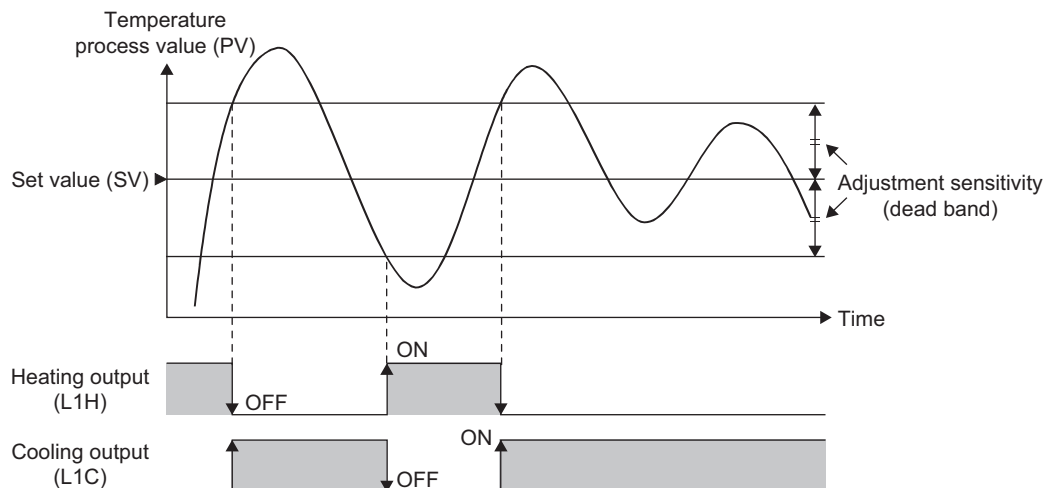
Condition	Transistor output status
The temperature process value (PV) is below the lower limit of the adjustment sensitivity (dead band).	ON
The temperature process value (PV) is above the upper limit of the adjustment sensitivity (dead band).	OFF



(b) Heating-cooling control

The module operates as follows outside the range of CH□ Adjustment sensitivity (dead band) setting (Un\G46, Un\G78, Un\G110, Un\G142).

Condition	Heating transistor output status	Cooling transistor output status
The temperature process value (PV) is below the lower limit of the adjustment sensitivity (dead band).	ON	OFF
The temperature process value (PV) is above the upper limit of the adjustment sensitivity (dead band).	OFF	ON



(c) Three-position control

Three-position control can also be performed by setting a dead band.

For more details, refer to the following.

☞ Page 217, Section 8.2.23 (3)

(d) Setting method

Set "Proportional band (P) setting/Heating control proportional band setting (Ph)" to 0.0%.

☞ Project window ⇒ [Intelligent Function Module] ⇒ Module name ⇒ [Parameter]

Item	CH1
Control basic parameter setting	The Q64TC exercises temperature adjust
Proportional band (P) setting/Heating control proportional band setting	0.0 %
Cooling proportional band (Pc) setting	3.0 %
Integral time (I) setting	240 s
Derivative time (D) setting	60 s
Control output cycle setting/Heating control output	30 s

(2) P Control

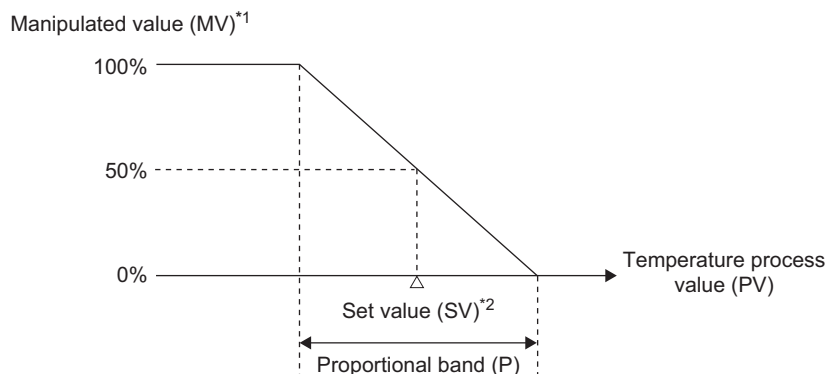
P control is a control method in which the manipulated value (MV) is determined proportional to the deviation (E) between the temperature process value (PV) and set value (SV).

(a) Standard control

The manipulated value is 50% in the following conditions.

- Temperature process value (PV) = Set value (SV)
- CH□ Manual reset amount setting (Un\G724, Un\G740, Un\G756, Un\G772) is set to 0 (0.0%).

(☞ Page 415, Appendix 2 (81))



*1 The actual output value is restricted within the output limiter range set in CH□ Upper limit output limiter (Un\G42, Un\G74, Un\G106, Un\G138) and CH□ Lower limit output limiter (Un\G43, Un\G75, Un\G107, Un\G139). (☞ Page 369, Appendix 2 (19))

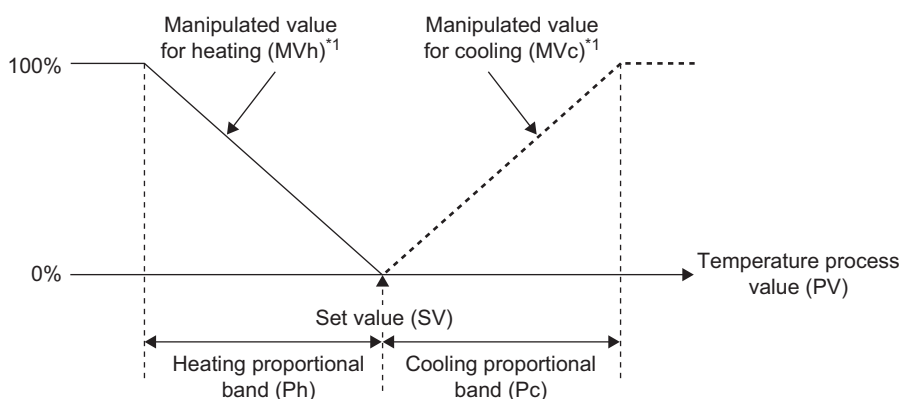
*2 The set value (SV) is in the center of the proportional band.

(b) Heating-cooling control

The manipulated value for heating (MVh) and the manipulated value for cooling (MVc) are both 0% in the following conditions.

- Temperature process value (PV) = Set value (SV)
- CH□ Manual reset amount setting (Un\G724, Un\G740, Un\G756, Un\G772) is set to 0 (0.0%).

(☞ Page 415, Appendix 2 (81))



*1 The actual output value is restricted within the output limiter range set in CH□ Heating upper limit output limiter (Un\G42, Un\G74, Un\G106, Un\G138) and CH□ Cooling upper limit output limiter (Un\G721, Un\G737, Un\G753, Un\G769). (☞ Page 369, Appendix 2 (19))

(c) Setting method

Set each item as follows.

- "Proportional band (P) setting/Heating control proportional band setting (Ph)" : any value
- "Integral time (I) setting": 0s
- "Derivative time (D) setting": 0s

 Project window ⇒ [Intelligent Function Module] ⇒ Module name ⇒ [Parameter]

Item	CH1	
Control basic parameter setting	The Q64TC exercises temperature adjust	
Proportional band (P) setting/Heating control proportional band setting (Ph)	3.0 %	3
Cooling proportional band (Pc) setting	3.0 %	3
Integral time (I) setting	0 s	2
Derivative time (D) setting	0 s	6

(3) PI Control

PI control is a control method in which integral elements are added to P control, thereby an offset (remaining deviation) is compensated. By setting the integral time (I) properly, the temperature process value (PV) matches with the set value (SV).

(a) Setting method

Set each item as follows.

- "Proportional band (P) setting/Heating control proportional band setting (Ph)" : any value
- "Integral time (I) setting": any value
- "Derivative time (D) setting": 0s

 Project window ⇒ [Intelligent Function Module] ⇒ Module name ⇒ [Parameter]

Item	CH1	
Control basic parameter setting	The Q64TC exercises temperature adjust	
Proportional band (P) setting/Heating control proportional band setting (Ph)	3.0 %	
Cooling proportional band (Pc) setting	3.0 %	
Integral time (I) setting	240 s	
Derivative time (D) setting	0 s	
Control output cycle setting/Heating control output cycle setting	30 s	

(4) PD Control

PD control is a control method in which the derivative time (D) is set in addition to PD control. The control mechanism is the same as P control.

(a) Setting method

Set each item as follows.

- "Proportional band (P) setting/Heating control proportional band setting (Ph)" : any value
- "Integral time (I) setting": 0s
- "Derivative time (D) setting": any value

 Project window ⇨ [Intelligent Function Module] ⇨ Module name ⇨ [Parameter]

Item	CH1
Control basic parameter setting	The Q64TC exercises temperature adjust
Proportional band (P) setting/Heating control proportional band setting (Ph)	3.0 %
Cooling proportional band (Pc) setting	3.0 %
Integral time (I) setting	0 s
Derivative time (D) setting	60 s

(5) PID Control

PID control is a control method in which derivative elements are added to PI control, thereby the temperature shifts to a stable status in a short period of time even when a drastic change has occurred. By setting the derivative time (D) properly, the control subject shifts to a stable status in a short period of time.

(a) Setting method

Set any value to "Proportional band (P) setting/Heating control proportional band setting (Ph)", "Integral time (I) setting", and "Derivative time (D) setting".

 Project window ⇨ [Intelligent Function Module] ⇨ Module name ⇨ [Parameter]

Item	CH1
Control basic parameter setting	The Q64TC exercises temperature adjust
Proportional band (P) setting/Heating control proportional band setting (Ph)	3.0 %
Cooling proportional band (Pc) setting	3.0 %
Integral time (I) setting	240 s
Derivative time (D) setting	60 s

(6) Condition to perform PID control

The condition to be able to perform PID control^{*1} depends on the settings of the followings.

- Setting/operation mode instruction (Yn1) (Page 340, Appendix 1.2 (1))
- PID continuation flag (Un\G169) (Page 390, Appendix 2 (43))
- CH□ PID control forced stop instruction (YnC to YnF) (Page 343, Appendix 1.2 (7))
- CH□ Stop mode setting (Un\G33, Un\G65, Un\G97, Un\G129) (Page 362, Appendix 2 (13))

The following table shows the relationship between the status of PID control^{*1} and each of the settings above.

○: Performed ×: Not performed

Setting/operation mode instruction (Yn1) ^{*2}	PID continuation flag (Un\G169)	CH□ PID control forced stop instruction (YnC to YnF)	CH□ Stop mode setting (Un\G33, Un\G65, Un\G97, Un\G129)	Control status of PID control ^{*1}
Setting mode at power-ON	Stop (0)/Continue (1)	OFF/ON	Stop (0)/Monitor (1)/Alert (2)	×
Operation mode (operating)	Stop (0)/Continue (1)	OFF	Stop (0)/Monitor (1)/Alert (2)	○
		ON	Stop (0)/Monitor (1)/Alert (2)	×
Setting mode (after operation)	Stop (0)	OFF/ON	Stop (0)/Monitor (1)/Alert (2)	×
	Continue (1)	OFF	Stop (0)/Monitor (1)/Alert (2)	○
		ON	Stop (0)/Monitor (1)/Alert (2)	×

^{*1} Here, this is the generic term for two-position control, P control, PI control, PD control, and PID control.

^{*2} For the timing of each, refer to Page 334, Appendix 1.1 (2)

Even though the conditions above are met, PID control is not performed when CH□ Unused channel setting (Un\G61, Un\G93, Un\G125, Un\G157) is set to Unused (1). (Page 385, Appendix 2 (35))

Point

The manipulated value (MV) and manipulated value (MV) for output with another analog module of when CH□ PID control forced stop instruction (YnC to YnF) is turned on from off are as follows.

Buffer memory area name	Buffer memory address				Stored value	Reference
	CH1	CH2	CH3	CH4		
CH□ Manipulated value (MV)	Un\G13	Un\G14	Un\G15	Un\G16	-50 (-5.0%)	Page 349, Appendix 2 (5)
CH□ Manipulated value (MV) for output with another analog module	Un\G177	Un\G178	Un\G179	Un\G180	0	Page 392, Appendix 2 (47)
CH□ Manipulated value for heating (MVh) (Un\G13 to Un\G16)	Un\G13	Un\G14	Un\G15	Un\G16	-50 (-5.0%)	Page 349, Appendix 2 (5)
CH□ Manipulated value of heating (MVh) for output with another analog module	Un\G177	Un\G178	Un\G179	Un\G180	0	Page 392, Appendix 2 (47)
CH□ Manipulated value for cooling (MVc)	Un\G704	Un\G705	Un\G706	Un\G707	-50 (-5.0%)	Page 349, Appendix 2 (5)
CH□ Manipulated value of cooling (MVc) for output with another analog module	Un\G708	Un\G709	Un\G710	Un\G711	0	Page 392, Appendix 2 (47)

When CH□ PID control forced stop instruction (YnC to YnF) is turned off from on, the forced stop of PID control is released. After the release, PID operation starts from the beginning.

(7) Buffer memory areas related to control method

The following table shows the buffer memory areas related to control method.

Buffer memory area name	Buffer memory address				Setting range					Reference
	CH1	CH2	CH3	CH4	Two- position control	P control	PD control	PI control	PID control	
CH□ Input range	Un\G32	Un\G64	Un\G96	Un\G128	Thermocouple: 1 to 4, 11 to 28, 36 to 48, 49 to 52, 100 to 117, 130 to 132, 201 to 205 Platinum resistance thermometer: 5 to 8, 53, 54, 140 to 143, 201 to 205					Page 355, Appendix 2 (12)
CH□ Set value (SV) setting	Un\G34	Un\G66	Un\G98	Un\G130	Set a value within the temperature measurement range of the set input range.					Page 363, Appendix 2 (14)
CH□ Proportional band (P) setting	Un\G35	Un\G67	Un\G99	Un\G131	Fix the setting to 0.	Configure the setting in the range from 0 to 10000 (0.0% to 1000.0%) toward the full scale of the set input range.				Page 364, Appendix 2 (15)
CH□ Heating proportional band (Ph) setting	Un\G35	Un\G67	Un\G99	Un\G131						
CH□ Cooling proportional band (Pc) setting	Un\G720	Un\G736	Un\G752	Un\G768	The setting is ignored.*1	Configure the setting in the range from 1 to 10000 (0.1% to 1000.0%) toward the full scale of the set input range.				
CH□ Integral time (I) setting	Un\G36	Un\G68	Un\G100	Un\G132	The setting is ignored.*1	Fix the setting to 0.	Fix the setting to 0.	1 to 3600 (s)	1 to 3600 (s)	Page 366, Appendix 2 (16)
CH□ Derivative time (D) setting	Un\G37	Un\G69	Un\G101	Un\G133	The setting is ignored.*1	Fix the setting to 0.	1 to 3600 (s)	Fix the setting to 0.	1 to 3600 (s)	Page 366, Appendix 2 (17)
CH□ Upper limit output limiter	Un\G42	Un\G74,	Un\G106	Un\G138	The setting is ignored.*1	-50 to 1050 (-5.0% to 105.0%)				Page 369, Appendix 2 (19)
CH□ Lower limit output limiter	Un\G43	Un\G75	Un\G107	Un\G139						
CH□ Heating upper limit output limiter	Un\G42	Un\G74	Un\G106	Un\G138		0 to 1050 (0.0% to 105.0%)				
CH□ Cooling upper limit output limiter	Un\G721	Un\G737	Un\G753	Un\G769						
CH□ Output variation limiter setting	Un\G44	Un\G76	Un\G108	Un\G140	The setting is ignored.*1	1 to 1000 (0.1%/s to 100.0%/s)				Page 371, Appendix 2 (20)
CH□ Adjustment sensitivity (dead band) setting	Un\G46	Un\G78	Un\G110	Un\G142	Configure the setting in the range from 1 to 100 (0.1% to 10.0%) toward the full scale of the set input range.	The setting is ignored.*1				Page 372, Appendix 2 (22)

Buffer memory area name	Buffer memory address				Setting range					Reference
	CH1	CH2	CH3	CH4	Two- position control	P control	PD control	PI control	PID control	
CH□ Control output cycle setting	Un\G47	Un\G79	Un\G111	Un\G143	The setting is ignored.*1	• The control output cycle unit selection setting on Switch Setting is 1s: 1 to 100 (1s to 100s) • The control output cycle unit selection setting on Switch Setting is 0.1s: 5 to 1000 (0.5s to 100.0s)				Page 373, Appendix 2 (23)
CH□ Heating control output cycle setting	Un\G47	Un\G79	Un\G111	Un\G143						
CH□ Cooling control output cycle setting	Un\G722	Un\G738	Un\G754	Un\G770						
CH□ Overlap/dead band setting	Un\G723	Un\G739	Un\G755	Un\G771	Configure the setting in the range from -100 to 100 (-10.0% to 10.0%) toward the full scale of the set input range.					Page 415, Appendix 2 (80)
CH□ Manual reset amount setting	Un\G724	Un\G740	Un\G756	Un\G772	The setting is ignored.*1	Configure the setting in the range from -1000 to 1000 (-100.0 to 100.0%) toward the full scale of the set input range.		The setting is ignored.*1		Page 415, Appendix 2 (81)

*1 When outside the setting range, a write data error (error code: □□□4_H) occurs.

Point

The L60TC4 automatically sets optimum PID constants if the following functions are used.

- Auto tuning function (☞ Page 145, Section 8.2.7)
- Self-tuning function (☞ Page 179, Section 8.2.15)

8.2.4 Manual Reset Function

Standard Heating-cooling

The position of the stable condition in P control or PD control can be shifted manually using this function.

By shifting the proportional band (P), an offset (remaining deviation) is manually reset.

The offset is reset by determining and setting the amount to shift the value of the manipulated value (MV) in a stable condition from the reference value.

The reference value is 50% for standard control, and 0% for heating-cooling control.

Point

This function can be active only in P control and PD control. This function is inactive when integral time (I) is other than 0. CH□ Manual reset amount setting (Un\G724, Un\G740, Un\G756, Un\G772) is ignored even if it is set. (Note that a write data error (error code: □□□4_H) occurs if it is outside the setting range.)

(1) Standard control

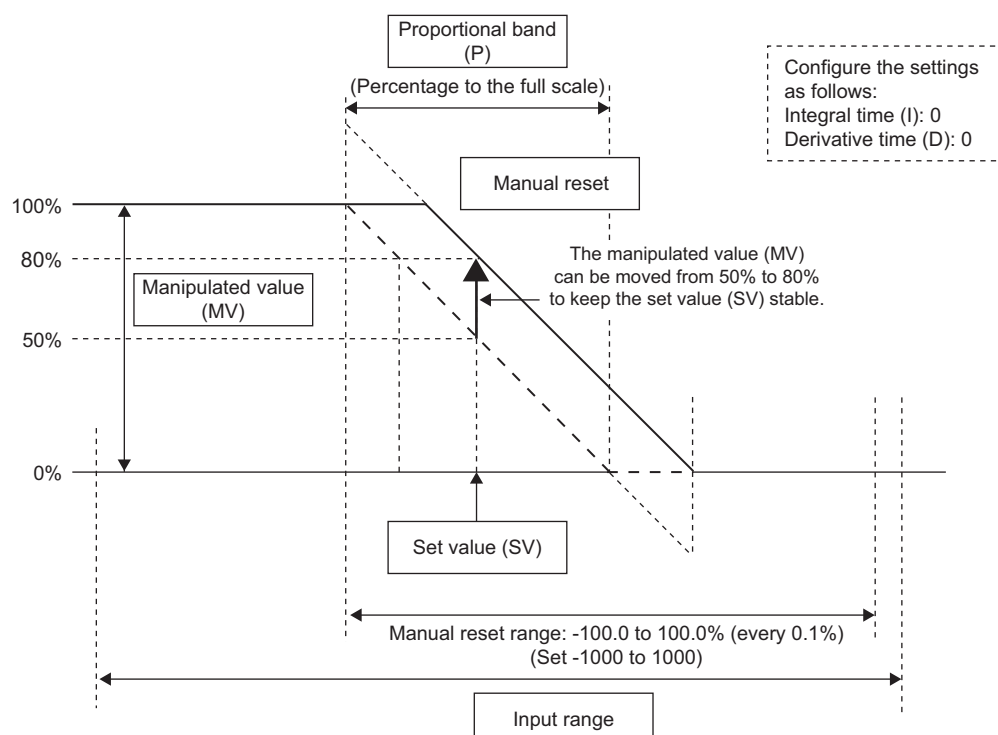
The set value (SV) is set where the manipulated value (MV) is 50%. Due to this, as long as the temperature process value (PV) and the set value (SV) is not in equilibrium at 50% of manipulated value, an offset (remaining deviation) generates.

When an offset generates, the proportional band (P) can be manually shifted by the amount of the offset (remaining deviation).

Ex. When using the manual reset function in the following conditions

- Control method: P control
- CH□ Manual reset amount setting (Un\G724, Un\G740, Un\G756, Un\G772): 300 (30%)

The L60TC4 shifts the manipulated value (MV) by which the temperature is stabilized at the set value (SV) from 50% to 80%.



(2) Heating-cooling control

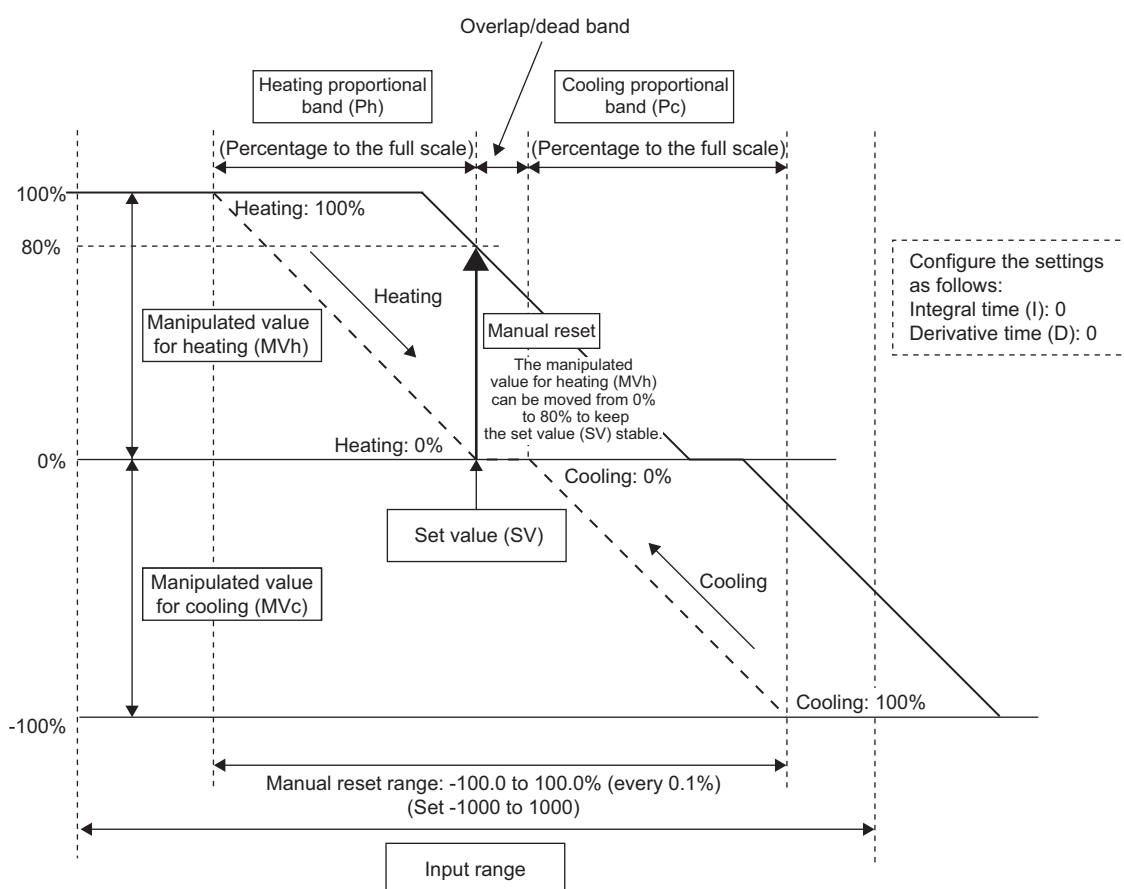
The set value (SV) is set where the manipulated value for heating (MVh)/manipulated value for cooling (MVC) is 0%. Due to this, as long as the temperature process value (PV) and the set value (SV) is not in equilibrium at 0% of manipulated value for heating (MVh)/manipulated value for cooling (MVC), an offset (remaining deviation) generates. When an offset generates, the heating proportional band (Ph)/cooling proportional band (Pc) can be manually shifted by the amount of the offset (remaining deviation).

Ex. When using the manual reset function in the following conditions

- Control method: P control

CH□ Manual reset amount setting (Un\G724, Un\G740, Un\G756, Un\G772): 800 (80%)

The L60TC4 shifts the manipulated value for heating (MVh) by which the temperature is stabilized at the set value (SV) from 0% to 80%.



(3) Setting method

Set a value in the following buffer memory area.

- CH□ Manual reset amount setting (Un\G724, Un\G740, Un\G756, Un\G772) (Page 415, Appendix 2 (81))

8.2.5 Manual Control

Standard Heating-cooling

Manual control is a form of control for which the user sets the manipulated value (MV) manually instead of obtaining it automatically by PID control.

The manipulated value (MV) is checked every 250ms or 500ms^{*1}, and is reflected to transistor output.

^{*1} This depends on the setting in "Sampling Cycle Selection". (☞ Page 111, Section 7.2 (1) (b))

(1) Setting method

Follow the following procedure for setting.

- 1. Shift to the MAN (manual) mode. (Set MAN (1) in CH□ AUTO/MAN mode shift (Un\G50, Un\G82, Un\G114, Un\G146).)** (☞ Page 376, Appendix 2 (26))
- 2. Check the storage of MAN mode shift completed (1) into MAN mode shift completion flag (Un\G30).** (☞ Page 352, Appendix 2 (10))
- 3. Set the manipulated value (MV) in CH□ MAN output setting (Un\G51, Un\G83, Un\G115, Un\G147)^{*1}** (☞ Page 377, Appendix 2 (27))

^{*1} The setting range differs for standard control and heating-cooling control.

Standard control: -50 to 1050 (-5.0% to 105.0%)

Heating-cooling control: -1050 to 1050 (-105.0% to 105.0%)

8.2.6 Control output cycle unit selection function

Standard Heating-cooling

The unit of the control output cycle can be selected from 1s or 0.1s using this function.

When the control output cycle is set in 0.1s, control can be more attentive.

The control output cycle is the ON/OFF cycle of transistor output for the temperature control function.

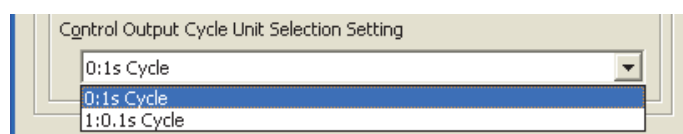
The cycle can be set in the following buffer memory areas.

Control mode	Buffer memory area name	Buffer memory address				Reference
		CH1	CH2	CH3	CH4	
Standard control	CH□ Control output cycle setting	Un\G47	Un\G79	Un\G111	Un\G143	Page 373, Appendix 2 (23)
Heating-cooling control	CH□ Heating control output cycle setting	Un\G47	Un\G79	Un\G111	Un\G143	
	CH□ Cooling control output cycle setting	Un\G722	Un\G738	Un\G754	Un\G770	

(1) Setting method

Select 1s cycle or 0.1s cycle in "Control Output Cycle Unit Selection Setting".

🖱️ Project window ⇨ [Intelligent Function Module] ⇨ Module name ⇨ [Switch Setting]



Point

- The setting range and default value of the control output cycle depends on this setting. (👉 Page 373, Appendix 2 (23))
- A setting value discrepancy error (error code: 002EH) occurs right after changing this setting. To recover from the error status, turn Set value backup instruction (Yn8) as follows: OFF→ON→OFF. Then, register the setting after the change to the L60TC4.

8.2.7 Auto tuning function

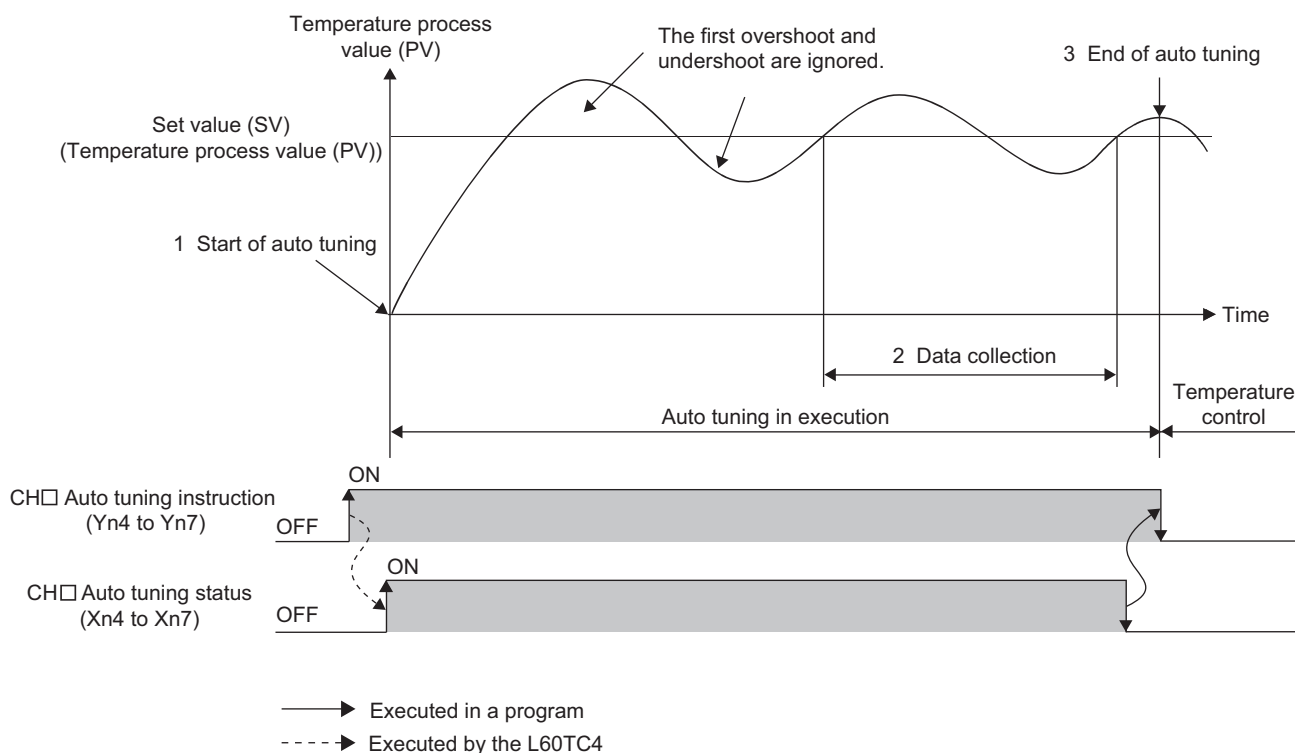
Standard Heating-cooling

This function is designed for the Q64TCN to set the optimum PID constants automatically. In auto tuning, the PID constants are calculated according to the hunting cycle and amplitude generated by repeated overshoot and undershoot of the process value (PV) against the set value (SV) due to the on-off action of control output.

(1) Auto tuning operation

The L60TC4 operates as follows.

Operation of the L60TC4	
1	Starts auto-tuning
2	Collects data from the point when the temperature process value (PV) reaches the set value (SV) after the first overshoot and undershoot
3	After data collection, auto tuning ends when PID constants and loop disconnection detection judgment time are set.



Remark

The time takes for auto tuning depends on the control subject.

(2) Buffer memory areas related to auto tuning

Auto tuning can be executed when the following data are set.

Note that other data must be preset to the values used for actual operation since actual control starts on completion of auto tuning.

When "0" is set to the proportional band (P)/heating proportional band (Ph), auto tuning is not executed.

( Page 364, Appendix 2 (15))

Buffer memory area name	Buffer memory address				Reference
	CH1	CH2	CH3	CH4	
CH□ Input range	Un\G32	Un\G64	Un\G96	Un\G128	Page 355, Appendix 2 (12)
CH□ Set value (SV) setting	Un\G34	Un\G66	Un\G98	Un\G130	Page 363, Appendix 2 (14)
CH□ Upper limit output limiter	Un\G42	Un\G74	Un\G106	Un\G138	Page 369, Appendix 2 (19)
CH□ Lower limit output limiter	Un\G43	Un\G75	Un\G107	Un\G139	
CH□ Heating upper limit output limiter	Un\G42	Un\G74	Un\G106	Un\G138	
CH□ Cooling upper limit output limiter	Un\G721	Un\G737	Un\G753	Un\G769	
CH□ Output variation limiter setting	Un\G44	Un\G76	Un\G108	Un\G140	Page 371, Appendix 2 (20)
CH□ Sensor correction value setting	Un\G45	Un\G77	Un\G109	Un\G141	Page 372, Appendix 2 (21)
CH□ Control output cycle setting	Un\G47	Un\G79	Un\G111	Un\G143	Page 373, Appendix 2 (23)
CH□ Heating control output cycle setting	Un\G47	Un\G79	Un\G111	Un\G143	
CH□ Cooling control output cycle setting	Un\G722	Un\G738	Un\G754	Un\G770	
CH□ Primary delay digital filter setting	Un\G48	Un\G80	Un\G112	Un\G144	Page 374, Appendix 2 (24)
CH□ AUTO/MAN mode shift	Un\G50	Un\G82	Un\G114	Un\G146	Page 376, Appendix 2 (26)
CH□ AT bias	Un\G53	Un\G85	Un\G117	Un\G149	Page 379, Appendix 2 (29)
CH□ Forward/reverse action setting	Un\G54	Un\G86	Un\G118	Un\G150	Page 380, Appendix 2 (30)
CH□ Auto tuning mode selection	Un\G184	Un\G185	Un\G186	Un\G187	Page 394, Appendix 2 (51)

(3) Storing the calculated value after auto tuning

After auto tuning is completed, the calculated values are stored into the following buffer memory areas.

Buffer memory area name	Buffer memory address				Reference
	CH1	CH2	CH3	CH4	
CH□ Proportional band (P) setting	Un\G35	Un\G67	Un\G99	Un\G131	Page 364, Appendix 2 (15)
CH□ Heating proportional band (Ph) setting	Un\G35	Un\G67	Un\G99	Un\G131	
CH□ Cooling proportional band (Pc) setting	Un\G720	Un\G736	Un\G752	Un\G768	
CH□ Integral time (I) setting	Un\G36	Un\G68	Un\G100	Un\G132	Page 366, Appendix 2 (16)
CH□ Derivative time (D) setting	Un\G37	Un\G69	Un\G101	Un\G133	Page 366, Appendix 2 (17)
CH□ Loop disconnection detection judgment time ^{*1}	Un\G59	Un\G91	Un\G123	Un\G155	Page 383, Appendix 2 (33)

*1 A value twice greater than the one in CH□ Integral time (I) setting (Un\G36, Un\G68, Un\G100, Un\G132) is automatically set. However, if this setting is 0(s) when auto tuning is in process, the loop disconnection detection judgment time is not stored.

(4) Backup of the calculated value on completion of auto tuning

By setting the following buffer memory area to Enable (1) at the start of auto tuning, the calculated value (☞ Page 146, Section 8.2.7 (3)) is automatically backed up into a non-volatile memory on completion of auto tuning.

- CH□ Automatic backup setting after auto tuning of PID constants (Un\G63, Un\G95, Un\G127, Un\G159) (☞ Page 387, Appendix 2 (37))

To read the calculated value (☞ Page 146, Section 8.2.7 (3)) from the non-volatile memory, set the following buffer memory area to Requested (1).

- CH□ Memory's PID constants read instruction (Un\G62, Un\G94, Un\G126, Un\G158) (☞ Page 386, Appendix 2 (36))

Point

To use the PID constants stored in the buffer memory also after the power is turned off, follow the methods below.

- Use the initial setting of GX Works2. (☞ Page 112, Section 7.3)
- Keep the PID constants in the non-volatile memory, and transfer them when the power is turned on from off or when the CPU module is released from the reset status. (☞ Page 242, Section 8.3.5)
- Write the value directly into the buffer memory through a program.

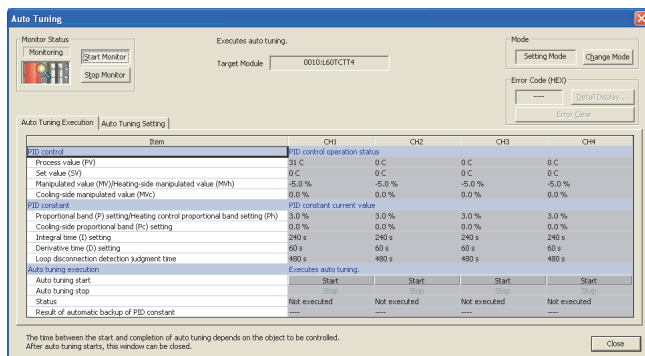
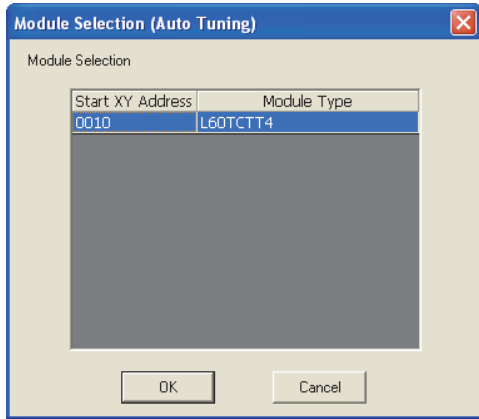
(5) Procedure of auto tuning

(a) GX Works2

Set this function on the "Auto Tuning" window.

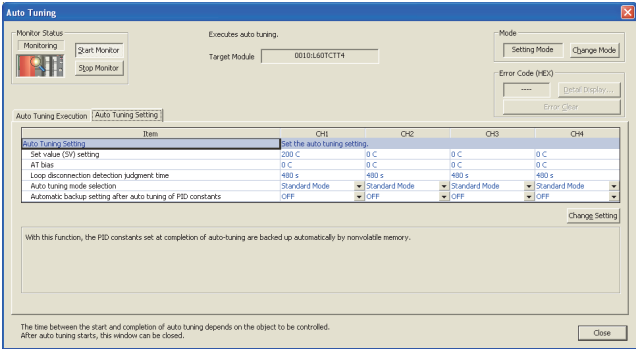
 [Tool] ⇨ [Intelligent Function Module Tool] ⇨ [Temperature Control Module] ⇨ [Auto Tuning...]

1. Select the module by which auto tuning is executed, and click .



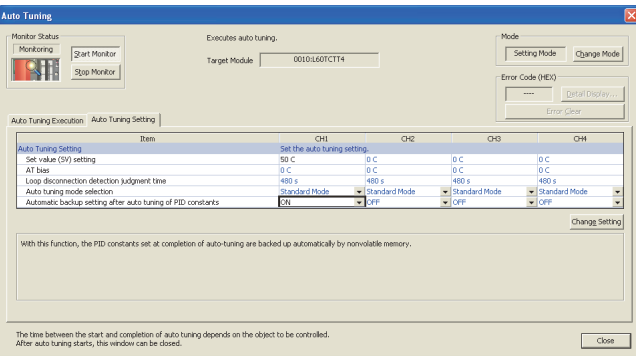
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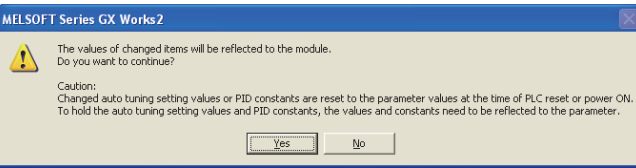
3. Configure the auto tuning setting.

↓



4. Click **Change Setting**.

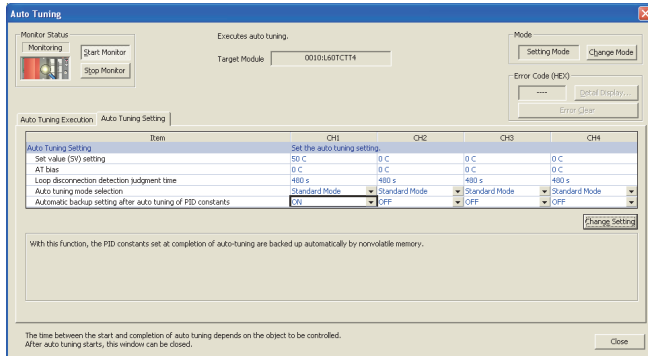
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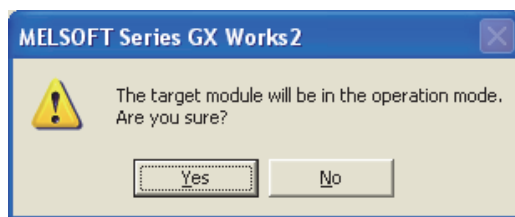
5. Click **Yes**.

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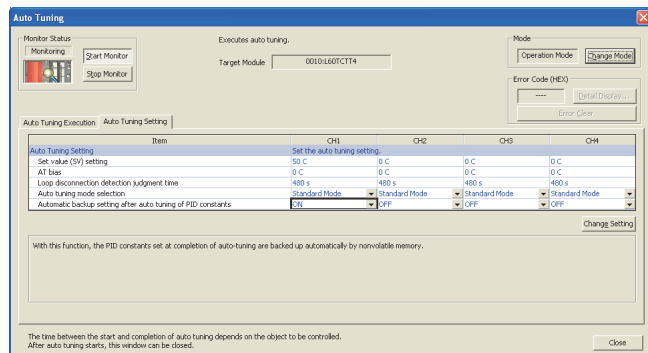
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6. Click **Change Mode**.



7. Click **Yes**.

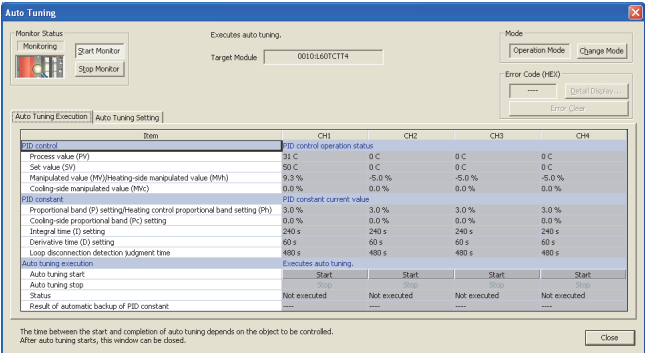


8. Click the "Auto Tuning Execution" tab.

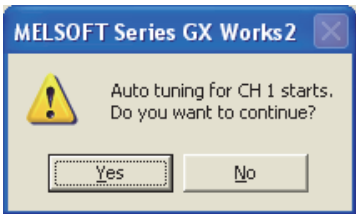


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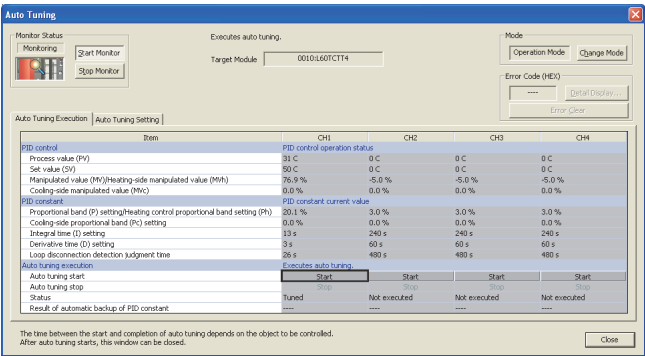
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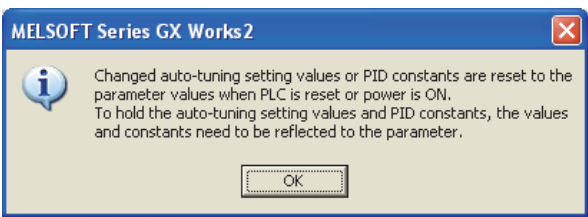
9. Click **Start** of the channel where auto tuning is to be executed.



10. Click **Yes**.



11. Check that "Status" has changed from "Executing" to "Tuned", and click **Close**.



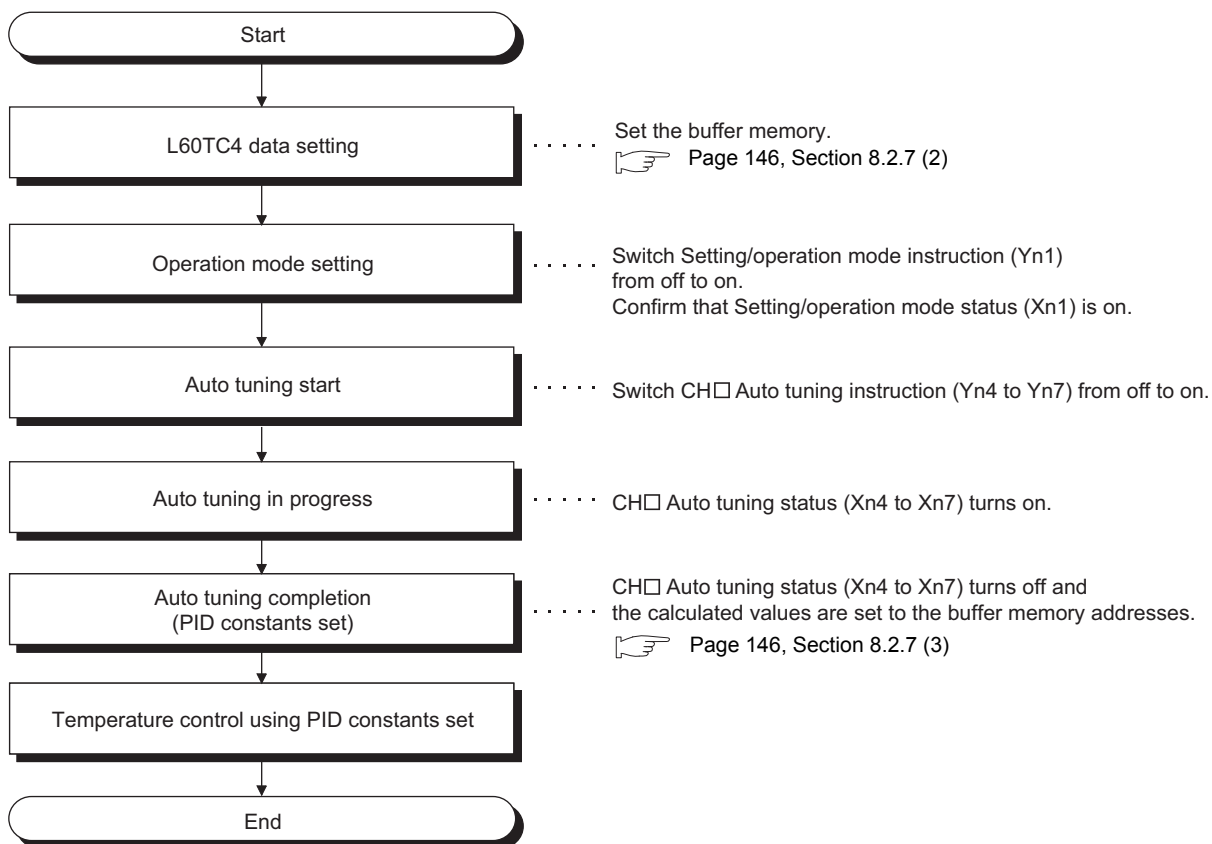
12. Click **OK**.



End

(b) Program

The execution procedure of auto tuning is as follows.



(6) Conditions where auto tuning cannot be executed

If one of the following conditions applies, auto tuning cannot be executed.

Conditions to start auto tuning		Reference
1	The module is in the setting mode (Setting/operation mode status (Xn1): OFF).	Page 334, Appendix 1.1 (2)
2	In standard control, CH□ Proportional band (P) setting (Un\G35, Un\G67, Un\G99, Un\G131) is set to 0. (operating in two-position control)	Page 364, Appendix 2 (15)
	In heating-cooling control, CH□ Heating proportional band (Ph) setting (Un\G35, Un\G67, Un\G99, Un\G131) is set to 0. (operating in two-position control)	
3	CH□ AUTO/MAN mode shift (Un\G50, Un\G82, Un\G114, Un\G146) is set to MAN (1).	Page 376, Appendix 2 (26)
4	Toward the corresponding channel, CH□ Unused channel setting (Un\G61, Un\G93, Un\G125, Un\G157) is set to Unused (1).	Page 385, Appendix 2 (35)
5	CH□ PID control forced stop instruction (YnC to YnF) is turned on.	Page 343, Appendix 1.2 (7)
6	Hardware failure has occurred. (The ERR. LED is on.)	Page 320, Section 11.3.2
7	CH□ Temperature process value (PV) (Un\G9 to Un\G12) has exceeded the temperature measurement range (CH□ Input range upper limit (b0 of Un\G5 to Un\G8) or CH□ Input range lower limit (b1 of Un\G5 to Un\G8) is 1 (ON)).	Page 346, Appendix 2 (3)
8	CH□ Memory's PID constants read instruction (Un\G62, Un\G94, Un\G126, Un\G158) is set to Requested (1).	Page 386, Appendix 2 (36)
9	CH□ Write completion flag (b4 to b7 of Un\G31) is on.	Page 353, Appendix 2 (11)

(a) When one of the conditions 1 to 5 applies

Auto tuning starts when the condition no longer applies.

(b) When the condition 7 applies

Even though the temperature process value (PV) goes back within the temperature measurement range, auto tuning does not start until CH□ Auto tuning instruction (Yn4 to Yn7) is turned on from off once again.

(c) When the condition 8 or 9 applies

Even though the internal processing of auto tuning is completed and PID constants are stored, CH□ Auto tuning status (Xn4 to Xn7) does not turn off, therefore the auto tuning is not completed.

(7) Conditions where auto tuning ends in fail

The conditions are described below.

(a) Shift from the operation mode to the setting mode

Shifting from the operation mode to the setting mode (Setting/operation mode instruction (Yn1) is turned off from on) ends auto tuning in fail. Note that an exception is when PID continuation flag (Un\G169) is set to Continue (1). (Page 390, Appendix 2 (43))

(b) Setting change of the buffer memory during the execution of auto tuning

If a setting in the following buffer memory areas is changed during the execution of auto tuning, the processing ends in fail.

Buffer memory area name	Buffer memory address				Reference
	CH1	CH2	CH3	CH4	
CH□ Set value (SV) setting	Un\G34	Un\G66	Un\G98	Un\G130	Page 363, Appendix 2 (14)
CH□ Upper limit output limiter	Un\G42	Un\G74	Un\G106	Un\G138	Page 369, Appendix 2 (19)
CH□ Lower limit output limiter	Un\G43	Un\G75	Un\G107	Un\G139	
CH□ Cooling upper limit output limiter	Un\G721	Un\G737	Un\G753	Un\G769	
CH□ Sensor correction value setting	Un\G45	Un\G77	Un\G109	Un\G141	
CH□ Control output cycle setting	Un\G47	Un\G79	Un\G111	Un\G143	Page 373, Appendix 2 (23)
CH□ Cooling control output cycle setting	Un\G722	Un\G738	Un\G754	Un\G770	
CH□ Primary delay digital filter setting	Un\G48	Un\G80	Un\G112	Un\G144	Page 374, Appendix 2 (24)
CH□ AUTO/MAN mode shift	Un\G50	Un\G82	Un\G114	Un\G146	Page 376, Appendix 2 (26)
CH□ AT bias	Un\G53	Un\G85	Un\G117	Un\G149	Page 379, Appendix 2 (29)
CH□ Forward/reverse action setting	Un\G54	Un\G86	Un\G118	Un\G150	Page 380, Appendix 2 (30)
CH□ Unused channel setting	Un\G61	Un\G93	Un\G125	Un\G157	Page 385, Appendix 2 (35)
Cold junction temperature compensation selection	Un\G182				Page 393, Appendix 2 (49)

(c) Out of the temperature measurement range

If CH□ Temperature process value (PV) (Un\G9 to Un\G12) exceeds the temperature measurement range (CH□ Input range upper limit (b0 of Un\G5 to Un\G8) or CH□ Input range lower limit (b1 of Un\G5 to Un\G8) becomes 1 (ON)), auto tuning ends in fail. (Page 346, Appendix 2 (3))

(d) Time until the temperature process value (PV) reaches the set value (SV) for the first time or a half the hunting cycle of the temperature process value (PV)

If the time below exceeds two hours, auto tuning ends in fail.

- Time from the start of auto tuning until CH□ Temperature process value (PV) (Un\G9 to Un\G12) reaches the set value (SV) for the first time
- A half the hunting cycle of CH□ Temperature process value (PV) (Un\G9 to Un\G12)

(e) Calculated values of PID constants after auto tuning

If a calculated value of PID constants after auto tuning exceeds one of the following ranges, auto tuning ends in fail.

- CH□ Proportional band (P) setting (Un\G35, Un\G67, Un\G99, Un\G131): 1 to 10000 (0.1% to 1000.0%)
- CH□ Integral time (I) setting (Un\G36, Un\G68, Un\G100, Un\G132): 1 to 3600 (1s to 3600s)
- CH□ Derivative time (D) setting (Un\G37, Un\G69, Un\G101, Un\G133): 0 to 3600 (0s to 3600s)

Point

If auto tuning ends in fail due to the calculated value of PID constants as described above, the system configuration needs to be reconsidered (such as selecting proper heater capacity).

(f) Change of the upper limit setting limiter or lower limit setting limiter and the set value (SV)

If the set value (SV) goes out of the setting range due to the change in one of the following buffer memory areas, auto tuning ends in fail.

- CH□ Upper limit setting limiter (Un\G55, Un\G87, Un\G119, Un\G151)
- CH□ Lower limit setting limiter (Un\G56, Un\G88, Un\G120, Un\G152)

(g) Other conditions

In addition to the conditions described up until here, if any of the following conditions applies, auto tuning ends in fail.

- CH□ PID control forced stop instruction (YnC to YnF) has been turned on from off. (☞ Page 343, Appendix 1.2 (7))
- Hardware failure has occurred.
- In standard control, CH□ Proportional band (P) setting (Un\G35, Un\G67, Un\G99, Un\G131) has been set to 0. (has been set to two-position control) (☞ Page 364, Appendix 2 (15))
- In heating-cooling control, CH□ Heating proportional band (Ph) setting (Un\G35, Un\G67, Un\G99, Un\G131) has been set to 0. (has been set to two-position control) (☞ Page 364, Appendix 2 (15))

(8) Operation on completion of auto tuning

(a) Normal completion

The L60TC4 operates as follows.

- Turns off CH□ Auto tuning status (Xn4 to Xn7)
- Stores the PID constants in the buffer memory (☞ Page 146, Section 8.2.7 (3))
- Stores a value in CH□ Loop disconnection detection judgment time (Un\G59, Un\G91, Un\G123, Un\G155) (If this was set to 0 (s) at the start of auto tuning, the setting remains unchanged.)

(b) Abnormal completion

The L60TC4 operates as follows.

- Turns off CH□ Auto tuning status (Xn4 to Xn7).
- Does not store the PID constants in the buffer memory. (☞ Page 146, Section 8.2.7 (3))

(9) Checking the completion of auto tuning

The completion of auto tuning can be checked by the status change from on to off in CH□ Auto tuning status (Xn4 to Xn7).

(10)Adjustment after auto tuning

To change the control response toward the PID constants calculated by auto tuning, change the setting in the following buffer memory area.

- CH□ Control response parameter (Un\G49, Un\G81, Un\G113, Un\G145) (☞ Page 375, Appendix 2 (25))

Point

In the system where the temperature rise rapidly, auto tuning may not be performed properly due to the excessive temperature rise during the auto tuning. Therefore, for a sequence program to perform auto tuning, incorporate the alert function so that the auto tuning will be stopped if an alert occurs.

For details on the sequence program, refer to the following.

☞ Page 257, CHAPTER 10

(11)During auto tuning loop disconnection detection function

For details on the during AT loop disconnection detection function, refer to the following.

☞ Page 210, Section 8.2.20)

8.2.8 Simple Two-degree-of-freedom

Standard Heating-cooling

This is the simplified control form of the two-degree-of-freedom PID control. In this form of PID control, the L60TC4 controls the target subject using not only PID constants but also the control response parameter. The response speed toward the change of the set value (SV) can be selected from three levels.

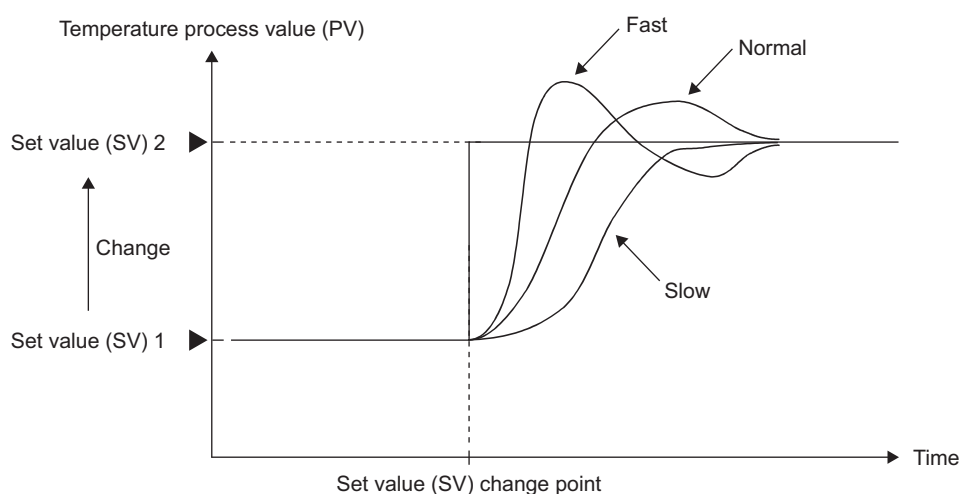
General PID control is called one-degree-of freedom PID control. In the one-degree-of freedom PID control, when PID constants to improve "response to the change of the set value (SV)" are set, "response to the disturbance" degrades. Conversely, when PID constants to improve "response to the disturbance" are set, "response to the change of the set value (SV)" degrades.

On the other hand, in the two-degree-of-freedom PID control, "response to the change of the set value (SV)" and "response to the disturbance" can be compatible with each other.

Note that required parameter settings increase and PID constants can hardly be auto-set by the auto tuning function for complete two-degree-of-freedom PID control. Therefore, the L60TC4 operates in the simple two-degree-of-freedom PID control for which parameters are simplified.

The level of "response to the change of the set value (SV)" can be selected from the following, maintaining the PID constants that improve "response to the disturbance".

- Fast
- Normal
- Slow



(1) Setting method

Set a value on "Control response parameter".

Project window ⇨ [Intelligent Function Module] ⇨ Module name ⇨ [Parameter]

Item	CH1
Control response parameter	0:Slow
Stop Mode Setting	0:Slow
PID continuation flag	1:Normal
Control detail parameter	2:Fast

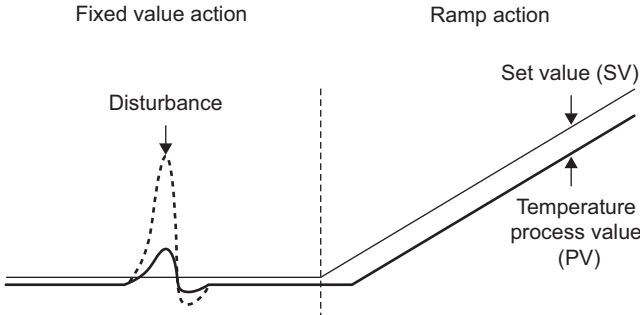
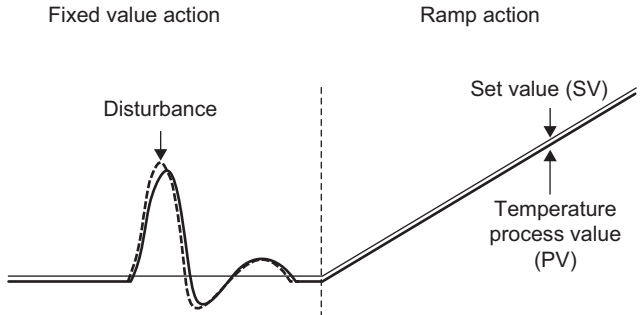
8.2.9 Derivative Action Selection Function

Standard Heating-cooling

An derivative action appropriate for each of fixed value action and ramp action can be selected and the action characteristic can be improved using this function.

(1) Action

Each type of derivative action operates as shown below.

CH□ Derivative action selection (Un\G729, Un\G745, Un\G761, Un\G777)	Action	
Measured value derivation (0)		This setting effectively prevents the temperature from being affected by disturbance, though the performance to follow the set value can be low.
Deviation derivation (1)		This setting allows the temperature to follow the set value well, though the disturbance effect is great.

(2) Setting method

Set a value on "Derivative action selection".

Project window ⇒ [Intelligent Function Module] ⇒ Module name ⇒ [Parameter]

Item	CH1
Derivative action selection	0:Measured Value
Simultaneous temperature rise group setting	0:Measured Value Derivative
Simultaneous temperature rise AT	1:Deviation Derivative

8.2.10 setting Change Rate Limiter Setting Function

Standard Heating-cooling

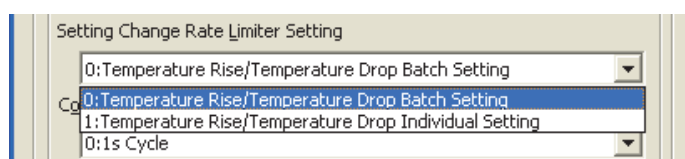
When the set value (SV) is changed, the change rate in the specified time unit can be set on "Setting Change Rate Limiter Setting". The user can select whether to set this rate for temperature rise and temperature drop individually or at once.

(1) Setting method

(a) Batch/individual setting for temperature rise and temperature drop

Select the value on "Setting Change Rate Limiter Setting".

Project window ⇨ [Intelligent Function Module] ⇨ Module name ⇨ [Switch Setting]



(b) Change rate setting

For batch-change, set "Setting change rate limiter or Setting change limiter (Temperature rise)" only.

Project window ⇨ [Intelligent Function Module] ⇨ Module name ⇨ [Parameter]

Item	CH1
Setting change rate limiter or Setting change rate limiter (Temperature rise)	40.0 %
Setting change rate limiter	

For individual setting, set "Setting change rate limiter or Setting change limiter (Temperature rise)" and "Setting change rate limiter (Temperature drop)".

Project window ⇨ [Intelligent Function Module] ⇨ Module name ⇨ [Parameter]

Item	CH1
Setting change rate limiter or Setting change rate limiter (Temperature rise)	40.0 %
Setting change rate limiter (Temperature drop)	20.0 %

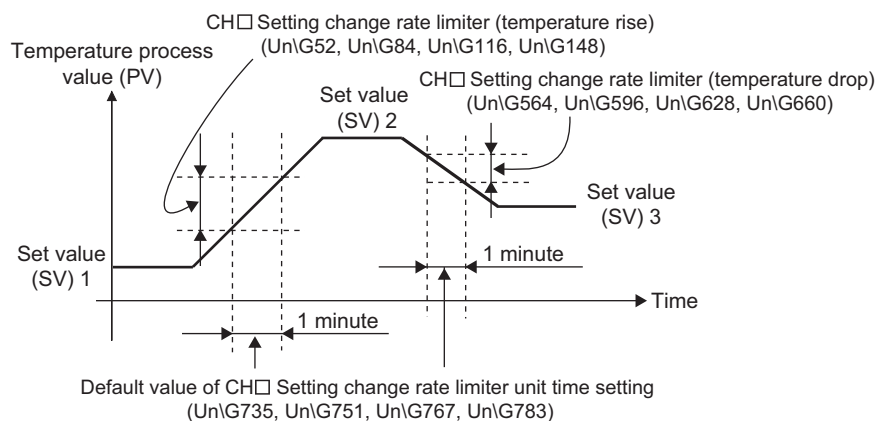
(c) Time unit setting

Set the time unit of the setting change rate limiter on "Setting change rate limiter Unit time setting".

🖱️ Project window ⇒ [Intelligent Function Module] ⇒ Module name ⇒ [Parameter]

Item	CH1
Setting change rate limiter Unit time setting	5 s
Back current suppression control	

Ex. Operation of when individual setting is selected on Switch Setting



8.2.11 Alert Function

Standard Heating-cooling

When the process value (PV) or deviation reaches the value set in advance, the system is set in an alert status. Use this function to activate danger signals of devices or safety devices.

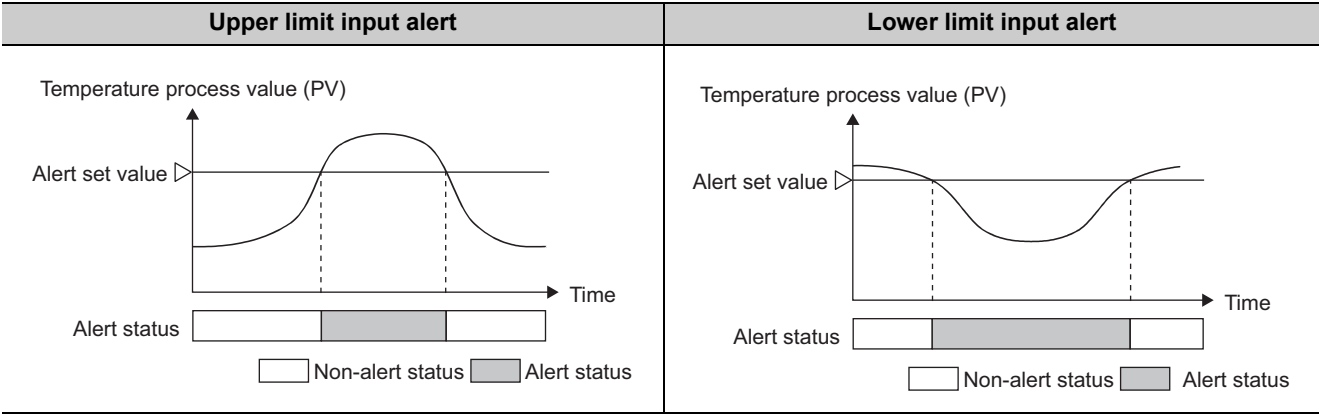
The alert function is classified into input alerts and deviation alerts depending on the setting of the alert mode.

- Input alert: upper limit input alert, lower limit input alert (☞ Page 161, Section 8.2.11 (1))
- Deviation alert: upper limit deviation alert, lower limit deviation alert, upper lower limit deviation alert, within-range alert (☞ Page 162, Section 8.2.11 (2))

(1) Input alert

With the upper limit input alert, when the process value (PV) is equal to or greater than the alert set value, the system is put in an alert status.

With the lower limit input alert, when the process value (PV) is equal to or less than the alert set value, the system is put in an alert status.



(a) Setting method

Set the alert mode. (☞ Page 171, Section 8.2.11 (7) (a))

- Upper limit input alert: Set the alert mode to "1: Upper Limit Input Alert".
- Lower limit input alert: Set the alert mode to "2: Lower Limit Input Alert".

(2) Deviation alert

With the deviation alert, when the deviation (E) between the temperature process value (PV) and the set value (SV) meets a particular condition, the system is put in an alert status.

The set value (SV) to be referred is either "set value (SV) monitor" or "set value (SV) setting" depending on the alert mode. When a setting change rate limiter is specified, "set value (SV) monitor" follows the set value (SV) by the specified change rate. (For details on the setting change rate limiter setting, refer to  Page 378, Appendix 2 (28).)

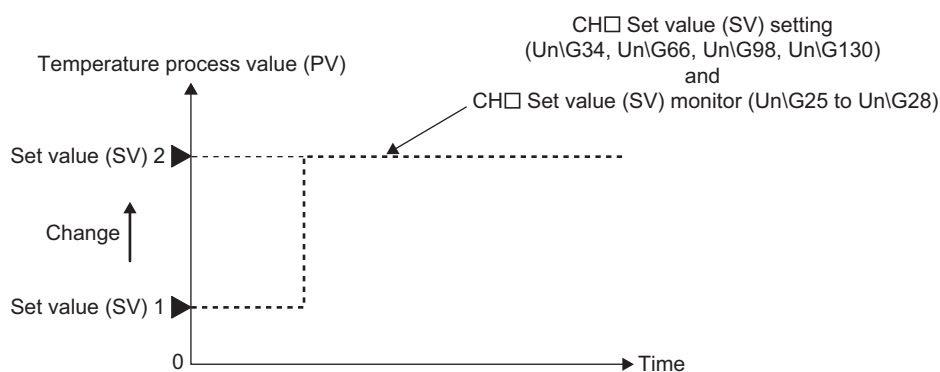
The following table describes the use of each set value (SV) of when a setting change rate limiter is specified, and can be referred to use a deviation alert.

Reference area of the set value (SV)	Use (when the set value (SV) is changed)
CH□ Set value (SV) monitor (Un\G25 to Un\G28)	This value is used when the temperature process value (PV) needs to follow the changing set value (SV) within a consistent deviation (E). If the temperature process value (PV) does not follow the set value (SV) and strays out of the set deviation range, an alert occurs.
CH□ Set value (SV) setting (Un\G34, Un\G66, Un\G98, Un\G130)	This value is used for the alert occurrence to be determined only by the deviation (E) from the set value (SV). In this case, how well the temperature process value (PV) is following the changing set value (SV) does not matter. Even if the value in CH□ Set value (SV) monitor (Un\G25 to Un\G28) is changing, an alert can occur depending on the deviation (E) from the set value (SV).

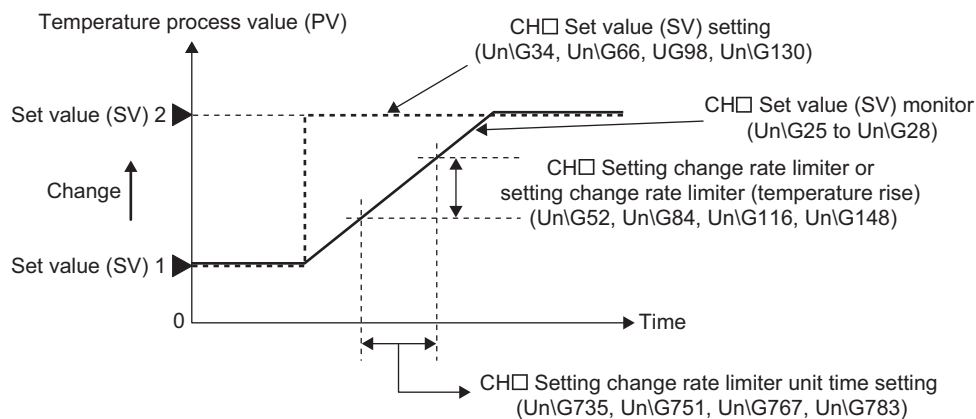
(a) Set value (SV) and the setting change rate limiter setting

The following figures show the relationships of two types of set value (SV) depending on whether the setting change rate limiter is specified or not.

- When the setting change rate limiter is not specified: The two types of set value (SV) are the same value.

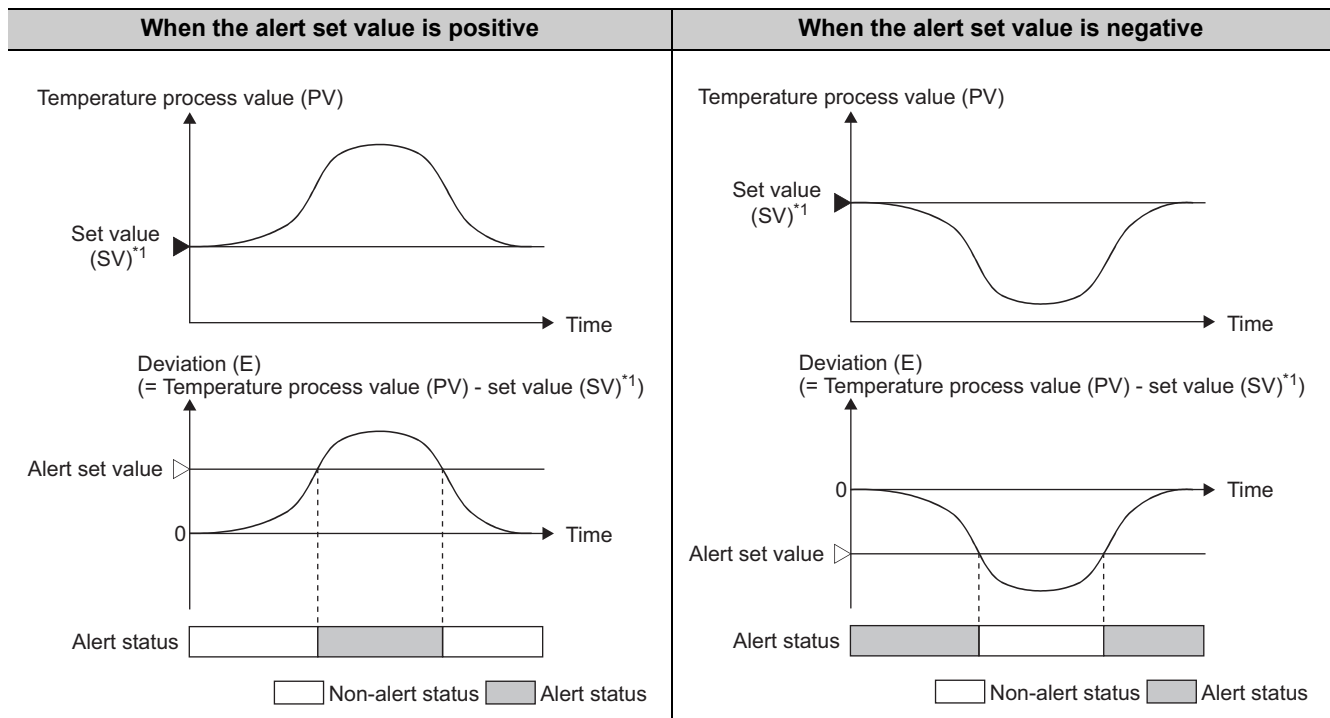


- When the setting change rate limiter is specified: The value in CH□ Set value (SV) monitor (Un\G25 to Un\G28) follows the set value (SV) of after the setting is reflected.



(b) Upper limit deviation alert

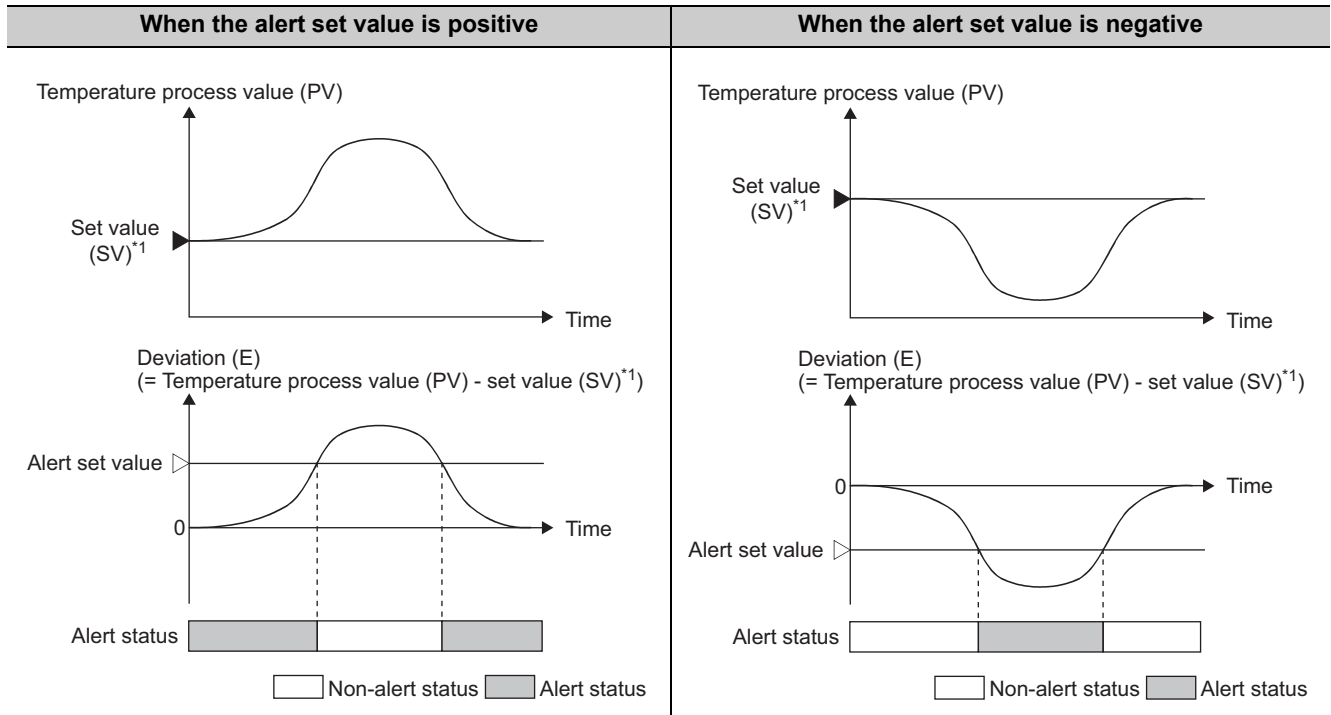
When the deviation (E) is equal to or greater than the alert set value, the system is put in an alert status.



*1 Depending on the alert mode, this value becomes "set value (SV) monitor" or "set value (SV) setting". (Page 162, Section 8.2.11 (2) (a))

(c) Lower limit deviation alert

When the deviation (E) is equal to or less than the alert set value, the system is put in an alert status.

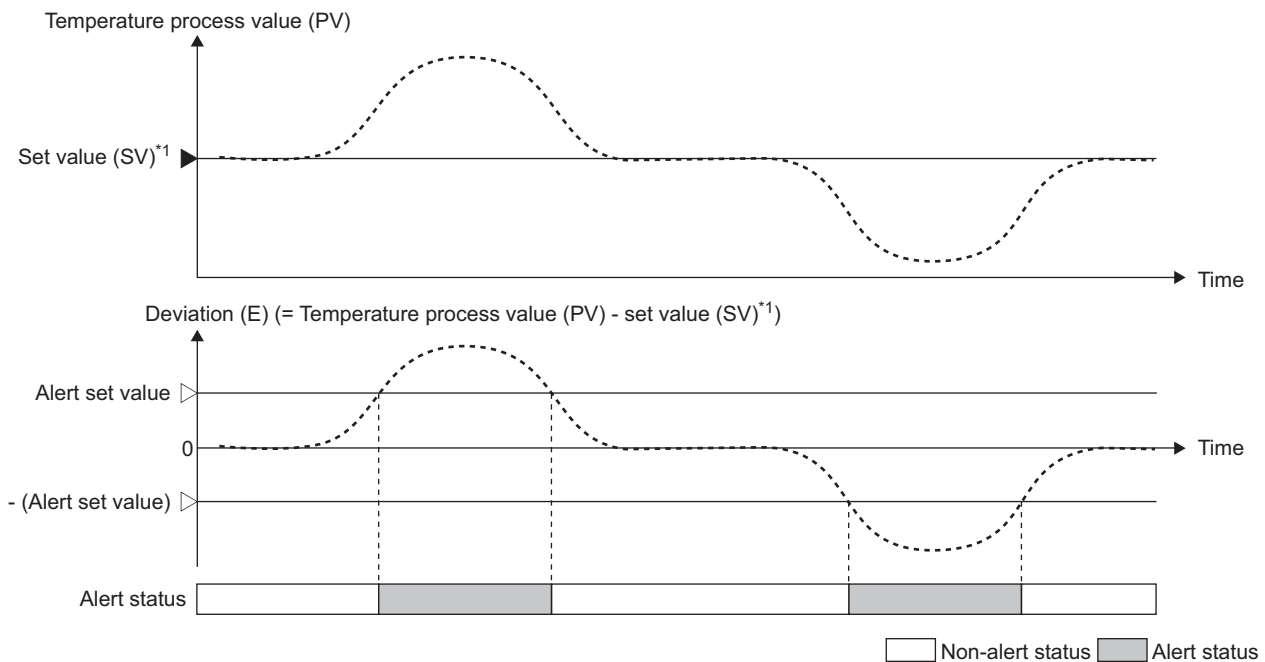


*1 Depending on the alert mode, this value becomes "set value (SV) monitor" or "set value (SV) setting". (☞ Page 162, Section 8.2.11 (2) (a))

(d) Upper lower limit deviation alert

When one of the following conditions is satisfied, the system is put in an alert status.

- Deviation (E) $\geq$ Alert set value
- Deviation (E) $\leq$ -(Alert set value)

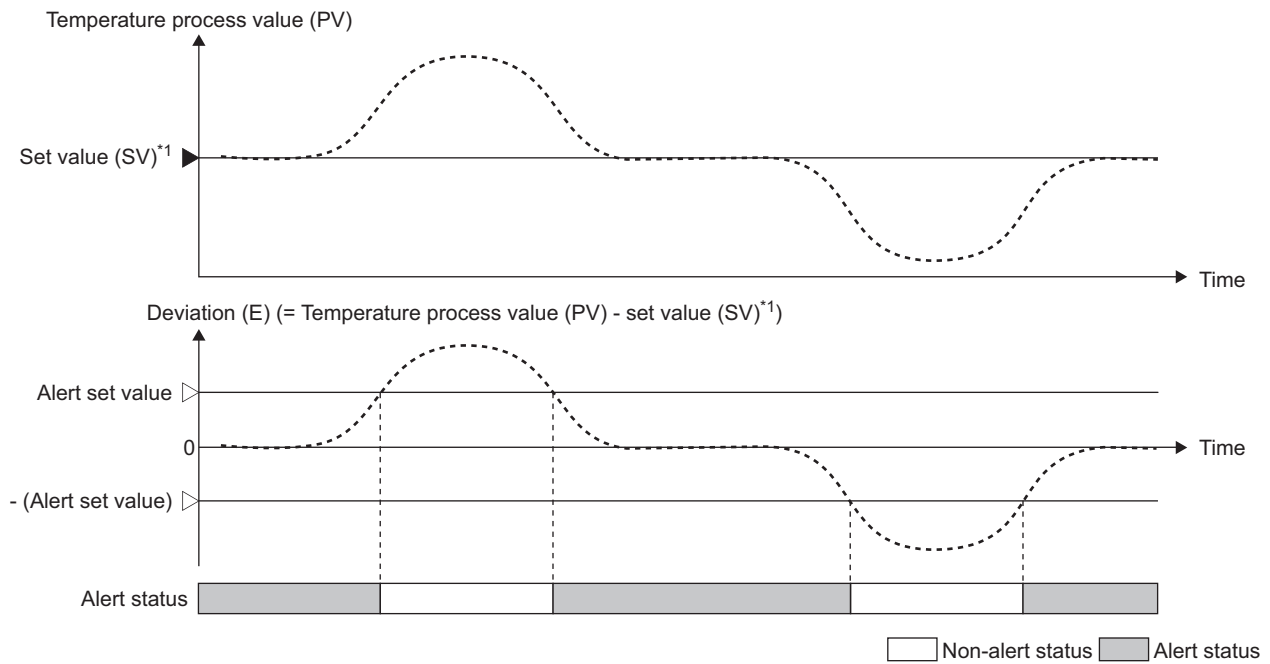


*1 Depending on the alert mode, this value becomes "set value (SV) monitor" or "set value (SV) setting". (☞ Page 162, Section 8.2.11 (2) (a))

(e) Within-range alert

When the following condition is satisfied, the system is put in an alert status.

- $-(\text{Alert set value}) \leq \text{Deviation (E)} \leq \text{Alert set value}$



*1 Depending on the alert mode, this value becomes "set value (SV) monitor" or "set value (SV) setting". (☞ Page 162, Section 8.2.11 (2) (a))

(f) Setting method (alert mode and the set value (SV) to be referred)

Select one of the two types of set value (SV) described in  Page 162, Section 8.2.11 (2) by specifying an alert mode.

- When the alert judgment requires the value in CH□ Set value (SV) monitor (Un\G25 to Un\G28), set one of the following values.

Alert mode setting ( Page 171, Section 8.2.11 (7) (a))	
Setting value	Alert mode name
3	Upper Limit Deviation Alert
4	Lower Limit Deviation Alert
5	Upper/Lower Limit Deviation Alert
6	Within-Range Alert
9	Upper Limit Deviation Alert with Wait
10	Lower Limit Deviation Alert with Wait
11	Upper/Lower Limit Deviation Alert with Wait
12	Upper Limit Deviation Alert with Re-Wait
13	Lower Limit Deviation Alert with Re-Wait
14	Upper/Lower Limit Deviation Alert with Re-Wait

- When the alert judgment requires the value in CH□ Set value (SV) setting (Un\G34, Un\G66, Un\G98, Un\G130), set one of the following values.

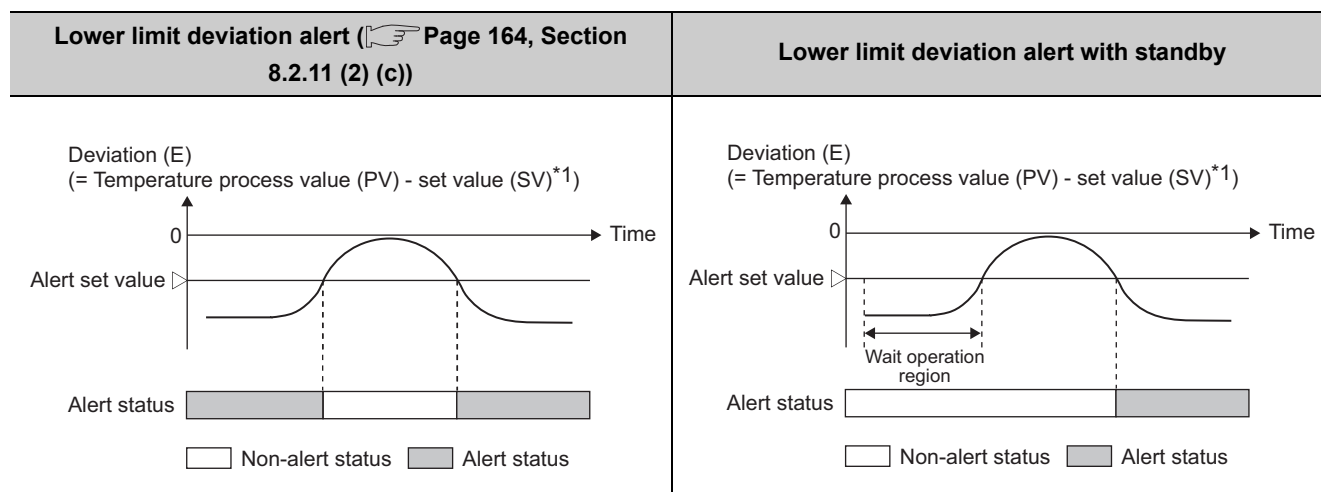
Alert mode setting ( Page 171, Section 8.2.11 (7) (a))	
Setting value	Alert mode name
15	Upper Limit Deviation Alert (Use Set Value (SV) Setting Value)
16	Lower Limit Deviation Alert (Use Set Value (SV) Setting Value)
17	Upper/Lower Limit Deviation Alert (Use Set Value (SV) Setting Value)
18	Within-Range Alert (Use Set Value (SV) Setting Value)
19	Upper Limit Deviation Alert with Wait (Use Set Value (SV) Setting Value)
20	Lower Limit Deviation Alert with Wait (Use Set Value (SV) Setting Value)
21	Upper/Lower Limit Deviation Alert with Wait (Use Set Value (SV) Setting Value)
22	Upper Limit Deviation Alert with Re-Wait (Use Set Value (SV) Setting Value)
23	Lower Limit Deviation Alert with Re-Wait (Use Set Value (SV) Setting Value)
24	Upper/Lower Limit Deviation Alert with Re-Wait (Use Set Value (SV) Setting Value)

(3) Alert with standby

Even if the temperature process value (PV) or deviation (E) is in a condition to be in an alert status when the module's status is changed from the setting mode to the operation mode (Setting/operation mode instruction (Yn1): OFF→ON), the alert does not occur. The alert function can be disabled until the temperature process value (PV) or deviation (E) strays out of the condition to be in an alert status.

Ex. When the alert mode is set to "10: Lower Limit Deviation Alert with Wait"

The alert function is inactive until the deviation (E) exceeds the alert set value (right figure below).



*1 Depending on the alert mode, this value becomes "set value (SV) monitor" or "set value (SV) setting". (☞ Page 162, Section 8.2.11 (2) (a))

Point

When the system goes into the non-alert status even once after an alert judgment started following the setting of the alert mode, the alert with standby will be inactive even if the mode is changed to the one with standby.

(a) Setting method

Select one of the following alert modes.

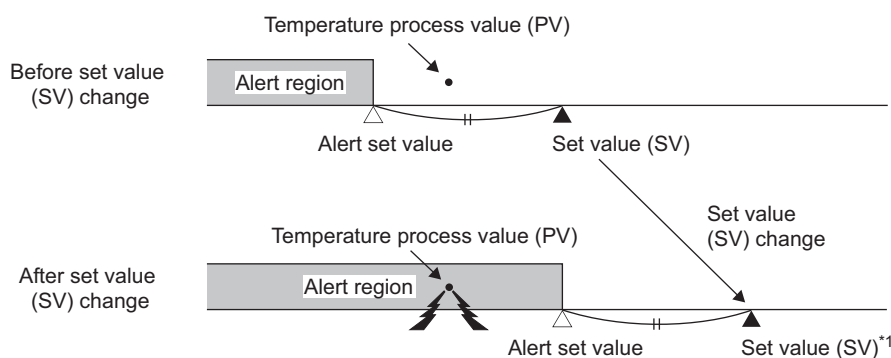
Alert mode setting (☞ Page 171, Section 8.2.11 (7) (a))	
Setting value	Alert mode name
7	Upper Limit Input Alert with Wait
8	Lower Limit Input Alert with Wait
9	Upper Limit Deviation Alert with Wait
10	Lower Limit Deviation Alert with Wait
11	Upper/Lower Limit Deviation Alert with Wait
19	Upper Limit Deviation Alert with Wait (Use Set Value (SV) Setting Value)
20	Lower Limit Deviation Alert with Wait (Use Set Value (SV) Setting Value)
21	Upper/Lower Limit Deviation Alert with Wait (Use Set Value (SV) Setting Value)

(4) Alert with standby (second time)

A function to deactivate the alert function once again when the set value (SV) is changed is added to an alert with standby. This is called an alert with standby (second time).

When control needs the set value (SV) change, the alert supposed to occur can be avoided when the set value is changed by selecting an alert with standby (second time).

Ex. When the temperature process value (PV) is on the position as below before the set value (SV) change



*1 Depending on the alert mode, this value becomes "set value (SV) monitor" or "set value (SV) setting". (Page 162, Section 8.2.11 (2) (a))

For a deviation alert, when the set value (SV) is changed, the temperature process value (PV) goes into the alert area; therefore, the system goes into an alert status.

To prevent the case above, the alert output is put on standby.

(a) Setting method

Select one of the following alert modes.

