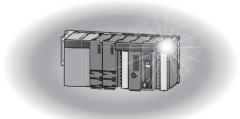


# Mitsubishi Programmable Controller



Energy Measuring Module User's Manual (Details)

QE84WH





(Read these precautions before using this product.)

This manual contains important instructions for MELSEC-Q series QE84WH.

Before using this product, please read this manual and the relevant manuals carefully and pay full attention to safety to handle the product correctly.

The precautions given in this manual are concerned with this product only. For the safety precautions of the programmable controller system, refer to the user's manual of the CPU module used.

In this manual, the safety precautions are classified into two levels: "DANGER" and "CAUTION".



Indicates that incorrect handling may cause hazardous conditions, resulting in death or severe injury.



Indicates that incorrect handling may cause hazardous conditions, resulting in medium or slight personal injury or physical damage.

Under some circumstances, failure to observe the precautions given under " CAUTION" may lead to serious consequences.

Observe the precautions of both levels because they are important for personal and system safety.

Keep this manual in an accessible place for future reference whenever needed, and make sure it is delivered to the end user.

# [Precautions for Operating Environment and Conditions]

# ∕<u>!</u>Caution

- Do not use this product in the places listed below. Failure to follow the instruction may cause malfunctions or decrease of product-life.
  - Places the Ambient temperature exceeds the range 0 °C to +55 °C.
  - Places the Relative humidity exceeds the range 5 % to 95 % or condensation is observed.
  - Altitude exceeds 2000 m.
  - Places exposed to rain or water drop.
  - Dust, corrosive gas, saline and oil smoke exist.
  - Vibration and impact exceed the specifications.
  - Installation on excluding the control board

# [Design Precautions]

# Danger

• Do not write data into "System Area" in the buffer memory of the intelligent function module.

Also, do not output (turn ON) the "use prohibited" signal in the output signal sent from the sequencer CPU to the intelligent function module.

Doing so may cause a malfunction to the sequencer system.

# **!**Caution

Do not install the input signal wire together with the main circuit lines or power cables. Keep a distance as below. (Except for the terminal input part) Failure to do so may result in malfunction due to noise.

Conditions	Distance
Below 600 V, or 600 A power lines	300 mm or more
Other power lines	600 mm or more

## [Installation Precautions]

# **!** Caution

- Any person who is involved in the installation and the wiring of this Sequencer should be fully competent to do the work.
- Use the programmable controller in an environment that meets the general specifications in the User's manual of the CPU module used.
  - Failure to do so may result in electric shock, fire, malfunction, or damage to or deterioration of the product.
- To mount the module, while pressing the module-mounting lever located in the lower part of the module, fully insert the module fixing projection(s) into the hole(s) in the base unit and press the module until it snaps into place.
  - Incorrect mounting may cause a malfunction, failure or a fall of the module.
  - When using the Sequencer in an environment of frequent vibrations, fix the module with a screw.
- Tighten the screws within the specified torque range.
  - Fixing-Module screw (arranged by user): M3 x 12 mm
  - Tightening torque of the fixing-module screws 0.36 N•m to 0.48 N•m
  - When the screw tightening is loose, it causes a fall, short-circuit, and a malfunction.
  - Over-tightening can damage the screws and the module, and it may cause a fall, short-circuit, or a malfunction.
- Shut off the external power supply for the system in all phases before mounting or removing the module. Failure to do so may result in damage to the product.
- Do not touch directly any conductive parts and electronic parts of the module.
  - Doing so can cause a malfunction or failure of the module.

# [Wiring Precautions]

# Danger

• For installation and wiring works, make sure that the power source is shut off for all outside phases. If all phases are not turned off, it may cause an electric shock or product damages.

# 

- FG terminal must be grounded according to the D-type ground (Type 3) dedicated for sequencer. Failure to do so may result in electric shock or malfunction.
- When using this product, make sure to use it in combination with current sensor (EMU-CT\*\*\*, EMU-CT\*\*\*-A or EMU2-CT5). Please not to exceed the ratings of this product for input of current sensor. For further details, please refer to current sensor manual to maintain the functionality and the accuracy of this product.
- Current sensor (EMU-CT\*\*\*, EMU-CT\*\*\*-A (Excluding EMU-CT5-A)) is used only for low voltage circuit. It cannot be used with a high voltage circuit. Also, EMU2-CT5 and EMU-CT5-A should be used with the secondary side (5 A) of transformer transfixed. If it is connected with a high-voltage circuit by mistake, it may cause a burnout of the device and a fire. It is critically dangerous. For the Allowable maximum voltage, refer to Appendix 2 "Optional devices".
- Current sensor has a polarity (directionality). Be careful about it when installing the module.
- Do not open the secondary side of current sensor.
- Take care not entering any foreign objects such as chips and wire pieces into the module. It may cause
  a fire, failure or a malfunction.
- In order to prevent the module from incoming foreign objects such as wire pieces during wiring work, a
  foreign-object preventive label is placed on the module. While a wiring work is performed, keep the
  label on the module. Before operating the system, peel off the label for heat release. If the
  foreign-object preventive label is not peeled and the system is in use, residual heat inside the module
  may reduce the product life.
- The wires to be connected to the module shall be put in a duct or fixed together by clamp. If not, the loosing and unstable wire or careless stretching results in poor contact of electric wires. That may cause a breakage of the module or wire or a malfunction.
- After wiring, confirm whether there is a wiring forgetting or a faulty wiring. They may cause a device malfunction, a fire, or an electric shock.
- If the wires connected to the module are strongly pulled off, it may cause a malfunction or a breakage to the module or the wire. (Tensile load: 22 N or less)
- Ensure the wiring to the module properly, checking the rated voltage and current of the product and the terminal pin assignment. If the input voltage exceed the rated voltage or the wiring is improper, it may cause a fire or a breakage.
- Do not exceed the specified voltage when doing an insulation resistance test and a commercial frequency withstand voltage test.
- To protect persons who do not have adequate knowledge of electric equipment from elevtric shocks, any of the following measures should be taken for the panel.
  - (a) To lock the panel so that only trained persons having adequate knowledge of electric equipment can open it.
  - (b) To design the structure so that the power is automatically interrupted upon opening of the panel. The protection class of the panel should be IP2X or higher.
- Terminal screws must be tightened to the specified torque.
  - Loose terminal screws may cause a short circuit or malfunction.
  - If terminal screws are over-tightened, the screws or the module may be damaged, causing a short circuit or malfunction.
  - For specified torque, refer to Section 8.1 Precautions for handling.
- Use an applicable solderless terminal for the current input line and tighten it to the specified torque.
   If a spade terminal is used, it may fall, causing a breakage of the module when the terminal screw is loosened.
- Use appropriate size of electric wires. If inappropriate size of electric wire is used, it may cause a fire
  due to generated heat. For appropriate size of electric wires, refer to Section 8.5.2 How to connect
  wires.
- In case using stranded wire, take measures so that the filament should not vary by processing the point twisted.
- To prevent persons with little knowledge about electric equipment from electric shock, panel must be
  taken either following measure. Lock the panel so that only those who get an education about electric
  equipment and have sufficient knowledge can unlock, or shut off power supply automatically by
  opening the panel. Cover the dangerous part of this unit.

# [Start-up Precautions]

# **!** Caution

- Use the product within the ratings specified in this manual. When using it outside the ratings, it not only causes a malfunction or failure but also there is a fear of igniting and damaging by a fire.
- Before operating the product, check that active bare wire and so on does not exist around the
  product. If any bare wire exists, stop the operation immediately, and take an appropriate action
  such as isolation protection.
- Do not disassemble or modify the module. It may cause failure, a malfunction, an injury or a fire.
- Attaching and detaching the module must be performed after the power source is shut off for all
  outside phases. If not all phases are shut off, it may cause failure or a malfunction of the module.
- Do not touch the live terminal. It may cause a malfunction.

# [Maintenance Precautions]

# **!** Caution

- Cleaning and additional tightening of screws must be performed after the input power source is shut off for all outside phases. If not all phases are shut off, it may cause failure or a malfunction of the module
- Use a soft dry cloth to clean off dirt of the module surface.
- Do not let a chemical cloth remain on the surface for an extended period nor wipe the surface with thinner or benzene.
  - Check for the following items for using this product properly for long time.
  - <Daily maintenance>
  - (1) No damage on this product (2) No abnormality with LED indicators (3) No abnormal noise, smell or heat.
  - <Periodical maintenance> (Once every 6 months to 1 year)
  - (4) Confirm there is loosing in installation, wire connection to terminal blocks, and the connection of the connectors. (Check these items under the power failure condition.)

# [Storage Precautions]

# **!** Caution

- To store this product, turn off the power and remove wires, and put it in a plastic bag.
  - For long-time storage, avoid the following places. Failure to follow the instruction may cause a failure and reduced life of the product.
    - Places the Ambient temperature exceeds the range -25  $^{\circ}$ C to +75  $^{\circ}$ C.
    - Places the Relative humidity exceeds the range 5 % to 95 % or condensation is observed.
    - Dust, corrosive gas, saline and oil smoke exist, and vibration and frequent physical impact occur.
    - Places exposed to rain or water drop.

# [Disposal Precautions]

# **!** Caution

• Dispose of the product as an industrial waste.

## Revision history

\* Instruction Manual Number is provided at the bottom of the cover page.

Driptod data	*Instruction Manual #	Instruction Manual Number is provided at the bottom of the cover page
Printed date	*Instruction Manual #	Description of revisions
July, 2012	IB-63720	First edition
Jan, 2016	IB63720A	Correction
		Cover Section 2.1, Section 6.1, Section 6.2.12, Section 9.1, Section
		9.2.1, Section 9.2.2, Section 9.3.1, Section 9.3.2, Appendix-2
		Back cover
Jul, 2017	IB63720B	Correction
		SAFETY PRECAUTIONS,
		Compliance with the EMC and Low Voltage Directives,
		Section 2.1, Chapter 3, Chapter 4, Section 6.2,
		Section 6.3, Section 7.2, Section 7.7, Section 7.8, Section 7.9,
		Section 8.2, Section 8.5, Section 8.6, Chapter 9, Section 10.2,
		Section 10.3, Appendix 2, Back cover
Jan, 2021	IB63720C	Correction
		Compliance with the EMC and Low Voltage Directives,
		Section 3.2, Back cover
Dec, 2021	IB63720D	Correction
		Precautions for Operating Environment and Conditions,
		Installation Precautions, Storage Precautions,
		Compliance with the EMC and Low Voltage Directives,
		Section 3.1, Section 3.2, Section 4.2, Section 6.1, Section 6.2,
		Section 7.4, Section 7.8, Section 8.1, Section 8.4, Section 8.5,
		Section 8.6, Appendix 2, Back cover

This manual does not guarantee to protect or does not give permission to any industrial property and any related rights. Also, our company shall not be held any responsible for any issues related to industrial properties due to product usage described in this manual.

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#### Compliance with the EMC and Low Voltage Directives

#### (1) For programmable controller system

To configure a system meeting the requirements of the EMC and Low Voltage Directives when incorporating the Mitsubishi programmable controller (EMC and Low Voltage Directives compliant) into other machinery or equipment, refer to QCPU User's Manual (Hardware Design, Maintenance and Inspection).

The CE mark, indicating compliance with the EMC and Low Voltage Directives, is printed on the rating plate of the programmable controller.

### (2) For the product

For the compliance of this product with the EMC and Low Voltage Directives, refer to Section 8.5 Wiring.

In addition, attach ferrite cores to power line of power supply module.

Ferrite cores used in our testing is below.

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#### (3) CE marking conformity combination module

This module conforms to CE marking standard in a condition to make combination use with following current censor and cable.

(a)Current input

current censor	EMU-CT50, EMU-CT100, EMU-CT250, EMU-CT400,EMU-CT600, EMU-CT400-A, EMU-CT600-A	EMU2-CT5
cable or current censor cable	CE marking cable (twisted pair cable) Stranded wire: AWG22 to AWG18 (0.4 mm² to 0.8 mm²) Tightening torque: 0.6 N·m to 0.85 N·m Solderless terminal: R1.25-3 (No solderless terminal with insulation sleeve can be used.)	EMU2-CB-Q5B(indispensable) EMU2-CB-T1M, EMU2-CB-T5M EMU2-CB-T10M, EMU2-CB-T1MS EMU2-CB-T5MS, EMU2-CB-T10MS
Max. cable length	50 m	11 m(EMU2-CT5 include)

(b)Voltage input

cable	CE marking cable (twisted pair cable)	
	Single wire:	
	AWG24 to AWG12 (φ0.5 mm to 2.0 mm)	Tightening torque: 0.5 N·m to 0.6 N·m
	Stranded wire:	
	AWG24 to AWG12 (0.2 mm <sup>2</sup> to 3.3 mm <sup>2</sup> )	Tightening torque: 0.5 N·m to 0.6 N·m
Max. cable length	50 ı	m

## Product configuration

The following describes the product configuration.

Model name	Product name	Quantity
050444	Energy Measuring Module	1
QE84WH	Voltage input terminals	1

Note			

### Chapter 1: Overview

This manual explains specifications, handling methods, and programming of Energy Measuring Module QE84WH (hereinafter, abbreviated as QE84WH) supporting MELSEC-Q series.

#### 1.1 Features

(1) This Energy Measuring Module can measure four channels of various types of electric quantity.

It can measure four channels of electric energy, reactive energy, current, voltage, electric power, reactive power, power factor, and frequency.

Both consumption and regeneration of the electric energy can be measured.

(2) Extensive monitoring functions

In addition to memorizing the maximum and minimum values, two types of alarm monitoring for upper and lower limit can be performed for each channel.

(3) It also can measure the electric energy for a certain period.

It can measure the electric energy for the duration of time for which the output device is on.

This feature enables to acquire the electric energy needed during device operation or energy per tact.

(4) Equipped with the current measuring mode where eight channels of current can be measured.

By selecting the current measuring mode using the intelligent function module switch, you can measure only the current through eight channels.

Note that the input/output signals and buffer memory to be used in the current measuring mode are different from those used in the regular operation mode. For details, refer to Chapter 7.

## Chapter 2: System Configuration

#### 2.1 Applicable system

The following describes applicable systems.

(1) Applicable module and the quantity of attachable pieces(a)When mounted with CPU module

CPU module to which QE84WH can be attached and the number of attachable pieces are shown below.

Depending on the combination of the attached module and the number of attached pieces, lack of power capacity may occur.

When attaching the module, please consider the power capacity.

If the power capacity is insufficient, reconsider the combination of modules to be attached.

Since the number of attachable modules are limited by the power module which used, please refer to the notes on the 2.2 precautions for system configuration.

used, please refer to the notes on the 2.2 precautions for system configuration.					
Attachable CPU Module Attachable Remarks					
CPL	Ј Туре	CPU Model	quantity.		
	Basic model QCPU	Q00JCPU	8		
		Q00CPU	24		
	QCFU	Q01CPU	24		
		Q02CPU			
	High porformance	Q02HCPU			
	High performance model QCPU	Q06HCPU	64		
	Iniodel QCFU	Q12HCPU			
		Q25HCPU			
		Q02PHCPU			
	Process CPU	Q06PHCPU	64		
	Process CPU	Q12PHCPU	64		
		Q25PHCPU			
	Redundant CPU	Q12PRHCPU	53		
		Q25PRHCPU	55		
	Universal model QCPU	Q00UJCPU	8		
Programmable		Q00UCPU	24		
controller		Q01UCPU			
CPU		Q02UCPU	36		
		Q03UDCPU			
		Q04UDHCPU			
		Q06UDHCPU			
		Q10UDHCPU			
		Q13UDHCPU			
		Q20UDHCPU			
		Q26UDHCPU	-		
		Q03UDECPU	64		
		Q04UDEHCPU	-		
		Q06UDEHCPU			
		Q10UDEHCPU	-		
		Q13UDEHCPU			
		Q20UDEHCPU	-		
		Q26UDEHCPU	-		
		Q50UDEHCPU	4		
		Q100UDEHCPU			

Attachable CPU Module			Attachable	Remarks
CPU	Туре	CPU Model	quantity.	
		Q03UDVCPU		
		Q04UDVCPU		
		Q06UDVCPU		
Programmable	High-speed	Q13UDVCPU		
controller	Universal model QCPU	Q26UDVCPU	64	
CPU		Q04UDPVCPU		
		Q06UDPVCPU		
		Q13UDPVCPU		
		Q26UDPVCPU		
		Q06CCPU-V		
C Controller module		Q06CCPU-V-B		
		Q12DCCPU-V	64	
		Q24DHCCPU-LS	04	
		Q24DHCCPU-V		
		Q26DHCCPU-LS		

#### (b) When mounted with MELSECNET/H remote I/O station

The table below shows the network modules applicable to the QE84WH and the number of network modules to be mounted.