Alert mode setting (Page 171, Section 8.2.11 (7) (a))	
Setting value	Alert mode name
12	Upper Limit Deviation Alert with Re-Wait
13	Lower Limit Deviation Alert with Re-Wait
14	Upper/Lower Limit Deviation Alert with Re-Wait
22	Upper Limit Deviation Alert with Re-Wait (Use Set Value (SV) Setting Value)
23	Lower Limit Deviation Alert with Re-Wait (Use Set Value (SV) Setting Value)
24	Upper/Lower Limit Deviation Alert with Re-Wait (Use Set Value (SV) Setting Value)

Remark

If a setting change rate limiter is specified, an alert with standby (second time) is not active even though one of the following alert modes is selected.

Alert mode setting (☞ Page 171, Section 8.2.11 (7) (a))	
Setting value	Alert mode name
12	Upper Limit Deviation Alert with Re-Wait
13	Lower Limit Deviation Alert with Re-Wait
14	Upper/Lower Limit Deviation Alert with Re-Wait

The standby (second time) is used to prevent alert occurrence when the set value (SV) is changed.

If a setting change rate limiter is specified, the value in CH□ Set value (SV) monitor (Un\G25 to Un\G28) gradually changes following the set value (SV) when the set value (SV) is changed. Suppose that the standby (second time) function is activated under such occasion. The alert standby would be always active; therefore an alert would not be output even when the temperature process value (PV) is not following the value in CH□ Set value (SV) monitor (Un\G25 to Un\G28). To prevent such cases, the standby (second time) function is deactivated if a setting change rate limiter is used.

(5) Condition for alert judgment

Whether alert occurrence is judged or not depends on the settings of the followings:

- Setting/operation mode instruction (Yn1) (Page 340, Appendix 1.2 (1))
- PID continuation flag (Un\G169) (Page 390, Appendix 2 (43))
- CH PID control forced stop instruction (YnC to YnF) (Page 343, Appendix 1.2 (7))
- CH Stop mode setting (Un\G33, Un\G65, Un\G97, Un\G129) (Page 362, Appendix 2 (13))

The following table shows the relationship between each setting above and the execution of alert judgment.

○: Judged ×: Not judged

Setting/operation mode instruction (Yn1)*1	PID continuation flag (Un\G169)	CH PID control forced stop instruction (YnC to YnF)	CH Stop mode setting (Un\G33, Un\G65, Un\G97, Un\G129)	Alert judgment
Power ON, Setting mode	Stop (0)/Continue (1)	OFF/ON	Stop (0)	×
			Monitor (1)	×
			Alert (2)	○
Operation mode (operating)	Stop (0)/Continue (1)	OFF	Stop (0)/Monitor (1)/Alert (2)	○
		ON	Stop (0)	×
			Monitor (1)	×
			Alert (2)	○
Setting mode (after operation)	Stop (0)	OFF/ON	Stop (0)	×
			Monitor (1)	×
			Alert (2)	○
	Continue (1)	OFF	Stop (0)/Monitor (1)/Alert (2)	○
		ON	Stop (0)	×
			Monitor (1)	×
			Alert (2)	○

*1 For details, refer to Page 334, Appendix 1.1 (2).

Even if the conditions above are satisfied, when CH Unused channel setting (Un\G61, Un\G93, Un\G125, Un\G157) is set to Unused (1), alert judgment is not executed. (Page 385, Appendix 2 (35))

(6) Condition where CH Alert occurrence flag (XnC to XnF) turns off

The condition where CH Alert occurrence flag turns off differs depending on the setting of the following buffer memory area.

- CH Stop mode setting (Un\G33, Un\G65, Un\G97, Un\G129) (Page 362, Appendix 2 (13))

CH Stop mode setting (Un\G33, Un\G65, Un\G97, Un\G129)	Condition where CH Alert occurrence flag (XnC to XnF) turns off
Stop (0)	When the cause of the alert is resolved, or when the system is shifted from the operation mode to the setting mode (when Setting/operation mode instruction (Yn1) is turned off from on).
Monitor (1)	
Alert (2)	When the cause of the alert is resolved,

(7) Setting alert modes and alert set values

Settings of the alert mode and alert set value are described below.

(a) Alert mode

Set the alert mode. Up to four modes can be set for each channel. Set modes in "Alert 1 mode setting" to "Alert 4 mode setting".

 Project window ⇨ [Intelligent Function Module] ⇨ Module name ⇨ [Parameter]

Item	CH1	CH2
Alert function setting	Set the temperature process value (PV) or warning status of deflection.	
Alert 1 mode setting	1:Upper Limit Input Alert	0:Not Warning
Alert 2 mode setting	0:Not Warning	0:Not Warning
Alert 3 mode setting	2:Lower Limit Input Alert	0:Not Warning
Alert 4 mode setting	0:Not Warning	0:Not Warning
Alert set value 1	7:Upper Limit Input Alert with Wait 8:Lower Limit Input Alert with Wait 9:Upper Limit Deviation Alert with Wait 10:Lower Limit Deviation Alert with Wait 11:Upper/Lower Limit Deviation Alert with Wait 12:Upper Limit Deviation Alert with Re-Wait 13:Lower Limit Deviation Alert with Re-Wait 14:Upper/Lower Limit Deviation Alert with Re-Wait 15:Upper Limit Deviation Alert (Use Set Value (SV) Setting Value) 16:Lower Limit Deviation Alert (Use Set Value (SV) Setting Value) 17:Upper/Lower Limit Deviation Alert (Use Set Value (SV) Setting Value) 18:Within-Range Alert (Use Set Value (SV) Setting Value) 19:Upper Limit Deviation Alert with Wait (Use Set Value (SV) Setting Value) 20:Lower Limit Deviation Alert with Wait (Use Set Value (SV) Setting Value)	
Alert set value 2		
Alert set value 3		
Alert set value 4		
Alert dead band setting		
Number of alert delay		
Loop disconnection detection judgment time		
Loop disconnection detection dead band		
Process alarm alert output enable/disable setting		
Process alarm lower limit		

Each alert mode for alert 1 to 4 corresponds to alert set value 1 to 4.

(b) Alert set value

Set the value where CH□ Alert 1 (b8 of Un\G5 to Un\G8) to CH□ Alert 4 (b11 of Un\G5 to Un\G8) turns on according to the set alert mode. Up to four values can be set for each channel.

Set values in "Alert set value 1" to "Alert set value 4".

 Project window ⇨ [Intelligent Function Module] ⇨ Module name ⇨ [Parameter]

Item	CH1	
Alert set value 1	200 C	0
Alert set value 2	0 C	0
Alert set value 3	200 C	0
Alert set value 4	30 C	0
Alert dead band setting	0.5 %	

Alert set value 1 to 4 corresponds to each alert mode for alert 1 to 4.

(8) Setting the alert dead band

When the temperature process value (PV) or deviation (E) is close to the alert set value, alert status and non-alert status may alternates repeatedly due to inconsistent input.
Such case can be prevented by setting an alert dead band.

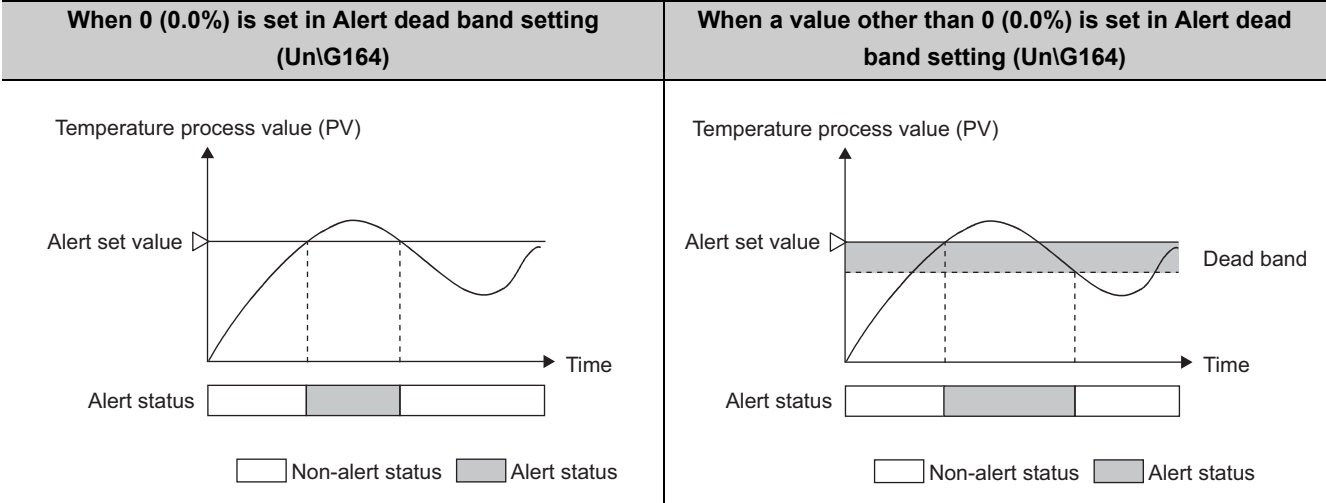
(a) Setting method

Set a value on "Alert dead band setting".

 Project window ⇒ [Intelligent Function Module] ⇒ Module name ⇒ [Parameter]

Item	CH1
Alert dead band setting	0.5 %
Number of alert delay	0 Times

Ex. When the alert mode is set to "1: Upper Limit Input Alert" ( Page 161, Section 8.2.11 (1))
When a value other than 0 (0.0%) is set in Alert dead band setting (Un\G164), the system is put in the alert status when upper limit input becomes equal to or greater than the alert set value. The system is put in the non-alert status when the upper limit falls below the alert dead band (figure on the right).



(9) Setting the number of alert delay

Set the number of sampling to judge alert occurrence. The system is set in the alert status when the temperature process value (PV) that has reached the alert set value remains in the alert range until the number of sampling becomes equal to or greater than the preset number of alert delays.

(a) Setting method

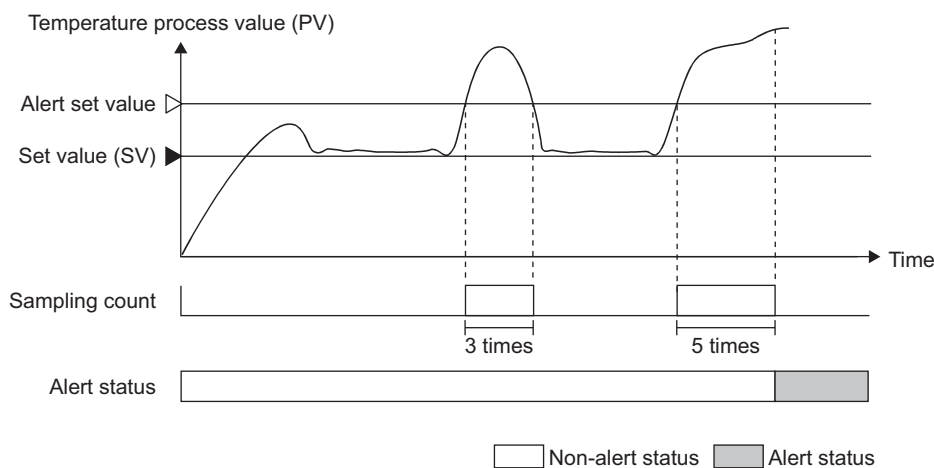
Set a value on "Number of alert delay".

 Project window ⇒ [Intelligent Function Module] ⇒ Module name ⇒ [Parameter]

Item	CH1
Number of alert delay	5 Times
Loop disconnection detection	

Ex. When the alert mode is set to "1: Upper Limit Input Alert" ( Page 161, Section 8.2.11 (1))

When 5 is set as the number of alert delay, the system is not put in the alert status if the number of sampling is 4 or less.



(10) Alert mode and settings

The following table shows the alert modes and validity/availability of related settings.

(Active/Yes: ○, Inactive/No: —)

Alert		Alert dead band setting ( Page 172, Section 8.2.11 (8))	Number of alert delay ( Page 173, Section 8.2.11 (9))	Alert with standby ( Page 167, Section 8.2.11 (3))	Alert with standby (second time) ( Page 168, Section 8.2.11 (4))
Input alert	Upper limit input alert ( Page 161, Section 8.2.11 (1))	○	○	○	—
	Lower limit input alert ( Page 161, Section 8.2.11 (1))	○	○	○	—
Deviation alert	Upper limit deviation alert ( Page 163, Section 8.2.11 (2) (b))	○	○	○	○
	Upper limit deviation alert (using the set value (SV)) ( Page 163, Section 8.2.11 (2) (b))	○	○	○	○
	Lower limit deviation alert ( Page 164, Section 8.2.11 (2) (c))	○	○	○	○
	Lower limit deviation alert (using the set value (SV)) ( Page 164, Section 8.2.11 (2) (c))	○	○	○	○
	Upper lower limit deviation alert ( Page 164, Section 8.2.11 (2) (d))	○	○	○	○
	Upper lower limit deviation alert (using the set value (SV)) ( Page 164, Section 8.2.11 (2) (d))	○	○	○	○
	Within-range alert ( Page 165, Section 8.2.11 (2) (e))	○	○	—	—
	Within-range alert (using the set value (SV)) ( Page 165, Section 8.2.11 (2) (e))	○	○	—	—

8.2.12 RFB Limiter Function

Standard Heating-cooling

The RFB (reset feed back) function operates when deviation (E) continues for a long period of time. In such occasion, this function limits the PID operation result (manipulated value (MV)) from an integral action so that it does not exceed the valid range of the manipulated value (MV).

This function operates automatically on execution of PID control; therefore, a setting by the user is unnecessary.

Remark

When the PID operation result exceeds the upper limit output limiter value, the L60TC4 operates as follows:

- The RFB function levels the manipulated value (MV) to the upper limit output limiter value by feeding back the exceeded value to the integral value.

When the PID operation result is below the lower limit output limiter value, the L60TC4 operates as follows:

- The RFB function levels the manipulated value (MV) to the lower limit output limiter value by feeding back the lacking value to the integral value.

8.2.13 Input/output (with another analog module) function

Standard Heating-cooling

Input and output can be processed using other analog modules (such as an A/D converter module or D/A converter module) in the system.

(1) Input

In general, a temperature control module uses the temperature measured through thermocouples or platinum resistance thermometers connected to the module as a temperature process value (PV).

In the L60TC4, the digital input value of current or voltage converted by other analog modules (such as an A/D converter module) in the system can also be used as a temperature process value (PV).

(a) Setting method

Follow the procedure below.

1. Select "Input range" from one of "201:Input with Another Analog Module Measured Temperature Range (0 to 4000)" to "205:Input with Another Analog Module Measured Temperature Range (0 to 32000)".

 Project window ⇨ [Intelligent Function Module] ⇨ Module name ⇨ [Parameter]

Item	CH1	CH2
Basic setting	Set the temperature conversion system.	
Input range	2:ThermocoupleK Measured Temperature Range(0 to 1300 C)	2:ThermocoupleK Measured Temperature Range(0 to 1300 C)
Set value (SV) setting	201:Input with Another Analog Module Measured Temperature Range (0 to 4000)	
Unused channel setting	202:Input with Another Analog Module Measured Temperature Range (0 to 12000)	
Conversion enable/disable setting	203:Input with Another Analog Module Measured Temperature Range (0 to 16000)	
Control basic parameter setting	204:Input with Another Analog Module Measured Temperature Range (0 to 4000)	
	205:Input with Another Analog Module Measured Temperature Range (0 to 32000)	

2. Store the value of another analog module (such as an A/D converter module) into CH□ Temperature process value (PV) for input with another analog module (Un\G689 to Un\G692).
( Page 412, Appendix 2 (75))

Point

- If the second procedure above is executed ahead of the first procedure, a write data error (error code: □□□4_H) occurs.
 - When this function is used, the value in the following buffer memory area is used for the temperature process value (PV) scaling function.
 - CH□ Temperature process value (PV) for input with another analog module (Un\G689 to Un\G692)
- For details on the temperature process value (PV) scaling function, refer to the following.

 Page 228, Section 8.3.2

(2) Output

Instead of the transistor output from the temperature control module, analog output values from other analog modules (such as a D/A converter module) can be used as the manipulated value (MV).

(a) Setting method

Follow the procedure below (for the standard control).

1. Select the value on "Resolution of the manipulated value for output with another analog module".

 Project window ⇨ [Intelligent Function Module] ⇨ Module name ⇨ [Parameter]

Resolution of the manipulated value for output with another analog module	0:0 to 4000
Choose any of the following four different	0:0 to 4000 1:0 to 12000 2:0 to 16000 3:0 to 20000

2. Store the value in CH□ Manipulated value (MV) for output with another analog module (Un\G177 to Un\G180) into the buffer memory in other analog module (such as a D/A converter module).

( Page 392, Appendix 2 (47))

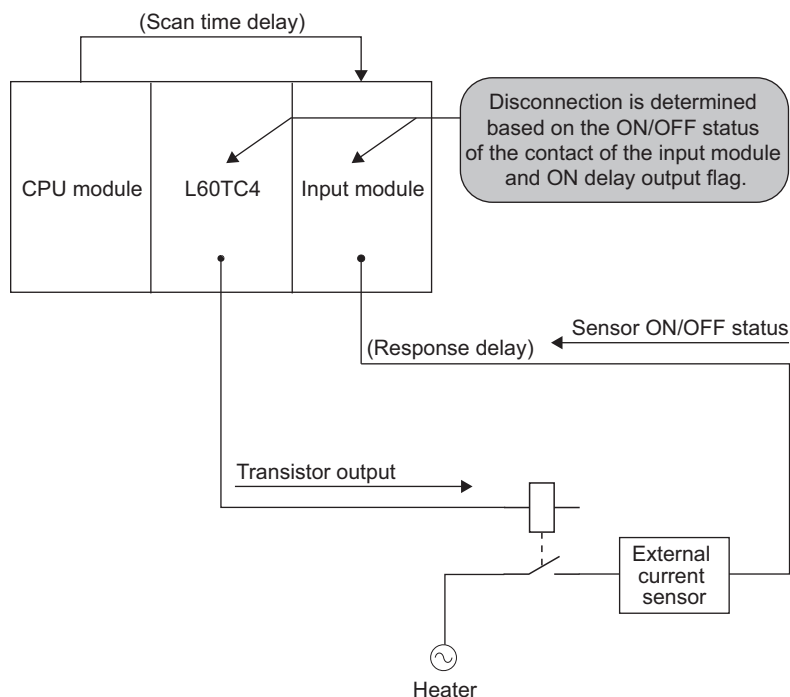
Point

- When the manipulated value (MV) is -5.0% to 0.0%, 0 is stored in Manipulated value (MV) for output with another analog module. When the manipulated value (MV) is 100.0% to 105.0%, 4000/12000/16000/20000 is stored in Manipulated value (MV) for output with another analog module.
- The manipulated value (MV) in a percentage value is stored into Manipulated value (MV) for output with another analog module (digital output value) in real time.

8.2.14 ON delay output function

Standard Heating-cooling

This function allows the user to set the delay (response/scan time delay) of transistor output. By setting a delay, and monitoring the ON delay output flag and external output on the program, disconnection of external output can be determined. The following figure is an example using the ON delay flag.



(1) Setting method

Set a value on "Transistor output monitor ON delay time setting".

Project window ⇒ [Intelligent Function Module] ⇒ Module name ⇒ [Parameter]

Transistor output monitor ON delay time setting	10
Resolution of the manipulated value for output with sensor	0.0 to 4000

8.2.15 Self-tuning function

Standard

The L60TC4 constantly monitors the control state. When the control system is oscillatory, this function allows PID constants to be automatically changed under the following situations such as:

- After the control has been just started
- When the set value (SV) is changed
- When the characteristics of a controlled object fluctuates

Unlike the auto tuning function, a normal control response waveform is monitored and PID constants are automatically calculated and set. This allows an object to be controlled with the most suitable PID constants all the time without disturbance.

(1) Differences between auto tuning and self-tuning

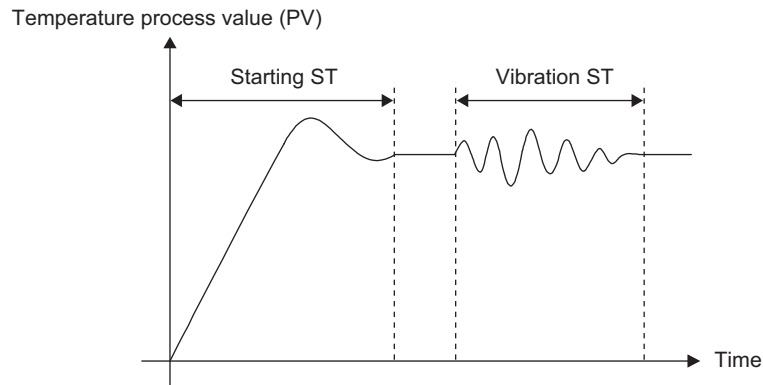
The following table lists the differences between auto tuning and self-tuning.

Item	Auto tuning	Self-tuning
PID constants calculation	The manipulated value (MV) is turned on/off and PID constants are calculated based on the hunting cycle and amplitude of the temperature process value (PV) for the set value (SV).	PID constants are calculated based on an oscillation occurred under situations such as after the control has been just started, the set value (SV) has been changed, and when a control response is oscillatory.
Execution method	Turning off and on CH□ Auto tuning instruction (Yn4 to Yn7) starts auto tuning and changes PID constants upon completion.	The L60TC4 constantly monitors the control response. PID constants are calculated and changed when the control response is slow.
Control response	PID constants are calculated based on the control response of when the manipulated value (MV) is turned on/off; therefore, the control may become unstable.	PID constants are calculated based on the control response during temperature control; therefore, the control is stable.
Calculation result	The optimum PID constants are calculated by one tuning. In the standard control, CH□ Loop disconnection detection judgment time (Un\G59, Un\G91, Un\G123, Un\G155) is also calculated.	The optimum PID constants may not be obtained by one tuning. CH□ Loop disconnection detection judgment time (Un\G59, Un\G91, Un\G123, Un\G155) is not calculated.
PID constants setting when the characteristics of a controlled object fluctuate	Users perform auto tuning again to change PID constants.	The L60TC4 automatically changes PID constants.
Available control mode	The standard control and heating-cooling control	The standard control only

(2) Starting ST and vibration ST

Two types of self-tuning (ST) are available depending on the state of the control system: starting ST and vibration ST.

- Starting ST: Self-tuning is performed immediately after the control is started or when the set value (SV) is changed.
- Vibration ST: Self-tuning is performed when the control system in a stable state has become oscillatory due to reasons such as disturbance.



(a) How to set starting ST

Select one of the following setting values in "Self-tuning setting" (Un\G574, Un\G606, Un\G638, Un\G670).
(The default is Do not run the ST (0).)

- 1: Starting ST (PID Constant Only)
- 2: Starting ST (Simultaneous Temperature Rise Parameter Only)
- 3: Starting ST (PID Constant and Simultaneous Temperature Rise Parameter)
- 4: Starting ST plus Vibration (PID Constant Only)

Project window ⇒ [Intelligent Function Module] ⇒ Module name ⇒ [Parameter]

Item	CH1	CH2	CH3
Self-tuning setting	0:Do Not Run the ST	0:Do Not Run the ST	0:Do Not Run the ST
Temperature conversion setting	0:Do Not Run the ST		
Cooling method setting	1:Starting ST (PID Constant Only)		
Cooling upper limit output limiter	2:Starting ST (Simultaneous Temperature Rise Parameter Only)		
Cooling control output cycle setting	3:Starting ST (PID Constant and Simultaneous Temperature Rise Parameter)		
	4:Starting ST plus Vibration (PID Constant Only)		

(b) How to set vibration ST

Set the following for "Self-tuning setting".

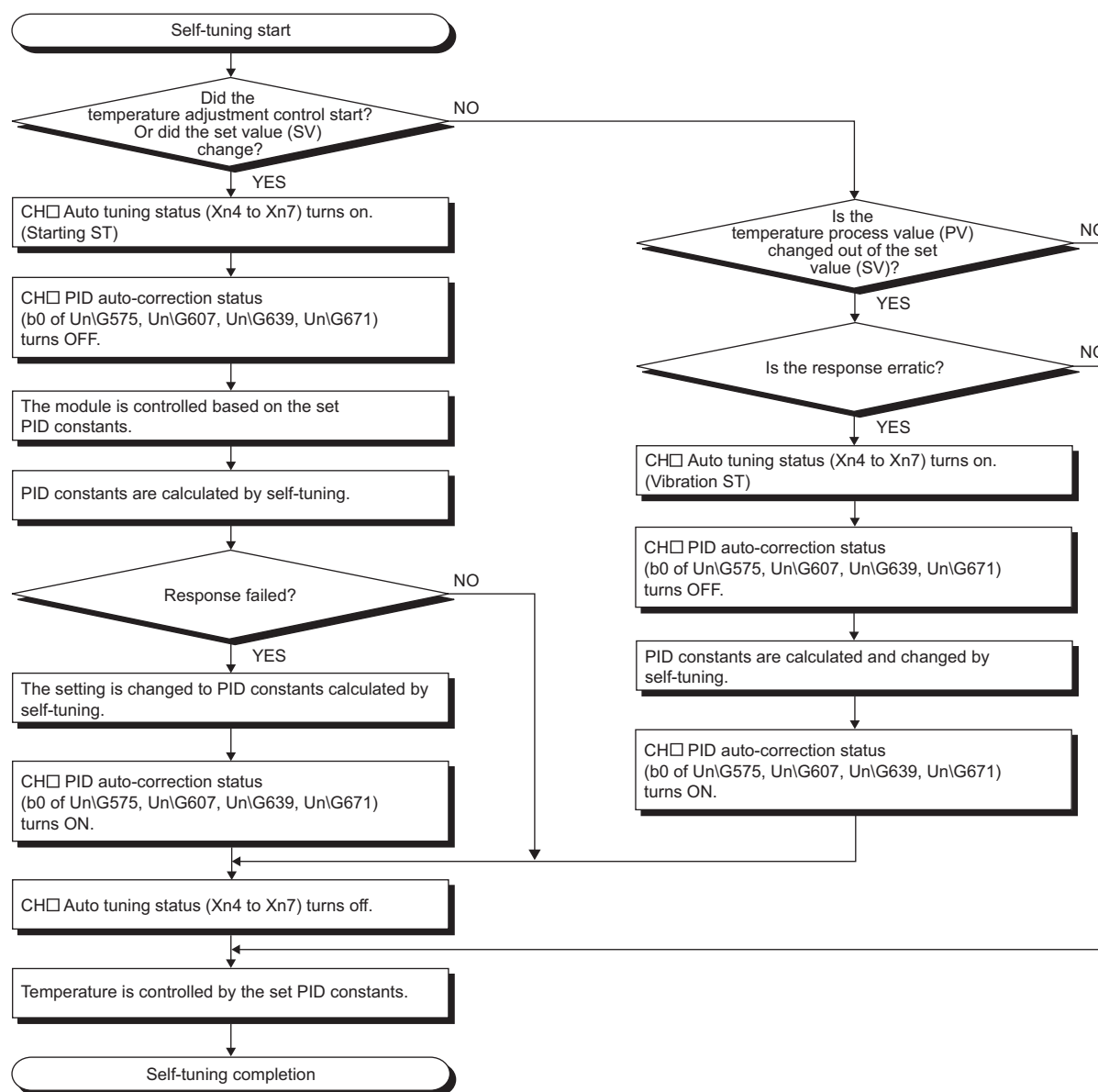
- 4: Starting ST plus Vibration (PID Constant Only)

Project window ⇒ [Intelligent Function Module] ⇒ Module name ⇒ [Parameter]

Item	CH1	CH2	CH3
Self-tuning setting	0:Do Not Run the ST	0:Do Not Run the ST	0:Do Not Run the ST
Temperature conversion setting	0:Do Not Run the ST		
Cooling method setting	1:Starting ST (PID Constant Only)		
Cooling upper limit output limiter	2:Starting ST (Simultaneous Temperature Rise Parameter Only)		
Cooling control output cycle setting	3:Starting ST (PID Constant and Simultaneous Temperature Rise Parameter)		
	4:Starting ST plus Vibration (PID Constant Only)		

(3) Procedure for the self-tuning control

The following is the flow chart for the control.

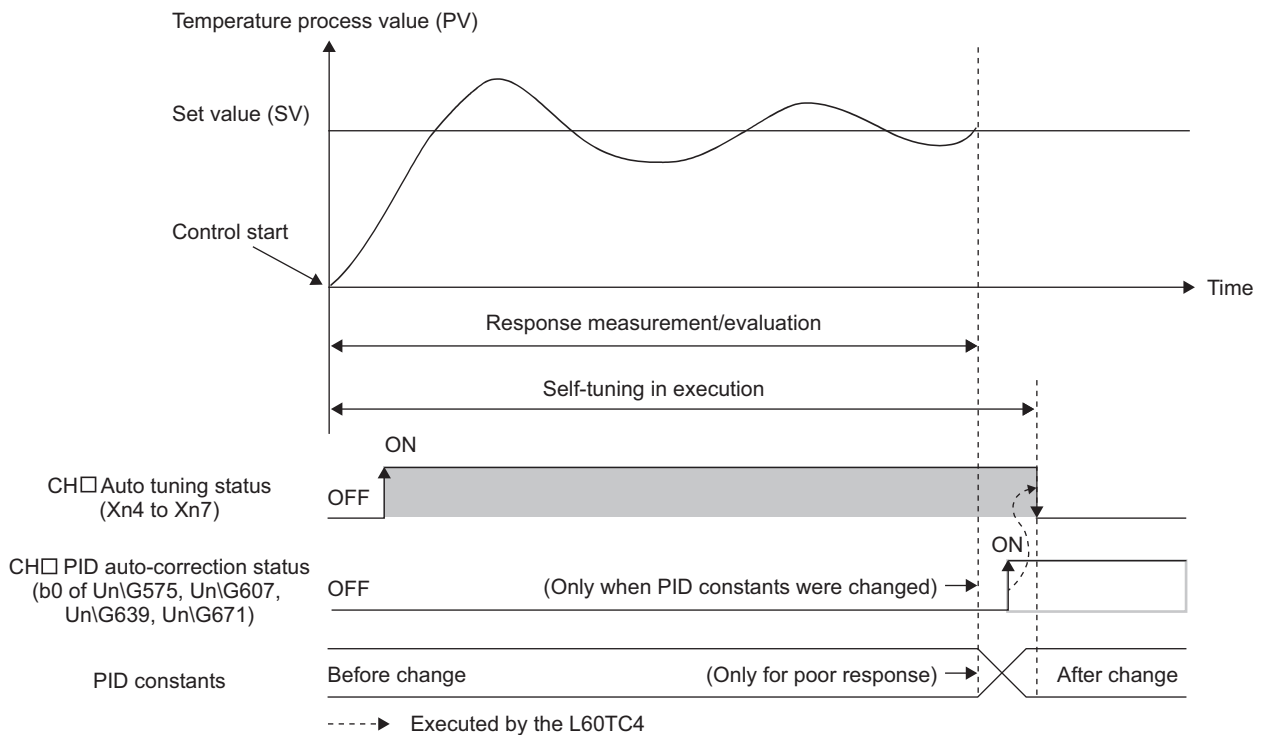


(4) Operation with starting ST

This section explains the operation of when the temperature control is started or the set value (SV) is changed (starting ST).

With starting ST, the module monitors the response waveform of the temperature process value (PV) of when the temperature control is started or when the set value (SV) is changed. Then PID constants are automatically corrected. The following table lists the operations of the module with starting ST.

Operation with starting ST	
1	CH□ PID auto-correction status (b0 of Un\G575, Un\G607, Un\G639, Un\G671) is turned 0 (OFF). In addition, CH□ Auto tuning status (Xn4 to Xn7) is turned on.
2	Temperature is controlled using the PID constants set.
3	When a control response is poor, PID constants are calculated based on the response waveform and are set in the buffer memory. In addition, CH□ PID auto-correction status (b0 of Un\G575, Un\G607, Un\G639, Un\G671) is turned 1 (ON). When a control response is good, CH□ PID auto-correction status (b0 of Un\G575, Un\G607, Un\G639, Un\G671) remains 0 (OFF) and PID constants are not changed.
4	CH□ Auto tuning status (Xn4 to Xn7) is turned off.



(a) Conditions for starting ST

Starting ST is executed under the following conditions:

- When the setting mode is shifted to the operation mode (Setting/operation mode instruction (Yn1) is turned off and on) the first time after the power is turned off and on or after the CPU module is reset and the reset is cancelled
- When the setting mode is shifted to the operation mode the second time or later after the power is turned off and on or after the CPU module is reset and the reset is cancelled (only when the temperature process value (PV) has been stable for two minutes or longer before the mode is shifted)
- When the set value (SV) is changed (only when the temperature process value (PV) before the set value (SV) change has been stable for two minutes or longer)

Point

If the starting ST is started when the temperature process value (PV) is not stable, incorrect PID constants may be determined. Execute the starting ST after the temperature process value (PV) has been stable for two minutes or longer.

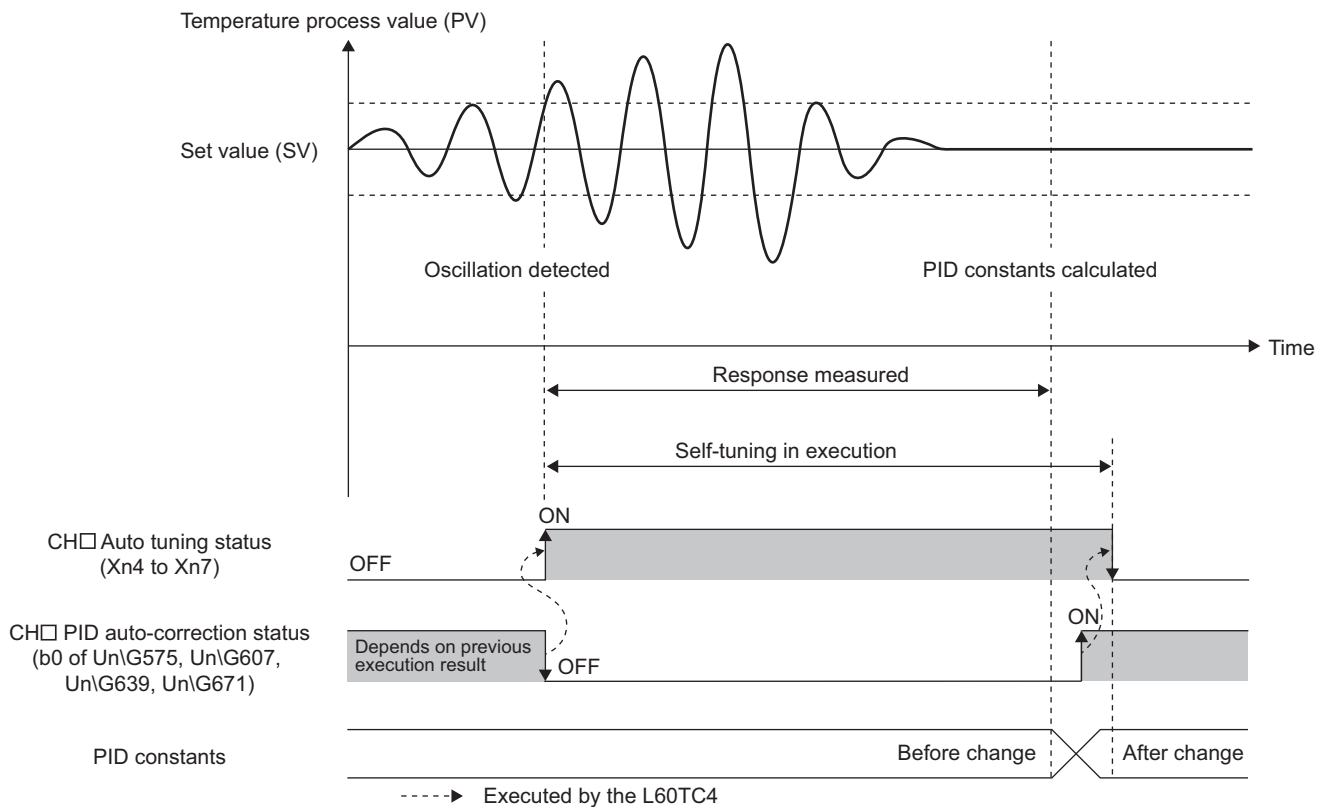
(5) Operation with vibration ST

This section explains the operation of when a control response is oscillatory (vibration ST).

With vibration ST, PID constants are automatically corrected to settle a vibration when a control response becomes oscillatory due to reasons such as the change in the characteristic of a controlled object and conditions for operation.

The following table lists the operations of the module with vibration ST. (The listed operations are those under the state where temperature is being controlled with the PID constants set.)

Operation with vibration ST	
1	CH□ PID auto-correction status (b0 of Un\G575, Un\G607, Un\G639, Un\G671) is turned 0 (OFF). In addition, CH□ Auto tuning status (Xn4 to Xn7) is turned on.
2	PID constants are calculated based on a response waveform.
3	PID constants are set in the buffer memory and CH□ PID auto-correction status (b0 of Un\G575, Un\G607, Un\G639, Un\G671) is turned 1 (ON).
4	CH□ Auto tuning status (Xn4 to Xn7) is turned off.



(a) Conditions for self-tuning

Vibration ST is executed when the temperature process value (PV) goes outside the range that is judged as stable.

(b) Precautions

If vibration ST is executed on the following objects, incorrect PID constants may be determined:

- Controlled objects where a disturbance periodically occurs
- Controlled objects with strong mutual interference

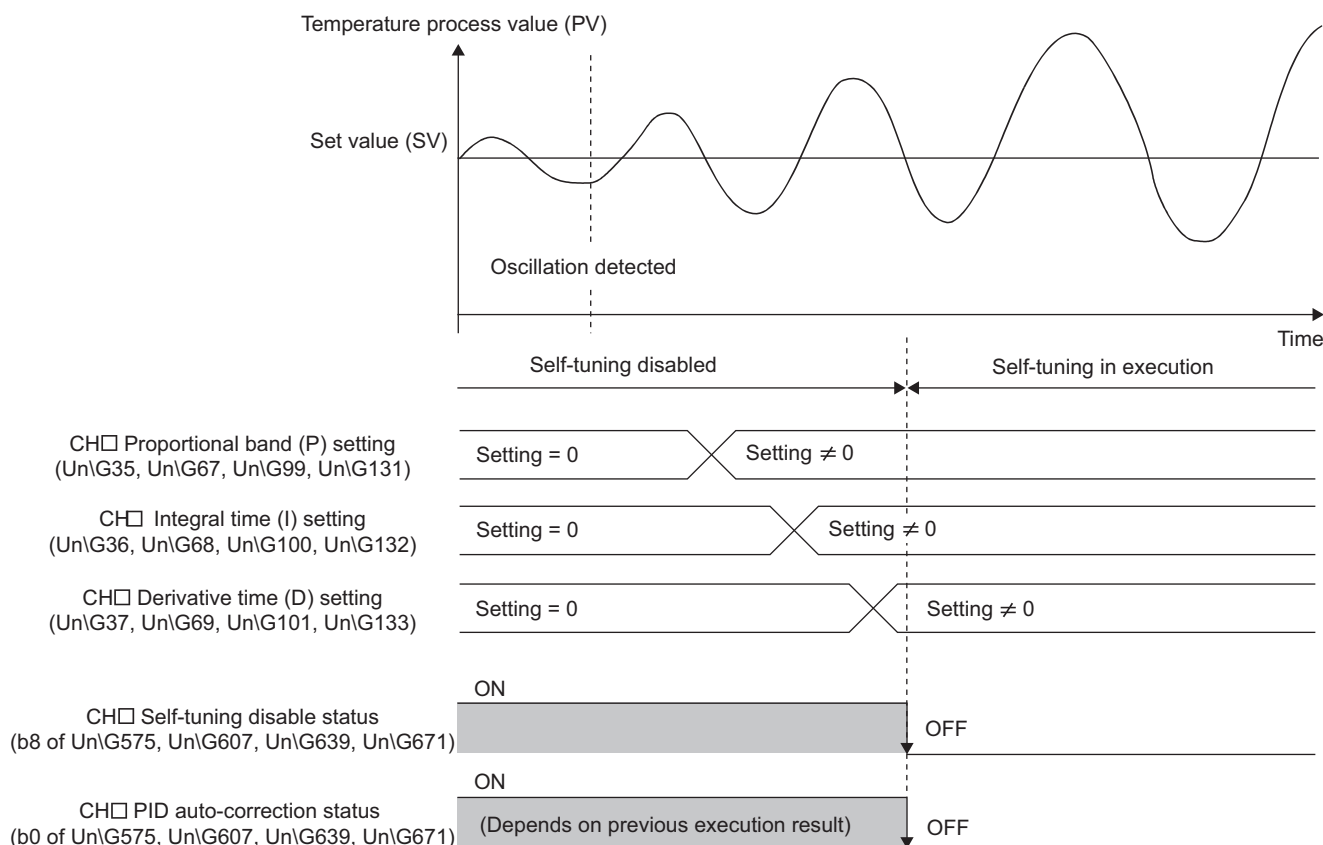
(6) Conditions where self-tuning is not executed

This section explains the conditions where self-tuning is not executed.

(a) The control method is not the PID control method

When the control method is one of the four methods other than the PID control (two-position control, P control, PI control, PD control), self-tuning is not executed. In addition, CH□ Self-tuning disable status (b8 of Un\G575, Un\G607, Un\G639, Un\G671) turns 1 (ON).

When all PID constants of target channels turn to a value other than 0, self-tuning is enabled.



(b) Auto tuning is being executed

Self-tuning is not executed during the auto tuning (no error occurs). At the time of when auto tuning is completed, self-tuning is enabled.

(c) The lower limit output limiter value is lower than the manipulated value (MV) and the manipulated value (MV) is lower than the upper limit output limiter value when the temperature control is started and the set value (SV) is changed

The starting ST does not start. However, self-tuning is enabled at the time of when a control response becomes oscillatory under the following setting.

- CH□ Self-tuning setting (Un\G574, Un\G606, Un\G638, Un\G670) is set to Starting ST plus vibration ST (4).

(d) The temperature process value (PV) is not within the temperature measurement range

Self-tuning is not executed. In addition, CH□ Self-tuning disable status (b8 of Un\G575, Un\G607, Un\G639, Un\G671) turns 1 (ON).

(e) The value set in CH□ Output variation limiter setting (Un\G44, Un\G76, Un\G108, Un\G140) is not 0 (☞ Page 371, Appendix 2 (20))

Self-tuning is not executed. In addition, CH□ Self-tuning disable status (b8 of Un\G575, Un\G607, Un\G639, Un\G671) turns 1 (ON).

(f) CH□ AUTO/MAN mode shift (Un\G50, Un\G82, Un\G114, Un\G146) is set to MAN (1) (☞ Page 376, Appendix 2 (26))

Self-tuning is not executed. In addition, CH□ Self-tuning disable status (b8 of Un\G575, Un\G607, Un\G639, Un\G671) turns 1 (ON).

(g) Values other than 0 (0.0%) have been set for the setting change rate limiter (☞ Page 378, Appendix 2 (28))

If the values other than 0 (0.0%) have been set to the following buffer memory areas, CH□ Self-tuning disable status (b8 of Un\G575, Un\G607, Un\G639, Un\G671) turns 1 (ON).

Buffer memory area name	Buffer memory address			
	CH1	CH2	CH3	CH4
CH□ Setting change rate limiter/Setting change rate limiter (temperature rise)	Un\G52	Un\G84	Un\G116	Un\G148
CH□ Setting change rate limiter (temperature drop)	Un\G564	Un\G596	Un\G628	Un\G660

(h) The heating-cooling control has been selected for the control mode (☞ Page 110, Section 7.2)

The self-tuning is not executed.

(7) Discontinuation of self-tuning

The following operation during self-tuning discontinues the self-tuning operation.

- The setting in CH□ Self-tuning setting (Un\G574, Un\G606, Un\G638, Un\G670) has been changed to Do Not run the ST (0).

The self-tuning operation in process is discontinued and self-tuning is not performed anymore after that. (An error does not occur.)

Whether self-tuning is being executed can be checked in CH□ Auto tuning status (Xn4 to Xn7). (☞ Page 336, Appendix 1.1 (5))

(8) Conditions where self-tuning does not complete due to errors

Under the following conditions, self-tuning does not complete due to errors. In addition, at this abnormal termination, CH□ Self-tuning error (b10 of Un\G575, Un\G607, Un\G639, Un\G671) turns 1 (ON).

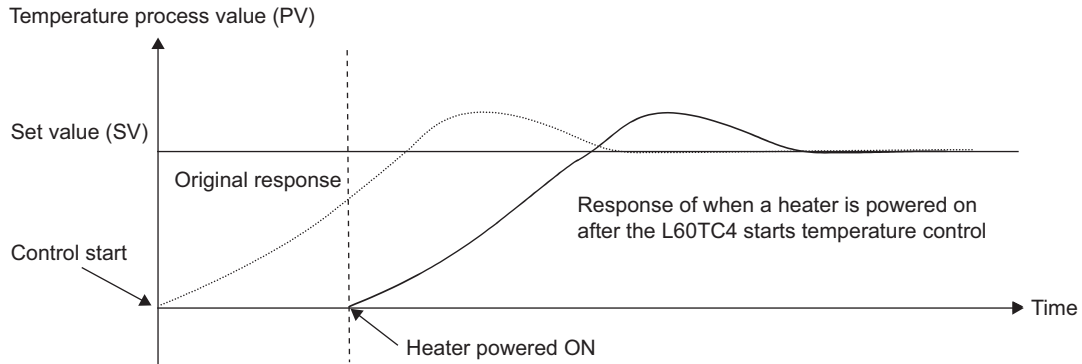
- When 6000 seconds (1 hour 40 minutes) or more have elapsed from the start of self-tuning
- When the change rate of the process value (PV) during self-tuning is less than 1.125°C/minute
- When CH□ Temperature process value (PV) (Un\G9 to Un\G12) is outside the temperature measurement range (☞ Page 346, Appendix 2 (3))
- When the manipulated value (MV) does not reach the upper limit output limiter value or lower limit output limiter value before the measurement is completed and necessary measurement data is not obtained
- When the temperature process value (PV) that is supposed to rise drops by 1°C (°F) or more after self-tuning is started with the starting ST
- When the temperature process value (PV) that is supposed to drop rises by 1°C (°F) or more after self-tuning is started with the starting ST
- When the setting for the buffer memory areas in the following table is changed during self-tuning

Buffer memory area name	Buffer memory address				Reference
	CH1	CH2	CH3	CH4	
CH□ Set value (SV) setting ^{*1}	Un\G34	Un\G66	Un\G98	Un\G130	Page 363, Appendix 2 (14)
CH□ Proportional band (P) setting	Un\G35	Un\G67	Un\G99	Un\G131	Page 364, Appendix 2 (15)
CH□ Integral time (I) setting	Un\G36	Un\G68	Un\G100	Un\G132	Page 366, Appendix 2 (16)
CH□ Derivative time (D) setting	Un\G37	Un\G69	Un\G101	Un\G133	Page 366, Appendix 2 (17)
CH□ Upper limit output limiter	Un\G42	Un\G74	Un\G106	Un\G138	Page 369, Appendix 2 (19)
CH□ Lower limit output limiter	Un\G43	Un\G75	Un\G107	Un\G139	
CH□ Output variation limiter setting	Un\G44	Un\G76	Un\G108	Un\G140	Page 371, Appendix 2 (20)
CH□ Sensor correction value setting	Un\G45	Un\G77	Un\G109	Un\G141	Page 372, Appendix 2 (21)
CH□ Control output cycle setting	Un\G47	Un\G79	Un\G111	Un\G143	Page 373, Appendix 2 (23)
CH□ Primary delay digital filter setting	Un\G48	Un\G80	Un\G112	Un\G144	Page 374, Appendix 2 (24)
CH□ AUTO/MAN mode shift	Un\G50	Un\G82	Un\G114	Un\G146	Page 376, Appendix 2 (26)
CH□ Setting change rate limiter/Setting change rate limiter (temperature rise)	Un\G52	Un\G84	Un\G116	Un\G148	Page 378, Appendix 2 (28)
CH□ Forward/reverse action setting	Un\G54	Un\G86	Un\G118	Un\G150	Page 380, Appendix 2 (30)
CH□ Unused channel setting	Un\G61	Un\G93	Un\G125	Un\G157	Page 385, Appendix 2 (35)
CH□ Setting change rate limiter (temperature drop)	Un\G564	Un\G596	Un\G628	Un\G660	Page 378, Appendix 2 (28)

*1 Only during starting

(9) Precautions

- Before starting the temperature control using the L60TC4, power on a controlled object such as a heater. If the temperature control is started with a heater powered off, PID constants are calculated based on a response that differs from the original characteristics using self-tuning.



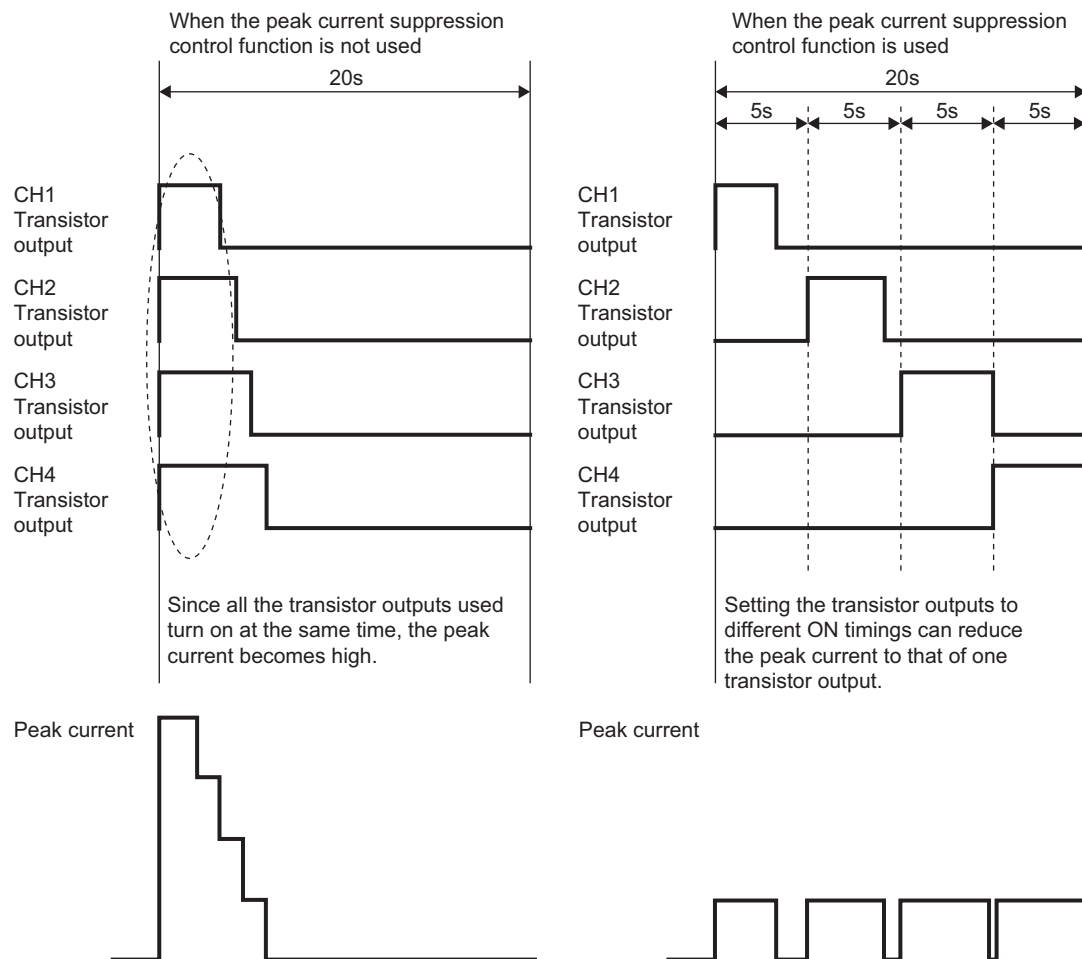
- Do not use the self-tuning function for controlled objects where a great disturbance (uncontrollable disturbance) occurs periodically. Doing so may cause improper PID constants to be determined by self-tuning. If the function is used for such objects, improper PID constants are set and the response for the set value (SV) change or disturbance becomes slow.

Ex. Temperature control for an injection mold, temperature control for a hot plate for a semiconductor manufacturing equipment

8.2.16 Peak current suppression function

Standard

The upper limit output limiter value for each channel is changed automatically and the peak current is suppressed by dividing timing for transistor outputs using this function. The timing can be divided into two to four intervals.



(1) The number of timing divided and upper limit output limiter

Set the number of timing to be divided (setting in Peak current suppression control group setting (Un\G784) in the setting mode (Setting/operation mode status (Xn1): off). The setting is enabled by turning off, on, and off Setting change instruction (YnB). At the time when the setting is enabled, the following buffer memory area is automatically set according to the number of timing divided.

- CH□ Upper limit output limiter (Un\G42, Un\G74, Un\G106, Un\G138) (☞ Page 369, Appendix 2 (19))

The following table lists the setting details.

The no. of timing divided	CH□ Upper limit output limiter (Un\G42, Un\G74, Un\G106, Un\G138)
2	500 (50.0%)
3	333 (33.3%)
4	250 (25.0%)

The following buffer memory area is set to 0.

- CH□ Lower limit output limiter (Un\G43, Un\G75, Un\G107, Un\G139) (☞ Page 369, Appendix 2 (19))

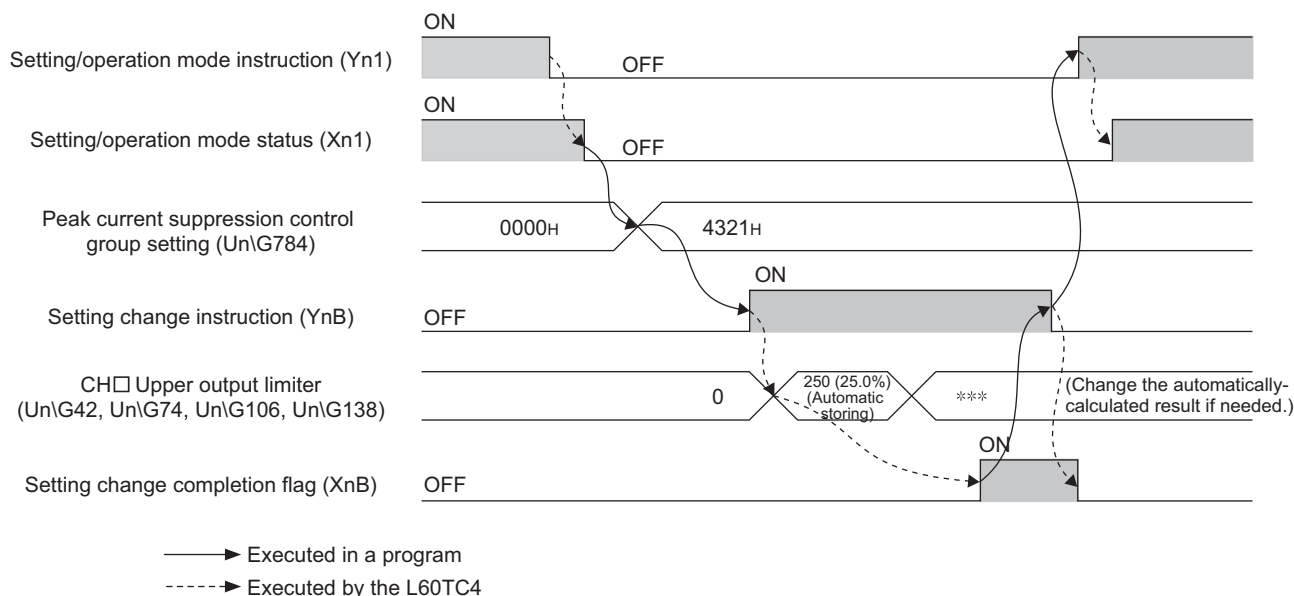
Point

When using this function, set the control output cycles for target channels to the same value. Even if the following buffer memory area setting is different by each channel, an error does not occur.

- CH□ Control output cycle setting (Un\G47, Un\G79, Un\G111, Un\G143) (☞ Page 373, Appendix 2 (23))

The module operates according to the value (%) of CH□ Upper limit output limiter (Un\G42, Un\G74, Un\G106, Un\G138) automatically set when this function is used.

Ex. Timing chart of when timing is divided into four timing



(2) Examples of dividing timing

(a) Four timing

The following table shows two examples.

Example	Channel	Group
Example 1	CH1	Group 1
	CH2	Group 2
	CH3	Group 3
	CH4	Group 4
Example 2	CH1	Group 1
	CH2	Group 2
	CH3	Not divided
	CH4	Group 4

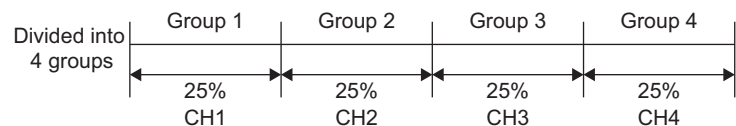
The following shows the relationship between groups and the values (%) of CH□ Upper limit output limiter (Un\G42, Un\G74, Un\G106, Un\G138).

Peak current suppression control group setting (Un\G784)

Example 1

4	3	2	1	H

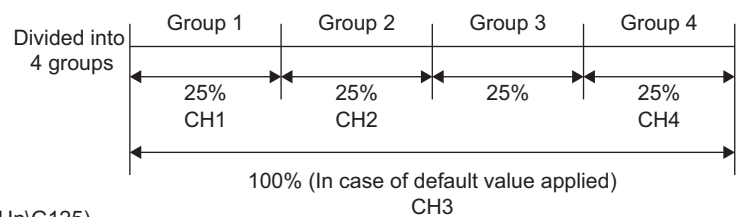
0100 0011 0010 0001
CH4 CH3 CH2 CH1



Example 2

4	0	2	1	H

0100 0000 0010 0001
CH4 CH3 CH2 CH1



Whether the transistor output is executed or not can be selected by CH3 Unused channel setting (Un\G125).

☞ Page 385, Appendix 2 (35)

In Example 2, the maximum number of groups is four; therefore, timing is divided into four timing. Because no channel is set for Group 3, no channel starts transistor output at the timing for Group 3.

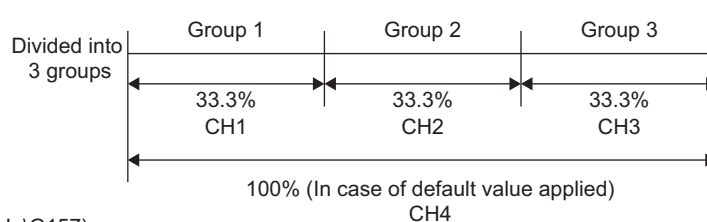
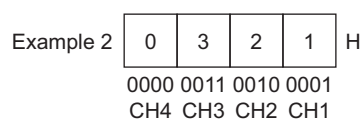
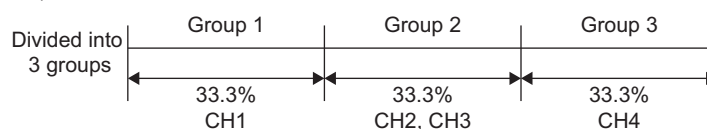
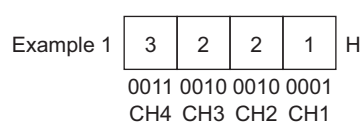
(b) Three timing

The following table shows two examples.

Example	Channel	Group
Example 1	CH1	Group 1
	CH2	Group 2
	CH3	Group 2
	CH4	Group 3
Example 2	CH1	Group 1
	CH2	Group 2
	CH3	Group 3
	CH4	Not divided

The following shows the relationship between groups and the values (%) of CH□ Upper limit output limiter (Un\G42, Un\G74, Un\G106, Un\G138).

Peak current suppression control group setting (Un\G784)



Whether the transistor output is executed or not can be selected by CH4 Unused channel setting (Un\G157).

☞ Page 385, Appendix 2 (35)

(c) Two timing

The following table shows two examples.

Example	Channel	Group
Example 1	CH1	Group 1
	CH2	Group 1
	CH3	Group 2
	CH4	Group 2
Example 2	CH1	Group 1
	CH2	Group 2
	CH3	Not divided
	CH4	Not divided

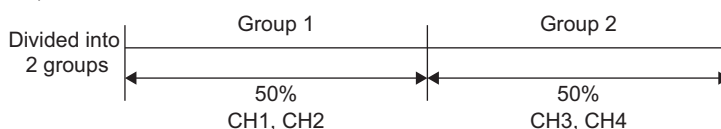
The following shows the relationship between groups and the values (%) of CH□ Upper limit output limiter (Un\G42, Un\G74, Un\G106, Un\G138).

Peak current suppression control group setting (Un\G784)

Example 1

2	2	1	1	H

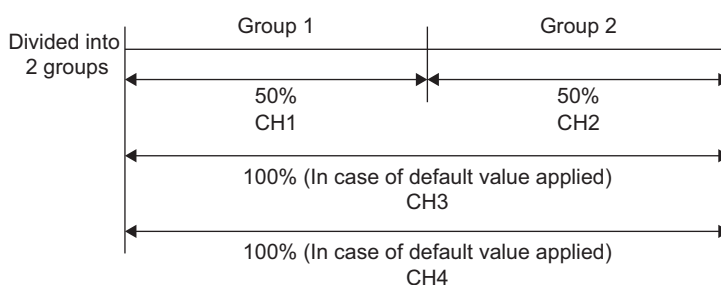
0010 0010 0001 0001
CH4 CH3 CH2 CH1



Example 2

0	0	2	1	H

0000 0000 0010 0001
CH4 CH3 CH2 CH1



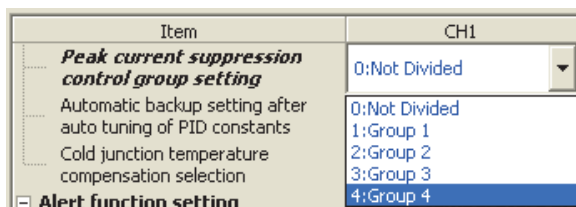
Whether the transistor output is executed or not can be selected by CH3 Unused channel setting (Un\G125) or CH4 Unused channel setting (Un\G157).

Page 385, Appendix 2 (35)

(3) Setting method

Set the timing under "Peak current suppression control group setting".

Project window ⇒ [Intelligent Function Module] ⇒ Module name ⇒ [Parameter]

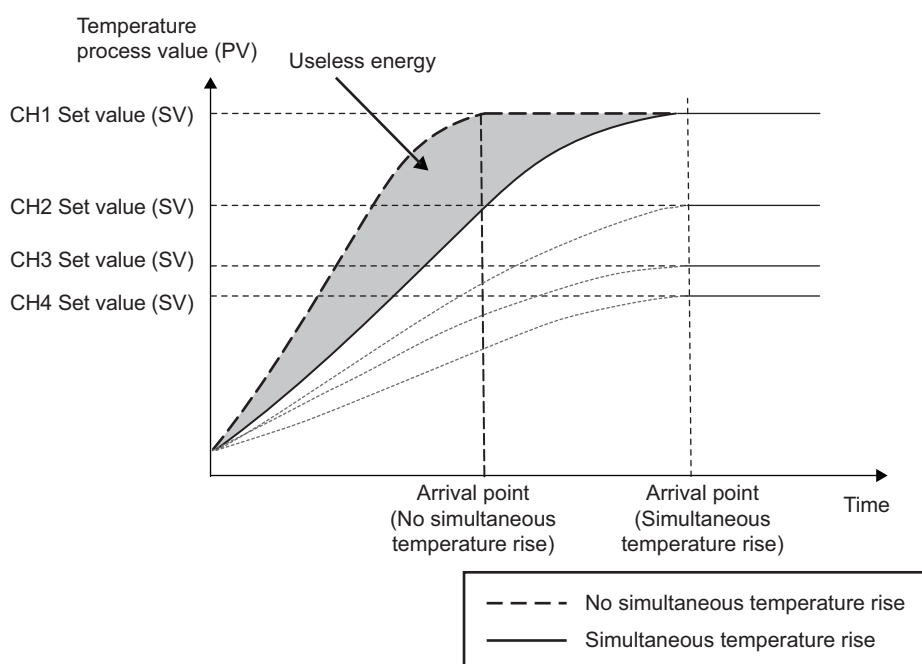


8.2.17 Simultaneous temperature rise function

Standard

This function allows several loops to reach the set value (SV) at the same time. Simultaneous temperature rise can be performed on up to two groups separately by setting a group of the channels where temperature rises at the same time. This function is effective for controlled objects where the temperature rise should complete at the same time. Aligning the time for temperature rise completion enables an even control of temperature without partial burning or partial heat expansion. In addition, the channel reaching the set value (SV) first does not need to be kept warm at the set value (SV) until the last channel reaches, leading to energy saving.

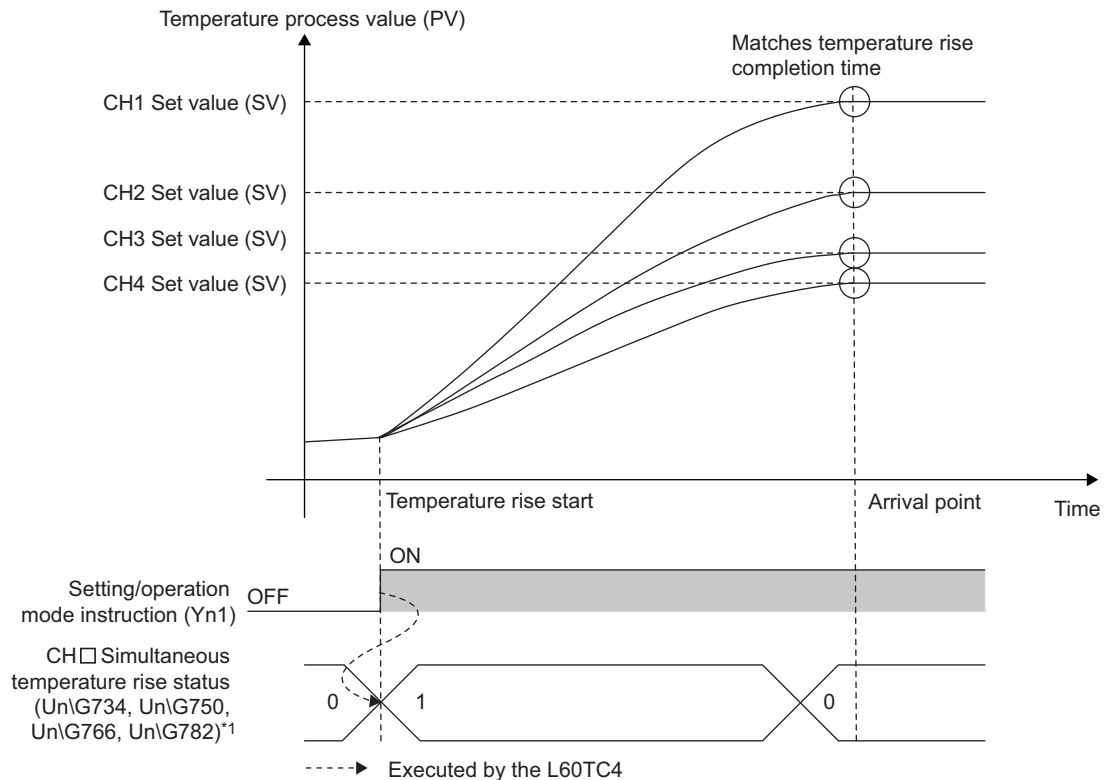
Ex. The simultaneous temperature rise function used and not used in CH1



(1) Operation of the simultaneous temperature rise function

The channel with the temperature rise reaching the set value (SV) last among channels satisfying the condition for start-up in the same group is used as a standard when the simultaneous temperature rise function is started up. The temperature of other channels rises following the temperature of the standard channel. The standard channel is determined based on the simultaneous temperature rise parameter and the deviation (E).

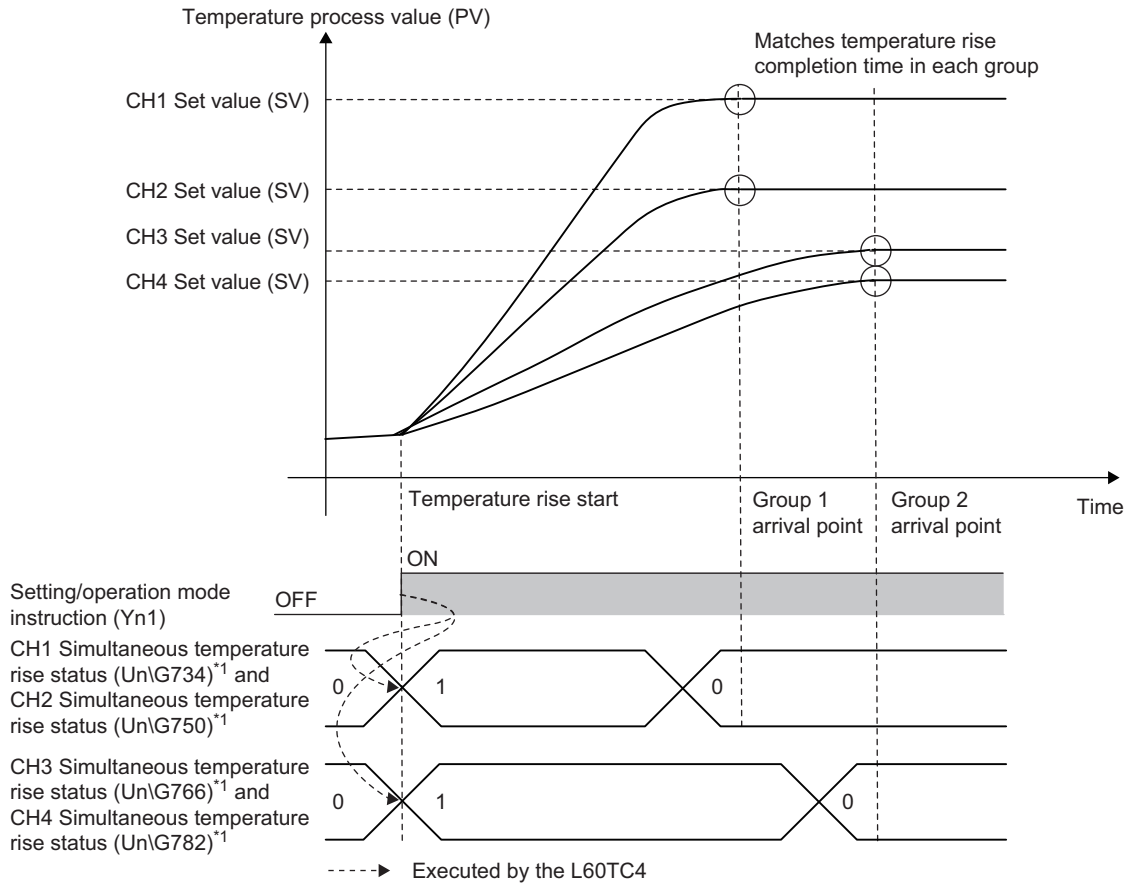
Ex. When all channels are selected for Group 1



*1 This becomes Simultaneous temperature rise in process (1) when the temperature rise starts; however, it becomes Simultaneous temperature rise not in process (0) before the temperature rise starts.

Ex. When channels are divided as following:

- CH1 and CH2: Group 1
- CH3 and CH4: Group 2



^{*1} They become Simultaneous temperature rise in process (1) when the temperature rise starts; however, they become Simultaneous temperature rise not in process (0) before the temperature rise starts.

Remark

- When the operation mode is changed to the setting mode (Setting/operation mode instruction (Yn1) is turned on and off) during simultaneous temperature rise, the control is stopped. In addition, CH□ Simultaneous temperature rise status (Un\G734, Un\G750, Un\G766, Un\G782) changes from Simultaneous temperature rise in process (1) to Simultaneous temperature rise not in process (0). (An error does not occur.)
- When the simultaneous temperature rise function is executed, the setting change rate limiter cannot be used.

(Page 378, Appendix 2 (28))

(2) Conditions for the simultaneous temperature rise function

The simultaneous temperature rise function can be executed when all the following conditions are satisfied:

- When the control is started
- When the set value (SV) is larger than the temperature process value (PV)
- When the standard control is selected on Switch Setting (not executed in the heating-cooling control)
(Page 110, Section 7.2)
- When the simultaneous temperature rise parameter has been determined (or has been set) and is not 0 (the default value)

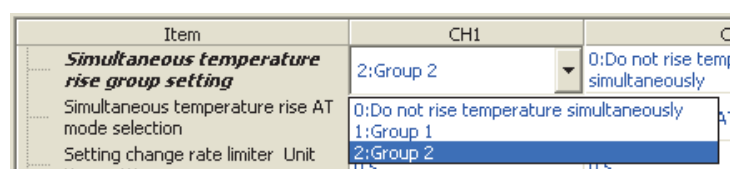
When the following buffer memory area setting is less than 100%, reaching time may vary.

- CH□ Upper limit output limiter (Un\G42, Un\G74, Un\G106, Un\G138) (Page 369, Appendix 2 (19))

(3) Setting method (dividing channels into groups)

Set the groups under "Simultaneous temperature rise group setting".

Project window ⇨ [Intelligent Function Module] ⇨ Module name ⇨ [Parameter]



(4) Simultaneous temperature rise parameter

The simultaneous temperature rise parameter is classified into the following two buffer memory values.

Buffer memory area name	Buffer memory address				Reference
	CH1	CH2	CH3	CH4	
CH□ Simultaneous temperature rise gradient data	Un\G731	Un\G747	Un\G763	Un\G779	Page 418, Appendix 2 (87)
CH□ Simultaneous temperature rise dead time	Un\G732	Un\G748	Un\G764	Un\G780	Page 418, Appendix 2 (88)

Before executing the simultaneous temperature rise function, the simultaneous temperature rise parameter needs to be automatically calculated (or arbitrarily set).

(a) Automatic calculation

The simultaneous temperature rise parameter can be automatically calculated using the following two methods:

- Simultaneous temperature rise AT (Page 198, Section 8.2.17 (5))
- Simultaneous temperature rise parameter setting using self-tuning (Page 201, Section 8.2.17 (6))

Point

If the setting in Peak current suppression control group setting (Un\G784) is changed after the simultaneous temperature rise parameter is calculated, the intended control may not be performed. If so, calculate the simultaneous temperature rise parameter again.

For details on the peak current suppression function, refer to the following.

Page 189, Section 8.2.16

(5) Simultaneous temperature rise AT

PID constants and the simultaneous temperature rise parameter are calculated. The waveform upon execution is the same as that for the auto tuning function.

For details on the auto tuning function, refer to the following.

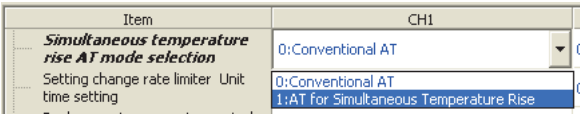
 Page 145, Section 8.2.7

(a) How to execute the simultaneous temperature rise AT function

Follow the instructions below.

1. Set "1:AT for Simultaneous Temperature Rise" under "Simultaneous temperature rise AT mode selection".

 Project window $\Rightarrow$ [Intelligent Function Module] $\Rightarrow$ Module name $\Rightarrow$ [Parameter]

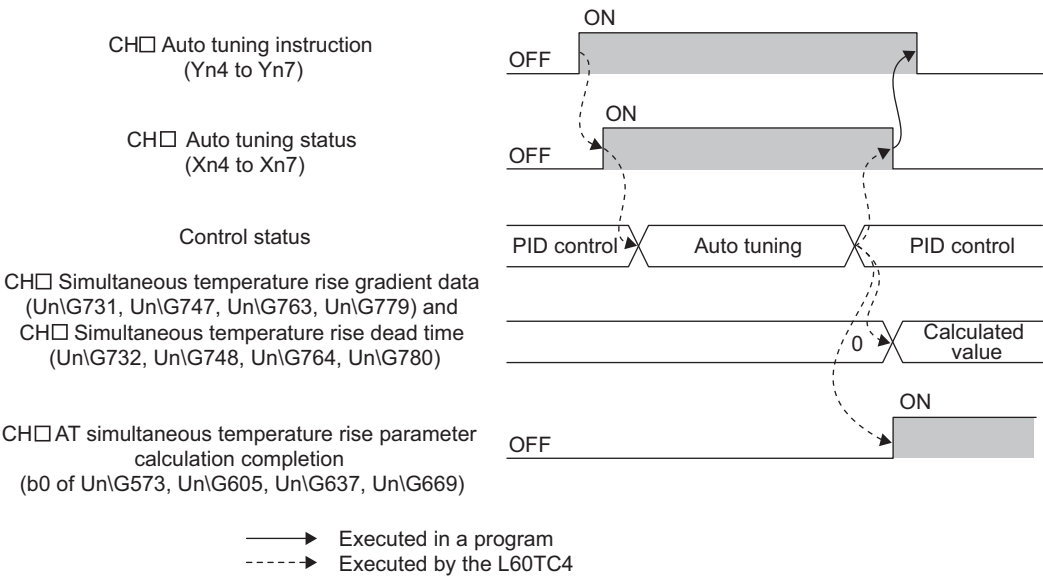


2. Turn off and on CH□ Auto tuning instruction (Yn4 to Yn7).
3. Set the module to the operation mode (turn off and on Setting/operation mode instruction (Yn1)).

(b) Operation with the simultaneous temperature rise AT function

After the procedure described on  Page 198, Section 8.2.17 (5) (a) is executed, the L60TC4 operates as following.

Operation of the L60TC4	
1	CH□ Auto tuning status (Xn4 to Xn7) is turned on. Then normal auto tuning is performed and the simultaneous temperature rise parameter is calculated.
2	The calculated value is stored in the buffer memory when the simultaneous temperature rise parameter is normally calculated. In addition, CH□ AT simultaneous temperature rise parameter calculation completion (b0 of Un\G573, Un\G605, Un\G637, Un\G669) is turned 1 (ON). After auto-tuning is completed, CH□ Auto tuning status (Xn4 to Xn7) is turned off and the module is shifted to the PID control.



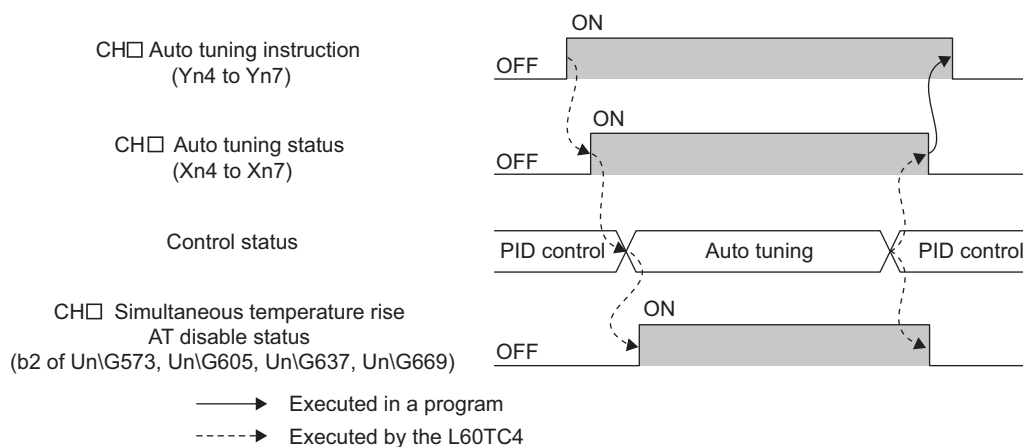
(c) Condition for the simultaneous temperature rise AT

The simultaneous temperature rise parameter is calculated when all the following conditions are satisfied after the procedure described on  Page 198, Section 8.2.17 (5) (a) is executed:

- When the module is in the PID control (all of the proportional band (P), integral time (I), and derivative time (D) are not 0)
- When the temperature process value (PV) has been stable for two minutes or longer just before the simultaneous temperature rise AT is executed
- When the temperature process value (PV) is within the temperature measurement range just before the simultaneous temperature rise AT is executed. If the temperature process value (PV) goes outside the range after the simultaneous temperature rise AT is executed, the auto tuning ends in fail. For the operation of the L60TC4 in that situation, refer to  Page 155, Section 8.2.7 (8) (b).
- When CH□ Output variation limiter setting (Un\G44, Un\G76, Un\G108, Un\G140) is set to 0. ( Page 371, Appendix 2 (20))

If all the conditions described above are not satisfied, the simultaneous temperature rise parameter is not calculated. Only PID constants are calculated.

The following shows how the L60TC4 operates when the simultaneous temperature rise AT has not been executed.



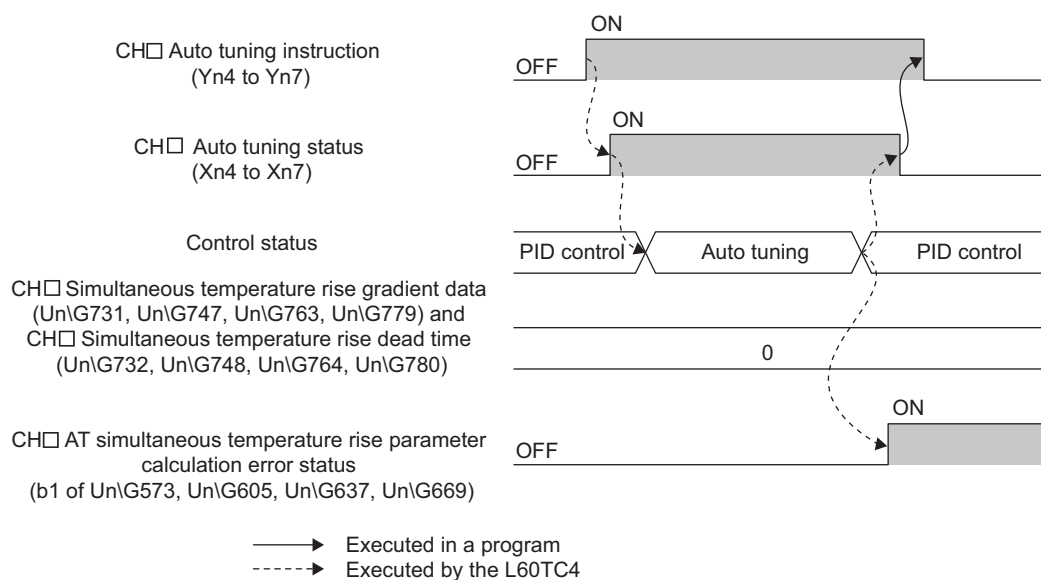
The L60TC4 turns CH□ Simultaneous temperature rise AT disable status (b2 of Un\G573, Un\G605, Un\G637, Un\G669) to 1 (ON). With CH□ Auto tuning status (Xn4 to Xn7) on, the module performs the same processing as normal auto tuning.

(d) When the simultaneous temperature rise parameter cannot be calculated

The simultaneous temperature rise parameter cannot be calculated under the following conditions:

- When the maximum gradient is not determined
- When the saturation time for output is short

The L60TC4 turns CH□ AT simultaneous temperature rise parameter calculation error status (b1 of Un\G573, Un\G605, Un\G637, Un\G669) to 1 (ON).



(6) The simultaneous temperature rise parameter setting using self-tuning

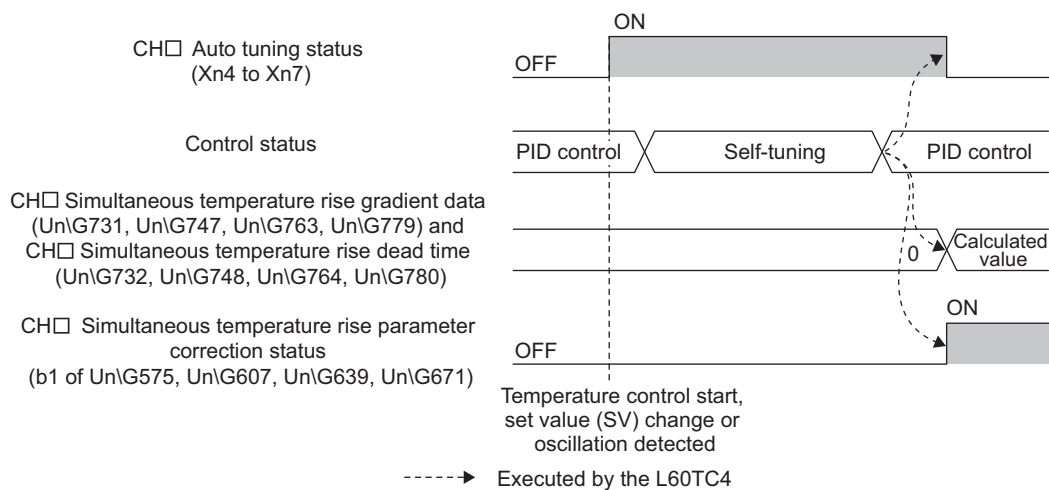
The control response at the time of temperature rise is constantly monitored during self-tuning and the simultaneous temperature rise parameter is calculated based on the characteristics of a controlled object. For details on the self-tuning function, refer to the following.

 Page 179, Section 8.2.15

(a) Operation with the simultaneous temperature rise parameter setting using self-tuning

The L60TC4 operates as following.

Operation of the L60TC4	
1	When self-tuning is normally started up, CH□ Auto tuning status (Xn4 to Xn7) is turned on and the simultaneous temperature rise parameter is calculated.
2	The calculated value is stored in the buffer memory when the simultaneous temperature rise parameter is normally calculated. Then CH□ Simultaneous temperature rise parameter correction status (b1 of Un\G575, Un\G607, Un\G639, Un\G671) is turned 1 (ON), CH□ Auto tuning status (Xn4 to Xn7) is turned off, and the module is shifted to the PID control.



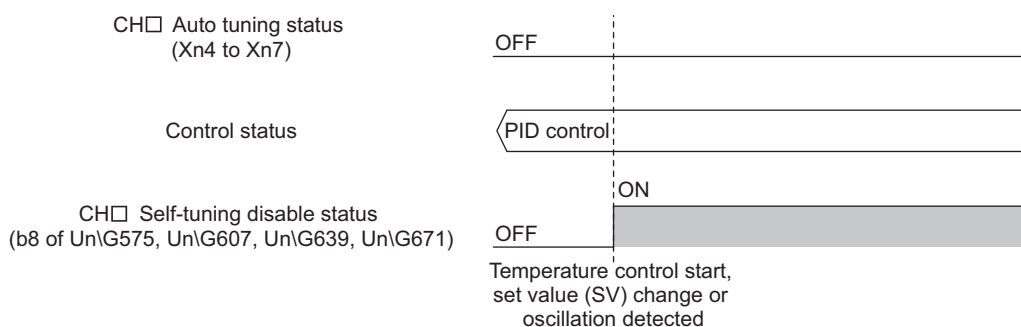
(b) Condition for the simultaneous temperature rise parameter setting using self-tuning

The condition is the same as that for the starting ST. ( Page 183, Section 8.2.15 (4) (a))

When the self-tuning cannot be started up, the L60TC4 operates as following with the PID control continued:

- CH□ Self-tuning disable status (b8 of Un\G575, Un\G607, Un\G639, Un\G671) is turned 1 (ON).

The following shows how the L60TC4 operates when self-tuning is not executed.

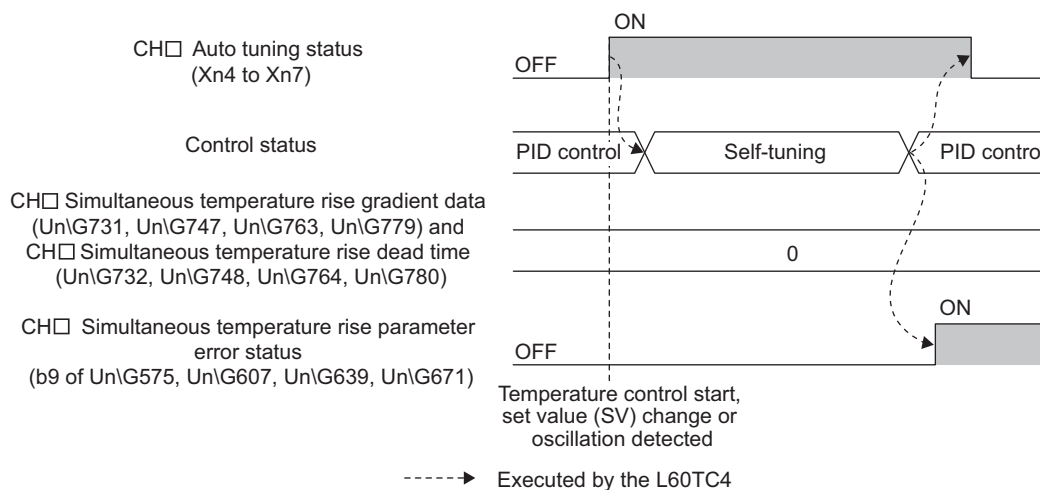


(c) When the simultaneous temperature rise parameter cannot be calculated

The simultaneous temperature rise parameter cannot be calculated under the following conditions:

- When the maximum gradient is not determined
- When the saturation time for output is short

The L60TC4 turns CH□ Simultaneous temperature rise parameter error status (b9 of Un\G575, Un\G607, Un\G639, Un\G671) to 1 (ON).



Point

To restore CH□ Simultaneous temperature rise parameter error status (b9 of Un\G575, Un\G607, Un\G639, Un\G671) to 0 (OFF), set the following:

- Set CH□ Self-tuning setting (Un\G574, Un\G606, Un\G638, Un\G670) to Do not run the ST (0).

To calculate the simultaneous temperature rise parameter, execute self-tuning again after the temperature has dropped.

(d) Stopping of calculation for the simultaneous temperature rise parameter

The optimum simultaneous temperature rise parameter may not be able to be calculated depending on the characteristics of a controlled object. In addition, the L60TC4 stops calculating the simultaneous temperature rise parameter during self-tuning under the following conditions:

- When the set value (SV) is changed
- When 6000s (1 hour and 40 minutes) or longer has passed after the self-tuning operation is started
- When the change rate of the temperature process value (PV) during self-tuning is less than 1.125 (°C/minute)
- When the setting for CH□ Output variation limiter setting (Un\G44, Un\G76, Un\G108, Un\G140) is changed (Page 371, Appendix 2 (20))

(e) How to set the simultaneous temperature rise parameter using self-tuning

Select one of the following setting values under "Self-tuning setting".

- 2: Starting ST (Simultaneous Temperature Rise Parameter Only)
- 3: Starting ST (PID Constant and Simultaneous Temperature Rise Parameter)

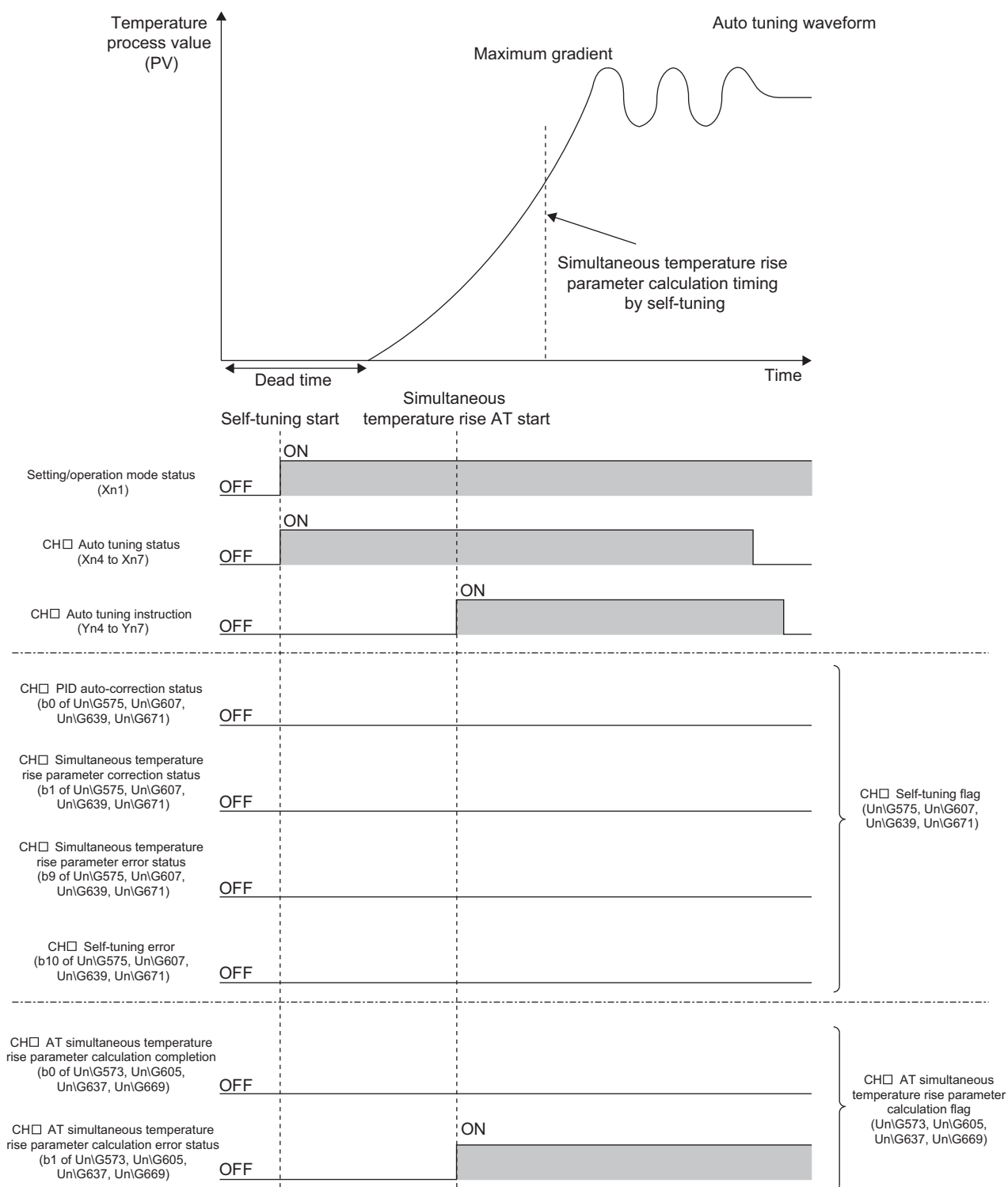
Project window ⇨ [Intelligent Function Module] ⇨ Module name ⇨ [Parameter]

Item	CH1	CH2	
Self-tuning setting	2:Starting ST	0:Do Not Run the ST	0:Do Not Run the
Temperature conversion setting	0:Do Not Run the ST		
Cooling method setting	1:Starting ST (PID Constant Only)		
Cooling upper limit output limiter	2:Starting ST (Simultaneous Temperature Rise Parameter Only)		
Cooling control output cycle setting	3:Starting ST (PID Constant and Simultaneous Temperature Rise Parameter)		
	4:Starting ST plus Vibration (PID Constant Only)		

(7) Operation when the simultaneous temperature rise parameter is calculated with self-tuning and auto tuning

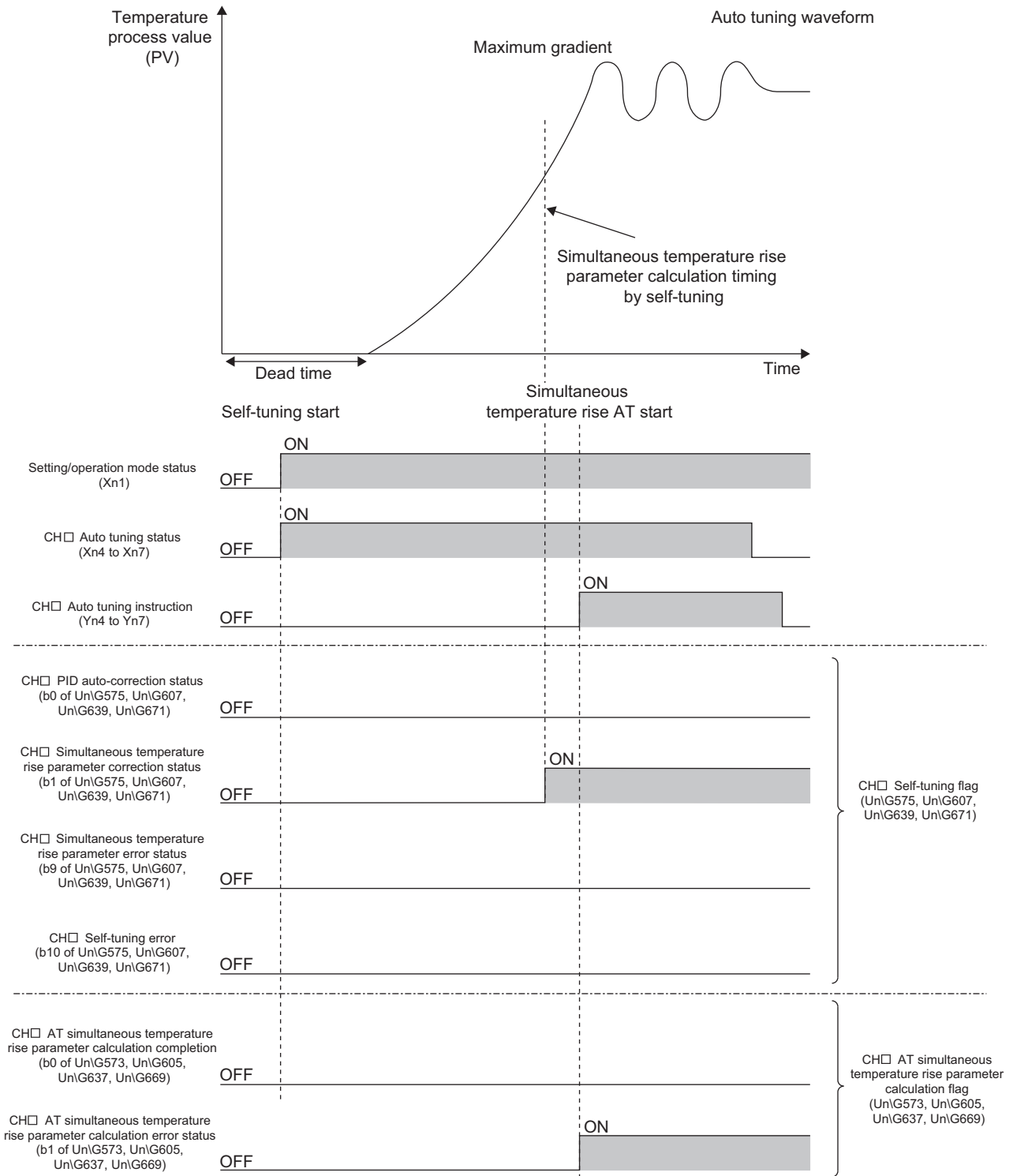
(a) When the simultaneous temperature rise AT is started before the simultaneous temperature rise parameter is calculated with self-tuning

The simultaneous temperature rise parameter is not calculated neither with self-tuning nor auto tuning. PID constants are changed.



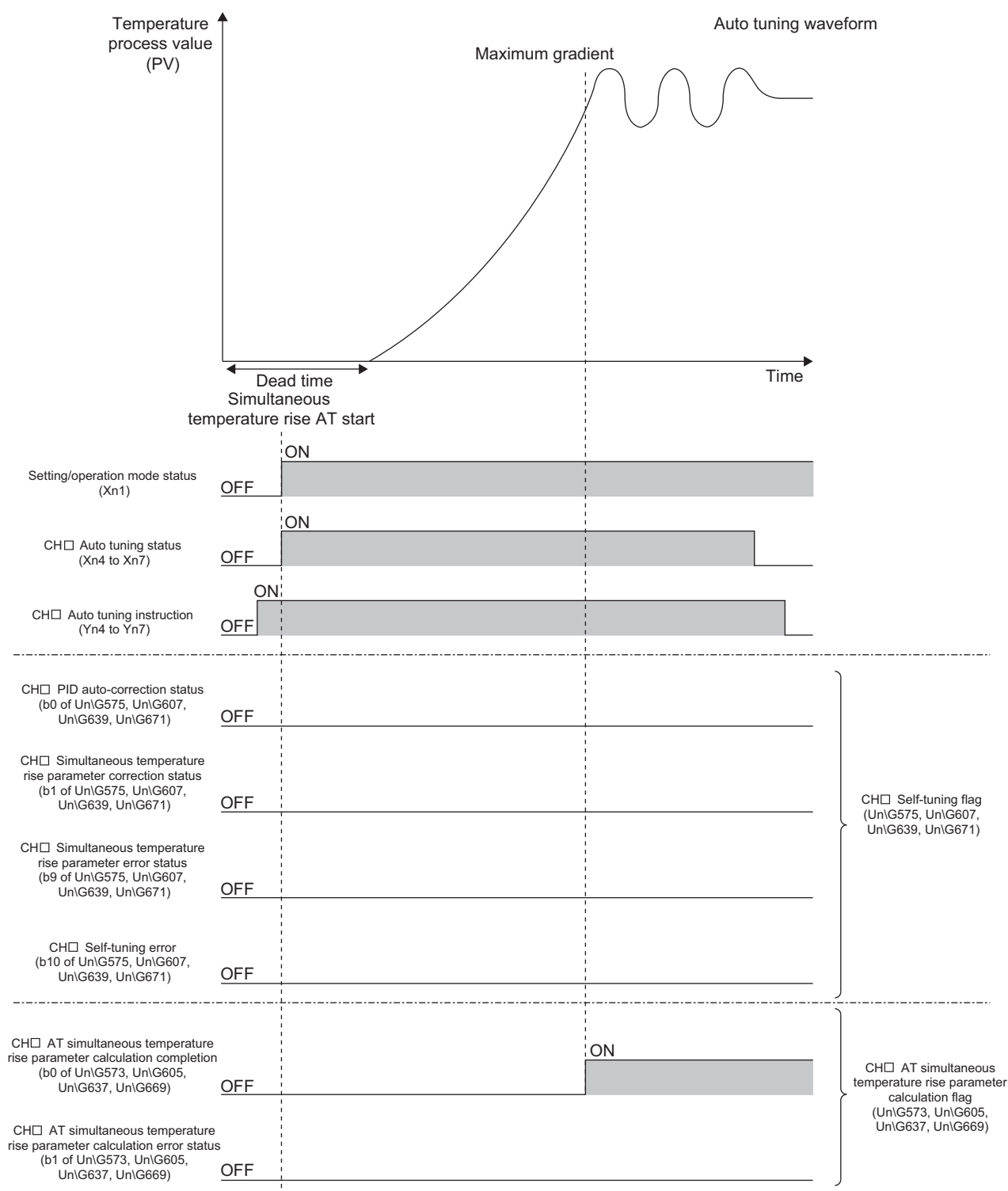
(b) When the simultaneous temperature rise AT is started after the simultaneous temperature rise parameter is calculated with self-tuning

The simultaneous temperature rise parameter calculated with self-tuning is effective. Then PID constants are changed with auto tuning.



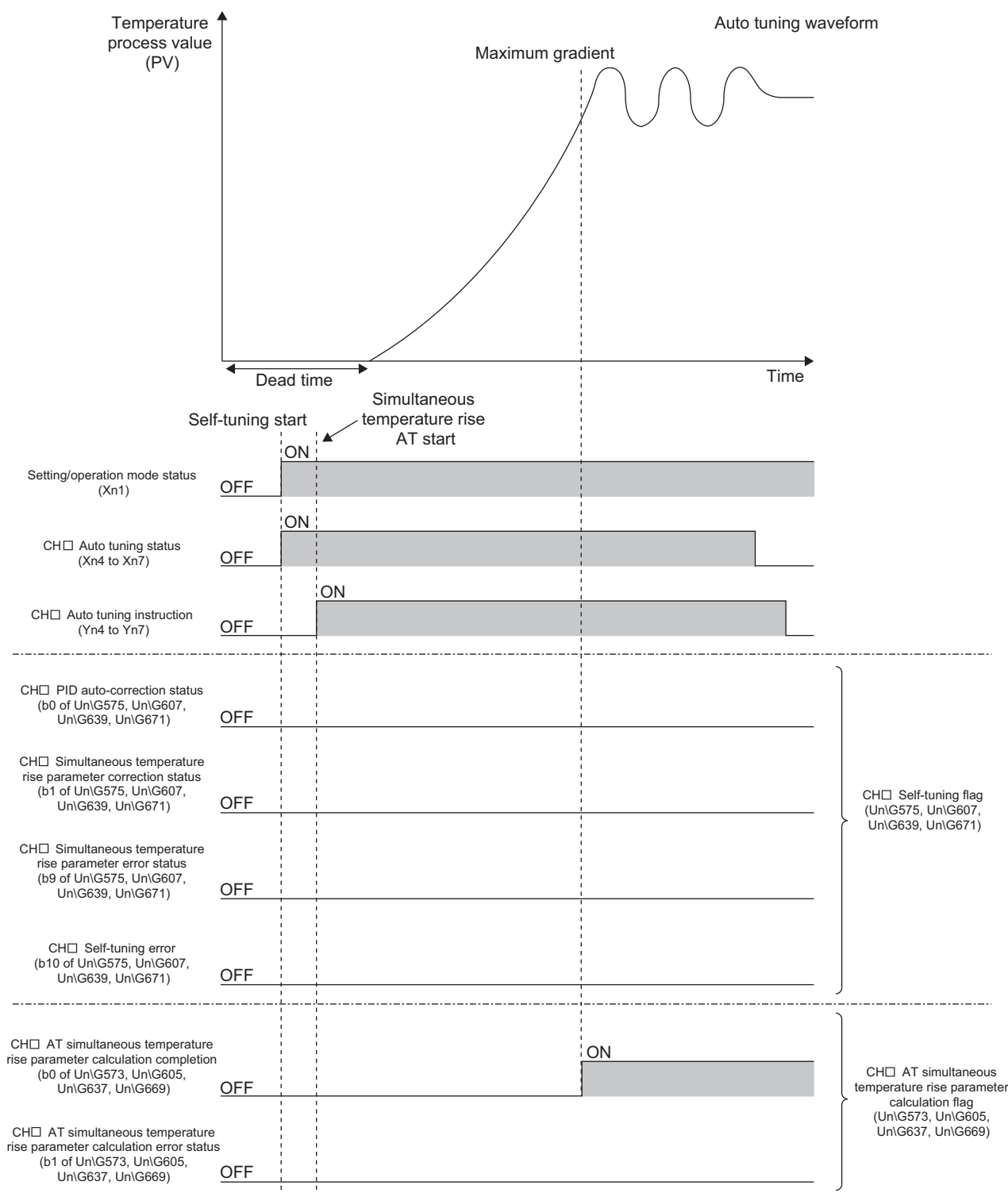
(c) When CH□ Auto tuning instruction (Yn4 to Yn7) is turned off and on in the setting mode and the module is shifted to the operation mode

After the module is shifted to the operation mode (Setting/operation mode instruction (Yn1) is turned off and on), the simultaneous temperature rise parameter and PID constants are changed with auto tuning.



(d) When auto tuning is started with the temperature process value (PV) within the stable judgment width (1°C (°F)) after the setting mode is changed to the operation mode

Until the temperature process value (PV) goes outside the stable judgment width (1°C (°F)), the data measured after the module is shifted to the operation mode (Setting/operation mode instruction (Yn1) is turned off and on) can be used. Therefore, the simultaneous temperature rise parameter can be calculated with auto tuning.



8.2.18 Forward/reverse action selection function

Standard

Whether PID operation is performed with forward action or reverse action can be selected using this function.

This function can be used in all the control methods (two-position control, P control, PI control, PD control, and PID control). (☞ Page 133, Section 8.2.3)

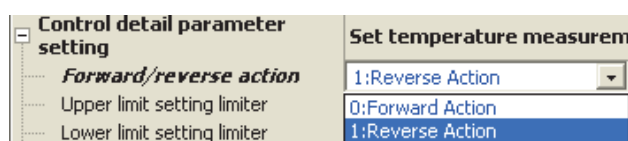
For details on the operation, refer to the following.

☞ Page 25, Section 1.4.2

(1) Setting method

Set the function under "Forward/reverse action setting".

☞ Project window ⇨ [Intelligent Function Module] ⇨ Module name ⇨ [Parameter]



8.2.19 Loop disconnection detection function

Standard

Using this function detects an error occurring within a control system (control loop) due to reasons such as a load (heater) disconnection, an externally-operable device (such as a magnetic relay) failure, and input disconnection.

(1) How an error is detected

From the point where the control output has reached upper limit output limiter value or lower limit output limiter value, the amount of changes in the temperature process value (PV) is monitored every unit time set and disconnection of a heater and input is detected.

(2) Examples of the errors detected

The following are the examples of the errors detected.

(a) When control output is being performed

The L60TC4 detects an error because the temperature does not rise even when control output is being performed under the following conditions:

- When a heater is disconnected
- When input is disconnected or short-circuited
- When the contact point of an externally-operable device does not turn on

After the control output has reached upper limit output limiter value, if the temperature does not rise by 2°C (°F) or more within the loop disconnection detection judgment time set, an alert is output. (The operation is reversed for forward action. (👉 Page 207, Section 8.2.18))

(b) When control output is not being performed

The L60TC4 detects an error because the temperature rises even when control output is not being performed under the following conditions:

- When input is disconnected
- When the contact point of an externally-operable device was bonded

After the control output has reached lower limit output limiter value, if the temperature does not drop by 2°C (°F) or more within the loop disconnection detection judgment time set, an alert is output. (The operation is reversed for forward action. (👉 Page 207, Section 8.2.18))

(3) Setting method

Two settings are available for the loop disconnection detection function.

(a) Setting for the unit time to monitor the amount of changes in the temperature process value (PV)

Set the unit time under "Loop disconnection detection judgement time".

 Project window ⇨ [Intelligent Function Module] ⇨ Module name ⇨ [Parameter]

Item	CH1
<i>Loop disconnection detection judgement time</i>	480 s

Point

When not using this function, set CH□ Loop disconnection detection judgement time (Un\G59, Un\G91, Un\G123, Un\G155) to 0.

(b) Setting for the dead band

To prevent an error alert for the loop disconnection detection, set a non-alert band (temperature band in which the loop disconnection is not detected) with the set value (SV) being its center. If the temperature process value (PV) is within the loop disconnection detection dead band, an alert is not output even though the alert conditions of loop disconnection are met.

Set the dead band under "Loop disconnection detection dead band".

 Project window ⇨ [Intelligent Function Module] ⇨ Module name ⇨ [Parameter]

Item	CH1
<i>Loop disconnection detection dead band</i>	30 C
<i>Process alarm alert output</i>	0

Point

If this function is not necessary, set 0 to CH□ Loop disconnection detection dead band (Un\G60, Un\G92, Un\G124, Un\G156).

8.2.20 During AT Loop Disconnection Detection Function

This function detects loop disconnections during auto tuning (AT). With this function, a channel that is not controlled can be detected during auto tuning, thus the error channel is detected more than 2 hours before the auto tuning error occurs. The auto tuning continues even if an alert is output for the loop disconnection detection. For details on the loop disconnection detection function, refer to the following.

☞ Page 208, Section 8.2.19

Point

- This function is enabled even when the peak current suppression function or the simultaneous temperature rise function is used.
- The loop disconnection detection dead band setting is disabled in loop disconnection detection during AT (The dead band is not set.)

(1) Conditions to start the during AT loop disconnection detection function

- Enable (1) is set to During AT loop disconnection detection function enable/disable setting (Un\G571).
- A value other than 0 is set to CH□ Loop disconnection detection judgment time (Un\G59, Un\G91, Un\G123, Un\G155).
- The standard control is set for the control mode. (The function can be used for CH3 or CH4 where the mix control is set.)

The during AT loop disconnection detection function does not operate if the above conditions are not met. An error or alarm does not occur even though the conditions are not met.

(2) Setting method

Set the function as shown below.

1. Set a value other than 0 to "Loop disconnection detection judgment time".*1

☞ Project window ⇒ [Intelligent Function Module] ⇒ Module name ⇒ [Parameter]

Item	CH1
Loop disconnection detection judgment time	480 s

*1 It takes time before the temperature starts rising due to the dead time of the controlled object. Consider the dead time of each object and set the value.

2. Set "1: Enable" to "During AT loop disconnection detection function enable/disable setting".

☞ Project window ⇒ [Intelligent Function Module] ⇒ Module name ⇒ [Parameter]

Item	CH1
Auto tuning mode selection	0:Standard Mode
Enable/disable the Loop disconnection detection function during AT	0:Disable
Temperature rise completion range setting	0:Disable 1:Enable

3. Execute auto tuning. (☞ Page 148, Section 8.2.7 (5))

Remark

- Setting example for the control to rise the temperature by 200°C for 40 minutes
It takes approx. 24 seconds to rise the temperature by 2°C. Also, the dead time of the controlled object must be added as the time required before the temperature starts rising. Therefore, when assuming the dead time of the controlled object is 6 seconds, set 30 (24 seconds + dead time of the controlled object) to CH□ Loop disconnection detection judgment time (Un\G59, Un\G91, Un\G123, Un\G155).

(3) When an alert occurs, or does not occur

If an alert for the loop disconnection detection occurs, CH□ Alert occurrence flag (XnC to XnF) and CH□ Loop disconnection detection (b13 of Un\G5 to Un\G8) turn on and Alarm code (03□A_H) is stored in Error code

(Un\G0). (☞ Page 328, Section 11.7)

If an alert for the loop disconnection detection does not occur and auto tuning is normally completed, the value in CH□ Loop disconnection detection judgment time (Un\G59, Un\G91, Un\G123, Un\G155) is automatically updated to the value calculated by auto tuning.

Point

There is a possibility of an error in the control loop if the loop disconnection alert occurs. For this reason, even when auto tuning is normally completed, check the control loop and examine the appropriateness of the loop disconnection detection judgment time during auto tuning.

(4) To clear the alert status

If any of the following conditions is met, CH□ Alert occurrence flag (XnC to XnF) and CH□ Loop disconnection detection (b13 of Un\G5 to Un\G8) turn off.

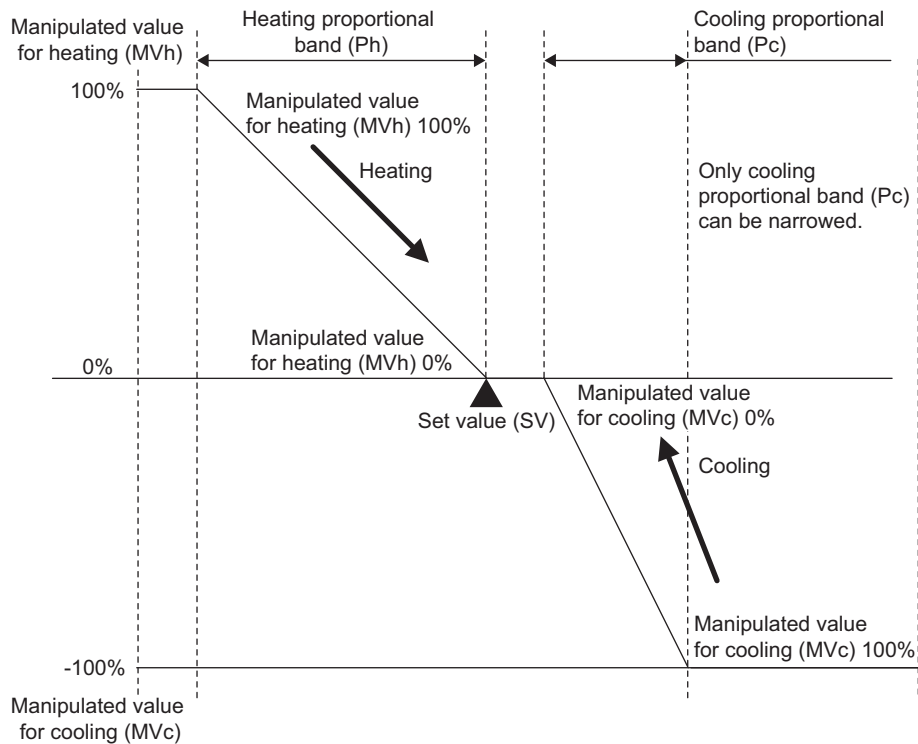
- CH□ PID control forced stop instruction (YnC to YnF) is turned on from off.
- Setting/operation mode instruction (Yn1) is turned off from on and the mode has shifted to the setting mode.
- A manipulated value (MV) becomes greater than the lower limit output limiter value and smaller than the upper limit output limiter value.
- Disable (0) is set to During AT loop disconnection detection function enable/disable setting (Un\G571).
- 0 is set to CH□ Loop disconnection detection judgment time (Un\G59, Un\G91, Un\G123, Un\G155).
- MAN (1) is set to CH□ AUTO/MAN mode shift (Un\G50, Un\G82, Un\G114, Un\G146).

After performing the operations above, turn on and off Error reset instruction (Yn2) to clear the value in Error code (Un\G0).

8.2.21 Proportional band setting function

Heating-cooling

Proportional band (P) values can be set for heating and cooling separately using this function. Different gradients can be set by using different proportional band (P) values in a heating and cooling area.



(1) Setting method

(a) For heating

Set the value under "Proportional band (P) setting/Heating control proportional band setting (Ph)".

Project window ⇒ [Intelligent Function Module] ⇒ Module name ⇒ [Parameter]

Item	CH1
Control basic parameter setting	The Q64TC exercises temperat
Proportional band (P) setting/Heating control proportional band setting	3.0 %
Cooling proportional band (Pc)	

(b) For cooling

Set the value under "Cooling proportional band (Pc) setting".

Project window ⇒ [Intelligent Function Module] ⇒ Module name ⇒ [Parameter]

Item	CH1
Cooling proportional band (Pc) setting	3.0 %
Integral time (Ti) setting	240 s

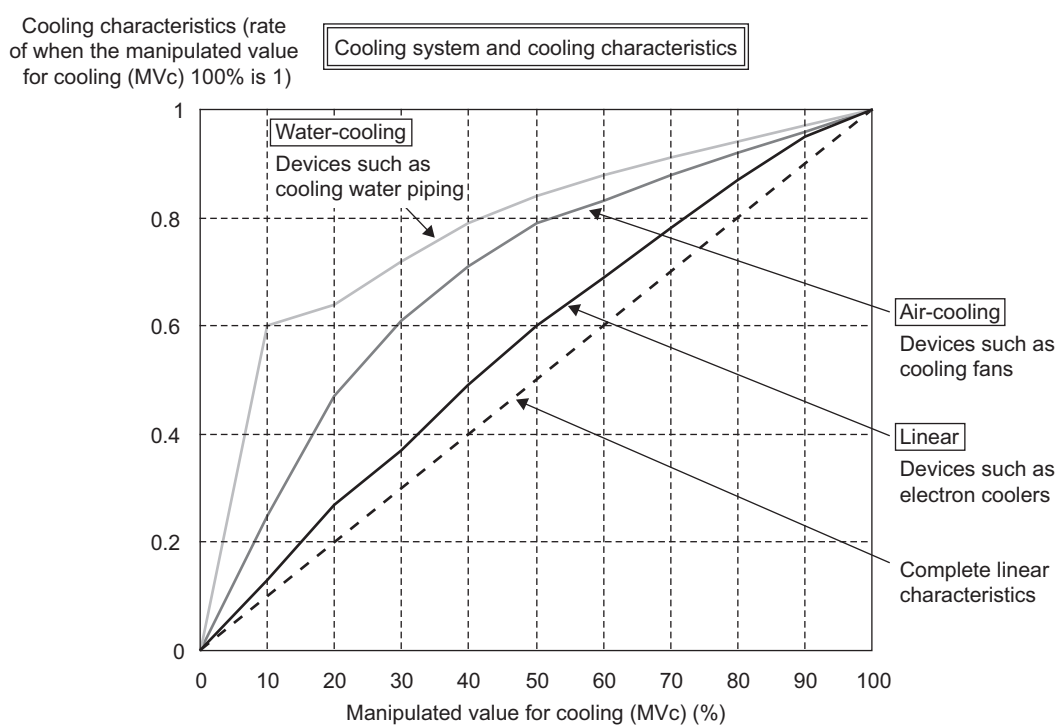
8.2.22 Cooling method setting function

Heating-cooling

An auto tuning calculation formula is automatically selected according to the selected cooling method during auto tuning and the operation is started using this function.

Select one of the following characteristics:

- Air cooled: The cooling characteristic is nonlinear and cooling ability is low.
- Water cooled: The cooling characteristic is nonlinear and cooling ability is high.
- Linear: The cooling characteristic is close to the linear shape.



PID constants are calculated and executed based on this setting during auto tuning; therefore, more appropriate PID constants can be found by setting more applicable cooling characteristic of a device.

For details on the auto tuning function, refer to the following.

☞ Page 145, Section 8.2.7

(1) Setting method

Set the characteristic under "Cooling method setting".

 Project window ⇨ [Intelligent Function Module] ⇨ Module name ⇨ [Parameter]

Item	CH1
Cooling method setting	0:Air Cooled
Cooling upper limit output limiter	0:Air Cooled
Cooling control output cycle setting	1:Water Cooled
	2:Linear

Point

- An auto tuning calculation formula to find PID constants is determined based on this setting; therefore, configure this setting before executing auto tuning.
- "Air Cooled" and "Water Cooled" roughly indicate the level of the cooling ability. When a device is too cooled even if it is set to air cooled, set the module to Water cooled (1_H). When a device is not very cooled even if it is set to water cooled, set the module to Air cooled (0_H).
- In general, the ability of water cooling is higher than that of air cooling and cooling may be too strong if the same PID constants as air cooling are used. Some time is required until the control becomes stable upon the initial start-up, disturbance, or setting change. Therefore, in auto tuning, PID constants for when the module is set to Water cooled (1_H) become larger than those for when the module is set to Air cooled (0_H).

8.2.23 Overlap/dead band function

Heating-cooling

In heating-cooling control, the temperature process value (PV) significantly changes due to slight heating or cooling control output when the heat produced by a controlled object and natural cooling are being balanced. Consequently, excessive output may be performed.

The temperature where the cooling control output starts can be shifted using this function; therefore, whether control stability is prioritized or energy saving is prioritized can be selected.

(1) Overlap

Overlap refers to the temperature area where both of heating control and cooling control are performed. In the temperature area where both heating and cooling output overlap, both of the output negate each other, thus the control gain becomes moderate. Consequently, the change amount in the temperature process value (PV) for the output becomes small, improving control stability.

Ex. When buffer memory values are set as following:

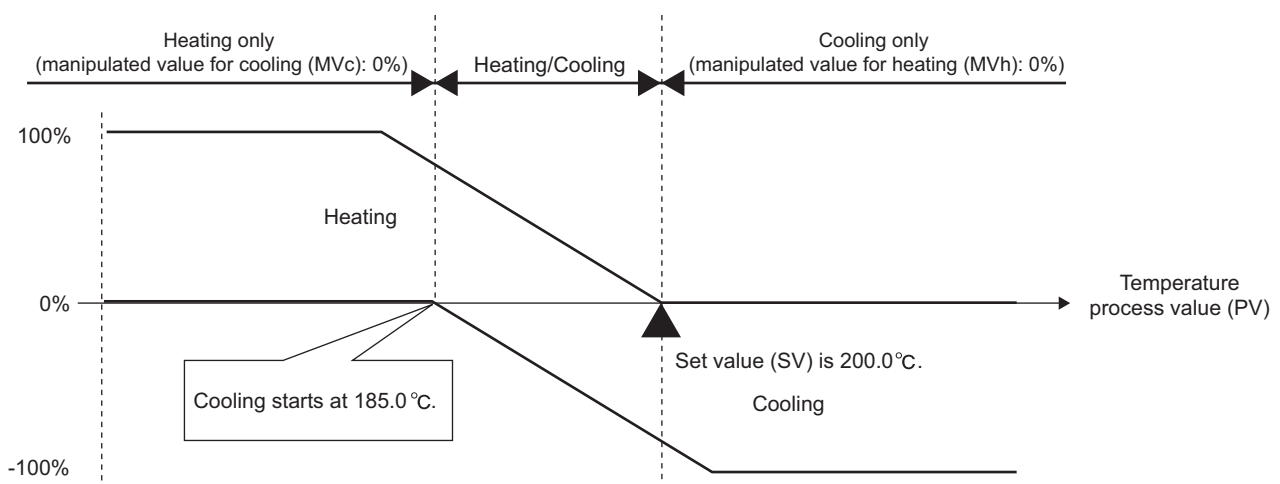
- CH□ Input range (Un\G32, Un\G64, Un\G96, Un\G128): 38 (temperature measurement range: -200.0°C to 400.0°C)
- CH□ Set value (SV) setting (Un\G34, Un\G66, Un\G98, Un\G130): 2000 (200.0°C)
- CH□ Overlap/dead band setting (Un\G723, Un\G739, Un\G755, Un\G771): -25 (-2.5%)

185.0°C to 200.0°C is the overlapping area.

$(\text{Full scale}) \times (\text{Overlap setting}) = (400.0^\circ\text{C} - (-200.0^\circ\text{C})) \times -0.025 = -15.0^\circ\text{C}$

The temperature where cooling operation starts = (Set value (SV)) - 15.0°C = 185.0°C

As shown below, shifting the temperature where cooling operation starts to the lower temperature side of the set value (SV) produces an overlapping area. (The following is an example of when the module is in P control.)



(2) Dead band

Dead band refers to the temperature area where neither heating control output nor cooling control output is performed. When the temperature process value (PV) is stable within this area, output is not performed for the slight change in the temperature, resulting in energy saving.

Ex. When buffer memory values are set as following:

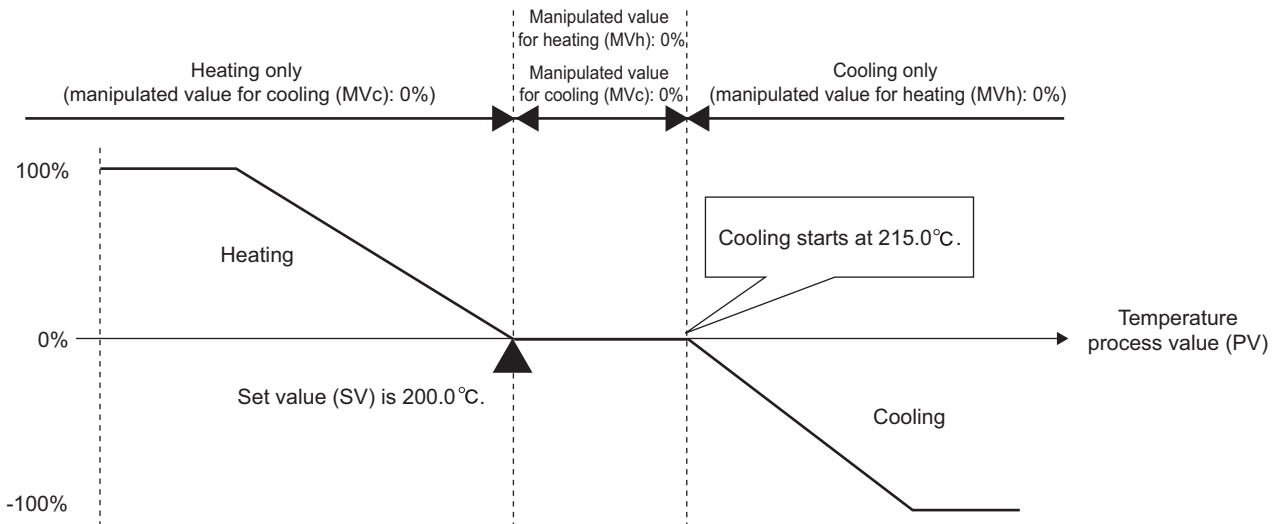
- CH□ Input range (Un\G32, Un\G64, Un\G96, Un\G128): 38 (temperature measurement range: -200.0°C to 400.0°C)
- CH□ Set value (SV) setting (Un\G34, Un\G66, Un\G98, Un\G130): 2000 (200.0°C)
- CH□ Overlap/dead band setting (Un\G723, Un\G739, Un\G755, Un\G771): 25 (2.5%)

200.0°C to 215.0°C is the area for dead band.

$$(\text{Full scale}) \times (\text{Overlap setting}) = (400.0^\circ\text{C} - (-200.0^\circ\text{C})) \times 0.025 = 15.0^\circ\text{C}$$

$$\text{The temperature where cooling operation starts} = (\text{Set value (SV)}) + 15.0^\circ\text{C} = 215.0^\circ\text{C}$$

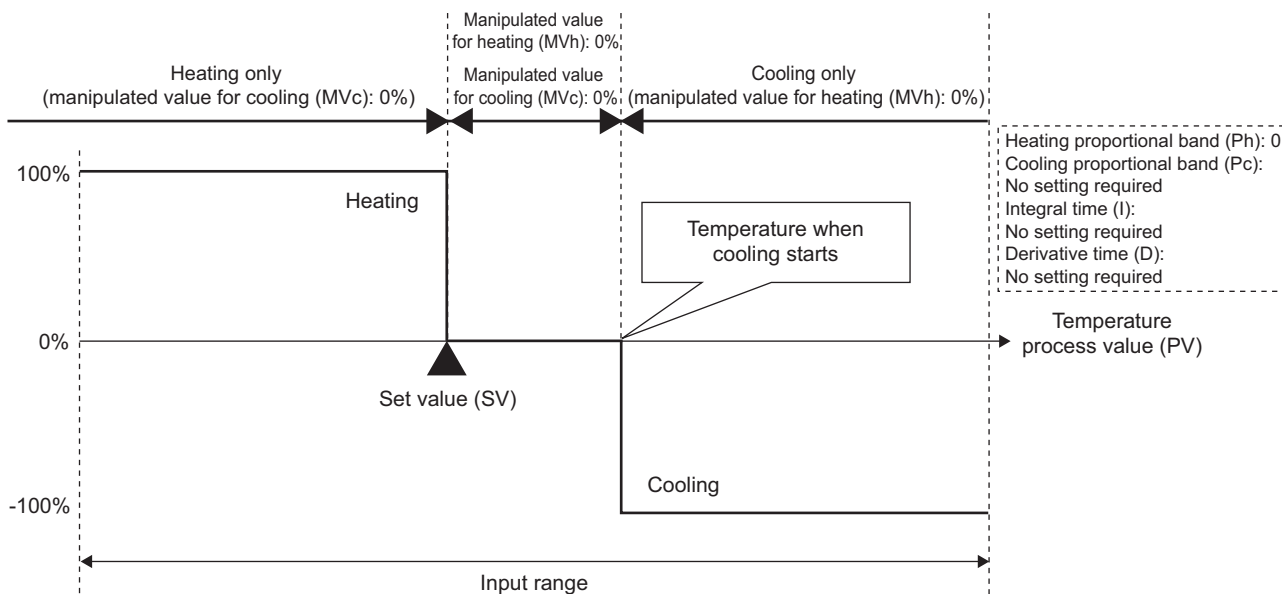
As shown below, shifting the temperature where cooling operation starts to the higher temperature side of the set value (SV) produces a dead band area. (The following is an example of when the module is in P control.)



(3) Dead band setting in two-position control (three-position control)

Set the dead band in two-position control.

Three-position control can be achieved by setting a dead band area in addition to areas for the manipulated value for heating (MVh) 100% and the manipulated value for cooling (MVc) 100%.



(4) Setting method

Set the function under "Overlap/dead band setting".

Project window ⇨ [Intelligent Function Module] ⇨ Module name ⇨ [Parameter]

Item	CH1
Overlap/dead band setting	5.0 %
Process value (PV) scaling function	0-100% (0-100%)

8.2.24 Temperature conversion function (using unused channels)

Heating-cooling

In heating-cooling control (normal mode) and mix control (normal mode), only temperature measurement can be performed by using unused temperature input terminals. When this function is used, temperature control and alert judgment are not performed.

(1) Temperature input terminals that can be used

Temperature input terminals that can be used for this function differ depending on the control mode.

Use the terminals indicating MT2□ (Monitor CH2), MT3□ (Monitor CH3), and MT4□ (Monitor CH4) in the following table.

Terminal No.	Terminal symbol			
	L60TCTT4/L60TCTT4BW ^{*1}		L60TCRT4/L60TCRT4BW ^{*1}	
	Heating-cooling control (normal mode)	Mix control (normal mode)	Heating-cooling control (normal mode)	Mix control (normal mode)
1	L1H	L1H	L1H	L1H
2	L1C	L1C	L1C	L1C
3	L2H	L3	L2H	L3
4	L2C	L4	L2C	L4
5	COM-	COM-	COM-	COM-
6	Unused	Unused	Unused	Unused
7	CH1+	CH1+	CH1 A	CH1 A
8	CH2+	MT2+	CH2 A	MT2 A
9	CH1-	CH1-	CH1 B	CH1 B
10	CH2-	MT2-	CH2 B	MT2 B
11	Unused	Unused	CH1 b	CH1 b
12	CJ	CJ	CH2 b	MT2 b
13	Unused	Unused	MT3A	CH3 A
14	CJ	CJ	MT4A	CH4 A
15	MT3+	CH3+	MT3B	CH3 B
16	MT4+	CH4+	MT4B	CH4 B
17	MT3-	CH3-	MT3b	CH3 b
18	MT4-	CH4-	MT4b	CH4 b

^{*1} For the L60TCTT4BW and L60TCRT4BW, the terminals in the table above are those on a terminal block for I/O.

(2) Buffer memory areas that can be used with this function

The following table lists the buffer memory areas that can be used with this function (the terminals used correspond to the buffer memory areas in the table).

Buffer memory area name	Buffer memory			Reference
	MT2 (Monitor CH2)	MT3 (Monitor CH3)	MT4 (Monitor CH4)	
Error code	Un\G0			Page 344, Appendix 2 (1)
CH□ Decimal point position	Un\G2	Un\G3	Un\G4	Page 344, Appendix 2 (2)
CH□ Alert definition	Un\G6	Un\G7	Un\G8	Page 346, Appendix 2 (3)
CH□ Temperature process value (PV)	Un\G10	Un\G11	Un\G12	Page 348, Appendix 2 (4)
Cold junction temperature process value	Un\G29			Page 352, Appendix 2 (9)
CH□ Input range	Un\G64	Un\G96	Un\G128	Page 355, Appendix 2 (12)
CH□ Sensor correction value setting	Un\G77	Un\G109	Un\G141	Page 372, Appendix 2 (21)
CH□ Primary delay digital filter setting	Un\G80	Un\G112	Un\G144	Page 374, Appendix 2 (24)
Cold junction temperature compensation selection	Un\G182			Page 393, Appendix 2 (49)
Control switching monitor	Un\G183			Page 394, Appendix 2 (50)
CH□ Sensor two-point correction offset value (measured value)	Un\G576	Un\G608	Un\G640	Page 403, Appendix 2 (63)
CH□ Sensor two-point correction offset value (corrected value)	Un\G577	Un\G609	Un\G641	Page 403, Appendix 2 (64)
CH□ Sensor two-point correction gain value (measured value)	Un\G578	Un\G610	Un\G642	Page 404, Appendix 2 (65)
CH□ Sensor two-point correction gain value (corrected value)	Un\G579	Un\G611	Un\G643	Page 404, Appendix 2 (66)
CH□ Sensor two-point correction offset latch request	Un\G580	Un\G612	Un\G644	Page 405, Appendix 2 (67)
CH□ Sensor two-point correction offset latch completion	Un\G581	Un\G613	Un\G645	Page 405, Appendix 2 (68)
CH□ Sensor two-point correction gain latch request	Un\G582	Un\G614	Un\G646	Page 406, Appendix 2 (69)
CH□ Sensor two-point correction gain latch completion	Un\G583	Un\G615	Un\G647	Page 406, Appendix 2 (70)
Sensor correction function selection	Un\G785			Page 423, Appendix 2 (93)
Temperature conversion completion flag	Un\G786			Page 423, Appendix 2 (94)
CH□ Temperature conversion setting	Un\G695	Un\G696	Un\G697	Page 413, Appendix 2 (77)

(3) Setting method

Set whether using this function under "Temperature conversion setting".

 Project window ⇨ [Intelligent Function Module] ⇨ Module name ⇨ [Parameter]

Item	CH1	CH2
Temperature conversion		0:Not Used
Cooling method setting	0:Air Cooled	0:Not Used
Cooling upper limit output limiter	100.0 %	1:Use

Point

When heating-cooling control (expanded mode) or mix control (expanded mode) is selected, the setting in CH□ Temperature conversion setting (Un\G695 to Un\G697) is ignored.

8.2.25 Heater disconnection detection function

When transistor output is on, whether a heater is disconnected or not can be checked based on a reference heater current value (load current value detected by a current sensor (CT)) using this function. A reference heater current value and heater disconnection alert current value are compared. When the reference heater current value becomes lower than the heater disconnection alert current value, the heater is regarded as disconnected.

Heater disconnection is detected every 500ms. When transistor output is on for 500ms or less, heater disconnection is not detected. (CH□ Heater disconnection detection (b12 of Un\G5 to Un\G8) remains 0 (OFF).) (Page 346, Appendix 2 (3))

The following is the timing output as an alert.

- 500ms × Setting value in Heater disconnection/output off-time current error detection delay count (Un\G166)

If a heater is disconnected longer than the time described above, Alarm code: 04□AH is stored in Error code (Un\G0).

(Page 328, Section 11.7)

(1) Modules where this function can be used

- L60TCTT4BW
- L60TCRT4BW

(2) Setting method

Set the function on "Parameter". Follow the instructions below.

Project window ⇒ [Intelligent Function Module] ⇒ Module name ⇒ [Parameter]

Item	CH1	CH2
CT1 CT selection	0:CTL-12-S36-8(0.0 to 100.0A)	
CT2 CT selection	0:CTL-12-S36-8(0.0 to 100.0A)	
CT3 CT selection	1:CTL-6-P(-H)(0.00 to 20.00A)	
CT4 CT selection	2:Use CT Ratio Setting (0.0 to 100.0A)	
CT5 CT selection	0:CTL-12-S36-8(0.0 to 100.0A)	
CT6 CT selection	0:CTL-12-S36-8(0.0 to 100.0A)	
CT7 CT selection	0:CTL-12-S36-8(0.0 to 100.0A)	
CT8 CT selection	0:CTL-12-S36-8(0.0 to 100.0A)	
CT1 Reference heater current		



CT1 CT Ratio setting	800
CT2 CT Ratio setting	800
CT3 CT Ratio setting	800
CT4 CT Ratio setting	800
CT5 CT Ratio setting	800
CT6 CT Ratio setting	800
CT7 CT Ratio setting	800
CT8 CT Ratio setting	800



Item	CH1	CH2
CT setting	External current sensors	
CT1 CT input channel assignment setting	1:CH1	
CT2 CT input channel assignment setting	0:Unused	
CT3 CT input channel assignment setting	1:CH1	
CT4 CT input channel assignment setting	2:CH2	
	3:CH3	
	4:CH4	
	0:Unused	



(To the next page)

1. Set the current sensor (CT) to be used under "CT□ CT selection".

2. When using a current sensor (CT) other than CTL-12-S36-8 and CTL-6-P(-H) manufactured by U.R.D.Co., LTD., set "CT□ CT Ratio setting".

3. Set the CT input assigned to each channel under "CT□ CT input channel assignment setting".

(From the previous page)



Address	F	E	D	C	B	A	9	8	7	6	5	4	3	2	1	0		
256	0	0	0	0	0	0	0	0	0	0	1	0	1	0	1	0	42	
257	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
258	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
259	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
260	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
261	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
262	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
263	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	



Item	CH1
CT1 Reference heater current value	4.2 A
CT2 Reference heater current value	0.0 A
CT3 Reference heater current value	0.0 A
CT4 Reference heater current value	0.0 A
CT5 Reference heater current value	0.0 A
CT6 Reference heater current value	0.0 A
CT7 Reference heater current value	0.0 A
CT8 Reference heater current value	0.0 A



Item	CH1
Heater disconnection alert	90 %
Heater disconnection/output off-time current error detection	3 Times



Item	CH1
Heater disconnection/output off-time current error detection delay count	3 Times
Heater disconnection	0:OFF



End

4. Monitor CT□ Heater current process value (Un\G256 to Un\G263) and check the current value of when the heater is on. (☞ Page 399, Appendix 2 (58))

5. Set the value monitored in CT□ Heater current process value (Un\G256 to Un\G263) under "CT□ Reference heater current value".

6. Set the judgment value to perform the heater disconnection detection and output off-time current error detection*1 at the rate of the reference heater current value (%) under "Heater disconnection alert setting".

7. Set how many times heater disconnection is detected successively to regard the heater as disconnected under "Heater disconnection/output off-time current error detection delay count".

*1 For details on the output off-time current error detection function, refer to ☞ Page 226, Section 8.2.26.

Point

- The standard setting value for CH□ Heater disconnection alert setting (Un\G58, Un\G90, Un\G122, Un\G154) is 80%. However, the current value may significantly change depending on the characteristics of a heater or how the heater is used. Check that there is no problem in the actual system.
- A write data error (error code: □□□4_H) occurs if the current value to be used as a judgment value to detect heater disconnection (reference heater current value × CH□ Heater disconnection alert setting (%)) is within 0.1A under one of the following situations:
 - CT□ CT selection (Un\G272 to Un\G279) is set to When CTL-12-S36-8 (0.0A to 100.0A) is used (0).
 - CT□ CT selection (Un\G272 to Un\G279) is set to When CT ratio setting is used (0.0A to 100.0A) (2).
 In addition, when CTL-6-P(-H) used (0.00A to 20.00A) (1) has been set and the current value to be used as a judgment value to detect heater disconnection (reference heater current value × CH□ Heater disconnection alert setting (%)) is within 0.01A, Write data error (error code: □□□4_H) occurs.

(3) Heater disconnection compensation function

When heater voltage is dropped, heater current is reduced. The L60TCTT4BW and L60TCRT4BW detect heater disconnection by measuring heater current; therefore, an accidental alert may occur due to a voltage change caused by a reduced heater voltage.

The heater disconnection compensation function offsets the amount of heater current reduced (heater disconnection compensation), preventing disconnection from being detected.

(a) Calculation formula for heater disconnection compensation

Calculate (CH□ Heater current) - (reference heater current value). The largest positive value is the correction value. When there is no positive value, the value with the smallest gap is the correction value. The heater current for each channel is corrected using a correction value. When the corrected value is larger than the heater disconnection alert setting value, heater disconnection is found.

Ex. When CH□ Heater disconnection alert setting (Un\G58, Un\G90, Un\G122, Un\G154) is 80% and the differences between CH□ Heater current and the reference heater current value are the following values:

- CH1: -2%
- CH2: 5%
- CH3: -1%
- CH4: -17%

The following table lists the result.

Channel	CH□ Heater disconnection alert setting (Un\G58, Un\G90, Un\G122, Un\G154)	Difference between CH□ Heater current and reference heater current value	Correction value	Difference between CH□ Heater current and reference heater current value after correction	Disconnection detected
CH1	80 (%)	-2%	5%	-7% (= -2% - 5%)	Not detected
CH2		5%		0% (= 5% - 5%)	Not detected
CH3		-1%		-6% (= -1% - 5%)	Not detected
CH4		-17%		-22% (= -17% - 5%)	Detected

In the table above, the correction value is 5%. Heater disconnection is detected based on the differences of -7% for CH1, 0% for CH2, -6% for CH3, and -22% for CH4. When Heater disconnection alert setting is set to 80%, disconnection is detected only for CH4.

Ex. When CH□ Heater disconnection alert setting (Un\G58, Un\G90, Un\G122, Un\G154) is 80% and the differences between CH□ Heater current and the reference heater current value are the following values:

- CH1: -16%
- CH2: -17%
- CH3: -22%
- CH4: -19%

The following table lists the result.

Channel	CH□ Heater disconnection alert setting (Un\G58, Un\G90, Un\G122, Un\G154)	Difference between CH□ Heater current and reference heater current value	Correction value	Difference between CH□ Heater current and reference heater current value after correction	Disconnection detected
CH1	80 (%)	-16%	-16%	0% (= -16% - (-16%))	Not detected
CH2		-17%		-1% (= -17% - (-16%))	Not detected
CH3		-22%		-6% (= -22% - (-16%))	Not detected
CH4		-19%		-3% (= -19% - (-16%))	Not detected

In the table above, the correction value is -16%. Heater disconnection is detected based on the differences of 0% for CH1, -1% for CH2, -6% for CH3, and -3% for CH4. When Heater disconnection alert setting is set to 80%, none of the channels are regarded as disconnected.

(b) Restrictions

- When only one channel is used, the heater disconnection compensation function does not work. To use this function, two channels or more need to be used.
- When several channels are used with a heater on for one channel and heaters off for other channels, the heater disconnection compensation function does not work. Therefore, disconnection may be detected even if there is no disconnection.
- The heater disconnection alert correction value is 20% at maximum. When Heater disconnection alert setting is set to 80% as shown in the two examples on  Page 223, Section 8.2.25 (3) (a), the conditions for disconnection detection are satisfied even if correction is performed by 20% with a voltage drop by 40% or more. Consequently, disconnection is detected.

(c) Setting method

Set "Heater disconnection compensation function selection" to "1: ON".

 Project window ⇒ [Intelligent Function Module] ⇒ Module name ⇒ [Parameter]

Item	CH1
Heater disconnection compensation function	0:OFF
Process alarm alert output enable/disable setting	0:OFF
	1:ON

(4) To clear the disconnection detection status

Disconnection detection is disabled by restoring the disconnection status and turning CH□ Heater disconnection detection (b12 of Un\G5 to Un\G8) from 1 (ON) to 0 (OFF). (☞ Page 346, Appendix 2 (3))

The timing when a heater turns on differs depending on the setting for the following buffer memory areas.

Buffer memory area name	Buffer memory address				Reference
	CH1	CH2	CH3	CH4	
CH□ Control output cycle setting	Un\G47	Un\G79	Un\G111	Un\G143	Page 373, Appendix 2 (23)
CH□ Heating control output cycle setting	Un\G47	Un\G79	Un\G111	Un\G143	
CH□ Cooling control output cycle setting	Un\G722	Un\G738	Un\G754	Un\G770	

8.2.26 Output off-time current error detection function

Standard Heating-cooling

Transistor output errors can be detected using this function. The current sensor (CT) for heater disconnection detection is used to check for errors of when transistor output is off.

A heater current process value and heater disconnection alert current value are compared. If the heater current process value is larger than the heater disconnection alert current value, an output off-time current error occurs. Output off-time current errors are detected every 500ms. When transistor output is off for 500ms or less, output off-time current errors are not detected. (CH□ Output off-time current error (b14 of Un\G5 to Un\G8) stays 0 (OFF).)

( Page 346, Appendix 2 (3))

The following is the timing output as an alert.

- 500ms × Setting value for Heater disconnection/output off-time current error detection delay count (Un\G166)

If an output off-time current error status lasts longer than the time described above, Alarm code (05□A_H) is stored in Error code (Un\G0). ( Page 328, Section 11.7)

(1) Modules where this function can be used

- L60TCTT4BW
- L60TCRT4BW

(2) Setting method

The setting method is the same as that for the heater disconnection detection function. ( Page 221, Section 8.2.25)

8.3 Common Functions

This section explains the common functions between the temperature input mode and temperature control mode.

8.3.1 Moving Averaging Process to a Temperature Process Value (PV)

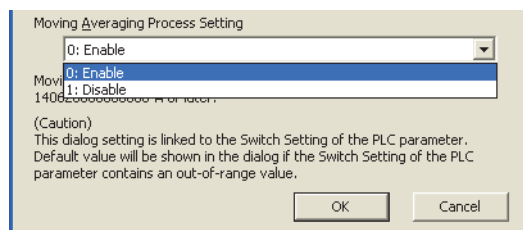
Common

Moving averaging process can be set to a temperature process value (PV). With this function, the fluctuation of temperature process values (PV) can be reduced in electrically noisy environments or in the environments where temperature process values (PV) fluctuate greatly. The moving averaging process can be disabled to hasten the response to the change of temperature process values (PV).

(1) Setting method

Configure the settings as below.

1. Set "0: Enable" to "Moving Averaging Process Setting" in "Switch Setting" to use the moving averaging process.
Set "1: Disable" to "Moving Averaging Process Setting" in "Switch Setting" when not using the moving averaging process.



2. Set the number of moving averaging to "Number of moving averaging".



Buffer memory area name	Buffer memory address				Setting range	Reference
	CH1	CH2	CH3	CH4		
Number of moving averaging	Un\G698	Un\G699	Un\G700	Un\G701	2 to 10 (times) (Default value: 2)	Page 414, Appendix 2 (78)

Point

- When Disable (1) is set to "Moving Averaging Process Setting" in the intelligent function module switch setting, the set value in CH□ Number of moving averaging (Un\G698 to Un\G701) is ignored. When Enable (0) is set to "Moving Averaging Process Setting" in the intelligent function module switch setting, if the value out of the setting range is set to CH□ Number of moving averaging (Un\G698 to Un\G701), a write data error (error code: □□□4_H) occurs.
- For the module, the moving averaging process is enabled and the number of moving averaging is 2 times as default. Change the settings if necessary.

8.3.2 Temperature process value (PV) scaling function

Common

The temperature process value (PV) is scaled up or down to the value in a set range, and can be stored into the buffer memory using this function. For example, the range of -100°C to 100°C can be scaled into the value range of 0 to 4000.

(1) Objects for scaling

CH□ Temperature process value (PV) (Un\G9 to Un\G12) is scaled in general, but setting CH□ Input range (Un\G32, Un\G64, Un\G96, Un\G128) into the 200s allows scaling for the values of other analog modules (such as A/D converter modules) on the system. (☞ Page 355, Appendix 2 (12))

For details, refer to the following.

☞ Page 179, Section 8.2.13 (1)

Point

This section describes objects for scaling as CH□ Temperature process value (PV) (Un\G9 to Un\G12). When scaling input values from other analog modules (such as A/D converter modules), substitute CH□ Temperature process value (PV) (Un\G9 to Un\G12) for CH□ Temperature process value (PV) for input with another analog module (Un\G689 to Un\G692) to set this.

(2) Monitoring the scaling value

The temperature process value (PV) after scaling processing is stored into the following buffer memory area.

- CH□ Process value (PV) scaling value (Un\G728, Un\G744, Un\G760, Un\G776) (☞ Page 416, Appendix 2 (84))

The calculation method of a scaling value is as follows:

$$\begin{array}{l} \text{CH□ Process value (PV) scaling value} \\ \text{(Un\G728, Un\G744, Un\G760, Un\G776)} \end{array} = \frac{(\text{SH} - \text{SL}) \times (\text{Px} - \text{P}_{\text{Min}})}{\text{P}_{\text{Max}} - \text{P}_{\text{Min}}} + \text{SL}$$

Px: CH□ Temperature process value (PV) (Un\G9, Un\G10, Un\G11, Un\G12)

P_{Max}: A maximum value of CH□ Input range (Un\G32, Un\G64, Un\G96, Un\G128)

P_{Min}: A minimum value of CH□ Input range (Un\G32, Un\G64, Un\G96, Un\G128)

SH: CH□ A maximum scaling value of process value (PV) (Un\G727, Un\G743, Un\G759, Un\G775)

SL: CH□ A minimum scaling value of process value (PV) (Un\G726, Un\G742, Un\G758, Un\G774)

(a) Calculation example

A calculation example to scale the temperature process value (PV) into percentage is shown below.

Set the following buffer memory areas as below.

- CH□ Input range (Un\G32, Un\G64, Un\G96, Un\G128): 38 (Temperature measurement range: -200.0°C to 400.0°C)
- CH□ Process value (PV) scaling lower limit value (Un\G726, Un\G742, Un\G758, Un\G774): 0
- CH□ Process value (PV) scaling upper limit value (Un\G727, Un\G743, Un\G759, Un\G775): 100

Suppose that 3600 (360.0°C) is stored in CH□ Temperature process value (PV) (Un\G9 to Un\G12).

The scaling value can be calculated as follows:

$$\begin{aligned}
 \text{CH}\square \text{ Process value (PV) scaling value} &= \frac{(100 - 0) \times (3600 - (-2000))}{4000 - (-2000)} + 0 \\
 (\text{Un}\backslash\text{G728}, \text{Un}\backslash\text{G744}, \text{Un}\backslash\text{G760}, \text{Un}\backslash\text{G776}) &= 93.333 \dots \\
 &= 93 \text{ (All decimal places are rounded off to an integer.)}
 \end{aligned}$$

(3) Setting method

Set the function on "Parameter". Follow the instructions below.

 Project window ⇨ [Intelligent Function Module] ⇨ Module name ⇨ [Parameter]

Item	CH1
Process value (PV) scaling function enable/disable setting	0:Disable
Process value (PV) scaling lower limit value	0:Disable 1:Enable



Item	CH1
Process value (PV) scaling lower limit value	0
Process value (PV) scaling upper limit value	100



End

1. Enable or disable the temperature process value (PV) scaling function under "Process value (PV) scaling function enable/disable setting".

2. Set a scaling upper limit value and lower limit value under "Process value (PV) scaling lower limit value" and "Process value (PV) scaling upper limit value".

Point

- An error does not occur even though the areas above are set as follows: Lower limit value $\geq$ Upper limit value. The scaling is processed according to the calculation method described on  Page 228, Section 8.3.2 (2).
- If a value outside the temperature measurement range is measured, the value set as a upper limit or lower limit is stored into the following buffer memory area.
 - CH□ Process value (PV) scaling value (Un\G728, Un\G744, Un\G760, Un\G776) ( Page 416, Appendix 2 (84))

8.3.3 Sensor correction function

Common

When a difference occurs between the temperature process value (PV) and the actual temperature due to reasons such as a measuring condition, the difference can be corrected using this function. The following two types are available.

- Normal sensor correction (one-point correction) function (☞ Page 230, Section 8.3.3 (1))
- Sensor two-point correction function (☞ Page 234, Section 8.3.3 (2))

(1) Normal sensor correction (one-point correction) function

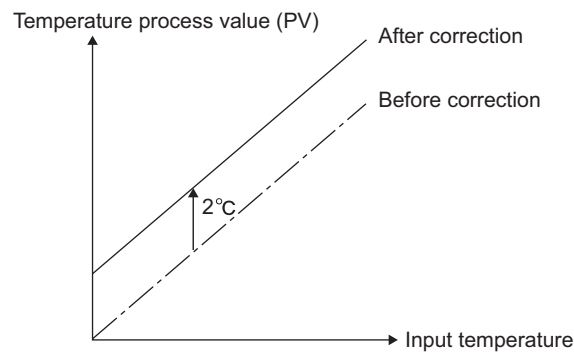
This function corrects a temperature correction value, the proportion of the temperature difference to the fullscale set input range.

Set a correction value to CH□ Sensor correction value setting (Un\G45, Un\G77, Un\G109, Un\G141).

Ex. When the temperature measurement range of input range is set to -200.0°C to 200.0°C with the actual temperature being 60°C and the temperature process value (PV) being 58°C

$$\begin{aligned}\text{Sensor compensation value setting} &= 100 \times \frac{(\text{Actual temperature} - \text{Temperature process value (PV)})}{\text{Full scale}} \\ &= 100 \times \frac{2}{400} = 0.5 (\%) \end{aligned}$$

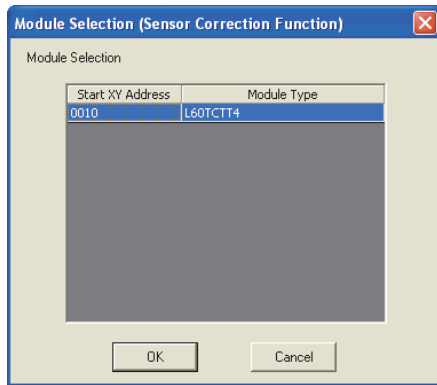
Based on the above formula, set 50 (0.50%) to CH□ Sensor correction value setting (Un\G45, Un\G77, Un\G109, Un\G141).



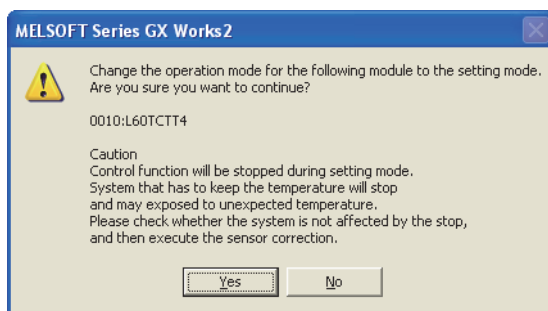
(a) How to execute normal sensor correction (one-point correction) (when using GX Works2)

Set this function on the "Sensor Correction Function" window.

[Tool] ⇒ [Intelligent Function Module Tool] ⇒ [Temperature Control Module]
⇒ [Sensor Correction Function...]



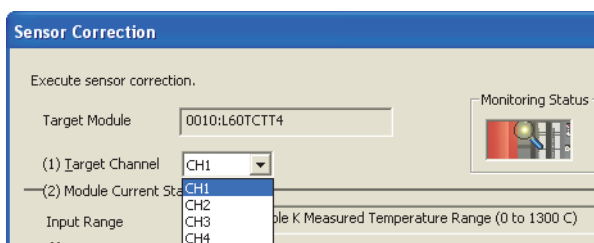
1. Select the module where sensor correction is executed and click .



2. Click .



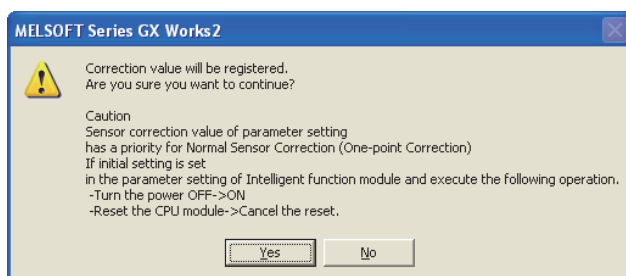
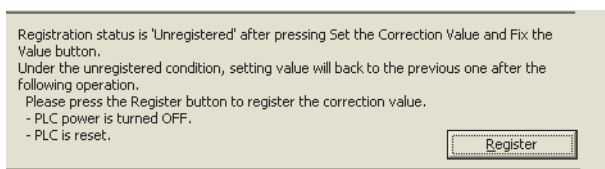
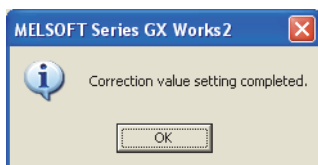
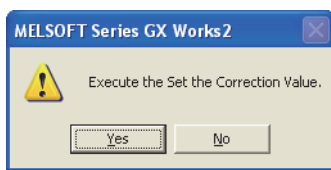
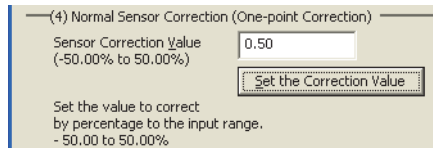
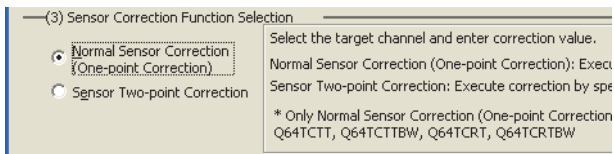
3. Click .



4. Select the channel where sensor correction is executed under "Target Channel".

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5. Select "Normal Sensor Correction (One-point Correction)" under "Sensor Correction Function Selection".

6. Set "Sensor Correction Value" and click



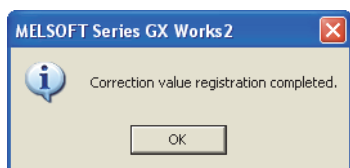
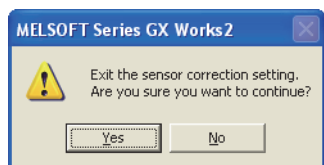
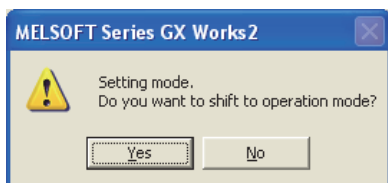
7. Click

8. Click

9. To back up the correction value in the non-volatile memory, click

10. Click

(From the previous page)

11. Click .12. Click .13. Click .14. Click .

End

Remark

The value set in "Sensor correction value setting" on the "Parameter" window of GX Works2 has a priority over the correction value obtained by step 8, if the initial settings are set on the "Parameter" window and the following operation is executed.

- Turn off and on the power.
- Reset the CPU module and cancel the reset.

To use the correction value obtained by step 8 after executing the above operation, correct the value set in "Sensor correction value setting" on the "Parameter" window.

Before correcting the value, check the operation temporarily following the contents obtained by step 8.

For the setting in "Parameter", refer to the following.

Page 112, Section 7.3

(b) How to execute normal sensor correction (one-point correction) (when using the program)

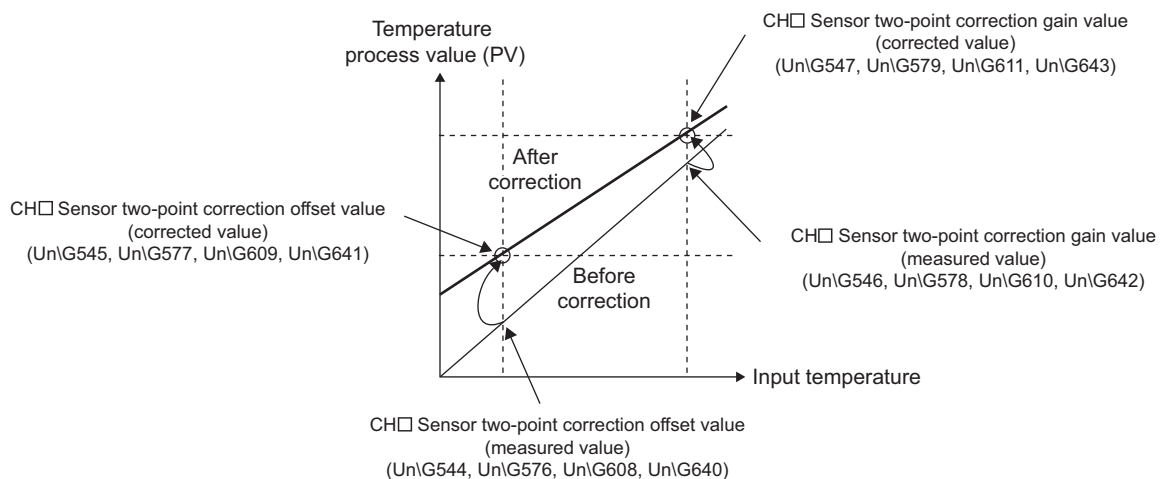
Follow the instructions below.

1. Set Normal sensor correction (one-point correction) (0_H) in Sensor correction function selection (Un\G785). (Page 423, Appendix 2 (93))
2. Set the correction value in CH□ Sensor correction value setting (Un\G45, Un\G77, Un\G109, Un\G141). (Page 372, Appendix 2 (21))

(2) Sensor two-point correction function

With this function, the difference between the temperature process value (PV) and the actual temperature between the two points selected in advance (a corrected offset value and a corrected gain value) is stored. Based on this gradient, the difference between a sensor and the actual temperature is corrected.

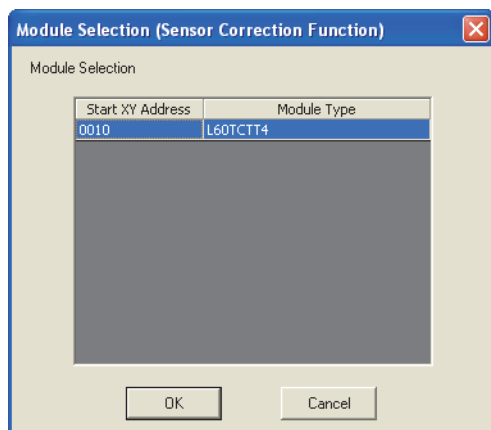
Sensor two-point correction is performed in the setting mode (Setting/operation mode status (Xn1): off). In addition, set CH□ Stop mode setting (Un\G33, Un\G65, Un\G97, Un\G129) to Monitor (1).



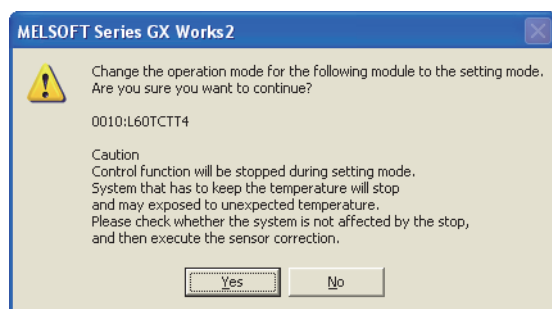
(a) How to execute sensor two-point correction (when using GX Works2)

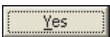
Set this function on the "Sensor Correction Function" window.

 [Tool] ⇒ [Intelligent Function Module Tool] ⇒ [Temperature Control Module]
⇒ [Sensor Correction Function...]



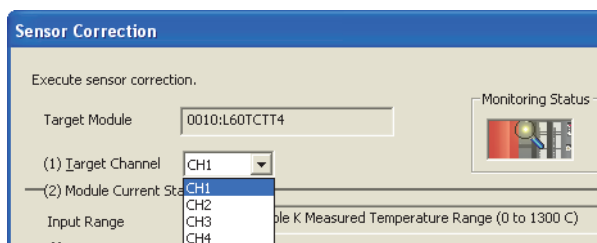
1. Select the module where sensor correction is executed and click .



2. Click .



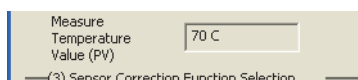
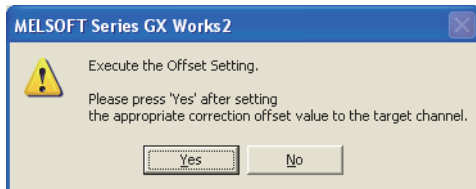
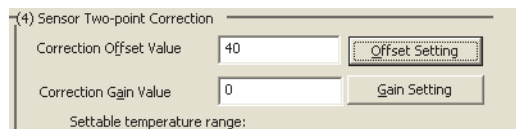
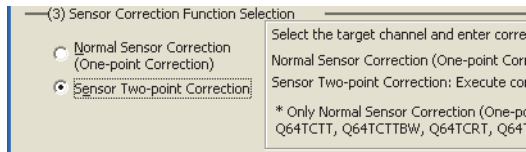
3. Click .



4. Select the channel where sensor correction is executed under "Target Channel".

(To the next page)

(From the previous page)



(To the next page)

5. Select "Sensor Two-point Correction" under "Sensor Correction Function Selection".

6. Monitor "Measure Temperature Value (PV)" and enter the corrected offset value.*1

7. Set the temperature process value (PV) to be input under "Correction Offset Value". Then click

Offset Setting.

8. Click **Yes**.

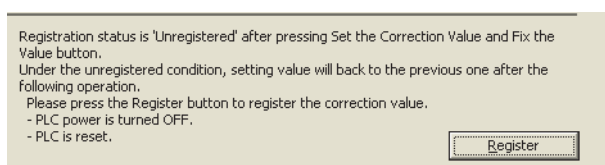
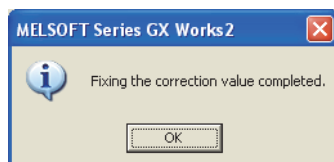
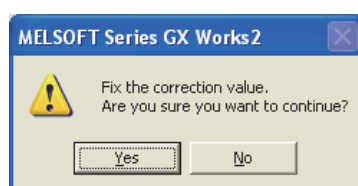
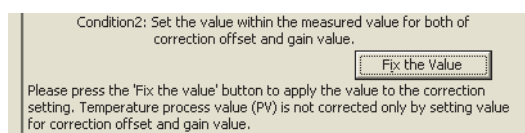
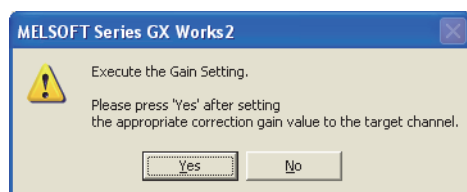
9. Click **OK**.

10. Monitor "Measure Temperature Value (PV)" and enter the corrected gain value.*1

11. Set the temperature process value (PV) to be input under "Correction Gain Value". Then click

Gain Setting.

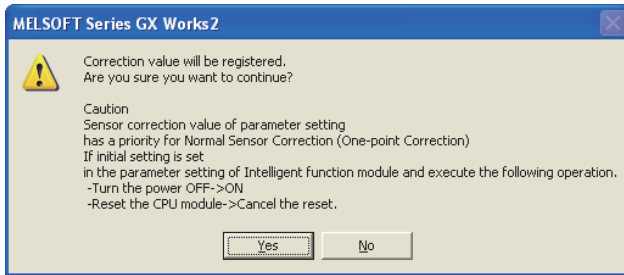
(From the previous page)



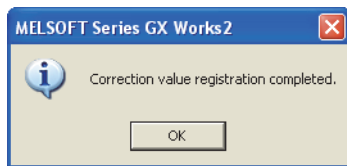
(To the next page)

12. Click .**13.** Click .**14.** Click .**15.** Click .**16.** Click .**17.** To back up the correction value in the non-volatile memory, click .

(From the previous page)



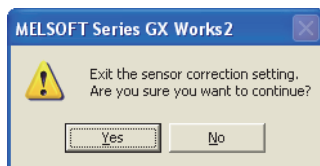
18. Click .



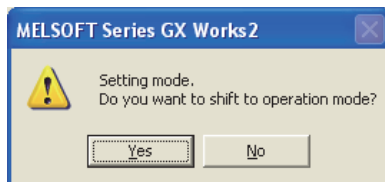
19. Click .



20. Click .



21. Click .



22. To shift from the setting mode to the operation mode, click .

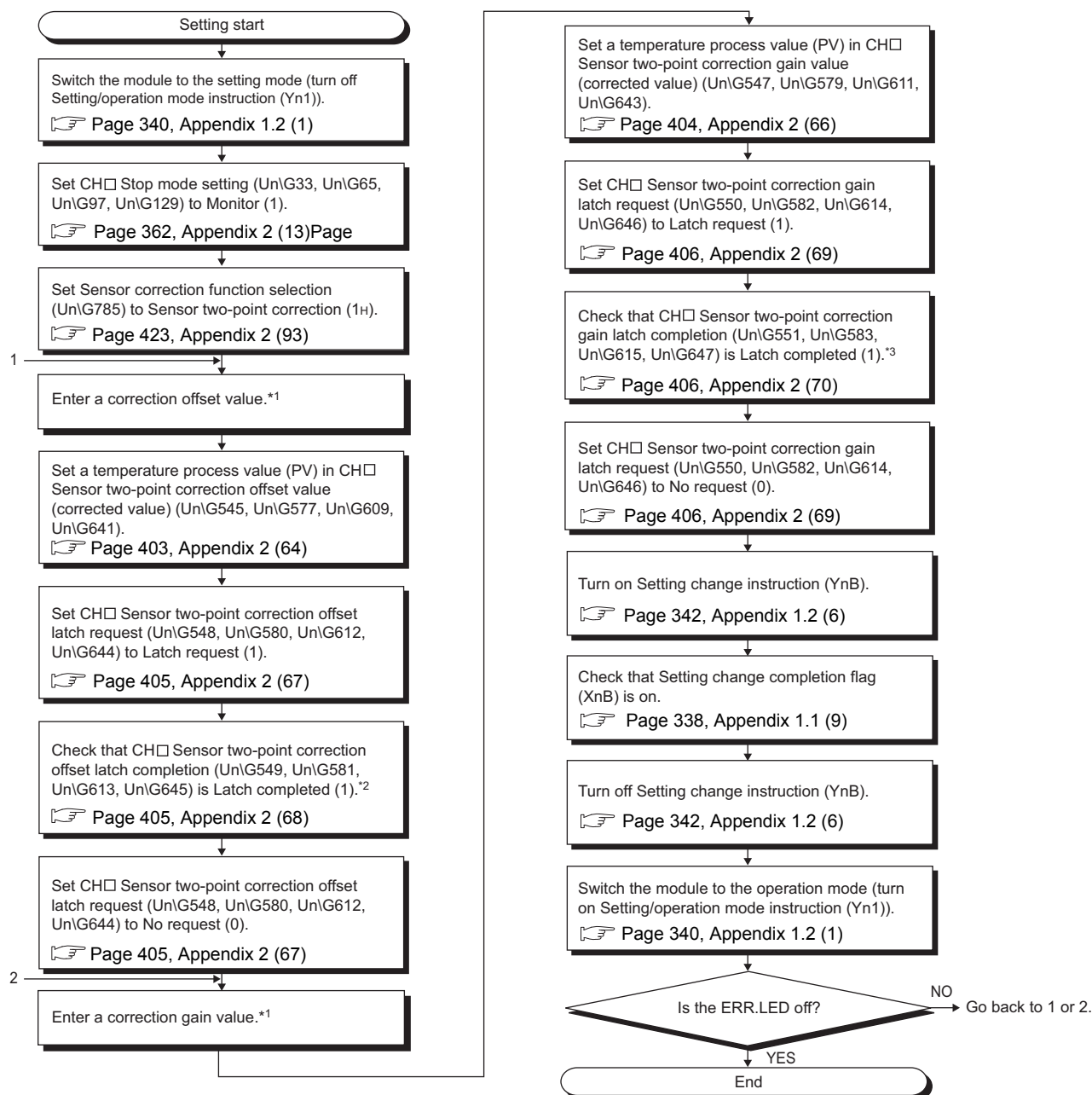


End

- *1 Enter the value using devices such as a thermocouple, platinum resistance thermometer, and standard DC voltage generator, or based on a general resistance value.

(b) How to execute sensor two-point correction (when using the program)

Follow the instructions below.



- *1 Enter the value using devices such as a thermocouple, platinum resistance thermometer, and standard DC voltage generator, or based on a general resistance value.
- *2 When the latch is completed, the temperature process value (PV) is stored in CH□ Sensor two-point correction offset value (measured value) (Un\G544, Un\G576, Un\G608, Un\G640). (☞ Page 403, Appendix 2 (63))
- *3 When the latch is completed, the temperature process value (PV) is stored in CH□ Sensor two-point correction gain value (measured value) (Un\G546, Un\G578, Un\G610, Un\G642). (☞ Page 404, Appendix 2 (65))

-
- If a write data error (error code: □□□7_H) occurs during sensor two-point correction, correctly configure the setting for sensor two-point correction again. (The value set for sensor two-point correction of when an error occurred is not written in the L60TC4.)
 - To use the value set for sensor two-point correction even after the power is turned off and on or the CPU module is reset and the reset is cancelled, back up the value with the following method.
 - Turn off and on Set value backup instruction (Yn8). ( Page 342, Appendix 1.2 (4))
-

8.3.4 Auto-setting at input range change

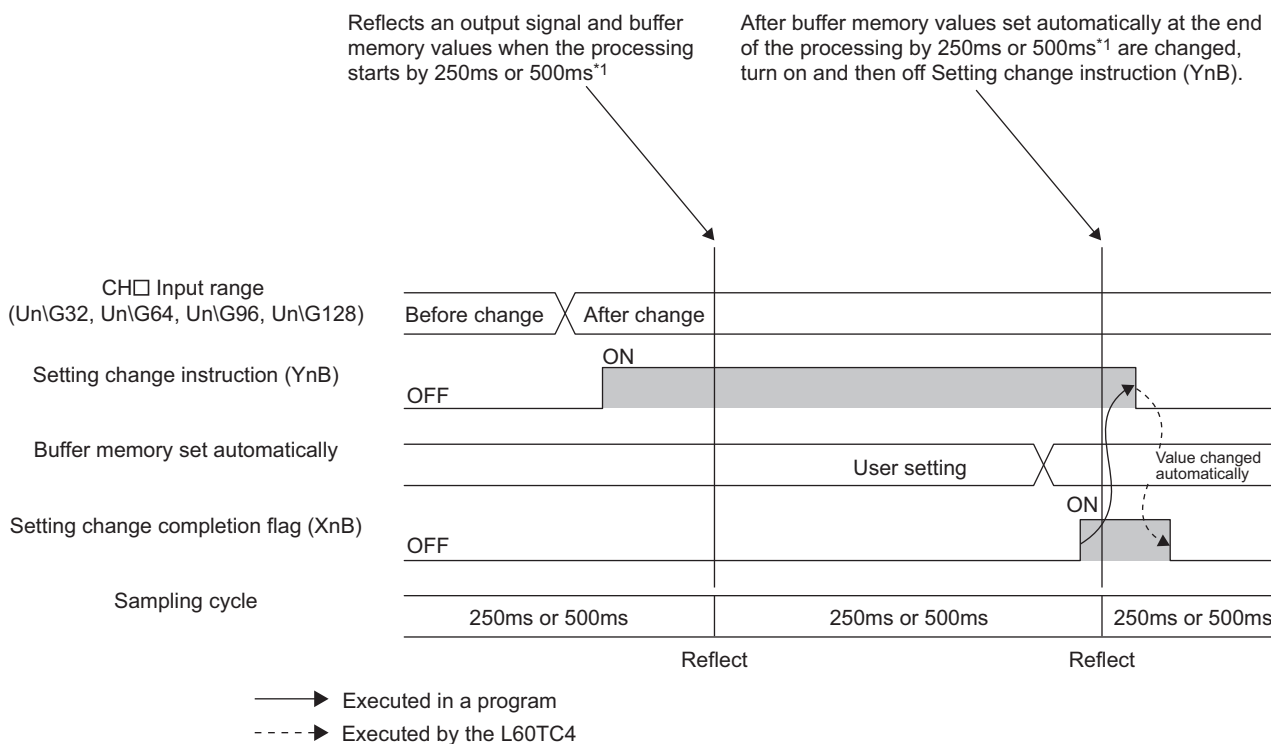
Common

When an input range is changed, using this function automatically changes related buffer memory data to prevent an error outside the setting range. Set the function on the "Switch Setting" window.

For details on the setting method, refer to the following.

☞ Page 110, Section 7.2

The following is the setting timing.



*1 This value differs depending on the setting under "Sampling Cycle Selection". (☞ Page 111, Section 7.2 (1) (b))

(1) Buffer memory automatically set

Refer to ☞ Page 360, Appendix 2 (12) (d).

8.3.5 Buffer memory data backup function

Common

This function allows buffer memory data to be stored in the non-volatile memory and backed up.

The backed-up data is transferred from the non-volatile memory to the buffer memory when the power is turned off and on or the CPU module is reset and the reset is cancelled. Therefore, temperature can be controlled without writing data when the power is turned off and on or the CPU module is reset and the reset is cancelled.

(1) Applicable buffer memory areas

Refer to the buffer memory assignment list.

☞ Page 45, Section 3.5

(2) Data write to non-volatile memory

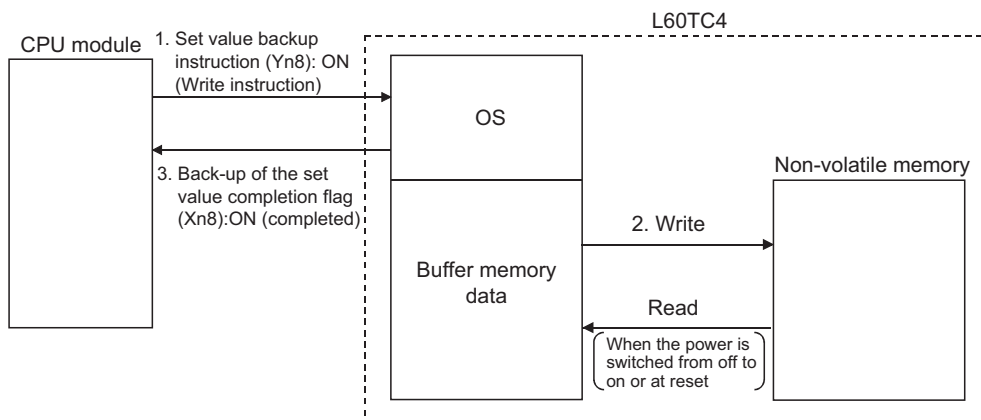
This function can be used to back up data directly written in the buffer memory using the PID constants set with the auto tuning function and the programming tool. When data is written to non-volatile memory and the power is turned off and on or the CPU module is reset and the reset is cancelled, the buffer memory setting value is not required to be set again.

Point

For the function that allows PID constants to be automatically backed up after auto tuning, refer to ☞ Page 147, Section 8.2.7 (4).

To write data to non-volatile memory, turn off and on Set value backup instruction (Yn8).

When data write to the non-volatile memory is completed, Back-up of the set value completion flag (Xn8) turns on.



If data write to non-volatile memory does not complete, Back-up of the set value fail flag (XnA) turns on.

(a) Setting change

Change the settings for buffer memory areas when Back-up of the set value completion flag (Xn8) is off.

(3) Data read from non-volatile memory

Follow the instructions below.

- Turn off and on the power or reset the CPU module and cancel the reset.
- Set CH□ Memory's PID constants read instruction (Un\G62, Un\G94, Un\G126, Un\G158) to Requested (1).
( Page 386, Appendix 2 (36)) Data to be read are the PID constants and loop disconnection detection judgment time for the corresponding channel only. ( Page 383, Appendix 2 (33))

(4) Precaution when executing the set value backup function

By executing this function, data are transferred to the buffer memory when the power is turned off and on or the CPU module is reset and the reset is cancelled. This transferred data can be overwritten by setting parameters on GX Works2.

To use the set values stored as backup data of the initial settings of the module, take either of following actions.

- Do not set parameters on GX Works2.
- When setting parameters on GX Works2, correct the set values of parameters to the ones stored as backup data, and write the parameters to the CPU module.

8.3.6 Error history function

Common

The error or alert occurred with the L60TC4 is stored in the buffer memory areas (Un\G1280 to Un\G1404) as history. Up to 16 error history data can be stored.