Depending on the combination with other modules or the number of mounted modules, power supply capacity may be insufficient.

Pay attention to the power supply capacity before mounting modules, and if the power supply capacity is insufficient, change the combination of the modules.

Applicable Network Module	Number of modules	Remarks
QJ72LP25-25		
QJ72LP25G	64	
QJ72BR15		

#### (c) Attachable base unit

QE84WH can be attached to any I/O slot of the basic base unit and expansion base unit (\*1) (\*2).

- \*1 In the case of dual CPU, it can be attached only to an expansion base unit. It cannot be attached to the base unit.
- \*2 It has to be within the range of I/O slots of the CPU module.

#### (2) For multiple CPU system

The function version of the first released CT input module is C, and the CT input module supports multiple CPU systems.

When using the CT input module in a multiple CPU system, refer to the following. \*QCPU User's Manual ( Multiple CPU system )

(3) Applicable software package

QE84WH supported software packages are as follows:

(a) Software package for sequencer

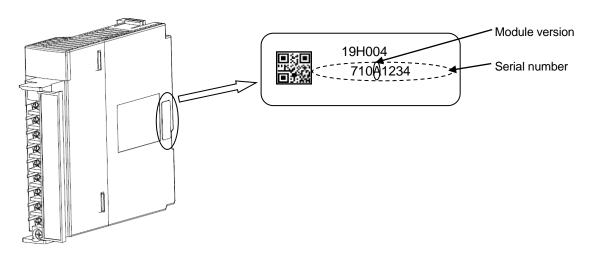
Product name	Model name	Remarks	
GX Works2	SW1DNC-GXW2	iQ Platform compatible programmable	
GA WOIKSZ	SWIDING-GAWZ	controller engineering software	
CV Davolanar	SWnD5C-GPPW	MELSEC sequencer programming software	
GV Developel	SWIIDSC-GPPW	"n" in the model name is 4 or larger.	

### 2.2 Precautions for system configuration

(1) When attaching it to an expansion base without a power module If QE84WH is attached to an expansion base without a power module, refer to the user's manual of the sequencer CPU to be used in order to select the power module and expansion cable.

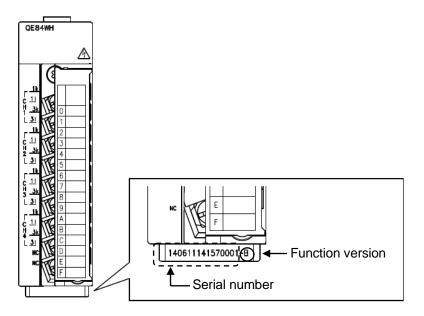
### 2.3 How to check the function version, serial number, and module version

(1) How to check the module version It can be checked with the serial number label (placed on the right side of QE84WH).

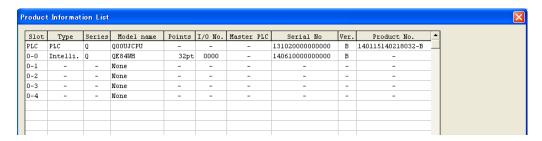


- (2) How to check the function version and serial number
  - (a) Checking on the front of the module

The serial number and function version on the rating plate is shown on the front (at the bottom) of the module.



(b) Checking on the System monitor dialog box (Product Information List)
To display the system monitor, select [Diagnostics] → [System monitor] and click the Product Information List button of GX Developer.



#### **Point**

The serial number displayed on the Product Information List dialog box of GX Developer may differ from that on the rating plate and on the front of the module.

- The serial number on the rating plate and front part of the module indicates the management information of the product.
- The serial number displayed on the Product Information List dialog box of GX Developer indicates the function information of the product.

The function information of the product is updated when a new function is added.

### Chapter 3: Specifications

#### 3.1 General specifications

	Ite	m	Specifications		
	Phase wir	e system	single-phase 2-wire / single-phase 3-wire / three-phase 3-wire		
Rating	Voltage circuit *1	single-phase 2-wire, three-phase 3-wire	100 V to 220 V AC		
		single-phase 3-wire	110 V AC (1 - 2 line, 2 - 3 line) 220 V AC (1 - 3 line)		
Current circuit			50 A, 100 A, 250 A, 400 A, 600 A AC  (Current sensor is used. Each value refers to the current at the primary side of current sensor.)  5 AAC  (Current sensor is used together with current transformer (CT), and the primary-side current is configurable up to 6000 A.) *2		
	Frequenc	СУ	50Hz to 60 Hz		
Allowable tolerance of main module (excluding current sensor) *3		ensor) * <sup>3</sup>	Current, current demand *4 : $\pm 1.0$ % (100 % of the rating)  Voltage : $\pm 1.0$ % (100 % of the rating)  Electric power, electric power demand *4 : $\pm 1.0$ % (100 % of the rating)  Reactive power : $\pm 1.0$ % (100 % of the rating)  Frequency : $\pm 1.0$ % (45 Hz to 65 Hz range of the rating)  Power factor : $\pm 3.0$ % (against the electric angle 90°)  Electric energy : $\pm 2.0$ % (5 % to 100 % range of the rating, power factor = 1)  Reactive energy : $\pm 2.5$ % (10 % to 100 % range of the rating, power factor = 0)		
Measura	ble circuit c	ount	4 circuits (4 channels) under the same voltage system, or 8 circuits (8 channels) in the current measuring mode		
	Data update cycle		500 ms *5 (100 ms in the current measuring mode)		
Response time			2 seconds or less		
Backup for electric blackout			Backup is made using nonvolatile memory.  (Stored items: settings, the max./min. values and time of occurrence, electric energy (consumption, regenerated), reactive energy (consumption lag), and periodic electric energy)		
I/O occupation			32 points (I/O assignment: intelligence 32 points)		

- \* 1 : 100 V to 220V AC direct connection is possible. For the circuit over this voltage, transformer (VT) is necessary (Primary voltage of VT can be set up to 6600 V, and secondary voltage of VT can be set up to 220 V as optional setting). Star delta connection and delta star connection transformer instead of VT cannot measure definitely to be out of phase. Please use a transformer of the same connection.
- \* 2 : 5 A primary current can be set when using the current sensor is as follows.
  5A, 6A, 7.5A, 8A, 10A, 12A, 15A, 20A, 25A, 30A, 40A, 50A, 60A, 75A, 80A, 100A, 120A, 150A, 200A, 250A, 300A, 400A, 500A, 600A, 750A, 800A, 1000A, 1200A, 1500A, 1600A, 2000A, 2500A, 3000A, 4000A, 5000A, 6000A (Primary current of CT can be set up to 6000A in any . However, secondary current of CT can not be set to other than 5A).
- \* 3 : The ratio error of the current sensor : ±1.0 %.(5 % to 100 % range of the rating)
- \* 4 : Demand shows the moving average of a set period.
- \* 5 : Always accumulating the integrated values of Wh and varh. It can capture short-cycled load fluctuation (500 ms or shorter).

### 3.2 Electrical and mechanical specifications

Item		Specifications							
Consumed V	Each phase 0.1 VA (at 110 V AC), Each phase 0.2 VA (at 220 V AC)								
	circuit			`	,,	•		,	
	Current circuit	Each phase 0.1 VA (secondary side of current sensor)							
Internal curre	nt	0.46 A							
consumption	(5 V DC)								
Operating ter					aily temperatur	e +35 °C or b	elow)		
Operating hu		5 % to 95 %		No conde	ensation)				
Storage temp		-25 °C to +7							
Storage hum		5 % to 95 %		No cond	ensation)				
Operating alt		2000 m or b							
Installation a		Inside a con		anei					
Operating en Vibration res		No corrosive Conforms	gas		Frequency	Constant	Half		Sweep time
Vibration res	Starice	to JIS B			Frequency	acceleration	amplitud	0	Sweep time
		3502, IEC	Inter	mittent	5 Hz to 8.4 Hz	-	3.5 mm		XYZ
		61131-2	vibra		8.4 Hz to	9.8 m/s <sup>2</sup>	-		each
					150 Hz	0.011#0			direction 10
									times
			Cont	inuous	5 Hz to 8.4 Hz	-	1.75 mm	)	-
			vibra	ition	8.4 Hz to	4.9 m/s <sup>2</sup>	-		
			L		150 Hz				
Impact resist			JIS E	3502, II	EC 61131-2 (1	47m/s², XYZ e	each direc	ction (	3 times)
Over voltage	category *1		II or less						
Pollution deg		2 or less							
Equipment ca		Class I		111100	4.4. 414.0.4.0	T=: 1			
Applicable wire	Voltage input terminal	Single wire		AWG24 to AWG12 Tightening torque : 0.		5 N •	m to 0.6		
(Usable	terminai	Strandad wii	(φ0.5 mm to 2.0 mm) N · m tranded wire *4 AWG24 to AWG12						
electric		Stranded wii	<b>C</b>	(0.2 mm <sup>2</sup> to 3.3 mm <sup>2</sup> )					
wire)	Current input	Stranded win	e *5		2 to AWG18	Applicable s	Applicable solderless terminals :		inals ·
- /	terminal *3	Ciranaca wii	•	(0.4 mm <sup>2</sup> to 0.8 mm <sup>2</sup> )		R1.25-3 (No			
				(-	,	insulation sle			
						Tightening torque: 0.6 N • m to 0.85			m to 0.85
						N · m			
Tightening to	rque	Current input terminal block fixing 0.66 N · m to 0.89 N			• m				
		screws (M3.	5)						
			Module-fixing screws (M3 screw) *6 0.36 N · m to 0.48 N · m						
Commercial	frequency	Between voltage/current input terminals - FG terminal 2210 V AC					0 V AC		
withstand vol	tage	5 sec							
		Between voltage/current input terminals - sequencer power source and GND terminals 5 sec 2210 V AC							
Insulation resistance		5 MΩ or more (500 V DC) at locations above							
Standard*7		EMC: EN61131-2:2007, EN61326-1:2013							
					N61010-1:2010	)			
		UL Standard							
			c-UL Standards: CSA C22.2 No.142						
Dimonoiona		KC Marking 27.4 mm (W) x 98 mm (H) x 112 mm (D) excluding protruding portions							
Dimensions			) x 98	) (H)	x 11∠ mm (D)	excluding pro	uuuing po	ortion	S .
Mass		0.19 kg							

<sup>\*1.</sup> This indicates the assumed area of electric distribution to which the device is connected, the area ranging from public distribution to factory machinery. The category II applies to the device power-supplied from fixed facility. The surge voltage of this product is 2500 V up to the rated voltage of 300 V.

- \*2. The index indicates the level of conductive substance at the device's operating environment. Contamination level 2 means only non-conductive substance. However, occasional condensation may lead to temporary conduction.
- \*3. At the connection between the secondary terminal of current sensor (k, l) and the main module terminal (1k, 1l, 3k, 3l), use twisted pair cable.
- \*4. When using stranded wires for the voltage input terminals, strand the wire edges to prevent thin wires from loosening.
- \*5. When using stranded wires for the current input terminals, use applicable solderless terminals. If any spade solderless terminal is used, it may be disconnected when the terminal screw comes loose, resulting in failure. In addition, no solderless terminal with insulation sleeve can be used.
- \*6. The module can be fixed easily to the base unit, using the hook on top of the module. However, if it is used under a vibrating environment, we strongly recommend that the module be fixed with screws.
- \*7. When combine this unit with a CT (Model: EMU2-CT5, EMU-CT50, EMU-CT100, EMU-CT250, EMU-CT400-A, EMU-CT600-A), it becomes UL standard.

## Chapter 4: Functions

### 4.1 List of functions

Functions of QE84WH are provided in Table 4.1-1.

The "n" that is used in this and later chapters (for example: Xn0, Yn0, Un\G0, etc.) refers to the number that appears at the beginning of QE84WH.

Table 4.1-1 List of Functions

No.	Function	Descriptions	Reference
1	Measurement	It measures current, current demand, voltage, electric power, electric power demand, reactive power, power factor, frequency, electric energy (consumption, regeneration), and reactive energy (consumption lag) and sequentially stores the records into the buffer memory.	Section Section 4.2.1
2	Periodic electric energy	The electric energy only for a period of time when a certain output signal is ON will be stored in the buffer memory.  Periodic energy 1 and 2 can be measured independently.	Section 4.2.2
3	Hold max./min. values	For current demand, voltage, electric power demand, and power factor, each maximum/minimum values and date/time of occurrence are stored.	Section 4.2.3
4	Upper/lower limit alarm monitoring	Of current demand, voltage, electric power demand, and power factor, you can select two items for which their upper/lower limit can be monitored.  If it exceeds the upper limit or goes below the lower limit, the specified input signal is turned on.	Section 4.2.4
5	Test	Selecting the test mode using the intelligent function module switch enables pseudo-storage of the specified value into the buffer memory, even with non-existence of input from voltage and current (sensor).  Using this module, you can create a sequence, etc.	Section 4.2.5
6		Set the integrated value (electric energy (consumption, regeneration), reactive energy (consumption lag)) to an arbitrary value.  It is used to clear integrated value.	l
7	Current measuring mode function	By selecting the current measuring mode using the intelligent function module switch, you can measure eight channels of current and sequentially store the records into the buffer memory.	Chapter 7

### 4.2 Functions in detail

## 4.2.1 Measuring functions

## (1) Measured items

Measured items of each channel are described as follows:

Each measured item is stored in the buffer memory every 500 ms.

Each measured item is stored in the puller me  Measured ite	
	Details
Current	1 - phase current
	2 - phase current*1
	3 - phase current*1
	average current
Current demand	1 - phase current demand
* The average of fluctuation for the set period of	2 - phase current demand*1
current demand time is indicated.	3 - phase current demand*1
	Max. value
	Min. value
	Date of max. value occurrence
	Date of min. value occurrence
Voltage	1 - 2 line voltage (voltage V12)
	2 - 3 line voltage <sup>*1</sup> (voltage V23)
	3 - 1 line voltage*1 (voltage V31)
	average voltage
	Max. value
	Min. value
	Date/time of max. value occurrence
	Date/time of min. value occurrence
Electric power	Present value
Electric power demand	Present value
* The average of fluctuation for the set period of	Max. value
electric power demand time is indicated.	Min. value
	Date/time of max. value occurrence
	Date/time of min. value occurrence
Reactive power	Reactive power
Power factor	Present value
	Max. value
	Min. value
	Date/time of max. value occurrence
	Date/time of min. value occurrence
Frequency	Present value
Electric energy	Electric energy (consumption)
	Electric energy (regeneration)
Reactive energy	Reactive energy (consumption lag)
Periodic electric energy	Periodic electric energy 1
	Periodic electric energy 2

<sup>\*1:</sup> If phase wire system is set to single-phase 2-wire, measurement will not be taken.

## (2) Total, maximum, and minimum values

The following describes how to calculate the maximum, minimum, and total values.