(1) Processing of the error history function

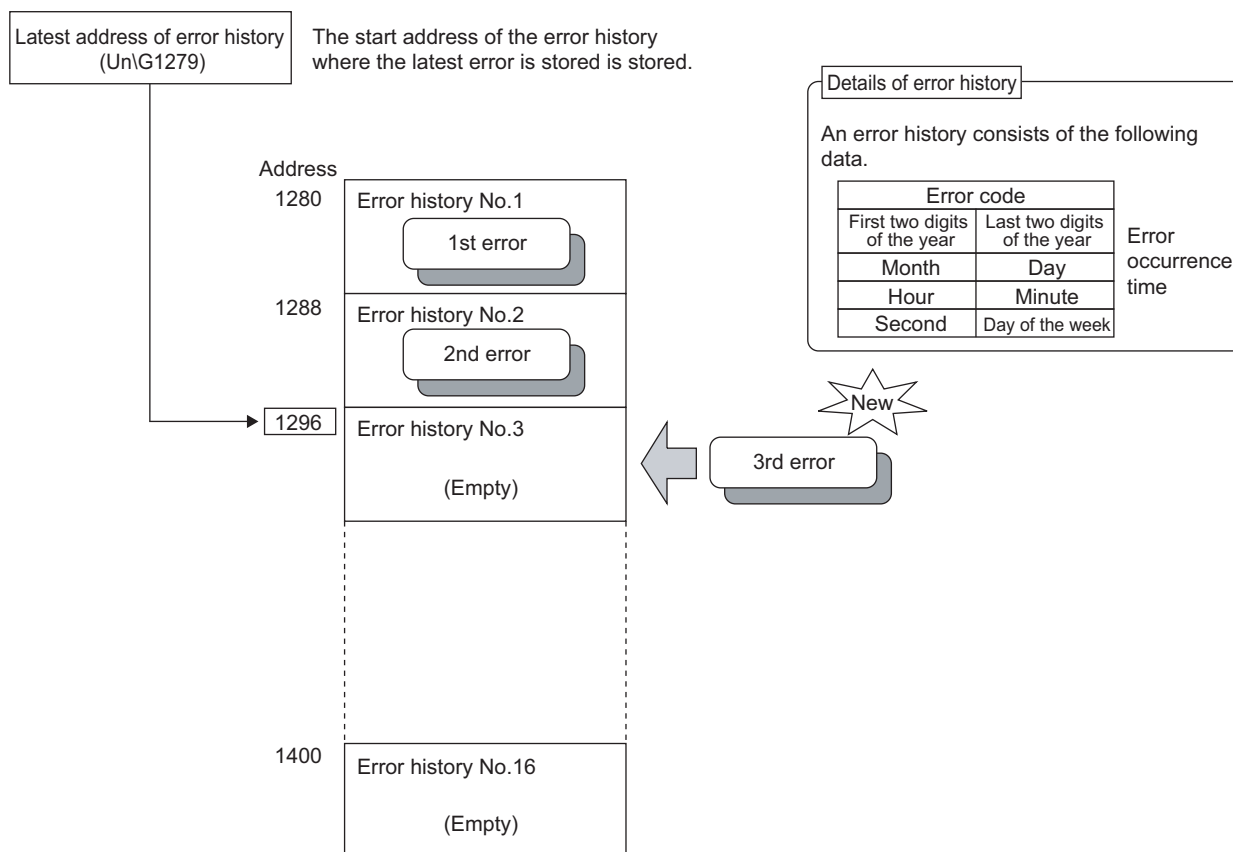
An error code and error occurrence time are stored starting from Error history No.1 (the start address is Un\G1280).

(2) How to check error history

The start address of the error history where the latest error is stored can be checked in Latest address of error history (Un\G1279).

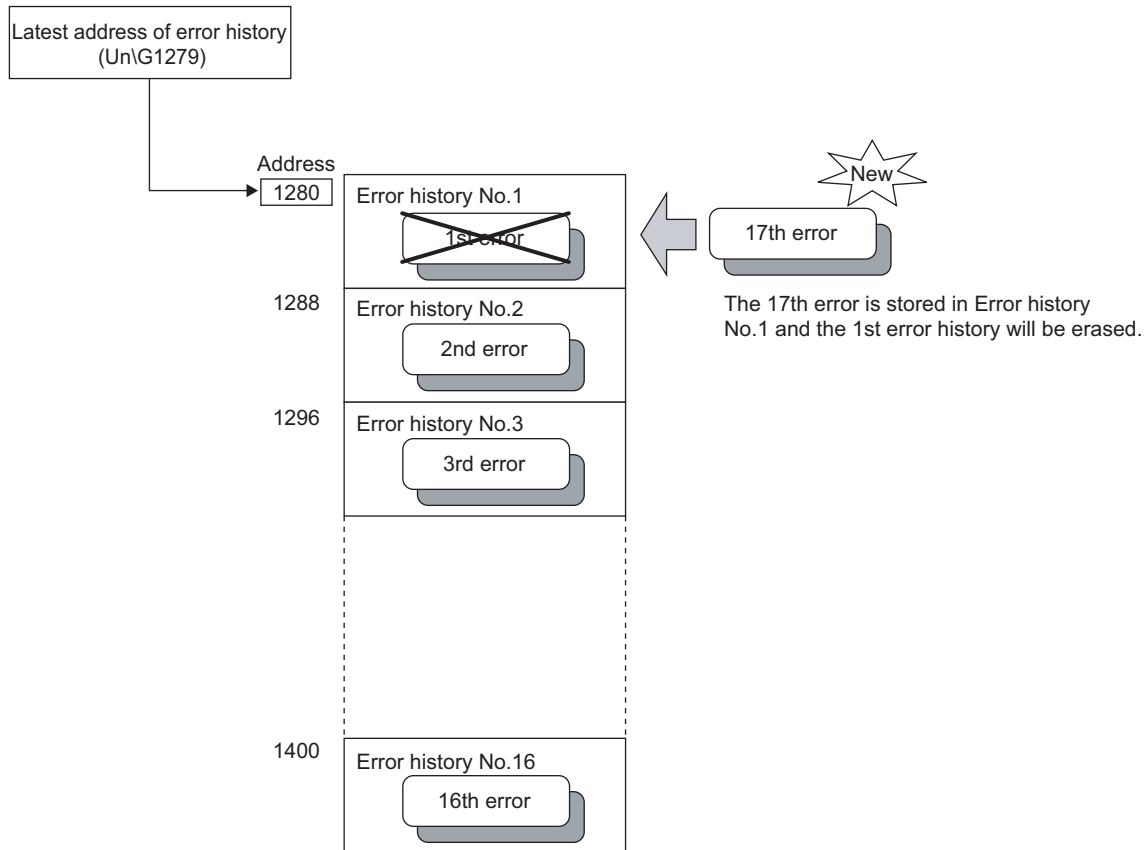
Ex. If the third error occurred:

The third error is stored in Error history No.3 and 1296 (the start address of Error history No.3) is stored in Latest address of error history (Un\G1279).



Ex. If the 17th error occurred:

The 17th error is stored in Error history No.1 and 1280 (the start address of Error history No.1) is overwritten in Latest address of error history (Un\G1279).



Point

- The same processing is performed for an alarm.
- When the storage area for error histories is full, data is overwritten starting from Error history No.1 (Un\G1280 to Un\G1284) and error history recording is continued. (The history before data overwritten is deleted.)
- Recorded error histories are cleared to 0 by turning off and on the power supply or by resetting the CPU module and canceling the reset.

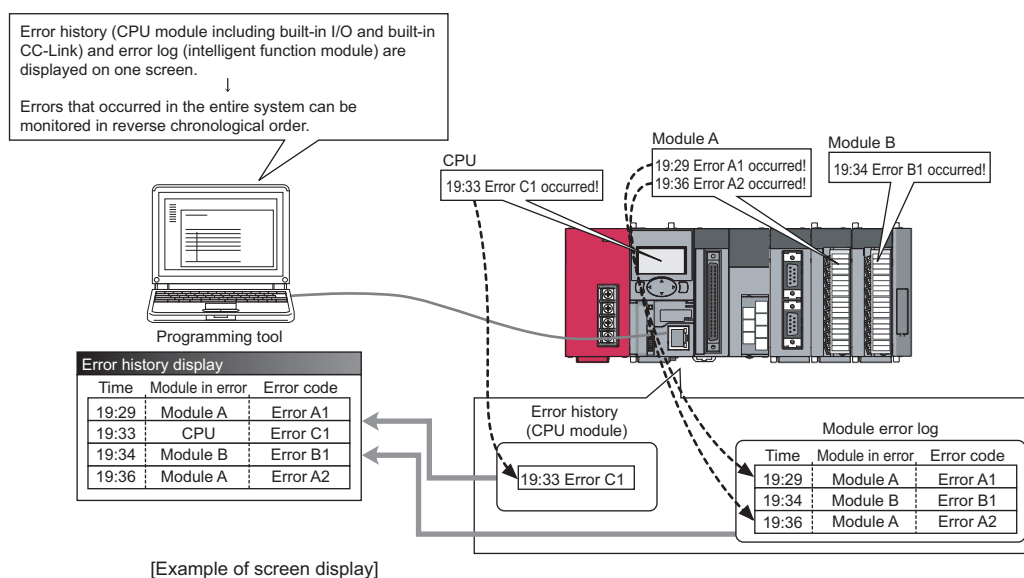
8.3.7 Module error history collection function

Common

The errors and alarms occurred with the L60TC4 are collected into the CPU module.

The CPU module keeps the error information collected from the L60TC4 as a module error history in the memory where data is maintained even at the time of the power failure. Therefore, the information of the errors occurred with the L60TC4 can be kept even if the power is turned off and on or the CPU module is reset and the reset is cancelled.

(1) Example of the operation of the module error history collection function



No.	✓	Error Code	Date and Time	Model Name	Start I/O
00125		0070	2009/12/10 17:02:37	L60AD4	0030
00124		0070	2009/12/10 17:00:05	L60AD4	0030
00123		0CE4	2009/12/10 17:00:04	L26CPU-BT	----
00122		05DC	2009/12/10 16:15:50	L26CPU-BT	----
00121		0070	2009/12/10 15:59:30	L60DA4	0030
00120		0070	2009/12/10 15:45:02	L60DA4	0010
00119		05DC	2009/12/10 14:14:38	L26CPU-BT	----
00118		0070	2009/12/10 14:12:03	L60DA4	0010
00117		0CE4	2009/12/10 13:59:54	L26CPU-BT	----
00116		0CE4	2009/12/10 13:35:11	L26CPU-BT	----
00115		05DC	2009/12/10 11:11:45	L26CPU-BT	----
00114		0070	2009/12/10 11:07:05	L60AD4	0010
00113		0CE4	2009/12/10 11:07:04	L26CPU-BT	----
00112		0070	2009/12/10 11:03:49	L60AD4	0010
00111		0CE4	2009/12/10 11:03:48	L26CPU-BT	----
00110		05DC	2009/12/09 16:30:58	L26CPU-BT	----
00109		0070	2009/12/09 16:29:33	L60DA4	0010
00108		0070	2009/12/09 16:29:12	L60DA4	0010
00107		083B	2009/12/09 16:29:11	L26CPU-BT	----



For details on the module error history collection function, refer to the following.

MELSEC-L CPU Module User's Manual (Function Explanation, Program Fundamentals)

8.3.8 Error clear function

Common

When an error occurs, the error can be cleared on the system monitor.

Clicking the **Error Clear** button on the system monitor clears the error code stored in Error code (Un\G0) and turns off the ERR.LED. The operation is the same as when an error is cleared using Error reset instruction (Yn2). However, the error history is not cleared.

For how to clear an error using Error reset instruction (Yn2), refer to the following.

- Error reset instruction (Yn2) (👉 Page 341, Appendix 1.2 (2))

👉 [Diagnostics] ⇨ [System Monitor...] ⇨ The module where an error occurred

Module's Detailed Information

Monitor Status: Monitoring

Module Information:

Module	
Model Name	L60TCTT4
I/O Address	0010
Mount Position	Main block 0th slot
Product Information	13041000000000-A
Production Number	---

Module Information:

Module Access	Possible
Status of External Power Supply	---
Fuse Blown Status	---
Status of I/O Address Verify	Agree
I/O Clear / Hold Setting	---
Noise Filter Setting	---
Input Type	---
Remote Password Setting Status	---

Error Information

Latest Error Code: 02B5

Update Error History

Clear Error History

Error Clear

Display Format: ☒ HEX ☐ DEC

No.	Error Code
1	02B5
2	0392
3	02B5

The error history is sequentially displayed from an old error. The latest error is displayed at the bottom line.

Error and Solution

Contents: The setting of the upper/lower limit value output limiter or the upper/lower limit setting limiter is invalid.

Solution: Set the value where the upper limit value is greater than the lower limit value.

Stop Monitor Close

CHAPTER 9 DISPLAY UNIT

This chapter describes the functions of the display unit that can be used with the L60TC4.
For details on how to operate the display unit, the functions, and menu structure, refer to the following.

 MELSEC-L CPU Module User's Manual (Function Explanation, Program Fundamentals)

9.1 Display Unit

The display unit is an LCD display to be attached to the CPU module. By attaching it to the CPU module, the following operations can be performed without using any software package.

- Checking the system status
- Changing system set values (only for use as a temperature input module)

When a problem occurs, the cause of the problem can be identified by the displayed error information.
For details on how to check and clear errors from the display unit, refer to the following.

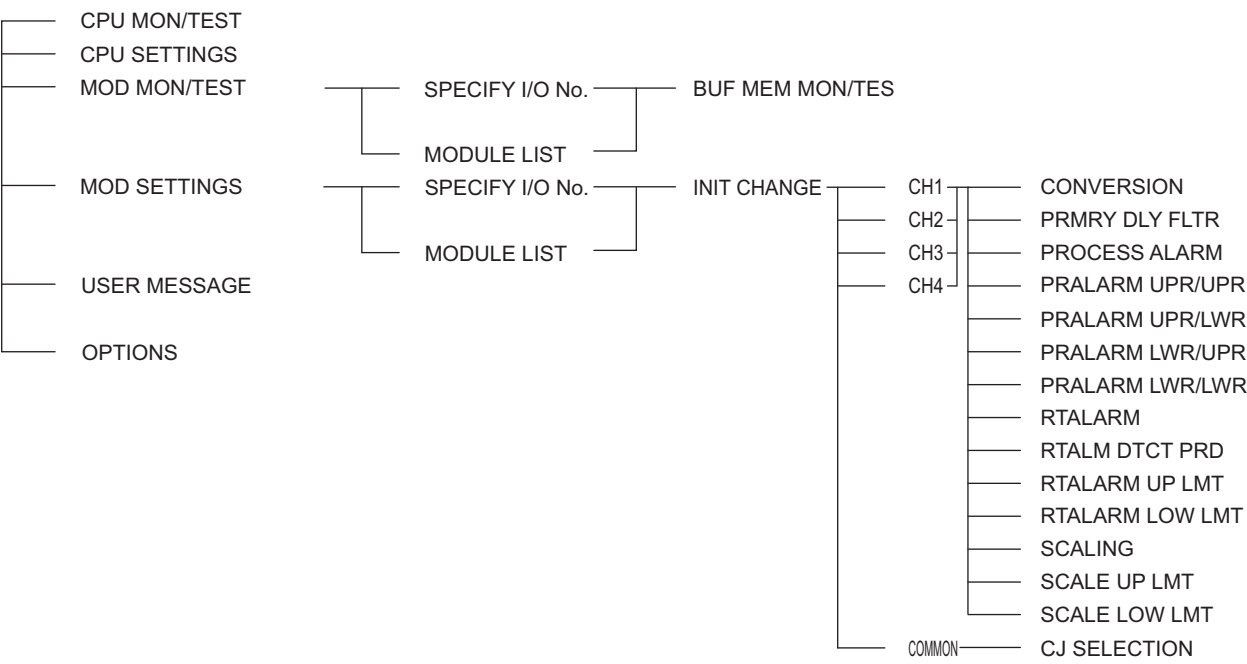
- Checking and clearing errors ( Page 255, Section 9.4)

Remark
To change system setting values in temperature control mode, use GX Works2. ( Page 109, CHAPTER 7)
.....

9.2 Menu Transition

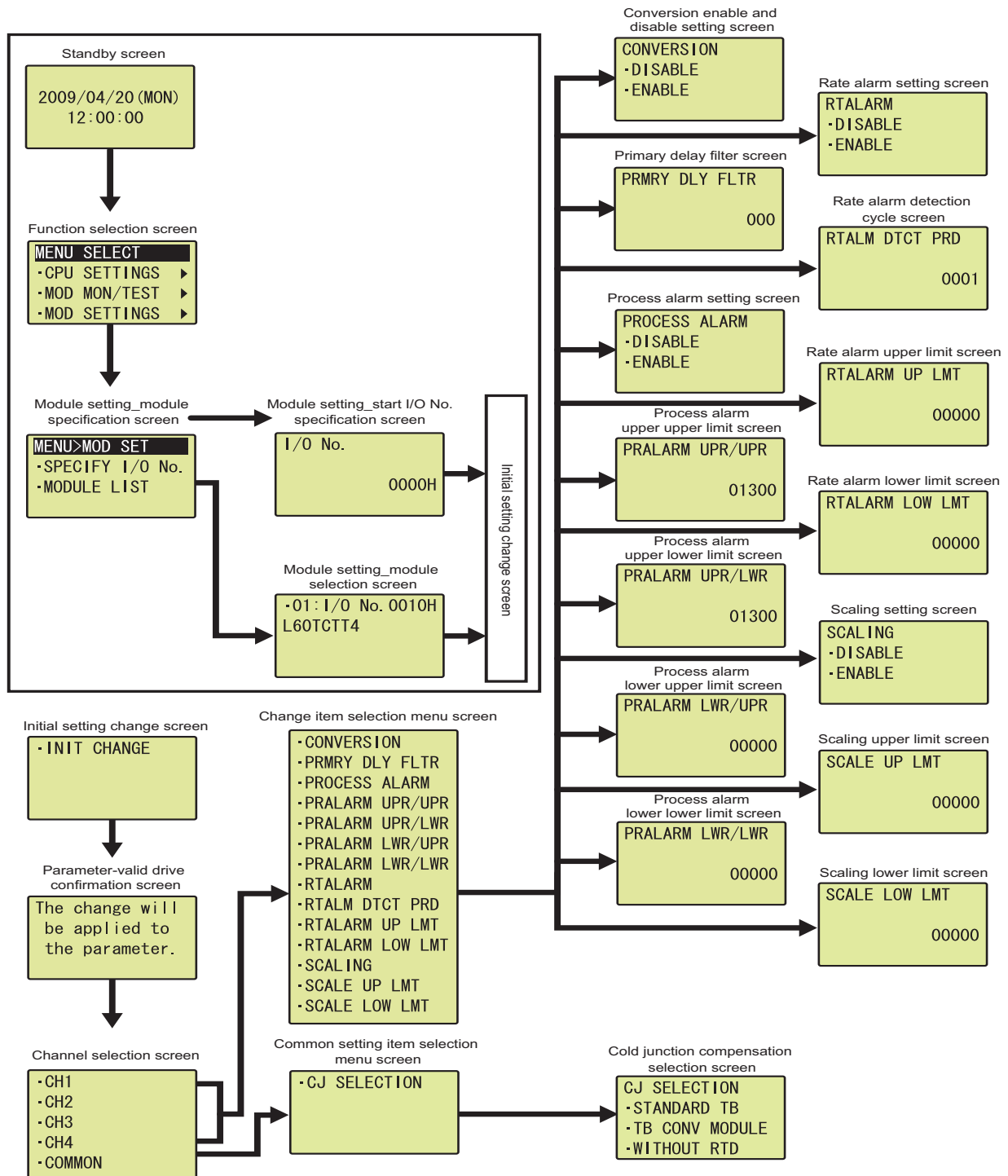
(1) Structure list

The following is the menu structure of "MOD MON/TEST" menu and "MOD SETTINGS" menu.



(2) Screen transition to the initial setting change screen

The following figure shows the screen transition to the initial setting change screen.



9.3 Setting Value Change Screen List

The following table shows the setting value change screen list.

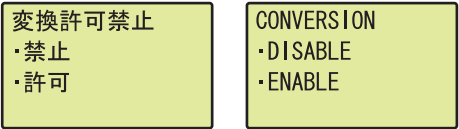
(1) Displayed in English

Name		Screen format	Input limits	
Setting item	Screen display		Upper limit value	Lower limit value
Conversion enable/disable setting	CONVERSION	Selection	—	—
Primary delay digital filter setting	PRMRY DLY FLTR	Numeric	100	0
Process alarm alert output enable/disable setting	PROCESS ALARM	Selection	—	—
Process alarm upper upper limit value	PRALARM UPR/UPR	Numeric	32767	-32768
Process alarm upper lower limit value	PRALARM UPR/LWR	Numeric	32767	-32768
Process alarm lower upper limit value	PRALARM LWR/UPR	Numeric	32767	-32768
Process alarm lower lower limit value	PRALARM LWR/LWR	Numeric	32767	-32768
Rate alarm alert output enable/disable setting	RTALARM	Selection	—	—
Rate alarm alert detection period	RTALM DTCT PRD	Numeric	6000	1
Rate alarm upper limit value	RTALARM UP LMT	Numeric	32767	-32768
Rate alarm lower limit value	RTALARM LOW LMT	Numeric	32767	-32768
Process value (PV) scaling function enable/disable setting	SCALING	Selection	—	—
Process value (PV) scaling upper limit value	SCALE UP LMT	Numeric	32000	-32000
Process value (PV) scaling lower limit value	SCALE LOW LMT	Numeric	32000	-32000
Cold junction temperature compensation selection	CJ SELECTION	Selection	—	—

(2) Conversion enable/disable setting

Select "DISABLE" or "ENABLE" in the "Conversion enable and disable setting" screen.

"Conversion enable and disable setting" screen

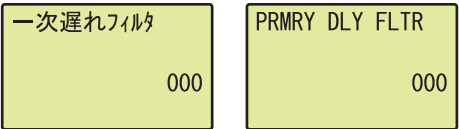


1. Use the ▲ and ▼ buttons to select "DISABLE" or "ENABLE", then make a confirmation with the button.

(3) Primary delay digital filter setting

Set the time constant for the primary delay digital filter in the "Primary delay filter" screen.

"Primary delay filter" screen



1. Move the cursor using the ◀ and ▶ buttons, then increment or decrement the value at the cursor, using the ▲ and ▼ buttons, respectively. Make a confirmation with the button.

Table of input items

Input item	Input range	
	Input upper limit	Input lower limit
Primary delay filter	100	0

(4) Process alarm setting

Select "DISABLE" or "ENABLE" in the "Process alarm setting" screen.

"Process alarm setting" screen

プロセスアラーム設定 ・禁止 ・許可	PROCESS ALARM ・DISABLE ・ENABLE



"Process alarm upper upper limit" screen

プロセスアラーム上上限 01300	PRALARM UPR/UPR 01300



"Process alarm upper lower limit" screen

プロセスアラーム上下限 01300	PRALARM UPR/LWR 01300



"Process alarm lower upper limit" screen

プロセスアラーム下上限 00000	PRALARM LWR/UPR 00000



"Process alarm lower lower limit" screen

プロセスアラーム下下限 00000	PRALARM LWR/LWR 00000

1. Use the ▲ and ▼ buttons to select "DISABLE" or "ENABLE", then make a confirmation with the  button. (If "ENABLE" is selected, proceed to step 2.)
2. Move the cursor using the ◀ and ▶ buttons, then increment or decrement the value at the cursor, using the ▲ and ▼ buttons, respectively. Make a confirmation with the  button.
3. Move the cursor using the ◀ and ▶ buttons, then increment or decrement the value at the cursor, using the ▲ and ▼ buttons, respectively. Make a confirmation with the  button.
4. Move the cursor using the ◀ and ▶ buttons, then increment or decrement the value at the cursor, using the ▲ and ▼ buttons, respectively. Make a confirmation with the  button.
5. Move the cursor using the ◀ and ▶ buttons, then increment or decrement the value at the cursor, using the ▲ and ▼ buttons, respectively. Make a confirmation with the  button.

Table of input items

Input item	Input range	
	Input upper limit	Input lower limit
Process alarm upper upper limit	32767	-32768
Process alarm upper lower limit		
Process alarm lower upper limit		
Process alarm lower lower limit		

(5) Rate alarm setting

Select "DISABLE" or "ENABLE" in the "Rate alarm setting" screen.

"Rate alarm setting" screen

レートアラーム設定 ・禁止 ・許可	RTALARM ・DISABLE ・ENABLE



"Rate alarm detection period" screen

レートアラーム検出周期 0001	RTALM DTCT PRD 0001



"Rate alarm upper limit" screen

レートアラーム上限 00000	RTALARM UP LMT 00000



"Rate alarm lower limit" screen

レートアラーム下限 00000	RTALARM LOW LMT 00000

1. Use the ▲ and ▼ buttons to select "DISABLE" or "ENABLE", then make a confirmation with the  button. (If "ENABLE" is selected, proceed to step 2.)
2. Move the cursor using the ◀ and ▶ buttons, then increment or decrement the value at the cursor, using the ▲ and ▼ buttons, respectively. Make a confirmation with the  button.
3. Move the cursor using the ◀ and ▶ buttons, then increment or decrement the value at the cursor, using the ▲ and ▼ buttons, respectively. Make a confirmation with the  button.
4. Move the cursor using the ◀ and ▶ buttons, then increment or decrement the value at the cursor, using the ▲ and ▼ buttons, respectively. Make a confirmation with the  button.

Table of input items

Input item	Input range	
	Input upper limit	Input lower limit
Rate alarm detection period	6000	1
Rate alarm upper limit	32767	-32768
Rate alarm lower limit		

(6) Scaling setting

Select "DISABLE" or "ENABLE" in the "Scaling setting" screen.

"Scaling setting" screen

スケーリング 設定 ・無効 ・有効	SCALING ・DISABLE ・ENABLE



"Scaling upper limit" screen

スケーリング 上限 00000	SCALE UP LMT 00000



"Scaling lower limit" screen

スケーリング 下限 00000	SCALE LOW LMT 00000

1. Use the ▲ and ▼ buttons to select "DISABLE" or "ENABLE", then make a confirmation with the  button. (If "ENABLE" is selected, proceed to step 2.)
2. Move the cursor using the ◀ and ▶ buttons, then increment or decrement the value at the cursor, using the ▲ and ▼ buttons, respectively. Make a confirmation with the  button.
3. Move the cursor using the ◀ and ▶ buttons, then increment or decrement the value at the cursor, using the ▲ and ▼ buttons, respectively. Make a confirmation with the  button.

Table of input items

Input item	Input range	
	Input upper limit	Input lower limit
Scaling upper limit	32000	-32000
Scaling lower limit		

(7) Cold junction compensation selection

Select "STANDARD TB" or "WITHOUT RTD" in the "Cold junction compensation selection" screen.

"Cold junction compensation selection" screen

冷接点補償選択 ・標準端子台 ・端子台変換ユニット ・使用しない	CJ SELECTION ・STANDARD TB ・TB CONV MODULE ・WITHOUT RTD

1. Use the ▲ and ▼ buttons to select "STANDARD TB" or "WITHOUT RTD", then make a confirmation with the  button. ("TB CONV MODULE" cannot be used.)

9.4 Checking and Clearing Errors

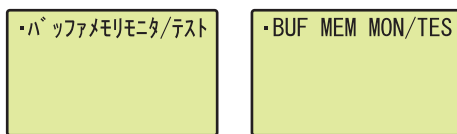
By operation from the display unit, the error that occurred in the L60TC4 can be checked. The error that is occurring can also be cleared.

(1) Checking the error

The error that occurred in the L60TC4 can be checked by specifying the error code (Un\G0) from "Buffer memory monitor/test".

Ex. When an error occurred in the L60TC4 with the start I/O number 1

"Buffer memory monitor/test" screen



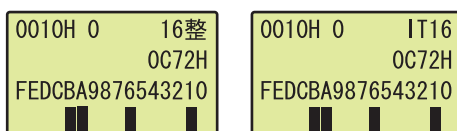
"Buffer memory address input format selection" screen



"Buffer memory address setting" screen



"Buffer memory monitor" screen



1. Press the **OK** button.

2. Use the **▲** and **▼** buttons to select "DEC" for the input format of the buffer memory address, then make a confirmation with the **OK** button.

3. Move the cursor using the **◀** and **▶** buttons, then increment or decrement the value at the cursor, using the **▲** and **▼** buttons, and set the value to 0. Make a confirmation with the **OK** button.

4. The error that occurred can be checked in the "Buffer memory monitor" screen.

(2) Clearing the error

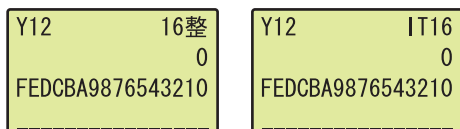
To clear the error, remove the error cause and turn Error clear request (Yn2) off, on, and off from "Device monitor/test".

Ex. When an error occurred in the L60TC4 with the start I/O number 1

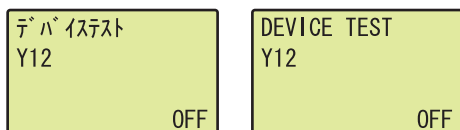
"CPU monitor/test" screen



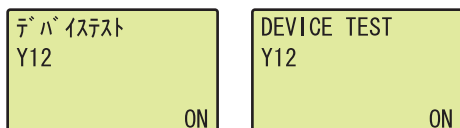
"Device monitor" screen



"Device test check" screen



"Device test" screen



1. Use the ▲ and ▼ buttons to select "DEV MON/TEST", then make a confirmation with the **OK** button.
2. Set the device to Y and press the **OK** button.
3. Use the ▲ and ▼ buttons to set the device to Y12, then make a confirmation with the **OK** button.
4. Use the ▲ and ▼ buttons to switch ON/OFF. Press the **OK** button to set the value set in the device test.

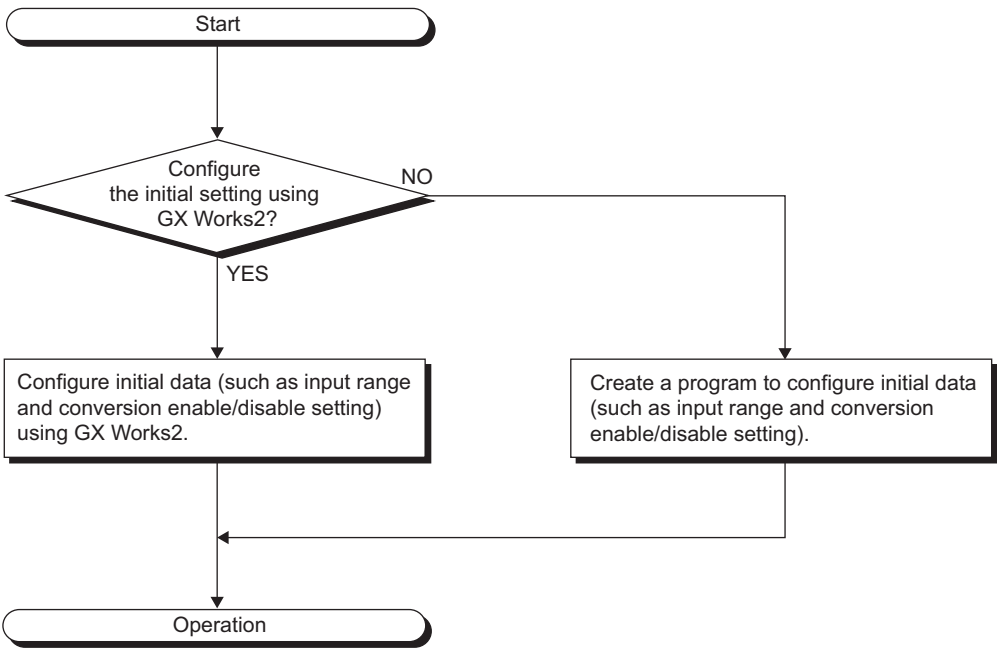
CHAPTER 10 PROGRAMMING

This chapter describes the programs of the L60TC4.
When applying any of the program examples introduced in this chapter to the actual system, verify that the control of the target system has no problem thoroughly.

10.1 Programming Procedure

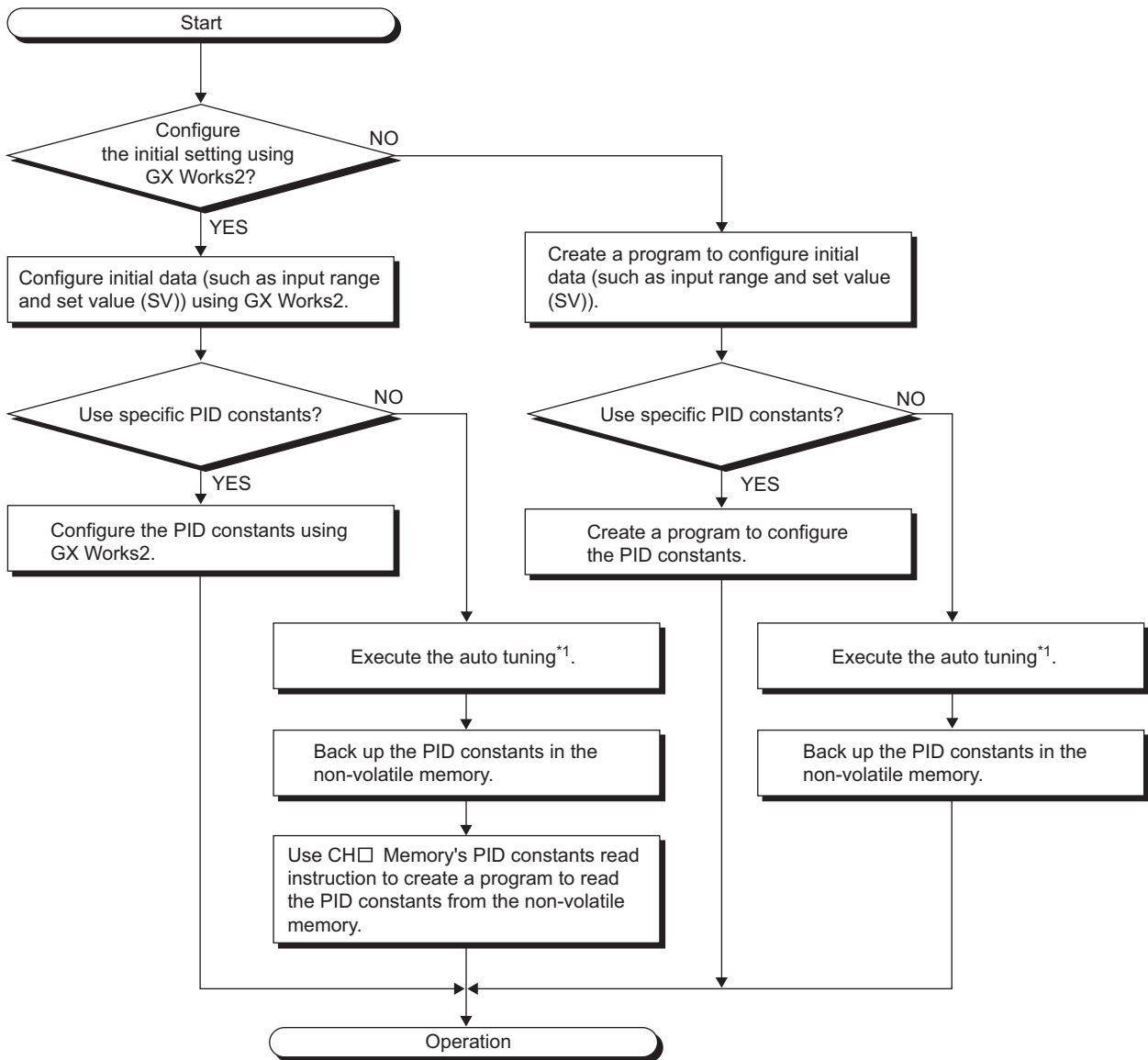
(1) Temperature input mode

Create a program that performs temperature conversion in the L60TC4 using the following procedure.



(2) Temperature control mode

Create a program that performs temperature control in the L60TC4 using the following procedure.



*1 In the standard control, the self-tuning can be selected if necessary.

10.2 When Using the Module in a Standard System Configuration

This section describes the following program examples.

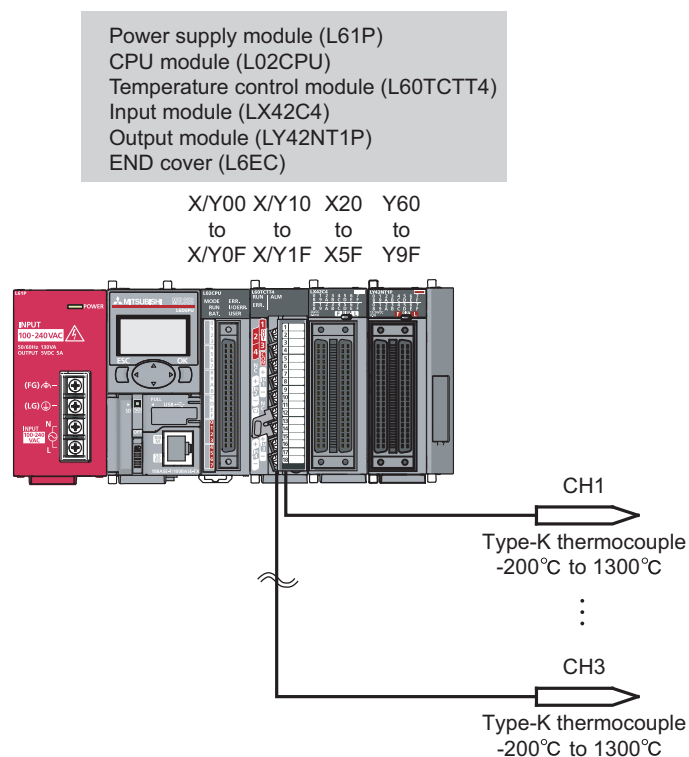
Mode		Overview of the program example	Reference
Temperature input mode		This is a program example where the L60TC4 is used as a temperature input module.	Page 259, Section 10.2.1
Temperature control mode	Standard control	This is a program example for operations such as the auto tuning, self-tuning, and error code read.	Page 270, Section 10.2.2
		This is a program example where the peak current suppression function and the simultaneous temperature rise function are used for the control.	Page 282, Section 10.2.3
	Heating-cooling control	This is a program example for the heating-cooling control.	Page 297, Section 10.2.4

10.2.1 When using the L60TC4 as a temperature input module

This section describes the program example of when the L60TC4 is used as a temperature input module.

(1) System configuration

The following figure shows the system configuration of when the L60TC4 is used as a temperature input module.



- When using the L26CPU-BT, set the I/O assignment of the built-in CC-Link of the L26CPU-BT to X/YFE0 to X/YFFF so that the I/O assignment be the same as that of the system configuration above.
- When the L60TCTT4BW or the L60TCRT4BW is used, the I/O assignment is the same as that of the system configuration shown above.
 - Slot 0: Intelligent 16 points
 - Slot 1: Input 64 points
 - Slot 2: Output 64 points

(2) Programming condition

This program is designed to read the temperatures measured by the thermocouple (K type, -200.0 to 1300.0°C) connected to CH1 to CH3.

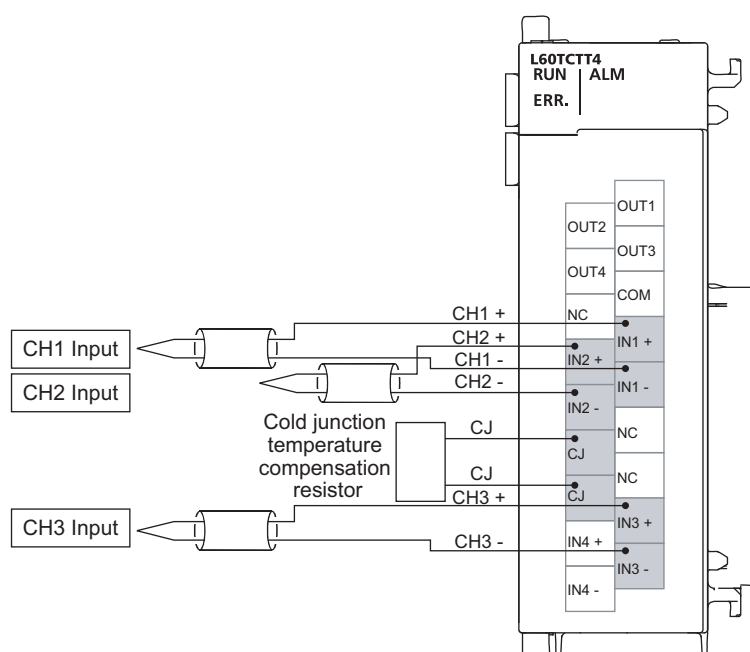
An error code can be read and reset.

The following table lists other programming conditions.

Item	Description		
	CH1	CH2	CH3
Sampling cycle	250ms		
Temperature conversion method	Sampling processing	Sampling processing	Primary delay digital filter (time constant 1s)
Alert output function	—	• Process alarm lower lower limit value: 2000 (200.0°C) • Process alarm lower upper limit value: 2050 (205.0°C) • Process alarm upper lower limit value: 2950 (295.0°C) • Process alarm upper upper limit value: 3000 (300.0°C)	• Rate alarm alert detection cycle: Four times (1s) • Rate alarm upper limit value: 50 (+5.0°C) • Rate alarm lower limit value: -50 (-5.0°C)

(3) Wiring example

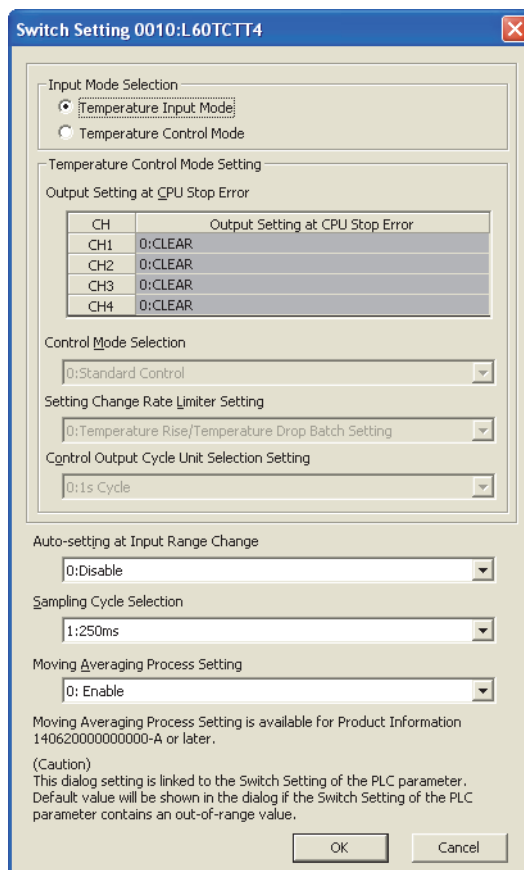
The following figure shows a wiring example.



(4) Switch Setting

Configure settings such as the input mode selection and the auto-setting at the input range change as follows.

 Project window ⇒ [Intelligent Function Module] ⇒ [L60TCTT4] ⇒ [Switch Setting]



Item	Setting value
Input Mode Selection	Temperature Input Mode
Auto-setting at Input Range Change	0: Disable
Sampling Cycle Selection	1: 250ms
Moving Averaging Process Setting	0: Enable

(5) Contents of the initial setting

Item	Description			
	CH1	CH2	CH3	CH4
Input range	49: Thermocouple K Measured Temperature Range (-200.0 to 1300.0°C)	49: Thermocouple K Measured Temperature Range (-200.0 to 1300.0°C)	49: Thermocouple K Measured Temperature Range (-200.0 to 1300.0°C)	2: Thermocouple K Measured Temperature Range (0 to 1300.0°C)
Conversion enable/disable setting	0: Enable	0: Enable	0: Enable	1: Disable
Primary delay digital filter setting	0s	0s	1s	0s
Process alarm alert output enable/disable setting	1: Disable	0: Enable	1: Disable	1: Disable

Item	Description			
	CH1	CH2	CH3	CH4
Process alarm lower lower limit value	-200.0°C	200.0°C	-200.0°C	-200°C
Process alarm lower upper limit value	-200.0°C	205.0°C	-200.0°C	-200°C
Process alarm upper lower limit value	1300.0°C	295°C	1300.0°C	1300°C
Process alarm upper upper limit value	1300.0°C	300°C	1300.0°C	1300°C
Rate alarm alert output enable/disable setting	1: Disable	1: Disable	0: Enable	1: Disable
Rate alarm alert detection cycle	1 Times	1 Times	4 Times	1 Times
Rate alarm upper limit value	0.0°C	0.0°C	5.0°C	0°C
Rate alarm lower limit value	0.0°C	0.0°C	-5.0°C	0°C

(6) When using the parameter of an intelligent function module

(a) Devices used by a user

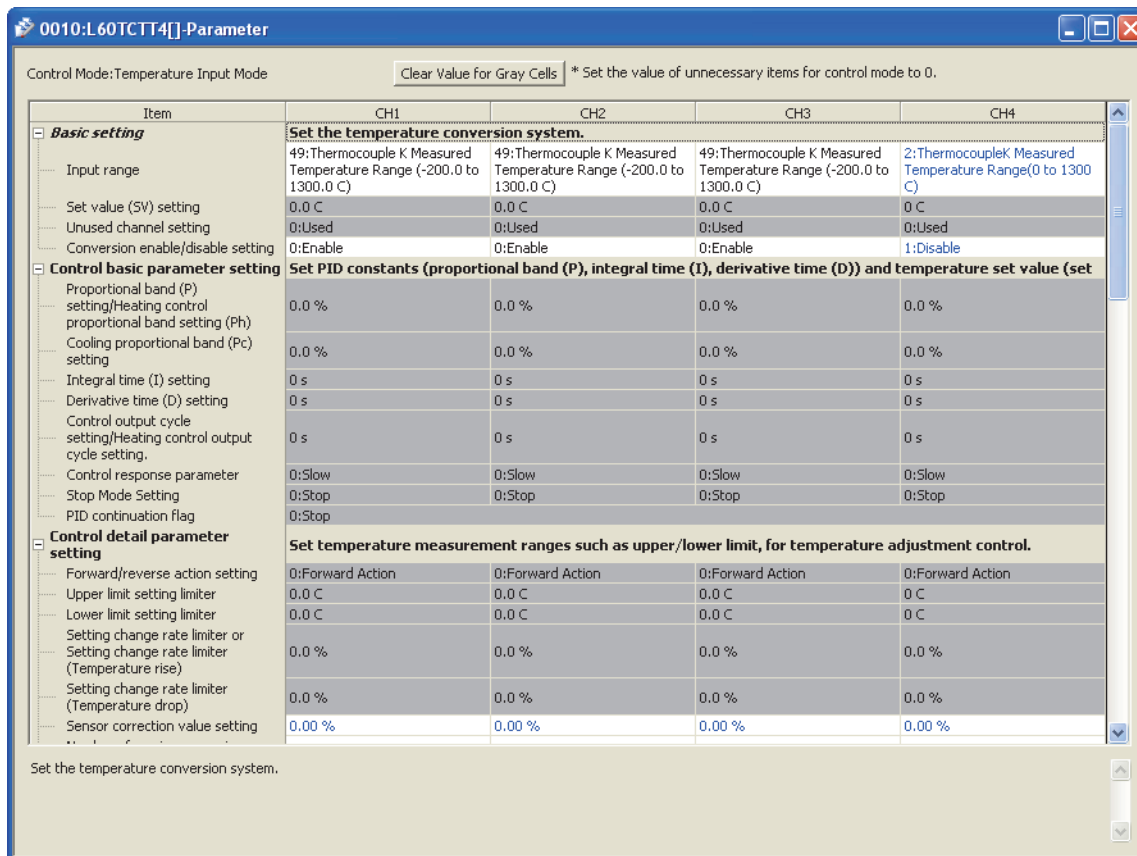
Device	Description	
X10	Module READY flag	L60TCTT4 (X10 to X1F)
X12	Error occurrence flag	
X22	Error code reset instruction	LX42C4 (X20 to X5F)
X23	Operation mode setting instruction	
X25	Temperature process value read instruction	
Y11	Setting/operation mode instruction	L60TCTT4 (Y10 to Y1F)
Y12	Error reset instruction	
Y1B	Setting change instruction	
Y60 to Y6F	Error code output	LY42NT1P (Y60 to Y9F)
D11	CH1 Temperature process value (PV)	Devices where data is written by auto refresh
D12	CH2 Temperature process value (PV)	
D13	CH3 Temperature process value (PV)	
D50	Error code	
D51	CH1 Temperature process value (PV)	
D52	CH2 Temperature process value (PV)	
D53	CH3 Temperature process value (PV)	
D55	CH2 Alert definition	
D56	CH3 Alert definition	
D60	Temperature conversion completion flag	

(b) Parameter setting

Set the contents of initial settings in the parameter.

1. Open the "Parameter" window.

Project window ⇨ [Intelligent Function Module] ⇨ [L60TCTT4] ⇨ [Parameter]

2. Click Clear Value for Gray Cells to set items unnecessary for the mode set on Switch Setting to 0.**3. Set the parameter.**

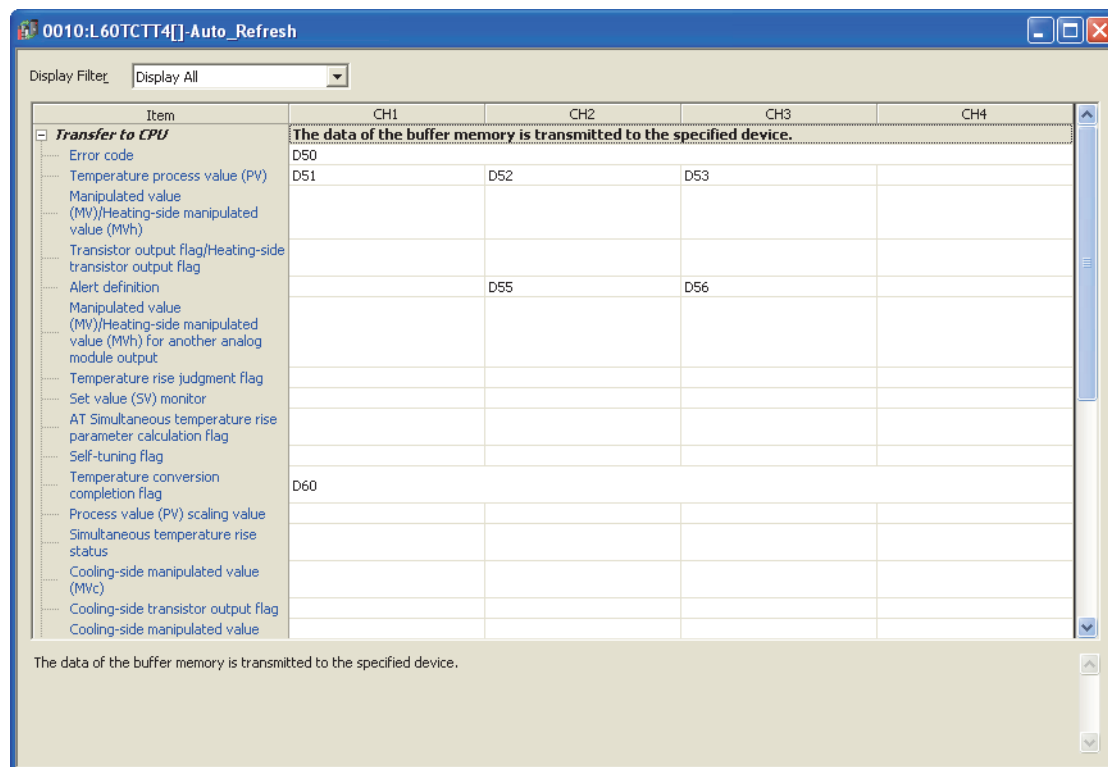
Item	Description	Setting value			
		CH1	CH2	CH3	CH4
Input range	Set the temperature sensor used for the L60TC4 and the measurement range.	49: Thermocouple K Measured Temperature Range (-200.0 to 1300.0°C)	49: Thermocouple K Measured Temperature Range (-200.0 to 1300.0°C)	49: Thermocouple K Measured Temperature Range (-200.0 to 1300.0°C)	2: Thermocouple K Measured Temperature Range (0 to 1300°C)
Conversion enable/disable setting	Set whether to enable or disable temperature conversion for each channel.	0: Enable	0: Enable	0: Enable	1: Disable
Primary delay digital filter setting	Set the primary delay digital filter that smoothes the temperature process value (PV).	0s	0s	1s	0s
Process alarm alert output enable/disable setting	Set whether to enable or disable the process alarm alert output for each channel.	1: Disable	0: Enable	1: Disable	1: Disable

Item	Description	Setting value			
		CH1	CH2	CH3	CH4
Process alarm lower lower limit value	Set the process alarm lower lower limit value.	0.0°C	200.0°C	0.0°C	0°C
Process alarm lower upper limit value	Set the process alarm lower upper limit value.	0.0°C	205.0°C	0.0°C	0°C
Process alarm upper lower limit value	Set the process alarm upper lower limit value.	1300.0°C	295.0°C	1300.0°C	1300°C
Process alarm upper upper limit value	Set the process alarm upper upper limit value.	1300.0°C	300.0°C	1300.0°C	1300°C
Rate alarm alert output enable/disable setting	Set whether to enable or disable the rate alarm alert output for each channel.	1: Disable	1: Disable	0: Enable	1: Disable
Rate alarm alert detection cycle	Set the cycle for checking the temperature process value (PV) for the rate alarm.	1 Times	1 Times	4 Times	1 Times
Rate alarm upper limit value	Set the rate alarm upper limit value.	0.0°C	0.0°C	5.0°C	0°C
Rate alarm lower limit value	Set the rate alarm lower limit value.	0.0°C	0.0°C	-5.0°C	0°C

(c) Auto refresh setting

Set the device to be automatically refreshed.

 Project window ⇒ [Intelligent Function Module] ⇒ [L60TCTT4] ⇒ [Auto_Refresh]



Item	Description	Setting value			
		CH1	CH2	CH3	CH4
Error code	An error code or alarm code is stored.	D50			
Temperature process value (PV)	The detected temperature value where sensor correction was performed is stored.	D51	D52	D53	—
Alert definition	Bits corresponding to alerts detected in each channel become 1.	—	D55	D56	—
Temperature conversion completion flag	This flag checks whether the temperature conversion has started properly for each channel.	D60			

Remark

The number of parameters of the auto refresh setting can be reduced by using the setting item reduction mode of auto refresh.

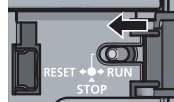
When the setting item reduction mode is set, consecutive devices are automatically set to the grouped setting items. For details on the setting item reduction mode of auto refresh, refer to the following.

 Page 116, Section 7.4

(d) Writing parameter of an intelligent function module

Write the set parameter to the CPU module. Then reset the CPU module or turn off and on the power supply of the programmable controller.

 [Online] ⇒ [Write to PLC...]



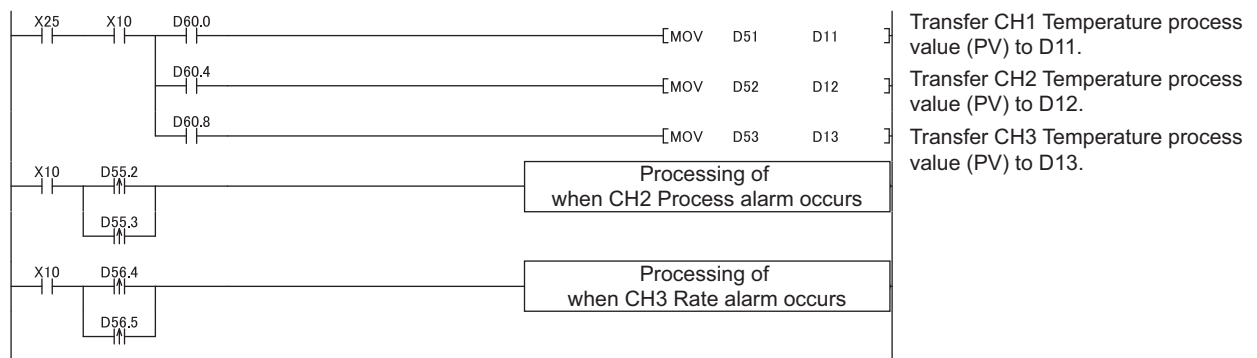
or Power OFF → ON

(e) Program example

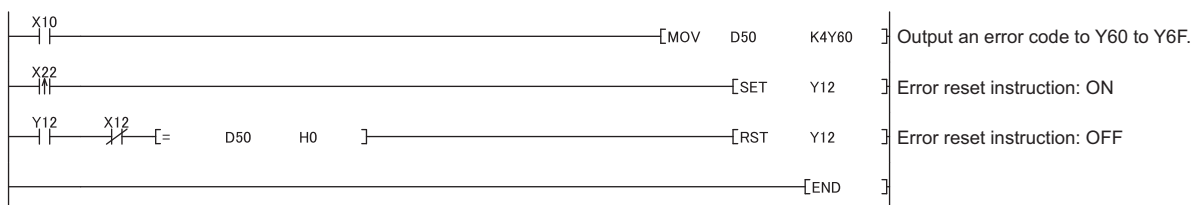
- Program that changes the setting/operation mode



- Program that reads the temperature process value (PV) and takes action when a process alarm or a rate alarm occurs



- Program that reads an error code



(7) Program example of when not using the parameter of an intelligent function module

(a) Devices used by a user

Device	Description	
X10	Module READY flag	L60TCTT4 (X10 to X1F)
X12	Error occurrence flag	
X13	Hardware error flag	
X1B	Setting change completion flag	
X20	Set value write instruction	LX42C4 (X20 to X5F)
X22	Error code reset instruction	
X23	Operation mode setting instruction	
X25	Temperature process value read instruction	
Y11	Setting/operation mode status	L60TCTT4 (Y10 to Y1F)
Y12	Error reset instruction	
Y1B	Setting change instruction	
Y60 to Y6F	Error code output	LY42NT1P (Y60 to Y9F)
D11	CH1 Temperature process value (PV)	
D12	CH2 Temperature process value (PV)	
D13	CH3 Temperature process value (PV)	
D50	Error code	
D55	CH2 Alert definition	
D56	CH3 Alert definition	
D60	Temperature conversion completion flag	
M0	Flag 0 for setting value write	
M1	Flag 1 for setting value write	
M2	Flag 2 for setting value write	

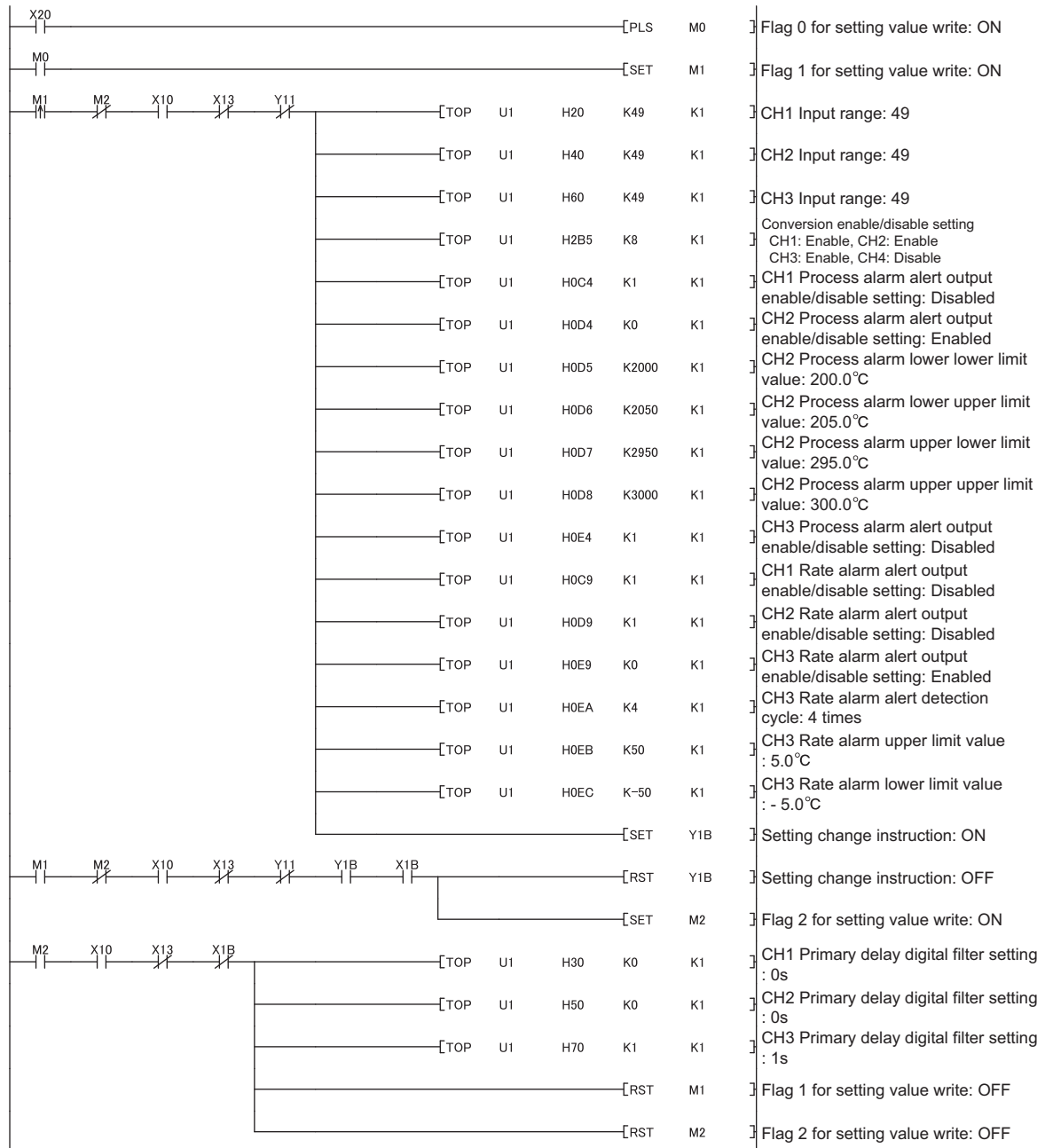
(b) Program example

- Program that changes the setting/operation mode

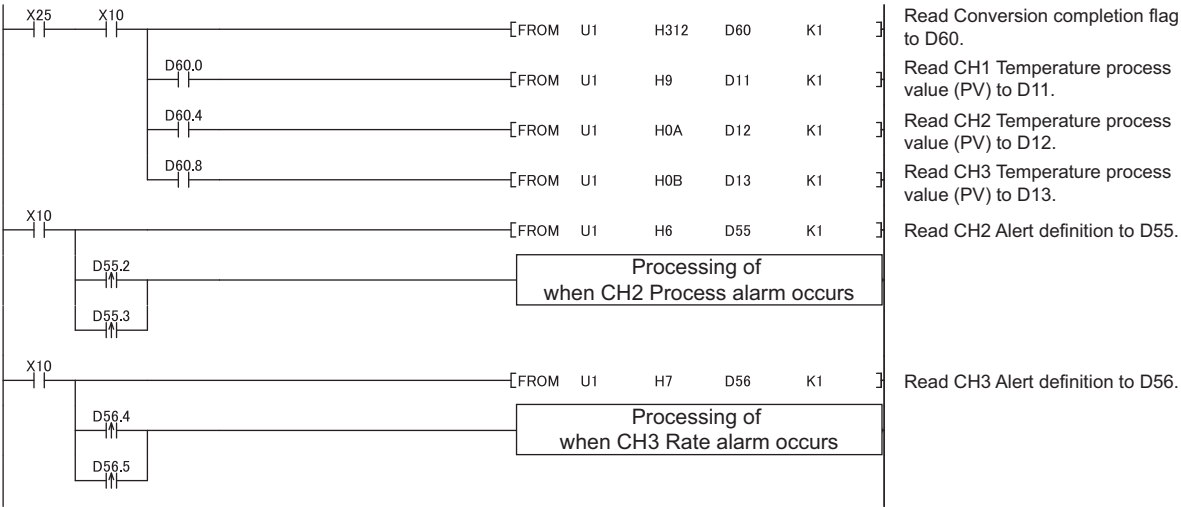
The program is the same as that of when the parameter of the intelligent function module is used.

( Page 266, Section 10.2.1 (6) (e))

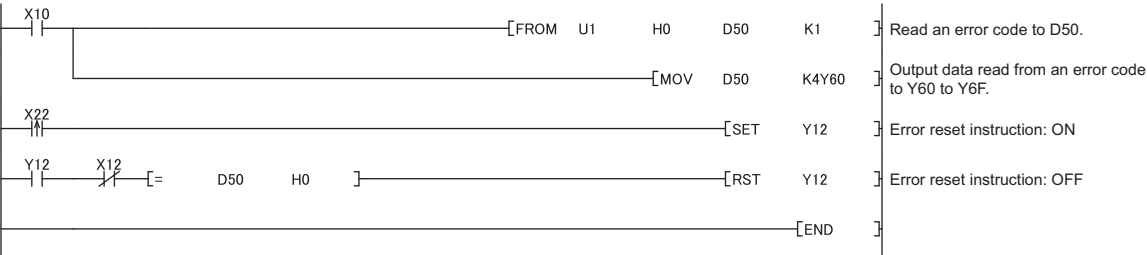
- Initial setting program



- Program that reads the temperature process value (PV) and takes action when a process alarm or a rate alarm occurs



- Program that reads an error code

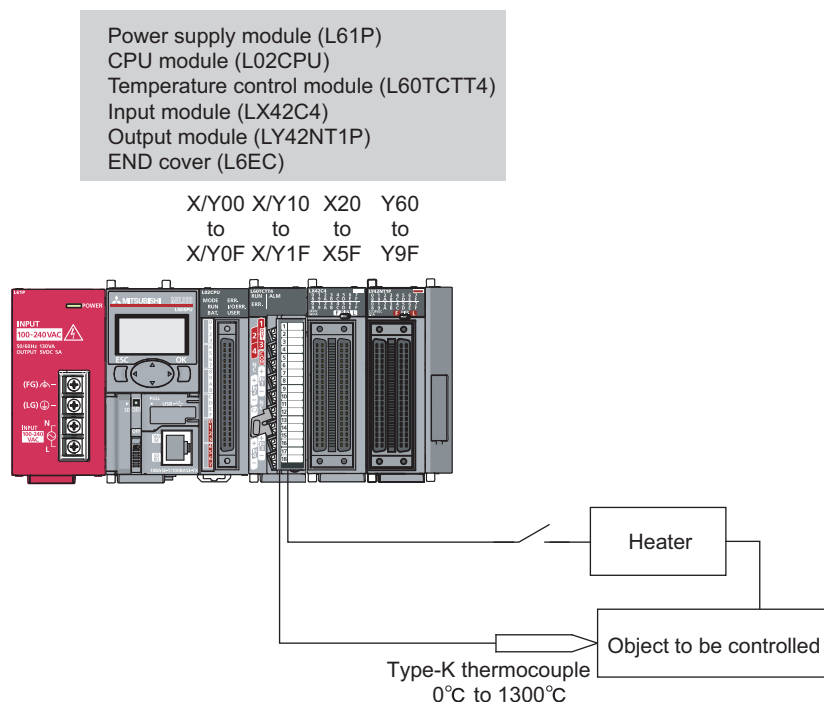


10.2.2 Standard control (such as auto tuning, self-tuning, and error code read)

This section describes the program example for operations such as the auto tuning, self-tuning, and error code read.

(1) System configuration

The following figure shows the system configuration for operations such as the auto tuning, self-tuning, and error code read.



Point

- When using the L26CPU-BT, set the I/O assignment of the built-in CC-Link of the L26CPU-BT to X/YFE0 to X/YFFF so that the I/O assignment be the same as that of the system configuration above.
- When the L60TCTT4BW or the L60TCRT4BW is used, the I/O assignment is the same as that of the system configuration shown above.
 - Slot 0: Intelligent 16 points
 - Slot 1: Input 64 points
 - Slot 2: Output 64 points

(2) Programming condition

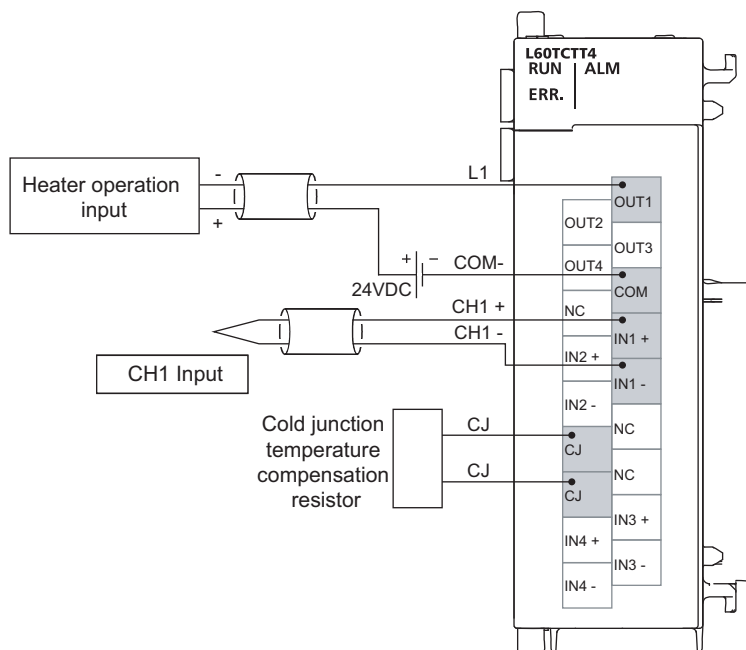
This program is designed to read the temperatures measured by the thermocouple (K type, 0°C to 1300°C) connected to CH1 for the control.

An error code can be read and reset.

The self-tuning function automatically sets the PID constants optimal to CH1.

(3) Wiring example

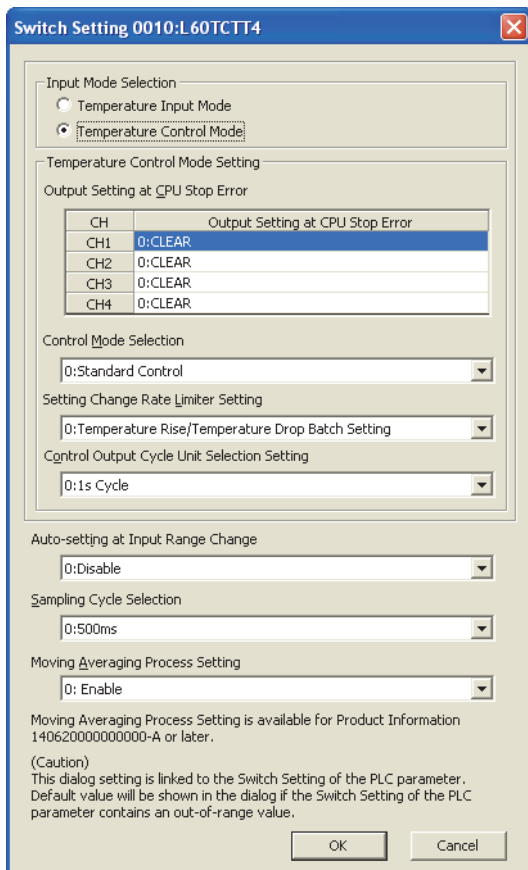
The following figure shows a wiring example.



(4) Switch Setting

Configure settings such as the input mode selection and the auto-setting at the input range change as follows.

 Project window ⇨ [Intelligent Function Module] ⇨ [L60TCTT4] ⇨ [Switch Setting]



Item		Set value			
		CH1	CH2	CH3	CH4
Input Mode Selection		Temperature Control Mode			
Temperature Control Mode Setting	Output Setting at CPU Stop Error	0: CLEAR	0: CLEAR	0: CLEAR	0: CLEAR
	Control Mode Selection	0: Standard Control			
	Setting Change Rate Limiter Setting	0: Temperature Rise/Temperature Drop Batch Setting			
	Control Output Cycle Unit Selection Setting	0: 1s Cycle			
Auto-setting at Input Range Change		0: Disable			
Sampling Cycle Selection		0: 500ms			
Moving Averaging Process Setting		0: Enable			

(5) Contents of the initial setting

Item	Description			
	CH1	CH2	CH3	CH4
Input range	2: Thermocouple K Measured Temperature Range (0 to 1300°C)	2: Thermocouple K Measured Temperature Range (0 to 1300°C)	2: Thermocouple K Measured Temperature Range (0 to 1300°C)	2: Thermocouple K Measured Temperature Range (0 to 1300°C)
Set value (SV) setting	200°C	0°C	0°C	0°C
Unused channel setting	0: Used	1: Unused	1: Unused	1: Unused
Control output cycle setting	30s	30s	30s	30s
Upper limit setting limiter	400°C	1300°C	1300°C	1300°C
Lower limit setting limiter	0°C	0°C	0°C	0°C
Self-tuning setting ^{*1}	1: Starting ST (PID Constant Only)	0: Do Not Run the ST	0: Do Not Run the ST	0: Do Not Run the ST
Alert 1 mode setting	1: Upper Limit Input Alert	0: Not Warning	0: Not Warning	0: Not Warning
Alert set value 1	250°C	0°C	0°C	0°C

^{*1} This setting is necessary only when the self-tuning function is used.

(6) When using the parameter of an intelligent function module**(a) Devices used by a user**

Device	Description	
X10	Module READY flag	L60TCTT4 (X10 to X1F)
X12	Error occurrence flag	
X22	Error code reset instruction	LX42C4 (X20 to X5F)
X23	Operation mode setting instruction	
X24	Memory's PID constants read instruction	
X30	CH1 Set value (SV) change instruction	
Y11	Setting/operation mode instruction	L60TCTT4 (Y10 to Y1F)
Y12	Error reset instruction	
Y18	Set value backup instruction	
Y1B	Setting change instruction	
Y60 to Y6F	Error code output	LY42NT1P (Y60 to Y9F)
D50	Error code	Devices where data is written by auto refresh
D51	CH1 Temperature process value (PV)	
D55	CH1 Alert definition	
M20 to M23	CH□ Read completion flag	
M24 to M27	CH□ Write completion flag	

10.2 When Using the Module in a Standard System Configuration
10.2.2 Standard control (such as auto tuning, self-tuning, and error code read)

(b) Parameter setting

Set the contents of initial settings in the parameter.

1. Open the "Parameter" window.

Project window ⇨ [Intelligent Function Module] ⇨ [L60TCTT4] ⇨ [Parameter]

2. Click **Clear Value for Gray Cells** to set items unnecessary for the mode set on Switch Setting to 0.

3. Set the parameter.

Item	CH1	CH2	CH3	CH4
Basic setting				
Set the temperature conversion system.				
Input range	2:ThermocoupleK Measured Temperature Range(0 to	2:ThermocoupleK Measured Temperature Range(0 to	2:ThermocoupleK Measured Temperature Range(0 to	2:ThermocoupleK Measured Temperature Range(0 to
Set value (SV) setting	200 C	0 C	0 C	0 C
Unused channel setting	0:Used	1:Unused	1:Unused	1:Unused
Conversion enable/disable setting	1:Disable	1:Disable	1:Disable	1:Disable
Control basic parameter setting				
Set PID constants (proportional band (P), integral time (I), derivative time (D)) and temperature set				
Proportional band (P) setting/Heating control proportional band setting (Ph)	3.0 %	3.0 %	3.0 %	3.0 %
Cooling proportional band (Pc) setting	3.0 %	3.0 %	3.0 %	3.0 %
Integral time (I) setting	240 s	240 s	240 s	240 s
Derivative time (D) setting	60 s	60 s	60 s	60 s
Control output cycle setting/Heating control output cycle setting.	30 s	30 s	30 s	30 s
Control response parameter	0:Slow	0:Slow	0:Slow	0:Slow
Stop Mode Setting	1:Monitor	1:Monitor	1:Monitor	1:Monitor
PID continuation flag	0:Stop			
Control detail parameter setting				
Set temperature measurement ranges such as upper/lower limit, for temperature adjustment control.				
Forward/reverse action setting	1:Reverse Action	1:Reverse Action	1:Reverse Action	1:Reverse Action
Upper limit setting limiter	400 C	1300 C	1300 C	1300 C
Lower limit setting limiter	0 C	0 C	0 C	0 C
Setting change rate limiter or Setting change rate limiter (Temperature rise)	0.0 %	0.0 %	0.0 %	0.0 %
Setting change rate limiter (Temperature drop)	0.0 %	0.0 %	0.0 %	0.0 %
Sensor correction value setting	0.00 %	0.00 %	0.00 %	0.00 %

Item	Description	Setting value			
		CH1	CH2	CH3	CH4
Input range	Set the temperature sensor used for the L60TC4 and the measurement range.	2: Thermocouple K Measured Temperature Range (0 to 1300°C)	2: Thermocouple K Measured Temperature Range (0 to 1300°C)	2: Thermocouple K Measured Temperature Range (0 to 1300°C)	2: Thermocouple K Measured Temperature Range (0 to 1300°C)
Set value (SV) setting	Set the target temperature value of PID control.	200°C	0°C	0°C	0°C
Unused channel setting	Configure this setting when the channels where the temperature control is not performed and the temperature sensor is not connected are set to be unused.	0: Used	1: Unused	1: Unused	1: Unused

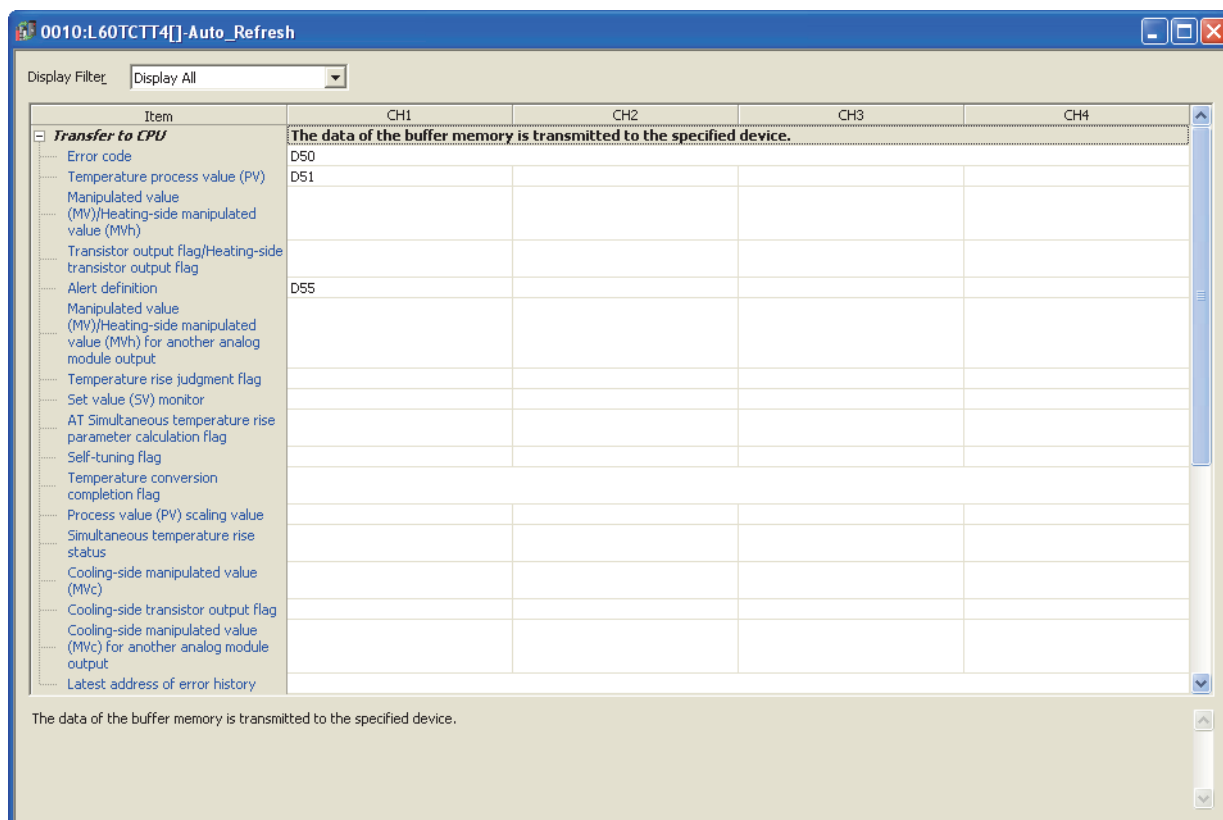
Item	Description	Setting value			
		CH1	CH2	CH3	CH4
Control output cycle setting/Heating control output cycle setting	Set the pulse cycle (ON/OFF cycle) of the transistor output.	30s	30s	30s	30s
Upper limit setting limiter	Set the upper limit of the set value (SV).	400°C	1300°C	1300°C	1300°C
Lower limit setting limiter	Set the lower limit of the set value (SV).	0°C	0°C	0°C	0°C
Self-tuning setting *1	Set the operation of the self-tuning.	1: Starting ST (PID Constant Only)	0: Do Not Run the ST	0: Do Not Run the ST	0: Do Not Run the ST
Alert 1 mode setting	Set the alert mode.	1: Upper Limit Input Alert	0: Not Warning	0: Not Warning	0: Not Warning
Alert set value 1	Set the temperature where CH□ Alert 1 (b8 of Un\G5 to Un\G8) turns on.	250°C	—	—	—

*1 This setting is necessary only when the self-tuning function is used.

(c) Auto refresh setting

Set the device to be automatically refreshed.

 Project window ⇨ [Intelligent Function Module] ⇨ [L60TCTT4] ⇨ [Auto_Refresh]



Item	Description	Set value			
		CH1	CH2	CH3	CH4
Error code	An error code or alarm code is stored.	D50			
Temperature process value (PV)	The detected temperature value where sensor correction was performed is stored.	D51	—	—	—
Alert definition	The value is stored depending on the detected alert.	D55	—	—	—

Remark

The number of parameters of the auto refresh setting can be reduced by using the setting item reduction mode of auto refresh.

When the setting item reduction mode is set, consecutive devices are automatically set to the grouped setting items.

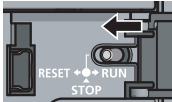
For details on the setting item reduction mode of auto refresh, refer to the following.

 Page 116, Section 7.4

(d) Writing parameter of an intelligent function module

Write the set parameter to the CPU module. Then reset the CPU module or turn off and on the power supply of the programmable controller.

 [Online] ⇒ [Write to PLC...]

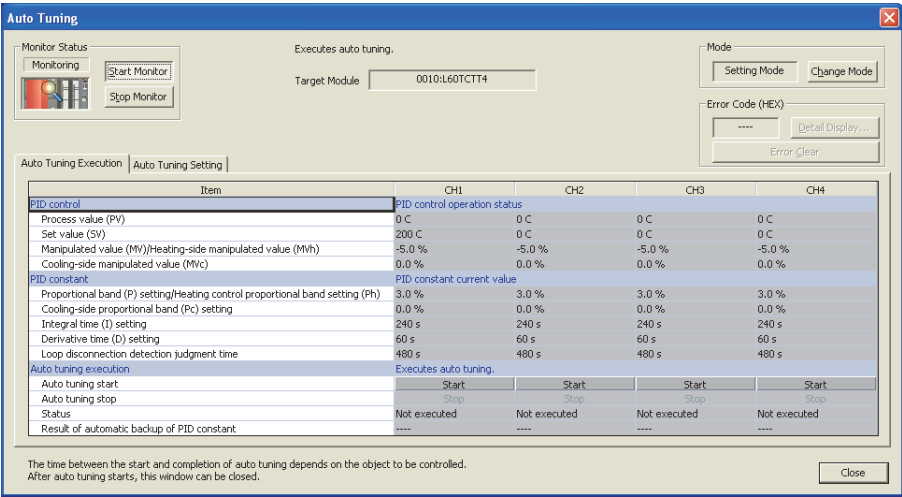


or Power OFF → ON

(e) Performing auto tuning

Set the "Automatic backup setting after auto tuning of PID constants" to "ON" and perform the auto tuning.

 [Tool] ⇒ [Intelligent Function Module Tool] ⇒ [Temperature Control Module]
⇒ [Auto Tuning...] ⇒ [L60TCTT4] ⇒ 

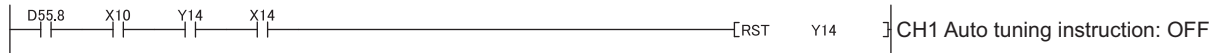


(f) Program example

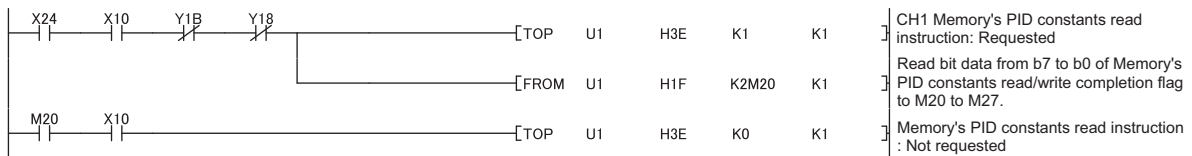
- Program that changes the setting/operation mode

This program is the same as that of when it is used as a temperature input module. (☞ Page 266, Section 10.2.1 (6) (e))

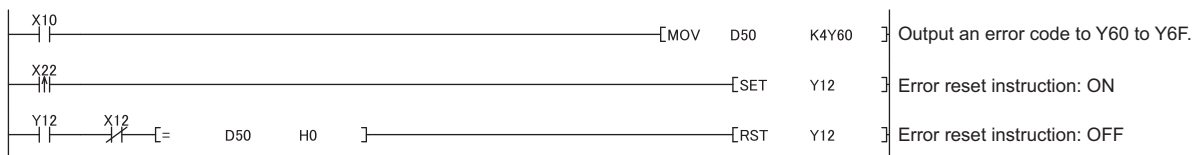
- Program that stops the auto tuning when an alert is detected



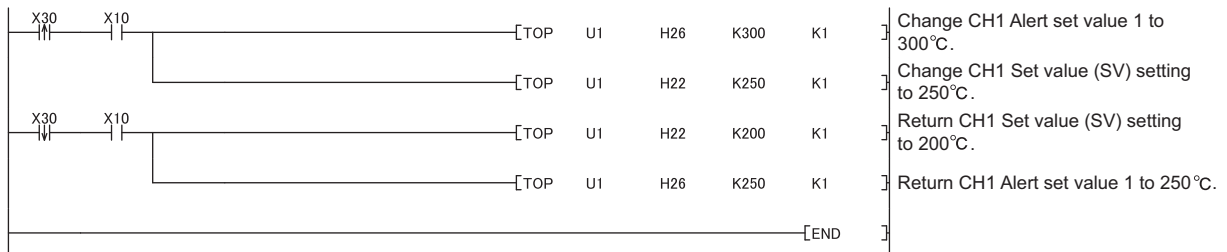
- Program that reads the PID constants from the non-volatile memory



- Program that reads an error code



- Program that changes the set values (SV) and the alert set value 1



(7) Program example of when not using the parameter of an intelligent function module

(a) Devices used by a user

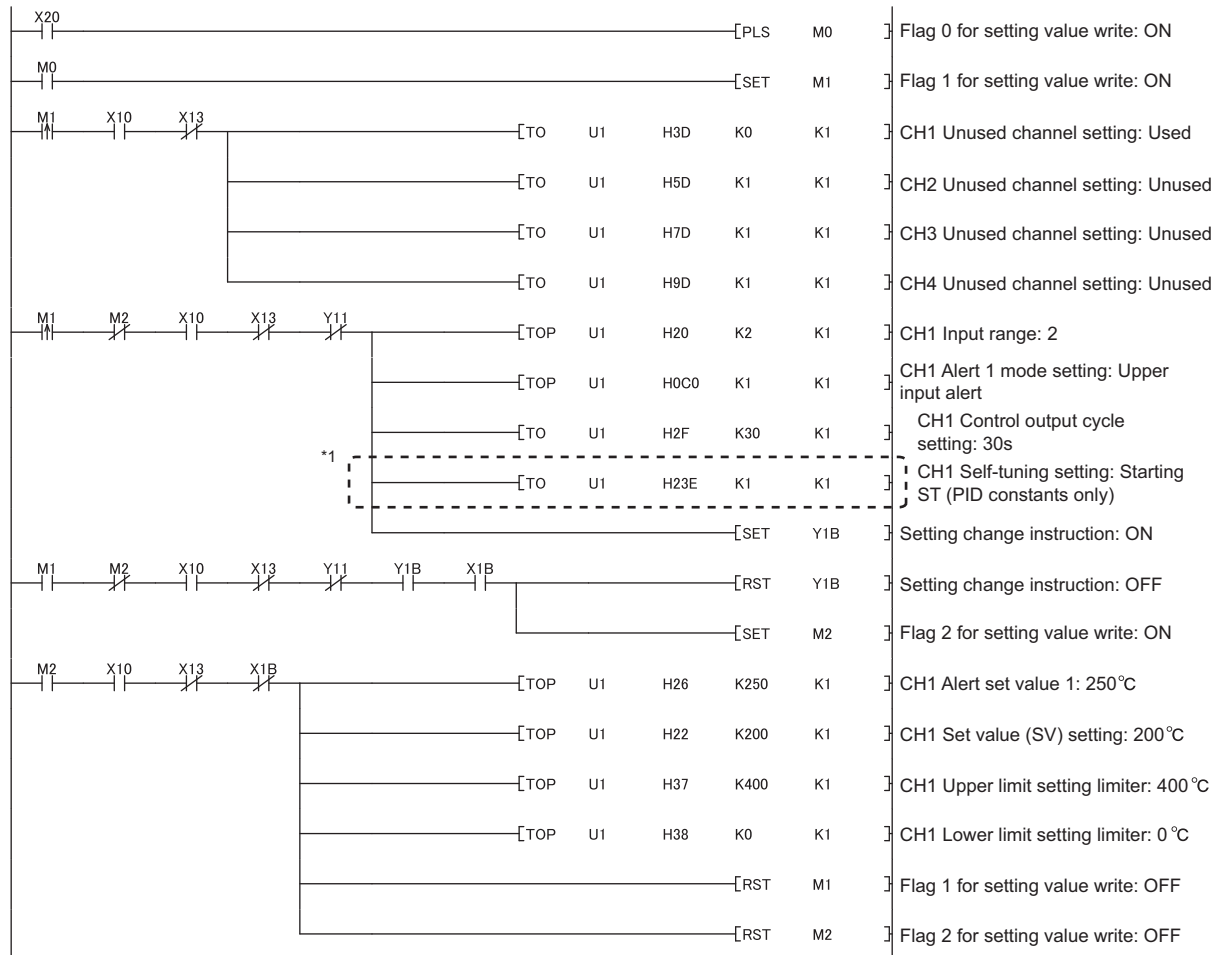
Device	Description	
X10	Module READY flag	L60TCTT4 (X10 to X1F)
X11	Setting/operation mode status	
X12	Error occurrence flag	
X13	Hardware error flag	
X14	CH1 Auto tuning status	
X18	Back-up of the set value completion flag	
X1B	Setting change completion flag	LX42C4 (X20 to X5F)
X20	Set value write instruction	
X21	Auto tuning execute instruction	
X22	Error code reset instruction	
X23	Operation mode setting instruction	
X24	Memory's PID constants read instruction	
X30	CH1 Set value (SV) change instruction	L60TCTT4 (Y10 to Y1F)
Y11	Setting/operation mode instruction	
Y12	Error reset instruction	
Y14	CH1 Auto tuning instruction	
Y18	Set value backup instruction	LY42NT1P (Y60 to Y9F)
Y1B	Setting change instruction	
Y60 to Y6F	Error code output	
D50	Error code	
D51	CH1 Temperature process value (PV)	
D55	CH1 Alert definition	
M0	Flag 0 for setting value write	
M1	Flag 1 for setting value write	
M2	Flag 2 for setting value write	
M10	CH1 Auto tuning completion flag	
M20 to M23	CH□ Read completion flag	
M24 to M27	CH□ Write completion flag	

(b) Program example

- Program that changes the setting/operation mode

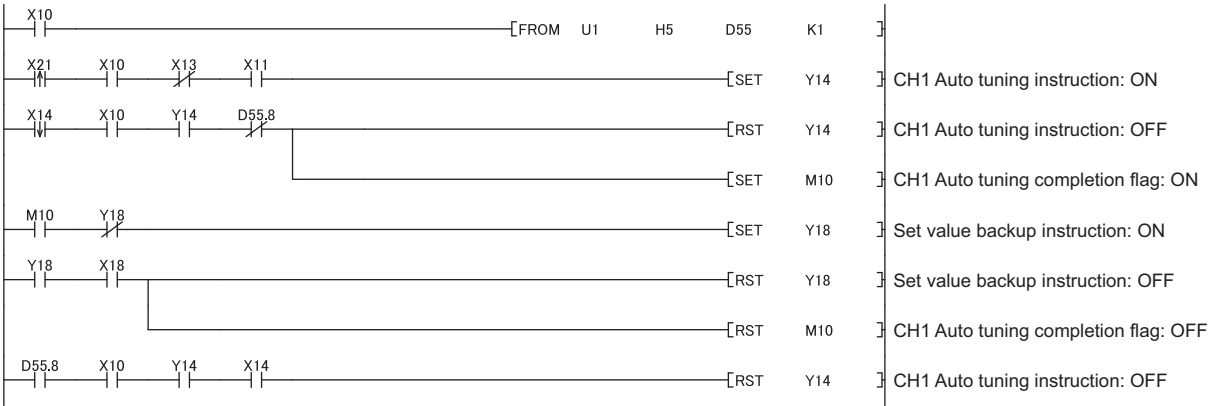
This program is the same as that of when it is used as a temperature input module. (☞ Page 266, Section 10.2.1 (6) (e))

- Initial setting program



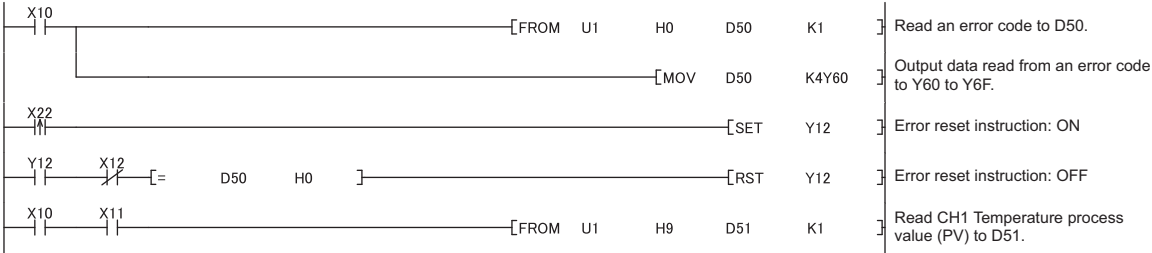
*1 Configure this setting only when the self-tuning function is used.

- Program that executes the auto tuning and backs up the PID constants in the non-volatile memory if the auto tuning is normally completed (The auto tuning is stopped when an alert is detected.)



- Program that reads the PID constants from the non-volatile memory
This program is the same as that of when the parameter of the intelligent function module is used.
(Page 278, Section 10.2.2 (6) (f))

- Program that reads an error code and the temperature process value (PV)



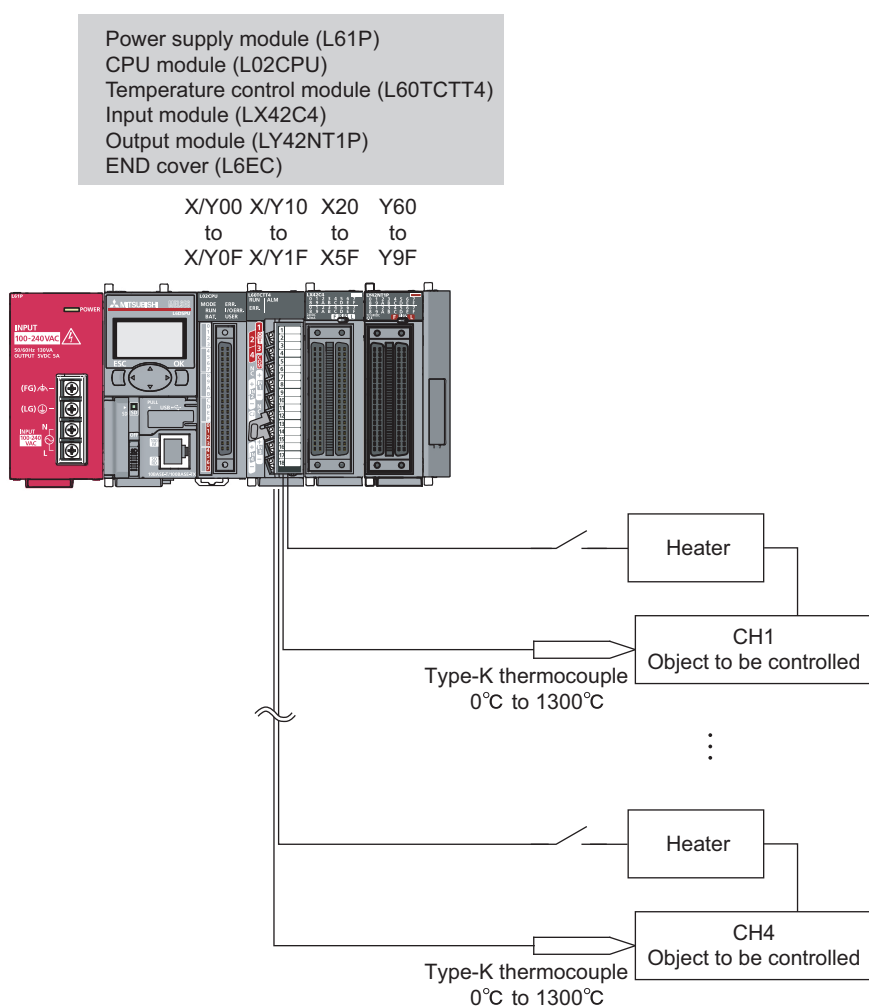
- Program that changes the set values (SV) and the alert set value 1
This program is the same as that of when the parameter of the intelligent function module is used.
(Page 278, Section 10.2.2 (6) (f))

10.2.3 Standard control (peak current suppression function, simultaneous temperature rise function)

This section describes the program example where the peak current suppression function and the simultaneous temperature rise function are used for the control.

(1) System configuration

The following figure shows the system configuration example of when the peak current suppression function and the simultaneous temperature rise function are used for the control.



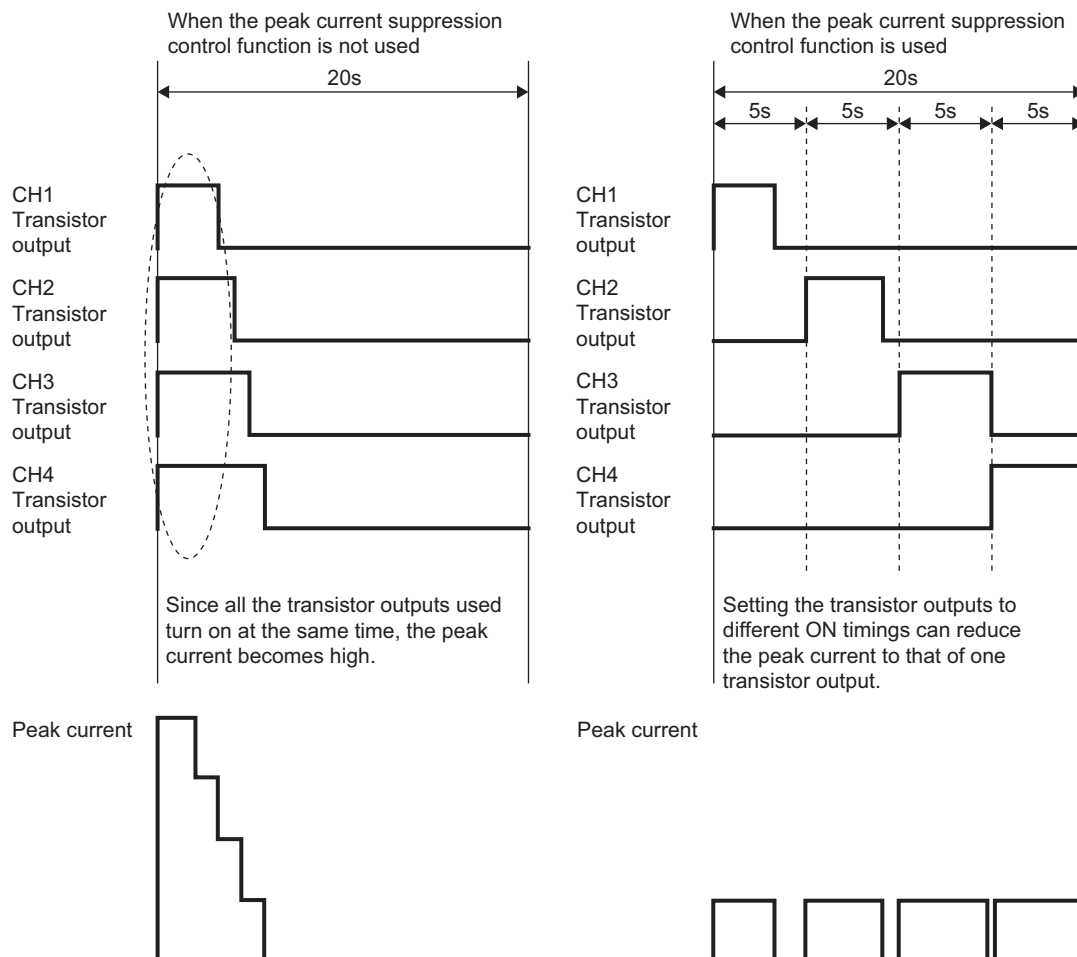
Point

- When using the L26CPU-BT, set the I/O assignment of the built-in CC-Link of the L26CPU-BT to X/YFE0 to X/YFFF so that the I/O assignment be the same as that of the system configuration above.
- When the L60TCTT4BW or the L60TCRT4BW is used, the I/O assignment is the same as that of the system configuration shown above.
 - Slot 0: Intelligent 16 points
 - Slot 1: Input 64 points
 - Slot 2: Output 64 points

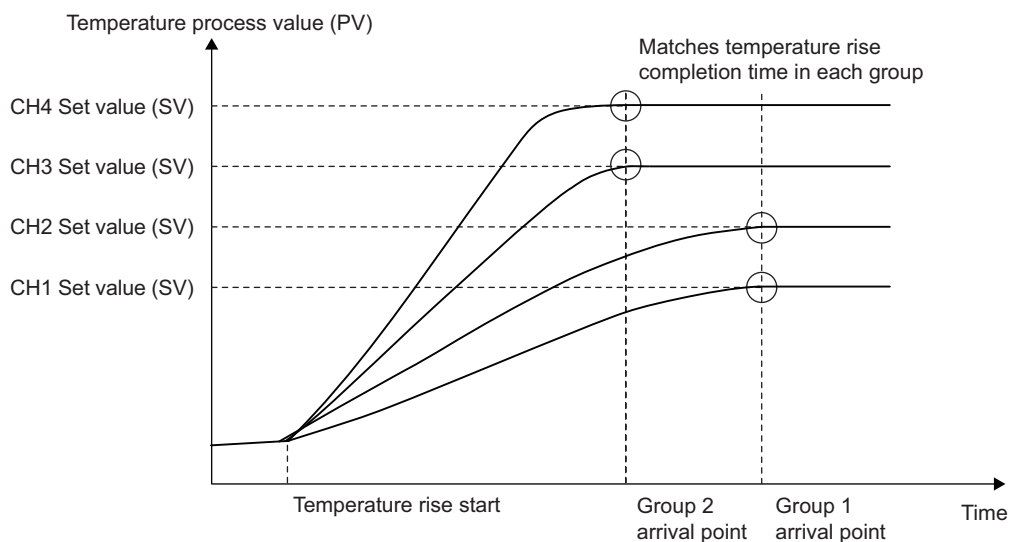
(2) Programming condition

- Program example where the peak current suppression function is used

This program is designed to suppress the peak current by automatically changing the values of the upper limit output limiter of CH1 to CH4 and dividing the timing of the transistor output into four timing.

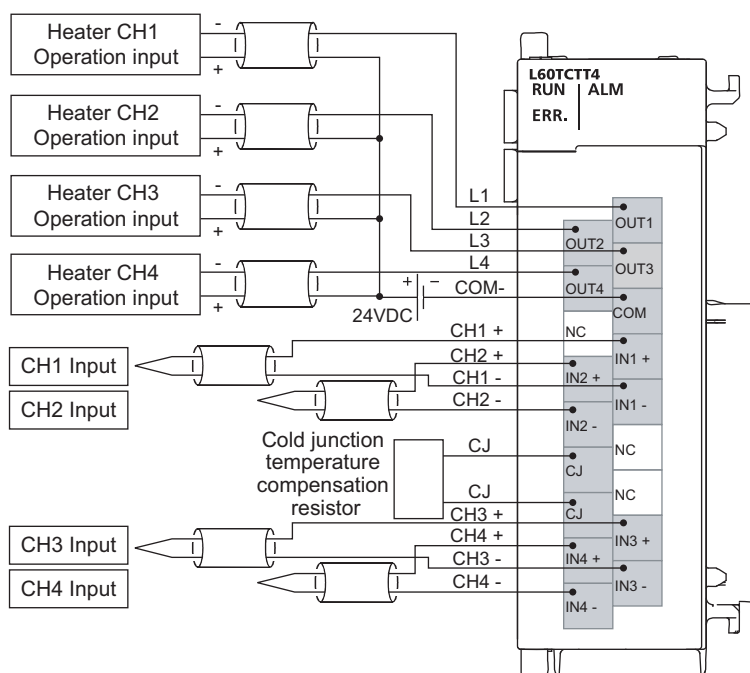


- Program example where the simultaneous temperature rise function is used
This program is designed to classify the CH1 and CH2 into group 1 and CH3 and CH4 into group 2 so that the channels in each group reach the set values (SV) simultaneously.



(3) Wiring example

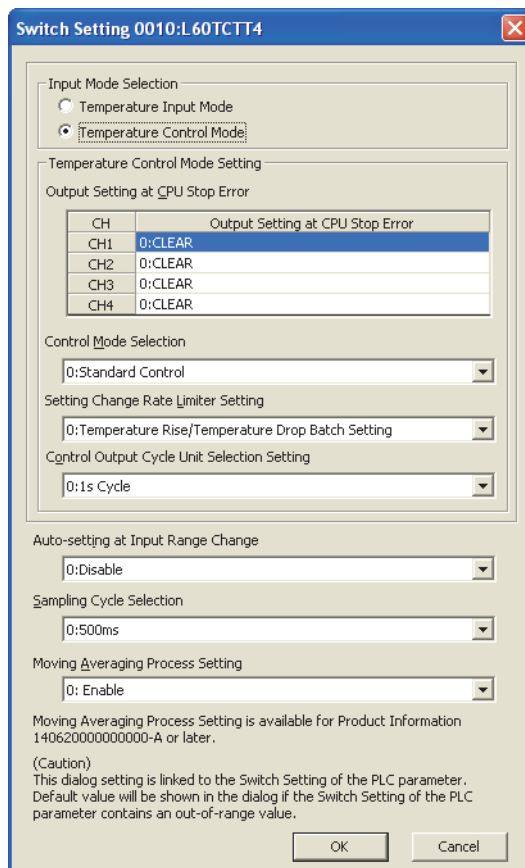
The following figure shows a wiring example.



(4) Switch Setting

Configure settings such as the input mode selection and the auto-setting at the input range change as follows.

 Project window ⇒ [Intelligent Function Module] ⇒ [L60TCTT4] ⇒ [Switch Setting]



Item		Set value			
		CH1	CH2	CH3	CH4
Input Mode Selection		Temperature Control Mode			
Temperature Control Mode Setting	Output Setting at CPU Stop Error	0: CLEAR	0: CLEAR	0: CLEAR	0: CLEAR
	Control Mode Selection	0: Standard Control			
	Setting Change Rate Limiter Setting	0: Temperature Rise/Temperature Drop Batch Setting			
	Control Output Cycle Unit Selection Setting	0: 1s Cycle			
Auto-setting at Input Range Change		0: Disable			
Sampling Cycle Selection		0: 500ms			
Moving Averaging Process Setting		0: Enable			

(5) Contents of the initial setting

Item	Description			
	CH1	CH2	CH3	CH4
Input range	2: Thermocouple K Measured Temperature Range (0 to 1300°C)	2: Thermocouple K Measured Temperature Range (0 to 1300°C)	2: Thermocouple K Measured Temperature Range (0 to 1300°C)	2: Thermocouple K Measured Temperature Range (0 to 1300°C)
Set value (SV) setting	200°C	250°C	300°C	350°C
Unused channel setting	0: Used	0: Used	0: Used	0: Used
Control output cycle setting	20s	20s	20s	20s
Simultaneous temperature rise group setting ^{*1}	1: Group 1	1: Group 1	2: Group 2	2: Group 2
Peak current suppression control group setting ^{*2}	1: Group 1	2: Group 2	3: Group 3	4: Group 4
Simultaneous temperature rise AT mode selection ^{*1}	1: AT for Simultaneous Temperature Rise	1: AT for Simultaneous Temperature Rise	1: AT for Simultaneous Temperature Rise	1: AT for Simultaneous Temperature Rise
Alert 1 mode setting	1: Upper Limit Input Alert	1: Upper Limit Input Alert	1: Upper Limit Input Alert	1: Upper Limit Input Alert
Alert set value 1	250°C	300°C	350°C	400°C

*1 Configure this setting only when the simultaneous temperature rise function is used.

*2 Configure this setting only when the peak current suppression function is used.

(6) When using the parameter of an intelligent function module

(a) Devices used by a user

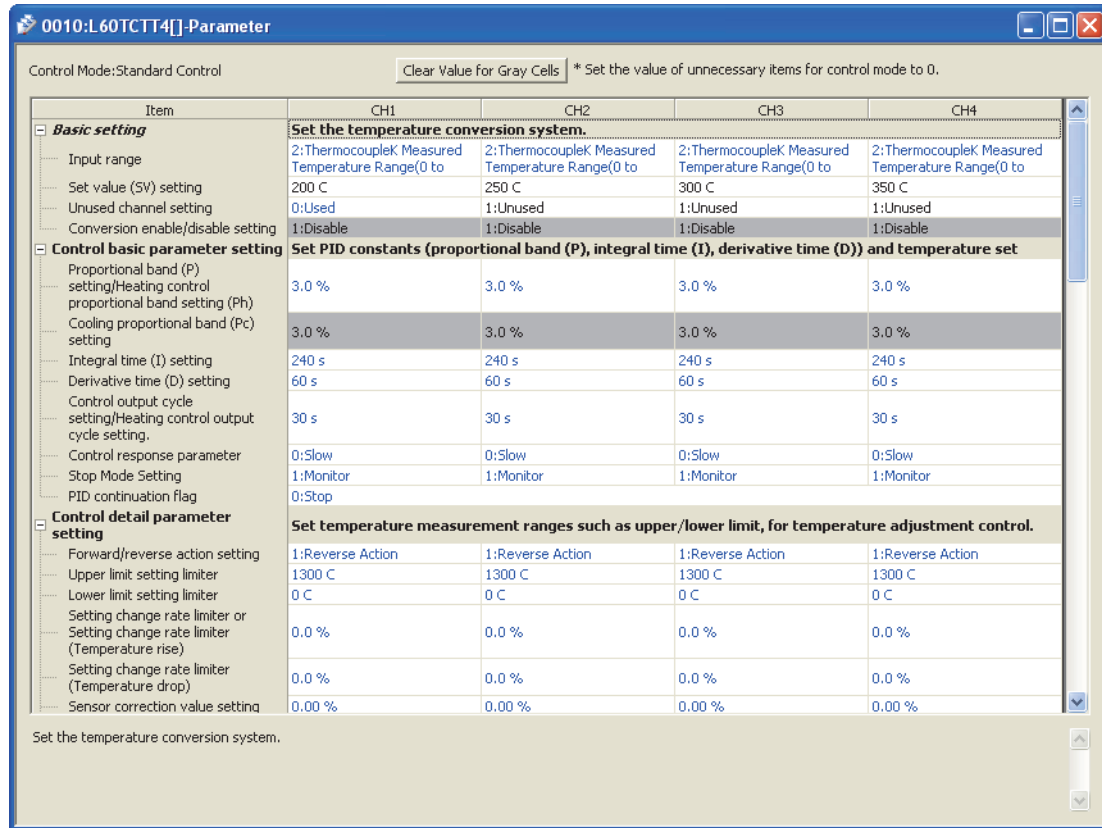
Device	Description	
X10	Module READY flag	L60TCTT4 (X10 to X1F)
X12	Error occurrence flag	
X22	Error code reset instruction	LX42C4 (X20 to X5F)
X23	Operation mode setting instruction	
X24	Memory's PID constants read instruction	
Y11	Setting/operation mode instruction	L60TCTT4 (Y10 to Y1F)
Y12	Error reset instruction	
Y18	Set value backup instruction	
Y1B	Setting change instruction	
Y60 to Y6F	Error code output	LY42NT1P (Y60 to Y9F)
D50	Error code	Devices where data is written by auto refresh
D51 to D54	CH□ Temperature process value (PV)	
D55 to D58	CH□ Alert definition	
M20 to M23	CH□ Read completion flag	
M24 to M27	CH□ Write completion flag	

(b) Parameter setting

Set the contents of initial settings in the parameter.

1. Open the "Parameter" window.

 Project window ⇨ [Intelligent Function Module] ⇨ [L60TCTT4] ⇨ [Parameter]

2. Click to set items unnecessary for the mode set on Switch Setting to 0.**3. Set the parameter.**

Item	Description	Setting value			
		CH1	CH2	CH3	CH4
Input range	Set the temperature sensor used for the L60TC4 and the measurement range.	2: Thermocouple K Measured Temperature Range (0 to 1300°C)	2: Thermocouple K Measured Temperature Range (0 to 1300°C)	2: Thermocouple K Measured Temperature Range (0 to 1300°C)	2: Thermocouple K Measured Temperature Range (0 to 1300°C)
Set value (SV) setting	Set the target temperature value of PID control.	200°C	250°C	300°C	350°C
Unused channel setting	Configure this setting when the channels where the temperature control is not performed and the temperature sensor is not connected are set to be unused.	0: Used	0: Used	0: Used	0: Used
Control output cycle setting/Heating control output cycle setting	Set the pulse cycle (ON/OFF cycle) of the transistor output.	20s	20s	20s	20s

Item	Description	Setting value			
		CH1	CH2	CH3	CH4
Simultaneous temperature rise group setting ^{*1}	Set the group to perform the simultaneous temperature rise function for each channel.	1: Group 1	1: Group 1	2: Group 2	2: Group 2
Peak current suppression control group setting ^{*2}	Set the target channels for the peak current suppression function and the gap of the control output cycles between channels.	1: Group 1	2: Group 2	3: Group 3	4: Group 4
Simultaneous temperature rise AT mode selection ^{*1}	Set the mode of the auto tuning.	1: AT for Simultaneous Temperature Rise	1: AT for Simultaneous Temperature Rise	1: AT for Simultaneous Temperature Rise	1: AT for Simultaneous Temperature Rise
Alert 1 mode setting	Set the alert mode.	1: Upper Limit Input Alert	1: Upper Limit Input Alert	1: Upper Limit Input Alert	1: Upper Limit Input Alert
Alert set value 1	Set the temperature where CH□ Alert 1 (b8 of Un\G5 to Un\G8) turns on.	250°C	300°C	350°C	400°C

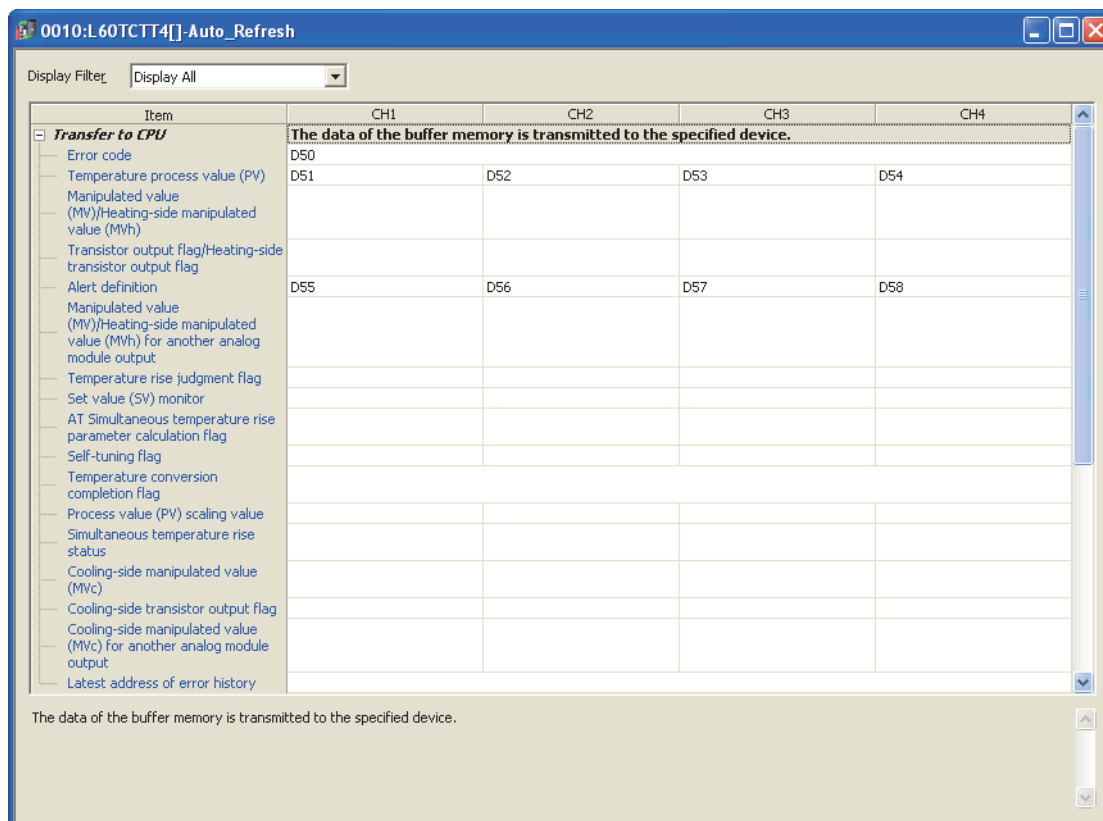
^{*1} Configure this setting only when the simultaneous temperature rise function is used.

^{*2} Configure this setting only when the peak current suppression function is used.

(c) Auto refresh setting

Set the device to be automatically refreshed.

 Project window ⇒ [Intelligent Function Module] ⇒ [L60TCTT4] ⇒ [Auto_Refresh]



Item	Description	Setting value			
		CH1	CH2	CH3	CH4
Error code	An error code or alarm code is stored.	D50			
Temperature process value (PV)	The detected temperature value where sensor correction was performed is stored.	D51	D52	D53	D54
Alert definition	The value is stored depending on the detected alert.	D55	D56	D57	D58

Remark

The number of parameters of the auto refresh setting can be reduced by using the setting item reduction mode of auto refresh.

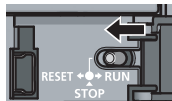
When the setting item reduction mode is set, consecutive devices are automatically set to the grouped setting items. For details on the setting item reduction mode of auto refresh, refer to the following.

 Page 116, Section 7.4

(d) Writing parameter of an intelligent function module

Write the set parameter to the CPU module. Then reset the CPU module or turn off and on the power supply of the programmable controller.

 [Online] ⇒ [Write to PLC...]



or Power OFF → ON

(e) Performing auto tuning

Set the "Automatic backup setting after auto tuning of PID constants" to "ON" and perform the auto tuning.

 [Tool] ⇒ [Intelligent Function Module Tool] ⇒ [Temperature Control Module]

⇒ [Auto Tuning...] ⇒ [L60TCTT4] ⇒ 

Auto Tuning

Monitoring

Start Monitor

Stop Monitor

Executes auto tuning.

Target Module: 0010:L60TCTT4

Mode

Setting Mode

Change Mode

Error Code (HEX)

Detail Display ...

Error Clear

Auto Tuning Execution

Auto Tuning Setting

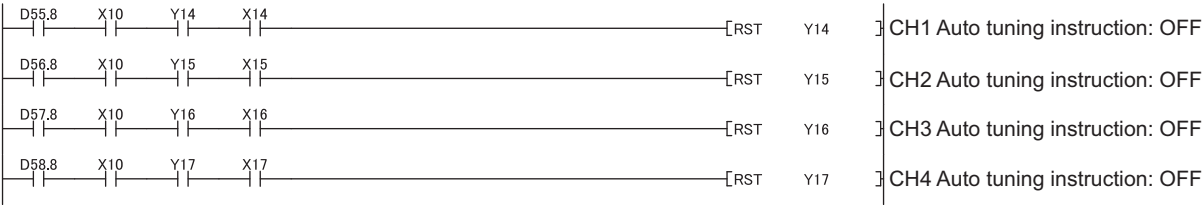
Item	CH1	CH2	CH3	CH4
PID control	PID control operation status			
Process value (PV)	0 C	0 C	0 C	0 C
Set value (SV)	200 C	250 C	300 C	350 C
Manipulated value (MV)/Heating-side manipulated value (MVh)	-5.0 %	-5.0 %	-5.0 %	-5.0 %
Cooling-side manipulated value (MVc)	0.0 %	0.0 %	0.0 %	0.0 %
PID constant	PID constant current value			
Proportional band (P) setting/Heating control proportional band setting (Ph)	3.0 %	3.0 %	3.0 %	3.0 %
Cooling-side proportional band (Pc) setting	0.0 %	0.0 %	0.0 %	0.0 %
Integral time (I) setting	240 s	240 s	240 s	240 s
Derivative time (D) setting	60 s	60 s	60 s	60 s
Loop disconnection detection judgment time	480 s	480 s	480 s	480 s
Auto tuning execution	Executes auto tuning.			
Auto tuning start	Start	Start	Start	Start
Auto tuning stop	Stop	Stop	Stop	Stop
Status	Not executed	Not executed	Not executed	Not executed
Result of automatic backup of PID constant	----	----	----	----

The time between the start and completion of auto tuning depends on the object to be controlled.
After auto tuning starts, this window can be closed.

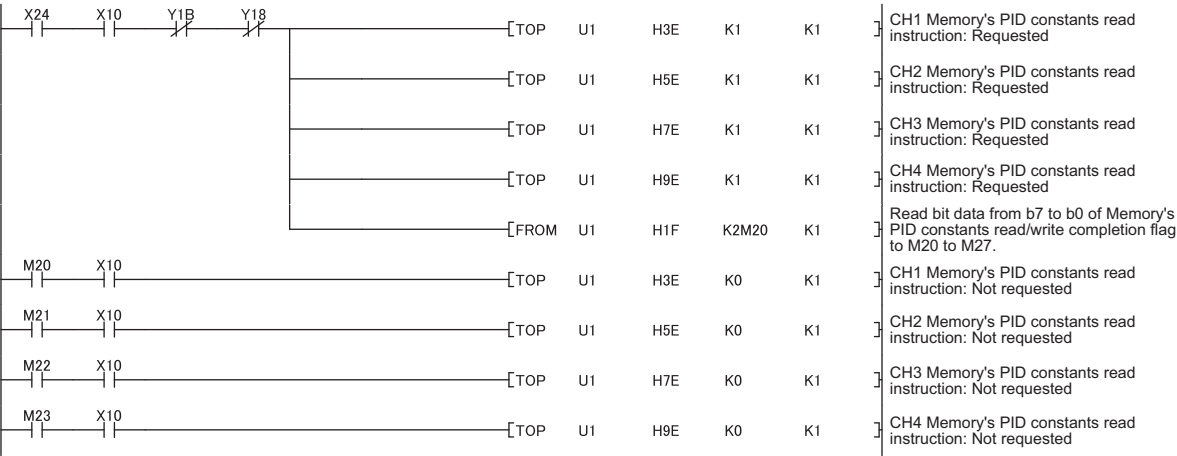
Close

(f) Program example where the peak current suppression function or the simultaneous temperature rise function is used

- Program that changes the setting/operation mode
This program is the same as that of when it is used as a temperature input module. (Page 266, Section 10.2.1 (6) (e))
- Program that stops the auto tuning when an alert is detected



- Program that reads the PID constants from the non-volatile memory



- Program that reads an error code
This program is the same as that of when it is used as a temperature input module. (Page 266, Section 10.2.1 (6) (e))

(7) Program example of when not using the parameter of an intelligent function module

(a) Devices used by a user

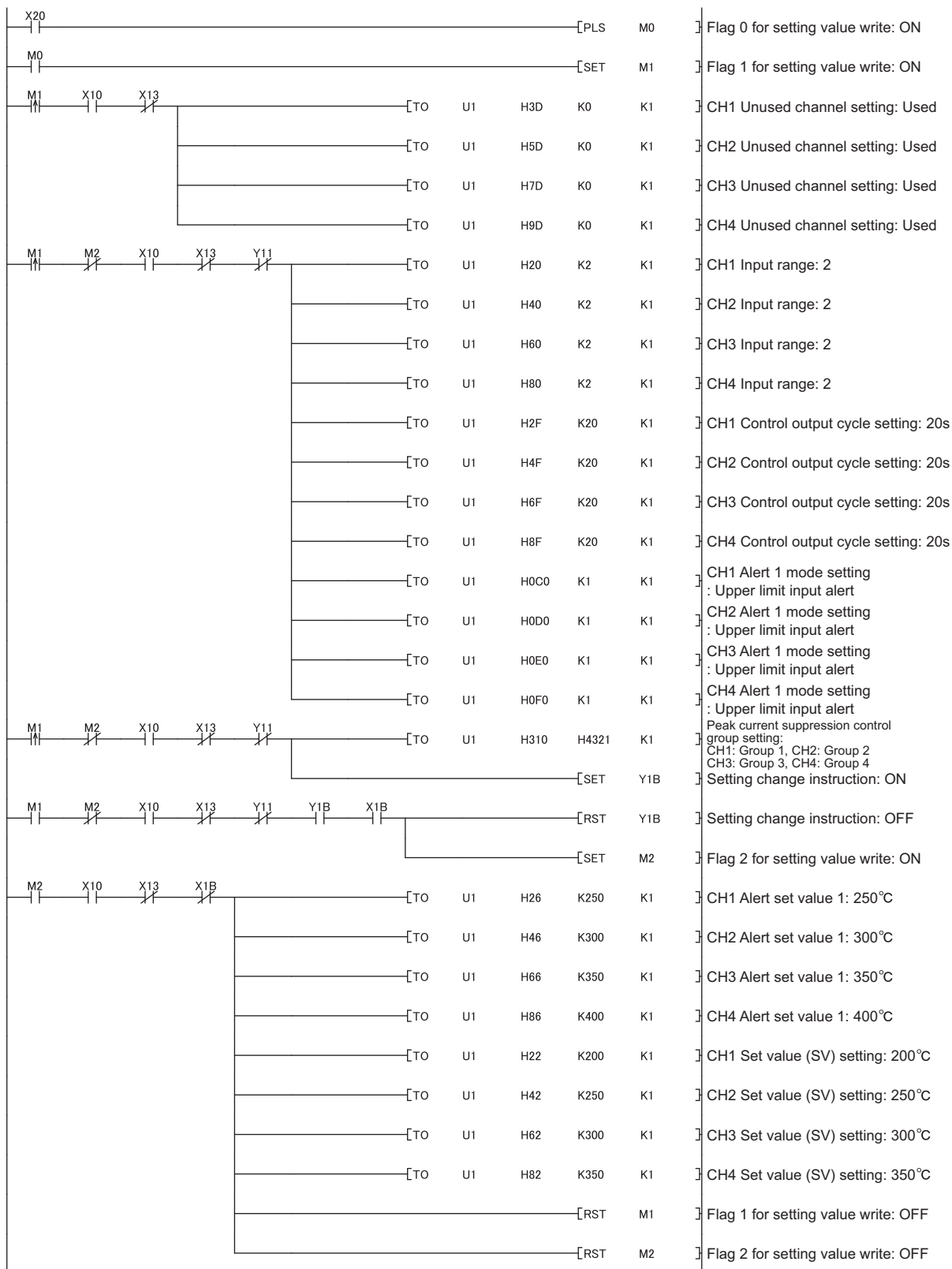
Device	Description	
X10	Module READY flag	L60TCTT4 (X10 to X1F)
X11	Setting/operation mode status	
X12	Error occurrence flag	
X13	Hardware error flag	
X14 to X17	CH□ Auto tuning status	
X18	Back-up of the set value completion flag	
X1B	Setting change completion flag	LX42C4 (X20 to X5F)
X20	Set value write instruction	
X21	Auto tuning execute instruction	
X22	Error code reset instruction	
X23	Operation mode setting instruction	
X24	Memory's PID constants read instruction	
Y11	Setting/operation mode instruction	L60TCTT4 (Y10 to Y1F)
Y12	Error reset instruction	
Y14 to Y17	CH□ Auto tuning instruction	
Y18	Set value backup instruction	
Y1B	Setting change instruction	
Y60 to Y6F	Error code output	LY42NT1P (Y60 to Y9F)
D50	Error code	
D51 to D54	CH□ Temperature process value (PV)	
D55 to D58	CH□ Alert definition	
M0	Flag 0 for setting value write	
M1	Flag 1 for setting value write	
M2	Flag 2 for setting value write	
M10 to M13	CH□ Auto tuning completion flag	
M20 to M23	CH□ Read completion flag	
M24 to M27	CH□ Write completion flag	

(b) Program example where the peak current suppression function is used

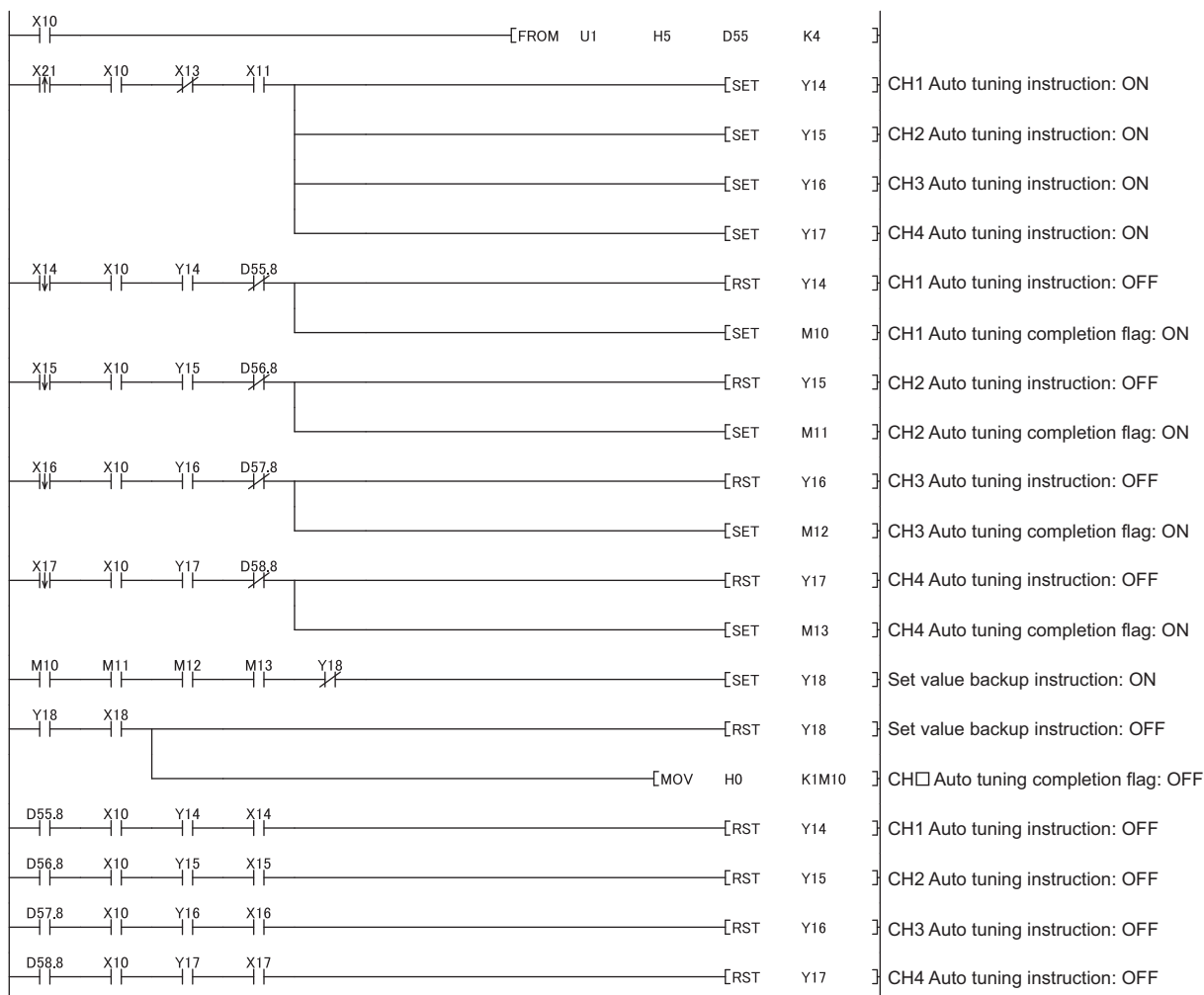
- Program that changes the setting/operation mode

This is the same as that of when it is used as a temperature input module. (☞ Page 266, Section 10.2.1 (6) (e))

- Initial setting program

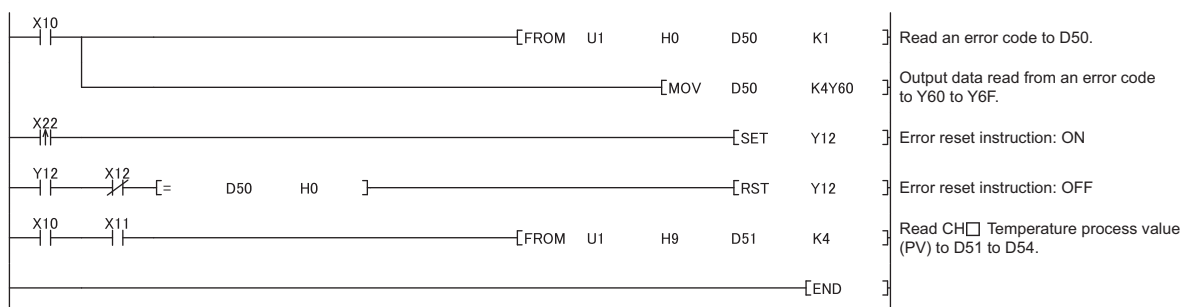


- Program that executes the auto tuning and backs up the PID constants in the non-volatile memory if the auto tuning is normally completed (The auto tuning is stopped when an alert is detected.)



- Program that reads the PID constants from the non-volatile memory
This program is the same as that of when the parameter of the intelligent function module is used.
(Page 291, Section 10.2.3 (6) (f))

- Program that reads an error code and the temperature process value (PV)

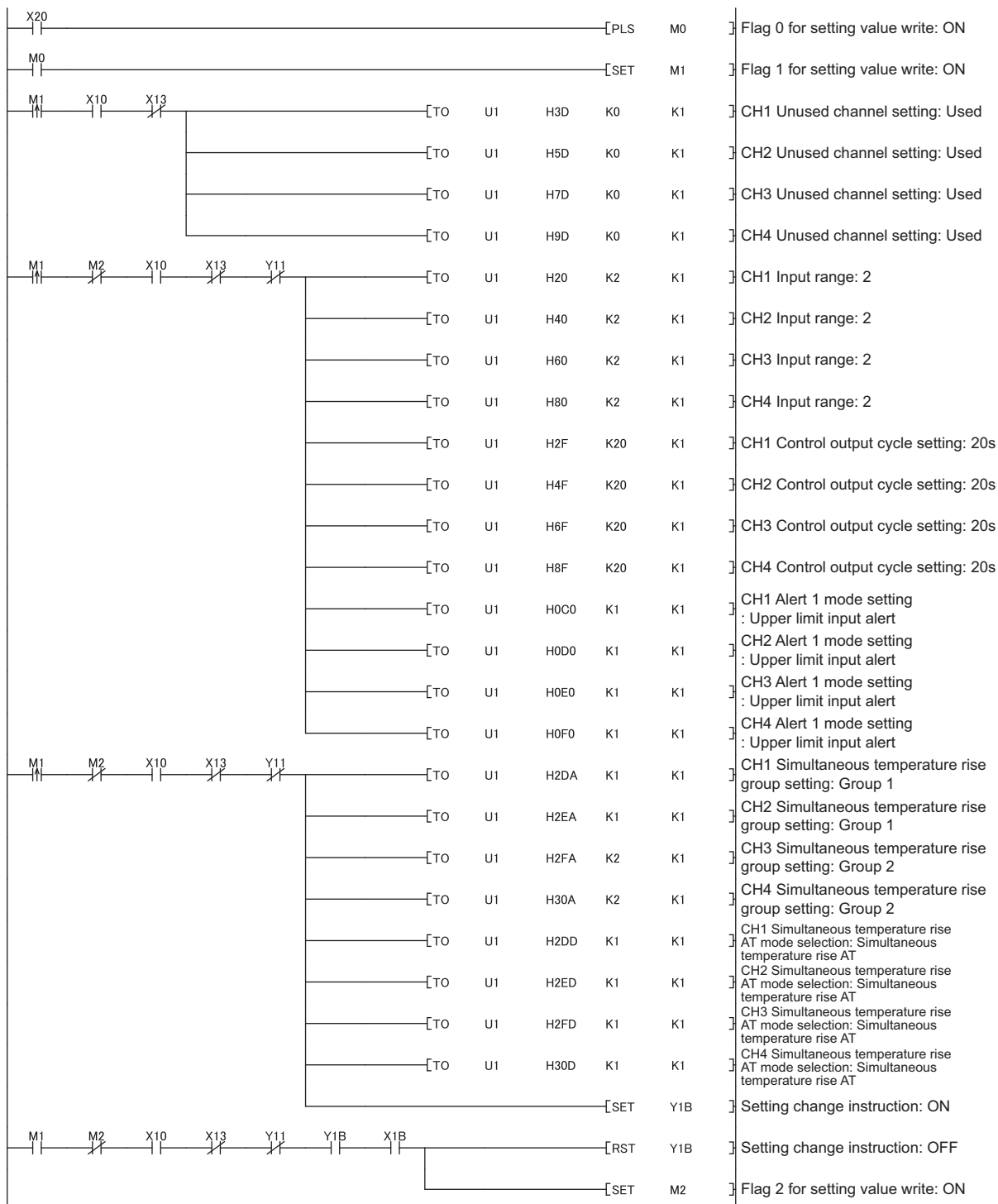


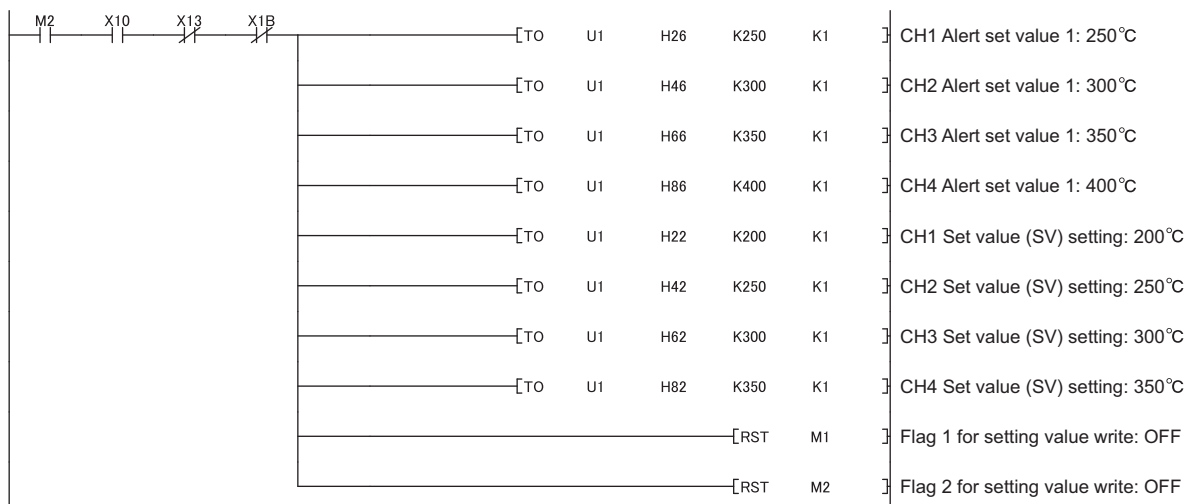
(c) Program example where the simultaneous temperature rise function is used

- Program that changes the setting/operation mode

This program is the same as that of when it is used as a temperature input module. (➡ Page 266, Section 10.2.1 (6) (e))

- Initial setting program





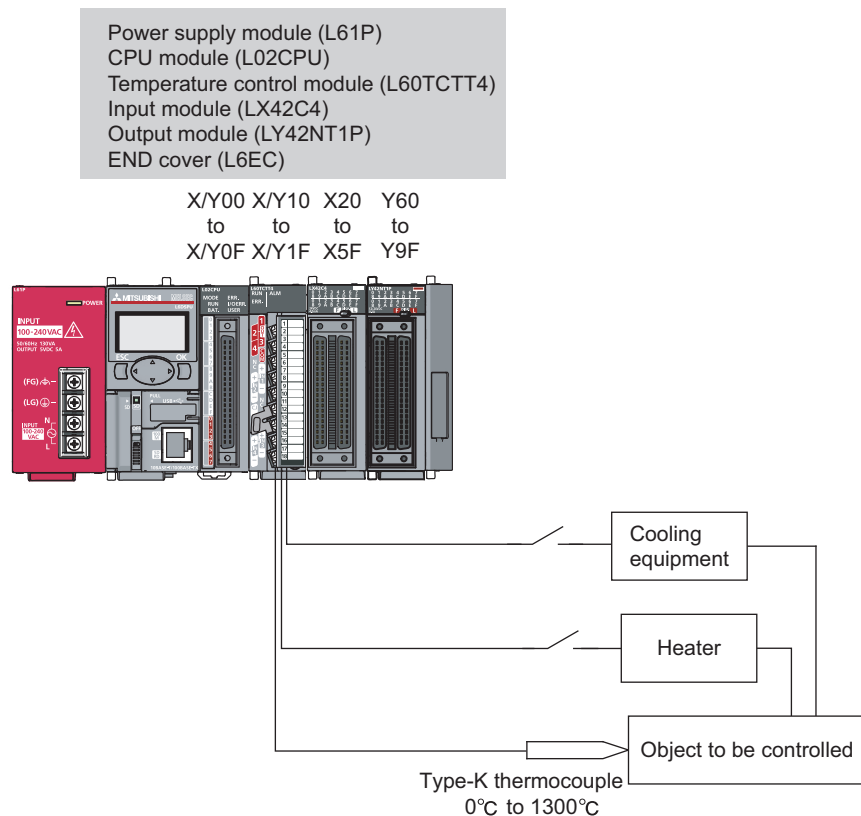
- Program that executes the auto tuning and backs up the PID constants in the non-volatile memory if the auto tuning is normally completed (The auto tuning is stopped when an alert is detected.)
This program is the same as that of when the peak current suppression function is used. (Page 293, Section 10.2.3 (7) (b))
- Program that reads the PID constants from the non-volatile memory
This program is the same as that of when the parameter of the intelligent function module is used. (Page 291, Section 10.2.3 (6) (f))
- Program that reads an error code
This program is the same as that of when the peak current suppression function is used. (Page 293, Section 10.2.3 (7) (b))

10.2.4 When performing the heating-cooling control

This section describes the program example to perform the heating-cooling control.

(1) System configuration

The following figure shows the system configuration example to perform the heating-cooling control.



Point

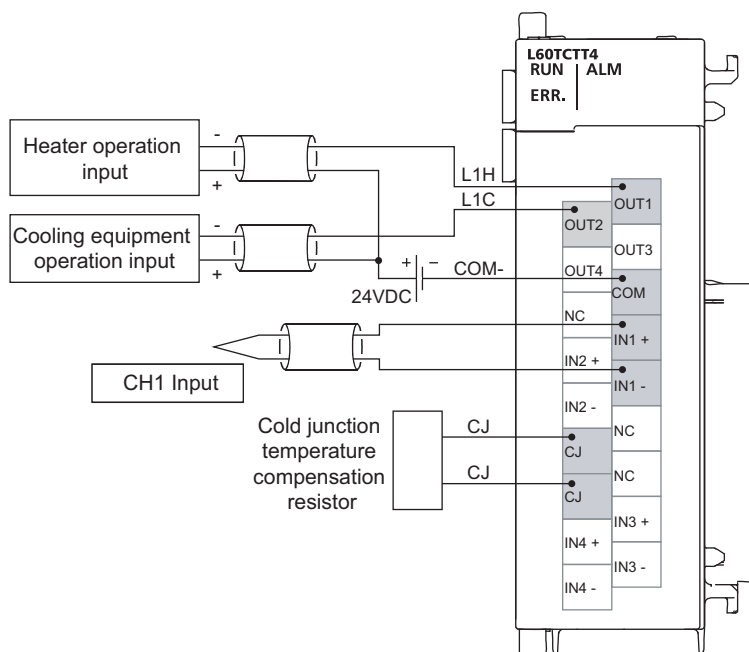
- When using the L26CPU-BT, set the I/O assignment of the built-in CC-Link of the L26CPU-BT to X/YFE0 to X/YFFF so that the I/O assignment be the same as that of the system configuration above.
- When the L60TCTT4BW or the L60TCRT4BW is used, the I/O assignment is the same as that of the system configuration shown above.
 - Slot 0: Intelligent 16 points
 - Slot 1: Input 64 points
 - Slot 2: Output 64 points

(2) Program conditions

This program is designed to perform the heating-cooling control by using the temperature input of CH1.

(3) Wiring example

The following figure shows a wiring example.



(4) Switch Setting

Configure settings such as the input mode selection and the auto-setting at input range change as follows.

 Project window ⇨ [Intelligent Function Module] ⇨ [L60TCTT4] ⇨ [Switch Setting]

Switch Setting 0010:L60TCTT4

Input Mode Selection

Temperature Input Mode

Temperature Control Mode

Temperature Control Mode Setting

Output Setting at CPU Stop Error

CH	Output Setting at CPU Stop Error
CH1	0: CLEAR
CH2	0: CLEAR
CH3	0: CLEAR
CH4	0: CLEAR

Control Mode Selection

3: Mix Control (Normal Mode)

Setting Change Rate Limiter Setting

0: Temperature Rise/Temperature Drop Batch Setting

Control Output Cycle Unit Selection Setting

0: 1s Cycle

Auto-setting at Input Range Change

0: Disable

Sampling Cycle Selection

0: 500ms

Moving Averaging Process Setting

0: Enable

Moving Averaging Process Setting is available for Product Information 14062000000000-A or later.

(Caution)
This dialog setting is linked to the Switch Setting of the PLC parameter. Default value will be shown in the dialog if the Switch Setting of the PLC parameter contains an out-of-range value.

OK

Cancel

Item		Setting value			
		CH1	CH2	CH3	CH4
Input Mode Selection		Temperature Control Mode			
Temperature Control Mode Setting	Output Setting at CPU Stop Error	0: CLEAR	0: CLEAR	0: CLEAR	0: CLEAR
	Control Mode Selection	3: Mix Control (Normal Mode)			
	Setting Change Rate Limiter Setting	0: Temperature Rise/Temperature Drop Batch Setting			
	Control Output Cycle Unit Selection Setting	0: 1s Cycle			
Auto-setting at Input Range Change		0: Disable			
Sampling Cycle Selection		0: 500ms			
Moving Averaging Process Setting		0: Enable			

10.2 When Using the Module in a Standard System Configuration
10.2.4 When performing the heating-cooling control

(5) Contents of the initial setting

Item	Description			
	CH1	CH2	CH3	CH4
Input range	2: Thermocouple K Measured Temperature Range (0 to 1300°C)	2: Thermocouple K Measured Temperature Range (0 to 1300°C)	2: Thermocouple K Measured Temperature Range (0 to 1300°C)	2: Thermocouple K Measured Temperature Range (0 to 1300°C)
Set value (SV) setting	200°C	0°C	0°C	0°C
Unused channel setting	0: Used	0: Used	1: Unused	1: Unused
Heating control output cycle setting	30s	0s	30s	30s
Cooling method setting	0: Air Cooled	0: Air Cooled	0: Air Cooled	0: Air Cooled
Cooling control output cycle setting	30s	0s	30s	30s
Overlap/Dead band setting	-0.3 %	0.0 %	0.0 %	0.0 %
Alert 1 mode setting	1: Upper Limit Input Alert	0: Not Warning	0: Not Warning	0: Not Warning
Alert set value 1	250°C	0°C	0°C	0°C

(6) When using the parameter of an intelligent function module

(a) Devices used by a user

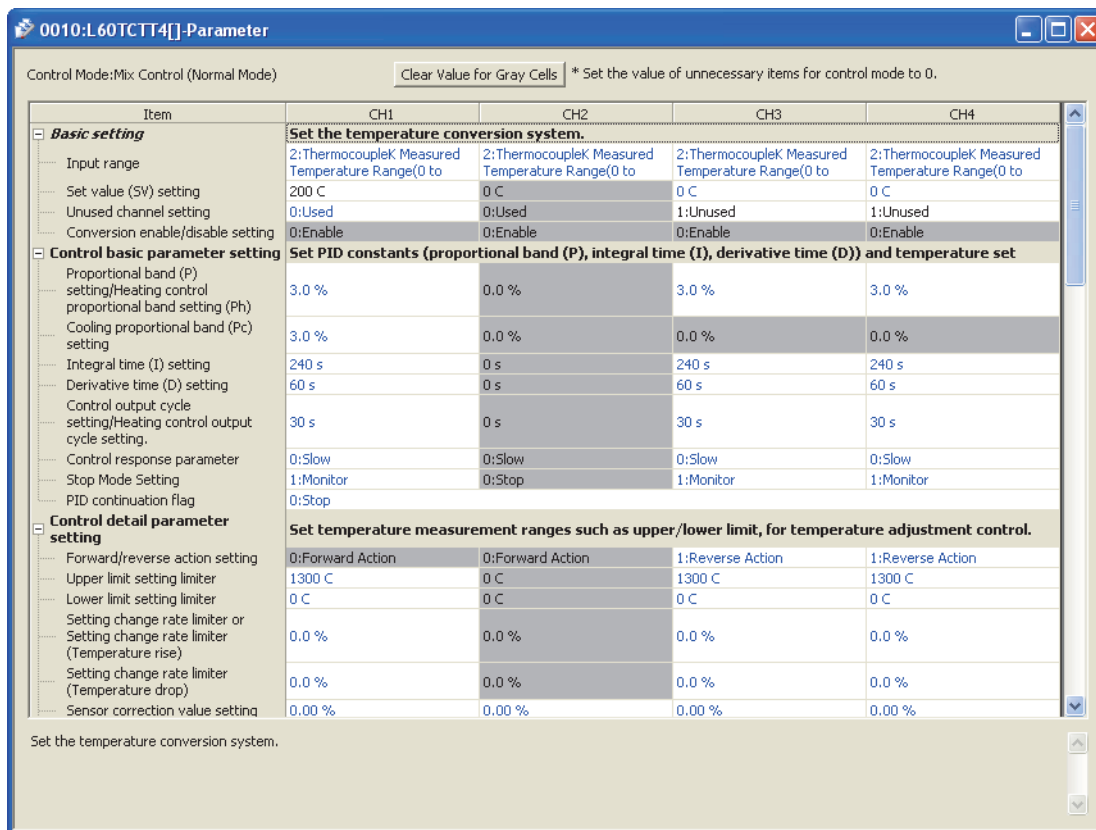
Device	Description	
X10	Module READY flag	L60TCTT4 (X10 to X1F)
X12	Error occurrence flag	
X22	Error code reset instruction	LX42C4 (X20 to X5F)
X23	Operation mode setting instruction	
X24	Memory's PID constants read instruction	
Y11	Setting/operation mode instruction	L60TCTT4 (Y10 to Y1F)
Y12	Error reset instruction	
Y18	Set value backup instruction	
Y1B	Setting change instruction	LY42NT1P (Y60 to Y9F)
Y60 to Y6F	Error code output	
D50	Error code	
D51	CH1 Temperature process value (PV)	Devices where data is written by auto refresh
D55	CH1 Alert definition	
M20 to M23	CH□ Read completion flag	
M24 to M27	CH□ Write completion flag	

(b) Parameter setting

Set the contents of initial settings in the parameter.

1. Open the "Parameter" window.

 Project window ⇨ [Intelligent Function Module] ⇨ [L60TCTT4] ⇨ [Parameter]

2. Click to set items unnecessary for the mode set on Switch Setting to 0.**3. Set the parameter.**

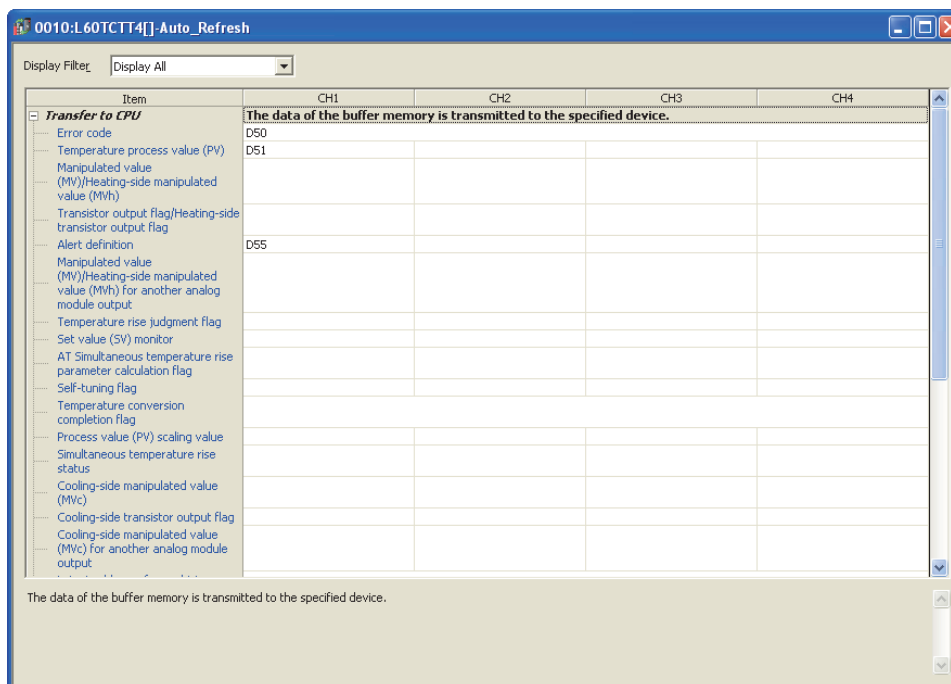
Item	Description	Setting value			
		CH1	CH2	CH3	CH4
Input range	Set the temperature sensor used for the L60TC4 and the measurement range.	2: Thermocouple K Measured Temperature Range (0 to 1300°C)	2: Thermocouple K Measured Temperature Range (0 to 1300°C)	2: Thermocouple K Measured Temperature Range (0 to 1300°C)	2: Thermocouple K Measured Temperature Range (0 to 1300°C)
Set value (SV) setting	Set the target temperature value of PID control.	200°C	0°C	0°C	0°C
Unused channel setting	Configure this setting when the channels where the temperature control is not performed and the temperature sensor is not connected are set to be unused.	0: Used	0: Used	1: Unused	1: Unused
Control output cycle setting/Heating control output cycle setting	Set the pulse cycle (ON/OFF cycle) of the transistor output.	30s	0s	30s	30s

Item	Description	Setting value			
		CH1	CH2	CH3	CH4
Cooling method setting	Set the method for the cooling control in the heating-cooling control.	0: Air Cooled	0: Air Cooled	0: Air Cooled	0: Air Cooled
Cooling control output cycle setting	Set the pulse cycle (ON/OFF cycle) of the transistor output.	30s	0s	30s	30s
Overlap/dead band setting	Configure the overlap/dead band setting.	-0.3 %	0.0 %	0.0 %	0.0 %
Alert 1 mode setting	Set the alert mode.	1: Upper Limit Input Alert	0: Not Warning	0: Not Warning	0: Not Warning
Alert set value 1	Set the temperature where CH□ Alert 1 (b8 of Un\G5 to Un\G8) turns on.	250°C	0°C	0°C	0°C

(c) Auto refresh setting

Set the device to be automatically refreshed.

 Project window ⇒ [Intelligent Function Module] ⇒ [L60TCTT4] ⇒ [Auto_Refresh]



Item	Description	Setting value			
		CH1	CH2	CH3	CH4
Error code	An error code or alarm code is stored.	D50			
Temperature process value (PV)	The detected temperature value where sensor correction is performed is stored.	D51	—	—	—
Alert definition	The value is stored depending on the detected alert.	D55	—	—	—

Remark

The number of parameters of the auto refresh setting can be reduced by using the setting item reduction mode of auto refresh.

When the setting item reduction mode is set, consecutive devices are automatically set to the grouped setting items.

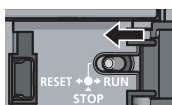
For details on the setting item reduction mode of auto refresh, refer to the following.

 Page 116, Section 7.4

(d) Writing parameter of an intelligent function module

Write the set parameter to the CPU module. Then reset the CPU module or turn off and on the power supply of the programmable controller.

 [Online] ⇒ [Write to PLC...]

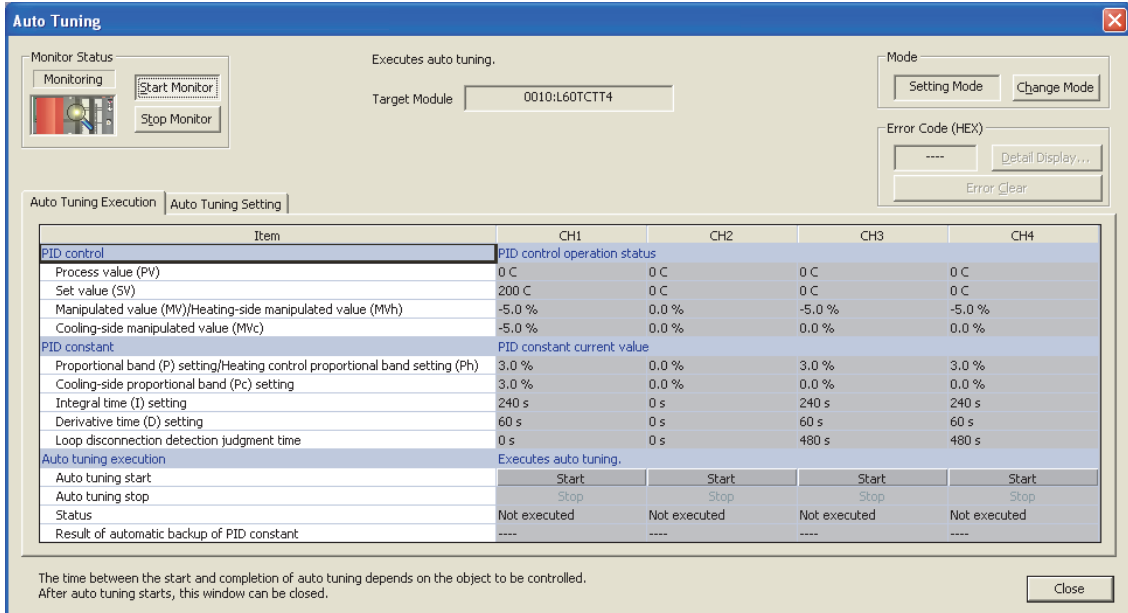


or Power OFF → ON

(e) Performing auto tuning

Set the "Automatic backup setting after auto tuning of PID constants" to "ON" and perform the auto tuning.

☞ [Tool] ⇨ [Intelligent Function Module Tool] ⇨ [Temperature Control Module]
 ⇨ [Auto Tuning...] ⇨ "L60TCTT4" ⇨ 



The screenshot shows the 'Auto Tuning' window. It has a 'Monitor Status' section with 'Monitoring' selected and buttons for 'Start Monitor' and 'Stop Monitor'. The 'Target Module' is set to '0010:L60TCTT4'. The 'Mode' section has 'Setting Mode' selected and a 'Change Mode' button. The 'Error Code (HEX)' section shows '----' and buttons for 'Detail Display...' and 'Error Clear'. The main area is divided into 'Auto Tuning Execution' and 'Auto Tuning Setting' tabs. The 'Auto Tuning Execution' tab is active, showing a table with columns for 'Item', 'CH1', 'CH2', 'CH3', and 'CH4'. The table lists various PID control parameters and their current values for four channels. At the bottom, there is a 'Close' button and a note: 'The time between the start and completion of auto tuning depends on the object to be controlled. After auto tuning starts, this window can be closed.'

Item	CH1	CH2	CH3	CH4
PID control	PID control operation status			
Process value (PV)	0 C	0 C	0 C	0 C
Set value (SV)	200 C	0 C	0 C	0 C
Manipulated value (MV)/Heating-side manipulated value (MVh)	-5.0 %	0.0 %	-5.0 %	-5.0 %
Cooling-side manipulated value (MVc)	-5.0 %	0.0 %	0.0 %	0.0 %
PID constant	PID constant current value			
Proportional band (P) setting/Heating control proportional band setting (Ph)	3.0 %	0.0 %	3.0 %	3.0 %
Cooling-side proportional band (Pc) setting	3.0 %	0.0 %	0.0 %	0.0 %
Integral time (I) setting	240 s	0 s	240 s	240 s
Derivative time (D) setting	60 s	0 s	60 s	60 s
Loop disconnection detection judgment time	0 s	0 s	480 s	480 s
Auto tuning execution	Executes auto tuning.			
Auto tuning start	Start	Start	Start	Start
Auto tuning stop	Stop	Stop	Stop	Stop
Status	Not executed	Not executed	Not executed	Not executed
Result of automatic backup of PID constant	----	----	----	----

(f) Program example

- Program that changes the setting/operation mode

This program is the same as that of when it is used as a temperature input module. (☞ Page 266, Section 10.2.1 (6) (e))

- Program that stops the auto tuning when an alert is detected

This program is used when the module is in the standard control (such as auto tuning, self-tuning, and error code read).

(☞ Page 278, Section 10.2.2 (6) (f))

- Program that reads the PID constants from the non-volatile memory

This program is used when the module is in the standard control (such as auto tuning, self-tuning, and error code read). (☞ Page 278, Section 10.2.2 (6) (f))

- Program that reads an error code

This program is the same as that of when it is used as a temperature input module. (☞ Page 266, Section 10.2.1 (6) (e))

(7) Program example of when not using the parameter of an intelligent function module

(a) Devices used by a user

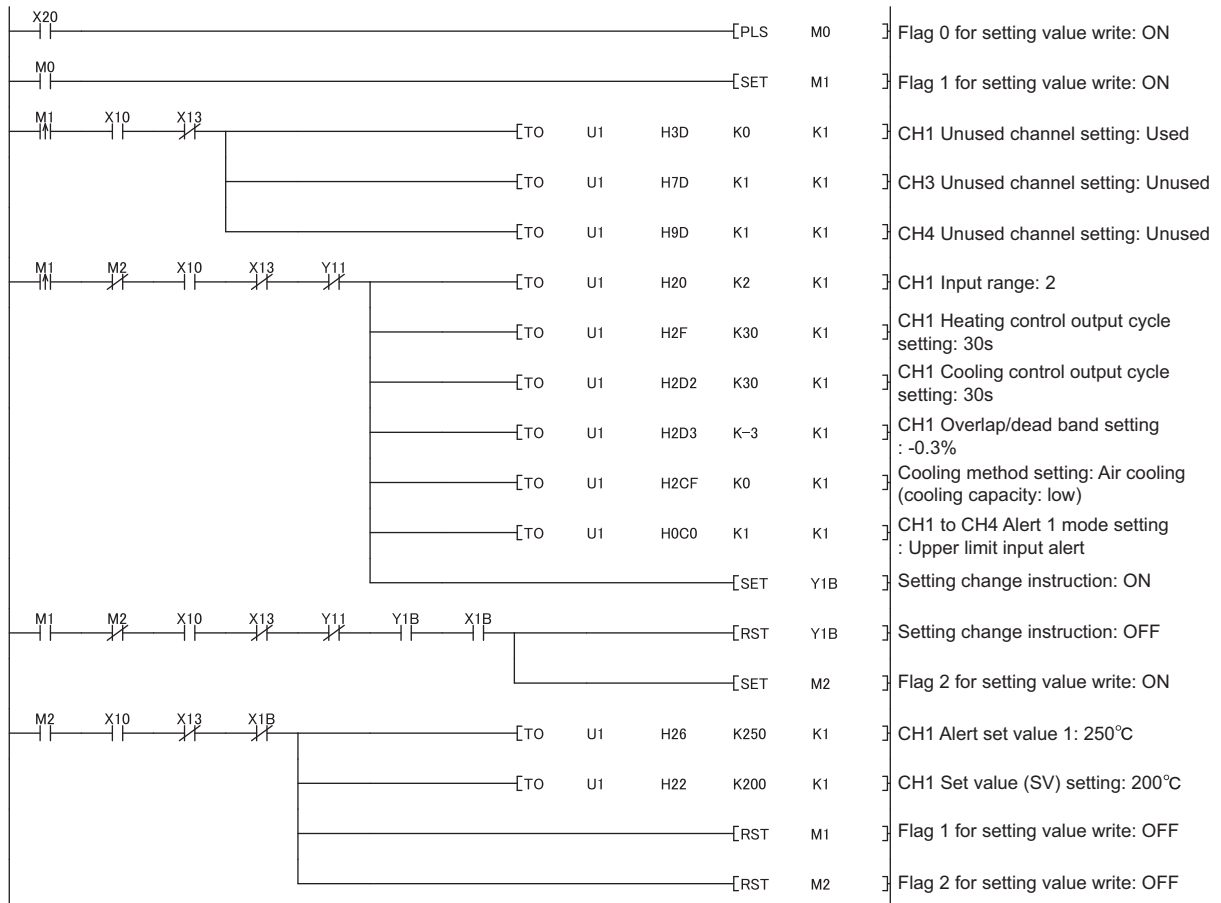
Device	Description	
X10	Module READY flag	L60TCTT4 (X10 to X1F)
X11	Setting/operation mode status	
X12	Error occurrence flag	
X13	Hardware error flag	
X14	CH1 Auto tuning status	
X18	Back-up of the set value completion flag	
X1B	Setting change completion flag	LX42C4 (X20 to X5F)
X20	Set value write instruction	
X21	Auto tuning execute instruction	
X22	Error code reset instruction	
X23	Operation mode setting instruction	
X24	Memory's PID constants read instruction	
Y11	Setting/operation mode instruction	L60TCTT4 (Y10 to Y1F)
Y12	Error reset instruction	
Y14	CH1 Auto tuning instruction	
Y18	Set value backup instruction	
Y1B	Setting change instruction	
Y60 to Y6F	Error code output	LY42NT1P (Y60 to Y9F)
D50	Error code	
D51	CH1 Temperature process value (PV)	
D55	CH1 Alert definition	
M0	Flag 0 for setting value write	
M1	Flag 1 for setting value write	
M2	Flag 2 for setting value write	
M10	CH1 Auto tuning completion flag	
M20 to M23	CH□ Read completion flag	
M24 to M27	CH□ Write completion flag	

(b) Program example

- Program that changes the setting/operation mode

This program is the same as that of when it is used as a temperature input module. (☞ Page 266, Section 10.2.1 (6) (e))

- Initial setting program



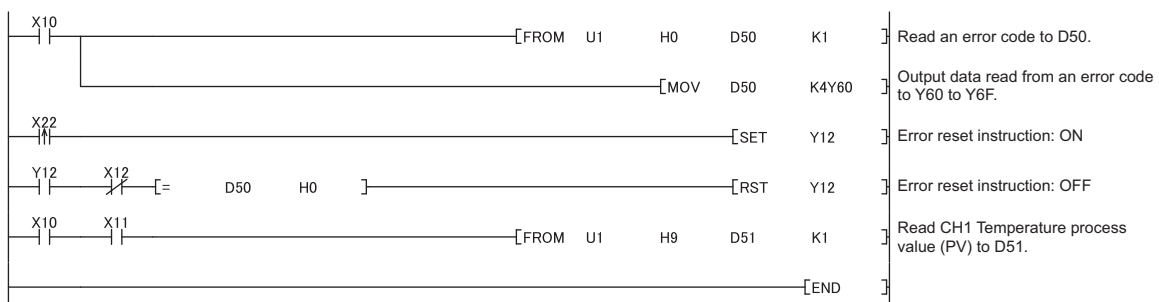
- Program that executes the auto tuning and backs up the PID constants in the non-volatile memory if the auto tuning is normally completed (The auto tuning is stopped when an alert is detected.)

This program is used when the module is in the standard control (such as auto tuning, self-tuning, and error code read). (☞ Page 280, Section 10.2.2 (7) (b))

- Program that reads the PID constants from the non-volatile memory

This program is used when the module is in the standard control (such as auto tuning, self-tuning, and error code read). (☞ Page 278, Section 10.2.2 (6) (f))

- Program that reads an error code

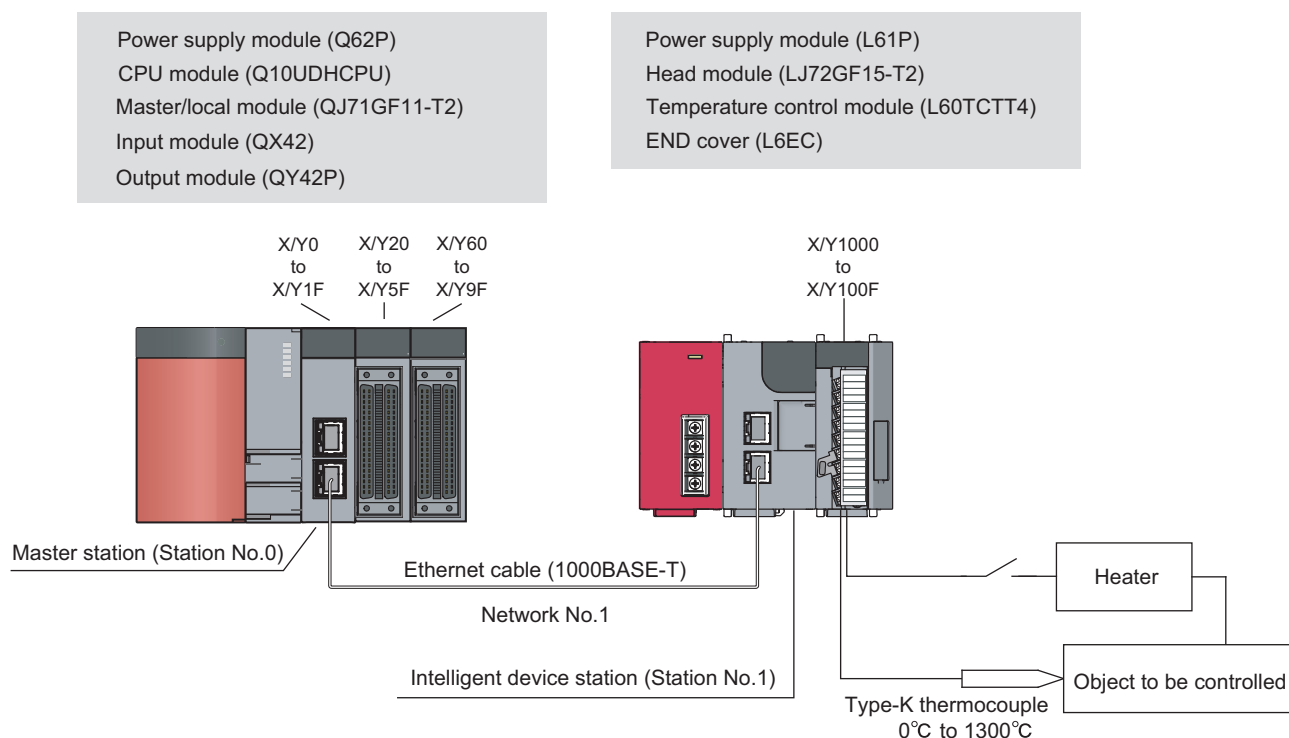


10.3 When the Module is Connected to the Head Module

This section describes the program example of when the module is connected to the head module.

(1) System configuration

The following figure shows the system configuration example of when the module is connected to the head module.



Point

When the L60TCTT4BW or the L60TCRT4BW is used, the I/O assignment is the same as that of the system configuration shown above.

- Slot 0: 16 intelligent points
- Slot 1: 64 input points
- Slot 2: 64 output points

(2) Programming condition

This program is designed to read the temperatures measured by the thermocouple (K type, 0 to 1300°C) connected to CH1.

An error code can be read and reset.

(3) Wiring example

The wiring is the same as the that of when the module is in the standard control (such as auto tuning, self-tuning, and error code read). (☞ Page 271, Section 10.2.2 (3))

(4) Switch Setting

Configure settings on the intelligent device station. (☞ Page 311, Section 10.3 (7))

(5) Contents of the initial setting

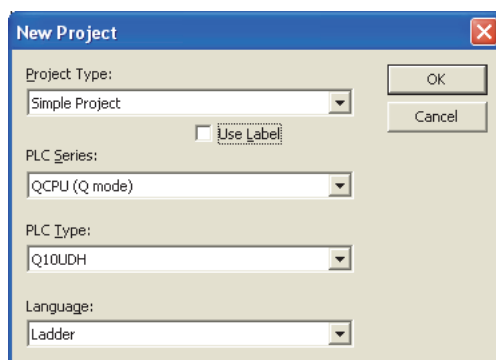
Item	Description			
	CH1	CH2	CH3	CH4
Input range	2: ThermocoupleK Measured Temperature Range (0 to 1300°C)	2: ThermocoupleK Measured Temperature Range (0 to 1300°C)	2: ThermocoupleK Measured Temperature Range (0 to 1300°C)	2: ThermocoupleK Measured Temperature Range (0 to 1300°C)
Set value (SV) setting	200°C	0°C	0°C	0°C
Unused channel setting	0: Used	1: Unused	1: Unused	1: Unused
Upper limit setting limiter	400°C	1300°C	1300°C	1300°C
Lower limit setting limiter	0°C	0°C	0°C	0°C
Alert 1 mode setting	1: Upper Limit Input Alert	0: Not Warning	0: Not Warning	0: Not Warning
Alert set value 1	250°C	0°C	0°C	0°C

(6) Setting on the master station

1. Create a project on GX Works2.

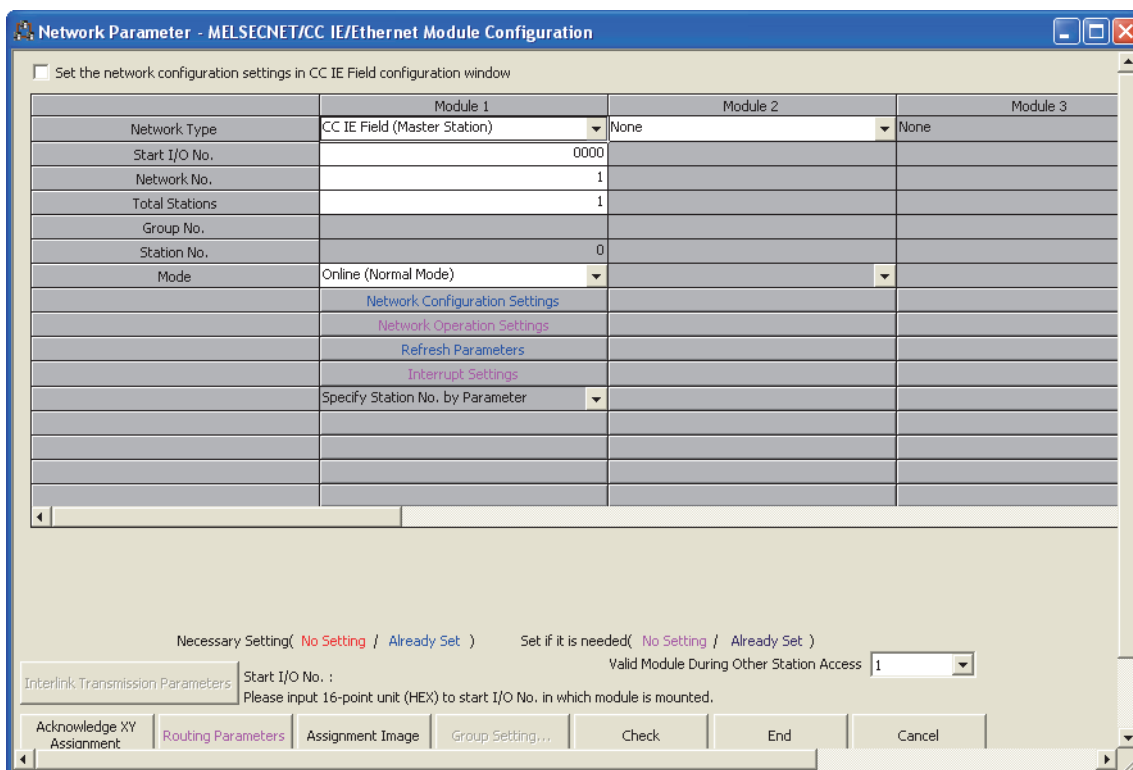
Select "QCPU (Q mode)" for "PLC Series:" and select the CPU module to be used for "PLC Type:".

☞ [Project] ➡ [New...]



2. Display the network parameter setting window and configure the setting as follows.

 Project window ⇨ [Parameter] ⇨ [Network Parameter]
 ⇨ [Ethernet/CC IE/MELSECNET]



Set the network configuration settings in CC IE Field configuration window

	Module 1	Module 2	Module 3
Network Type	CC IE Field (Master Station)	None	None
Start I/O No.	0000		
Network No.	1		
Total Stations	1		
Group No.			
Station No.	0		
Mode	Online (Normal Mode)		
	Network Configuration Settings		
	Network Operation Settings		
	Refresh Parameters		
	Interrupt Settings		
	Specify Station No. by Parameter		

Necessary Setting(No Setting / Already Set) Set if it is needed(No Setting / Already Set)

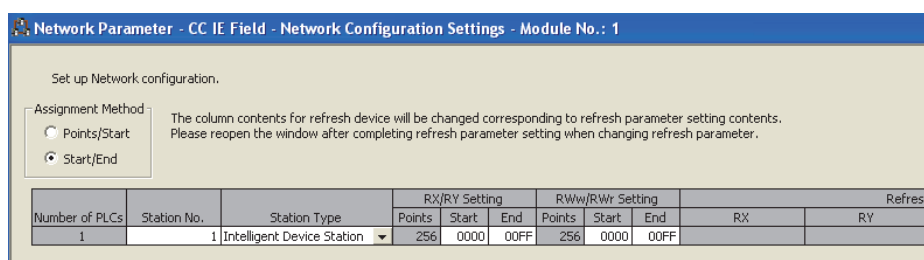
Interlink Transmission Parameters Start I/O No. : Valid Module During Other Station Access 1

Please input 16-point unit (HEX) to start I/O No. in which module is mounted.

Acknowledge XY Assignment Routing Parameters Assignment Image Group Setting... Check End Cancel

3. Display the network range assignment setting window and configure the setting as follows.

 Project window ⇨ [Parameter] ⇨ [Network Parameter]
 ⇨ [Ethernet/CC IE/MELSECNET] ⇨ **Network Configuration Settings**



Set up Network configuration.

Assignment Method

☐ Points/Start
☒ Start/End

The column contents for refresh device will be changed corresponding to refresh parameter setting contents. Please reopen the window after completing refresh parameter setting when changing refresh parameter.

Number of PLCs	Station No.	Station Type	RX/RX Setting			RWw/RWw Setting			Refresh	
			Points	Start	End	Points	Start	End	RX	RY
1	1	Intelligent Device Station	256	0000	00FF	256	0000	00FF		

4. Display the refresh parameter setting window and configure the setting as follows.

Project window ⇨ [Parameter] ⇨ [Network Parameter]

⇨ [Ethernet/CC IE/MELSECNET] ⇨ **Refresh Parameters**

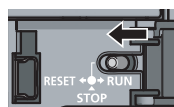
Network Parameter - CC IE Field - Refresh Parameters - Module No.: 1

Assignment Method
☐ Points/Start
☒ Start/End

	Link Side					PLC Side			
	Dev. Name	Points	Start	End		Dev. Name	Points	Start	End
Transfer SB	SB	512	0000	01FF	↔	SB	512	0000	01FF
Transfer SW	SW	512	0000	01FF	↔	SW	512	0000	01FF
Transfer 1	RX	256	0000	00FF	↔	X	256	1000	10FF
Transfer 2	RY	256	0000	00FF	↔	Y	256	1000	10FF
Transfer 3	RWw	256	0000	00FF	↔	W	256	000000	0000FF
Transfer 4	RWr	256	0000	00FF	↔	W	256	001000	0010FF
Transfer 5					↔				
Transfer 6					↔				

5. Write the set parameter to the CPU module on the master station. Then reset the CPU module or turn off and on the power supply of the programmable controller.

[Online] ⇨ [Write to PLC...]



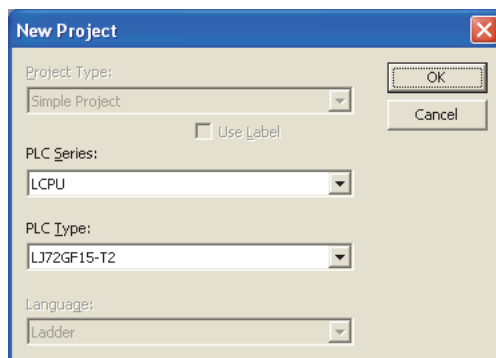
or Power OFF → ON

(7) Setting on the intelligent device station

1. Create a project on GX Works2.

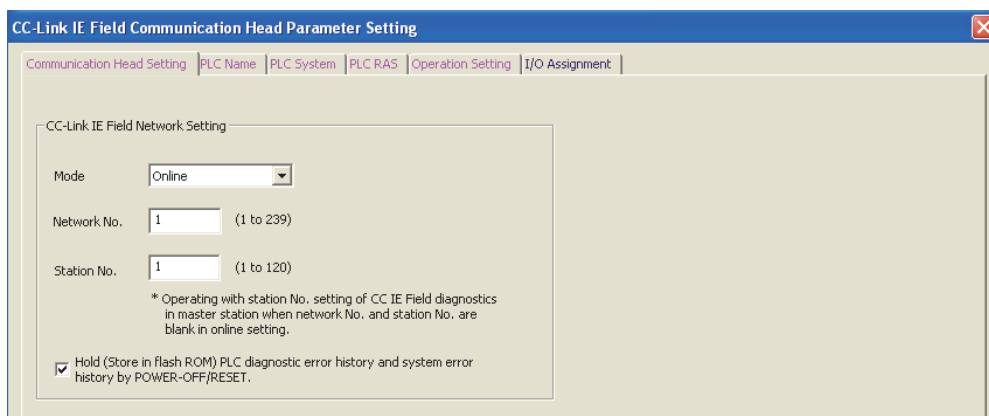
Select "LCPU" for "PLC Series:" and select "LJ72GF15-T2" for "PLC Type:".