Item	Phase wire system	Formula
Average	single-phase 2-wire	Average current = 1-phase current
current	single-phase 3-wire	Average current = (1-phase current + 3-phase current) / 2
	three-phase 3-wire	
Average	single-phase 2-wire	Average voltage = voltage V12
voltage	single-phase 3-wire	Average voltage = (voltage V12 + voltage V23) / 2
	three-phase 3-wire	
Maximum	single-phase 2-wire	Maximum value of 1-phase current demand
current		(The highest value after the max./min. value was reset.)
demand	single-phase 3-wire	Highest value of either 1-phase current demand or 3-phase current
		demand
		(The highest value after the max./min. value was reset.)
	three-phase 3-wire	Highest value among 1-phase current demand, 2-phase current
		demand, or 3-phase current demand
		(The highest value after the max./min. value was reset.)
Minimum	single-phase 2-wire	Minimum value of 1-phase current demand
current		(The lowest value after the max./min. value was reset.)
demand	single-phase 3-wire	Lowest value of either 1-phase current demand or 3-phase current
		demand
		(The lowest value after the max./min. value was reset.)
	three-phase 3-wire	Lowest value among 1-phase current demand, 2-phase current
		demand, or 3-phase current demand
		(The lowest value after the max./min. value was reset.)
Maximum	single-phase 2-wire	Highest value of the 1 - 2 line voltage
voltage		(The highest value after the max./min. value was reset.)
	single-phase 3-wire	Highest value of either the 1 - 2 line voltage or the 2 - 3 line voltage
		(The highest value after the max./min. value was reset.)
	three-phase 3-wire	Highest value among the 1 - 2 line voltage, the 2 - 3 line voltage, or 3
		- 1 line voltage
		(The highest value after the max./min. value was reset.)
Minimum	single-phase 2-wire	Lowest value of the 1 - 2 line voltage
voltage		(The lowest value after the max./min. value was reset.)
	single-phase 3-wire	Lowest value of either the 1 - 2 line voltage or the 2 - 3 line voltage
		(The lowest value after the max./min. value was reset.)
	three-phase 3-wire	Lowest value among the 1 - 2 line voltage, the 2 - 3 line voltage, or 3
		- 1 line voltage
		(The lowest value after the max./min. value was reset.)

#### (3) Resolution of measured data

Resolution of measured data according to the rating (phase wire system, primary voltage, and primary current) is described as follows.

#### 1) Current, current demand

Rated primary current setting	Multiplier	Resolution	*
5 A to 30 A	-3	2 digits after the decimal point	0.01 A
40 A to 300 A	-3	1 digit after the decimal point	0.1 A
400 A to 3000 A	-3	Integer	1 A
4000 A to 6000 A	-3	×10	10 A

<sup>\*</sup> Digits lower than the resolution are fixed to 0.

#### 2) Voltage

Rated primary voltage setting	Multiplier	Resolution*	
110 V to 220 V	-3	1 digit after the decimal point	0.1 V
440 V to 2200 V	-3	Integer	1 V
3300 V to 6600 V	-3	×10	10 V

<sup>\*</sup> Digits lower than the resolution are fixed to 0.

### 3) Electric power, electric power demand, reactive power

Full load power W*1	Multiplier	Resolution*2*3	
I . W <12 kW	-3	3 digits after the decimal point	0.001 kW
II . 12 kW ≤ W < 120 kW	-3	2 digits after the decimal point	0.01 kW
III. 120 kW ≤ W < 1200 kW	-3	1 digit after the decimal point	0.1 kW
IV. 1200 kW ≤ W < 12000 kW	-3	Integer	1 kW
V.12000 kW ≤ W < 120000 kW	-3	×10	10 kW

<sup>\*1</sup> For calculating full load power W, refer to Table 4.2.1-1.

#### 4) Power factor

Power factor Multiplier Resolutio		n*	
All setting ranges	-3	1 digit after the decimal point	0.1 %

<sup>\*</sup> Digits lower than the resolution are fixed to 0.

## 5) Frequency

Frequency	Multiplier	Resolution*	
All setting ranges	-3	1 digit after the decimal point	0.1 Hz

<sup>\*</sup> Digits lower than the resolution are fixed to 0.

<sup>\*2</sup> Digits lower than the resolution are fixed to 0.

<sup>\*3</sup> In the case of reactive power, the unit will be kvar.

6) Electric energy, Reactive energy, periodic electric energy

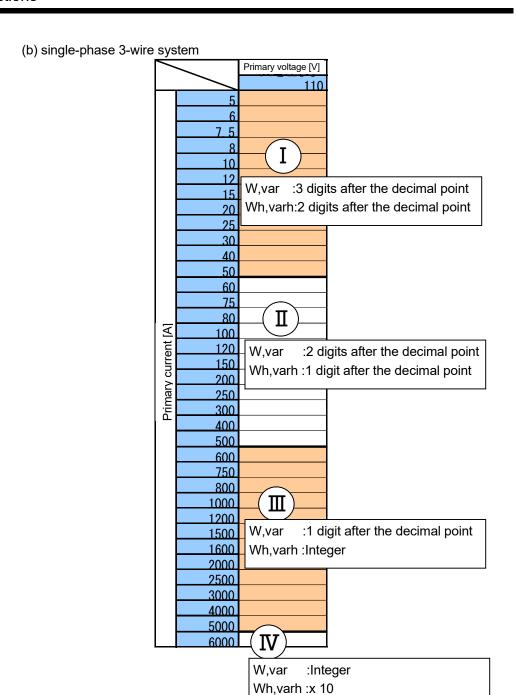
	Full load power W*1	Multiplier	Resolution*2		Range [kWh,kvarh]
Ι.	W < 12 kW	-5	5 digits after the decimal point	0.00001 kWh, kvarh	0.00001 to 9999.99999
Ι.	12kW ≤ W < 120 kW	-4	4 digits after the decimal point	0.0001 kWh, kvarh	0.0001 to 99999.9999
Ⅲ.	120kW ≤ W < 1200 kW	-3	3 digits after the decimal point	0.001 kWh, kvarh	0.001 to 999999.999
IV.	1200kW ≤ W < 12000 kW	-2	2 digits after the decimal point	0.01 kWh, kvarh	0.01 to 9999999.99
٧.	12000kW ≤ W < 120000 kW	-1	1 digit after the decimal point	0.1 kWh, kvarh	0.1 to 99999999.9

<sup>\*1</sup> For calculating full load power W, refer to Table 4.2.1-1.

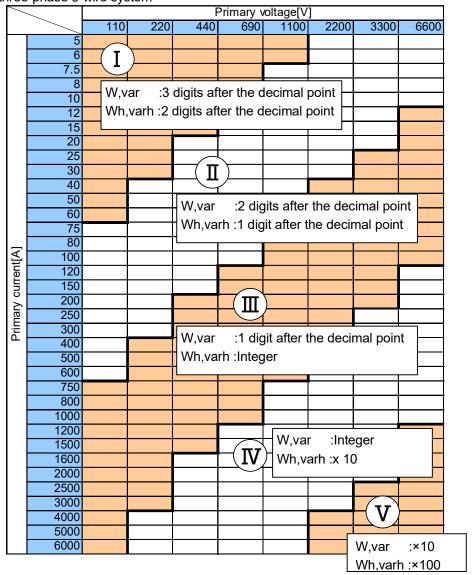
Table 4.2.1-1 How to calculate full load power

(a) single-phase 2-wire system Primary voltage [V] 110 220 690 1100 2200 3300 440 6600 5 6 5 W,var :3 digits after the decimal point 8 Wh,varh :2 digits after the decimal point 10 12 15 20 25 30 40 Π 50 60 75 W,var :2 digits after the decimal point 80 Wh,varh: 1 digit after the decimal point Primary current [A] 100 120 150  ${\rm I\hspace{-.1em}I\hspace{-.1em}I}$ 200 250 300 W,var : 1 digit after the decimal point 400 Wh,varh: Integer 500 600 750 IV 800 1000 W,var 1200 :Intege 1500 Wh,varh :×10 1600 2000 V 2500 3000 4000 W,var :×10 5000 Wh,varh :×100 6000

<sup>\*2</sup> Because the higher resolution than a typical watt-hour meter, the minimum digit values will change more than 2 at once update. According to setting value of input voltage, primary current, primary voltage of VT and the condition of load.



(c) three-phase 3-wire system



#### (4) Restrictions for measuring data

- Measurement cannot be performed immediately after the power loading to the sequencer system (Module ready signal is under the OFF condition).
  - After checking that Module ready (Xn0) is ON, obtain measuring data.
- Measurement cannot be performed immediately after operating conditions are set up to the module. After checking that Operating condition setting completion flag (Xn9) becomes ON, obtain measuring data.
- Behaviors during operation are as follows:

Measuring item	Behavior of the module			
Current	When the input current is less than 0.4 % of the rating current, it			
	becomes 0 A.			
Current demand	Current demand is obtained by current moving average.			
	Therefore, even if current is 0 A, current demand may not be 0 A.			
Voltage	When the input voltage is less than 10 % of the rating voltage, it			
	becomes 0 V.			
Electric power,	When current is 0 A (at all phases are 0 A) or when voltage is 0 V			
Reactive power	(all in-between wires are 0 V), it becomes 0 kW.			
Electric power demand	Electric power demand is obtained by electric power moving			
	average. Therefore, even if electric power is 0 kW, electric power			
	demand may not be 0 kW.			
Electric energy	The electric energy is measured with a load that is about 0.4 % or			
	more of all load power. Even if the indicated value is "0",			
	measurement value will increase.			
Power factor	When current is 0 A (at all phases are 0 A) or when voltage is 0 V			
	(all in-between wires are 0 V), it becomes 100 %.			
Frequency	Voltage condition			
	When the input voltage is less than 10 % of the rating voltage, it			
	becomes 0 Hz.			
	Frequency condition			
	When it is less than 44.5 Hz, it is fixed to 44.5 Hz.			

#### 4.2.2 Measuring function for periodic electric energy

This function is to measure electric energy for a certain period, and stores it into the buffer memory. It can be used to measure electric energy for a certain tact or energy (standby power) when the facility or equipment is not in operation.

#### (1) Overview

- 1) It can measure two periodic electric energy (periodic electric energy 1 and periodic electric energy 2) of each channel. Each of these can be measured independently.
- 2) During the time when Periodic electric energy 1 measurement flag/ Periodic electric energy 2 measurement flag is ON, periodic electric energy can be measured.
- 3) Periodic electric energy is stored in the nonvolatile memory, so that it can be retained even at a power source reset.
- 4) I/O signals and buffer memory corresponding to each periodic electric energy 1 and 2 are provided below.

		Buffer memory (Double words)	Periodic electric energy measurement flag	Periodic electric energy data completion flag	Periodic electric energy reset request	Periodic electric energy reset completion flag
CH1	Periodic electric energy 1	Un\G114, 115	Yn5	Xn5	Yn7	Xn7
	Periodic electric energy 2	Un\G116, 117	Yn6	Xn6	Yn8	Xn8
CH2	Periodic electric energy 1	Un\G1114, 1115	YnB	XnB	YnD	XnD
	Periodic electric energy 2	Un\G1116, 1117	YnC	XnC	YnE	XnE
СНЗ	Periodic electric energy 1	Un\G2114, 2115	Yn11	Xn11	Yn13	Xn13
	Periodic electric energy 2	Un\G2116, 2117	Yn12	Xn12	Yn14	Xn14
CH4	Periodic electric energy 1	Un\G3114, 3115	Yn17	Xn17	Yn19	Xn19
	Periodic electric energy 2	Un\G3116, 3117	Yn18	Xn18	Yn1A	Xn1A

Note

Measurement of periodic electric energy is performed every measuring cycle (500 ms). Therefore, if the time to turn ON the periodic electric energy measurement flag is set to 500 ms or less, measurement may not be taken.

#### (2) Basic procedure

- 1) Measuring periodic electric energy
- (a) Check that CH1 periodic electric energy 1 measurement flag (Yn5) is OFF.
- (b) Check CH1 periodic electric energy 1 (Un\G114, 115).
- (c) When starting measurement, set CH1 periodic electric energy 1 measurement flag (Yn5) to ON.
  - This module starts measuring the specified periodic electric energy, and CH1 periodic electric energy 1 data completion flag (Xn5) will be turned OFF
- (d) When stopping measurement, set CH1 periodic electric energy 1 measurement flag (Yn5) to OFF.
  - This module stops measuring the specified periodic electric energy, and CH1 periodic electric energy 1 data completion flag (Xn5) will be turned ON.
- (e) Check that CH1 periodic electric energy 1 data completion flag (Xn5) becomes ON, and obtain the value of periodic electric energy.

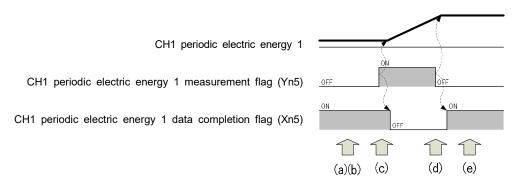


Figure 4.2.2-1 Basic procedure of measuring the periodic electric energy

- 2) Resetting periodic electric power
  - (a) Check that CH1 periodic electric energy 1 measurement flag (Yn5) is OFF and CH1 periodic electric energy 1 reset request (Yn7) is OFF.
  - (b) Set CH1 periodic electric energy 1 reset request (Yn7) to ON. The specified periodic electric energy is reset to 0 kWh, and CH1 periodic electric energy 1 reset completion flag (Xn7) will be turned ON.
  - (c) Check that CH1 periodic electric energy 1 reset completion flag (Xn7) has become ON, and then set CH1 periodic electric energy 1 reset request (Yn7) to OFF.
    CH1 periodic electric energy 1 reset completion flag (Xn7) will be turned OFF.

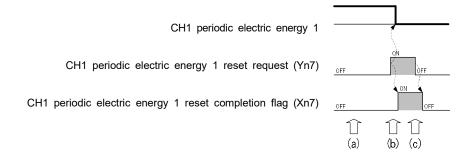


Figure 4.2.2-2 How to reset the periodic electric energy

- (3) Sample use case
  - 1) Procedure for continuously measuring periodic electric energy
    If you turn CH1 periodic electric energy 1 measurement flag to ON only for the extent of time
    you want to measure, this module accumulates the power starting at the previously
    measured amount. Usage procedure is the same as 1) in (2).

    An example is provided below.

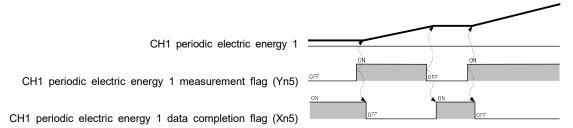


Figure 4.2.2-3 Example of continuous measurement of periodic electric energy

- 2) Procedure for measuring periodic electric energy after every reset

  If you turn Periodic electric energy measurement flag (Yn1/Yn2) to ON only for the extent of
  time you want to measure, this module accumulates the power starting at the previously
  measured amount. The following describes the usage procedure.
  - (a) Check that CH1 periodic electric energy 1 measurement flag (Yn5) is OFF and CH1 periodic electric energy 1 reset request (Yn7) is OFF.
  - (b) Set CH1 periodic electric energy 1 reset request (Yn7) to ON. The specified periodic electric energy is reset to 0 kWh, and CH1 periodic electric energy 1 reset completion flag (Xn7) will be turned ON.
  - (c) Check that CH1 periodic electric energy 1 reset completion flag (Xn7) has become ON, and then set CH1 periodic electric energy 1 reset request (Yn7) to OFF.
    CH1 periodic electric energy 1 reset completion flag (Xn7) will be turned OFF.
- (d) When starting measurement, set CH1 periodic electric energy 1 measurement flag (Yn5) to ON.
  - This module starts measuring the specified periodic electric energy, and CH1 periodic electric energy 1 data completion flag (Xn5) will be turned OFF.
- (e) When stopping measurement, set CH1 periodic electric energy 1 measurement flag (Yn5) to OFF.
  - This module stops measuring the specified periodic electric energy, and CH1 periodic electric energy 1 data completion flag (Xn5) will be turned ON.
- (f) Check that CH1 periodic electric energy 1 data completion flag (Xn5) becomes ON, and obtain the value of periodic electric energy.

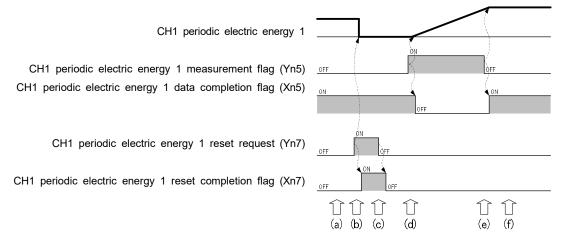


Figure 4.2.2-4 Example of measurement of periodic electric energy after every reset

#### 4.2.3 Max./min. value hold function

It memorizes the max./min. value for each measured item, and retains it until the max./min. value clear is performed.