 [Project] ⇒ [New...]



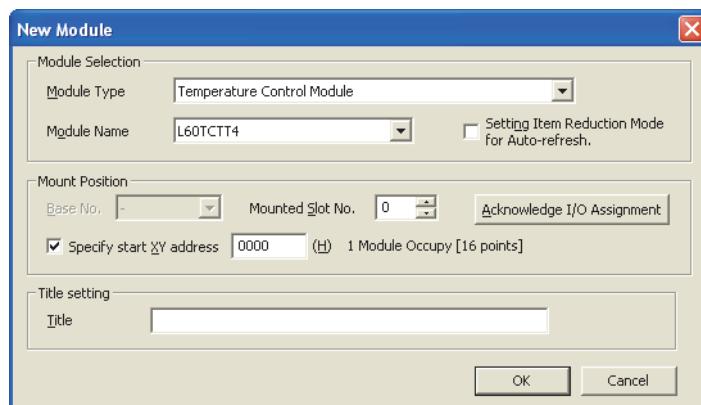
2. Display the PLC parameter setting window and configure the setting as follows.

 Project window ⇒ [Parameter] ⇒ [PLC Parameter] ⇒ "Communication Head Setting"



3. Add the L60TCTT4 to the project on GX Works2.

 Project window ⇒ [Intelligent Function Module] ⇒ Right-click ⇒ [New Module...]



4. Display the L60TCTT4 Switch Setting window and configure the setting as follows.

Project window ⇨ [Intelligent Function Module] ⇨ [L60TCTT4] ⇨ [Switch Setting]

Switch Setting 0000:L60TCTT4

Input Mode Selection

☐ Temperature Input Mode

☒ Temperature Control Mode

Temperature Control Mode Setting

Output Setting at CPU Stop Error

CH	Output Setting at CPU Stop Error
CH1	0: CLEAR
CH2	0: CLEAR
CH3	0: CLEAR
CH4	0: CLEAR

Control Mode Selection

0: Standard Control

Setting Change Rate Limiter Setting

0: Temperature Rise/Temperature Drop Batch Setting

Control Output Cycle Unit Selection Setting

0: 1s Cycle

Auto-setting at Input Range Change

0: Disable

Sampling Cycle Selection

0: 500ms

Moving Averaging Process Setting

0: Enable

Moving Averaging Process Setting is available for Product Information 14062000000000-A or later.

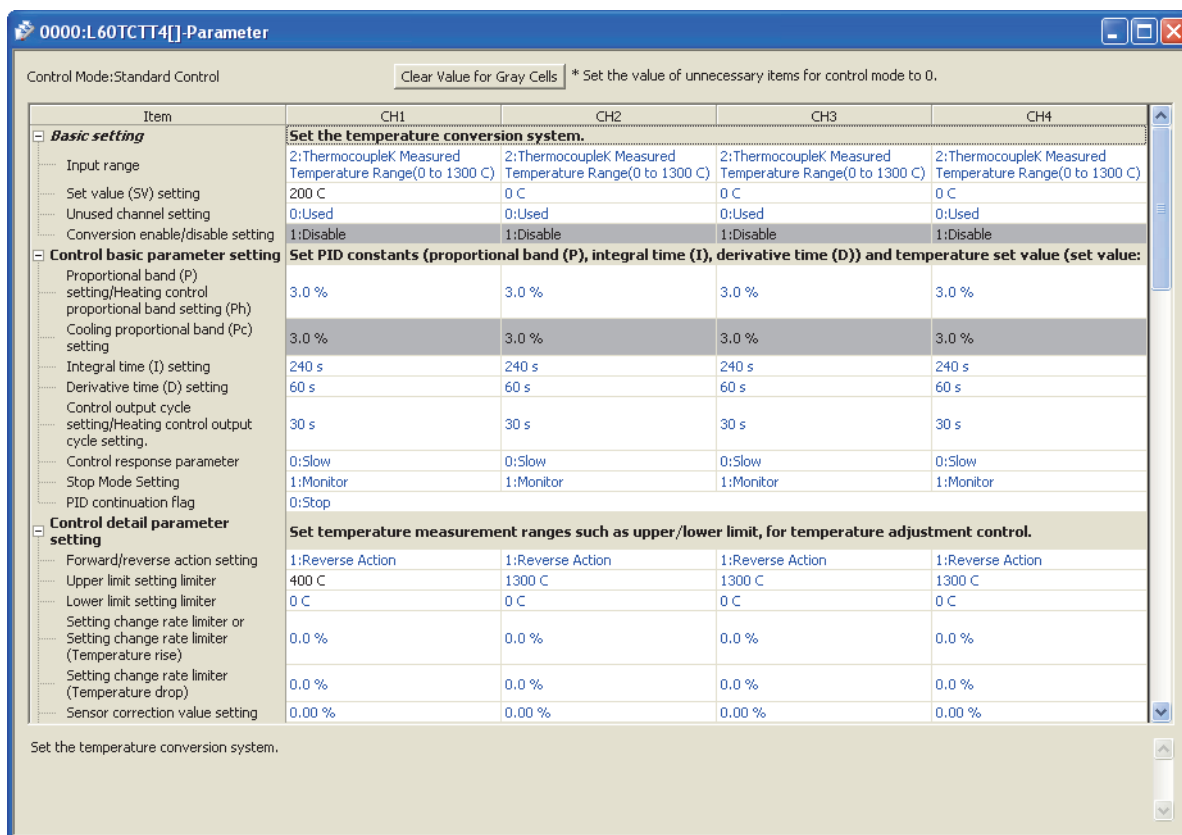
(Caution)
This dialog setting is linked to the Switch Setting of the PLC parameter.
Default value will be shown in the dialog if the Switch Setting of the PLC parameter contains an out-of-range value.

OK Cancel

Item		Setting value			
		CH1	CH2	CH3	CH4
Input Mode Selection		Temperature Control Mode			
Temperature Control Mode Setting	Output Setting at CPU Stop Error	0: CLEAR	0: CLEAR	0: CLEAR	0: CLEAR
	Control Mode Selection	0: Standard Control			
	Setting Change Rate Limiter Setting	0: Temperature Rise/Temperature Drop Batch Setting			
	Control Output Cycle Unit Selection Setting	0: 1s Cycle			
Auto-setting at Input Range Change		0: Disable			
Sampling Cycle Selection		0: 500ms			
Moving Averaging Process Setting		0: Enable			

5. Display the L60TCTT4 initial setting window, click **Clear Value for Gray Cells**, and configure the setting as follows.

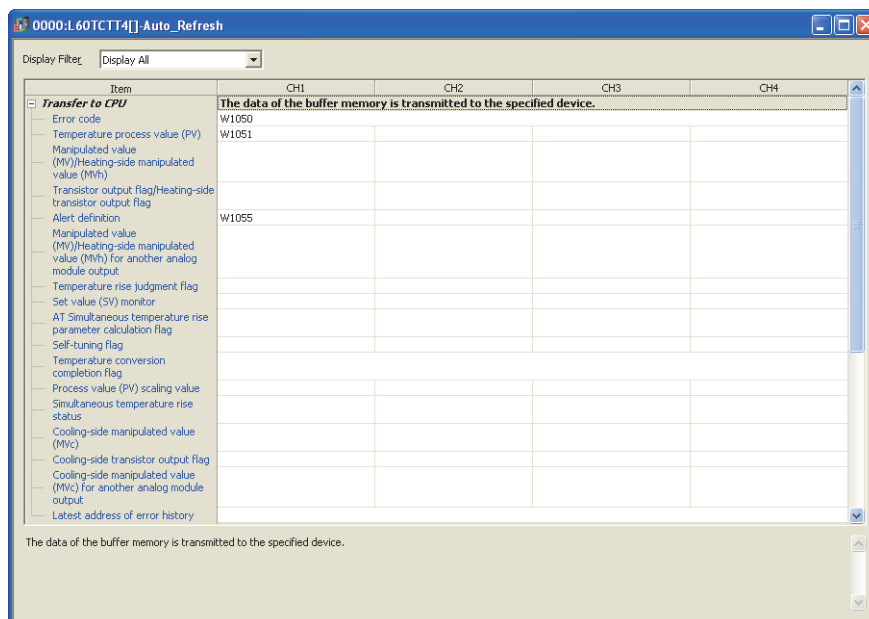
Project window ⇒ [Intelligent Function Module] ⇒ [L60TCTT4] ⇒ [Parameter]



Item	Description	Setting value			
		CH1	CH2	CH3	CH4
Input range	Set the temperature sensor used for the L60TC4 and the measurement range.	2: Thermocouple K Measured Temperature Range (0 to 1300°C)	2: Thermocouple K Measured Temperature Range (0 to 1300°C)	2: Thermocouple K Measured Temperature Range (0 to 1300°C)	2: Thermocouple K Measured Temperature Range (0 to 1300°C)
Set value (SV) setting	Set the target temperature value of PID control.	200°C	0°C	0°C	0°C
Unused channel setting	Configure this setting when the channels where the temperature control is not performed and the temperature sensor is not connected are set to be unused.	0: Used	1: Unused	1: Unused	1: Unused
Upper limit setting limiter	Set the upper limit of the set value (SV).	400°C	1300°C	1300°C	1300°C
Lower limit setting limiter	Set the lower limit of the set value (SV).	0°C	0°C	0°C	0°C
Alert 1 mode setting	Set the alert mode.	1: Upper Limit Input Alert	0: Not Warning	0: Not Warning	0: Not Warning
Alert set value 1	Set the temperature where CH□ Alert 1 (b8 of Un\G5 to Un\G8) turns on.	250°C	—	—	—

6. Display the L60TCTT4 auto refresh setting window and configure the setting as follows.

Project window ⇒ [Intelligent Function Module] ⇒ [L60TCTT4] ⇒ Right-click ⇒ [Auto_Refresh]



Item	Description	Setting value			
		CH1	CH2	CH3	CH4
Error code	An error code or alarm code is stored.	W1050			
Temperature process value (PV)	The detected temperature value where sensor correction is performed is stored.	W1051	—	—	—
Alert definition	The value is stored depending on the detected alert.	W1055	—	—	—

Remark

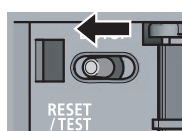
The number of parameters of the auto refresh setting can be reduced by using the setting item reduction mode of auto refresh.

When the setting item reduction mode is set, consecutive devices are automatically set to the grouped setting items. For details on the setting item reduction mode of auto refresh, refer to the following.

Page 116, Section 7.4

7. Write the set parameter to the head module. Then reset the head module or turn off and on the power supply.

[Online] ⇒ [Write to PLC...]



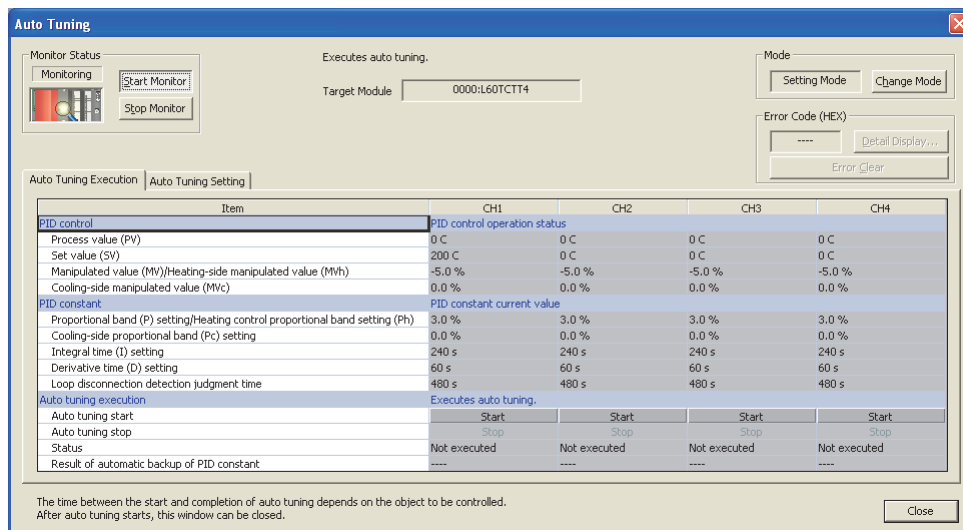
or Power OFF→ON

8. Perform auto tuning.

Set the "Automatic backup setting after auto tuning of PID constants" to "ON" and perform the auto tuning.

[Tool] ⇨ [Intelligent Function Module Tool] ⇨ [Temperature Control Module]

⇨ [Auto Tuning...] ⇨ "L60TCTT4" ⇨ 

**(a) Devices used by a user**

Device	Description	
X22	Error code reset instruction	LX42C4 (X20 to X5F)
X23	Operation mode setting instruction	
X24	Memory's PID constants read instruction	
X1000	Module READY flag	L60TCTT4 (X1000 to X100F)
X1002	Error occurrence flag	
Y60 to Y6F	Error code output	LY42NT1P (Y60 to Y9F)
Y1001	Setting/operation mode instruction	L60TCTT4 (Y1000 to Y100F)
Y1002	Error reset instruction	
Y1008	Set value backup instruction	
Y100B	Setting change instruction	
D9	Write data storage device using Z(P).REMTO instruction (for non-volatile memory read of PID constants)	
D10	Read data storage device using Z(P).REMFR instruction (for non-volatile memory read of PID constants)	
D11	Write data storage device using Z(P).REMTO instruction (for non-volatile memory read of PID constants)	
M0	Master module status check device (for MC and MCR instructions)	
M300 to M305	CH1 Memory's PID constants read flag	
M310, M311	Z(P).REMTO instruction completion/result device	
M312, M313	Z(P).REMFR instruction completion/result device	
M314, M315	Z(P).REMTO instruction completion/result device	
W1050	Error code	Devices where data is written by auto refresh
W1051	CH1 Temperature process value (PV)	
W1055	CH1 Alert definition	
SB49	Data link status (own station)	
SWB0.0	Data link status (each station) (station number 1)	

(b) Program example

Write the program to the CPU module on the master station.

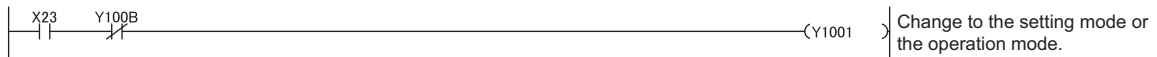
- Program that checks the data link status of the head module



*1 Add the following MCR instruction to the end of the program.



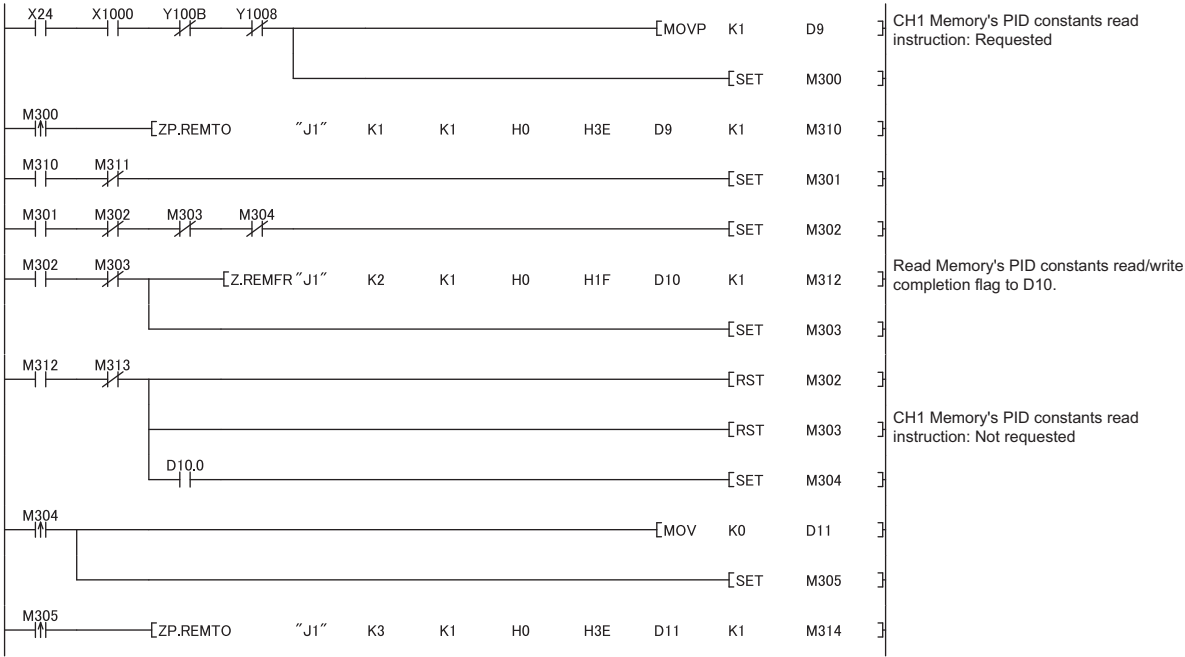
- Program that changes the setting/operation mode



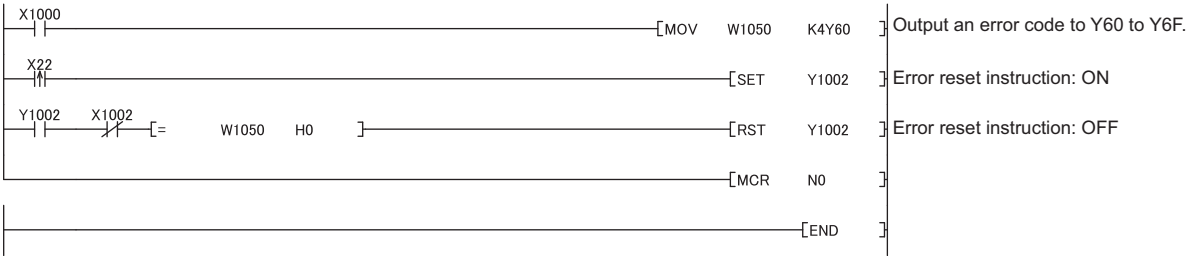
- Program that stops the auto tuning when an alert is detected



• Program that reads the PID constants from the non-volatile memory



• Program that reads an error code



CHAPTER 11 TROUBLESHOOTING

This chapter describes the causes and corrective actions to take when a problem occurs in the L60TC4.

11.1 Before Troubleshooting

Check whether any of the following LEDs are on.

- The POWER LED on the power supply module
- The MODE LED on the CPU module or head module

If both are off, proceed with CPU module or head module troubleshooting.

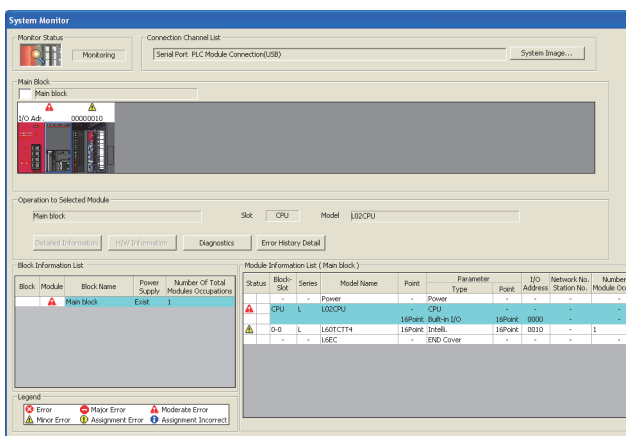
-  MELSEC-L CPU Module User's Manual (Hardware Design, Maintenance and Inspection)
-  MELSEC-L CC-Link IE Field Network Head Module User's Manual

11.2 Troubleshooting Procedure

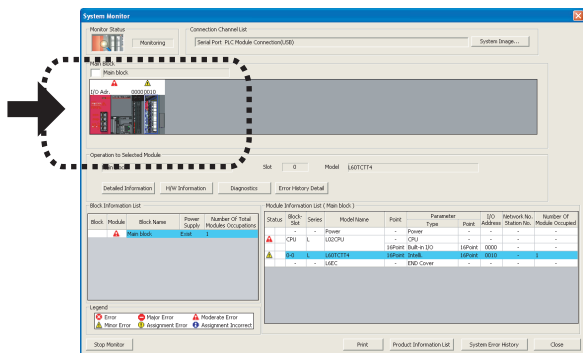
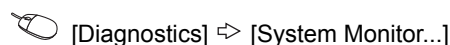
This section describes how to find problem causes and take corrective action.

Use GX Works2 to find problem causes and take corrective action.

(1) Procedure



- 1. Connect GX Works2 to the CPU module to display the "System Monitor" window.**

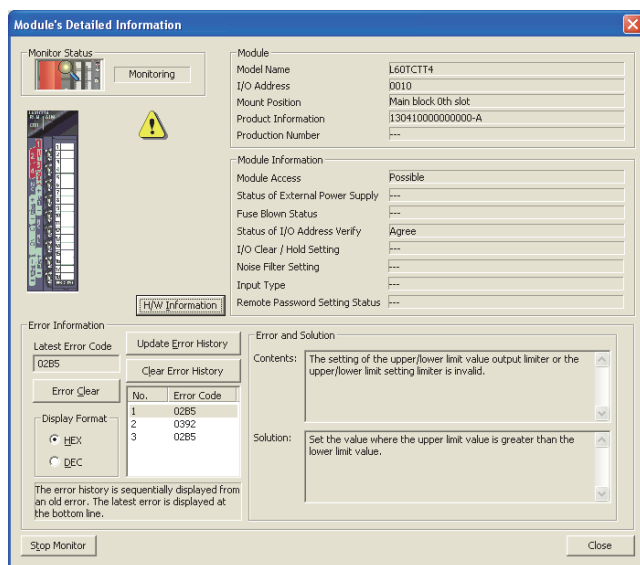


- 2. After confirming that an error is displayed on the L60TC4, select the L60TC4 and click [Detailed Information](#).**

If an error LED is ON on a module other than the L60TC4, refer to the user's manual for the module and take corrective action.

(To the next page)

(From the previous page)



3. Click **Detailed Information** to open the "Module's Detailed Information" window.

Check the error description and the corrective action to take under "Error and Solution".

4. When the error description cannot be confirmed after doing the operation above, proceed with the following troubleshooting.

- Checks using LEDs (☞ Page 320, Section 11.3)
- Checks using input signals (☞ Page 322, Section 11.4)

11.3 Checks Using LEDs

This section describes troubleshooting using LEDs.

11.3.1 When the RUN LED flashes or turns off

Check Item	Action
Is the power supplied?	Check that the supply voltage of the power supply module is within the rated range.
Is the capacity of power supply module enough?	Calculate the current consumption of the installed CPU module, I/O module, and intelligent function module to check whether power supply capacity is sufficient.
Has a watchdog timer error occurred?	• Reset the CPU module or turn on the power supply again. • Replace the L60TC4.
Is the intelligent function module switch setting value outside the setting range?	Set the switch setting value of the intelligent function module to the value within the setting range.

11.3.2 When the ERR. LED turns on or flashes

(1) When turning on

Check Item	Action
Is the intelligent function module switch setting outside the setting range?	Set the switch setting value of the intelligent function module to the value within the setting range.
Is the cold junction temperature compensation resistor disconnected or loose? (The L60TCTT4 and L60TCTT4BW only)	Properly connect the cold junction temperature compensation resistor.
Others	A hardware failure occurred in the L60TC4. Please consult your local Mitsubishi representative.

(2) When flashing

Check Item	Action
Has an error occurred?	Check the error code list ( Page 325, Section 11.6) and take actions described.

11.3.3 When the ALM LED turns on or flashes

(1) When turning on

Check Item	Action
Is CH□ Alert occurrence flag (XnC to XnF) on?	Check CH□ Alert definition (Un\G5 to Un\G8) and take the appropriate corrective action. (☞ Page 346, Appendix 2 (3))

(2) When flashing

Check Item	Action
Has the temperature process value (PV) exceeded the temperature measurement range set as the input range?	Change the setting of CH□ Input range (Un\G32, Un\G64, Un\G96, Un\G128) to a setting in the temperature measurement range to be used. (☞ Page 355, Appendix 2 (12))
Is there a channel where no temperature sensor is connected?	Set the channel where no temperature sensor is connected to unused in CH□ Unused channel setting (Un\G61, Un\G93, Un\G125, Un\G157). (☞ Page 385, Appendix 2 (35))
Has a loop disconnection been detected?	Check for a load disconnection, externally-operable device failure, and sensor disconnection.

11.4 Checks Using Input Signals

This section describes troubleshooting using input signals.

11.4.1 When Module READY flag (Xn0) does not turn on

Check Item	Action
Has a watchdog timer error occurred?	• Reset the CPU module or turn on the power supply again. • Replace the L60TC4.
Has an error occurred in the programmable controller?	Refer to the user's manual of the used CPU module and take corrective action.

11.4.2 When Error occurrence flag (Xn2) is on

Check Item	Action
Has an error occurred?	Check the error code list (☞ Page 325, Section 11.6) and take actions described.

11.4.3 When Hardware error flag (Xn3) is on

Check Item	Action
Is the cold junction temperature compensation resistor disconnected or loose? (The L60TCTT4 and L60TCTT4BW only)	Properly connect the cold junction temperature compensation resistor.
Others	A hardware failure occurred in the L60TC4. Please consult your local Mitsubishi representative.

11.4.4 When the auto tuning does not start (CH□ Auto tuning status (Xn4 to Xn7) does not turn on)

Check Item	Action
Have the auto tuning start conditions been met?	Refer to the "Auto tuning function" section (☞ Page 145, Section 8.2.7) and confirm that all conditions have been met.
Has auto tuning ended abnormally?	Check the conditions that signify an abnormal end for auto tuning (☞ Page 154, Section 8.2.7 (7)) to see whether it has ended abnormally. If it has ended abnormally, remove the cause. Then execute auto tuning again.

11.4.5 When the auto tuning does not complete (CH□ Auto tuning status (Xn4 to Xn7) stays on and does not turn off)

Check Item	Action
Are b4 to b7 of Memory's PID constants read/write completion flag (Un\G31) set to 1 (ON)?	Set CH□ Automatic backup setting after auto tuning of PID constants (Un\G63, Un\G95, Un\G127, Un\G159) to Disable (0). (☞ Page 387, Appendix 2 (37)) To back up the setting, turn off and on Set value backup instruction (Yn8).
Is CH□ Memory's PID constants read instruction (Un\G62, Un\G94, Un\G126, Un\G158) set to Requested (1)?	Set CH□ Memory's PID constants read instruction (Un\G62, Un\G94, Un\G126, Un\G158) to Not requested (0). (☞ Page 386, Appendix 2 (36))
Has the set value (SV) been set correctly? (Is the manipulated value (MV) still 0% because the set value (SV) is small?)	Set the set value (SV) to the desired value.

11.4.6 When the self-tuning does not start (CH□ Auto tuning status (Xn4 to Xn7) does not turn on)

Check Item	Action
Have the self-tuning start conditions been met?	Refer to the "Self-tuning function" section (☞ Page 179, Section 8.2.15) and confirm that all conditions have been met.
Has self-tuning ended abnormally?	Check the conditions that signify an abnormal end for self-tuning (☞ Page 187, Section 8.2.15 (8)) to see whether it has ended abnormally. If it has ended abnormally, remove the cause. If the buffer memory setting was changed during self-tuning, restore the value to the one prior to change.

11.4.7 When Back-up of the set value fail flag (XnA) is on

Check Item	Action
Has a backup to non-volatile memory failed?	Turn off and on Set value backup instruction (Yn8) and write the setting to the non-volatile memory.
Has reading data from non-volatile memory failed?	When writing fails again, a hardware is in failure. Please consult your local Mitsubishi representative.

11.4.8 When CH□ Alert occurrence flag (XnC to XnF) is on

Check Item	Action
Has the temperature process value (PV) exceeded the alert set value range?	• Check CH□ Alert definition (Un\G5 to Un\G8) and take the appropriate corrective action. (☞ Page 346, Appendix 2 (3)) • Correct the alert set value. (☞ Page 367, Appendix 2 (18))
Has a disconnection been detected?	• Check CH□ Alert definition (Un\G5 to Un\G8) and take the appropriate corrective action. (☞ Page 346, Appendix 2 (3))

11.5 Troubleshooting by Symptom

This section describes troubleshooting using the wiring resistance values of thermocouples.

11.5.1 When the temperature process value (PV) is abnormal

Check Item	Action
Is the thermocouple wiring resistance value too high?	• Check the thermocouple wiring resistance value and check whether a difference in the temperatures was caused by the wiring resistance. (☞ Page 37, Section 3.2.2 (1)) • Use the sensor correction function to correct the difference in the temperatures caused by the wiring resistance. (☞ Page 230, Section 8.3.3 (3))

11.6 Error Code List

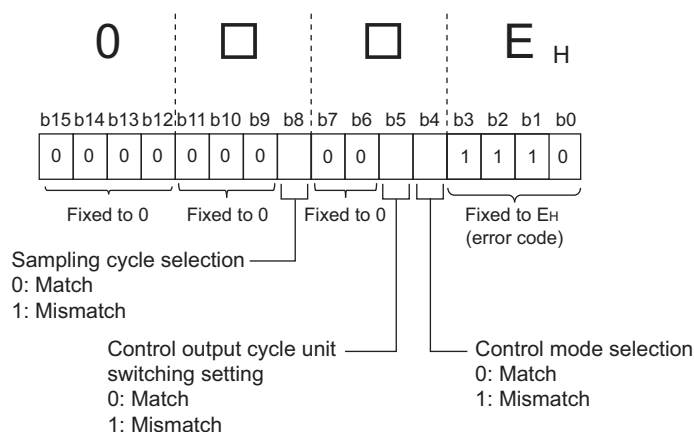
When the L60TC4 error occurs during data write to the CPU module or during data read from the CPU module, one of the following error codes is stored in Error code (Un\G0).

In addition, the error occurred is notified to the CPU module.

Error code (hexadecimal)	Cause	Operation at error occurrence	Action
0001 _H	Hardware error	The operation varies depending on the symptom.	• Check that the terminal block or the cold junction temperature compensation resistor is not disconnected or loose. • Replace the L60TC4. • Please consult your local Mitsubishi representative.
□□□2 _H ^{*1}	Data (other than 0) is being written to the system area ^{*2} .	• The data written is retained. • When data is written to multiple system areas, the address with the smallest number of the buffer memory area where an error was detected is stored.^{*5}	• Return the value to 0 and turn off, on, and off Error reset instruction (Yn2). • Delete the program that is writing data to the system area.
□□□3 _H ^{*1}	Data is being written in the operation mode ^{*4} to the area where data can be written only in the setting mode ^{*3} .	• The data written is retained. • When data is written to multiple system areas, the address with the smallest number of the buffer memory area where an error was detected is stored.^{*5}	• Follow the instructions below for error reset. 1. Change the mode to the setting mode. 2. Set the correct value and turn off, on, and off Setting change instruction (YnB). 3. Turn off, on, and off Error reset instruction (Yn2). • If switching from the operation mode to the setting mode, check that PID continuation flag (Un\G169) is set to Stop (0), and turn on and off Setting/operation mode instruction (Yn1).
□□□4 _H ^{*1}	Data outside the settable range is being written.	• The data written is retained. • If temperature, time, or percentage settings exceed upper limit value/lower limit value, change the data within those values. • When data is written to multiple system areas, the address with the smallest number of the buffer memory area where an error was detected is stored.^{*5}	Set data within the range.
□□□5 _H ^{*1}	The setting of the upper/lower limit value output limiter or the upper/lower limit setting limiter is invalid.	• The data written is retained. • Change the setting to an allowable value for the upper/lower limit value. • When data is written to multiple system areas, the address with the smallest number of the buffer memory area where an error was detected is stored.^{*5}	Set the value where the upper limit value is greater than the lower limit value.

Error code (hexadecimal)	Cause	Operation at error occurrence	Action
□□□6 _H ^{*1}	The setting value is being changed while Default setting registration instruction (Yn9) was on.	- The data written is ignored. - The setting cannot be changed until an error reset is performed. - The content of Error code (Un\G0) does not change even if another write error occurs.	After turning off, on, and off Error reset instruction (Yn2), change the setting value.
□□□7 _H ^{*1}	The sensor two-point correction setting is invalid.	- The data written is retained. - Use the data of before the setting. - When data is written to multiple system areas, the address with the smallest number of the buffer memory area where an error was detected is stored.^{*5} - When both the offset value and gain value are within the input range and the offset value is greater than or equal to the gain value, the gain value address is stored as the address where the error occurred.	- Enter the temperature within the input range. - Set the values so that the sensor two-point correction offset value (measured value) is smaller than the sensor two-point correction gain value (measured value) and the sensor two-point correction offset value (corrected value) is smaller than the sensor two-point correction gain value (corrected value).
□□□8 _H ^{*1}	The setting is described by one of the following. - The process alarm upper upper limit value is smaller than the upper lower limit value. - The process alarm upper lower limit value is smaller than the lower upper limit value. - The process alarm lower upper limit value is smaller than the lower lower limit value.	- The data written is retained. - the address with the smallest number of the buffer memory area where an error was detected is used as the address where the error occurred. - Use the data of before the setting. - When data is written to multiple system areas, the address with the smallest number of the buffer memory area where an error was detected is stored.^{*5}	Set the values that meet the following conditions. - Process alarm upper upper limit value ≥ Upper lower limit value - Process alarm upper lower limit value ≥ Lower upper limit value - Process alarm lower upper limit value ≥ Lower lower limit value
□□□A _H	An alarm has occurred. Refer to the alarm code list (👉 Page 328, Section 11.7).		
0□□E _H ^{*6}	A set value discrepancy error occurred. The current set value is different from the set value backed up in non-volatile memory because one of the following settings on Switch Setting has been changed. - Control Mode Selection - Control Output Cycle Unit Selection Setting - Sampling Cycle Selection	- The set value cannot be changed until the control mode is determined. - When the setting under "Control Mode Selection" was changed: All parameters are overwritten with defaults. - When the setting under "Control Output Cycle Unit Selection Setting" was changed: Settings are overwritten with defaults for "Control Output Cycle Setting", "Heating Control Output Cycle Setting", and "Cooling Control Output Cycle Setting"; other settings are overwritten with backed up values. - When the setting under "Sampling Cycle Selection" was changed: All parameters are overwritten with defaults.	Turn off, on, and off Set value backup instruction (Yn8).
000F _H	Values set in the intelligent function module switch setting are those outside the setting range.	The RUN LED turns off, the ERR. LED turns on, and the module does not operate.	Set the correct values on the intelligent function module switch setting.

- *1 The address where the error occurred is stored in $\square\square\square_H$.
Buffer memory addresses are written in decimal (Intelligent function module device (Un\G□)) in this manual. Read the stored value in decimal and refer to the buffer memory list (Page 45, Section 3.5).
- *2 The buffer memory areas checked are Un\G0 to Un\G287. No error occurs for writes in the system area in or after Un\G288.
- *3 For the writable area in setting mode, refer to the buffer memory list (Page 45, Section 3.5).
- *4 "In the operation mode" refers to one of the following states.
- When Setting/operation mode instruction (Yn1) or Setting/operation mode status (Xn1) is on.
 - When Setting/operation mode instruction (Yn1) turns on and off and PID continuation flag (Un\G169) is set to Continue (1).
- *5 **Ex.** When an error occurs in CH1 Alert 1 mode setting (Un\G192) and CH1 Alert 2 mode setting (Un\G193), 0C0_H (hex) in the buffer memory address with the smallest number "Un\G192" is stored in Error code (Un\G0).
- *6 The error code for a set value discrepancy error indicates the match/no match status with the set value on Switch Setting backed up to non-volatile memory as follows.



Remark

- When a value outside the setting range is written in the following buffer memory areas while in setting mode, the error code 4_H is stored. Switching to operation mode without error reset changes the error code to 3_H. If this happens, take the corrective action for error code 3_H.

Buffer memory area name	Buffer memory address				Reference
	CH1	CH2	CH3	CH4	
Input range	Un\G32	Un\G64	Un\G96	Un\G128	Page 355, Appendix 2 (12)
Alert 1 mode setting	Un\G192	Un\G208	Un\G224	Un\G240	Page 395, Appendix 2 (52)
Alert 2 mode setting	Un\G193	Un\G209	Un\G225	Un\G241	
Alert 3 mode setting	Un\G194	Un\G210	Un\G226	Un\G242	
Alert 4 mode setting	Un\G195	Un\G211	Un\G227	Un\G243	

- Error code priorities are as described below.

Priority

1, F ← E ← 6 ← 3 ← 7 ← 5, 8 ← 2, 4
Higher Lower

When error codes are in the same priority level, the lower error addresses are prioritized.

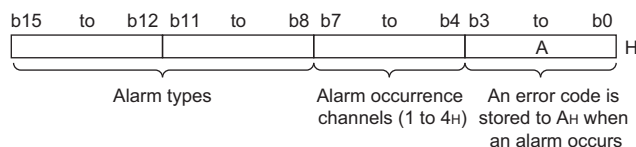
When a high-priority error occurs during a low-priority error, the error code of the high-priority error is written over the error occurrence address.

- Only one error code, as dictated by error priority, is stored in Error code (Un\G0). For that reason, when multiple errors occur at the same time, the next error code is stored, even when the error of the stored error code is corrected. Check for errors other than the stored error code in the parameters of other channels.

11.7 Alarm Code List

The following table lists alarm codes.

The alarm code is stored in all bits of Error code (Un\G0).



If the lower four bits are "0001" (1_H) to "1001" (9_H) or "1011" (B_H) to "1111" (F_H), an error occurs. When an error occurs, refer to the error code list (Page 325, Section 11.6).

Alarm code (hexadecimal) *1	Cause	Operation at alarm occurrence	Action
01□A _H	The temperature process value (PV) has exceeded the temperature measurement range that was set as the input range.	- The ALM LED flashes. - CH□ Alert occurrence flag (XnC to XnF) turns on. - CH□ Input range upper limit (b0 of Un\G5 to Un\G8) turns on.	When Error reset instruction (Yn2) is turned OFF → ON → OFF after the temperature process value (PV) has returned to the value within the temperature measurement range, Error code (Un\G0) is cleared to 0.
02□A _H	The temperature process value (PV) is below the temperature measurement range that was set as the input range.	- The ALM LED flashes. - CH□ Alert occurrence flag (XnC to XnF) turns on. - CH□ Input range lower limit (b1 of Un\G5 to Un\G8) turns on.	The following flags and buffer memory bits that turn on when an alarm occurs turn off automatically when the temperature process value (PV) has returned to the value within the temperature measurement range. - CH□ Alert occurrence flag (XnC to XnF) - The applicable bit (Page 346, Appendix 2 (3)) of CH□ Alert definition (Un\G5 to Un\G8)
03□A _H	A loop disconnection has been detected.	- The ALM LED flashes. - CH□ Alert occurrence flag (XnC to XnF) turns on. - CH□ Loop disconnection detection (b13 of Un\G5 to Un\G8) turns on.	When Error reset instruction (Yn2) is turned OFF → ON → OFF after a current error due to a disconnection or output-off is restored, Error code (Un\G0) is cleared to 0.
04□A _H	A heater disconnection has been detected.	- The HBA LED turns on. - CH□ Alert occurrence flag (XnC to XnF) turns on. - CH□ Heater disconnection detection (b12 of Un\G5 to Un\G8) turns on.	The following flags and buffer memory bits that turn on when an alarm occurs turn off automatically when the current error due to disconnection or output-off is restored. - CH□ Alert occurrence flag (XnC to XnF) - The applicable bit (Page 346, Appendix 2 (3)) of CH□ Alert definition (Un\G5 to Un\G8)
05□A _H	A current error at an output off-time has been detected.	- The HBA LED turns on. - CH□ Alert occurrence flag (XnC to XnF) turns on. - CH□ Output off-time current error (b14 of Un\G5 to Un\G8) turns on.	

Alarm code (hexadecimal) *1	Cause	Operation at alarm occurrence	Action
06□A _H	Alert 1 has occurred.	- The ALM LED turns on. - CH□ Alert occurrence flag (XnC to XnF) turns on. - CH□ Alert 1 (b8 of Un\G5 to Un\G8) turns on.	When Error reset instruction (Yn2) is turned OFF → ON → OFF after the temperature process value (PV) is restored from alert status, Error code (Un\G0) is cleared to 0. The following flags and buffer memory bits that turn on when an alarm occurs turn off automatically when the temperature process value (PV) is restored from alert status. - CH□ Alert occurrence flag (XnC to XnF) - The applicable bit (☞ Page 346, Appendix 2 (3)) of CH□ Alert definition (Un\G5 to Un\G8)
07□A _H	Alert 2 has occurred.	- The ALM LED turns on. - CH□ Alert occurrence flag (XnC to XnF) turns on. - CH□ Alert 2 (b9 of Un\G5 to Un\G8) turns on.	
08□A _H	Alert 3 has occurred.	- The ALM LED turns on. - CH□ Alert occurrence flag (XnC to XnF) turns on. - CH□ Alert 3 (b10 of Un\G5 to Un\G8) turns on.	
09□A _H	Alert 4 has occurred.	- The ALM LED turns on. - CH□ Alert occurrence flag (XnC to XnF) turns on. - CH□ Alert 4 (b11 of Un\G5 to Un\G8) turns on.	
0A□A _H	A process alarm upper limit alert has occurred.	- The ALM LED turns on. - CH□ Alert occurrence flag (XnC to XnF) turns on. - CH□ Process alarm upper limit alert (b2 of Un\G5 to Un\G8) turns on.	When Error reset instruction (Yn2) is turned OFF → ON → OFF after the temperature process value (PV) is restored from alert status, Error code (Un\G0) is cleared to 0. The following flags and buffer memory bits that turn on when an alarm occurs turn off automatically when the temperature process value (PV) is restored from alert status. - CH□ Alert occurrence flag (XnC to XnF) - The applicable bit (☞ Page 346, Appendix 2 (3)) of CH□ Alert definition (Un\G5 to Un\G8)
0B□A _H	A process alarm lower limit alert has occurred.	- The ALM LED turns on. - CH□ Alert occurrence flag (XnC to XnF) turns on. - CH□ Process alarm upper limit alert (b3 of Un\G5 to Un\G8) turns on.	
0C□A _H	A rate alarm upper limit alert has occurred.	- The ALM LED turns on. - CH□ Alert occurrence flag (XnC to XnF) turns on. - CH□ Rate alarm upper limit alert (b4 of Un\G5 to Un\G8) turns on.	
0D□A _H	A rate alarm lower limit alert has been occurred.	- The ALM LED turns on. - CH□ Alert occurrence flag (XnC to XnF) turns on. - CH□ Process alarm upper limit alert (b5 of Un\G5 to Un\G8) turns on.	

*1 □ represents the number of the channel (1_H to 4_H) where the alarm occurred.

Remark

- The error code is always given priority over the alarm code for being stored in Error code (Un\G0). For that reason, when an alarm occurs during an error, the alarm code is not stored in Error code (Un\G0). Further, when an error occurs during an alarm, the error code is written over the alarm code in Error code (Un\G0).
- Alarm priorities are as follows.

Priority	
High	01□A _H , 02□A _H , 03□A _H , 04□A _H , 05□A _H
	↑
	06□A _H , 07□A _H , 08□A _H , 09□A _H ,
	↑
Low	0A□A _H , 0B□A _H , 0C□A _H , 0D□A _H

When an alarm occurs, if its priority is the same as or higher than that of alarms already occurred, the new alarm code is written over Error code (Un\G0).

11.8 Check the L60TC4 Status

The error code and hardware status can be checked by selecting "Module's Detailed Information" of the L60TC4 in the system monitor of the programming tool.

(1) Operating the programming tool

From [Diagnostics] ⇨ [System Monitor...] ⇨ "Main Block", select L60TC4 ⇨ **Detailed Information**.

(2) Module's Detailed Information

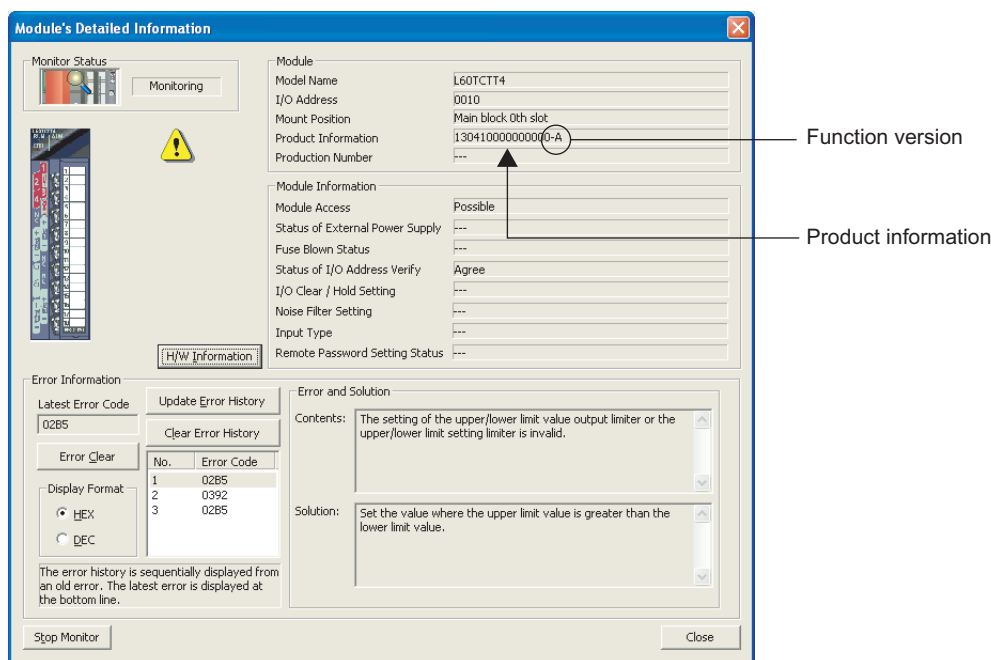
(a) Checking the function version and product information

The Product Information field shows the L60TC4 function version and product information.

(b) Checking the error code

The Latest Error Code field shows the error code stored in Error code (Un\G0) in the L60TC4.

(Press **Update Error History** to display the content shown under Latest Error Code as No.1.)



(3) Hardware information

On the "Module's Detailed Information" window, click .

(a) H/W LED information

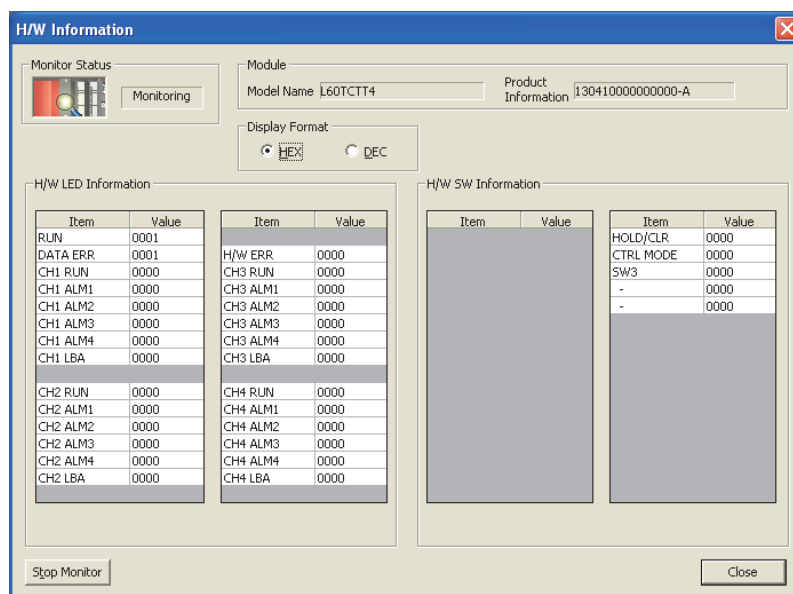
The following information is displayed.

Item	Value	Condition for 0001 _H
RUN	• 0000_H: off • 0001_H: on	Operating normally (same as the RUN LED)
DATA ERR		A write data error has occurred
CH□ RUN		PID control is being run
CH□ ALM1		Alert 1 is on
CH□ ALM2		Alert 2 is on
CH□ ALM3		Alert 3 is on
CH□ ALM4		Alert 4 is on
CH□ LBA		A loop disconnection has been detected
CH□ HBA		Either of the following has been detected. (the L60TCTT4BW and L60TCRT4BW only)
H/W ERR		A hardware error has occurred

(b) H/W switch information

The setting status of the intelligent function module switch setting is displayed.

Item	Intelligent function module switch setting	Value
HOLD/CLR	Switch 1: Output setting at CPU stop error	 Refer to Page 110, Section 7.2
CTRL MODE	Switch 2: Control mode selection	
SW3	Switch 3: • Setting change rate limiter setting • Control output cycle unit selection setting • Auto-setting at input range change • Sampling cycle selection • Moving averaging process setting	



APPENDICES

Appendix 1 Details of I/O Signals

The following section describes the details of the L60TC4 I/O signals toward the CPU module. The I/O numbers (X/Y) described in Appendix 1 is for the case when the start I/O number of the L60TC4 is set to 0.

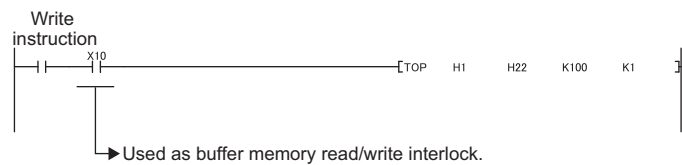
Appendix 1.1 Input signal

A

(1) Module READY flag (Xn0)

This flag turns on to indicate that the preparation for the L60TC4 is completed when the module is turned on from off or when the CPU module's reset is released.

Make sure that this flag is on when reading/writing data from/in the buffer memory of the L60TC4 from the CPU module. The following shows an example of a program. (In the following example, the start I/O number of the L60TC4 is set to 10.)

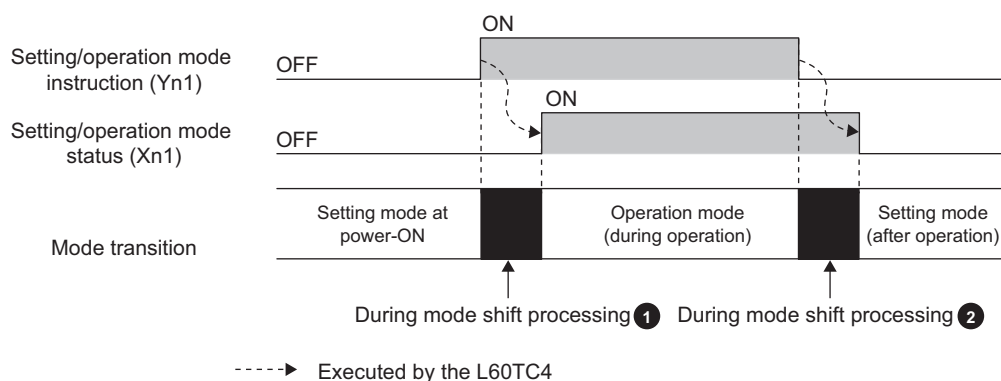


If the watchdog timer error is detected, this flag turns off. The L60TC4 stops controlling the temperature and the transistor output turns off. (The RUN LED turns off and ERR. LED turns on.)

Appendix 1 Details of I/O Signals
Appendix 1.1 Input signal

(2) Setting/operation mode status (Xn1)

This signal turns on at the operation mode, off at the setting mode.



(a) Precautions during the mode shifting

The mode shifting means the following timings.

- From Setting/operation mode instruction (Yn1) OFF → ON to Setting/operation mode status (Xn1) ON (above figure ①)
- From Setting/operation mode instruction (Yn1) ON → OFF to Setting/operation mode status (Xn1) OFF (above figure ②)

During the mode shifting, do not change the set values. If the set values are changed during the mode shifting, the module operation cannot be guaranteed. Use Setting/operation mode status (Xn1) as an interlock condition for Setting/operation mode instruction (Yn1) when changing the setting.

Point

The conditions whether to perform the temperature judgment, PID control, and alert judgment by the L60TC4 differ among the following timings.

- Setting mode at power-ON
- Operation mode (in operation)
- Setting mode (after operation)

For each detail on the temperature judgment, PID control, and alert judgment, refer to the following.

- Temperature judgment: Page 346, Appendix 2 (3)
- PID control: Page 138, Section 8.2.3 (6)
- Alert judgment: Page 170, Section 8.2.11 (5)

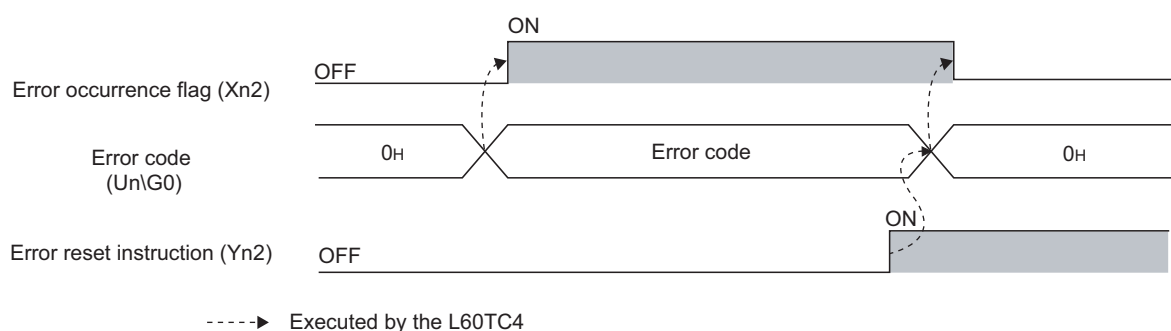
(3) Error occurrence flag (Xn2)

This flag turns on when errors other than a hardware error occur.

After an error occurs and the error code is stored in Error code (Un\G0), this flag turns on.

Errors occur under the following conditions.

- When data is set in the buffer memory of the system area
- When the setting of the area which can be written only during the setting mode (Setting/operation mode status (Xn1): OFF) is changed during the operation mode (Setting/operation mode status (Xn1): ON)
( Page 334, Appendix 1.1 (2))
- When the data which cannot be set is set
- When the setting of the buffer memory is changed during the default setting registration ( Page 342, Appendix 1.2 (5))
- When the current set value and the set value backed up in the non-volatile memory are different due to the change on Switch Setting.



(4) Hardware error flag (Xn3)

This flag turns on when hardware error occurs in the L60TC4.

(5) CH□ Auto tuning status (Xn4 to Xn7)

This signal turns on when auto tuning of each channel is set by the user or when the L60TC4 performs self-tuning.

Channel	Auto tuning status			ON/OFF status
	Standard control	Heating-cooling control	Mix control	
CH1	Xn4	Xn4	Xn4	ON: The auto tuning/self-tuning is being performed. OFF: The auto tuning/self-tuning is not being performed or is completed.
CH2	Xn5	Xn5	Xn5 ^{*2}	
CH3	Xn6	Xn6 ^{*1}	Xn6	
CH4	Xn7	Xn7 ^{*1}	Xn7	

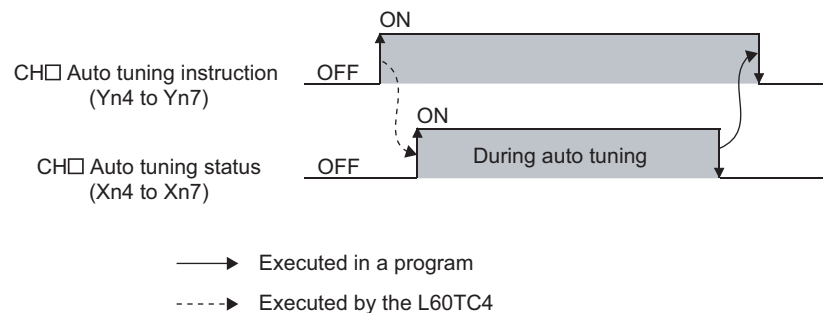
*1 Available only under the heating-cooling control (expanded mode). For details on the expanded mode, refer to  Page 131, Section 8.2.1 (3).

*2 Available only under the mix control (expanded mode). For details on the expanded mode, refer to  Page 131, Section 8.2.1 (3).

(a) Performing auto tuning

To perform auto tuning, turn CH□ Auto tuning instruction (Yn4 to Yn7) on from off.

While auto tuning is in process, this signal is on, and turns off at the completion of the auto tuning.



For details on the auto tuning function, refer to the following.

 Page 145, Section 8.2.7

(b) Self-tuning

This signal turns on when self-tuning starts. This signal automatically turns off at the completion of the self-tuning.

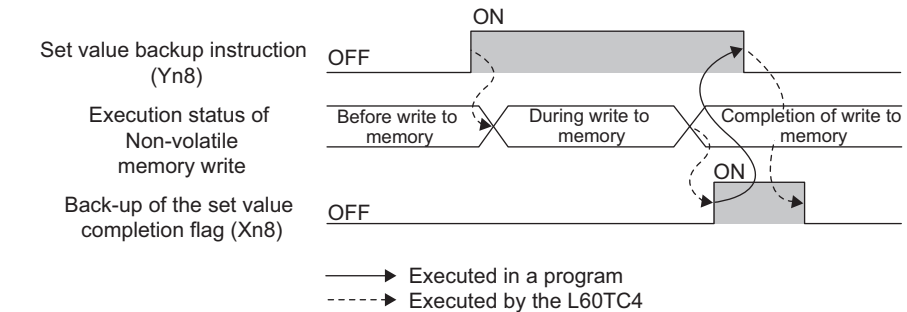
Set a self-tuning option in CH□ Self-tuning setting (Un\G574, Un\G606, Un\G638, Un\G670). ( Page 408, Appendix 2 (73)) Self-tuning can be executed only in the standard control.

For details on the self-tuning function, refer to the following.

 Page 179, Section 8.2.15

(6) Back-up of the set value completion flag (Xn8)

Turning Set value backup instruction (Yn8) on from off starts the writing of the buffer memory data to the non-volatile memory. After the data writing is completed, this flag turns on. Turning Set value backup instruction (Yn8) off from on also turns off this flag.

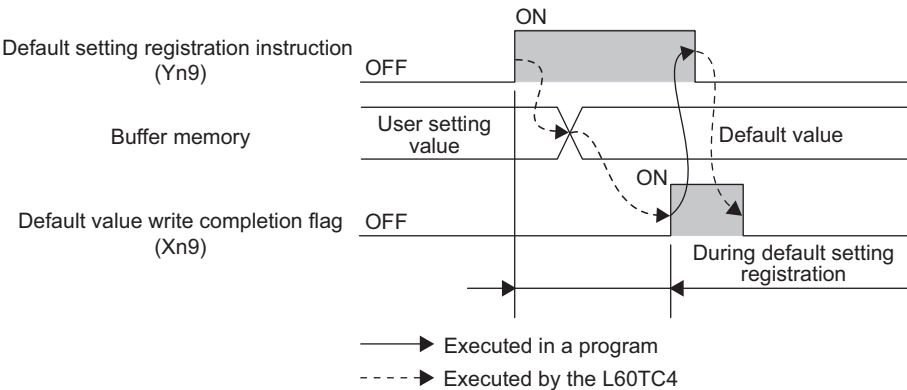


For details on the data writing to the non-volatile memory, refer to the following.

👉 Page 242, Section 8.3.5

(7) Default value write completion flag (Xn9)

Turning Default setting registration instruction (Yn9) on from off starts the writing of the default value of the L60TC4 to the buffer memory. After the data writing is completed, this flag turns on. Turning Default setting registration instruction (Yn9) off from on also turns off this flag.



(a) Unused channel

For unused channels (which temperature sensors are not connected to), CH□ Unused channel setting (Un\G61, Un\G93, Un\G125, Un\G157) must be set to Unused (1) after the completion of the writing of the default value.

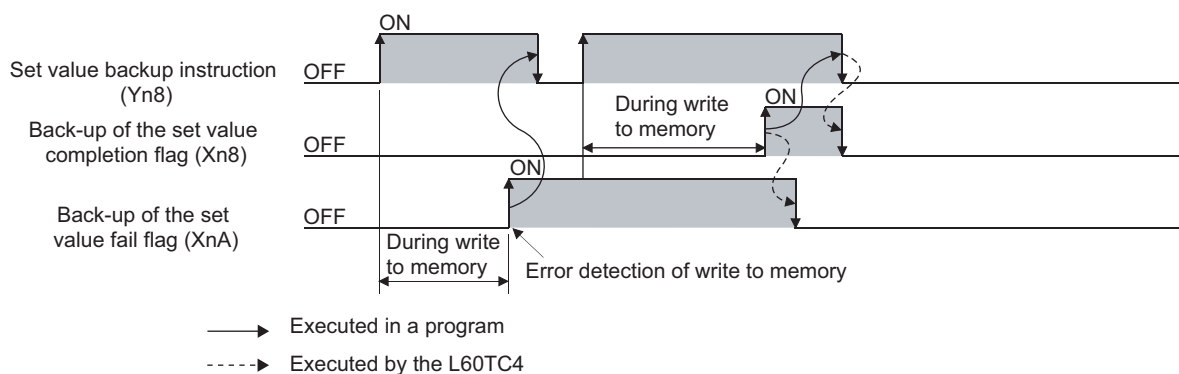
If not, ALM LED blinks.

For details on the unused channel setting, refer to the following.

👉 Page 108, Section 6.6

(8) Back-up of the set value fail flag (XnA)

Turning Set value backup instruction (Yn8) on from off starts the writing of the buffer memory data to the non-volatile memory. This flag turns on when the writing failed.



This flag turns off when Set value backup instruction (Yn8) is turned on from off to complete the data writing to the non-volatile memory properly.

For details on the data writing to the non-volatile memory, refer to the following.

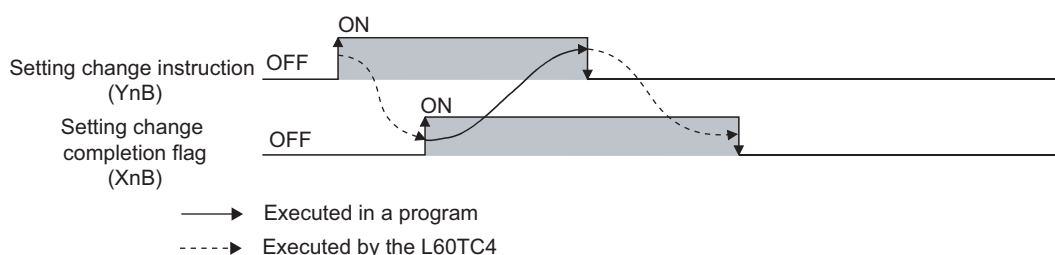
☞ Page 242, Section 8.3.5

Point

When an error of the data read from the non-volatile memory is detected at power-on, Back-up of the set value fail flag (XnA) turns on and the L60TC4 operates with the default value. In this case, turn Set value backup instruction (Yn8) on from off to complete the data writing to the non-volatile memory properly. If the data writing to the non-volatile memory fails, hardware failure is a likely cause. Please consult your local Mitsubishi representative.

(9) Setting change completion flag (XnB)

Turning Setting change instruction (YnB) on from off during the setting mode (Setting/operation mode status (Xn1): OFF) reflects the set contents of each buffer memory to the control. After the data is reflected, this flag turns on. Turning Setting change instruction (YnB) off from on also turns off this flag.



This flag can be used as an interlock condition for Setting/operation mode instruction (Yn1).

(10)CH□ Alert occurrence flag (XnC to XnF)

When an alert occurs, the alert definition is stored in CH□ Alert definition (Un\G5 to Un\G8), and this flag turns on.

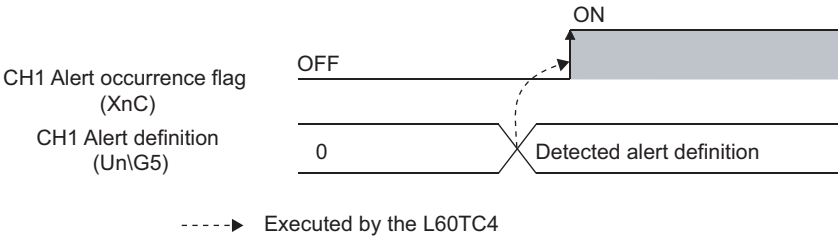
For conditions where this flag turns off, refer to the following.

 Page 170, Section 8.2.11 (6)

The following table lists the particular flag and buffer memory addresses of alert definitions for each channel.

Channel	Alert occurrence flag	ON/OFF status	CH□ Alert definition (buffer memory address)  Page 346, Appendix 2 (3))
CH1	XnC	OFF: Alert does not occur. ON: Alert occurs.	Un\G5
CH2	XnD		Un\G6
CH3	XnE		Un\G7
CH4	XnF		Un\G8

 Ex. Time chart for CH1



A

Appendix 1.2 Output signal

(1) Setting/operation mode instruction (Yn1)

Use this signal to select the setting mode or the operation mode.

- OFF: Setting mode
- ON: Operation mode

Some buffer memory areas can be set only in the setting mode.

(a) Buffer memory areas that can be set only in the setting mode

The following settings can be changed only when Setting/operation mode instruction (Yn1) is off. If the settings are changed in the operation mode, a write data error (error code: □□□ 3_H) occurs.

Buffer memory area name	Buffer memory address				Reference
	CH1	CH2	CH3	CH4	
CH□ Input range	Un\G32	Un\G64	Un\G96	Un\G128	Page 355, Appendix 2 (12)
Resolution of the manipulated value for output with another analog module	Un\G181				Page 393, Appendix 2 (48)
CH□ Alert 1 mode setting	Un\G192	Un\G208	Un\G224	Un\G240	Page 395, Appendix 2 (52)
CH□ Alert 2 mode setting	Un\G193	Un\G209	Un\G225	Un\G241	
CH□ Alert 3 mode setting	Un\G194	Un\G210	Un\G226	Un\G242	
CH□ Alert 4 mode setting	Un\G195	Un\G211	Un\G227	Un\G243	
CH□ Process alarm alert output enable/disable setting	Un\G196	Un\G212	Un\G228	Un\G244	Page 396, Appendix 2 (53)
CH□ Process alarm lower lower limit value	Un\G197	Un\G213	Un\G229	Un\G245	Page 397, Appendix 2 (54)
CH□ Process alarm lower upper limit value	Un\G198	Un\G214	Un\G230	Un\G246	
CH□ Process alarm upper lower limit value	Un\G199	Un\G215	Un\G231	Un\G247	
CH□ Process alarm upper upper limit value	Un\G200	Un\G216	Un\G232	Un\G248	
CH□ Rate alarm alert output enable/disable setting	Un\G201	Un\G217	Un\G233	Un\G249	Page 398, Appendix 2 (55)
CH□ Rate alarm alert detection cycle	Un\G202	Un\G218	Un\G234	Un\G250	Page 398, Appendix 2 (56)
CH□ Rate alarm upper limit value	Un\G203	Un\G219	Un\G235	Un\G251	Page 399, Appendix 2 (57)
CH□ Rate alarm lower limit value	Un\G204	Un\G220	Un\G236	Un\G252	
CT□ CT selection	Un\G272 to Un\G279 (set for each current sensor (CT))				Page 401, Appendix 2 (60)
CH□ Sensor two-point correction offset value (measured value)	Un\G544	Un\G576	Un\G608	Un\G640	Page 403, Appendix 2 (63)
CH□ Sensor two-point correction offset value (corrected value)	Un\G545	Un\G577	Un\G609	Un\G641	Page 403, Appendix 2 (64)
CH□ Sensor two-point correction gain value (measured value)	Un\G546	Un\G578	Un\G610	Un\G642	Page 404, Appendix 2 (65)
CH□ Sensor two-point correction gain value (corrected value)	Un\G547	Un\G579	Un\G611	Un\G643	Page 404, Appendix 2 (66)
CH□ Sensor two-point correction offset latch request	Un\G548	Un\G580	Un\G612	Un\G644	Page 405, Appendix 2 (67)
CH□ Sensor two-point correction gain latch request	Un\G550	Un\G582	Un\G614	Un\G646	Page 406, Appendix 2 (69)
Conversion enable/disable setting	Un\G693				Page 412, Appendix 2 (76)
CH□ Number of moving averaging	Un\G698	Un\G699	Un\G700	Un\G701	Page 414, Appendix 2 (78)
Cooling method setting	Un\G719				Page 414, Appendix 2 (79)

Buffer memory area name	Buffer memory address				Reference
	CH1	CH2	CH3	CH4	
CH□ Process value (PV) scaling function enable/disable setting	Un\G725	Un\G741	Un\G757	Un\G773	Page 415, Appendix 2 (82)
CH□ Process value (PV) scaling lower limit value	Un\G726	Un\G742	Un\G758	Un\G774	Page 416, Appendix 2 (83)
CH□ Process value (PV) scaling upper limit value	Un\G727	Un\G743	Un\G759	Un\G775	
CH□ Derivative action selection	Un\G729	Un\G745	Un\G761	Un\G777	Page 417, Appendix 2 (85)
CH□ Simultaneous temperature rise group setting	Un\G730	Un\G746	Un\G762	Un\G778	Page 417, Appendix 2 (86)
CH□ Setting change rate limiter unit time setting	Un\G735	Un\G751	Un\G767	Un\G783	Page 421, Appendix 2 (91)
Peak current suppression control group setting	Un\G784				Page 422, Appendix 2 (92)
Sensor correction function selection	Un\G785				Page 423, Appendix 2 (93)

(2) Error reset instruction (Yn2)

Use this signal to turn off Error occurrence flag (Xn2) and to reset Error code (Un\G0). For the method to reset an error, refer to Error occurrence flag (Xn2). (☞ Page 335, Appendix 1.1 (3))

(3) CH□ Auto tuning instruction (Yn4 to Yn7)

Use this signal to start auto tuning per channel. Turning this signal on from off starts auto tuning and turns on CH□ Auto tuning status (Xn4 to Xn7). After auto tuning is completed, CH□ Auto tuning status (Xn4 to Xn7) turns off.

Keep this instruction ON during auto tuning and turn it off from on at the completion of the auto tuning. If this instruction is turned off from on during auto tuning, the auto tuning stops. If the auto tuning stops, PID constants in the buffer memory do not change.

Point

- If proportional band (P)/heating proportional band (Ph) is set to 0, auto tuning cannot be performed. (☞ Page 364, Appendix 2 (15))
- If Setting/operation mode instruction (Yn1) is turned off from on and the operation status shifts to the setting mode during auto tuning, the auto tuning stops. After that, even if Setting/operation mode instruction (Yn1) is turned on from off and the the operation status shifts back to the operation mode, the auto tuning does not resume. To resume the auto tuning, turn Auto tuning instruction (Yn4 to Yn7) off from on, and turn it on from off again.

For details on the auto tuning function, refer to the following.

☞ Page 145, Section 8.2.7

(4) Set value backup instruction (Yn8)

Use this signal to write the buffer memory data to the non-volatile memory. Turning this instruction on from off starts the data writing to the non-volatile memory.

For the buffer memory areas whose data is to be backed up, refer to the following.

 Page 45, Section 3.5

(a) When data writing to the non-volatile memory has completed normally

Back-up of the set value completion flag (Xn8) turns on.

(b) When data writing to the non-volatile memory has not completed normally

Back-up of the set value fail flag (XnA) turns on. When Back-up of the set value fail flag (XnA) turns on, turn Set value backup instruction (Yn8) on from off to write the data to the non-volatile memory again.

(c) Timings when this instruction cannot be received

In the following timings, this instruction cannot be received.

- 1: While PID constants are written after auto tuning
- 2: While PID constants are read from the non-volatile memory
- 3: While a setting error is occurring
- 4: While a setting is being changed by Setting change instruction (YnB)

For 1 to 3 above, turn this instruction on from off after each condition is resolved.

For 4, data writing to the non-volatile memory automatically starts if the factor is resolved.

For details on the data writing to the non-volatile memory, refer to the following.

 Page 242, Section 8.3.5

(5) Default setting registration instruction (Yn9)

Turning Default setting registration instruction (Yn9) on from off sets the data in the buffer memory areas back to the default values according to the control output cycle unit selection setting and control mode selection.

(a) When Setting/operation mode status (Xn1) is on (in operation mode)

Turning this instruction on from off does not set data back to the default value. Turn on this instruction when Setting/operation mode status (Xn1) is off (in the setting mode).

(6) Setting change instruction (YnB)

Use this instruction to confirm the set value of the buffer memory (the buffer memory areas that can be set only in the setting mode (Setting/operation mode status (Xn1): OFF). ( Page 340, Appendix 1.2 (1))

(a) Reflection of set value

Even though the set values are written into the buffer memory, they cannot be reflected to the L60TC4's operation immediately. To confirm the set values, turn this instruction OFF → ON → OFF after the set values are written into the buffer memory. Doing so lets the L60TC4 operate according to the setting in each buffer memory area.

(7) CH□ PID control forced stop instruction (YnC to YnF)

Use this signal to temporarily stop PID control forcibly.

(a) Mode when PID control stops

The mode depends on the setting of CH□ Stop mode setting (Un\G33, Un\G65, Un\G97, Un\G129).

For details on CH□ Stop mode setting (Un\G33, Un\G65, Un\G97, Un\G129), refer to the following.

 Page 362, Appendix 2 (13)

Appendix 2 Details of the Buffer Memory

This chapter describes details on the buffer memory of the L60TC4.

Point

For buffer memory areas indicated with the icons **Standard** and **Heating-cooling**, or with **Common**, the following terms are used, unless otherwise specified.

- Proportional band (P): includes heating proportional band (Ph) and cooling proportional band (Pc)
- Manipulated value (MV): includes manipulated value for heating (MVh) and manipulated value for cooling (MVc).
- Transistor output: includes heating transistor output and cooling transistor output
- Control output cycle: includes heating control output cycle and cooling control output cycle

(1) Error code (Un\G0) **Common**

An error code or alarm code is stored in this buffer memory area.

For error codes and alarm codes, refer to the following.

☞ Page 325, Section 11.6, Page 328, Section 11.7

(2) CH□ Decimal point position (Un\G1 to Un\G4) **Common**

According to the setting of CH□ Input range (Un\G32, Un\G64, Un\G96, Un\G128), the decimal point position applicable in the following buffer memory areas is stored in this buffer memory area.

Buffer memory area name	Buffer memory address				Reference
	CH1	CH2	CH3	CH4	
CH□ Temperature process value (PV)	Un\G9	Un\G10	Un\G11	Un\G12	Page 348, Appendix 2 (4)
CH□ Set value (SV) setting	Un\G34	Un\G66	Un\G98	Un\G130	Page 363, Appendix 2 (14)
CH□ Alert set value 1	Un\G38	Un\G70	Un\G102	Un\G134	Page 367, Appendix 2 (18)
CH□ Alert set value 2	Un\G39	Un\G71	Un\G103	Un\G135	
CH□ Alert set value 3	Un\G40	Un\G72	Un\G104	Un\G136	
CH□ Alert set value 4	Un\G41	Un\G73	Un\G105	Un\G137	
CH□ AT bias setting	Un\G53	Un\G85	Un\G117	Un\G149	Page 379, Appendix 2 (29)
CH□ Upper limit setting limiter	Un\G55	Un\G87	Un\G119	Un\G151	Page 381, Appendix 2 (31)
CH□ Lower limit setting limiter	Un\G56	Un\G88	Un\G120	Un\G152	
CH□ Loop disconnection detection dead band	Un\G60	Un\G92	Un\G124	Un\G156	Page 384, Appendix 2 (34)
CH□ Process alarm lower lower limit value	Un\G197	Un\G213	Un\G229	Un\G245	Page 397, Appendix 2 (54)
CH□ Process alarm lower upper limit value	Un\G198	Un\G214	Un\G230	Un\G246	
CH□ Process alarm upper lower limit value	Un\G199	Un\G215	Un\G231	Un\G247	
CH□ Process alarm upper upper limit value	Un\G200	Un\G216	Un\G232	Un\G248	
CH□ Rate alarm upper limit value	Un\G203	Un\G219	Un\G235	Un\G251	Page 399, Appendix 2 (57)
CH□ Rate alarm lower limit value	Un\G204	Un\G220	Un\G236	Un\G252	
CH□ Sensor two-point correction offset value (measured value)	Un\G544	Un\G576	Un\G608	Un\G640	Page 403, Appendix 2 (63)
CH□ Sensor two-point correction offset value (corrected value)	Un\G545	Un\G577	Un\G609	Un\G641	Page 403, Appendix 2 (64)

Buffer memory area name	Buffer memory address				Reference
	CH1	CH2	CH3	CH4	
CH□ Sensor two-point correction gain value (measured value)	Un\G546	Un\G578	Un\G610	Un\G642	Page 404, Appendix 2 (65)
CH□ Sensor two-point correction gain value (corrected value)	Un\G547	Un\G579	Un\G611	Un\G643	Page 404, Appendix 2 (66)
CH□ Simultaneous temperature rise gradient data	Un\G731	Un\G747	Un\G763	Un\G779	Page 418, Appendix 2 (87)

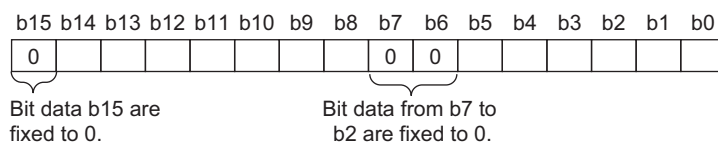
Stored values differ depending on the setting in CH□ Input range (Un\G32, Un\G64, Un\G96, Un\G128).

Setting of CH□ Input range (Un\G32, Un\G64, Un\G96, Un\G128) ( Page 355, Appendix 2 (12))	Stored value	Setting contents
Resolution is 1.	0	Nothing after decimal point
Resolution is 0.1.	1	First decimal place

A

(3) CH□ Alert definition (Un\G5 to Un\G8) Common

Bits corresponding to alerts detected in each channel become 1.



Target bit number	Flag name	Alert definition
b0	CH□ Input range upper limit	Temperature process value (PV) has exceeded the temperature measurement range*1 of the set input range.
b1	CH□ Input range lower limit	Temperature process value (PV) has fallen below the temperature measurement range*1 of the set input range.
b2	CH□ Process alarm upper limit	Temperature process value (PV) has reached the process alarm upper upper limit value or more.
b3	CH□ Process alarm lower limit	Temperature process value (PV) has reached the process alarm lower lower limit value or lower.
b4	CH□ Rate alarm upper limit	The variation of temperature process value (PV) has reached the rate alarm upper limit value or more.
b5	CH□ Rate alarm lower limit	The variation of temperature process value (PV) has reached the rate alarm lower limit value or lower.
b6 to b7	— (fixed to 0)	— (Unused)
b8	CH□ Alert 1	Alert 1 has occurred. (☞ Page 161, Section 8.2.11)
b9	CH□ Alert 2	Alert 2 has occurred. (☞ Page 161, Section 8.2.11)
b10	CH□ Alert 3	Alert 3 has occurred. (☞ Page 161, Section 8.2.11)
b11	CH□ Alert 4	Alert 4 has occurred. (☞ Page 161, Section 8.2.11)
b12	CH□ Heater disconnection detection	Heater disconnection has been detected. (☞ Page 221, Section 8.2.25)
b13	CH□ Loop disconnection detection	Loop disconnection has been detected. (☞ Page 208, Section 8.2.19)
b14	CH□ Output off-time current error	Output off-time current error has been detected. (☞ Page 226, Section 8.2.26)
b15	— (fixed to 0)	— (Unused)

*1 For the temperature measurement range, refer to Page 347, Appendix 2 (3) (a).

Point

Bit data from b6 to b15 become Unused in the temperature input mode.

(a) Temperature measurement range

The temperature measurement range is as follows.

- Input range lower limit - 5% of full scale to Input range upper limit + 5% of full scale

Ex. A calculation example when CH□ Input range (Un\G32, Un\G64, Un\G96, Un\G128): 38
(temperature measurement range: -200.0 to 400.0°C)

- Input range lower limit - 5% of full scale = $-200 - ((400.0 - (-200.0)) \times 0.05) = -230.0$
- Input range upper limit + 5% of full scale = $400 + ((400.0 - (-200.0)) \times 0.05) = 430.0$

Therefore, the temperature measurement range is -230.0 to 430.0°C.

The L60TC4 checks whether the input temperature is in temperature measurement range of the input range. When the input temperature is out of the temperature measurement range, CH□ Input range upper limit (b0 of Un\G5 to Un\G8), or CH□ Input range lower limit (b1 of Un\G5 to Un\G8) becomes 1 (ON). The conditions which the L60TC4 uses to judge whether the measured temperature is within the temperature measurement range differ depending on the following settings.

- Setting/operation mode instruction (Yn1) (Page 340, Appendix 1.2 (1))
- PID continuation flag (Un\G169) (Page 390, Appendix 2 (43))
- CH□ PID control forced stop instruction (YnC to YnF) (Page 343, Appendix 1.2 (7))
- CH□ Stop mode setting (Un\G33, Un\G65, Un\G97, Un\G129) (Page 362, Appendix 2 (13))

Point

The following table lists the conditions whether to perform the temperature judgment.

○: Executed ×: Not executed

Setting/operation mode instruction (Yn1)*1	PID continuation flag (Un\G169)	CH□ PID control forced stop instruction (YnC to YnF)	CH□ Stop mode setting (Un\G33, Un\G65, Un\G97, Un\G129)	Temperature judgment
Setting mode at power-ON	Stop (0)/Continue (1)	OFF/ON	Stop (0)	×
			Monitor (1)	○
			Alert (2)	○
Operation mode (in operation)	Stop (0)/Continue (1)	OFF	Stop (0)/Monitor (1)/Alert (2)	○
		ON	Stop (0)	×
			Monitor (1)	○
Setting mode (after operation)	Stop (0)	OFF/ON	Alert (2)	○
			Stop (0)	×
			Monitor (1)	○
	Continue (1)	OFF	Stop (0)/Monitor (1)/Alert (2)	○
		ON	Stop (0)	×
			Monitor (1)	○
			Alert (2)	○

*1 Refer to Page 334, Appendix 1.1 (2) for each timing.

If CH□ Unused channel setting (Un\G61, Un\G93, Un\G125, Un\G157) is set to Disable (1), temperature judgment is not executed even though the condition above is satisfied. (Page 385, Appendix 2 (35))

(4) CH□ Temperature process value (PV) (Un\G9 to Un\G12) Common

The detected temperature value where sensor correction is performed is stored in this buffer memory area.

The value to be stored differs depending on the stored value in CH□ Decimal point position (Un\G1 to Un\G4).

(☞ Page 344, Appendix 2 (2))

- No decimal place (0): Stored as it is.
- One decimal place (1): Stored after a multiplication by 10.

Point

When value measured by a temperature sensor exceeds the temperature measurement range, the following value is stored.

- When measured value exceeds temperature measurement range: Input range upper limit + 5% of full scale
 - When measured value falls below temperature measurement range: Input range lower limit - 5% of full scale
-

(5) CH□ Manipulated value (MV) (Un\G13 to Un\G16) Standard**CH□ Manipulated value for heating (MVh) (Un\G13 to Un\G16)** Heating-cooling**CH□ Manipulated value for cooling (MVc) (Un\G704 to Un\G707)** Heating-cooling

The result of PID operation based on temperature process value (PV) is stored in these buffer memory areas. The area Un\G13 to Un\G16 are used for heating in the case of the heating-cooling control. The following table lists the range of values to be stored.

Store description	Store range in control	Stored value when control stops
Manipulated value (MV)	-50 to 1050 (-5% to 105.0%)	-50 (-5.0%)
Manipulated value for heating (MVh)	0 to 1050 (0.0% to 105.0%)	-50 (-5.0%)
Manipulated value for cooling (MVc)		

However, values are output in the range of 0% to 100%. For 0% or less and 100% or more, refer to the following.

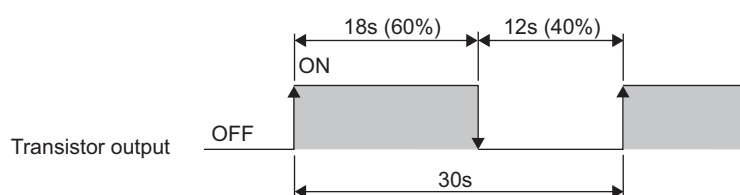
- For 0% or less: 0%
- For 100% or more: 100%

(a) Manipulated value (MV) and control output cycle

- Manipulated value (MV) indicates ON time of CH□ Control output cycle setting (Un\G47, Un\G79, Un\G111, Un\G143) in percentage. (☞ Page 373, Appendix 2 (23))
- Manipulated value for heating (MVh) indicates ON time of CH□ Heating control output cycle setting (Un\G47, Un\G79, Un\G111, Un\G143) in percentage. (☞ Page 373, Appendix 2 (23))
- Manipulated value for cooling (MVc) indicates ON time of CH□ Cooling control output cycle setting (Un\G722, Un\G738, Un\G754, Un\G770) in percentage. (☞ Page 373, Appendix 2 (23))

Ex. When 600 (60.0%) is stored in CH□ Manipulated value (MV) (Un\G13 to Un\G16) and the value of the buffer memory is set as shown in the following.

- CH□ Control output cycle setting (Un\G47, Un\G79, Un\G111, Un\G143): 30s
 ON time of transistor output = Control output cycle setting (s) × Manipulated value (MV) (%) = 30 × 0.6 = 18 (s)
 ON time of transistor output is 18s.
 Transistor output is pulse of ON for 18s, OFF for 12s.



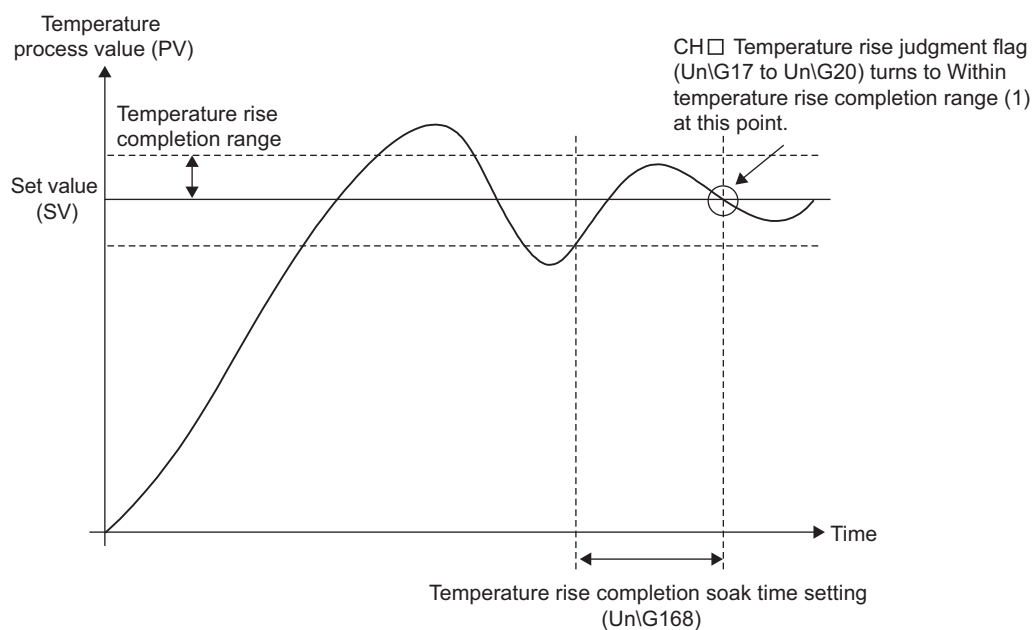
(6) CH□ Temperature rise judgment flag (Un\G17 to Un\G20) Standard Heating-cooling

This flag is for checking whether the temperature process value (PV) is in the temperature rise completion range or not.

The following values are stored in this buffer memory area.

- 0: Out of temperature rise completion range
- 1: Within temperature rise completion range

When the temperature process value (PV) stays in the temperature rise completion range during the set temperature rise completion soak time, 1 is stored in this buffer memory area, which is within temperature rise completion range (1).



Set the temperature rise completion range and temperature rise completion soak time in the following buffer memory areas.

- Temperature rise completion range setting (Un\G167) (☞ Page 389, Appendix 2 (41))
- Temperature rise completion soak time setting (Un\G168) (☞ Page 390, Appendix 2 (42))

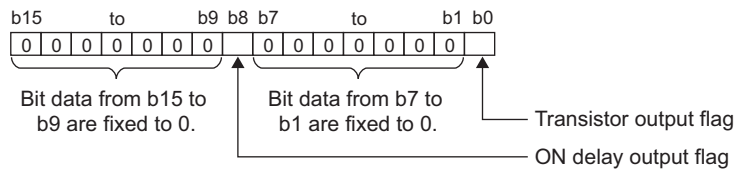
(7) CH Transistor output flag (Un\G21 to Un\G24) Standard

CH Heating transistor output flag (Un\G21 to Un\G24) Heating-cooling

CH Cooling transistor output flag (Un\G712 to Un\G715) Heating-cooling

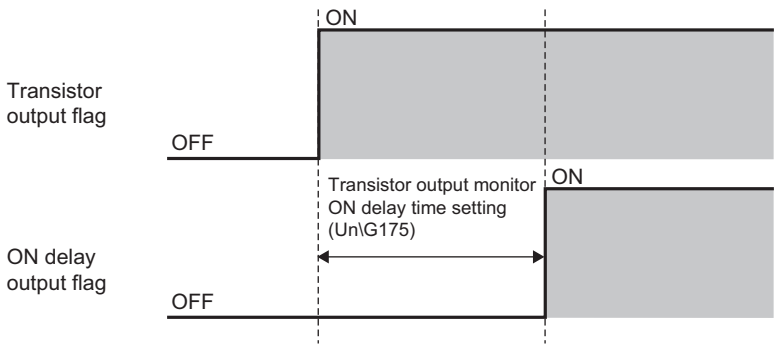
ON/OFF status of transistor output and ON delay output are stored in these flags. In the heating-cooling control, ON/OFF status of transistor output/ON delay output for heating are stored in Un\G21 to Un\G24.

- OFF: 0
- ON: 1



(a) Relationship with ON delay output flag

Relationship between Transistor output flag and ON delay output flag is shown in the following.



Transistor output monitor ON delay time setting (Un\G175) enables setting considering delay time (response/scan time delay) of actual transistor output. (☞ Page 391, Appendix 2 (45))
By monitoring the ON delay output flag and external output on the program, disconnection of external output can be judged.
For details on the ON delay output function, refer to the following.
☞ Page 178, Section 8.2.14

(8) CH□ Set value (SV) monitor (Un\G25 to Un\G28) Standard Heating-cooling

Set value (SV) of each time unit set in CH□ Setting change rate limiter time unit setting (Un\G735, Un\G751, Un\G767, Un\G783) is stored in this buffer memory area. (☞ Page 421, Appendix 2 (91))
The set value (SV) can be monitored in real time.