- (1) Max./min. value memory
  - 1) It memorizes the max. and min. values of the following measured items of each channel.
    - Current demand
    - Voltage
    - Electric power demand
    - Power factor
  - 2) It memorizes the date and time of occurrence (year/month/day/hour/minute/second/day of the week) together with the max. and min. values.
  - 3) The max. and min. values and the date of occurrence are stored in the nonvolatile memory, so that these values can be retained even at a power source reset.
- (2) How to clear the max. and min. values
  - 1) You can use the I/O signal to clear the max. and min. values.
  - 2) The max. and min. values immediately after the clear will be the present values and the date of occurrence will be the present date and time.
  - 3) The following describes how to clear the max. and min. values.
    - (a) Check that Max./min. values clear request (Yn4) is OFF.
    - (b) In the max./min. value clear target (Un\G56), set the measured items of the channel you want to clear.
    - (c) Set Max./min. values clear request (Yn4) to ON. This module clears the max./min. values of the measured items of the channel you selected in step (b) above and their date of occurrence and turns Max./min. values clear completion flag (Xn4) to ON.
  - (d) Check that Max./min. values clear completion flag (Xn4) is ON, and then set Max./min. values clear request (Yn4) to OFF. Max./min. values clear completion flag (Xn4) will be turned OFF.



Figure 4.2.3-1 Procedure for clearing max./min. value

## 4.2.4 Upper/lower limit alarm monitoring function

You can set an upper and lower limit alarm for maximum two points for each channel and implement a monitoring function for them. During the alarm monitoring, it can monitor the input signal to check for the occurrence.

(1) Setting the upper/lower limit alarm monitoring

1) Setting items and setting range for the alarm monitoring are described below.

Items set in the buffer memory	Setting range	Description		
Alarm item	O: No monitoring 1: Current demand upper limit 2: Current demand lower limit 3: Voltage upper limit 4: Voltage lower limit 5: Power demand upper limit 6: Power demand lower limit 7: Power factor upper limit 8: Power factor lower limit	For respective alarm 1 and alarm 2, set the measuring item and either upper or lower limit for monitoring target.		
Alarm value	-2147483648 to 2147483647 [Unit] Current:×10 <sup>-3</sup> A Voltage:×10 <sup>-3</sup> V Power:×10 <sup>-3</sup> kW PF:×10 <sup>-3</sup> %	The value to be monitored for the alarm. Set the value according to the unit of the measuring item that is set as an alarm monitoring item.  (Double words)		
Alarm reset method	0: Self-retention 1: Auto reset	Set whether or not the alarm-occurrence condition should be retained if the value goes below the upper limit alarm value or goes over the lower limit alarm value after the upper/lower limit alarm occurred.		
Alarm delay time	0 to 300 [Unit] second	If it exceeds the upper limit alarm value or if it goes below the lower limit alarm value, and the situation continues for the period of the alarm delay time, then it is considered as an alarm occurrence.		

The table below shows I/O signals and buffer memory for alarm 1 and alarm 2.

		Alarm reset	Alarm flag	Buffer memory (Double words)			
		request		Alarm item	Alarm value	Alarm reset	Alarm delay
						method	time
CH1	Alarm 1	Yn9	Xn9	Un\G11	Un\G12, 13	Un\G14	Un\G15
	Alarm 2	YnA	XnA	Un\G21	Un\G22, 23	Un\G24	Un\G25
CH2	Alarm 1	YnF	XnF	Un\G1011	Un\G1012, 1013	Un\G1014	Un\G1015
	Alarm 2	Yn10	Xn10	Un\G1021	Un\G1022, 1023	Un\G1024	Un\G1025
CH3	Alarm 1	Yn15	Xn15	Un\G2011	Un\G2012, 2013	Un\G2014	Un\G2015
	Alarm 2	Yn16	Xn16	Un\G2021	Un\G2022, 2023	Un\G2024	Un\G2025
CH4	Alarm 1	Yn1B	Xn1B	Un\G3011	Un\G3012, 3013	Un\G3014	Un\G2015
	Alarm 2	Yn1C	Xn1C	Un\G3021	Un\G3022, 3023	Un\G3024	Un\G2025

- 2) Setting procedures are as follows:
  - (a) Check that Operating condition setting request (Yn2) is OFF.
  - (b) Set the alarm item, alarm value, alarm reset method, and alarm delay time in the buffer memory. For the address of buffer memory for alarm 1 and alarm 2, refer to Chapter 6.
  - (c) Set Operating condition setting request (Yn2) to ON. Operation starts at each set value, and then Operating condition setting completion flag (Xn2) is turned ON.
- (d) Check that Operating condition setting completion flag (Xn2) becomes ON, and then set Operating condition setting request (Yn2) to OFF. Operating condition setting completion flag (Xn2) will be turned OFF.



Figure 4.2.4-1 Time chart of alarm monitoring setting

- 3) Each item of the alarm monitoring is stored in the nonvolatile memory, so that values can be retained even at a power source reset.
- (2) Behavior of the upper/lower limit alarm
  - 1) When the alarm reset method is set to "0: self-retention" (example of the upper limit monitoring with CH1 alarm 1)
    - (a) If the measured value that was set with the alarm 1 item exceeds the upper limit and the situation continues and remains for the alarm 1 delay time, CH1 alarm 1 flag (Xn9) will turn ON. At the same time, ALM1 LED flashes.
    - (b) Even if the measured value goes below the upper limit, CH1 alarm 1 flag (Xn9) remains in the ON status (self-retention). During the self-retention, ALM1 LED is lit.
    - (c) By turning CH1 alarm 1 reset request (Yn9) to ON, CH1 alarm 1 flag (Xn9) will turn OFF. At this time, ALM1 LED is turned off.
    - (d) Check that CH1 alarm 1 flag (Xn9) becomes OFF, and then set CH1 alarm 1 reset request (Yn9) to OFF.

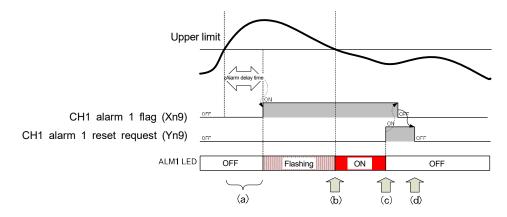


Figure 4.2.4-2 Time chart of the upper/lower limit alarm (alarm reset method = "self-retention")

- 2) When the alarm reset method is set to "1: auto reset" (example of the upper limit monitoring with CH1 alarm 1)
  - (a) If the measured value that was set with the alarm 1 item exceeds the upper limit and the situation continues and remains for the alarm 1 delay time, CH1 alarm 1 flag (Xn9) will turn ON. At the same time, ALM1 LED flashes.
  - (b) If the measured value goes below the upper limit, CH1 alarm 1 flag (Xn9) will turn OFF. At this time, ALM1 LED is turned off.
  - (c) If the measured value that was set with the alarm 1 item exceeds the upper limit but goes below the upper limit within the alarm 1 delay time, then CH1 alarm 1 flag (Xn9) will remain in the OFF status.

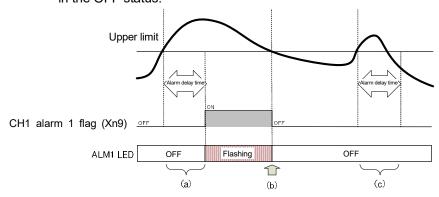


Figure 4.2.4-3 Time chart of the upper/lower limit alarm (alarm reset method = "auto-reset")

3) An example of the alarm 1 was indicated in 1) and 2) above. The alarm 2 will be in accordance with the same behavior.

For the setting items for the buffer memory that corresponds to the alarm 2 and the I/O signals, refer to Chapters 5 and 6. The following describes a case with the alarm 2.

[When the alarm reset method is set to "1: auto reset" (example of the lower limit monitoring with CH1 alarm 2)]

- (a) If the measured value that was set with the alarm 2 item goes below the lower limit and the situation continues and remains for the alarm 2 delay time, CH1 alarm 2 flag (XnA) will turn ON. At the same time, ALM2 LED flashes.
- (b) If the measured value exceeds the lower limit, CH1 alarm 2 flag (XnA) will turn OFF. At this time, ALM2 LED is turned off.
- (c) If the measured value that was set with the alarm 2 item goes below the lower limit but exceeds the lower limit within the alarm 2 delay time, then CH1 alarm 2 flag (XnA) will remain in the OFF status.

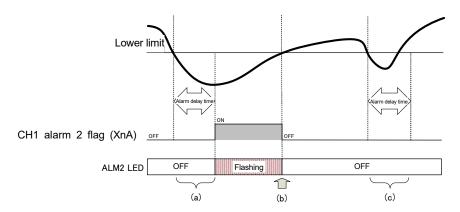


Figure 4.2.4-4 Time chart of the upper/lower limit alarm (alarm reset method = "auto-reset")

- (3) How to reset Alarm flag
  - 1) When Alarm flag is ON during the alarm occurrence or the self-retention (in the case of the alarm reset method = "self-retention"), Alarm flag can be reset (turned OFF) using Alarm reset request.
  - 2) How to reset Alarm flag during alarm occurrence (example of the upper limit alarm monitoring with CH1 alarm 1)
    - (a) If the measured value that was set with the alarm 1 item exceeds the upper limit, CH1 alarm 1 flag (Xn9) will turn ON. At the same time, ALM1 LED flashes.
    - (b) By turning CH1 alarm 1 reset request (Yn9) to ON, CH1 alarm 1 flag (Xn9) will turn OFF. At this time, ALM1 LED will remain flashing (because ALM1 LED is synchronized with the alarm status, it will not turn off).
    - (c) Check that CH1 alarm 1 flag (Xn9) becomes OFF, and then set CH1 alarm 1 reset request (Yn9) to OFF.
    - (d) If the measured value goes below the upper limit, ALM1 LED will turn off.
    - (e) After that, if the measured value exceeds the upper limit, CH1 alarm 1 flag (Xn9) will turn ON again. At the same time, ALM1 LED flashes.

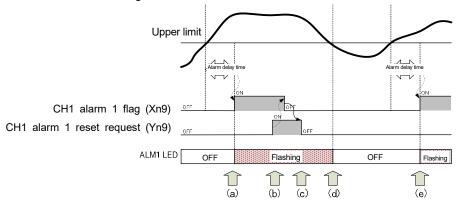


Figure 4.2.4-5 Procedure for resetting Alarm 1 flag (alarm reset method = "auto-reset")

3) How to reset Alarm flag during self-retention (in the case the alarm reset method = "self-retention" only)

Refer to the procedure described in (2) 1).

#### (4) Precautions during the alarm monitoring

- When current demand time and electric power demand time are set to anytime except 0 second, current demand and electric power demand become lower than the actual values (closer to 0) immediately after the power source ON and the CPU reset. When current demand and electric power demand are being monitored for their lower limit, the alarm occurrence flag may turn ON. Thus, to avoid this from happening, follow the procedure below.
  - (a) Set the alarm monitoring target to "no monitoring" immediately after the power source ON and the CPU reset.
  - (b) After passing for a 3-times longer period than the demand time, set the alarm monitoring target again, and start the alarm monitoring.

#### 4.2.5 Test function

This function is to output pseudo-fixed value to a buffer memory for debugging sequence program. The value can be output to the buffer memory without input of voltage and current.

#### (1) How to use the test function

- 1) Using the intelligent function module switch setting, you can start the test mode to output the fixed value
- 2) For procedure for the intelligent function module switch setting, refer to the following. For GX Works2, refer to 8.6.2.

For GX Developer, refer to 8.7.2.

3) To finish the test mode, the set value is returned by the intelligent function module switch setting, and after that, it enters to a measuring mode by resetting it.

(It resumes with the previous set value, electric energy and periodic electric energy.)

#### (2) Content of fixed-output

For the value to be output to the buffer memory, refer to Table 6.1-1 to 6.1-3 in 6.1 Buffer memory assignment.

(3) LED display when using the test function

All LED lights.

(4) I/O signals when using the test function

Unit READY (Xn0) only ON. Other input and output signals are all OFF.

#### (5) Precautions for using the test function

Because fixed-output is output to the buffer memory, isolate the actual device to avoid unexpected operation before running the sequence program.

#### 4.2.6 Integrated value set function

This is a function that can set the integrated value (electric energy (consumption, regeneration), reactive energy (consumption lag)) to an arbitrary value.

It is used to clear integrated value.

#### (1) Setting procedure

(a) Set integrated value setting target (Un\G51) in the buffer memory. Setting range is as follows:

Setting value					Description
CH1	CH2	CH3	CH4	All CHs	
0	0	0	0	0	No set
11	21	31	41	91	Electric energy (consumption)
12	22	32	42	92	Electric energy (regeneration)
13	23	33	43	93	Reactive energy (consumption lag)
19	29	39	49	99	Total integrated value

- (b) Set integrated value setting value (Un\G52, 53) in the buffer memory.
  - Configurable range: 0 to 999999999
  - The unit used for the setting value is the same as that used for the electric energy and reactive energy that are output to the buffer memory.

    For details, refer to section 6.3.2.
- (c) Turn Integrated value setting request (Yn3) from OFF to ON to enable\* the setting.

  Integrated value set completion flag (Xn3) turns ON after Integrated value set request (Yn3) is set OFF to ON.
- (d) After checking that integrated value set completion flag (Xn3) turns ON and setting is completed, set the integrated value set request (Yn3) to OFF.

After detected that the integrated value set request (Yn3) turns OFF, the integrated value set completion flag (Xn3) turns OFF.



Figure 4.2.6 Integrated value setting procedure

#### (2) Default value

integrated value setting target (Un\G51) is set to 0 (No set). integrated value setting value (Un\G52, Un\G53) is set to 0.

# Chapter 5: I/O signals for the CPU module

## 5.1 List of I/O signals

I/O signals of QE84WH are listed in Table 5.1-1.

Table 5.1-1 List of I/O signals

Table 5.1-1 List of I/O signals						
i i	nal (signal direction from QE84WH to CPU module)		gnal (signal direction from CPU module to QE84WH)			
Device #	Signal name	Device #	Signal name			
Xn0	Module ready	Yn0	Use prohibited *1			
Xn1	Data acquisition clock	Yn1	Use prohibited *1			
Xn2	Operating condition setting completion flag	Yn2	Operating condition setting request			
Xn3	Integrated value set completion flag	Yn3	Integrated value set request			
Xn4	Max./min. values clear completion flag	Yn4	Max./min. values clear request			
Xn5	CH1 periodic electric energy 1 data completion flag	Yn5	CH1 periodic electric energy 1 measurement flag			
Xn6	CH1 periodic electric energy 2 data completion flag	Yn6	CH1 periodic electric energy 2 measurement flag			
Xn7	CH1 periodic electric energy 1 reset completion flag	Yn7	CH1 periodic electric energy 1 reset request			
Xn8	CH1 periodic electric energy 2 reset completion flag	Yn8	CH1 periodic electric energy 2 reset request			
Xn9	CH1 alarm 1 flag	Yn9	CH1 alarm 1 reset request			
XnA	CH1 alarm 2 flag	YnA	CH1 alarm 2 reset request			
XnB	CH2 periodic electric energy 1 data completion flag	YnB	CH2 periodic electric energy 1 measurement flag			
XnC	CH2 periodic electric energy 2 data completion flag	YnC	CH2 periodic electric energy 2 measurement flag			
XnD	CH2 periodic electric energy 1 reset completion flag	YnD	CH2 periodic electric energy 1 reset request			
XnE	CH2 periodic electric energy 2 reset completion flag	YnE	CH2 periodic electric energy 2 reset request			
XnF	CH2 alarm 1 flag	YnF	CH2 alarm 1 reset request			
Xn10	CH2 alarm 2 flag	Yn10	CH2 alarm 2 reset request			
Xn11	CH3 periodic electric energy 1 data completion flag	Yn11	CH3 periodic electric energy 1 measurement flag			
Xn12	CH3 periodic electric energy 2 data completion flag	Yn12	CH3 periodic electric energy 2 measurement flag			
Xn13	CH3 periodic electric energy 1 reset completion flag	Yn13	CH3 periodic electric energy 1 reset request			
Xn14	CH3 periodic electric energy 2 reset completion flag	Yn14	CH3 periodic electric energy 2 reset request			
Xn15	CH3 alarm 1 flag	Yn15	CH3 alarm 1 reset request			
Xn16	CH3 alarm 2 flag	Yn16	CH3 alarm 2 reset request			
Xn17	CH4 periodic electric energy 1 data completion flag	Yn17	CH4 periodic electric energy 1 measurement flag			
Xn18	CH4 periodic electric energy 2 data completion flag	Yn18	CH4 periodic electric energy 2 measurement flag			
Xn19	CH4 periodic electric energy 1 reset completion flag	Yn19	CH4 periodic electric energy 1 reset request			
Xn1A	CH4 periodic electric energy 2 reset completion flag	Yn1A	CH4 periodic electric energy 2 reset request			
Xn1B	CH4 alarm 1 flag	Yn1B	CH4 alarm 1 reset request			
Xn1C	CH4 alarm 2 flag	Yn1C	CH4 alarm 2 reset request			
Xn1D	Use prohibited *1	Yn1D	Use prohibited *1			
Xn1E	Use prohibited *1	Yn1E	Use prohibited *1			
Xn1F	Error flag	Yn1F	Error clear request			

## Point

<sup>\*1</sup> These signals cannot be used by the user since they are for system use only. If these are set to on or off by the sequence program, the performance of the QE84WH cannot be guaranteed.