(9) Cold junction temperature process value (Un\G29) Common

The measured temperature of cold junction temperature compensation resistor is stored in this buffer memory area.

Values to be stored*¹ vary depending on the temperature unit set in CH1 Input range (Un\G32). (☞ Page 355, Appendix 2 (12))

- For other than °F : -10 to 100
- For °F : 14 to 212

*¹ The operation of the L60TC4 is guaranteed in the ambient temperature of 0 to 55°C.
For the general specifications of the L60TC4, refer to the following.

☞ "Safety Guidelines", the manual supplied with a CPU module or head module

(a) Usable modules

- L60TCTT4
- L60TCTT4BW

(10) MAN mode shift completion flag (Un\G30) Standard Heating-cooling

This flag is for checking completion of the mode shift when shifting AUTO (auto) mode to MAN (manual) mode.
The following values are stored in this buffer memory area.

- 0: MAN mode shift uncompleted
- 1: MAN mode shift completed

The following figure shows bits of the buffer memory area that correspond to each channel.

b15	b14	b13	b12	b11	b10	b9	b8	b7	b6	b5	b4	b3	b2	b1	b0
0	0	0	0	0	0	0	0	0	0	0	0	CH4	CH3	CH2	CH1

Bit data from b15 to b4 are fixed to 0.

When shift to MAN mode is completed, bits corresponding to appropriate channel become MAN mode shift completed (1).

(a) How to shift the mode

Shift the mode in the following buffer memory area.

- CH□ AUTO/MAN mode shift (Un\G50, Un\G82, Un\G114, Un\G146) (☞ Page 376, Appendix 2 (26))

(b) Setting manipulated value (MV) in MAN mode

Set the manipulated value (MV) in the following buffer memory area.

- CH□ MAN output setting (Un\G51, Un\G83, Un\G115, Un\G147) (☞ Page 377, Appendix 2 (27))

Set the manipulated value (MV) after confirming MAN mode shift completion flag (Un\G30) has become MAN mode shift completed (1).

(11)Memory's PID constants read/write completion flag (Un\G31)

Standard Heating-cooling

This flag indicates whether the operation for a non-volatile memory by setting the following buffer memory areas is normally completed or failed.

- CH□ Memory's PID constants read instruction (Un\G62, Un\G94, Un\G126, Un\G158)( Page 386, Appendix 2 (36))
- CH□ Automatic backup setting after auto tuning of PID constants (Un\G63, Un\G95, Un\G127, Un\G159)( Page 387, Appendix 2 (37))

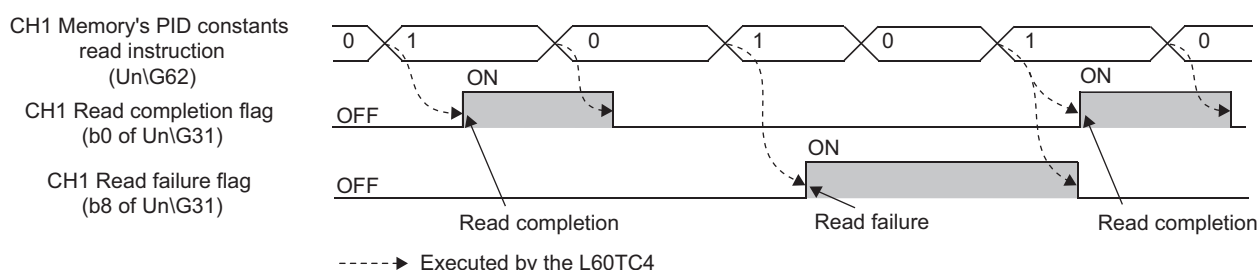
(a) Correspondence between each bit and flag

The following table lists flags correspond to bits of this buffer memory area.

Bit number	Flag description	Bit number	Flag description
b0	CH1 Read completion flag	b8	CH1 Read failure flag
b1	CH2 Read completion flag	b9	CH2 Read failure flag
b2	CH3 Read completion flag	b10	CH3 Read failure flag
b3	CH4 Read completion flag	b11	CH4 Read failure flag
b4	CH1 Write completion flag	b12	CH1 Write failure flag
b5	CH2 Write completion flag	b13	CH2 Write failure flag
b6	CH3 Write completion flag	b14	CH3 Write failure flag
b7	CH4 Write completion flag	b15	CH4 Write failure flag

(b) ON/OFF timing for CH□ Memory's PID constants read instruction (Un\G62, Un\G94, Un\G126, Un\G158) (Page 386, Appendix 2 (36))

The following figure shows the ON/OFF timing of this flag for CH□ Memory's PID constants read instruction (Un\G62, Un\G94, Un\G126, Un\G158). (For CH1)



When the data reading from the non-volatile memory is completed normally, CH□ Read completion flag (b0 to b3 of Un\G31) of the corresponding channel turns on.

CH□ Read completion flag (b0 to b3 of Un\G31) turns off when CH□ Memory's PID constants read instruction (Un\G62, Un\G94, Un\G126, Un\G158) is turned off from on.

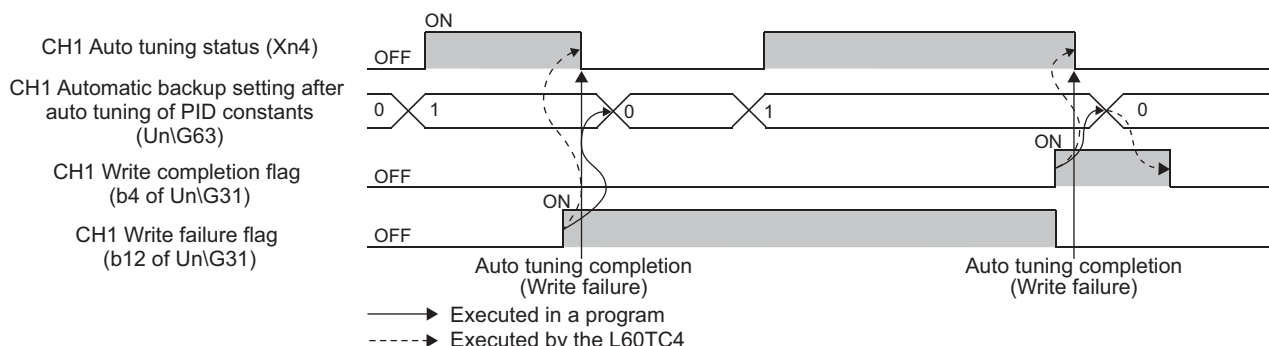
When the data reading from the non-volatile memory fails, CH□ Read failure flag (b8 to b11 of Un\G31) of the corresponding channel turns on and the L60TC4 operates with PID constants before the data reading. (The LED status remains.)

CH□ Read failure flag (b8 to b11 of Un\G31) turns off when the data reading of the corresponding channel is completed normally.

When the data reading fails, try again by turning CH□ Memory's PID constants read instruction (Un\G62, Un\G94, Un\G126, Un\G158) ON → OFF → ON.

(c) ON/OFF timing for CH□ Automatic backup setting after auto tuning of PID constants (Un\G63, Un\G95, Un\G127, Un\G159) (☞ Page 387, Appendix 2 (37))

The following figure shows ON/OFF timing of this flag for CH□ Automatic backup setting after auto tuning of PID constants (Un\G63, Un\G95, Un\G127, Un\G159). (For CH1)



When the data writing to the non-volatile memory is completed normally, CH□ Write completion flag (b4 to b7 of Un\G31) turns on.

CH□ Write completion flag (b4 to b7 of Un\G31) turns off when CH□ Automatic backup setting after auto tuning of PID constants (Un\G63, Un\G95, Un\G127, Un\G159) is set to Disable (0) from Enable (1).

When the data writing to the non-volatile memory fails, CH□ Write failure flag (b12 to b15 of Un\G31) of the corresponding channel turns on and the L60TC4 operates with PID constants calculated in the previous auto tuning. (The LED status remains.)

CH□ Write failure flag (b12 to b15 of Un\G31) turns off when the data writing of the corresponding channel is completed normally.

When the data writing fails, perform auto tuning again by turning CH□ Auto tuning instruction (Yn4 to Yn7) ON → OFF → ON. If the data writing fails even after executing auto tuning again, a hardware error can be the reason. Please consult your local Mitsubishi representative.

Point

- By referring to this flag at the completion of auto tuning, whether the automatic data backup is completed normally or not can be checked.
 - After confirming that the following flags are on, set CH□ Automatic backup setting after auto tuning of PID constants (Un\G63, Un\G95, Un\G127, Un\G159) to Disable (0).
 - CH□ Write completion flag (b4 to b7 of Un\G31) (when automatic data backup is completed normally)
 - CH□ Write failure flag (b12 to b15 of Un\G31) (when automatic data backup fails)
- If auto tuning is executed under Enable (1), although PID constants are stored after auto tuning is complete, CH□ Auto tuning status (Xn4 to Xn7) does not turn off.

For details on the auto tuning function, refer to the following.

☞ Page 145, Section 8.2.7

(12)CH□ Input range (Un\G32, Un\G64, Un\G96, Un\G128) Common

Select the set value according to temperature sensor, temperature measurement range^{*1}, output temperature unit (Celsius (°C)/Fahrenheit (°F)/digit) and resolution (1/0.1) which are used with the L60TC4.

^{*1} In the case of input from other analog modules (such as an A/D converter module) also, set these values.

Ex. When the L60TCTT4 or L60TCTT4BW is used and the following thermocouple is selected

- Thermocouple type: R
- Temperature measurement range: 0 to 1700°C
- Resolution: 1

Set 1 in CH□ Input range (Un\G32, Un\G64, Un\G96, Un\G128).

When using the L60TCTT4 or L60TCTT4BW, refer to  Page 356, Appendix 2 (12) (a).

When using the L60TCRT4 or L60TCRT4BW, refer to  Page 359, Appendix 2 (12) (b).

A

(a) Setting range of the L60TCTT4, L60TCTT4BW

The following table lists setting values of CH□ Input range (Un\G32, Un\G64, Un\G96, Un\G128) and the corresponding thermocouple types.

The relationship between temperature unit and setting values is as follows.

Setting of CH□ Input range (Un\G32, Un\G64, Un\G96, Un\G128)	Item	
1 to 99	Thermocouple is used. (No input from other analog modules (such as an A/D converter module)) (1 to 199)	Output temperature unit is Celsius (°C).
100 to 199		Output temperature unit is Fahrenheit (°F).
200 to 299	Other analog modules (such as an A/D converter module) are used. (200 to 299)	Unit is digit.

Thermocouple type	Temperature measurement range	Celsius (°C)/ Fahrenheit (°F)/digit	Resolution	CH□ Input range (Un\G32, Un\G64, Un\G96, Un\G128)	Auto-setting at input range change*1	
					CH□ Upper limit setting limiter, CH□ Process alarm upper lower limit value, CH□ Process alarm upper upper limit value	CH□ Lower limit setting limiter, CH□ Process alarm lower lower limit value, CH□ Process alarm lower upper limit value
R	0 to 1700	°C	1	1	1700	0
	0 to 3000	°F	1	105	3000	0
K	-200.0 to 400.0	°C	0.1	38	4000	-2000
	0.0 to 400.0	°C	0.1	36	4000	0
	0 to 1300	°C	1	2 (Default value)	1300	0
	0 to 500	°C	1	11	500	0
	0.0 to 500.0	°C	0.1	40	5000	0
	0 to 800	°C	1	12	800	0
	0.0 to 800.0	°C	0.1	41	8000	0
	-200.0 to 1300.0	°C	0.1	49	13000	-2000
	0 to 1000	°F	1	100	1000	0
	0.0 to 1000.0	°F	0.1	130	10000	0
J	0 to 2400	°F	1	101	2400	0
	0.0 to 400.0	°C	0.1	37	4000	0
	0 to 500	°C	1	13	500	0
	0.0 to 500.0	°C	0.1	42	5000	0
	0 to 800	°C	1	14	800	0
	0.0 to 800.0	°C	0.1	43	8000	0
	-200.0 to 1000.0	°C	0.1	50	10000	-2000
	0 to 1200	°C	1	3	1200	0
	0 to 1000	°F	1	102	1000	0
	0.0 to 1000.0	°F	0.1	131	10000	0
	0 to 1600	°F	1	103	1600	0
	0 to 2100	°F	1	104	2100	0

Thermocouple type	Temperature measurement range	Celsius (°C)/ Fahrenheit (°F)/digit	Resolution	CH□ Input range (Un\G32, Un\G64, Un\G96, Un\G128)	Auto-setting at input range change*1	
					CH□ Upper limit setting limiter, CH□ Process alarm upper lower limit value, CH□ Process alarm upper upper limit value	CH□ Lower limit setting limiter, CH□ Process alarm lower lower limit value, CH□ Process alarm lower upper limit value
T	-200 to 400	°C	1	4	400	-200
	-200 to 200	°C	1	21	200	-200
	-200.0 to 400.0	°C	0.1	39	4000	-2000
	0 to 200	°C	1	19	200	0
	0 to 400	°C	1	20	400	0
	0.0 to 400.0	°C	0.1	45	4000	0
	-300 to 400	°F	1	110	400	-300
	0 to 700	°F	1	109	700	0
	0.0 to 700.0	°F	0.1	132	7000	0
S	0 to 1700	°C	1	15	1700	0
	0 to 3000	°F	1	106	3000	0
B	0 to 1800	°C	1	16	1800	0
	0 to 3000	°F	1	107	3000	0
E	0 to 400	°C	1	17	400	0
	0.0 to 700.0	°C	0.1	44	7000	0
	0 to 1000	°C	1	18	1000	0
	-200.0 to 1000.0	°C	0.1	51	10000	-2000
	0 to 1800	°F	1	108	1800	0
N	0 to 1300	°C	1	22	1300	0
	0.0 to 1000.0	°C	0.1	52	10000	0
	0 to 2300	°F	1	111	2300	0
U	-200 to 200	°C	1	26	200	-200
	0 to 400	°C	1	25	400	0
	0.0 to 600.0	°C	0.1	46	6000	0
	-300 to 400	°F	1	115	400	-300
	0 to 700	°F	1	114	700	0
L	0 to 400	°C	1	27	400	0
	0.0 to 400.0	°C	0.1	47	4000	0
	0 to 900	°C	1	28	900	0
	0.0 to 900.0	°C	0.1	48	9000	0
	0 to 800	°F	1	116	800	0
	0 to 1600	°F	1	117	1600	0
PLII	0 to 1200	°C	1	23	1200	0
	0 to 2300	°F	1	112	2300	0
W5Re/W26Re	0 to 2300	°C	1	24	2300	0
	0 to 3000	°F	1	113	3000	0

A

Thermocouple type	Temperature measurement range	Celsius (°C)/ Fahrenheit (°F)/digit	Resolution	CH□ Input range (Un\G32, Un\G64, Un\G96, Un\G128)	Auto-setting at input range change *1	
					CH□ Upper limit setting limiter, CH□ Process alarm upper lower limit value, CH□ Process alarm upper upper limit value	CH□ Lower limit setting limiter, CH□ Process alarm lower lower limit value, CH□ Process alarm lower upper limit value
Input from other analog modules (0 to 4000)*2	0 to 4000	digit	1	201	4000	0
Input from other analog modules (0 to 12000)*2	0 to 12000	digit	1	202	12000	0
Input from other analog modules (0 to 16000)*2	0 to 16000	digit	1	203	16000	0
Input from other analog modules (0 to 20000)*2	0 to 20000	digit	1	204	20000	0
Input from other analog modules (0 to 32000)*2	0 to 32000	digit	1	205	32000	0

*1 When the input range is changed, the set values in some buffer memory areas are initialized automatically and return to the default value (0).

(☞ Page 360, Appendix 2 (12) (d))

*2 Same as the L60TCRT4, L60TCRT4BW

Remark

For the following mode and channel, CH□ Input range (Un\G32, Un\G64, Un\G96, Un\G128) cannot be set to 201 to 205. If these values are set, a write data error (error code: □□□4_H) occurs.

Mode		Corresponding channel
Temperature input mode		CH1 to CH4
Temperature control mode	Heating-cooling control (normal mode)	CH3, CH4
	Mix control (normal mode)	CH2

(b) Setting range of the L60TCRT4, L60TCRT4BW

The following table lists setting values of CH□ Input range (Un\G32, Un\G64, Un\G96, Un\G128) and the corresponding platinum resistance thermometer types.

Platinum resistance thermometer type	Temperature measurement range	Celsius (°C)/ Fahrenheit (°F)/digit	Resolution	CH□ Input range (Un\G32, Un\G64, Un\G96, Un\G128)	Auto-setting at input range change*1	
					CH□ Upper limit setting limiter, CH□ Process alarm upper lower limit value, CH□ Process alarm upper upper limit value	CH□ Lower limit setting limiter, CH□ Process alarm lower lower limit value, CH□ Process alarm lower upper limit value
Pt100	-200.0 to 600.0	°C	0.1	7 (Default value)	6000	-2000
	-200.0 to 200.0	°C	0.1	8	2000	-2000
	-200.0 to 850.0	°C	0.1	54	8500	-2000
	-300 to 1100	°F	1	141	1100	-300
	-300.0 to 300.0	°F	0.1	143	3000	-3000
JPt100	-200.0 to 500.0	°C	0.1	5	5000	-2000
	-200.0 to 200.0	°C	0.1	6	2000	-2000
	-200.0 to 640.0	°C	0.1	53	6400	-2000
	-300 to 900	°F	1	140	900	-300
	-300.0 to 300.0	°F	0.1	142	3000	-3000
Input from other analog modules (0 to 4000)*2	0 to 4000	digit	1	201	4000	0
Input from other analog modules (0 to 12000)*2	0 to 12000	digit	1	202	12000	0
Input from other analog modules (0 to 16000)*2	0 to 16000	digit	1	203	16000	0
Input from other analog modules (0 to 20000)*2	0 to 20000	digit	1	204	20000	0
Input from other analog modules (0 to 32000)*2	0 to 32000	digit	1	205	32000	0

*1 When the input range is changed, the set values in some buffer memory areas are initialized automatically and return to the default value (0).

( Page 360, Appendix 2 (12) (d))

*2 Same as the L60TCTT4, L60TCTT4BW

Remark

For the following mode and channel, CH□ Input range (Un\G32, Un\G64, Un\G96, Un\G128) cannot be set to 201 to 205. If these values are set, a write data error (error code: □□□4_H) occurs.

Mode		Corresponding channel
Temperature input mode		CH1 to CH4
Temperature control mode	Heating-cooling control (normal mode)	CH3, CH4
	Mix control (normal mode)	CH2

(c) Resolution

The resolution is applied to the stored values and the set values of particular buffer memory areas as described in the following table.

Resolution	Stored value	Set value
1	Value in 1°C (°F or digit) unit is stored.	Set a value in 1°C (°F or digit) unit.
0.1	Value in 0.1°C (°F) unit (tenfold value) is stored.	Set a value in 0.1°C (°F) unit (tenfold value).

For applicable buffer memory areas, refer to the following.

☞ Page 344, Appendix 2 (2)

(d) When "Auto-setting at Input Range Change" is set to "1: Enable" on Switch Setting

☞ Page 110, Section 7.2)

When the input range is changed, the following buffer memory areas are set automatically according to selected temperature sensor. Set the buffer memory areas again if necessary.

Buffer memory area name	Buffer memory address				Reference
	CH1	CH2	CH3	CH4	
CH□ Upper limit setting limiter	Un\G55	Un\G87	Un\G119	Un\G151	Page 381, Appendix 2 (31)
CH□ Lower limit setting limiter	Un\G56	Un\G88	Un\G120	Un\G152	
CH□ Process alarm lower lower limit value	Un\G197	Un\G213	Un\G229	Un\G245	Page 397, Appendix 2 (54)
CH□ Process alarm lower upper limit value	Un\G198	Un\G214	Un\G230	Un\G246	
CH□ Process alarm upper lower limit value	Un\G199	Un\G215	Un\G231	Un\G247	
CH□ Process alarm upper upper limit value	Un\G200	Un\G216	Un\G232	Un\G248	

At the same time, the following buffer memory areas related to the input range is initialized to the default value (0) automatically. Set the buffer memory areas again if necessary.

Buffer memory area name	Buffer memory address				Reference
	CH1	CH2	CH3	CH4	
CH□ Set value (SV) setting	Un\G34	Un\G66	Un\G98	Un\G130	Page 363, Appendix 2 (14)
CH□ Alert set value 1	Un\G38	Un\G70	Un\G102	Un\G134	Page 367, Appendix 2 (18)
CH□ Alert set value 2	Un\G39	Un\G71	Un\G103	Un\G135	
CH□ Alert set value 3	Un\G40	Un\G72	Un\G104	Un\G136	
CH□ Alert set value 4	Un\G41	Un\G73	Un\G105	Un\G137	
CH□ AT bias setting	Un\G53	Un\G85	Un\G117	Un\G149	Page 379, Appendix 2 (29)
CH□ Loop disconnection detection dead band	Un\G60	Un\G92	Un\G124	Un\G156	Page 384, Appendix 2 (34)
CH□ Sensor two-point correction offset value (measured value)	Un\G544	Un\G576	Un\G608	Un\G640	Page 403, Appendix 2 (63)

Buffer memory area name	Buffer memory address				Reference
	CH1	CH2	CH3	CH4	
CH□ Sensor two-point correction offset value (corrected value)	Un\G545	Un\G577	Un\G609	Un\G641	Page 403, Appendix 2 (64)
CH□ Sensor two-point correction gain value (measured value)	Un\G546	Un\G578	Un\G610	Un\G642	Page 404, Appendix 2 (65)
CH□ Sensor two-point correction gain value (corrected value)	Un\G547	Un\G579	Un\G611	Un\G643	Page 404, Appendix 2 (66)
CH□ Simultaneous temperature rise gradient data	Un\G731	Un\G747	Un\G763	Un\G779	Page 418, Appendix 2 (87)
CH□ Simultaneous temperature rise dead time	Un\G732	Un\G748	Un\G764	Un\G780	Page 418, Appendix 2 (88)

These 19 buffer memory areas are set automatically when the input range is changed and Setting change instruction (YnB) is turned OFF → ON → OFF during setting mode (Setting/operation mode status (Xn1): OFF).

(e) When "Auto-setting at Input Range Change" is set to "0: Disable" on Switch Setting (☞ Page 110, Section 7.2)

Set values in the buffer memory (☞ Page 360, Appendix 2 (12) (d)) can be out of the setting range. (When the setting range changes according to the change of the input range, the set value before the change can turn out of the range.) In this case, a write data error (error code: □□□4_H) occurs in the buffer memory area where the value turns out of the setting range. Change the input range after setting each buffer memory area with values within the setting range after the input range change.

(f) Enablement of set contents

Enable the set contents by turning Setting change instruction (YnB) OFF → ON → OFF during the setting mode (Setting/operation mode status (Xn1): OFF).

(g) Precautions

Soon after the input range is changed, input temperature may be unstable. Do not start the control until Temperature conversion completion flag (Un\G786) becomes First temperature conversion completed (1_H).

A

(13)CH□ Stop mode setting (Un\G33, Un\G65, Un\G97, Un\G129) Standard Heating-cooling

Set the mode activated at PID control stop.

(a) Setting range and action of L60TC4

The following table lists the relationship.

○: Executed ×: Not executed

Mode which can be set	Set value of CH□ Stop mode setting (Un\G33, Un\G65, Un\G97, Un\G129)	Action		
		PID control	Temperature judgment ^{*1}	Alert judgment
Stop	0	×	×	×
Monitor	1	×	○	×
Alert	2	×	○	○

*1 Means that the L60TC4 checks whether the input temperature is in the temperature measurement range set in the input range.

However, action of the L60TC4 differs depending on the following settings.

- CH□ Unused channel setting (Un\G61, Un\G93, Un\G125, Un\G157) (Page 385, Appendix 2 (35))
- Setting/operation mode instruction (Yn1) (Page 340, Appendix 1.2 (1))
- PID continuation flag (Un\G169) (Page 390, Appendix 2 (43))
- CH□ PID control forced stop instruction (YnC to YnF) (Page 343, Appendix 1.2 (7))
- "Output Setting at CPU Stop Error" (Switch Setting) (Page 110, Section 7.2)

For details, refer to the following.

- PID control: Page 154, Section 8.2.7 (7)
- Temperature judgment: Page 346, Appendix 2 (3)
- Alert judgment: Page 170, Section 8.2.11 (5)

(b) Default value

The default values are set to Monitor (1) in all channels.

Point

Default values are set to Monitor (1).

Therefore, channels which temperature sensors are not connected to detect sensor input disconnection and the ALM LED blinks.

When CH□ Unused channel setting (Un\G61, Un\G93, Un\G125, Un\G157) is set to Unused (1), control of the corresponding channel is not performed. For channels which temperature sensors are not connected to, CH□ Unused channel setting (Un\G61, Un\G93, Un\G125, Un\G157) must be set to Unused (1).

(14)CH□ Set value (SV) setting (Un\G34, Un\G66, Un\G98, Un\G130) **Standard** **Heating-cooling**

Set the target temperature value of PID control.

(a) Setting range

The setting range is identical to the temperature measurement range of the set input range. (☞ Page 355, Appendix 2 (12))

When a value which is out of the setting range is set, a write data error (error code: □□□4_H) and the following situations occur.

- Error occurrence flag (Xn2) turns on.
- The error code is stored in Error code (Un\G0).

(b) Setting unit

The value to be set differs depending on the stored value in CH□ Decimal point position (Un\G1 to Un\G4).

(☞ Page 344, Appendix 2 (2))

- No decimal place (0): Set a value in 1°C (°F or digit) unit.
- One decimal place (1): Set a value in 0.1°C (°F) unit (tenfold value).

(c) Default value

The default values are set to 0 in all channels.

A

(15)CH□ Proportional band (P) setting (Un\G35, Un\G67, Un\G99, Un\G131) Standard

CH□ Heating proportional band (Ph) setting (Un\G35, Un\G67, Un\G99,

Un\G131) Heating-cooling

CH□ Cooling proportional band (Pc) setting (Un\G720, Un\G736, Un\G752,

Un\G768) Heating-cooling

Set proportional band (P)/heating proportional band (Ph)/cooling proportional band (Pc) to perform PID control.
(In the heating-cooling control, set heating proportional band (Ph) to Un\G35, Un\G67, Un\G99, Un\G131.)

(a) Setting range

Set the value within the following ranges for the full scale of the set input range. ( Page 355, Appendix 2 (12))

- Proportional band (P) setting: 0 to 10000 (0.0% to 1000.0%)
- Heating proportional band (Ph) setting: 0 to 10000 (0.0% to 1000.0%)
- Cooling proportional band (Pc) setting: 1 to 10000 (0.1% to 1000.0%)

Ex. When the value of the buffer memory area is set as follows, the proportional band (P) is 60°C.

- CH□ Input range (Un\G32, Un\G64, Un\G96, Un\G128): 38 (temperature measurement range: -200.0 to 400.0°C)
- CH□ Proportional band (P) setting (Un\G35, Un\G67, Un\G99, Un\G131): 100 (10.0%)

$$(\text{Full scale}) \times (\text{Proportional band (P) setting}) = (400.0^{\circ}\text{C} - (-200.0)) \times 0.1 = 60^{\circ}\text{C}$$

(b) Two-position control

Set the proportional band (P)/heating proportional band (Ph) to 0.

For details on Two-position control, refer to the following.

 Page 133, Section 8.2.3

(c) Default value

The default values are set to 30 (3.0%) in all channels.

Point

If the proportional band (P)/heating proportional band (Ph) is set to 0 (0.0%), the auto tuning cannot be performed. To perform the auto tuning, set proportional band (P)/heating proportional band (Ph) to other than 0.
For details on the auto tuning function, refer to the following.

☞ Page 145, Section 8.2.7

Remark

The proportional band (P) is the variation width of deviation (E) necessary for manipulated value (MV) to vary 0% to 100%. The following formula shows the relationship between deviation (E) and manipulated value (MV) in proportional action.

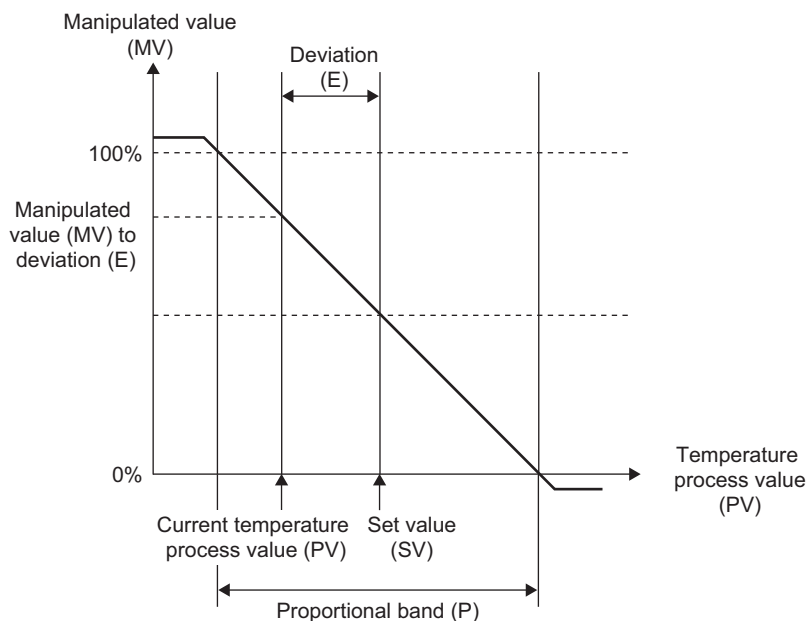
$$MV = K_p \cdot E$$

K_p is proportional gain. The following formula shows proportional band (P) in this case.

$$P = \frac{1}{K_p} \cdot 100$$

When the value of the proportional band (P) is increased, the proportional gain (K_p) decreases. Therefore, the manipulated value (MV) for variation of the deviation (E) becomes small.

When the value of proportional band (P) is decreased, the proportional gain (K_p) increases. Therefore, the manipulated value (MV) for variation of the deviation (E) becomes large. The following figure shows the proportional band (P) in reverse action.



(16)CH□ Integral time (I) setting (Un\G36, Un\G68, Un\G100, Un\G132) Common

Set integral time (I) to perform PID control.

(a) Setting range

The setting range is 0 to 3600 (0 to 3600s).

(b) In the P control or PD control

Set this setting to 0.

For details on control methods, refer to the following.

 Page 133, Section 8.2.3

(c) Default value

The default values are set to 240 (240s) in all channels.

(17)CH□ Derivative time (D) setting (Un\G37, Un\G69, Un\G101, Un\G133) Common

Set derivative time (D) to perform PID control.

(a) Setting range

The setting range is 0 to 3600 (0 to 3600s).

(b) In the P control or PI control

Set this setting to 0.

For details on control methods, refer to the following.

 Page 133, Section 8.2.3

(c) Default value

The default values are set to 60 (60s) in all channels.

(18)CH□ Alert set value 1 (Un\G38, Un\G70, Un\G102, Un\G134) **Standard** **Heating-cooling**

CH□ Alert set value 2 (Un\G39, Un\G71, Un\G103, Un\G135) **Standard** **Heating-cooling**

CH□ Alert set value 3 (Un\G40, Un\G72, Un\G104, Un\G136) **Standard** **Heating-cooling**

CH□ Alert set value 4 (Un\G41, Un\G73, Un\G105, Un\G137) **Standard** **Heating-cooling**

Set temperature values where CH□ Alert 1 (Un\G5 to Un\G8 of b8) to CH□ Alert 4 (Un\G5 to Un\G8 of b11) turn on according to selected alert mode of alert 1 to 4.

For CH□ Alert definition (Un\G5 to Un\G8), refer to the following.

☞ Page 346, Appendix 2 (3)

For details on the alert function, refer to the following.

☞ Page 161, Section 8.2.11

(a) Alert mode

Set the alert mode of alert 1 to 4 in the following buffer memory areas. Alert mode of alert 1 to 4 respectively correspond to alert set value 1 to 4.

(b) Setting range

Buffer memory area name	Buffer memory address				Reference
	CH1	CH2	CH3	CH4	
CH□ Alert 1 mode setting	Un\G192	Un\G208	Un\G224	Un\G240	Page 395, Appendix 2 (52)
CH□ Alert 2 mode setting	Un\G193	Un\G209	Un\G225	Un\G241	
CH□ Alert 3 mode setting	Un\G194	Un\G210	Un\G226	Un\G242	
CH□ Alert 4 mode setting	Un\G195	Un\G211	Un\G227	Un\G243	

The setting range differs depending on the setting of the following buffer memory area. (each full scale differs)

- CH□ Input range (Un\G32, Un\G64, Un\G96, Un\G128) (☞ Page 355, Appendix 2 (12))

Also, the setting range differs depending on alert mode to be set. (☞ Page 367, Appendix 2 (18) (a))

Alert mode	Setting range of alert set value	Remarks
No alert	—	—
Upper limit input alert, lower limit input alert	Temperature measurement range of the input range	Same as with standby
Upper limit deviation alert, lower limit deviation alert, upper limit deviation alert (using the set value (SV)), lower limit deviation alert (using the set value (SV))	(-(full scale)) to full scale	Same as with standby and standby (second time)
Upper lower limit deviation alert, within-range alert, upper lower limit deviation alert (using the set value (SV)), within-range alert (using the set value (SV))	0 to full scale	Same as with standby and standby (second time)

When a value which is out of the setting range is set, a write data error (error code: □□□4_H) and the following situations occur.

- Error occurrence flag (Xn2) turns on.
- The error code is stored in Error code (Un\G0).

(c) Setting unit

The value to be set differs depending on the stored value in CH□ Decimal point position (Un\G1 to Un\G4).

( Page 344, Appendix 2 (2))

- No decimal place (0): Set a value in 1°C (°F or digit) unit.
- One decimal place (1): Set a value in 0.1°C (°F) unit (tenfold value).

(d) Default value

The default values are set to 0 in all channels.

(19)CH□ Upper limit output limiter (Un\G42, Un\G74, Un\G106, Un\G138) **Standard**

CH□ Lower limit output limiter (Un\G43, Un\G75, Un\G107, Un\G139) **Standard**

CH□ Heating upper limit output limiter (Un\G42, Un\G74, Un\G106,

Un\G138) **Heating-cooling**

CH□ Cooling upper limit output limiter (Un\G721, Un\G737, Un\G753, Un\G769)

Heating-cooling

In the standard control, set upper limit value/lower limit value for actual output of manipulated value (MV) calculated by the PID operation to an external device. In the heating-cooling control, set upper limit value of heating/cooling for actual output of manipulated value for heating (MVh)/manipulated value for cooling (MVc) calculated by the PID operation to an external device. Additionally, Un\G42, Un\G74, Un\G106, Un\G138 are used for heating in the heating-cooling control. During the auto tuning, setting of Heating upper limit output limiter and Cooling upper limit output limiter are disabled.

(a) Setting range

The following table lists setting range of each buffer memory.

Buffer memory	Setting range	Remarks
CH□ Upper limit output limiter (Un\G42, Un\G74, Un\G106, Un\G138)	-50 to 1050 (-5.0% to 105.0%)	Set the values to lower limit output limiter value < upper limit output limiter value. When lower limit output limiter value ≥ upper limit output limiter value, write data error (error code: □□□5 _H) occurs. In addition, if the setting is out of the setting value, a write data error (error code: □□□4 _H) occurs. When the error occurs, the following situations occur. • Error occurrence flag (Xn2) turns on. • The error code is stored in Error code (Un\G0).
CH□ Lower limit output limiter (Un\G43, Un\G75, Un\G107, Un\G139)		
CH□ Heating upper limit output limiter (Un\G42, Un\G74, Un\G106, Un\G138)	0 to 1050 (0.0% to 105.0%)	If the setting is out of the setting value, a write data error (error code: □□□4 _H) occurs. When the error occurs, the following situations occur. • Error occurrence flag (Xn2) turns on. • The error code is stored in Error code (Un\G0).
CH□ Cooling upper limit output limiter (Un\G721, Un\G737, Un\G753, Un\G769)		

Point

- In the standard control, CH□ Cooling upper limit output limiter (Un\G721, Un\G737, Un\G753, Un\G769) is invalid even it is set.
- In the heating-cooling control, lower limit value is not used. When CH□ Lower limit output limiter (Un\G43, Un\G75, Un\G107, Un\G139) is set to other than 0, a write data error (error code: □□□2_H) occurs.

(b) Two-position control (👉 Page 133, Section 8.2.3 (1))

The following table lists Enable/Disable of the setting.

Buffer memory	Enable/Disable of the setting in the two-position control
CH□ Upper limit output limiter (Un\G42, Un\G74, Un\G106, Un\G138)	Disable
CH□ Lower limit output limiter (Un\G43, Un\G75, Un\G107, Un\G139)	
CH□ Heating upper limit output limiter (Un\G42, Un\G74, Un\G106, Un\G138)	Enable
CH□ Cooling upper limit output limiter (Un\G721, Un\G737, Un\G753, Un\G769)	

(c) Manual control (👉 Page 143, Section 8.2.5)

The following table lists Enable/Disable of the setting.

Buffer memory	Enable/Disable of the setting in the manual control	Remarks
CH□ Upper limit output limiter (Un\G42, Un\G74, Un\G106, Un\G138)	Enable	When an output exceeds the upper limit output limiter value, the manipulated value (MV) of the manual control is fixed (clipped) to the upper limit output limiter value that is set. When an output falls below the lower limit output limiter value, the manipulated value (MV) of the manual control is fixed (clipped) to the lower limit output limiter value that is set.
CH□ Lower limit output limiter (Un\G43, Un\G75, Un\G107, Un\G139)		
CH□ Heating upper limit output limiter (Un\G42, Un\G74, Un\G106, Un\G138)	Disable	—
CH□ Cooling upper limit output limiter (Un\G721, Un\G737, Un\G753, Un\G769)		

(d) Default value

The following table lists the default value of each buffer memory area.

Buffer memory	Default value
CH□ Upper limit output limiter (Un\G42, Un\G74, Un\G106, Un\G138)	1000 (100.0%)
CH□ Lower limit output limiter (Un\G43, Un\G75, Un\G107, Un\G139)	0 (0.0%)
CH□ Heating upper limit output limiter (Un\G42, Un\G74, Un\G106, Un\G138)	1000 (100.0%)
CH□ Cooling upper limit output limiter (Un\G721, Un\G737, Un\G753, Un\G769)	

(20)CH□ Output variation limiter setting (Un\G44, Un\G76, Un\G108, Un\G140)

Standard Heating-cooling

Set the limit of an output variation per 1s to regulate a rapid change of the manipulated value (MV).

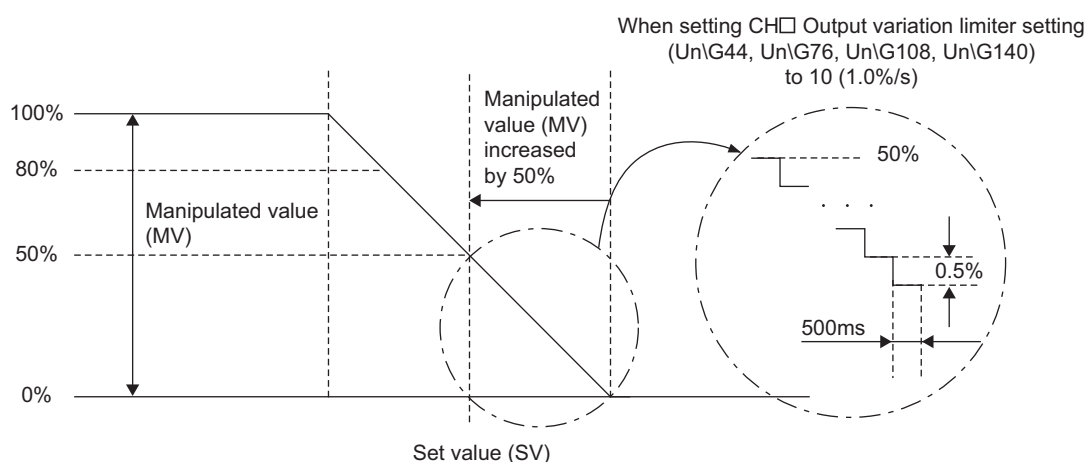
(a) Setting range

The setting range is 0 or 1 to 1000 (0.1%/s to 100.0%/s). When 0 is set, an output variation is not regulated.

Ex. When the value of the buffer memory is set as follows

- CH□ Output variation limiter setting (Un\G44, Un\G76, Un\G108, Un\G140): 10(1.0%/s)

The output changes by 0.5% per 500ms, and by 0.2% or 0.3% per 250ms respectively when the sampling cycle is 500ms and 250ms. If the manipulated value (MV) rapidly changes by 50%, the variation is regulated to 1%/s. Therefore, it takes 50s until the output actually changes by 50%.

**(b) Two-position control (☞ Page 133, Section 8.2.3 (1))**

The setting is invalid.

(c) Manual control (☞ Page 143, Section 8.2.5)

The setting is enabled.

(d) Auto tuning function execution (☞ Page 145, Section 8.2.7)

The setting is enabled, but some change in Output variation limiter setting during auto tuning does not lead to a calculation of the appropriate PID constants. During auto tuning, therefore, no adjustment for output variation is recommended.

(e) Default value

The default values are set to 0 in all channels.

(21)CH□ Sensor correction value setting (Un\G45, Un\G77, Un\G109, Un\G141)

Common

Set the correction value when measured temperature and actual temperature are different.

For details on the sensor correction function, refer to the following.

☞ Page 230, Section 8.3.3

(a) Setting range

Set the value within the range -5000 to 5000 (-50.00% to 50.00%) of the full scale of the set input range.

☞ Page 355, Appendix 2 (12))

(b) Enablement of setting contents

When Normal sensor correction (one-point correction) (0_H) is set in Sensor correction function selection

(Un\G785), the setting content is enabled. (☞ Page 423, Appendix 2 (93))

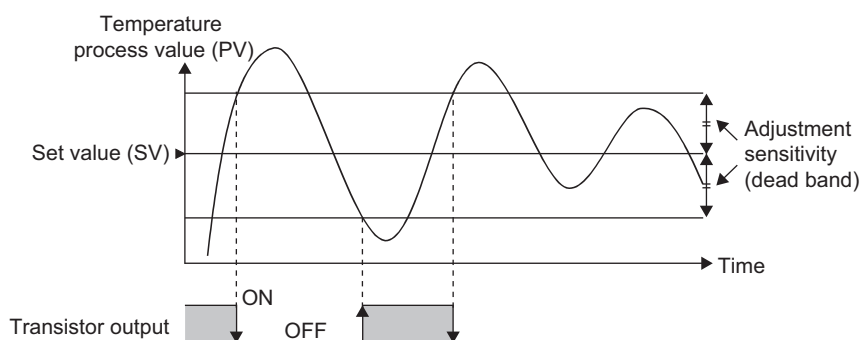
(c) Default value

The default values are set to 0 (0.00%) in all channels.

(22)CH□ Adjustment sensitivity (dead band) setting (Un\G46, Un\G78, Un\G110, Un\G142)

Standard Heating-cooling

To prevent a chattering in the two-position control, set the adjustment sensitivity (dead band) for the set value (SV).



For details on the two-position control, refer to the following.

☞ Page 133, Section 8.2.3

(a) Setting range

Set the value within the range 1 to 100 (0.1% to 10.0%) of the full scale of the set input range. (☞ Page 355, Appendix 2 (12))

Ex. When the value of the buffer memory is set as follows

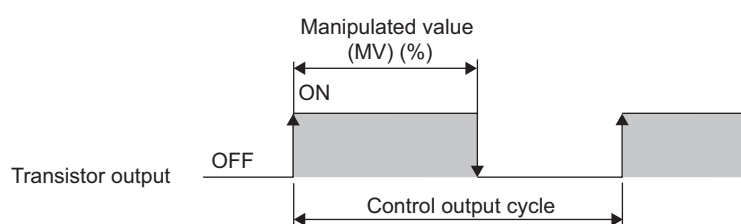
- CH□ Input range (Un\G32, Un\G64, Un\G96, Un\G128): 38 (temperature measurement range: -200.0 to 400.0°C)
- CH□ Adjustment sensitivity (dead band) setting (Un\G46, Un\G78, Un\G110, Un\G142): 10 (1.0%)
(Full scale) × (Adjustment sensitivity (dead band) setting) = (400.0°C - (-200.0)) × 0.01 = 6.0°C
The dead band is the set value (SV) ±6.0°C.

(b) Default value

The default values are set to 5 (0.5%) in all channels.

(23)CH□ Control output cycle setting (Un\G47, Un\G79, Un\G111, Un\G143) Standard**CH□ Heating control output cycle setting (Un\G47, Un\G79, Un\G111, Un\G143)**Heating-cooling**CH□ Cooling control output cycle setting (Un\G722, Un\G738, Un\G754, Un\G770)** Heating-cooling

Set the pulse cycle (ON/OFF cycle) of the transistor output. In the heating-cooling control, the output cycle of the heating control and cooling control can be set individually. Additionally, Un\G47, Un\G79, Un\G111, Un\G143 are used for heating in the heating-cooling control.

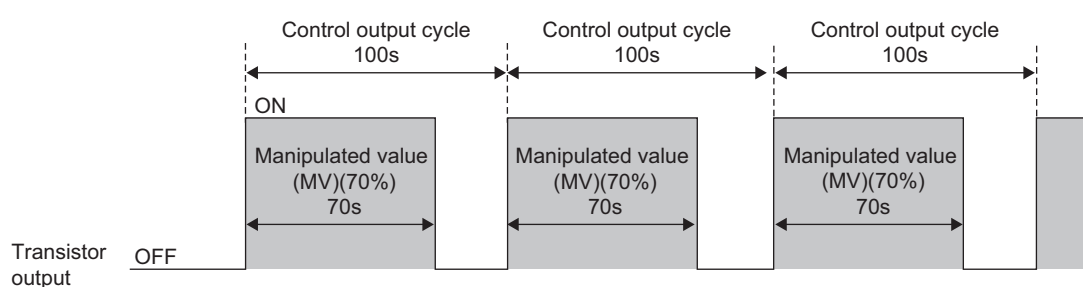


The ON time of the control output cycle is determined by multiplying the control output cycle by the manipulated value (MV)^{*1} (%) calculated by PID operation. If the manipulated value (MV)^{*1} is constant, a pulse of the same cycle is output repeatedly.

^{*1} For the heating control output cycle, the manipulated value for heating (MVh) is used. For the cooling control output cycle, manipulated value for cooling (MVC) is used.

Ex. When 700 (70%) is stored in CH□ Manipulated value (MV) (Un\G13 to Un\G16) and the value of the buffer memory is set as follows

- CH□ Control output cycle setting (Un\G47, Un\G79, Un\G111, Un\G143): 100 (100s)
 $100\text{s} \times 0.7 (70\%) = 70\text{s}$
 The ON time is 70s.
 The transistor output turns on for 70s and off for 30s per 100s.

**(a) Setting range**

- When the control output cycle unit selection setting on Switch Setting is set to the cycle of 1s: 1 to 100 (1s to 100s)
- When the control output cycle unit selection setting on Switch Setting is set to the cycle of 0.1s: 5 to 1000 (0.5s to 100.0s)

For details on the control output cycle unit selection setting function, refer to the following.

Page 144, Section 8.2.6

(b) Two-position control (👉 Page 133, Section 8.2.3 (1))

The setting is invalid.

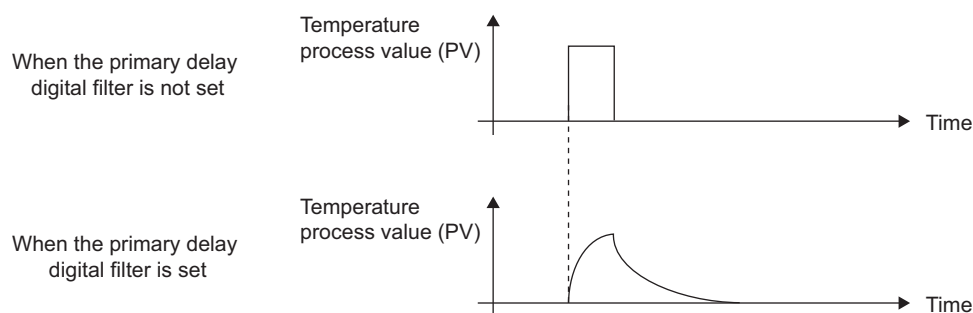
(c) Default value

- When the control output cycle unit selection setting on Switch Setting is set to the cycle of 1s: 30 (30s)
- When the control output cycle unit selection setting on Switch Setting is set to the cycle of 0.1s: 300 (30.0s)

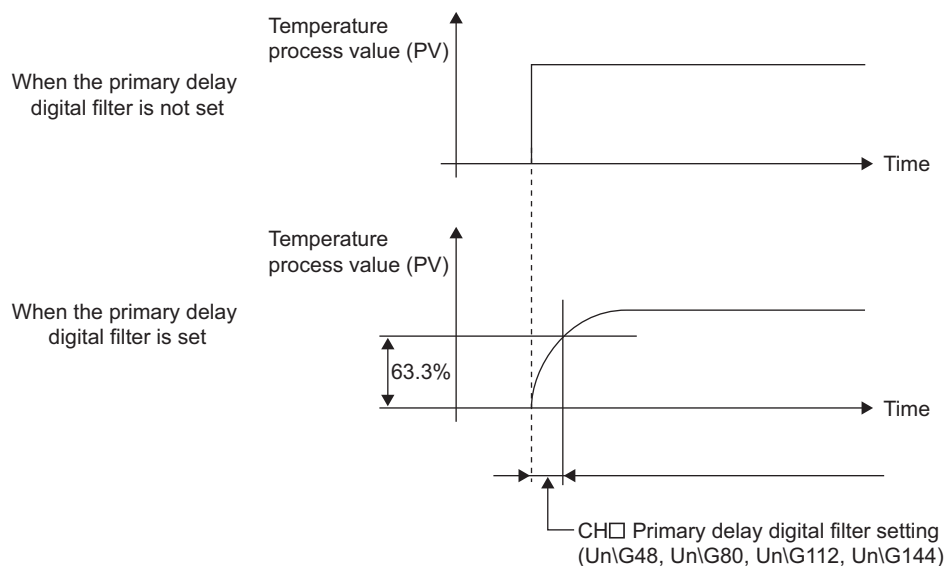
(24)CH□ Primary delay digital filter setting (Un\G48, Un\G80, Un\G112, Un\G144)

Common

The temperature process values (PV) are smoothed and sudden changes are absorbed by using the primary delay digital filter.



The time for the temperature process value (PV) to change by 63.3% can be set by the primary delay digital filter setting (filter setting time).



(a) Setting range

The setting range is 0 or 1 to 100 (1s to 100s). When 0 is set, the primary delay digital filter processing is not performed.

(b) Default value

The default values are set to 0 (primary delay digital filter processing disabled) in all channels.

(25)CH□ Control response parameter (Un\G49, Un\G81, Un\G113, Un\G145)

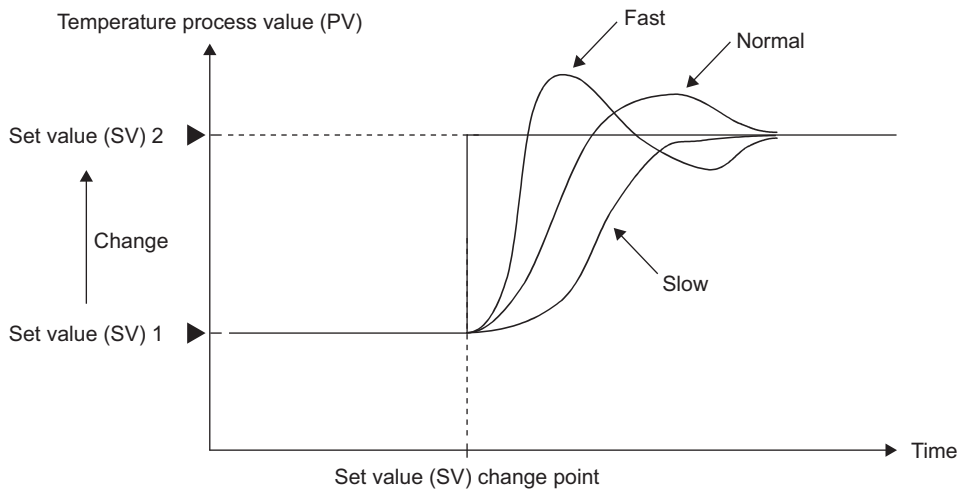
Standard Heating-cooling

In the simple two-degree-of-freedom PID control, select the response speed to the change of the set value (SV) from the following three levels: Slow, Normal, and Fast.
For details on the simple two-degree-of-freedom, refer to the following.

☞ Page 157, Section 8.2.8

(a) Setting range

Set value	Setting contents	Description
0	Slow	Set Slow when reducing an overshoot and undershoot to the change of the set value (SV). However, the settling time is the longest of the three settings.
1	Normal	Normal has features between Slow and Fast.
2	Fast	Set Fast when speeding up the response to the change of the set value (SV). However, an overshoot and undershoot is the largest of the three settings.



(b) Default value

The default values are set to Slow (0) in all channels.

(26)CH□ AUTO/MAN mode shift (Un\G50, Un\G82, Un\G114, Un\G146) Standard Heating-cooling

Select whether to calculate the manipulated value (MV) by PID operation or to set it manually by the user.

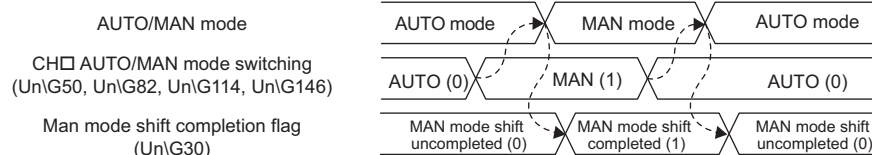
(a) Setting range

Set value	Setting contents	Description
0	AUTO	Activates the AUTO mode. The manipulated value (MV) calculated by PID operation is used to calculate the ON time of the control cycle.
1	MAN	Activates the MAN mode. The manipulated value (MV) written in CH□ MAN output setting (Un\G51, Un\G83, Un\G115, Un\G147) is used to calculate the ON time of the control output cycle.

(b) When AUTO mode is shifted to MAN mode

The following operation is performed.

- The manipulated value (MV) calculated by PID operation is transferred to CH□ MAN output setting (Un\G51, Un\G83, Un\G115, Un\G147). (For preventing a rapid change of the manipulated value (MV))
- When the shift to the MAN mode is completed, bits of the corresponding channel of MAN mode shift completion flag (Un\G30) are set to MAN mode shift completed (1).



-----> Executed by the L60TC4



Set the manipulated value (MV) in MAN mode after confirming completion of the mode shift.

(c) When performing auto tuning

Set to AUTO (0). If MAN (1) is set, the auto tuning is not performed.

(d) Default value

The default values are set to AUTO (0) in all channels.

(27)CH□ MAN output setting (Un\G51, Un\G83, Un\G115, Un\G147) Standard Heating-cooling

This buffer memory area is used for setting the manipulated value (MV) in the MAN mode.

(a) How to shift the mode

Shift the mode by the following buffer memory area.

- CH□ AUTO/MAN mode shift (Un\G50, Un\G82, Un\G114, Un\G146) (☞ Page 376, Appendix 2 (26))

(b) Setting range

The setting range is different between the standard control and the heating-cooling control. (☞ Page 130, Section 8.2.1)

- In standard control: -50 to 1050 (-5.0 to 105.0%)
- In heating-cooling control: -1050 to 1050 (-105.0 to 105.0%)

(c) Enablement of setting contents

Make sure the corresponding bits of MAN mode shift completion flag (Un\G30) has been set to 1 (ON) and write a value in the MAN output setting.

A value that is written when MAN mode shift completion flag is OFF will be replaced with the manipulated value (MV) calculated by PID operation by the system.

(d) Default value

The default values are set to 0 (0.0%) in all channels.

A

(28)CH□ Setting change rate limiter (Un\G52, Un\G84, Un\G116, Un\G148)

Standard Heating-cooling

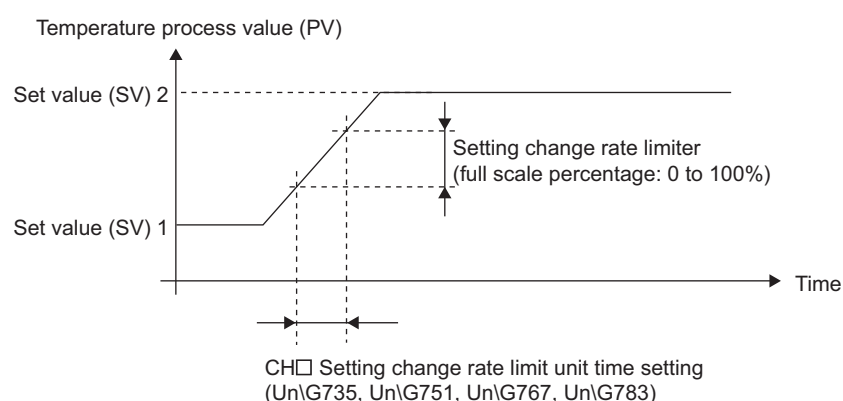
CH□ Setting change rate limiter (temperature rise) (Un\G52, Un\G84, Un\G116,

Un\G148) Standard Heating-cooling

CH□ Setting change rate limiter (temperature drop) (Un\G564, Un\G596,

Un\G628, Un\G660) Standard Heating-cooling

Set the change rate of the set value (SV) per a set time unit when the set value (SV) is changed. This setting can regulate a rapid change of the manipulated value (MV). Set a time unit in CH□ Setting change rate limiter time unit setting (Un\G735, Un\G751, Un\G767, Un\G783). (☞ Page 421, Appendix 2 (91))



(a) Batch/individual setting of temperature rise and temperature drop

Setting change rate limiter for the temperature rise and the temperature drop can be set in a batch or individually. Select it on Switch Setting.

For details on the setting method, refer to the following.

☞ Page 110, Section 7.2

When setting change rate limiter is set individually, Un\G52, Un\G84, Un\G116, Un\G148 is for the temperature rise. The following table lists the buffer memory areas to be referred to.

Batch/Individual	Buffer memory area name	Buffer memory address			
		CH1	CH2	CH3	CH4
Batch	CH□ Setting change rate limiter	Un\G52	Un\G84	Un\G116	Un\G148
Individual	CH□ Setting change rate limiter (temperature rise)	Un\G52	Un\G84	Un\G116	Un\G148
	CH□ Setting change rate limiter (temperature drop)	Un\G564	Un\G596	Un\G628	Un\G660

For details on the function, refer to the following.

☞ Page 159, Section 8.2.10

(b) Setting range

Set 0 or the value within the range of 1 to 1000 (0.1% to 100.0%) toward the full scale of the set input range. When 0 is set, the setting is disabled.

(c) Default value

The default values are set to 0 in all channels.

(29)CH□ AT bias setting (Un\G53, Un\G85, Un\G117, Un\G149) Standard Heating-cooling

The point set as the set value (SV) in the auto tuning can be rearranged by using this buffer memory area.

The auto tuning function determines each PID constant by performing the two-position control toward the set value (SV) and making a temperature process value (PV) hunting.

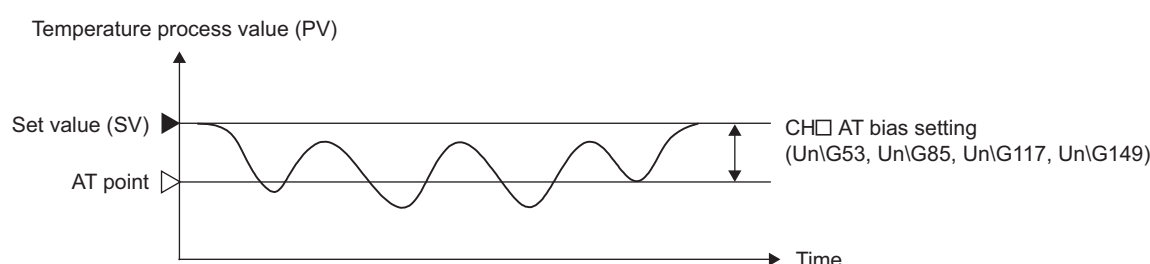
Set CH□ AT bias setting (Un\G53, Un\G85, Un\G117, Un\G149) when an overshoot caused by the hunting is improper.

The auto tuning is performed with having the AT point (the point rearranged by the setting) as its center. When the auto tuning is completed, AT bias is not added and a control is performed toward the set value (SV).

For details on the auto tuning function, refer to the following.

☞ Page 145, Section 8.2.7

Ex. When AT bias is set to minus value (reverse action)

**(a) Setting range**

The setting range is from -(full scale) to full scale. The setting range depends on the input range setting.

☞ Page 355, Appendix 2 (12))

Ex. When the value of the buffer memory is set as follows

- CH□ Input range (Un\G32, Un\G64, Un\G96, Un\G128): 38 (temperature measurement range -200.0 to 400.0°C, resolution: 0.1)

The setting range is -6000 to 6000.

(b) Setting unit

The value to be set differs depending on the stored value in CH□ Decimal point position (Un\G1 to Un\G4).

☞ Page 344, Appendix 2 (2))

- No decimal place (0): Set a value in 1°C (°F or digit) unit.
- One decimal place (1): Set a value in 0.1°C (°F) unit (tenfold value).

(c) Default value

The default values are set to 0 in all channels.

(d) Precautions

For CH□ AT bias setting (Un\G53, Un\G85, Un\G117, Un\G149), set the range where PID operation fluctuates slightly and the control result get no effect.

Depending on the controlled object, accurate PID constants may not be obtained.

(30)CH□ Forward/reverse action setting (Un\G54, Un\G86, Un\G118, Un\G150)

Standard

Select whether to use channels in the forward action or reverse action.

Select the forward action for the cooling control. Select the reverse action for the heating control.

For details on the forward/reverse action selection function, refer to the following.

 Page 207, Section 8.2.18

(a) Setting range

- 0: Forward action
- 1: Reverse action

(b) Default value

The default values are set to Reverse action (1) in all channels.

(31)CH□ Upper limit setting limiter (Un\G55, Un\G87, Un\G119, Un\G151)

Standard Heating-cooling

CH□ Lower limit setting limiter (Un\G56, Un\G88, Un\G120, Un\G152)

Standard Heating-cooling

Upper/lower limit value of the set value (SV) can be set.

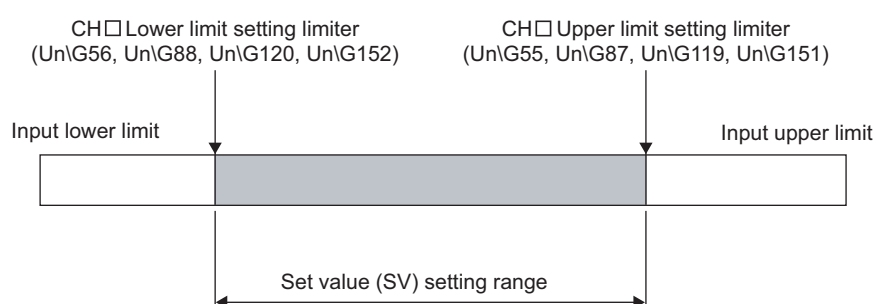
(a) Setting range

The setting range is identical to the temperature measurement range of the set input range. (☞ Page 355, Appendix 2 (12))

The setting should meet the following conditions.

- CH□ Lower limit setting limiter < CH□ Upper limit setting limiter

If the above conditions are not met, a write data error (error code: □□□5_H) occurs.

**(b) Setting unit**

The value to be set differs depending on the stored value in CH□ Decimal point position (Un\G1 to Un\G4).

(☞ Page 344, Appendix 2 (2))

- No decimal place (0): Set a value in 1°C (°F or digit) unit.
- One decimal place (1): Set a value in 0.1°C (°F) unit (tenfold value).

(c) Default value

A default value differs depending on modules to be used.

Buffer memory	Default value	
	L60TCTT4/L60TCTT4BW	L60TCRT4/L60TCRT4BW
CH□ Upper limit setting limiter (Un\G55, Un\G87, Un\G119, Un\G151)	1300	6000
CH□ Lower limit setting limiter (Un\G56, Un\G88, Un\G120, Un\G152)	0	-2000

(32)CH□ Heater disconnection alert setting (Un\G58, Un\G90, Un\G122, Un\G154)

Standard Heating-cooling

Set the set value in heater disconnection detection and off-time current error detection in percentage of the reference heater current value.

For details on the heater disconnection detection function, refer to the following.

☞ Page 221, Section 8.2.25

For details on the output off-time current error detection function, refer to the following.

☞ Page 226, Section 8.2.26

(a) Supported modules

- L60TCTT4BW
- L60TCRT4BW

(b) Setting range

The setting range is 0 to 100 (%).

Ex. To generate Heater disconnection alert with the following conditions

- CT□ Reference heater current value (Un\G280 to Un\G287): 100 (10.0A)
- When CT□ Heater current process value (Un\G256 to Un\G263) is 80 (8.0A) or less, set CH□ Heater disconnection alert setting (Un\G58, Un\G90, Un\G122, Un\G154) to 80 (%).

$$\begin{array}{l} \text{Heater} \\ \text{disconnection} \\ \text{alert setting} \end{array} = 100 - \frac{\text{Reference heater current value} - \text{Heater current process value}}{\text{Reference heater current value}} \times 100 = 100 - \frac{100 - 80}{100} \times 100 = 80(\%)$$

When 0 is set, heater disconnection detection and off-time current error detection are not performed.

(c) Default value

The default values are set to 0 (%) in all channels.

(33)CH□ Loop disconnection detection judgment time (Un\G59, Un\G91, Un\G123,**Un\G155)** **Standard**

Errors such as disconnection of resistors, malfunction of an external controller, and errors of the control system due to troubles such as disconnection of the sensor can be detected by the loop disconnection detection function.

If temperature does not change by 2°C (°F) or more in the Loop disconnection detection judgment time, a loop disconnection is detected.

For details on the loop disconnection detection function, refer to the following.

 Page 208, Section 8.2.19

(a) Setting range

The setting range is 0 to 7200 (s).

Set a value that exceeds the time in which temperature changes by 2°C (°F).

(b) When performing auto tuning

For this setting, the twice value of that of CH□ Integral time (I) setting (Un\G36, Un\G68, Un\G100, Un\G132)

is automatically set. ( Page 366, Appendix 2 (16)) However, when this setting is set to 0 (s) at the start of the auto tuning, Loop disconnection detection judgment time is not stored.

(c) Default value

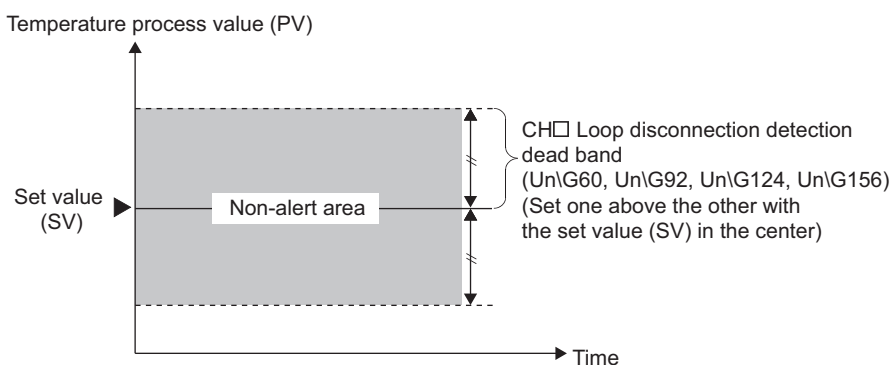
The default values are set to 480 (s) in all channels.

A

(34)CH□ Loop disconnection detection dead band (Un\G60, Un\G92, Un\G124,

Un\G156) **Standard**

To prevent an error alarm of loop disconnection detection, set a non-alert band (temperature band in which the loop disconnection is not detected) where the set value (SV) is at the center.



For details on the loop disconnection detection function, refer to the following.

Page 208, Section 8.2.19

(a) Setting range

The range is 0 to the full scale.

Ex. When the value of the buffer memory is set as follows

- CH□ Input range (Un\G32, Un\G64, Un\G96, Un\G128): 38 (resolution: 0.1)
- CH□ Loop disconnection detection dead band (Un\G60, Un\G92, Un\G124, Un\G156): 50
(Loop disconnection detection dead band set value) × (resolution) = 50 × 0.1 = 5.0°C

Within the range of the set value (SV) ±5.0°C, Loop disconnection is not detected.

(b) Setting unit

The value to be set differs depending on the stored value in CH□ Decimal point position (Un\G1 to Un\G4).

Page 344, Appendix 2 (2))

- No decimal place (0): Set a value in 1°C (°F or digit) unit.
- One decimal place (1): Set a value in 0.1°C (°F) unit (tenfold value).

(c) Default value

The default values are set to 0 in all channels.

(35)CH□ Unused channel setting (Un\G61, Un\G93, Un\G125, Un\G157) **Standard** **Heating-cooling**

Set this buffer memory area when treating channels that do not control temperature or are not connected with temperature sensors as "Unused". Setting them as unused channels stops detection of an alert.

For details on the unused channel setting, refer to the following.

 Page 108, Section 6.6

(a) Setting range

- 0: Use
- 1: Unused

(b) Default value

The default values are set to Use (0) in all channels.

(c) ON of Default setting registration instruction (Yn9) (Page 342, Appendix 1.2 (5))

When Default setting registration instruction (Yn9) is turned on from off, CH□ Unused channel setting (Un\G61, Un\G93, Un\G125, Un\G157) is reset to Use (0).

Channels that do not control temperature or are not connected to temperature sensors needs to be set as unused channels again after settings of other buffer memory areas and non-volatile memories return to the default values. Set CH□ Unused channel setting (Un\G61, Un\G93, Un\G125, Un\G157) to Unused (1) again.

A

(36)CH□ Memory's PID constants read instruction (Un\G62, Un\G94, Un\G126,

Un\G158) **Standard** **Heating-cooling**

PID constants are read from a non-volatile memory and stored in the buffer memory by using this instruction. Setting this buffer memory area to Requested (1) stores the value backed up in the non-volatile memory in the buffer memory.

(a) Buffer memory areas to store set value of non-volatile memory

The following table lists the buffer memory areas whose set value is read.

Buffer memory area name	Buffer memory address				Reference
	CH1	CH2	CH3	CH4	
CH□ Proportional band (P) setting	Un\G35	Un\G67	Un\G99	Un\G131	Page 364, Appendix 2 (15)
CH□ Heating proportional band (Ph) setting	Un\G35	Un\G67	Un\G99	Un\G131	
CH□ Cooling proportional band (Pc) setting	Un\G720	Un\G736	Un\G752	Un\G768	
CH□ Integral time (I) setting	Un\G36	Un\G68	Un\G100	Un\G132	Page 366, Appendix 2 (16)
CH□ Derivative time (D) setting	Un\G37	Un\G69	Un\G101	Un\G133	Page 366, Appendix 2 (17)
CH□ Loop disconnection detection judgment time	Un\G59	Un\G91	Un\G123	Un\G155	Page 383, Appendix 2 (33)

(b) Setting range

- 0: Not requested
- 1: Requested

(c) Default value

The default values are set to Not requested (0) in all channels.

(d) Precautions

When Requested (1) is set, do not perform the following operations. An incorrect value may be stored in the non-volatile memory.

- Change of the set value of the buffer memory read from the non-volatile memory by this instruction (☞ Page 387, Appendix 2 (37) (a))
- Memory back up (☞ Page 242, Section 8.3.5)
- Default setting registration (☞ Page 342, Appendix 1.2 (5))
- Auto tuning (☞ Page 145, Section 8.2.7)

Point

- When the initial setting by a programming tool is already configured, PID constants should be backed up to a non-volatile memory after the auto tuning. Turning on this instruction at the next start-up can omit the auto tuning.
- This instruction is enabled in the setting mode or operation mode. (☞ Page 334, Appendix 1.1 (2))
However, it is disabled when CH□ Auto tuning instruction (Yn4 to Yn7) is ON. (☞ Page 145, Section 8.2.7)

(37)CH□ Automatic backup setting after auto tuning of PID constants (Un\G63, Un\G95, Un\G127, Un\G159) Standard Heating-cooling

The set value to be stored in the buffer memory is automatically backed up to a non-volatile memory by using this function. By reading the set value that is backed up, when the power is turned on from off or the CPU module is released from the reset status, another auto tuning can be omitted.

For details on the auto tuning function, refer to the following.

 Page 145, Section 8.2.7

(a) buffer memory areas whose set value is backed up to a non-volatile memory

The following table lists the buffer memory areas whose setting is backed up.

Buffer memory area name	Buffer memory address				Reference
	CH1	CH2	CH3	CH4	
CH□ Proportional band (P) setting	Un\G35	Un\G67	Un\G99	Un\G131	Page 364, Appendix 2 (15)
CH□ Heating proportional band (Ph) setting	Un\G35	Un\G67	Un\G99	Un\G131	
CH□ Cooling proportional band (Pc) setting	Un\G720	Un\G736	Un\G752	Un\G768	
CH□ Integral time (I) setting	Un\G36	Un\G68	Un\G100	Un\G132	Page 366, Appendix 2 (16)
CH□ Derivative time (D) setting	Un\G37	Un\G69	Un\G101	Un\G133	Page 366, Appendix 2 (17)
CH□ Loop disconnection detection judgment time	Un\G59	Un\G91	Un\G123	Un\G155	Page 383, Appendix 2 (33)

(b) Setting range

- 0: Disable
- 1: Enable

(c) Default value

The default values are set to Disable (0) in all channels.

(d) Precautions

When Enable (1) is set, do not perform the following operations. An incorrect value may be stored in the non-volatile memory.

- Changing the set value of the buffer memory
- Memory back up ( Page 242, Section 8.3.5)
- Default setting registration ( Page 342, Appendix 1.2 (5))
- Change to Disable (0) during the auto tuning

(38) Alert dead band setting (Un\G164) Standard Heating-cooling

This setting is for using the alarm function.

For details on the alert function, refer to the following.

 Page 161, Section 8.2.11

(a) Setting range

Set the value within the range 0 to 100 (0.0% to 10.0%) of the full scale of the set input range. ( Page 355, Appendix 2 (12))

Ex. When the value of the buffer memory is set as follows

- CH□ Input range (Un\G32, Un\G64, Un\G96, Un\G128): 2 (temperature measurement range 0 to 1300°C)
- Alert dead band setting (Un\G164): 5 (0.5%)

$$(\text{Full scale}) \times (\text{Alert dead band}) = (1300^{\circ}\text{C} - 0^{\circ}\text{C}) \times 0.005 = 6.5^{\circ}\text{C}$$

The dead band is the alert set value (SV) $\pm 6.5^{\circ}\text{C}$.

(b) Default value

The default value is set to 5 (0.5%).

(39) Number of alert delay (Un\G165) Standard Heating-cooling

Set the number of sampling for an alert judgment.

By setting number of sampling, when the temperature process value (PV) stays within the alert area until the number of sampling exceeds the number of alert delay, the alert status will be active.

For details on the alert function, refer to the following.

 Page 161, Section 8.2.11

(a) Setting range

The setting range is 0 to 255 (times).

Under 0 (times) condition, if the temperature process value (PV) enters the alert area, the alert status becomes active instantly.

(b) Default value

The default value is set to 0 (times).

(40) Heater disconnection/output off-time current error detection delay count**(Un\G166)** **Standard** **Heating-cooling**

Set the limit value for consecutive heater disconnection detections and output off-time current error detections so that the errors exceeding the limit value triggers an alert judgment.

For details on the heater disconnection detection function, refer to the following.

☞ Page 221, Section 8.2.25

For details on the output off-time current error detection function, refer to the following.

☞ Page 226, Section 8.2.26

(a) Supported modules

- L60TCTT4BW
- L60TCRT4BW

(b) Setting range

The setting range is 3 to 255 (times).

(c) Default value

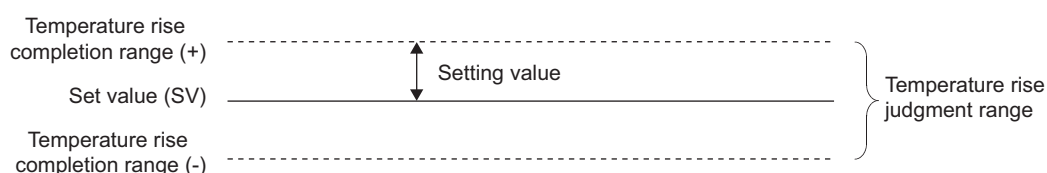
The default value is set to 3 (times).

(41) Temperature rise completion range setting (Un\G167) **Standard** **Heating-cooling**

Set the vertical range of the temperature rise completion range.

When the temperature process value (PV) meets the following conditions, the temperature rise is completed.

- Set value (SV) - Temperature rise completion range $\leq$ Temperature process value (PV) $\leq$ Set value (SV) + Temperature rise completion range



When CH□ Temperature process value (PV) (Un\G9 to Un\G12) enters the temperature rise judgment range, CH□ Temperature rise judgment flag (Un\G17 to Un\G20) is set to Within temperature rise completion range (1). (Set the time from the temperature rise completion to Within temperature rise completion range (1) in Temperature rise completion soak time setting (Un\G168).)

(a) Setting range

- When the temperature unit of the input range is °C: 1 to 10 (°C)
- When the temperature unit of the Input range is °F: 1 to 10 (°F)
- Other than above: 1 to 10 (%) of the full scale

(b) Default value

The default value is set to 1.

(42)Temperature rise completion soak time setting (Un\G168) Standard Heating-cooling

Set the time for CH□ Temperature rise judgment flag (Un\G17 to Un\G20) (☞ Page 350, Appendix 2 (6)) to be set to Within temperature rise completion range (1) after the completion of temperature rise.

(a) Setting range

The setting range is 0 to 3600 (min).

(b) Default value

The default value is set to 0 (min).

(43)PID continuation flag (Un\G169) Standard Heating-cooling

Set the operation status at the time when the mode has shifted from the operation mode to the setting mode (Setting/operation mode instruction (Yn1) ON → OFF).

For details on the relationship between this flag and the control status, refer to the following.

- PID control: ☞ Page 138, Section 8.2.3 (6)
- Temperature judgment: ☞ Page 346, Appendix 2 (3)
- Alert judgment: ☞ Page 170, Section 8.2.11 (5)

(a) Setting range

- 0: Stop
- 1: Continue

(b) Default value

The default value is set to Stop (0).

(44)Heater disconnection compensation function selection (Un\G170) Standard Heating-cooling

Set whether to use the heater disconnection compensation function or not.

For details on the heater disconnection compensation function, refer to the following.

☞ Page 223, Section 8.2.25 (3)

(a) Supported modules

- L60TCTT4BW
- L60TCRT4BW

(b) Setting range

- 0: Not use the heater disconnection compensation function
- 1: Use the heater disconnection compensation function

(c) Default value

The default value is set to Not use the heater disconnection compensation function (0).

(45) Transistor output monitor ON delay time setting (Un\G175) **Standard** **Heating-cooling**

Set the delay time of the ON delay output flag.

Set this buffer memory area to perform the heater disconnection detection with other input modules provided on the system.

For ON delay output flag, refer to the following.

 Page 351, Appendix 2 (7)

For details on the ON delay output function, refer to the following.

 Page 178, Section 8.2.14

(a) Setting range

The setting range is 0 or 1 to 50 (10 to 500ms).

When 0 is set, ON delay output flag is not set to 1 (ON).

(b) Default value

The default value is set to 0.

(46) CT monitor method switching (Un\G176) **Standard** **Heating-cooling**

Set the method for performing the heater current measurement.

(a) Supported modules

- L60TCTT4BW
- L60TCRT4BW

(b) Setting range

- 0: ON/OFF current
- 1: ON current

When ON/OFF current (0) is set, the present current value of the current sensor (CT) is measured.

Selecting ON current (1) fixes the current value of the heater being OFF as the current value of the heater previously being ON.

(c) Default value

The default value is set to ON/OFF current (0).

(47)CH□ Manipulated value (MV) for output with another analog module (Un\G177 to Un\G180) Standard

CH□ Manipulated value of heating (MVh) for output with another analog module (Un\G177 to Un\G180) Heating-cooling

CH□ Manipulated value of cooling (MVc) for output with another analog module (Un\G708 to Un\G711) Heating-cooling

The values stored in the following buffer memory areas are converted for other analog modules such as a D/A converter module and stored in these buffer memory areas.

Buffer memory area name	Buffer memory address				Reference
	CH1	CH2	CH3	CH4	
CH□ Manipulated value (MV)	Un\G13	Un\G14	Un\G15	Un\G16	Page 349, Appendix 2 (5)
CH□ Manipulated value for heating (MVh)	Un\G13	Un\G14	Un\G15	Un\G16	
CH□ Manipulated value for cooling (MVc)	Un\G704	Un\G705	Un\G706	Un\G707	

Un\G177 to Un\G180 are used for heating in the heating-cooling control.

The store range differs depending on the resolution set in the following buffer memory area. (0 to 4000/0 to 12000/0 to 16000/0 to 20000)

- Resolution of the manipulated value for output with another analog module (Un\G181) ( Page 393, Appendix 2 (48))

For details, refer to the following.

 Page 177, Section 8.2.13 (2)

Point

When the device which performs heating or cooling can receive only the analog input, use other analog modules (such as D/A converter module) to convert the digital output to the analog input.

(48) Resolution of the manipulated value for output with another analog module**(Un\G181)** **Standard** **Heating-cooling**

Set the resolution of the following buffer memory areas. (☞ Page 349, Appendix 2 (5))

- CH□ Manipulated value (MV) (Un\G13 to Un\G16)
- CH□ Manipulated value for heating (MVh) (Un\G13 to Un\G16)
- CH□ Manipulated value for cooling (MVc) (Un\G704 to Un\G707)

For details, refer to the following.

☞ Page 177, Section 8.2.13 (2)

(a) Setting range

- 0: 0 to 4000
- 1: 0 to 12000
- 2: 0 to 16000
- 3: 0 to 20000

The manipulated value (MV) reflecting the resolution is stored in the following buffer memory areas.

☞ Page 392, Appendix 2 (47))

- CH□ Manipulated value (MV) for output with another analog module (Un\G177 to Un\G180)
- CH□ Manipulated value of heating (MVh) for output with another analog module (Un\G177 to Un\G180)
- CH□ Manipulated value of cooling (MVc) for output with another analog module (Un\G708 to Un\G711)

(b) Enablement of setting contents

Enable the setting contents by turning Setting change instruction (YnB) OFF → ON → OFF during the setting mode (Setting/operation mode status (Xn1): OFF).

(c) Default value

The default value is set to 0 to 4000 (0).

(49) Cold junction temperature compensation selection (Un\G182) **Common**

Select whether to perform the cold junction temperature compensation using a standard terminal block or not to perform the cold junction temperature compensation.

(a) Supported modules

- L60TCTT4
- L60TCTT4BW

(b) Setting range

- 0: Use Standard Terminal Block
- 1: This setting cannot be used.
- 2: Not use cold junction temperature compensation

(c) Default value

The default value is set to Use Standard Terminal Block (0).

(50)Control switching monitor (Un\G183) Common

The setting contents of the mode selection set on Switch Setting are stored in this buffer memory area.

The mode in operation can be confirmed.

The following table lists the stored values and the contents.

Stored value		Mode
		Control mode
0 _H	Temperature control mode	Standard control
1 _H		Heating-cooling control (normal mode)
2 _H		Heating-cooling control (expanded mode)
3 _H		Mix control (normal mode)
4 _H		Mix control (expanded mode)
100 _H	Temperature input mode	

Select the mode on Switch Setting.

For details on the setting method, refer to the following.

☞ Page 110, Section 7.2

For details on the modes, refer to the following.

☞ Page 120, Section 8.1, Page 130, Section 8.2.1

(51)CH□ Auto tuning mode selection (Un\G184 to Un\G187) Standard Heating-cooling

Select the auto tuning mode from the following two modes according to the controlled object to be used.

Auto tuning mode	Description
Standard mode	The standard mode is appropriate for most controlled objects. This mode is especially suitable for controlled objects that have an extremely slow response speed or can be affected by noise or disturbance. However, PID constants of slow response (low gain) may be calculated from controlled objects whose ON time or OFF time in the auto tuning is only around 10s. In this case, PID constants of fast response can be calculated by selecting the high response mode and performing the auto tuning.
High response mode	This mode is suitable for controlled objects whose ON time or OFF time in the auto tuning is only around 10s. PID constants of fast response (high gain) can be calculated. However, the temperature process value (PV) may oscillates near the set value (SV) because of the too high gain of the PID constants calculated. In this case, select the normal mode and perform the auto tuning.

For details on the auto tuning function, refer to the following.

☞ Page 145, Section 8.2.7

(a) Setting range

- 0: Standard mode
- 1: High response mode

(b) Default value

The default values are set to Standard mode (0) in all channels.

(52)CH□ Alert 1 mode setting (Un\G192, Un\G208, Un\G224, Un\G240) **Standard** **Heating-cooling**

CH□ Alert 2 mode setting (Un\G193, Un\G209, Un\G225 Un\G241) **Standard** **Heating-cooling**

CH□ Alert 3 mode setting (Un\G194, Un\G210, Un\G226, Un\G242) **Standard** **Heating-cooling**

CH□ Alert 4 mode setting (Un\G195, Un\G211, Un\G227, Un\G243) **Standard** **Heating-cooling**

Set the alert mode of alert 1 to 4.

For details on the alert function, refer to the following.

 Page 161, Section 8.2.11

(a) Alert mode and alert set value

Any alert set value can be set in each alert mode of alert 1 to 4 selected in this setting. Set the alert set value 1 to 4 in the following buffer memory areas. Alert set values 1 to 4 respectively correspond to alert modes of alert 1 to 4.

Buffer memory area name	Buffer memory address				Reference
	CH1	CH2	CH3	CH4	
CH□ Alert set value 1	Un\G38	Un\G70	Un\G102	Un\G134	Page 367, Appendix 2 (18)
CH□ Alert set value 2	Un\G39	Un\G71	Un\G103	Un\G135	
CH□ Alert set value 3	Un\G40	Un\G72	Un\G104	Un\G136	
CH□ Alert set value 4	Un\G41	Un\G73	Un\G105	Un\G137	

(b) Setting range

The following table lists set values and setting ranges which are available for alert set values set in each alert mode.

Set value	Alert mode	Setting range of alert set value
0	— (no alert)	—
1	Upper limit input alert	Within the temperature measurement range of the set input range ( Page 355, Appendix 2 (12))
2	Lower limit input alert	
3	Upper limit deviation alert	(-(full scale)) to full scale
4	Lower limit deviation alert	
5	Upper lower limit deviation alert	0 to full scale
6	Within-range alert	
7	Upper limit input alert with standby	Within the temperature measurement range of the set input range ( Page 355, Appendix 2 (12))
8	Lower limit input alert with standby	
9	Upper limit deviation alert with standby	(-(full scale)) to full scale
10	Lower limit deviation alert with standby	
11	Upper lower limit deviation alert with standby	0 to full scale
12	Upper limit deviation alert with standby (second time)	
13	Lower limit deviation alert with standby (second time)	(-(full scale)) to full scale
14	Upper lower limit deviation alert with standby (second time)	
15	Upper limit deviation alert (using the set value (SV))	(-(full scale)) to full scale
16	Lower limit deviation alert (using the set value (SV))	
17	Upper lower limit deviation alert (using the set value (SV))	0 to full scale
18	Within-range alert (using the set value (SV))	

Set value	Alert mode	Setting range of alert set value
19	Upper limit deviation alert with standby (using the set value (SV))	(-(full scale)) to full scale
20	Lower limit deviation alert with standby (using the set value (SV))	
21	Upper lower limit deviation alert with standby (using the set value (SV))	0 to full scale
22	Upper limit deviation alert with standby (second time) (using the set value (SV))	(-(full scale)) to full scale
23	Lower limit deviation alert with standby (second time) (using the set value (SV))	
24	Upper lower limit deviation alert with standby (second time) (using the set value (SV))	0 to full scale

(c) Enablement of setting contents

Enable the setting contents by turning Setting change instruction (YnB) OFF → ON → OFF during the setting mode (Setting/operation mode status (Xn1): OFF).

When the set value is out of the range, a write data error (error code: □□□4_H) occurs, and the L60TC4 operates with the previous set value. Turning Setting change instruction (YnB) OFF → ON → OFF after the error occurrence and setting a value within the range operate the L60TC4 with the new set value.

(d) Default value

The default values are set to 0 in all channels.

(53)CH□ Process alarm alert output enable/disable setting (Un\G196, Un\G212, Un\G228, Un\G244)

Temperature Input

Set whether to enable or disable alert output of process alarm. For details on the process alarm, refer to the following.

 Page 124, Section 8.1.3 (1)

(a) Setting range

- 0: Enable
- 1: Disable

(b) Enablement of setting contents

Enable the setting contents by turning Setting change instruction (YnB) OFF → ON → OFF during the setting mode (Setting/operation mode status (Xn1): OFF).

(c) Default value

The default values are set to Disable (1) in all channels.

- (54)CH□ Process alarm lower lower limit value (Un\G197, Un\G213, Un\G229, Un\G245) 
- CH□ Process alarm lower upper limit value (Un\G198, Un\G214, Un\G230, Un\G246) 
- CH□ Process alarm upper lower limit value (Un\G199, Un\G215, Un\G231, Un\G247) 
- CH□ Process alarm upper upper limit value (Un\G200, Un\G216, Un\G232, Un\G248) 

Set the lower lower limit value, lower upper limit value, upper lower value, and upper upper limit of process alarm.

(a) Setting range

The setting range should meet the both of the following. If the setting value does not fall within the specified range, out of range error (error code: □□□8_H) occurs.

- Within the temperature measurement range of set input range ( Page 355, Appendix 2 (12))
- Process alarm lower lower limit value ≤ Process alarm lower upper limit value ≤ Process alarm upper lower limit value ≤ Process alarm upper upper limit value

(b) Setting unit

The value to be set differs depending on the stored value in CH□ Decimal point position (Un\G1 to Un\G4).

( Page 344, Appendix 2 (2))

- No decimal place (0): Set a value in 1°C (°F or digit) unit.
- One decimal place (1): Set a value in 0.1°C (°F) unit (tenfold value).

(c) Enablement of setting contents

Enable the setting contents by turning Setting change instruction (YnB) OFF → ON → OFF during the setting mode (Setting/operation mode status (Xn1): OFF).

(d) Default value

Item	Default value	
	L60TCTT4/L60TCTT4BW	L60TCRT4/L60TCRT4BW
CH□ Process alarm lower lower limit value	0	-2000
CH□ Process alarm lower upper limit value	0	-2000
CH□ Process alarm upper lower limit value	1300	6000
CH□ Process alarm upper upper limit value	1300	6000

(55)CH□ Rate alarm alert output enable/disable setting (Un\G201, Un\G217,

Un\G233, Un\G249) 

Set whether to enable or disable alert output of rate alarm. For details on the rate alarm, refer to the following.