### 5.2 Details of I/O signals

Detailed explanation about I/O signals of QE84WH is provided as follows:

### 5.2.1 Input signals

- (1) Module ready (Xn0)
  - (a) When the power of CPU module is turned on or the CPU module reset is performed, it will turn ON as soon as the measurement is ready.
  - (b)This signal (Xn0) is turned OFF when energy measuring module displays a hardware error, and RUN LED is turned off.
- (2) Data acquisition clock (Xn1)
  - · Regular operating mode
  - (a) When the power is supplied to the CPU module and immediately after the initial computation is performed, this signal (Xn1) is turned ON and count of the output period of data acquisition clock is started. After that, this signal turns ON at the timing when the measurement data is completely written into the buffer memory after the elapse of the output period of data acquisition clock.
    - If the settings of the input voltage, primary current, primary voltage of VT, secondary voltage of VT, primary current of CT and output period of data acquisition clock are changed, this signal turns ON immediately after the change of the settings and count of the output period of data acquisition clock is started.
  - (b) This signal (Xn1) turns OFF 150 ms after it turns ON.

### · Current measuring mode

(a) When the power is supplied to the CPU module and immediately after the initial computation is performed, this signal (Xn1) is turned ON and count of the output period of data acquisition clock is started. After that, this signal turns ON at the timing when the measurement data is completely written into the buffer memory after the elapse of the output period of data acquisition clock.

If the settings of the primary current, primary current of CT and output period of data acquisition clock are changed, this signal turns ON immediately after the change of the settings and count of the output period of data acquisition clock is started.

- (b) This signal (Xn1) turns OFF 150ms after it turns ON.
  - When output period of data acquisition clock is 1 from 100, this signal (Xn1) turns OFF 50ms after it turns ON.
  - When output period of data acquisition clock is 101 from 200, this signal (Xn1) turns OFF 100ms after it turns ON.
  - When output period of data acquisition clock is more than 201, this signal (Xn1) turns OFF 150ms after it turns ON.

- (3) Operating condition setting completion flag (Xn2)
  - (a) When Operating condition setting request (Yn2) is turned ON, the following settings are changed and this signal (Xn2) turns ON.
    - Phase wire system (Un\G0)
    - Primary voltage (Un\G1)
    - Primary current (Un\G2/1002/2002/3002)
    - Current demand time (Un\G3/1003/2003/3003)
    - Electric power demand time (Un\G4/1004/2004/3004)
    - Primary voltage of VT (Un\G5)
    - Secondary voltage of VT (Un\G6)
    - Primary current of CT (Un\G7/1007/2007/3007)
    - Alarm 1 item (Un\G11/1011/2011/3011)
    - Alarm 1 value (Un\G12, 13/1012, 1013/2012, 2013/3012, 3013)
    - Alarm 1 reset method (Un\G14/1014/2014/3014)
    - Alarm 1 delay time (Un\G15/1015/2015/3015)
    - Alarm 2 item (Un\G21/1021/2021/3021)
    - Alarm 2 value (Un\G22, 23/1022, 1023/2022, 2023/3022, 3023)
    - Alarm 2 reset method (Un\G24/1024/2024/3024)
    - Alarm 2 delay time (Un\G25/1025/2025/3025)
    - Output period of data acquisition clock (Un\G60, 61/1060, 1061/2060, 2061/3060, 3061)
  - (b) When Operating condition setting request (Yn2) is turned OFF, this signal (Xn2) turns OFF.

- (4) Integrated value set completion flag (Xn3)
  - (a) When Integrated value set request (Yn3) is turned ON and preset of each integrated value such as electric energy (consumption), electric energy (regeneration), and reactive energy (consumption delay) is completed, this signal (Xn3) turns ON.
  - (b) When Integrated value set request (Yn3) is turned OFF, this signal (Xn3) turns OFF.
- (5) Max./min. values clear completion flag (Xn4)
  - (a) When Max./min. values clear request (Yn4) is turned ON and the data of max./min. value (maximum value, minimum value, and their date and time of occurrence) are cleared, this signal (Xn4) turns ON.
  - (b) When Max./min. values clear request (Yn4) is turned OFF, this signal (Xn4) turns OFF.
- (6) CH1 periodic electric energy 1 data completion flag (Xn5)
  - (a) When CH1 periodic electric energy 1 measurement flag (Yn5) is turned OFF and calculation of CH1 periodic electric energy 1 is stopped, this signal (Xn5) turns ON.
  - (b) When CH1 periodic electric energy 1 measurement flag (Yn5) is turned ON and calculation of CH1 periodic electric energy 1 is started, this signal (Xn5) turns OFF.
  - (c) In order to acquire the data under the condition where CH1 periodic electric energy 1 is checked after the accumulation of the periodic electric energy is stopped, obtain the data while this signal (Xn5) is ON.
    - \*For specific usage procedures, refer to Section 4.2.2.
- (7) CH1 periodic electric energy 2 data completion flag (Xn6)

The usage procedure is the same as that of CH1 periodic electric energy 1 data completion flag (Xn5). Refer to (6).

- (8) CH1 periodic electric energy 1 reset completion flag (Xn7)
  - (a) When CH1 periodic electric energy 1 reset request (Yn7) is turned ON and CH1 periodic electric energy 1 that is stored in the buffer memory is reset, this signal (Xn7) turns ON.
  - (b) When CH1 periodic electric energy 1 reset request (Yn7) is turned OFF, this signal (Xn7) turns OFF.
    - \*For specific usage procedures, refer to Section 4.2.2.
- (9) CH1 periodic electric energy 2 reset completion flag (Xn8)

The usage procedure is the same as that of CH1 periodic electric energy 1 reset completion flag (Xn7). Refer to (8).

### (10)CH1 alarm 1 flag (Xn9)

- (a) If the measured value of CH1 alarm 1 item (Un\G11) exceeds the upper limit (or if it goes below the lower limit in the case of the lower alarm), after the elapse of CH1 alarm 1 delay time (Un\G15), this signal (Xn9) turns ON.
- (b) Operations after this signal (Xn9) is turned ON vary depending on the setting of CH1 alarm 1 reset method (Un\G14).

## [When CH1 alarm 1 reset method (Un\G14) is "0: self-retention"]

Even if the measured value of CH1 alarm 1 monitoring target goes below the upper limit (or if it exceeds the lower limit in the case of lower limit alarm), this signal (Xn9) remains ON. When CH1 alarm 1 reset request (Yn9) is turned ON, this signal (Xn9) turns OFF.

## [When CH1 alarm 1 reset method (Un\G14) is "1: auto reset"]

- If the measured value of CH1 alarm 1 monitoring target goes below the upper limit (or it exceeds the lower limit in the case of lower limit alarm), this signal (Xn9) turns OFF.
- (c) When the measured value of the alarm 1 monitoring target is set to "not monitoring", this signal (Xn9) always turns OFF.
  - \*For the actual behavior of alarm monitoring, refer to Section 4.2.4.

### (11)CH1 alarm 2 flag (XnA)

The usage procedure is the same as that of CH1 alarm 1 flag (Xn9). Refer to (10).

### (12) Error flag (Xn1F)

- (a) If an outside-set-value error occurs or a hardware error occurs, this signal (Xn1F) turns ON.
- (b) The description of the error can be checked with latest error code (Un\G4500).
  - \*For description of error codes, refer to Section 10.1.
- (c) If an outside-set-value error occurs, this signal (Xn1F) is turned OFF by setting a value within the range again.

### 5.2.2 Output signals

- (1) Operating condition setting request (Yn2)
  - (a) When switching this request (Yn2) from the OFF status to the ON status, the following operating conditions will be set.
  - Phase wire system (Un\G0)
  - Primary voltage (Un\G1)
  - Primary current (Un\G2/1002/2002/3002)
  - Current demand time (Un\G3/1003/2003/3003)
  - Electric power demand time (Un\G4/1004/2004/3004)
  - Primary voltage of VT (Un\G5)
  - Secondary voltage of VT (Un\G6)
  - Primary current of CT (Un\G7/1007/2007/3007)
  - Alarm 1 item (Un\G11/1011/2011/3011)
  - Alarm 1 value (Un\G12, 13/1012, 1013/2012, 2013/3012, 3013)
  - Alarm 1 reset method (Un\G14/1014/2014/3014)
  - Alarm 1 delay time (Un\G15/1015/2015/3015)
  - Alarm 2 item (Un\G21/1021/2021/3021)
  - Alarm 2 value (Un\G22, 23/1022, 1023/2022, 2023/3022, 3023)
  - Alarm 2 reset method (Un\G24/1024/2024/3024)
  - Alarm 2 delay time (Un\G25/1025/2025/3025)
  - Output period of data acquisition clock (Un\G60, 61/1060, 1061/2060, 2061/3060, 3061)
  - (b) When the operating condition setting is completed, Operating condition setting completion flag (Xn2) turns ON.
  - (c) When this request (Yn2) is turned OFF, Operating condition setting completion flag (Xn2) turns OFF.

#### (2) Integrated value set request (Yn3)

- (a) If you want to set the electric energy (consumption and regeneration) and the reactive energy to an arbitrary value, write Integrated value setting target (Un\G51) and Integrated value setting value (Un\G52, 53) into it, and after that, turn this request (Yn3) to ON.
- (b) When switching this request (Yn3) from the OFF status to the ON status, the integrated value setting value will be set. When the integrated value setting is completed, Integrated value set completion flag (Xn3) turns ON.
- (c) When this request (Yn3) is set to OFF, Integrated value set completion flag (Xn3) turns OFF.

#### (3) Max./min. values clear request (Yn4)

- (a) When the max./min. value data (max./min. value and their date/time of occurrence) is reset, this request (Yn4) turns ON.
- (b) After writing max./min. values clear item (Un\G56), switching this request (Yn4) from the OFF status to the ON status will clear the max./min. values. When clearing the max./min. data is completed, Max./min. values clear completion flag (Xn4) turns ON.
- (c) When this request (Xn4) is set to OFF, Max./min. values clear completion flag (Xn4) turns OFF.

- (4) CH1 periodic electric energy 1 measurement flag (Yn5)
  - (a) When switching this signal (Yn5) from the ON status to the OFF status, CH1 periodic electric energy 1 is measured and stored in the buffer memory.
  - (b) When this signal (Yn5) is turned OFF, CH1 periodic electric energy 1 data completion flag (Xn5) turns ON at the time that CH1 periodic electric energy 1 is checked for that period, and then CH1 periodic electric energy 1 is retained.
  - (c) In order to read the checked data of CH1 periodic electric energy 1 using the sequence program, use CH1 periodic electric energy 1 data completion flag (Xn5) as the interlock condition.

\*For specific usage procedures, refer to Section 4.2.2.

## (5) CH1 periodic electric energy 2 measurement flag (Yn6)

The usage procedure is the same as that of CH1 periodic electric energy 1 measurement flag (Yn5). Refer to (4).

#### (6) CH1 periodic electric energy 1 reset request (Yn7)

- (a) When this request (Yn7) is turned ON from the OFF status, CH1 periodic electric energy 1 reset completion flag (Xn7) turns ON, and CH1 periodic electric energy 1 that has been stored in the buffer memory is reset.
- (b) Regardless of the status of CH1 periodic electric energy 1 measurement flag (Yn5), either OFF or ON, the periodic electric energy 1 can be reset using this request (Yn7). When CH1 periodic electric energy 1 measurement flag (Yn5) is ON, and the measurement is taking place, the measurement will resume immediately after the reset.
- (c) When this request (Yn7) is set to OFF, CH1 periodic electric energy 1 reset completion flag (Xn7) turns OFF.

\*For specific usage procedures, refer to Section 4.2.2.

### (7) CH1 periodic electric energy 2 reset request (Yn8)

The usage procedure is the same as that of CH1 periodic electric energy 1 reset request (Yn7). Refer to (6).

## (8) CH1 alarm 1 reset request (Yn9)

- (a) When CH1 alarm 1 flag (Xn9) is reset, this request (Yn9) turns ON. (b) When this request (Yn9) is switched from the OFF status to the ON status, CH1 alarm 1 flag (Xn9) will forcibly be turned OFF regardless of the present alarm occurrence status.
- (b) Check that CH1 alarm 1 flag (Xn9) becomes OFF, and then set this request (Yn9) to OFF.

#### (9) CH1 alarm 2 reset request (YnA)

The usage procedure is the same as that of CH1 periodic electric energy 1 reset request (Yn9). Refer to (8).

- (10) Error clear request (Yn1F)
  - (a) When switching this request (Yn1F) from the OFF status to the ON status while an outside-set-value error is present, Error flag (Xn1F) turns OFF, and the latest error code in the buffer memory (Un\G4500) will be cleared.
  - (b) At the same time as clearing the error above, the values that were set in the buffer memory below will be replaced with the previously set values, and integrated value setting target (Un\G51) and integrated value setting value (Un\G52, 53) will be reset to 0. [Set values to be replaced with the previously set values]
  - Phase wire system (Un\G0)
  - Primary voltage (Un\G1)
  - Primary current (Un\G2/1002/2002/3002)
  - Current demand time (Un\G3/1003/2003/3003)
  - Electric power demand time (Un\G4/1004/2004/3004)
  - Primary voltage of VT (Un\G5)
  - Secondary voltage of VT (Un\G6)
  - Primary current of CT (Un\G7/1007/2007/3007)
  - Alarm 1 item (Un\G11/1011/2011/3011)
  - Alarm 1 value (Un\G12, 13/1012, 1013/2012, 2013/3012, 3013)
  - Alarm 1 reset method (Un\G14/1014/2014/3014)
  - Alarm 1 delay time (Un\G15/1015/2015/3015)
  - Alarm 2 item (Un\G21/1021/2021/3021)
  - Alarm 2 value (Un\G22, 23/1022, 1023/2022, 2023/3022, 3023)
  - Alarm 2 reset method (Un\G24/1024/2024/3024)
  - Alarm 2 delay time (Un\G25/1025/2025/3025)
  - Output period of data acquisition clock (Un\G60, 61/1060, 1061/2060, 2061/3060, 3061)
  - (c) While a hardware error is present (error code: 0000h to 0FFFh), it will not be cleared even if this signal (Yn1F) turns ON.

## Chapter 6: Buffer memory

## 6.1 Buffer memory assignment

The following describes buffer memory assignment.

Point

In the buffer memory, do not write data to the "system area" or area where data writing data from sequence programs is disabled.

Doing so may cause malfunction.

(1) Configurable sections (CH1: Un\G0 to Un\G99, CH2: Un\G1000 to Un\G1099, CH3: Un\G2000 to Un\G2099, CH4: Un\G3000 to Un\G3099)

Table 6.1-1 Configurable sections

Item	Address (decimal)  CH1 CH2 CH3 CH4		Description	Default value	R/W	Back up*1	Outp		e during ode*2 CH3	
Setting value		_	System area	_	_	_	GIII	-	-	OH
	0	Pr	Phase wire system	3	R/W	0		(	3	
	1	Pr	Primary voltage	2	R/W	0	2		2	
	2 1002 2002 3002	Pr	Primary current	2	R/W	0	2	3	4	5
	3 1003 2003 3003	Pr	Current demand time	120	R/W	0	100	200	300	400
	4 1004 2004 3004	Pr	Electric power demand time	120	R/W	0	150	250	350	450
	5	Pr	Primary voltage of VT	0	R/W	0		(	)	
	6	Pr	Secondary voltage of VT	0	R/W	0			)	
	7   1007   2007   3007	Pr	Primary current of CT	0	R/W	0	0	0	0	0
	8 1008 2008 3008 to to to to — 10 1010 2010 3010		System area	1	-			-	_	
	11 1011 2011 3011	Pr	Alarm 1 item	0	R/W	0	1	3	5	7
	12 1012 2012 3012	Pr	Alarm 1 value	0	R/W	0	1100	2100	3100	4100
	13 1013 2013 3013		Alarm i value	U	-	_	1100	2100	3100	4100
	14 1014 2014 3014 Pr		Alarm 1 reset method	0	R/W	0	0	1	0	1
	15   1015   2015   3015   Pr		Alarm 1 delay time	0	R/W	0	110	120	130	140
	16		System area	-	_			-	_	
	21 1021 2021 3021 Pr		Alarm 2 item	0	R/W	0	2	4	6	8
	22 1022 2022 3022 23 1023 2023 3023	Pr	Alarm 2 value	0	R/W	0	510	520	530	540
	24 1024 2024 3024	Pr	Alarm 2 reset method	0	R/W	0	1	0	1	0
	25 1025 2025 3025	Pr	Alarm 2 delay time	0	R/W	0	210	220	230	240
	26 1026 2026 3026 to to to to 50 1053 2053 3053		System area	ı			_			
	51	Pr	Integrated value setting target	0	W	_		(	)	
	52 53	Pr	Integrated value setting value	0	W	_	0			
	54 1054 2054 3054 to to to to 55 1056 2056 3056	-	System area	ı	l	1		-	_	
	56	Pr	Max./min values clear item	0	W	_		(	)	
	57   1057   2057   3057 to to to to 59   1061   2061   3061	_	System area	-				=	_	
	60 61	Pr	output period of data acquisition clock	0	R/W	0		(	)	
	62 1062 2062 3062		System area	_	_	_	-			

<sup>\*1</sup> Even if the power failure is restored, data is held because data is backed up by the nonvolatile memory.

<sup>\*2</sup> For the procedure for using the test mode, refer to section 4.2.5.

(2) Measurement sections (CH1: Un\G100 to Un\G999, CH2: Un\G1100 to Un\G1999,

CH3: Un\G2100 to Un\G2999, CH4: Un\G3100 to Un\G3999)

Table 6.1-2 Measurement sections 1/3

Item	Ad	dress(	(Decim	al)	Data	Description	Default	R/W	Back	Output value during the test mode*2			
itom	CH1	CH2	CH3	CH4	Туре	·	value	10,00	up*1	CH1	CH2	CH3	CH4
Electric	100	1100	2100	3100	Md	Multiplier of Electric energy, reactive energy	-4	R	_	-4	-3	-2	-1
energy	101	1101	2101		_	System area	_	_	_				
	102	1102 1103	2102 2103	3102 3103	Md	Electric energy (consumption)	0	R	0	1101000	1201000	1301000	1401000
	104 105	1104 1105	2104 2105	3104 3105	Md	Electric energy (regeneration)	0	R	0	1102000	1202000	1302000	1402000
	106 107	1106 1107		3106 3107	Md	Electric energy (consumption lag)	0	R	0	1103000	1203000	1303000	1403000
	107 108 to 113	1107 1108 to 1113		3108 to	_	System area	_	_	_		_	_	
	114 115	1114 1115	2114		Md	Periodic electric energy1	0	R	0	1104000	1204000	1304000	1404000
	116 117	1116 1117	2116 2117	3116 3117	Md	Periodic electric energy2	0	R	0	1105000	1205000	1305000	1405000
	118 to 199	1118 to 1199	2118 to 2199	3118 to 3199	_	System area	_		_		_	_	
Current	200	1200	2200	3200	Md	Multiplier of current	-3	R	_	-3	-3	-3	-3
	201	1201	2201	3201	_	System area		_			_		
	202	1202 1203	2202 2203	3202 3203	Md	1-phase current	0	R	_	210100	220100	230100	240100
	204	1204 1205	2204 2205	3204 3205	Md	2-phase current	0	R	_	210200	220200	230200	240200
	206 207	1206 1207	2206 2207	3206 3207	Md	3-phase current	0	R	_	210300	220300	230300	240300
	208 to 209	1208 to 1209	2208 to 2209	3208 to 3209	_	System area	_	_	_	_			
	210	1210 1211	2210 2211	3210 3211	Md	1-phase current demand	0	R	_	210500	220500	230500	240500
	212	1212	2212	3212 3213	Md	2-phase current demand	0	R	_	210600	220600	230600	240600
	214	1214 1215	2214 2215	3214 3215	Md	3-phase current demand	0	R	_	210700	220700	230700	240700
	216 to 217	1216 to 1217	2216 to 2217	3216 to 3217	_	System area	_	_	_		_	_	
	218	1218 1219	2218 2219	3218 3219	Md	Average current	0	R	_	210900	220900	230900	240900
	220 221	1220 1221	2220 2221	3220 3221	Md	Maximum current demand	0	R	0	211000	221000	231000	241000
	222	1222	2222	3222	Md	Year of time of max.current demand	0	R	0	2001h	2002h	2003h	2004h
	223	1223	2223	3223	Md	month and day of time of max. current demand	0	R	0	0101h	0102h	0103h	0104h
	224	1224	2224	3224	Md	Hour and minute of time of max.current demand	0	R	0	1331h	1332h	1333h	1334h
	225	1225	2225	3225	Md	Second and day of the week of time of max. current demand	0	R	0	3000h	3001h	3002h	3003h
	226 227	1226	2226 2227	3226	Md	Minimum current demand	0	R	0	211100	221100	231100	241100
	228		2228		Md	Year of time of min.current demand	0	R	0	2006h	2007h	2008h	2009h
	229	1229	2229	3229	Md	month and day of time of min.	0	R	0	0206h	0207h	0208h	0209h
	230	1230	2230	3230	Md	Hour and minute of time of min.current demand	0	R	0	1436h	1437h	1438h	1439h
	231	1231	2231	3231	Md	Second and day of the week of time of min. current demand	0	R	0	3503h	350 <b>4</b> h	3505h	3506h
	232 to	1232 to	2232 to	3232 to	_	System area	_	_	_				
	299	1299		3299									

<sup>\*1</sup> Even if the power failure is restored, data is held because data is backed up by the nonvolatile memory.

<sup>\*2</sup> For the procedure for using the test mode, refer to section 4.2.5.

Table 6.1-2 Measurement sections 2/3

Item			Decima		Data Type	Description	Default value	R/W	Back up*1		alue durin		
Voltage	CH1 300	CH2 1300	CH3 2300	CH4 3300	Md	Multiplier of voltage		R	_	CH1 -3	CH2 -3	CH3 -3	CH4 -3
Voltage	300	1300	2300	3301	IVIG	Multiplier of voltage System area	-3 —			-3	-3	-3 -	-3
	302	1302	2302	3302 3303	Md	1-2 line voltage	0	R	_	310100	320100	330100	340100
	304 305	1304 1305	2304 2305	3304 3305	Md	2-3 line voltage	0	R	_	310200	320200	330200	340200
	306 307	1306 1307	2306 2307	3306 3307	Md	3-1 line voltage	0	R	_	310300	320300	330300	340300
	308 to 313	1308 to 1313	2308 to 2313	3308 to 3313	_	System area	ı	_	ı		_	_	
	314 315	1314 1315	2314 2315	3314 3315	Md	Average voltage	0	R	ı	310700	320700	330700	340700
	316 to 319	1316 to 1319	2316 to 2319	3316 to 3319	_	System area	_	_	_		-	_	
	320 321	1320 1321	2320 2321	3320 3321	Md	Maximum voltage	0	R	0	310900	320900	330900	340900
	322	1322	2322	3322	Md	Year of time of max.voltage	0	R	0	2011h	2012h	2013h	2014h
	323	1323	2323	3323	Md	Month and day of time of max. voltage	0	R	0	0311h	0312h	0313h	0314h
	324	1324	2324	3324	Md	Hour and minute of time of max. voltage	0	R	0	1541h	1542h	1543h	1544h
	325	1325	2325	3325	Md	Second and day of the week of time of max. voltage	0	R	0	4000h	4001h	4002h	4003h
	326 327	1326 1327	2326	3326 3327	Md	Minimum voltage	0	R	0	311000	321000	331000	341000
	328	1328	2328	3328	Md	Year of time of min.voltage	0	R	0	2016h	2017h	2018h	2019h
	329	1329	2329	3329	Md	Month and day of time of min. voltage	0	R	0	0416h	417h	418h	419h
	330	1330	2330	3330	Md	Hour and minute of time of min. voltage	0	R	0	1646h	1647h	1648h	1649h
	331	1331	2331	3331	Md	Second and day of the week of time of min. voltage	0	R	0	4503h	4504h	4505h	4506h
	332 to 399	1332 to 1399	2332 to 2399	3332 to 3339	_	System area		1	_				
Electric	400	1400	2400	3400	Md	Multiplier of electric power	-3	R	_	-3	-3	-3	-3
power	401	1401	2401	3401		System area	_	_	_		_	_	
	402	1402 1403	2402	3402 3403	Md	Electric power	0	R	_	410100	420100	430100	440100
	404	1404	2404	3404 3405	Md	Electric power demand	0	R	_	410200	420200	430200	440200
	406 to 419	1406 to 1419	2406 to 2419	3406 to 3419	_	System area	_	_	_		_	-	
	420 421	1420 1421	2420 2421	3420 3421	Md	Maximum value of electric power demand	0	R	0	410300	420300	430300	440300
	422	1422	2422	3422	Md	Year of time of max.electric power demand	0	R	0	2031h	2032h	2033h	2034h
	423	1423	2423	3423	Md	Month and day of time of max. electric power demand	0	R	0	0701h	0702h	0703h	0704h
	424	1424	2424	3424	Md	Hour and minute of time of max. electric power demand	0	R	0	1901h	1902h	1903h	1904h
	425	1425	2425	3425	Md	Second and day of the week of time of max. electric power demand		R	0	0000h	0001h	0002h	0003h
	426	1426	2426	3426	Md	Minimum value of electric power demand	0	R	0	410400	420400	430400	440400
	427	1427	2427	3427		·							
	428	1428	2428	3428	Md	Year of time of min.electric power demand	0	R	0	2036h	2037h	2038h	2039h
	429	1429		3429	Md	demand		0	0806h	0807h	0808h	0809h	
	430	1430	2430	3430	Md	Hour and minute of time of min. electric power demand	0	R	0	2106h	2107h	2108h	2109h
	431	1431	2431	3431	Md	Second and day of the week of time of min. electric power demand	0	R	0	0503h	0504h	0505h	0506h
	432 to 499	1432 to 1499	2432 to 2499	3432 to 3499	_	System area	_		_				

<sup>\*1</sup> Even if the power failure is restored, data is held because data is backed up by the nonvolatile memory.

<sup>\*2</sup> For the procedure for using the test mode, refer to section 4.2.5.

Table 6.1-2 Measurement sections 3/3

Type	- - - 3 3 3
Dower   Sol	530100 54011 - - -3 -3 -3
Solid   1502   2502   3502   Md   Reactive power   0   R   -     510100   520100	- 3 3
Solid   Soli	- 3 3
System area	<u>-</u> -
To   To   To   To   To   To   System area   To   To   To   To   To   To   To   T	<u>-</u> -
Power factor	<u>-</u> -
Power factor	<u>-</u> -
factor	<u>-</u> -
Total   Tota	730100 7401
Total   Tota	- 730100 7401 -
Total   Tota	_
T19	_
Total   Tota	
Total   Tota	
1721   1721   2721   3721	730200 7402
1722   1722   2722   3722   Md   factor   0   R   O   2041h   2042h	
723 1723 2723 3723 Md max. power factor 0 R O 0911n 0912n  724 1724 2724 3724 Md Hour and minute of time of max. power factor 0 R O 2211h 2212h  Second and day of the week	2043h 2044
724 1724 2724 3724 Md max. power factor 0 R O 2211h 2212h	0913h 0914
Second and day of the week	2213h 2214
725 1725 2725 3725 Md Second and day of the week 0 R 0 1000h 1001h	1002h 1003
726 1726 2726 3726 Md Minimum power factor 0 R O 710300 720300	730300 74030
728         1728         2728         3728         Md         Year of time of min. power factor         0         R         O         2046h         2047h	2048h 2049
729         1729         2729         3729         Md         Month and day of time of min. power factor         0         R         O         1016h         1017h	1018h 1019
730   1730   2730   3730   Md   Hour and minute of time of min. power factor   0   R   O   2316h   2317h	2318h 2319
731         1731         2731         3731         Md         Second and day of the week of time of min. power factor         0         R         O         1503h         1504h	1505h 1506
732 1732 2732 3732	· · ·
to to to to to System area — — — — — — — — — — — — — — — — — — —	_
Frequency         800         1800         2800         3800         Md         Multiplier of frequency         -3         R         -         -3         -3	-3 -3
801         1801         2801         3801         —         System area         —         —         —         —	
802 1802 2802 3802 Md Frequency 0 R — 810100 820100	830100 84010
803   1803   2803   3803	1
804 1804 2804 3804   to to to to - System area	

<sup>\*1</sup> Even if the power failure is restored, data is held because data is backed up by the nonvolatile memory.

<sup>\*2</sup> For the procedure for using the test mode, refer to section 4.2.5.

## (3) Common sections (Un\G4500 to Un\G4999)

Table 6.1-3 Common sections (Un\G4500 to Un\G4999)

Item	Address (Decimal)	Data Type	Description	Default value	R/W	Back up*1		st mode	*2
	CH1 CH2 CH3						CH1	CH2	CH3
Error	4500		Latest error code	_	R			1	
	4501 —		Year of time of error	_	R		2051h		
	4502	_	Month and day of time of	_	R	_	1130h		
	4503		Hour and minute of time of	_	R		0059h		
	4504	_	Second and day of the week	_	R		5906h		
	4505 to 4549 —		System area	_	_		_		
	4550		State of measuring	_	R	_	_		
	4551 to 4999		System area	_				_	

<sup>\*1</sup> Even if the power failure is restored, data is held because data is backed up by the nonvolatile memory.

<sup>\*2</sup> For the procedure for using the test mode, refer to section 4.2.5.

6.2 Configurable sections (CH1: Un\G0 to Un\G99, CH2: Un\G1000 to Un\G1099,

CH3: Un\G2000 to Un\G2099, CH4: Un\G3000 to Un\G3099)

## 6.2.1 Phase wire system (Un\G0)

Phase wire system for target electric circuits is configured below. This setting is common to all channels.

## (1) Setting procedure

(a) Set the phase wire in the buffer memory. Setting range is as follows:

Setting value	Description
1	single-phase 2-wire
2	single-phase 3-wire
3	three-phase 3-wire

- (b) Turn Operating condition setting request (Yn2) from OFF to ON to enable the setting. (Refer to 5.2.2 (1).)
- (2) Default value

It is set to 0 (three-phase 3-wire).

- 6.2.2 Primary voltage (Un\G1), Primary voltage of VT (Un\G5), Secondary voltage of VT (Un\G6)
  - Primary voltage (Un\G1): set the primary voltage of the target electric circuit. This setting is common to all channels.
  - •Primary voltage of VT (Un\G5): when use for primary voltage of voltage transformer that is not in the primary voltage (Un\G1) setting, set the voltage of the primary side of voltage transformer.
  - Secondary voltage of VT (Un\G6): when use for primary voltage of voltage transformer that is not in the primary voltage (Un\G1) setting, set the voltage of the secondary side of voltage transformer.

### (1) Setting procedure

(a) Set the primary voltage, primary voltage of VT and secondary voltage of VT in the buffer memory. Setting range is as follows:

When set other than "1 to 9" the value of this setting, set to "0:any setting" this setting, and set primary / secondary voltage of VT (Un\G5 / Un\G6).

Please setup the primary voltage is 110V (Direct connection) in 1 phase 3 wire.

When the value of this setup is set as "1 to 9", primary/ secondary voltage of VT are disabled.

Prima	ry voltage (Un\G1)	Primary voltage	Secondary voltage
Setting value	Description	of VT (Un\G5)	of VT (Un\G6)
0	Any setting	1 to 6600	1 to 220
1	110 V (Direct connection)		
2	220 V (Direct connection)		
3	220/110 V		
4	440/110 V	0 to 6600	0 to 220
5	690/110 V	(However, this	(However, this
6	1100/110 V	setting is disabled)	setting is disabled)
7	2200/110 V		
8	3300/110 V		
9	6600/110 V		

(b) Turn Operating condition setting request (Yn2) from OFF to ON to enable the setting. (Refer to 5.2.2 (1).)