 Page 126, Section 8.1.3 (2)

(a) Setting range

- 0: Enable
- 1: Disable

(b) Enablement of setting contents

Enable the setting contents by turning Setting change instruction (YnB) OFF → ON → OFF during the setting mode (Setting/operation mode status (Xn1): OFF).

(c) Default value

The default values are set to Enable (1) in all channels.

(56)CH□ Rate alarm alert detection cycle (Un\G202, Un\G218, Un\G234,

Un\G250) 

Set the check cycle of the temperature process value (PV) for the rate alarm. Set the frequency of checks in the unit of sampling cycles.

The check cycle can be calculated from the following formula.

- Rate alarm alert detection cycle = Set value of Rate alarm alert detection cycle × Sampling cycle

(a) Setting range

The setting range is 1 to 6000 (times).

(b) Enablement of setting contents

Enable the setting contents by turning Setting change instruction (YnB) OFF → ON → OFF during the setting mode (Setting/operation mode status (Xn1): OFF).

(c) Default value

The default values in all channels are 1 (checks per one sampling cycle).

(57)CH□ Rate alarm upper limit value (Un\G203, Un\G219, Un\G235, Un\G251)Temperature
Input**CH□ Rate alarm lower limit value (Un\G204, Un\G220, Un\G236, Un\G252)**Temperature
Input

Set the rate alarm upper limit value and lower limit value.

(a) Setting range

The setting is -32768 to 32767.

(b) Setting unit

The value to be set differs depending on the stored value in CH□ Decimal point position (Un\G1 to Un\G4).

( Page 344, Appendix 2 (2))

- No decimal place (0): Set a value in 1°C (°F or digit) unit.
- One decimal place (1): Set a value in 0.1°C (°F) unit (tenfold value).

(c) Enablement of setting contents

Enable the setting contents by turning Setting change instruction (YnB) OFF → ON → OFF during the setting mode (Setting/operation mode status (Xn1): OFF).

(d) Default value

The default values are set to 0 in all channels.

(58)CT□ Heater current process value (Un\G256 to Un\G263)

Standard

Heating-cooling

The heater current value which L60TCTT4BW or L60TCRT4BW detects is stored in this buffer memory area.

Values to be stored vary depending on the setting of CT□ CT selection (Un\G272 to Un\G279). ( Page 401, Appendix 2 (60)).

Setting of CT□ CT selection (Un\G272 to Un\G279)	Store range
When CTL-12-S36-8 is used (0.0 to 100.0A) (0)	0 to 1050 (0.0 to 105.0A)
When CTL-6-P(-H) is used (0.00 to 20.00A) (1)	0 to 2100 (0.00 to 21.00A)
When CT ratio setting is used (0.0 to 100.0A) (2)	0 to 1050 (0.0 to 105.0A)

(a) Supported module

- L60TCTT4BW
- L60TCRT4BW

Point

To perform the measurement of the heater current, the following buffer memory areas need to be set.

- CT□ CT input channel assignment setting (Un\G264 to Un\G271) ( Page 400, Appendix 2 (59))
- CT□ Reference heater current value (Un\G280 to Un\G287) ( Page 402, Appendix 2 (61))

If the both are set to 0, the heater current cannot be measured. If either of them is not set, the heater current cannot be measured precisely.

(59)CT□ CT input channel assignment setting (Un\G264 to Un\G271) Standard Heating-cooling

Set the assignment of each current sensor (CT) input to the channels.

(a) Supported modules

- L60TCTT4BW
- L60TCRT4BW

(b) Correspondence between CT input terminal and buffer memory address

CT input terminal	Buffer memory address
CT1	Un\G264
CT2	Un\G265
CT3	Un\G266
CT4	Un\G267
CT5	Un\G268
CT6	Un\G269
CT7	Un\G270
CT8	Un\G271

(c) Setting range

- 0: Unused
- 1: CH1
- 2: CH2
- 3: CH3
- 4: CH4

(d) Default value

The default values are set to Unused (0) for all terminals.

Point

- If a three-phase heater is used, the same channel should be assigned to two current sensor (CT) inputs.
For setting examples, refer to the following.

 Page 107, Section 6.5

- In the heating-cooling control, CH3 and CH4 cannot be assigned to this setting.
In the mix control, CH2 cannot be assigned to this setting.

(60)CT□ CT selection (Un\G272 to Un\G279) Standard Heating-cooling

Select the current sensor to be connected to each current sensor (CT) input.

(a) Supported modules

- L60TCTT4BW
- L60TCRT4BW

(b) Setting range

- 0: When CTL-12-S36-8 is used (0.0 to 100.0A)
- 1: When CTL-6-P(-H) is used (0.00 to 20.00A)
- 2: When CT ratio setting is used (0.0A to 100.0A)

(c) Current sensor (CT) to be used and buffer memory setting

When using a current sensor (CT) other than CTL-12-S36-8 and CTL-6-P(-H), set the number of second-winding (turns) of the current sensor (CT) to be connected in CT□ CT ratio setting (Un\G288 to Un\G295).
Set the buffer memory area as follows according to the specification of the current sensor (CT) to be used.

Current sensor (CT) to be used		CT□ CT Selection (Un\G272 to Un\G279)	CT□ CT ratio setting (Un\G288 to Un\G295) (☞ Page 402, Appendix 2 (62))	Note
Products of U.R.D.Co., LTD.	CTL-12-S36-8	When CTL-12-S36-8 is used (0.0A to 100.0A) (0)	Setting not necessary	The product is discontinued, though it can be used.
	CTL-6-P	When CTL-6-P(-H) is used (0.00A to 20.00A) (1)	Setting not necessary	
	CTL-6-P-H	When CTL-6-P(-H) is used (0.00A to 20.00A) (1)	Setting not necessary	—
	CTL-12-S36-10	When CT ratio setting is used (0.0A to 100.0A) (2)	Set 1000, which is the number of second-winding (turns).	—
	CTL-12-S56-10	When CT ratio setting is used (0.0A to 100.0A) (2)	Set 1000, which is the number of second-winding (turns).	—
Other current sensors (CT)		When CT ratio setting is used (0.0A to 100.0A) (2)	Set the number of second-winding (turns) depending on the current sensor (CT) specification.	Current sensors (CT) whose number of second-winding (turns) is 600 to 9999 can be used.

For the URL of U.R.D.Co., LTD., refer to the following.

☞ Page 84, Section 5.2 (4)

(d) Enablement of setting contents

Enable the setting contents by turning Setting change instruction (YnB) OFF → ON → OFF during the setting mode (Setting/operation mode status (Xn1): OFF).

(e) Occurrence of write data error

In the following case, a write data error (error code: □□□4_H) occurs as when the setting is out of the setting value. Error occurrence flag (Xn2) turns on and the error code is stored in Error code (Un\G0).

- When the set value of CT□ CT ratio setting (Un\G288 to Un\G295) is out of the setting when Setting change instruction (YnB) is turned OFF → ON → OFF

(f) Default value

The default values are set to When CTL-12-S36-8 is used (0.0 to 100.0A) (0) for all terminals.

Point

When CT ratio setting is used (0.0 to 100.0A) (2) is selected, the setting of CT□ CT ratio setting (Un\G288 to Un\G295) is enabled. In advance, set CT□ CT ratio setting (Un\G288 to Un\G295) corresponding to the sensor to be connected. After that, select When CT ratio setting is used (0.0 to 100.0A) (2).

(61)CT□ Reference heater current value (Un\G280 to Un\G287) Standard Heating-cooling

Set the reference value of CT□ Heater current process value (Un\G256 to Un\G263) of when the heater is turned on (☞ Page 399, Appendix 2 (58)).

(a) Supported modules

- L60TCTT4BW
- L60TCRT4BW

(b) Setting range

The setting range is within the heater current range of the current sensor selected in CT□ CT selection (Un\G272 to Un\G279). (☞ Page 401, Appendix 2 (60))

Setting of CT□ CT selection (Un\G272 to Un\G279)	Setting range
• When CTL-12-S36-8 is used (0.0 to 100.0A) (0) • When CT ratio setting is used (0.0 to 100.0A) (2)	0 to 1000 (0.0 to 100.0A)
When CTL-6-P(-H) is used (0.00 to 20.00A) (1)	0 to 2000 (0.00 to 20.00A)

(c) Default value

The default values are set to 0 (0.0A) for all terminals.

(62)CT□ CT ratio setting (Un\G288 to Un\G295) Standard Heating-cooling

Set the number of second-winding (turning number) of the current sensor (CT) to be connected.

This buffer memory area is available only when CT□ CT selection (Un\G272 to Un\G279) is set to When CT ratio setting is used (0.0 to 100.0A) (2). (☞ Page 401, Appendix 2 (60))

(a) Supported modules

- L60TCTT4BW
- L60TCRT4BW

(b) Setting range

The setting range is 600 to 9999.

(c) Default value

The default values are set to 800 for all terminals.

(63)CH□ Sensor two-point correction offset value (measured value) (Un\G544,**Un\G576, Un\G608, Un\G640) Common**

The measured value of temperature corresponding to the offset value of the sensor two-point correction is stored in this buffer memory area.

The value to be stored differs depending on the stored value in CH□ Decimal point position (Un\G1 to Un\G4).

( Page 344, Appendix 2 (2))

- No decimal place (0): stored as it is.
- One decimal place (1): stored after a multiplication by 10.

For details on the sensor two-point correction function, refer to the following.

( Page 234, Section 8.3.3 (2))

(a) Enablement of the stored value

Turn Setting change instruction (YnB) OFF → ON → OFF during the setting mode (Setting/operation mode status (Xn1): OFF) to enable stored contents.

(64)CH□ Sensor two-point correction offset value (corrected value) (Un\G545,**Un\G577, Un\G609, Un\G641) Common**

Set the temperature of the offset value of the sensor two-point correction.

For details on the sensor two-point correction function, refer to the following.

( Page 234, Section 8.3.3 (2))

(a) Setting range

The setting range is identical to the temperature measurement range of the set input range. ( Page 355, Appendix 2 (12))

(b) Setting unit

The value to be set differs depending on the stored value in CH□ Decimal point position (Un\G1 to Un\G4).

( Page 344, Appendix 2 (2))

- No decimal place (0): Set a value in 1°C (°F or digit) unit.
- One decimal place (1): Set a value in 0.1°C (°F) unit (tenfold value).

(c) Enablement of setting contents

Enable the setting contents by turning Setting change instruction (YnB) OFF → ON → OFF during the setting mode (Setting/operation mode status (Xn1): OFF).

(d) Default value

The default values are set to 0 in all channels.

(65)CH□ Sensor two-point correction gain value (measured value) (Un\G546,

Un\G578, Un\G610, Un\G642) Common

The measured value of temperature corresponding to the gain value of the sensor two-point correction is stored in this buffer memory area.

The value to be stored differs depending on the stored value in CH□ Decimal point position (Un\G1 to Un\G4).

( Page 344, Appendix 2 (2))

- No decimal place (0): stored as it is.
- One decimal place (1): stored after a multiplication by 10.

For details on the sensor two-point correction function, refer to the following.

( Page 234, Section 8.3.3 (2))

(a) Enablement of the stored value

Turn Setting change instruction (YnB) OFF → ON → OFF during the setting mode (Setting/operation mode status (Xn1): OFF) to enable stored contents.

(66)CH□ Sensor two-point correction gain value (corrected value) (Un\G547,

Un\G579, Un\G611, Un\G643) Common

Set temperature of gain value of the sensor two-point correction.

For details on the sensor two-point correction function, refer to the following.

( Page 234, Section 8.3.3 (2))

(a) Setting range

The setting range is identical to the temperature measurement range of the set input range. ( Page 355, Appendix 2 (12))

(b) Setting unit

The value to be set differs depending on the stored value in CH□ Decimal point position (Un\G1 to Un\G4).

( Page 344, Appendix 2 (2))

- No decimal place (0): Set a value in 1°C (°F or digit) unit.
- One decimal place (1): Set a value in 0.1°C (°F) unit (tenfold value).

(c) Enablement of setting contents

Enable the setting contents by turning Setting change instruction (YnB) OFF → ON → OFF during the setting mode (Setting/operation mode status (Xn1): OFF).

(d) Default value

The default values are set to 0 in all channels.

(67)CH□ Sensor two-point correction offset latch request (Un\G548, Un\G580, Un\G612, Un\G644) Common

This request is for storing temperature process value (PV) as sensor two-point correction offset value to the following buffer memory area.

- CH□ Sensor two-point correction offset value (measured value) (Un\G544, Un\G576, Un\G608, Un\G640)

(☞ Page 403, Appendix 2 (63))

For details on the sensor two-point correction function, refer to the following.

(☞ Page 234, Section 8.3.3 (2))

(a) Setting range

- 0: No request
- 1: Latch request

(b) Default value

The default values are set to No request (0) in all channels.

(68)CH□ Sensor two-point correction offset latch completion (Un\G549, Un\G581, Un\G613, Un\G645) Common

When sensor two-point correction offset value is stored, 1 is stored in this buffer memory area, which is Latch completed (1).

When CH□ Sensor two-point correction offset latch request (Un\G548, Un\G580, Un\G612, Un\G644) is set to No request (0), 0 is stored in this buffer memory area, which is No request (0). (☞ Page 405, Appendix 2 (67))

For details on the sensor two-point correction function, refer to the following.

(☞ Page 234, Section 8.3.3 (2))

(69)CH□ Sensor two-point correction gain latch request (Un\G550, Un\G582,

Un\G614, Un\G646) Common

This is a request for storing temperature process value (PV) as sensor two-point correction gain value to the following buffer memory area.

- CH□ Sensor two-point correction gain value (measured value) (Un\G546, Un\G578, Un\G610, Un\G642)

( Page 404, Appendix 2 (65))

For details on the sensor two-point correction function, refer to the following.

( Page 234, Section 8.3.3 (2))

(a) Setting range

- 0: No request]
- 1: Latch request

(b) Default value

The default values are set to No request (0) in all channels.

(70)CH□ Sensor two-point correction gain latch completion (Un\G551, Un\G583,

Un\G615, Un\G647) Common

When sensor two-point correction gain value is stored, 1 is stored in this buffer memory area, which is Latch completed (1).

When CH□ Sensor two-point correction gain latch request (Un\G550, Un\G582, Un\G614, Un\G646) is set to No request (0), 0 is stored in this buffer memory area, which is No request (0). ( Page 406, Appendix 2 (69))

For details on the sensor two-point correction function, refer to the following.

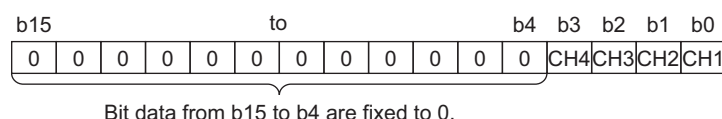
( Page 234, Section 8.3.3 (2))

(71)During AT loop disconnection detection function enable/disable setting**(Un\G571)** **Standard**

Set whether to enable or disable the loop disconnection detection function during auto tuning (AT).

For details on the during AT loop disconnection detection function, refer to the following.

 Page 210, Section 8.2.20

**(a) Setting range**

- 0: Disable
- 1: Enable

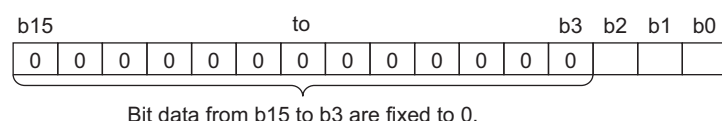
(b) Default value

The default values are set to Disable (0) in all channels.

(72)CH□ AT simultaneous temperature rise parameter calculation flag (Un\G573,**Un\G605, Un\G637, Un\G669)** **Standard**

The status when simultaneous temperature rise AT (auto tuning) calculates simultaneous temperature rise parameter is stored in this buffer memory area.

- 0: OFF
- 1: ON



Bit	Flag name	Description
b0	AT simultaneous temperature rise parameter calculation completion	This flag is set to 1 (ON) when the simultaneous temperature rise parameter ^{*1} is calculated by simultaneous temperature rise AT.
b1	AT simultaneous temperature rise parameter calculation error status	This flag is set to 1 (ON) when the simultaneous temperature rise parameter ^{*1} cannot be calculated by simultaneous temperature rise AT.
b2	Simultaneous temperature rise AT disable status	This flag is set to 1 (ON) when the simultaneous temperature rise AT cannot be performed.
b3 to b15	— (fixed to 0)	— (Unused)

^{*1} Indicates the values of CH□ Simultaneous temperature rise gradient data (Un\G731, Un\G747, Un\G763, Un\G779) and CH□ Simultaneous temperature rise dead time (Un\G732, Un\G748, Un\G764, Un\G780).

Point

This area is enabled only for the following channels.

- CH1 to CH4 when the standard control is used
- CH3 and CH4 when mix control (normal mode) or mix control (expanded mode) is used

For details on the simultaneous temperature rise function, refer to the following.

 Page 194, Section 8.2.17

(73)CH□ Self-tuning setting (Un\G574, Un\G606, Un\G638, Un\G670) Standard

Perform operation setting of self-tuning with this buffer memory area.

For details on the self-tuning function, refer to the following.

 Page 179, Section 8.2.15

(a) Setting range

- 0: Do not run the ST
- 1: Starting ST (PID constants only)
- 2: Starting ST (Simultaneous temperature rise parameter only^{*1})
- 3: Starting ST (PID constants and simultaneous temperature rise parameter^{*1})
- 4: Starting ST plus vibration ST (PID constants only)

^{*1} Indicates the values of CH□ Simultaneous temperature rise gradient data (Un\G731, Un\G747, Un\G763, Un\G779) and CH□ Simultaneous temperature rise dead time (Un\G732, Un\G748, Un\G764, Un\G780) to be used in the simultaneous temperature rise function.

For details on the simultaneous temperature rise function, refer to the following.

 Page 194, Section 8.2.17

(b) Default value

The default values are set to Do not run the ST (0) in all channels.

Point

This area is enabled only for the following channels.

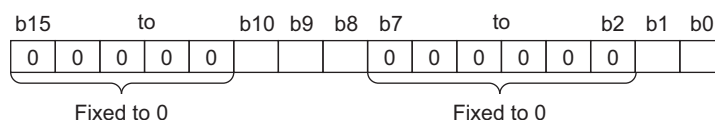
- CH1 to CH4 when the standard control is used
 - CH3 and CH4 when mix control (normal mode) or mix control (expanded mode) is used
-

(74)CH□ Self-tuning flag (Un\G575, Un\G607, Un\G639, Un\G671) **Standard**

The execution status of self-tuning can be monitored in this buffer memory area.

For details on the self-tuning function, refer to the following.

 Page 179, Section 8.2.15



The following contents are stored in each bit.

- 0: OFF
- 1: ON

Bit	Flag name	Condition on which value turns to 1 (ON)	Condition on which value turns to 0 (OFF)
b0	PID auto-correction status	This flag is set to 1 (ON) when PID constants are corrected by the self-tuning.	This flag is set to 0 (OFF) when either of the following operation is performed. • When the operation mode shifts to the setting mode by turning off from on Setting/operation mode instruction (Yn1) • When CH□ Unused channel setting (Un\G61, Un\G93, Un\G125, Un\G157) is set to Unused (1) • When CH□ PID control forced stop instruction (YnC to YnF) is turned on from off • When CH□ Self-tuning setting (Un\G574, Un\G606, Un\G638, Un\G670) is set to Do not run the ST (0)
b1	Simultaneous temperature rise parameter correction status	This flag is set to 1 (ON) when simultaneous temperature rise parameter*1 is corrected by self-tuning.	This flag is also set to 0 (OFF) in the following cases. • When the self-tuning starts by changing the set value (SV) • When the vibration ST starts by vibration caused by disturbance of the process value (PV)
b2 to b7	— (fixed to 0)	— (Unused)	—
b8	Self-tuning disable status	This flag is set to 1 (ON) when the self-tuning cannot be performed.	This flag is set to 0 (OFF) when either of the following operation is performed. • When the operation mode shifts to the setting mode by turning off from on Setting/operation mode instruction (Yn1) • When CH□ Unused channel setting (Un\G61, Un\G93, Un\G125, Un\G157) is set to Unused (1) • When CH□ PID control forced stop instruction (YnC to YnF) is turned on from off • When CH□ Self-tuning setting (Un\G574, Un\G606, Un\G638, Un\G670) is set to Do not run the ST (0) This flag is also set to 0 (OFF) when all disable conditions are released. For disable conditions, refer to  Page 185, Section 8.2.15 (6).

Bit	Flag name	Condition on which value turns to 1 (ON)	Condition on which value turns to 0 (OFF)
b9	Simultaneous temperature rise parameter error status	This flag is set to 1 (ON) when simultaneous temperature rise parameter ^{*1} cannot be calculated by self-tuning.	
b10	Self-tuning error	This flag is set to 1 (ON) when either of the following operation is performed during the self-tuning.^{*2} • Set value (SV) setting change (only during starting) • PID constants change • Setting change rate limiter change • Output limiter change • Output variation limiter change • Control output cycle change • Sensor correction change • Primary delay digital filter change • AUTO to MAN mode shift • Forward/reverse action shift This flag is also set to 1 (ON) in the following cases • When 6000 seconds (1 hour 40 minutes) or more have elapsed from the start of self-tuning • When the change rate of the process value (PV) during self-tuning is less than 1.125°C/minute • When the temperature process value (PV) is out of the temperature measurement range • When required measurement data is not obtained because the manipulated value (MV) does not reach the upper limit output limiter value or the lower limit output limiter value until the measurement is completed • When the temperature process value (PV) decreases by 1°C (°F) or more though it should increase after the self-tuning is started as the starting ST • When temperature process value (PV) increases by 1°C (°F) or more though it should decrease after the self-tuning is started as the starting ST	This flag is set to 0 (OFF) when either of the following operation is performed. • When the operation mode shifts to the setting mode by turning off from on Setting/operation mode instruction (Yn1) • When CH□ Unused channel setting (Un\G61, Un\G93, Un\G125, Un\G157) is set to Unused (1) • When CH□ PID control forced stop instruction (YnC to YnF) is turned on from off • When CH□ Self-tuning setting (Un\G574, Un\G606, Un\G638, Un\G670) is set to Do not run the ST (0) This flag is also set to 0 (OFF) in the following cases. • When the self-tuning starts by changing the set value (SV) • When the vibration ST starts by vibration caused by disturbance of the process value (PV)
b11 to b15	— (fixed to 0)	— (Unused)	—

*1 Indicates the values of CH□ Simultaneous temperature rise gradient data (Un\G731, Un\G747, Un\G763, Un\G779) and CH□ Simultaneous temperature rise dead time (Un\G732, Un\G748, Un\G764, Un\G780).

For details on the simultaneous temperature rise function, refer to  Page 194, Section 8.2.17.

*2 If conditions other than above lead to 1 (ON), also check the following table depending on the set content in CH□ Self-tuning setting (Un\G574, Un\G606, Un\G638, Un\G670).

Set content in CH□ Self-tuning setting (Un\G574, Un\G606, Un\G638, Un\G670)	Check description
1: Starting ST (PID constants only)	• Check the control loop for wiring problems. • Switch CH□ Self-tuning setting (Un\G574, Un\G606, Un\G638, Un\G670) to "4: Starting ST plus vibration ST (PID constants only)" to perform control.
3: Starting ST (PID constants and simultaneous temperature rise parameter)	• Check the control loop for wiring problems. • Save the calculated simultaneous temperature rise parameter, if any. Then, switch CH□ Self-tuning setting (Un\G574, Un\G606, Un\G638, Un\G670) to "4: Starting ST plus vibration ST (PID constants only)" to perform control. If no simultaneous temperature rise parameter is calculated, check the control loop for wiring problems.

Point

This area is enabled only for the following channels.

- CH1 to CH4 when the standard control is used
- CH3 and CH4 when mix control (normal mode) or mix control (expanded mode) is used

A

(75)CH□ Temperature process value (PV) for input with another analog module

(Un\G689 to Un\G692) Standard Heating-cooling

Digital input value of the current/voltage converted in another analog module (such as A/D conversion module) on system can be used as a temperature process value (PV).

Store digital input values of current/voltage converted by another analog module (such as A/D conversion module) in this area.

For details, refer to the following.

 Page 176, Section 8.2.13 (1)

Point

If a stored value is out of the set input range, the value to be used in control is fixed to the upper limit value or the lower limit value of the input range.

(76)Conversion enable/disable setting (Un\G693) Temperature Input

Set enable or disable temperature input. For details on the temperature input function, refer to the following.

 Page 120, Section 8.1

b15	b14	b13	b12	b11	b10	b9	b8	b7	b6	b5	b4	b3	b2	b1	b0
0	0	0	0	0	0	0	0	0	0	0	0	CH4	CH3	CH2	CH1

Bit data from b15 to b4 are fixed to 0.

(a) Setting range

- 0: Enable
- 1: Disable

(b) Enablement of setting contents

Enable the setting contents by turning Setting change instruction (YnB) OFF → ON → OFF during the setting mode (Setting/operation mode status (Xn1): OFF).

(c) Default value

All channels are set to Conversion disable (000F_H).

(77)CH□ Temperature conversion setting (Un\G695 to Un\G697) Heating-cooling

In the heating-cooling control (normal mode) or the mix control (normal mode), only the temperature measurement can be performed using temperature input terminals of unused channels.

The following table lists the settable buffer memory addresses for each control mode selection.

Channel	Control mode				
	Standard control	Heating-cooling control (normal mode)	Heating-cooling control (expanded mode)	Mix control (normal mode)	Mix control (expanded mode)
CH1	—	—	—	—	—
CH2	—	—	—	Un\G695	—
CH3	—	Un\G696	—	—	—
CH4	—	Un\G697	—	—	—

When the combination of the control mode and the buffer memory address is not the setting target in the above list, the combination is invalid even if it is set.

For details on the temperature conversion function (using unused channels), refer to the following.

 Page 218, Section 8.2.24

(a) Setting range

- 0: Not use
- 1: Use

(b) Default value

The default values are set to Not use (0) in all channels.

Point

- When this setting is set from Not use (0) to Use (1), after completion of the first temperature conversion, Temperature conversion completion flag (Un\G786) is set to First temperature conversion completed (1_H). Before referring to the temperature process value (PV) of each channel, check Temperature conversion completion flag (Un\G786) has been set to First temperature conversion completed (1_H).
- When the following control mode is selected, this setting is invalid.
 - Standard control
 - Heating-cooling control (expanded mode)
 - Mix control (expanded mode)

(78)CH□ Number of moving averaging (Un\G698 to Un\G701) Common

For each channel, set the number of moving averaging to be performed to temperature process values (PV).
For details on the moving averaging process to temperature process values (PV), refer to the following.

 Page 227, Section 8.3.1

This setting is enabled only when Enable (0) is set to the moving averaging process setting in the intelligent function module switch setting. If Disable (1) is set to the moving averaging process setting, this setting is ignored.

For details on the intelligent function module switch setting, refer to the following.

 Page 110, Section 7.2

(a) Setting range

2 to 10 (times)

(b) Default value

2 (times) are set in all channels as default values.

(79)Cooling method setting (Un\G719) Heating-cooling

Set the method for the cooling control in the heating-cooling control. Select the suitable cooling method for cooling characteristics of devices.

The following figure shows the channel assignment of the buffer memory area.

b15	to	b12	b11	to	b8	b7	to	b4	b3	to	b0
CH4			CH3			CH2			CH1		

For details on the cooling method setting function, refer to the following.

 Page 213, Section 8.2.22

(a) Setting range

- 0_H: Air cooled
- 1_H: Water cooled
- 2_H: Linear

(b) Enablement of setting contents

Enable the setting contents by turning Setting change instruction (YnB) OFF → ON → OFF during the setting mode (Setting/operation mode status (Xn1): OFF).

(c) Default value

The default value is set to Air cooled (0_H).

(80)CH□ Overlap/dead band function (Un\G723, Un\G739, Un\G755,**Un\G771)** Heating-cooling

Configure the overlap/dead band setting.

For details on the overlap/dead band function, refer to the following.

 Page 215, Section 8.2.23

(a) Setting range

Set the value within the following ranges for the full scale of the set input range. ( Page 355, Appendix 2 (12))

- -100 to -1 (-10.0% to -0.1%): Overlap
- 0(0.0%): None
- 1 to 100 (0.1% to 10.0%): Dead band

(b) Default value

The default values are set to 0 (0.0%) in all channels.

(81)CH□ Manual reset amount setting (Un\G724, Un\G740, Un\G756, Un\G772)Standard Heating-cooling

Set the amount of the proportional band (P) to be moved.

For details on the manual reset function, refer to the following.

 Page 141, Section 8.2.4

(a) Setting range

Set the value within the range of -1000 to 1000 (-100.0% to 100.0%) for the full scale of the set input range.

( Page 355, Appendix 2 (12))

The setting range is the same between the standard control and heating-cooling control.

(b) Default value

The default values are set to 0 (0.0%) in all channels. The default value is the same between the standard control and the heating-cooling control.

(82)CH□ Process value (PV) scaling function enable/disable setting (Un\G725,**Un\G741, Un\G757, Un\G773)** Common

Set enable/disable of the temperature process value (PV) scaling function.

For details on the temperature process value (PV) scaling function, refer to the following.

 Page 228, Section 8.3.2

(a) Setting range

- 0: Disable
- 1: Enable

(b) Enablement of setting contents

Enable the setting contents by turning Setting change instruction (YnB) OFF → ON → OFF during the setting mode (Setting/operation mode status (Xn1): OFF).

(c) Default value

The default values are set to Disable (0) in all channels.

(83)CH□ Process value (PV) scaling lower limit value (Un\G726, Un\G742, Un\G758, Un\G774) Common

CH□ Process value (PV) scaling upper limit value (Un\G727, Un\G743, Un\G759, Un\G775) Common

Set the upper limit value/lower limit value of the temperature process value (PV) scaling function.

For details on the temperature process value (PV) scaling function, refer to the following.

 Page 228, Section 8.3.2

(a) Setting range

The setting range is -32000 to 32000.

(b) Enablement of setting contents

Enable the setting contents by turning Setting change instruction (YnB) OFF → ON → OFF during the setting mode (Setting/operation mode status (Xn1): OFF).

(c) Default value

The default values are set to 0 in all channels.

Point

The setting where the lower limit value is not less than the upper limit value does not cause an error. The temperature process value (PV) is scaled according to the formula of  Page 228, Section 8.3.2 (2).

(84)CH□ Process value (PV) scaling value (Un\G728, Un\G744, Un\G760, Un\G776) Common

When the temperature process value (PV) scaling function is enabled, the scaled temperature process value (PV) is stored.

For details on the temperature process value (PV) scaling function, refer to the following.

 Page 228, Section 8.3.2

(85)CH□ Derivative action selection (Un\G729, Un\G745, Un\G761, Un\G777)**Standard** **Heating-cooling**

Select the type of derivative action. Dynamic performance can be improved by selecting the suitable derivative action for the fixed value action and the ramp action. For details on the derivative action selection function, refer to the following.

 Page 158, Section 8.2.9

(a) Setting range

- 0: Measured value derivation
- 1: Deviation derivation

(b) Enablement of setting contents

Enable the setting contents by turning Setting change instruction (YnB) OFF → ON → OFF during the setting mode (Setting/operation mode status (Xn1): OFF).

(c) Default value

All channels are set to Measured value derivation (0).

(86)CH□ Simultaneous temperature rise group setting (Un\G730, Un\G746,**Un\G762, Un\G778)** **Standard**

Set a group to perform the simultaneous temperature rise function for each channel. The simultaneous temperature rise function enables channels in the same group to complete the rise of temperature simultaneously. When the control mode is the heating-cooling control, this setting is invalid.

For details on the simultaneous temperature rise function, refer to the following.

 Page 194, Section 8.2.17

(a) Setting range of the standard control

- 0: No simultaneous temperature rise
- 1: Group 1 selection
- 2: Group 2 selection

(b) Setting range of the mix control

- 0: No simultaneous temperature rise
- 1: Simultaneous temperature rise

The setting range in the mix control does not include group selection because the mix control has only two channels for the standard control.

(c) Enablement of setting contents

Enable the setting contents by turning Setting change instruction (YnB) OFF → ON → OFF during the setting mode (Setting/operation mode status (Xn1): OFF).

(d) Default value

The default values are set to No simultaneous temperature rise (0) in all channels.

(87)CH□ Simultaneous temperature rise gradient data (Un\G731, Un\G747, Un\G763, Un\G779) Standard

Set Simultaneous temperature rise gradient data (temperature rising per minute).

For details on the simultaneous temperature rise function, refer to the following.

 Page 194, Section 8.2.17

(a) Setting range

The setting range is 0 to full scale.

(b) Setting unit

The value to be set differs depending on the stored value in CH□ Decimal point position (Un\G1 to Un\G4).

 Page 344, Appendix 2 (2))

- No decimal place (0): Set a value in 1°C (°F or digit) unit.
- One decimal place (1): Set a value in 0.1°C (°F) unit (tenfold value).

(c) Default value

The default values are set to 0 in all channels.

Point

This setting can not only be set manually but also be calculated automatically. Automatic calculation is performed when the simultaneous temperature rise AT (auto tuning) or self-tuning (when the automatic calculation of the temperature rise parameter is set) is normally completed.

(88)CH□ Simultaneous temperature rise dead time (Un\G732, Un\G748, Un\G764, Un\G780) Standard

Set Simultaneous temperature rise dead time (time taken for the temperature to start rising after the output is turned on).

For details on the simultaneous temperature rise function, refer to the following.

 Page 194, Section 8.2.17

(a) Setting range

The setting range is 0 to 3600 (s).

(b) Default value

The default values are set to 0 in all channels.

Point

This setting can not only be set manually but also be calculated automatically. Automatic calculation is performed when the simultaneous temperature rise AT (auto tuning) or self-tuning (when the automatic calculation of the temperature rise parameter is set) is normally completed.

(89)CH□ Simultaneous temperature rise AT mode selection (Un\G733, Un\G749,**Un\G765, Un\G781)** **Standard**

Select mode of the auto tuning.

For details on the auto tuning function, refer to the following.

 Page 145, Section 8.2.7

For details on the simultaneous temperature rise function, refer to the following.

 Page 194, Section 8.2.17

(a) Setting range

- 0: Select normal auto tuning
- 1: Simultaneous temperature rise AT

(b) Default value

The default values are set to Select normal auto tuning (0) in all channels.

Point

-
- This setting can be used with the setting of CH□ Auto tuning mode selection (Un\G184 to Un\G187). ( Page 394, Appendix 2 (51))
 - If this setting is changed during the auto tuning, it is enabled in the next auto tuning.
-

(90)CH□ Simultaneous temperature rise status (Un\G734, Un\G750, Un\G766,

Un\G782) Standard

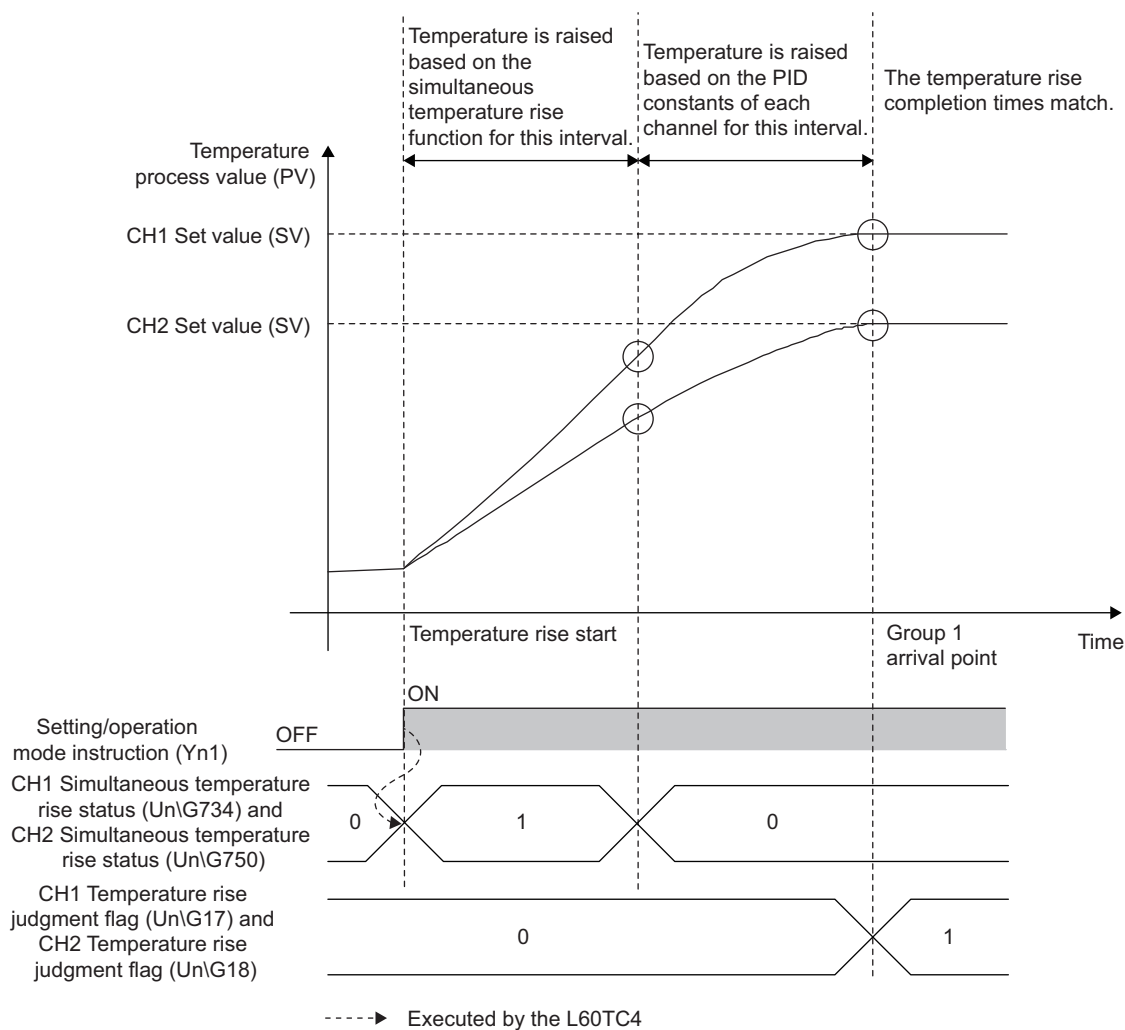
The execution state of the simultaneous temperature rise is monitored.

- 0: Simultaneous temperature rise not in process
- 1: Simultaneous temperature rise in process

During control by the simultaneous temperature rise function, Simultaneous temperature rise in process (1) is stored in this buffer memory area.

The following figure shows the timing when the value is set to Simultaneous temperature rise not in process (0).

(In the following, CH1 and CH2 are set to group 1. (☞ Page 417, Appendix 2 (86))



Completion of the temperature rise does not set CH□ Simultaneous temperature rise status (Un\G734, Un\G750, Un\G766, Un\G782) to Simultaneous temperature rise not in process (0). As in the figure above, the temperature rise is performed by the simultaneous temperature rise function to a certain point, and Simultaneous temperature rise in process (1) is set during the performance. After the point, the temperature rise is performed based on the PID constants of each channel, and Simultaneous temperature rise not in process (0) is set.

For details on the simultaneous temperature rise function, refer to the following.

☞ Page 194, Section 8.2.17

(91)CH□ Setting change rate limiter time unit setting (Un\G735, Un\G751, Un\G767,**Un\G783)** **Standard** **Heating-cooling**

Set the time unit of setting change rate limiter.

For details on the setting change rate limiter time unit setting function, refer to the following.

 Page 159, Section 8.2.10

(a) Setting range

- 0 (Not use time unit setting)
- 1 to 3600 (1 to 3600s)

A setting of 0 results in the same operation with the setting of 60 corresponding to one minute.

(b) Enablement of setting contents

Enable the setting contents by turning Setting change instruction (YnB) OFF → ON → OFF during the setting mode (Setting/operation mode status (Xn1): OFF).

(c) Default value

The default values are set to 0 (Not use time unit setting) in all channels.

Remark

When 0 is set, the L60TC4 operation is the same as the case when 60, a variation per minute, is set.

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(92)Peak current suppression control group setting (Un\G784) Standard

Set the target channels for the peak current suppression function and the gap of the control output cycle between channels.

b15	to	b12	b11	to	b8	b7	to	b4	b3	to	b0
CH4			CH3			CH2			CH1		

For details on the peak current suppression function, refer to the following.

 Page 189, Section 8.2.16

(a) Setting range

- 0_H: Not divide
- 1_H: Group 1
- 2_H: Group 2
- 3_H: Group 3
- 4_H: Group 4

(b) Enablement of setting contents

Enable the setting contents by turning Setting change instruction (YnB) OFF → ON → OFF during the setting mode (Setting/operation mode status (Xn1): OFF).

(c) Default value

The default value is set to Not divide (0_H).

Point

The division number depends on this setting. The upper limit output limiter value is automatically set to correspond to the specified division number.

The following table lists the upper limit output limiter values which are set when this setting is enabled.

Division Number	CH□ Upper limit output limiter (Un\G42, Un\G74, Un\G106, Un\G138) ( Page 369, Appendix 2 (19))
2	500 (50.0%)
3	333 (33.3%)
4	250 (25.0%)

CH□ Lower limit output limiter (Un\G43, Un\G75, Un\G107, Un\G139) is set to 0.

(93)Sensor correction function selection (Un\G785) Common

Select the method of the sensor correction for each channel.

b15 to b12	b11 to b8	b7 to b4	b3 to b0
CH4	CH3	CH2	CH1

For details on the sensor correction function, refer to the following.

 Page 230, Section 8.3.3

(a) Setting range

- 0_H: Normal sensor correction (one-point correction)
- 1_H: Sensor two-point correction

(b) Enablement of setting contents

Enable the setting contents by turning Setting change instruction (YnB) OFF → ON → OFF during the setting mode (Setting/operation mode status (Xn1): OFF).

(c) Default value

Default value is set to Normal sensor correction (one-point correction) (0_H).

(94)Temperature conversion completion flag (Un\G786) Common

This flag checks whether the temperature conversion has started properly for each channel. The following values are stored in this buffer memory area.

- 0_H: During conversion or unused CH
- 1_H: First temperature conversion completed

This flag becomes During conversion or unused CH (0_H) during temperature conversion or for unused channels.

When the first temperature conversion is completed and the temperature process value (PV) is stored in the buffer memory, First temperature conversion completed (1_H) is set.

The following figure shows the channel assignment of this area.

b15 to b12	b11 to b8	b7 to b4	b3 to b0
CH4	CH3	CH2	CH1

(95)Function extension bit monitor (Un\G787) Common

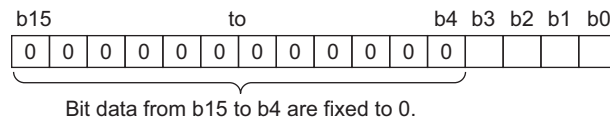
The following settings configured on Switch Setting are stored.

- "Auto-setting at Input Range Change"
- "Setting Change Rate Limiter Setting"
- "Control Output Cycle Unit Selection Setting"
- "Moving Averaging Process Setting"

For details on Switch Setting, refer to the following.

 Page 110, Section 7.2

The following figure and table show how the setting is stored.



Bit	Flag name (Function extension bit monitor)	Description
b0	Auto-setting at input range change	When the input range is changed, the related buffer memory data is automatically changed to prevent the values in those buffer memory areas from being out of the setting range. ( Page 360, Appendix 2 (12) (d)) 0: Disable 1: Enable
b1	Setting change rate limiter setting	Select whether the setting change rate limiter to be set in a batch or individually. ( Page 159, Section 8.2.10) 0: Temperature Rise/Temperature Drop Batch Setting 1: Temperature Rise/Temperature Drop Individual Setting
b2	Control output cycle unit selection setting	Select 0.1s or 1s as a unit for the cycle of turning on/off the transistor output. ( Page 144, Section 8.2.6) 0: 1s Cycle 1: 0.1s Cycle
b3	Moving averaging process setting	Select whether the moving averaging process setting is used. ( Page 227, Section 8.3.1) 0: Enable 1: Disable
b4 to b15	— (fixed to 0)	— (Unused)

(96)Sampling cycle monitor (Un\G788) Common

Current sampling cycle is stored.

- 0: 500ms/4 channels
- 1: 250ms/4 channels

Sampling cycle is set on Switch Setting. For details on Switch Setting, refer to the following.

 Page 110, Section 7.2

(97)Latest address of error history (Un\G1279) Common

The latest address of error history is stored.
For details on the error history function, refer to the following.
☞ Page 244, Section 8.3.6

(98)Error history 1 to 16 (Un\G1280 to Un\G1407) Common

The maximum of 16 errors and alarms occurred in the module are recorded.

Ex. For the error history 1

Buffer memory address	b15	to	b8	b7	to	b0
Un\G1280	Error code* ¹					
Un\G1281	First two digits of the year			Last two digits of the year		
Un\G1282	Month			Day		
Un\G1283	Hour			Minute		
Un\G1284	Second			Day of the week * ²		
Un\G1285	System area					
to						
Un\G1287						

- *1 For error codes and alarm codes, refer to the following.
☞ Page 325, Section 11.6, Page 328, Section 11.7
- *2 The following table lists the stored value and corresponding each day of the week.

Stored value	Day of the week
0	Sunday
1	Monday
2	Tuesday
3	Wednesday
4	Thursday
5	Friday
6	Saturday

For details on the error history function, refer to the following.
☞ Page 244, Section 8.3.6

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Appendix 3 How to Check the Serial Number and Function Version

For details on how to check the serial number and function version, refer to the following.

 MELSEC-L CPU Module User's Manual (Hardware Design, Maintenance and Inspection)

 MELSEC-L CC-Link IE Field Network Head Module User's Manual

Appendix 4 Addition and Change of Functions

Appendix 4.1 Additional function

The following table shows the function added to the L60TC4 and the product information of the L60TC4 that supports the additional function.

Additional function	Product information	Applicable GX Works2 version	Reference
Moving averaging process to a temperature process value (PV)	The first five digits are 14062 or later.	1.91V or later	Page 227, Section 8.3.1
During AT loop disconnection detection function	The first five digits are 15042 or later.	1.501X or later	Page 210, Section 8.2.20

Appendix 4.2 Change of functions

The following table shows the changed functions of the L60TC4 and the product information of the L60TC4 that supports the changed functions.

Changed function	Product information	Applicable GX Works2 version	Reference
Function extension bit monitor (Un\G787)	The first five digits are 14062 or later.	1.91V or later	Page 427, Appendix 4.2 (1)
Intelligent function module switch setting			Page 427, Appendix 4.2 (2)

(1) Function extension bit monitor (Un\G787)

The following contents set in the intelligent function module switch setting are stored.

- "Auto-setting at Input Range Change"
- "Setting Change Rate Limiter Setting"
- "Moving Averaging Process Setting"

(a) When using the L60TC4 that does not support this function

Because the module does not support "Moving Averaging Process Setting", setting contents of "Moving Averaging Process Setting" cannot be checked.

(2) Intelligent function module switch setting

Whether to perform the moving averaging process can be selected in the intelligent function module switch setting.

(a) When using the L60TC4 that does not support this function

The moving averaging process setting cannot be configured in the intelligent function module switch setting.

Appendix 5 Differences with MELSEC-Q series Modules

Appendix 5.1 Differences with temperature control modules

This section describes the differences in functions and programming methods between the MELSEC-Q series temperature control modules (Q64TCTTN, Q64TCTTBWN, Q64TCRTN, Q64TCRTBWN) and the L60TC4.

(1) Functional comparison

(a) Added functions

The following table lists the functions added in the L60TC4.

Item	Description	Reference
Input range	The following input ranges are available in the L60TC4. (1) L60TCTT4, L60TCTT4BW • K: -200.0 to 1300.0°C • J: -200.0 to 1000.0°C • E: -200.0 to 1000.0°C • N: 0.0 to 1000.0°C (2) L60TCRT4, L60TCRT4BW • Pt100: -200.0 to 850.0°C • JPt100: -200.0 to 640.0°C	Page 37, Section 3.2.2
Temperature input mode	The L60TC4 can be used as a temperature input module. It also enables application of the primary delay digital filter to temperature input, the alert output, and other functions.	Page 120, Section 8.1
Switching the sampling cycle	The sampling cycle can be selected from 250ms/4 channels and 500ms/4 channels. (The cycle is fixed to 500ms in MELSEC-Q series temperature control modules.)	Page 39, Section 3.2.3 (1), Page 110, Section 7.2
Switching the unit of control output cycle	The control output cycle can be selected by 0.1s (0.5s to 100.0s) with the L60TC4. The cycle can be also selected by 1s (1s to 100s) similar to MELSEC-Q series temperature control modules.	Page 39, Section 3.2.3 (2), Page 110, Section 7.2

(b) Function that cannot be used

Online module change is not available with the L60TC4.

(2) Program compatibility

Programs used in the MELSEC-Q series temperature control modules (Q64TCTTN, Q64TCTTBWN, Q64TCRTN, Q64TCRTBWN) can be used with the L60TC4.

(a) I/O signal

Although some I/O numbers of the L60TC4 have different names from those of the MELSEC-Q series temperature control modules, they have the same function and are compatible with each other.

(b) Buffer memory

Although some buffer memory areas have been added to the L60TC4, the functions are the same and the program has compatibility.

(c) Sampling cycle

For the L60TC4, the sampling cycle can be selected from 250ms and 500ms. For the MELSEC-Q series temperature control modules, the cycle is fixed to 500ms. When using the program used in the MELSEC-Q series temperature control modules with the L60TC4, check that the sampling cycle for the L60TC4 is set to 500ms. When changing the cycle to 250ms, thoroughly verify that the control of the target system has no problem.

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Appendix 6 When Using GX Developer

This section describes how to configure the setting of the L60TC4 using GX Developer.

Appendix 6.1 I/O assignment and intelligent function module switch setting

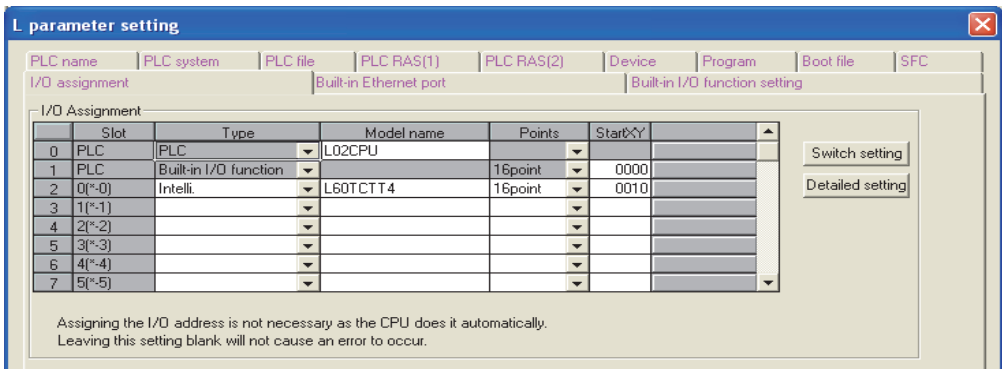
Configure the setting on the following windows when using GX Developer.

Window name	Application
I/O assignment	Set the type of a module to be connected and the range of I/O signal.
Intelligent function module switch setting	Configure the switch setting of the intelligent function module.

(1) I/O assignment

Configure the setting on "I/O assignment" in "PLC parameter".

 Parameter ⇒ [PLC parameter] ⇒ [I/O assignment]



Item	Description
Type	Select "Intelli.".
Model name	Enter the model name of the module.
Points	Select "16 point".
Start XY	Enter an arbitrary start I/O number of the L60TC4.

Remark

Select "16 point" in Points when using the L60TCTT4BW or L60TCRT4BW.

(2) Intelligent function module switch setting

Configure the setting on "Switch setting" in "PLC parameter".

 Parameter ⇨ [PLC parameter] ⇨ [I/O assignment] ⇨ Click .

Switch setting for I/O and intelligent function module

Input format

HEX.

	Slot	Type	Model name	Switch 1	Switch 2	Switch 3	Switch 4	Switch 5
0	PLC	PLC	L02CPU					
1	PLC	Built-in I/O function						
2	0(*-0)	Intelli.	L60TCTT4	0000	0001	0000	0000	0000
3	1(*-1)							
4	2(*-2)							
5	3(*-3)							
6	4(*-4)							
7	5(*-5)							
8	6(*-6)							
9	7(*-7)							
10	8(*-8)							
11	9(*-9)							

End

Cancel

Select "HEX.".

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Item	Setting item			
Switch 1	CH4CH3CH2CH1 H	Control output HOLD/CLEAR setting		
		Setting value	Output setting	
		0	CLEAR	
		Other than 0	HOLD	
Switch 2	Setting value*2	Mode selection*1		
		Control mode		Number of control loops
	0000 _H	Temperature control mode	Standard control	Standard control 4 loops
	0001 _H		Heating-cooling control (normal mode)	Heating-cooling control 2 loops
	0002 _H		Heating-cooling control (expanded mode)*3	Heating-cooling control 4 loops
	0003 _H		Mix control (normal mode)	Heating-cooling control 1 loop
	0004 _H		Mix control (expanded mode)*3	Standard control 2 loops
	0100 _H			Heating-cooling control 2 loops
		Temperature input mode	—	

Appendix 6 When Using GX Developer
Appendix 6.1 I/O assignment and intelligent function module switch setting

Item	Setting item
	Function extension bit specification, sampling cycle selection
Switch 3	Diagram of the 16-bit register for Switch 3. Bits b15 to b12 are grouped as "Fixed to 0". Bits b11 to b8 are grouped as "Fixed to 0". Bit b7 is connected to b12. Bit b6 is connected to b12. Bit b5 is connected to b12. Bit b4 is connected to b12. Bit b3 is connected to b12. Bit b2 is connected to b12. Bit b1 is connected to b12. Bit b0 is connected to b12. Extended function bit setting - b0: Automatic setting when the input range is changed 0: Disable 1: Enable - b1: Setting change rate limiter setting 0: Temperature rise/Temperature drop batch setting 1: Temperature rise/Temperature drop individual setting - b2: Control cycle unit switch setting*1 0: 1-second intervals 1: 0.1-second intervals - b3: Moving averaging process setting 0: Enable 1: Disable b12: Sampling cycle selection*1 0: 500ms/4 channels 1: 250ms/4 channels
Switch 4	0: Fixed (empty)
Switch 5	0: Fixed (empty)

- *1 Immediately after the setting is changed, a set value discrepancy error (error code: 0□□E_H) occurs. To clear the set value discrepancy error, turn off, on, and off Set value backup instruction (Yn8).
- *2 When the setting is out of the setting value, a switch setting error (error code: 000F_H) occurs. In this case, the module does not operate properly. Set the correct value.
- *3 Control in the expanded mode requires an external output module. For details, refer to Page 131, Section 8.2.1 (3).

Appendix 6.2 Initial setting and auto refresh setting

The initial setting and auto refresh setting cannot be configured when GX Developer is used. Use the program instead.

(1) Initial setting

Configure the initial setting using the program. (📖 Page 257, CHAPTER 10)

(2) Auto refresh setting

To access the buffer memory using the program, perform one of the following methods.

(a) Access using FROM/TO instruction

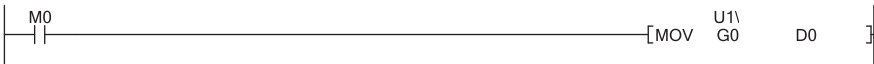
Use FROM instruction to store the data read from the buffer memory in the L60TC4 into the specified device.
Use TO instruction to write the data of the specified device to the buffer memory in the L60TC4.
For details on FROM/TO instruction, refer to the following.

📖 MELSEC-Q/L Programming Manual (Common Instructions)

(b) Access using Intelligent function module device

Use Intelligent function module device (Un\G□) to access the buffer memory in the L60TC4.

Ex. When Error code (Un\G0) is transferred to D0 in the CPU module.



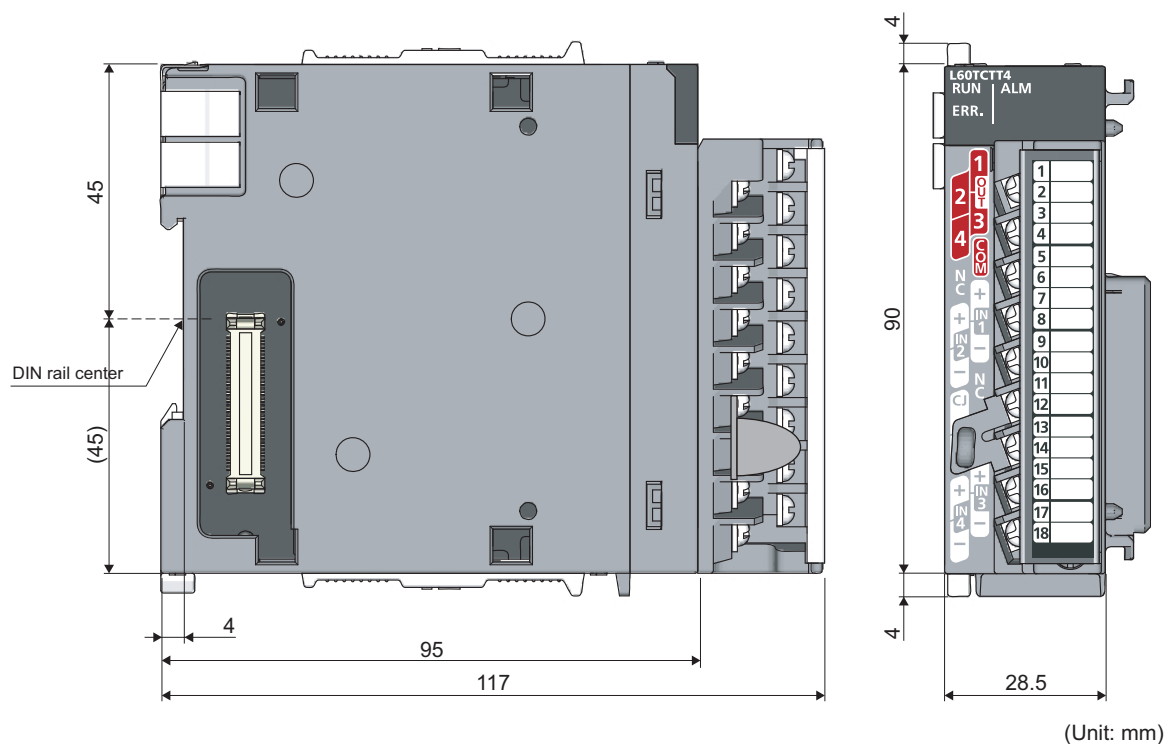
A

Appendix 6 When Using GX Developer
Appendix 6.2 Initial setting and auto refresh setting

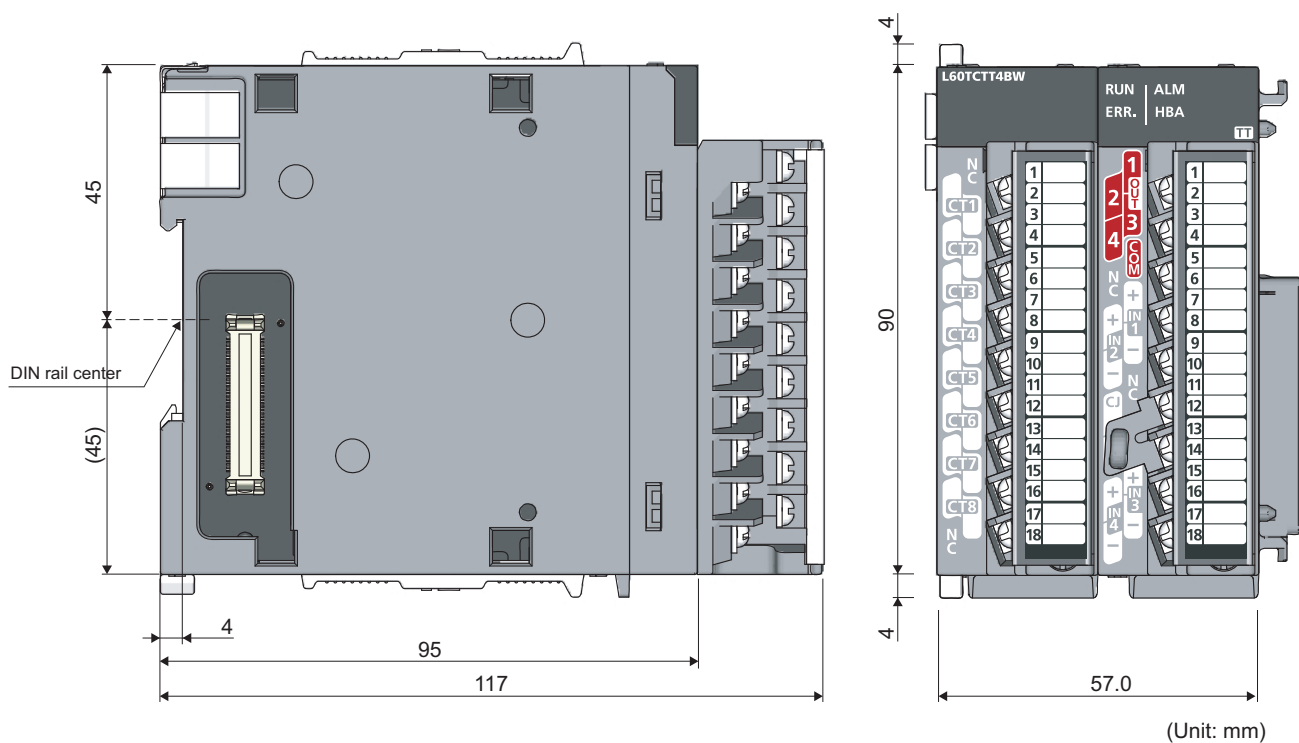
Appendix 7 External Dimensions

The following shows the external dimensions of the L60TC4.

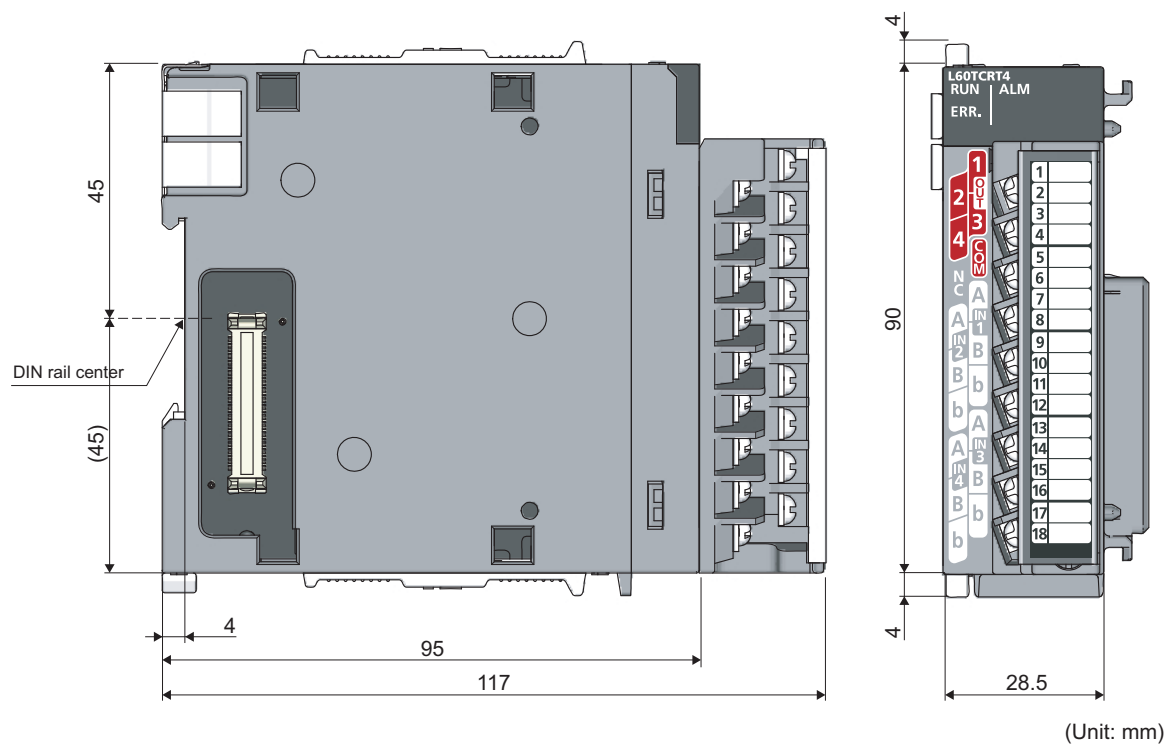
(1) L60TCTT4



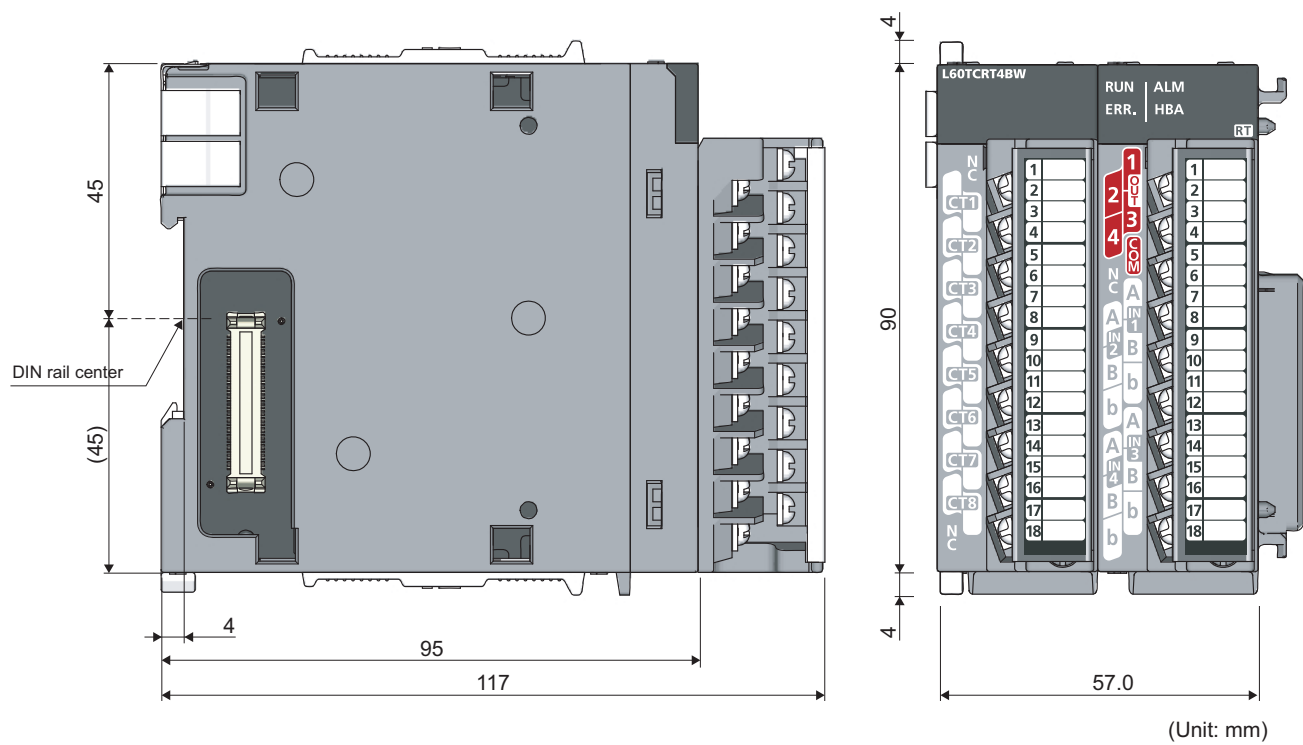
(2) L60TCTT4BW



(3) L60TCRT4



(4) L60TCRT4BW



INDEX

A

Accuracy	33
Added functions	428
Adjustment after auto tuning	156
Air cooled	213
Air cooling	414
Alarm code list	328
Alarm priorities	330
Alert	161
Alert dead band	172
Alert dead band setting (Un\G164)	388
Alert mode and settings	174
Alert mode and the set value (SV) to be referred	166
Alert output	124
Alert with standby	167
Alert with standby (second time)	168
Algorithm of PID control in process-value incomplete derivation	24
ALM LED	30,321
Applicable software version	84
Applicable solderless terminal	34
Applicable systems	84
Applicable wire size	34
AT point	379
AT simultaneous temperature rise parameter calculation completion	407
AT simultaneous temperature rise parameter calculation error status	407
Auto refresh	116
Auto tuning	145
Auto-setting at input range change	110,111,241,360,361,424

B

Backup of the calculated value on completion of auto tuning	147
Back-up of the set value completion flag (Xn8)	337
Back-up of the set value fail flag (XnA)	323,338
Batch/individual setting for temperature rise and temperature drop	159
Buffer memory	14
Buffer memory address by mode	45
Buffer memory address for error history	78
Buffer memory areas related to auto tuning	146
Buffer memory areas related to control method	139
Buffer memory areas which can be set only in the setting mode	340
Buffer memory data backup	242
Buffer memory list	45

C

Calculation formula for heater disconnection compensation	223
Checking the completion of auto tuning	155
Checking the error	255

CH□ Adjustment sensitivity (dead band) setting (Un\G46, Un\G78, Un\G110, Un\G142)	133,134,372
CH□ Alert 1 mode setting (Un\G192, Un\G208, Un\G224, Un\G240)	395
CH□ Alert 2 mode setting (Un\G193, Un\G209, Un\G225, Un\G241)	395
CH□ Alert 3 mode setting (Un\G194, Un\G210, Un\G226, Un\G242)	395
CH□ Alert 4 mode setting (Un\G195, Un\G211, Un\G227, Un\G243)	395
CH□ Alert definition (Un\G5 to Un\G8)	346
CH□ Alert occurrence flag (XnC to XnF)	323,339
CH□ Alert set value 1 (Un\G38, Un\G70, Un\G102, Un\G134)	367
CH□ Alert set value 2 (Un\G39, Un\G71, Un\G103, Un\G135)	367
CH□ Alert set value 3 (Un\G40, Un\G72, Un\G104, Un\G136)	367
CH□ Alert set value 4 (Un\G41, Un\G73, Un\G105, Un\G137)	367
CH□ AT bias setting (Un\G53, Un\G85, Un\G117, Un\G149)	379
CH□ AT simultaneous temperature rise parameter calculation flag (Un\G573, Un\G605, Un\G637, Un\G669)	407
CH□ Auto tuning instruction (Yn4 to Yn7)	341
CH□ Auto tuning mode selection (Un\G184 to Un\G187)	394,419
CH□ Auto tuning status (Xn4 to Xn7)	322,323,336
CH□ AUTO/MAN mode shift (Un\G50, Un\G82, Un\G114, Un\G146)	376,377
CH□ Automatic backup setting after auto tuning of PID constants (Un\G63, Un\G95, Un\G127, Un\G159)	387
CH□ Control output cycle setting (Un\G47, Un\G79, Un\G111, Un\G143)	373
CH□ Control response parameter (Un\G49, Un\G81, Un\G113, Un\G145)	375
CH□ Cooling control output cycle setting (Un\G722, Un\G738, Un\G754, Un\G770)	373
CH□ Cooling proportional band (Pc) setting (Un\G720, Un\G736, Un\G752, Un\G768)	364
CH□ Cooling transistor output flag (Un\G712 to Un\G715)	351
CH□ Cooling upper limit output limiter (Un\G721, Un\G737, Un\G753, Un\G769)	369
CH□ Decimal point position (Un\G1 to Un\G4)	344
CH□ Derivative action selection (Un\G729, Un\G745, Un\G761, Un\G777)	417
CH□ Derivative time (D) setting (Un\G37, Un\G69, Un\G101, Un\G133)	366
CH□ Forward/reverse action setting (Un\G54, Un\G86, Un\G118, Un\G150)	380
CH□ Heater disconnection alert setting (Un\G58, Un\G90, Un\G122, Un\G154)	382
CH□ Heating control output cycle setting (Un\G47, Un\G79, Un\G111, Un\G143)	373
CH□ Heating proportional band (Ph) setting (Un\G35, Un\G67, Un\G99, Un\G131)	364

CH□ Heating transistor output flag (Un\G21 to Un\G24)	351
CH□ Heating upper limit output limiter (Un\G42, Un\G74, Un\G106, Un\G138)	369
CH□ Input range (Un\G32, Un\G64, Un\G96, Un\G128)	355
CH□ Integral time (I) setting (Un\G36, Un\G68, Un\G100, Un\G132)	366
CH□ Loop disconnection detection dead band (Un\G60, Un\G92, Un\G124, Un\G156)	384
CH□ Loop disconnection detection judgment time (Un\G59, Un\G91, Un\G123, Un\G155)	383
CH□ Lower limit output limiter (Un\G43, Un\G75, Un\G107, Un\G139)	369
CH□ Lower limit setting limiter (Un\G56, Un\G88, Un\G120, Un\G152)	381
CH□ MAN output setting (Un\G51, Un\G83, Un\G115, Un\G147)	377
CH□ Manipulated value (MV) (Un\G13 to Un\G16)	349
CH□ Manipulated value (MV) for output with another analog module (Un\G177 to Un\G180)	392
CH□ Manipulated value for cooling (MVc) (Un\G704 to Un\G707)	349
CH□ Manipulated value for heating (MVh) (Un\G13 to Un\G16)	349
CH□ Manipulated value of cooling (MVc) for output with another analog module (Un\G708 to Un\G711)	392
CH□ Manipulated value of heating (MVh) for output with another analog module (Un\G177 to Un\G180)	392
CH□ Manual reset amount setting (Un\G724, Un\G740, Un\G756, Un\G772)	415
CH□ Memory's PID constants read instruction (Un\G62, Un\G94, Un\G126, Un\G158)	353, 386
CH□ Number of moving averaging (Un\G698 to Un\G701)	414
CH□ Output variation limiter setting (Un\G44, Un\G76, Un\G108, Un\G140)	371
CH□ Overlap/dead band function (Un\G723, Un\G739, Un\G755, Un\G771)	415
CH□ PID control forced stop instruction (YnC to YnF)	343
CH□ Primary delay digital filter setting (Un\G48, Un\G80, Un\G112, Un\G144)	374
CH□ Process alarm alert output enable/disable setting (Un\G196, Un\G212, Un\G228, Un\G244)	396
CH□ Process alarm lower lower limit value (Un\G197, Un\G213, Un\G229, Un\G245)	397
CH□ Process alarm lower upper limit value (Un\G198, Un\G214, Un\G230, Un\G246)	397
CH□ Process alarm upper lower limit value (Un\G199, Un\G215, Un\G231, Un\G247)	397
CH□ Process alarm upper upper limit value (Un\G200, Un\G216, Un\G232, Un\G248)	397
CH□ Process value (PV) scaling function enable/disable setting (Un\G725, Un\G741, Un\G757, Un\G773)	415
CH□ Process value (PV) scaling lower limit value (Un\G726, Un\G742, Un\G758, Un\G774)	416
CH□ Process value (PV) scaling upper limit value (Un\G727, Un\G743, Un\G759, Un\G775)	416
CH□ Process value (PV) scaling value (Un\G728, Un\G744, Un\G760, Un\G776)	416

CH□ Proportional band (P) setting (Un\G35, Un\G67, Un\G99, Un\G131)	364
CH□ Rate alarm alert detection cycle (Un\G202, Un\G218, Un\G234, Un\G250)	398
CH□ Rate alarm alert output enable/disable setting (Un\G201, Un\G217, Un\G233, Un\G249)	398
CH□ Rate alarm lower limit value (Un\G204, Un\G220, Un\G236, Un\G252)	399
CH□ Rate alarm upper limit value (Un\G203, Un\G219, Un\G235, Un\G251)	399
CH□ Self-tuning flag (Un\G575, Un\G607, Un\G639, Un\G671)	409
CH□ Self-tuning setting (Un\G574, Un\G606, Un\G638, Un\G670)	408
CH□ Sensor correction value setting (Un\G45, Un\G77, Un\G109, Un\G141)	372
CH□ Sensor two-point correction gain latch completion (Un\G551, Un\G583, Un\G615, Un\G647)	406
CH□ Sensor two-point correction gain latch request (Un\G550, Un\G582, Un\G614, Un\G646)	406
CH□ Sensor two-point correction gain value (corrected value) (Un\G547, Un\G579, Un\G611, Un\G643)	404
CH□ Sensor two-point correction gain value (measured value) (Un\G546, Un\G578, Un\G610, Un\G642)	404
CH□ Sensor two-point correction offset latch completion (Un\G549, Un\G581, Un\G613, Un\G645)	405
CH□ Sensor two-point correction offset latch request (Un\G548, Un\G580, Un\G612, Un\G644)	405
CH□ Sensor two-point correction offset value (corrected value) (Un\G545, Un\G577, Un\G609, Un\G641)	403
CH□ Sensor two-point correction offset value (measured value) (Un\G544, Un\G576, Un\G608, Un\G640)	403
CH□ Set value (SV) monitor (Un\G25 to Un\G28)	162, 352
CH□ Set value (SV) setting (Un\G34, Un\G66, Un\G98, Un\G130)	162, 363
CH□ Setting change rate limiter (temperature drop) (Un\G564, Un\G596, Un\G628, Un\G660)	378
CH□ Setting change rate limiter (temperature rise) (Un\G52, Un\G84, Un\G116, Un\G148)	378
CH□ Setting change rate limiter (Un\G52, Un\G84, Un\G116, Un\G148)	378
CH□ Setting change rate limiter time unit setting (Un\G735, Un\G751, Un\G767, Un\G783)	352, 421
CH□ Simultaneous temperature rise AT mode selection (Un\G733, Un\G749, Un\G765, Un\G781)	419
CH□ Simultaneous temperature rise dead time (Un\G732, Un\G748, Un\G764, Un\G780)	418
CH□ Simultaneous temperature rise gradient data (Un\G731, Un\G747, Un\G763, Un\G779)	418
CH□ Simultaneous temperature rise group setting (Un\G730, Un\G746, Un\G762, Un\G778)	417
CH□ Simultaneous temperature rise status (Un\G734, Un\G750, Un\G766, Un\G782)	420
CH□ Stop mode setting (Un\G33, Un\G65, Un\G97, Un\G129)	362
CH□ Temperature conversion setting (Un\G695 to Un\G697)	413
CH□ Temperature process value (PV) (Un\G9 to Un\G12)	348
CH□ Temperature process value (PV) for input with another analog module (Un\G689 to Un\G692)	412
CH□ Temperature rise judgment flag (Un\G17 to Un\G20)	350

CH□ Transistor output flag (Un\G21 to Un\G24)	351
CH□ Unused channel setting (Un\G61, Un\G93, Un\G125, Un\G157)	385
CH□ Upper limit output limiter (Un\G42, Un\G74, Un\G106, Un\G138)	369,422
CH□ Upper limit setting limiter (Un\G55, Un\G87, Un\G119, Un\G151)	381
Clearing error	256
Cold junction temperature compensation accuracy: (ambient temperature: 0 to 55&drcent)	33
Cold junction temperature compensation resistor	31,89
Cold junction temperature compensation selection (Un\G182)	393
Cold junction temperature process value (Un\G29)	352
Compensation lead wire	95,96,97,98,99,100
Condition for alert judgment	170
Condition where CH□ Alert occurrence flag (XnC to XnF) turns off	170
Conditions for self-tuning (starting ST)	183
Conditions for self-tuning (vibration ST)	184
Conditions for the simultaneous temperature rise function	197
Conditions where auto tuning cannot be executed	153
Conditions where auto tuning ends in fail	154
Conditions where self-tuning does not complete due to errors	187
Conditions where self-tuning is not executed	185
Connection terminal	34
Control method	14,133
Control mode	14,130
Control mode selection	111
Control output	33
Control output cycle	33,39,144
Control output cycle unit selection	144
Control output cycle unit selection setting	111,424
Control output setting at CPU stop error	132
Control switching monitor (Un\G183)	394
Conversion enable/disable	121
Conversion enable/disable setting (Un\G693)	412
Cooling method setting	213
Cooling method setting (Un\G719)	414
CPU module	14,83
CT monitor method switching (Un\G176)	391
CT ratio setting	402
CTL-12-S36-10 (0.0 to 100.0A)	84
CTL-12-S36-8 (0.0 to 100.0A)	84
CTL-12-S56-10 (0.0 to 100.0A)	84
CTL-6-P (0.00 to 20.00A)	84
CTL-6-P-H (0.00 to 20.00A)	84
CT□ CT input channel assignment setting (Un\G264 to Un\G271)	399,400
CT□ CT ratio setting (Un\G288 to Un\G295)	401,402
CT□ CT selection (Un\G272 to Un\G279)	401
CT□ Heater current process value (Un\G256 to Un\G263)	399
CT□ Reference heater current value (Un\G280 to Un\G287)	399,402
Current sensor for heater disconnection detection	84

D

Data read from non-volatile memory	243
Data write to non-volatile memory	242
Dead band	216
Dead band setting range	33
Default setting registration instruction (Yn9)	342,385
Default value write completion flag (Xn9)	337
Derivative action (D-action)	28
Derivative action selection	158
Deviation alert	162
Dielectric withstand voltage	34
Differences	427
Differences between auto tuning and self-tuning	179
DIN rail hook	31
Discontinuation of self-tuning	186
Display unit	14,248
Displayed in English	250
During AT Loop Disconnection Detection Function	210
During AT loop disconnection detection function enable/disable setting (UnG571)	407

E

Effect from wiring resistance of 1 ohm	37
ERR. LED	30,320
Error clear	247
Error code	331
Error code (Un\G0)	344
Error code list	325
Error code priorities	327
Error history	244
Error history 1 to 16 (Un\G1280 to Un\G1407)	425
Error occurrence flag (Xn2)	322,335
Error reset instruction (Yn2)	341
Expanded mode	131
External dimensions	434
External output	14

F

Fixed value action	14,417
Forward action	25,207
Full scale	14
Function extension bit monitor (Un\G787)	424
Function list	40
Function version	331,426
Functional comparison	428

G

GX Developer	14,430
GX Works2	14

H

H/W LED information	332
H/W switch information	332
Hardware error flag (Xn3)	322,335
HBA LED	30

Head module	14,83
Heater disconnection compensation function	223
Heater disconnection compensation function selection (UnG170)	390
Heater disconnection detection	221
Heater disconnection detection specifications	34
Heater disconnection detection wiring and setting example for three-phase heater	107
Heater disconnection/output off-time current error detection delay count(UnG166)	389
Heating-cooling control	130
Heating-cooling control (expanded mode)	130,131
Heating-cooling control (normal mode)	130
High response mode	394
How to check error history	244
How to execute sensor two-point correction (when using GX Works2)	235
How to execute sensor two-point correction (when using the program)	239

I

Indication accuracy	33
Initial setting change screen	249
Input alert	161
Input filter	33
Input impedance	33
Input range	355
Input signal	333
Input signal list	43
Input/output (with another analog module)	176
Installation of the terminal block	93
Insulation method	33
Insulation resistance	34
Integral action (I-action)	27
Internal current consumption	34

L

L60TC4	14
L60TC4 actions	25
L60TC4 as a temperature control module	111
L60TCRT4	14,435
L60TCRT4BW	14,435
L60TCTT4	14,434
L60TCTT4BW	14,434
Latest address of error history (UnG1279)	425
LED	320
Linear	213,414
Loop disconnection detection	208
Loops	130
Lower limit deviation alert	164

M

MAN mode shift completion flag (UnG30)	352,377
Manipulated value (MV) and control output cycle	349
Manual control	143,370,371
Manual reset	133,141
MELSEC-Q series	428
Memory's PID constants read/write completion flag (UnG31)	353
Mix control (expanded mode)	130,131

Mix control (normal mode)	130
Mode shifting	334
Module error history	246
Module joint levers	30
Module READY flag (Xn0)	322,333
Module selection	109
Module's detailed information	331
Monitoring the scaling value	228
Mount position	109
Moving averaging process setting	110,111
Moving averaging process to a temperature process value (PV)	227

N

New module	109
Normal mode	35
Normal sensor correction (one-point correction) function	230,423
Number of accesses to non-volatile memory	33
Number of alert delay	173
Number of alert delay (UnG165)	388
Number of connectable modules	84
Number of loops	14
Number of occupied I/O points	34
Number of parameters	35
Number of temperature input points	33

O

Offset	26
Offset (remaining deviation)	141
ON delay output	178
ON delay output flag	351,391
ON/OFF timing for CH□ Automatic backup setting after auto tuning of PID constants (UnG63, UnG95, UnG127, UnG159)	354
Operation at sensor input disconnection	33
Operation method and formula	24
Operation mode (in operation)	334
Operation of the simultaneous temperature rise function	195
Operation on completion of auto tuning	155
Operation with starting ST	182
Operation with vibration ST	184
Outline dimensions	34
Output off-time current error detection	226
Output Setting at CPU Stop Error	132
Output setting at CPU stop error	111
Output signal	340
Output signal list	44
Overlap	215

P

P control	135,141,366
Package	15
Parameter setting	112
Part names	30
PD control	137,141
Peak current suppression	189
Peak current suppression control group setting (UnG784)	197,422
Performance specifications	33

PI control	136,366
PID action	29
PID auto-correction status	409
PID constant range	33
PID constants	14
PID continuation flag (Un\G169)	132,390
PID control	137
Platinum resistance thermometer type	359
Primary delay digital filter	122
Procedure before operation	81
Procedure for the self-tuning control	181
Procedure of auto tuning	148
Process alarm	124
Processing of the error history function	244
Product information	331
Program compatibility	429
Programming procedure	257
Programming tool	14
Proportional action	365
Proportional action (P-action)	26
Proportional band setting	212
Proportional gain	26,365

Q

Q64TCRTBWN	428
Q64TCRTN	428
Q64TCTTBWN	428
Q64TCTTN	428

R

R1.25-3	87
Ramp action	14,417
Rate alarm	126
Removal and installation of the terminal block	93
Resolution	37,355,360
Resolution of the manipulated value for output with another analog module(Un\G181)	393
Reverse action	25,207
RFB limiter function	175
RUN LED	30,320

S

Sampling cycle	33,39,108,121
Sampling cycle monitor (Un\G788)	424
Sampling cycle selection	110,111
Self-tuning	179
Self-tuning disable status	409
Self-tuning error	410
Sensor correction function	230
Sensor correction function selection (UnG785)	423
Sensor correction value setting	33
Sensor two-point correction function	234,423
Serial number plate	31
Serial number	426
Set value (SV) and the setting change rate limiter setting	162
Set value (SV) setting range	33
Set value backup instruction (Yn8)	342
Setting change completion flag (XnB)	338
Setting change instruction (YnB)	342
Setting change rate limiter setting	111,159,424

Setting item reduction mode	35,116
Setting manipulated value (MV) in MAN mode	352
Setting mode (after operation)	334
Setting mode at power-ON	334
Setting value change screen list	250
Setting/operation mode instruction (Yn1)	338,340
Setting/operation mode status (Xn1)	334
Signal names of terminal blocks	88
Simple two-degree-of-freedom	23,157
Simultaneous temperature rise	194
Simultaneous temperature rise AT	198
Simultaneous temperature rise AT disable status	407
Simultaneous temperature rise parameter	197,408,410
Simultaneous temperature rise parameter correction status	409
Simultaneous temperature rise parameter error status	410
Solderless terminal	87
Standard control	130
Standard mode	394
Starting ST	408
Switch setting	110
System configuration	83

T

Temperature	121
Temperature control method	33
Temperature control mode	13,14,129
Temperature control modules	428
Temperature conversion	218
Temperature conversion completion flag (Un\G786)	423
Temperature conversion method	121
Temperature input mode	13,14,120
Temperature judgment	347
Temperature measurement range	37,346
Temperature process value (PV) scaling	228
Temperature rise completion range setting (Un\G167)	350,389
Temperature rise completion soak time setting (Un\G168)	350,390
Temperature sensor	14,355
Temperature unit	355
Terminal	31
Terminal block	87
Terminal block for CT	31,92
Terminal block for I/O	31,88,90
Terminal block mounting screw	87
Terminal screw	87
Terms	14
The condition to be able to perform PID control	138
The simultaneous temperature rise parameter setting using self-tuning	201
Thermocouple type	356
Thermocouple wiring resistance value	324
Three-phase heater	107
Three-position control	217
Tightening torque range	87
Time constant	122
Title setting	109
To clear the disconnection detection status	225

To forcibly start up self-tuning	188
Transistor output	33
Transistor output monitor ON delay time setting (Un\G175)	351,391
Troubleshooting	318
Troubleshooting by symptom	324
Two-position control	133,364,370,371
Type of usable temperature sensors	37

U

Unused channel	337
Unused channel setting	108
Upper limit deviation alert	163
Upper lower limit deviation alert	164

V

Vibration ST	408

W

Watchdog timer error	333
Water cooled	213
Water cooling	414
Weight	34
When AUTO mode is shifted to MAN mode	376
When measured value exceeds temperature measurement range	348
When measured value falls below temperature measurement range	348
When the auto tuning does not complete	323
When the auto tuning does not start	322
When the self-tuning does not start	323
When the temperature process value (PV) is abnormal	324
When using the L60TC4 as a temperature input module	110
Wire	87
Wiring	94,95
Within-range alert	165

REVISIONS

*The manual number is given on the bottom left of the back cover.

Print date	*Manual number	Revision
July, 2011	SH(NA)-081000ENG-A	First edition
August, 2014	SH(NA)-081000ENG-B	Revision due to the following: • changes of the setting method when using CTL-12-S36-10 or CTL-12-S56-10 as a current sensor (CT) • addition of the setting item reduction mode of auto refresh • additional function of moving averaging process to a temperature process value (PV) • changes of the switch setting window and parameter setting window of GX Works2 • addition of the during AT loop disconnection detection function • changes of the parameter setting window of GX Works2

Japanese manual version SH-080999-F

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- (2) Product supply (including repair parts) is not available after production is discontinued.

3. Overseas service

Overseas, repairs shall be accepted by Mitsubishi's local overseas FA Center. Note that the repair conditions at each FA Center may differ.

4. Exclusion of loss in opportunity and secondary loss from warranty liability

Regardless of the gratis warranty term, Mitsubishi shall not be liable for compensation of damages caused by any cause found not to be the responsibility of Mitsubishi, loss in opportunity, lost profits incurred to the user by Failures of Mitsubishi products, special damages and secondary damages whether foreseeable or not, compensation for accidents, and compensation for damages to products other than Mitsubishi products, replacement by the user, maintenance of on-site equipment, start-up test run and other tasks.

5. Changes in product specifications

The specifications given in the catalogs, manuals or technical documents are subject to change without prior notice.

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MELSEC-L Temperature Control Module

User's Manual

MODEL	L60TCTT4/RT4-U-E
MODEL CODE	13JZ64
SH(NA)-081000ENG-B(1408)MEE	



HEAD OFFICE : TOKYO BUILDING, 2-7-3 MARUNOUCHI, CHIYODA-KU, TOKYO 100-8310, JAPAN
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