### (2) Default value

Primary voltage (Un\G1) is set to 220 V (2).

Primary voltage of VT (Un¥G5) is set to 0.

Secondary voltage of VT (Un¥G6) is set to 0.

## 6.2.3 CH1 primary current (Un\G2), CH1 primary current of CT (Un\G7)

- •CH1 primary current (Un\G2): set the primary current of the target electric circuit.
- •CH1 primary current of CT (Un\G7): when use for primary current of current transformer that is not in the CH1 primary current (Un\G2) setting, set the current of the primary side of current transformer.

Secondary current of CT cannot be set. Because secondary current of CT is fixed to 5A.

### (1) Setting procedure

(a) Set the primary current and primary current of CT in the buffer memory. Setting range is as follows: Please choose the settings to match the current sensor to be used.

When set other than "1 to 5, 501 to 536" the value of this setting, set to "0: any setting" this setting, and set primary current of CT (Un\G7).

When the value of this setup is set as "1 to 5, 501 to 536", primary current of CT is disabled.

CH1 primary cu	rrent (Un\G2)	CH1 primary current of	Comment
Setting value	Description	CT (Un\G7)	Current sensor
0	Any setting	4.4- 0000	EMU2-CT5,
		1 to 6000	EMU-CT5-A
1	50 A		EMU-CT50,
			EMU-CT50-A
2	100 A		EMU-CT100,
			EMU-CT100-A
3	250 A		EMU-CT250,
			EMU-CT250-A
4	400 A		EMU-CT400,
			EMU-CT400-A
5	600 A		EMU-CT600,
			EMU-CT600-A
501	5/5 A		
502	6/5 A	0 to 6000	
503	7.5/5 A	(However, this setting is	
504	8/5 A	disabled)	
505	10/5 A		
506	12/5 A		
507	15/5 A		51410 OT5
508	20/5 A		EMU2-CT5,
509	25/5 A		EMU-CT5-A
510	30/5 A		
511	40/5 A		
512	50/5 A		
513	60/5 A		
514	75/5 A		
515	80/5 A		

CH1 primary cu	rrent (Un\G2)	CH1 primary current of	Current sensor		
Setting value	Description	CT (Un\G7)	Current sensor		
516	100/5 A				
517	120/5 A				
518	150/5 A				
519	200/5 A				
520	250/5 A				
521	300/5 A				
522	400/5 A				
523	500/5 A				
524	600/5 A		EMU2-CT5, EMU-CT5-A		
525	750/5 A	0 to 6000			
526	800/5 A	(However, this setting is			
527	1000/5 A	disabled)	EMU-C15-A		
528	1200/5 A				
529	1500/5 A				
530	1600/5 A				
531	2000/5 A				
532	2500/5 A				
533	3000/5 A				
534	4000/5 A				
535	5000/5 A				
536	6000/5 A				

(b) Turn Operating condition setting request (Yn2) from OFF to ON to enable the setting. (Refer to 5.2.2 (1).)

### (2) Default value

CH1 Primary current (Un\G2) is set to 2 (100 A).

CH1 Primary current of CT (Un\G7) is set to 0.

## 6.2.4 CH1 current demand time (Un\G3)

Set a time duration for which the average fluctuation of current demand is measured from the measured current value.

If current demand time is set short, the response to change of current will be quick; however, the fluctuation range may be too large. Adjust the duration according to the load and purposes.

## (1) Setting procedure

- (a) Set current demand time in the buffer memory.
  - Configurable range: 0 to 1800 (seconds)
  - Set the value in seconds.
- (b) Turn Operating condition setting request (Yn2) from OFF to ON to enable the setting. (Refer to 5.2.2 (1).)
- (2) Default value It is set to 120 (seconds).

## 6.2.5 CH1 electric power demand time (Un\G4)

Set a time duration for which the average fluctuation of electric power demand is measured from the measured power value.

If electric power demand time is set short, the response to change of power will be quick; however, the fluctuation range may be too large. Adjust the duration according to the load and purposes.

## (1) Setting procedure

- (a) Set electric power demand time in the buffer memory.
  - Configurable range: 0 to 1800 (seconds)
  - Set the value in seconds.
- (b) Turn Operating condition setting request (Yn2) from OFF to ON to enable the setting. (Refer to 5.2.2 (1).)
- (2) Default value It is set to 120 (seconds).

## 6.2.6 CH1 alarm 1 item (Un\G11), CH1 alarm 2 item (Un\G21)

Set which measuring item will be monitored for the upper/lower limit alarm. Alarm 1 and 2 operate independently.

## (1) Setting procedure

(a) Set the item for alarm 1 and 2 in the buffer memory. Setting range is as follows:

Setting value	Description			
0	No monitoring			
1	Current demand upper limit			
2	Current demand lower limit			
3	Voltage upper limit			
4	Voltage lower limit			
5	Electric power demand upper limit			
6	Electric power demand lower limit			
7	Power factor upper limit			
8	Power factor lower limit			

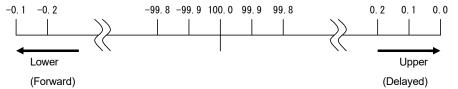
(b) Measuring items for the monitoring target are as follows:

Description	Meas	uring item of monitoring	target		
Description	single-phase 2-wire single-phase 3-wire		three-phase 3-wire		
Current demand upper limit Current demand lower limit	1-phase current demand	1-phase current demand 3-phase current demand *1	1-phase current demand 2-phase current demand 3-phase current demand *1		
Voltage upper limit Voltage lower limit	1 - 2 line voltage	1 - 2 line voltage 2 - 3 line voltage *1	1 - 2 line voltage 2 - 3 line voltage 3 - 1 line voltage *1		
Electric power demand upper limit Electric power demand lower limit	Electric power demand				
Power factor upper limit Power factor lower limit	Power factor *2				

\*1 When multiple number of measuring items are targeted for monitoring, the alarm judgment condition will be as following.

	Alarm judgment conditions				
Upper/lower limits	Condition for occurrence	Condition for			
	Condition for occurrence	non-occurrence			
Current demand upper limit	Any one of alarm item	All alarm item go below the			
Voltage upper limit	exceeds the alarm value.	alarm value.			
Current demand lower limit	Any one of alarm item go	All alarm item exceeds the			
Voltage lower limit	below the alarm value	alarm value			

\*2 The idea of upper and lower for PF upper /lower limit judgment is shown below.



- (c) Turn Operating condition setting request (Yn2) from OFF to ON to enable the setting. (Refer to 5.2.2 (1).)
- (2) Default value It is set to 0 (no monitoring).
- 6.2.7 CH1 alarm 1 value (Un\G12, 13), CH1 alarm 2 value (Un\G22, 23)

Set the upper/lower limit monitoring value for the target that was set in alarm 1 item and alarm 2 item.

- (1) Setting procedure
  - (a) Set the monitoring values for alarm 1 and 2 in the buffer memory.
    - Configurable range: -2147483648 to 2147483647
    - The unit of the setting value is the same as below which was used for the measuring value of the monitored target configured in alarm 1 item and alarm 2 item.

Alarm 1 item	Unit of alarm 1 value
Alarm 2 item	and alarm 2 value
Current demand upper limit	4034
Current demand lower limit	×10 <sup>-3</sup> A
Voltage upper limit	×10 <sup>-3</sup> V
Voltage lower limit	× 10 ° V
Electric power demand upper limit	W
Electric power demand lower limit	(×10 <sup>-3</sup> kW)
Power factor upper limit	×10 <sup>-3</sup> %
Power factor lower limit	× 10 ° %

- (b) Turn Operating condition setting request (Yn2) from OFF to ON to enable the setting.
- (2) Default value It is set to 0.

### 6.2.8 CH1 alarm 1 reset method (Un\G14), CH1 alarm 2 reset method (Un\G24)

Set the reset method of the alarm1 and alarm 2.

For differences in behavior of alarm monitoring for different reset methods, refer to 4.2.4 (2).

### (1) Setting procedure

(a) Set the reset method for alarm 1 and 2 in the buffer memory. Setting range is as follows:

Setting value	Description
0	Self-retention
1	Auto reset

(b) Turn Operating condition setting request (Yn2) from OFF to ON to enable the setting.

### (2) Default value

It is set to 0 (self retention).

### 6.2.9 CH1 alarm 1 delay time (Un\G15), CH1 alarm 2 delay time (Un\G25)

Set the alarm delay time for the alarm 1 and alarm 2.

Alarm delay time means a grace period that takes from the moment when it exceeds the upper limit or goes under the lower limit of the alarm 1 value or alarm 2 value until the alarm flag is turned ON. For detailed behavior, refer to 4.2.4 (2).

### (1) Setting procedure

- (a) Set the delay time for alarm 1 and alarm 2 in the buffer memory.
  - Configurable range: 0 to 300 (seconds)
  - Set the value in seconds.
- (b) Turn Operating condition setting request (Yn2) from OFF to ON to enable the setting.
- (2) Default value

It is set to 0 (seconds).

6.2.10 Integrated value setting target (Un\G51), integrated value setting value (Un\G52, 53)

## (1) Setting procedure

(a) Set integrated value setting target (Un\G51) in the buffer memory. Setting range is as follows:

Setting value					Description
CH1	CH2	CH3	CH4	All CHs	
0	0	0	0	0	No set
11	21	31	41	91	Electric energy (consumption)
12	22	32	42	92	Electric energy (regeneration)
13	23	33	43	93	Reactive energy (consumption lag)
19	29	39	49	99	Total integrated value

- (b) Set integrated value setting value (Un\G52, 53) in the buffer memory.
  - Configurable range: 0 to 999999999
  - The unit used for the setting value is the same as that used for the electric energy and reactive energy that are output to the buffer memory.

For details, refer to section 6.3.2.

- (c) Turn Integrated value setting request (Yn3) from OFF to ON to enable\* the setting.
- (d) After checking that integrated value set completion flag (Xn3) turns ON and setting is completed, set the integrated value set request (Yn3) to OFF.

After detected that the integrated value set request (Yn3) turns OFF, the integrated value set completion flag (Xn3) turns OFF.

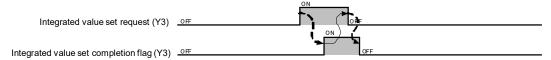


Figure 6.2.10 Integrated value setting procedure

### (2) Default value

integrated value setting target (Un\G51) is set to 0 (No set). integrated value setting value (Un\G52, Un\G53) is set to 0.

## 6.2.11 Max./min. values clear item (Un¥G56)

Select the max./min. values you want to clear.

- · Regular operating mode
  - (1) Setting procedure
    - (a) Set max./min values clear item (Un¥G56) in the buffer memory.

Setting range is as follows:

Setting	value				
CH1	CH2	CH3	CH4	All	Description
				CHs	
0	0	0	0	0	No clear
11	21	31	41	91	Current demand
12	22	32	42	92	Voltage
13	23	33	43	93	Electric power demand
14	24	34	44	94	Power factor
19	29	39	49	99	All items

- (b) Turn Max./min. values clear request (Yn4) from OFF to ON to enable the setting.
- (2) Default value

It is set to 0 (No clear).

- · Current measuring mode
- (1) Setting procedure
  - (a) Set max./min values clear item (Un¥G4002) in the buffer memory. Setting range is as follows:

	Setting value					Description			
CH1	CH2	CH3	CH4	CH5	CH6	CH7	CH8	All CHs	Description
0	0	0	0	0	0	0	0	0	No clear
11	21	31	41	51	61	71	81	91	Current demand

- (b) Turn Max./min. values clear request (Yn4) from OFF to ON to enable the setting.
- (2) Default value

It is set to 0 (No clear).

### 6.2.12 Output period of data acquisition clock (Un\G60, 61)

Set the output period of Data acquisition clock (Xn1). This setting is common to all channels.

- Data acquisition clock (Regular operating mode)
- (1) Setting procedure
  - (a) Set output period of data acquisition clock (Un\G60, 61) in the buffer memory.
    - Configurable range: 0 to 86400000 (ms)
    - \*When the output period of data acquisition clock is set to 0, Data acquisition clock (Xn1) is always OFF.
  - (b) Because the data update interval is 500 ms, Data acquisition clock (Xn1) runs every 500 ms. Note that the output period of data acquisition clock is not a multiple of 500 ms, Data acquisition clock turns ON at the time of the first data update after the elapse of the output period of data acquisition clock.
    - <Example> When the output period of data acquisition clock is 1600 ms:

Measurement data update count = 1600 ms/500 ms = quotient 3 + remainder 100 ms Thus, the input device (Xn1) turns ON once in every four times the measurement data is updated.

As a result, it is same as the case where the output period of data acquisition clock is 2000 ms.

- (c) Turn Operating condition setting request (Yn2) from OFF to ON to enable the setting.
- (2) Default value It is set to 0 (ms).
- · Data acquisition clock (Current measuring mode)
- (1) Setting procedure
  - (a) Set output period of data acquisition clock (Un\G60, 61) in the buffer memory.
    - Configurable range: 0 to 86400000 (ms)
    - \*When the output period of data acquisition clock is set to 0, Data acquisition clock (Xn1) is always OFF.
  - (b) Because the data update interval is 100 ms, Data acquisition clock (Xn1) runs every 100 ms. Note that the output period of data acquisition clock is not a multiple of 100 ms, Data acquisition clock turns ON at the time of the first data update after the elapse of the output period of data acquisition clock.
    - <Example> When the output period of data acquisition clock is 250 ms:

Measurement data update count = 250 ms/100 ms = quotient 2 + remainder 50 ms Thus, the input device (Xn1) turns ON once in every three times the measurement data is updated.

As a result, it is same as the case where the output period of data acquisition clock is 300 ms.

- (c) Turn Operating condition setting request (Yn2) from OFF to ON to enable the setting.
- (2) Default value It is set to 0 (ms).

6.3 Measurement sections (CH1: Un\G100 to Un\G999, CH2: Un\G1100 to Un\G1999,

CH3: Un\G2100 to Un\G2999, CH4: Un\G3100 to Un\G3999)

This product divides the measuring data into the Data and Multiplier, and output them to Buffer memory. Actual measuring data is obtained by the following formula.

Measuring data = Data  $\times$  10° (Multiplier is n).

(Example)

The values output to the Buffer memory are as follows when total current is measured 123.456A.

Data (Un\G218, 219): 123456

Multiplier (Un\G200): -3

The actual measuring data is obtained from the value of Buffer memory as follows.

Measuring data = Data  $\times$  10<sup>-3</sup> = 123.456 A

#### 6.3.1 Multiplier of CH1 electric energy (Un\G100)

Multiplier of electric energy are stored.

As to how the multiplier is determinate, refer to section 4.2.1 (3).

#### (1) Details of stored data

### (a) Storage format

Data are stored as 16-bit signed binary in the buffer memory.

- Data range: -5 to -1

#### (b) Update timing

It will be updated when phase wire system (Un\G0), primary voltage (Un\G1), and CH1 primary current (Un\G2), primary voltage of VT(Un\G5), secondary voltage of VT(Un\G6), and CH1 primary current of CT(Un\G7) are set.

6.3.2 CH1 electric energy (consumption) (Un\G102, 103), CH1 electric energy (regeneration) (Un\G104,105)

Stores the electric energy of the consumption side and the regeneration side will be stored.

### (1) Details of stored data

#### (a) Storage format

Data are stored as double-word 32-bit signed binary in the buffer memory.

- Data range: 0 to 999999999

When the stored data exceeds 999999999, stored data turns to 0 and continues measuring.

\*Restrictions for measured data including resolution and measuring range, refer to section 4.2.1.

### (b) Unit

Unit can be determined by multiplier of CH1 electric energy (Un\G100), as shown below.

Multiplier of CH1 electric energy (Un\G100)	Unit
-5	×10 <sup>-5</sup> kWh
-4	×10 <sup>-4</sup> kWh
-3	×10 <sup>-3</sup> kWh
-2	×10 <sup>-2</sup> kWh
-1	×10 <sup>-1</sup> kWh

### (c) Update timing

### 6.3.3 CH1 reactive energy (consumption lag) (Un\G106, 107)

Delayed consumption of the reactive energy is stored.

#### (1) Details of stored data

#### (a) Storage format

Data are stored as double-word 32-bit signed binary in the buffer memory.

- Data range: 0 to 999999999

When the stored data exceeds 99999999, stored data turns to 0 and continues measuring.

\*Restrictions for measured data including resolution and measuring range, refer to section 4.2.1.

#### (b) Unit

Unit can be determined by multiplier of CH1 electric energy (Un\G100), as shown below.

Multiplier of CH1 electric energy (Un\G100)	Unit
-5	×10 <sup>-5</sup> kvarh
-4	×10 <sup>-4</sup> kvarh
-3	×10 <sup>-3</sup> kvarh
-2	×10 <sup>-2</sup> kvarh
-1	×10 <sup>-1</sup> kvarh

#### (c) Update timing

It will be updated every measuring cycle (500 ms).

### 6.3.4 CH1 periodic electric energy 1 (Un\G114, 115), CH1 periodic electric energy 2 (Un\G116, 117)

Stores the periodic electric energy 1 and periodic electric energy 2. The periodic electric energy of the consumption side is measured.

For specific usage procedures for the periodic electric energy, refer to section 4.2.2.

### (1) Details of stored data

#### (a) Storage format

Data are stored as double-word 32-bit signed binary in the buffer memory.

- Data range: 0 to 99999999

When the stored data exceeds 99999999, stored data turns to 0 and continues measuring.

\*Restrictions for measured data including resolution and measuring range, refer to section 4.2.1.

#### (b) Unit

Unit can be determined by multiplier of CH1 electric energy (Un\G100), as shown below.

Multiplier of CH1 electric energy (Un\G100)	Unit
-5	×10 <sup>-5</sup> kWh
-4	×10 <sup>-4</sup> kWh
-3	×10 <sup>-3</sup> kWh
-2	×10 <sup>-2</sup> kWh
-1	×10 <sup>-1</sup> kWh

#### (c) Update timing

### 6.3.5 Multiplier of CH1 electric current (Un\G200)

The multiplier of the electric current is stored.

- (1) Details of stored data
  - (a) Storage format

Data are stored as 16-bit signed binary in the buffer memory.

- Data range: -3 (fixed)
- (b) Update timing

Because it is fixed at -3, there is no update.

6.3.6 CH1 1-phase current (Un\G202, 203), CH1 2-phase current (Un\G204, 205),

CH1 3-phase current (Un\G206, 207)

The electric current (effective value) of each phase is stored.

- (1) Details of stored data
  - (a) Storage format

Data are stored as double-word 32-bit signed binary in the buffer memory.

- Data range: 0 to 99999999 (0 to 99999.990 A)
- \*Restrictions for measured data including resolution and measuring range, refer to section 4.2.1.
- (b) Unit
  - ×10<sup>-3</sup> A \*Unit is fixed.
- (c) Update timing

It will be updated every measuring cycle (500 ms).

6.3.7 CH1 1-phase current demand (Un\G210, 211), CH1 2-phase current demand (Un\G212, 213),

CH1 3-phase current demand (Un\G214, 215)

Stores the electric current (effective value) at each phase that is calculated based on the moving average for the duration of time configured in current demand time (Un\G3).

- (1) Details of stored data
  - (a) Storage format

Data are stored as double-word 32-bit signed binary in the buffer memory.

- Data range: 0 to 99999999 (0 to 99999.990 A)
- \*Restrictions for measured data including resolution and measuring range, refer to section 4.2.1.
- (b) Unit
  - ×10<sup>-3</sup> A \*Unit is fixed.
- (c) Update timing

### 6.3.8 CH1 average current (Un\G218, 219)

Stores the average current.

For procedure for storing the average current using phase wire system, refer to section 4.2.1 (2).

#### (1) Details of stored data

### (a) Storage format

Data are stored as double-word 32-bit signed binary in the buffer memory.

- Data range: 0 to 99999999 (0 to 99999.990 A)
- \*Restrictions for measured data including resolution and measuring range, refer to section 4.2.1.
- (b) Unit

×10<sup>-3</sup> A \*Unit is fixed.

(c) Update timing

It will be updated every measuring cycle (500 ms).

### 6.3.9 CH1 maximum current demand (Un\G220, 221), CH1 minimum current demand (Un\G226,227)

Stores the max./min. values of the electric current demand among phases.

For procedure for storing the max./min. the electric current demand using phase wire system, refer to section 4.2.1 (2).

### (1) Details of stored data

### (a) Storage format

Data are stored as double-word 32-bit signed binary in the buffer memory.

- Data range: 0 to 99999999 (0 to 99999.990 A)
- \*Restrictions for measured data including resolution and measuring range, refer to section 4.2.1.
- (b) Unit

×10<sup>-3</sup> A \*Unit is fixed.

### (c) Update timing

It will be updated every measuring cycle (500ms) if it exceeds the current max. value or goes under the current min. value.

### 6.3.10 Year of time of CH1 max. current demand (Un\G222),

month and day of time of CH1 max. current demand (Un\G223),

hour and minute of time of CH1 max. current demand (Un\G224),

second and day of the week of time of CH1 max. current demand (Un\G225),

year of time of CH1 min. current demand (Un\G228),

month and day of time of CH1 min. current demand (Un\G229),

hour and minute of time of CH1 min. current demand (Un\G230),

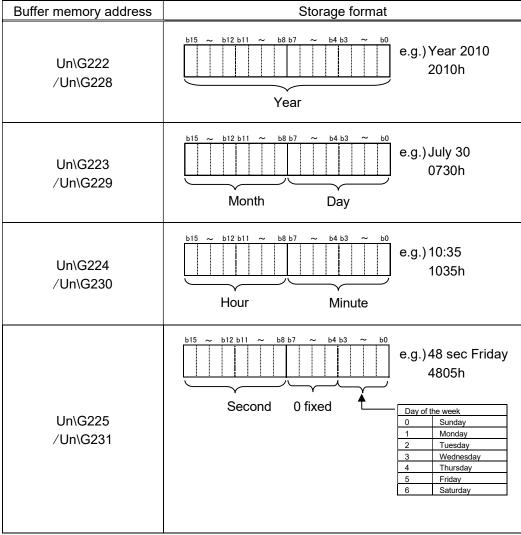
second and day of the week of time of CH1 min. current demand (Un\G231)

Stores year, month, day, hour, minute, second, and day of the week of time when CH1 max. current demand (Un\G220, 221) and CH1 min. current demand (Un\G226, 227) were updated.

### (1) Details of stored data

## (a) Storage format

As indicated below, data are stored as BCD code in the buffer memory.



## (b) Update timing

It will be updated every measuring cycle (500 ms) if it exceeds the current max. value or goes under the current min. value.

### 6.3.11 Multiplier of CH1 the electric voltage (Un\G300)

The multiplier of the electric voltage is stored.

- (1) Details of stored data
  - (a) Storage format

Data are stored as 16-bit signed binary in the buffer memory.

- Data range: -3 (fixed)
- (b) Update timing

Because it is fixed at -3, there is no update.

6.3.12 CH1 1 - 2 line voltage (Un\G302, 303), CH1 2 - 3 line voltage (Un\G304, 305),

CH1 3 - 1 line voltage (Un\G306, 307)

The electric voltage between every combination of wires (effective value) is stored.

- (1) Details of stored data
  - (a) Storage format

Data are stored as double-word 32-bit signed binary in the buffer memory.

- Data range: 0 to 99999900 (0 to 99,999.900 V)
- \*Restrictions for measured data including resolution and measuring range, refer to section 4.2.1.
- (b) Unit

×10<sup>-3</sup> V \*Unit is fixed.

(c) Update timing

It will be updated every measuring cycle (500 ms).

### 6.3.13 CH1 average voltage (Un\G314, 315)

Stores the average voltage.

For procedure for storing the average voltage using phase wire system, refer to 4.2.1 (2).

- (1) Details of stored data
  - (a) Storage format

Data are stored as double-word 32-bit signed binary in the buffer memory.

- Data range: 0 to 99999900 (0 to 99,999.900 V)
- \*Restrictions for measured data including resolution and measuring range, refer to section 4.2.1.
- (b) Unit

×10<sup>-3</sup> V \*Unit is fixed.

(c) Update timing

6.3.14 CH1 maximum voltage (Un\G320, 321), CH1 minimum voltage (Un\G326, 327)

Stores the max./min. values of the voltage among in-between wires. For procedure for storing the max./min. voltage using phase wire system, refer to section 4.2.1 (2).

## (1) Details of stored data

## (a) Storage format

Data are stored as double-word 32-bit signed binary in the buffer memory.

- Data range: 0 to 99999900 (0 to 99,999.900 V)
- \*Restrictions for measured data including resolution and measuring range, refer to section 4.2.1.
- (b) Unit
  - ×10<sup>-3</sup> V \*Unit is fixed.

## (c) Update timing

It will be updated every measuring cycle (500 ms) if it exceeds the current max. value or goes under the current min. value.

6 Buffer memory

QE84WH

6.3.15 Year of time of CH1 the max. voltage (Un\G322),

month and day of time of CH1 max. voltage (Un\G323),

hour and minute of time of CH1 max. voltage (Un\G324),

second and day of the week of time of CH1 max. voltage (Un\G325),

year of time of CH1 min. voltage (Un\G328),

month and day of time of CH1 min. voltage (Un\G329),

hour and minute of time of CH1 min. voltage (Un\G330),

second and day of the week of time of CH1 min. voltage (Un\G331)

Stores year, month, day, hour, minute, and the day of the week of time of maximum voltage (Un\G320, 321) and minimum voltage (Un\G326, 327) were updated.

## (1) Details of stored data

## (a) Storage format

As indicated below, data are stored as BCD code in the buffer memory.

Buffer memory address	Storage format
Un\G322 /Un\G328	e.g.)Year 2010 Year
Un\G323 /Un\G329	e.g.) July 30 0730h  Month Day
Un\G324 /Un\G330	b15 ~ b12 b11 ~ b8 b7 ~ b4 b3 ~ b0 e.g.) 10:35 1035h  Hour Minute
Un\G325 /Un\G331	Second 0 fixed  Day of the week  Second 0 fixed  Day of the week  Sunday  Monday  Tuesday  Tuesday  Thursday  Friday  Saturday

## (b) Update timing

It will be updated every measuring cycle (500ms) and if it exceeds the max. value or goes under the min. value.

## 6.3.16 Multiplier of CH1 power (Un\G400)

The multiplier of power is stored.

- (1) Details of stored data
  - (a) Storage format

Data are stored as 16-bit signed binary in the buffer memory.

- Data range: -3 (fixed)
- (b) Update timing

Because it is fixed at -3, there is no update.

### 6.3.17 CH1 electric power (Un\G402,403)

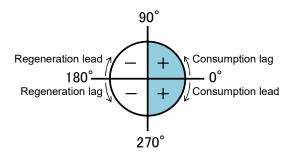
The electric power (effective value) is stored.

- (1) Details of stored data
  - (a) Storage format

Data are stored as double-word 32-bit signed binary in the buffer memory.

If the power is negative, represents the regenerative power.

- Data range:-999999999 to 9999999999 (-999999.999 to 999999.999 kW)
- \*Restrictions for measured data including resolution and measuring range, refer to section 4.2.1.
- \*The sign of the data is as shown in the following figure.



- (b) Unit
  - ×10<sup>-3</sup> kW \*Unit is fixed.
- (c) Update timing

## 6.3.18 CH1 electric power demand (Un\G404,405)

Stores the electric power that is measured based on the moving average for the duration of time configured in CH1 electric power demand time (Un\G4).

### (1) Details of stored data

#### (a) Storage format

Data are stored as double-word 32-bit signed binary in the buffer memory.

If the power is negative, represents the regenerative power.

- Data range: -999999999 to 999999999 (-999999.999 to 999999.999 kW)
- \*Restrictions for measured data including resolution and measuring range, refer to section 4.2.1.
- (b) Unit
  - ×10-3 kW \*Unit is fixed.
- (c) Update timing

It will be updated every measuring cycle (500 ms).

## 6.3.19 CH1 maximum value of electric power demand (Un\G420, 421),

CH1 minimum value of electric power demand (Un\G426, 427)

Stores the max./min. values of the electric power demand.

## (1) Details of stored data

#### (a) Storage format

Data are stored as double-word 32-bit signed binary in the buffer memory.

If the power is negative, represents the regenerative power.

- Data range: -999999999 to 999999999 (-999999.999 to 999999.999 kW)
- \*Restrictions for measured data including resolution and measuring range, refer to section 4.2.1.
- (b) unit
  - ×10<sup>-3</sup> kW \*Unit is fixed.

## (c) Update timing

It will be updated every measuring cycle (500 ms) if it exceeds the current max. value or goes under the current min. value.

6.3.20 Year of time of CH1 max. electric power demand (Un\G422),

month and day of time of CH1 max. electric power demand (Un\G423),

hour and minute of time of CH1 max. electric power demand (Un\G424),

second and day of the week of time of CH1 max. electric power demand (Un\G425),

year of time of CH1 min. electric power demand (Un\G428),

month and day of time of CH1 min. electric power demand (Un\G429)

hour and minute of time of CH1 min. electric power demand (Un\G430),

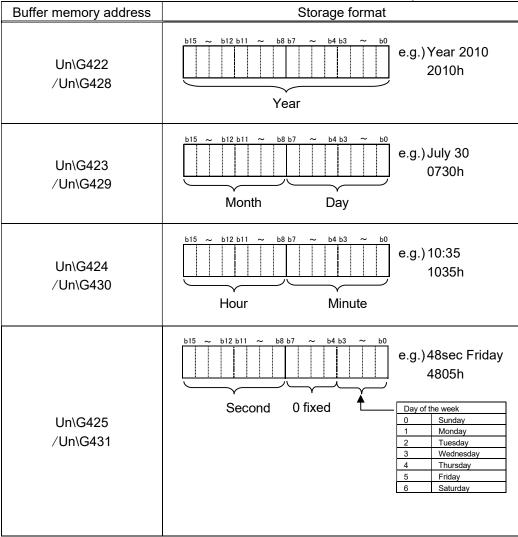
second and day of the week of time of CH1 min. electric power demand (Un\G431)

Stores year, month, day, hour, minute, second, and day of the week of time when CH1 max. electric power demand (Un\G420, 421) and CH1 min. electric power demand (Un\G426, 427) were updated.

### (1) Details of stored data

## (a) Storage format

As indicated below, data are stored as BCD code in the buffer memory.



#### (b) Update timing

It will be updated every measuring cycle (500 ms) if it exceeds the current max. value or goes under the current min. value.

### 6.3.21 Multiplier of CH1 reactive power (Un\G500)

The multiplier of reactive power is stored.

- (1) Details of stored data
  - (a) Storage format

Data are stored as 16-bit signed binary in the buffer memory.

- Data range: -3 (fixed)
- (b) Update timing

Because it is fixed at -3, there is no update.

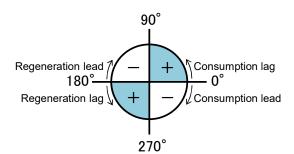
### 6.3.22 CH1 reactive power (Un\G502, 503)

The reactive power is stored.

- (1) Details of stored data
  - (a) Storage format

Data are stored as double-word 32-bit signed binary in the buffer memory.

- Data range: -999999999 to 999999999 (-999999.999 to 999999.999 kvar)
- \*Restrictions for measured data including resolution and measuring range, refer to section 4.2.1.
- \*The sign of the data is as shown in the following figure.



- (b) Unit
  - ×10<sup>-3</sup> kvar \*Unit is fixed.
- (c) Update timing

It will be updated every measuring cycle (500 ms).

### 6.3.23 Multiplier of CH1 power factor (Un\G700)

The multiplier of the power factor is stored.

- (1) Details of stored data
  - (a) Storage format

Data are stored as 16-bit signed binary in the buffer memory.

- Data range: -3 (fixed)
- (b) Update timing

Because it is fixed at -3, there is no update.

#### 6.3.24 CH1 power factor (Un\G702, 703)

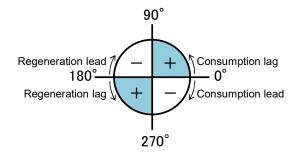
Stores the power factor.

#### (1) Details of stored data

#### (a) Storage format

Data are stored as double-word 32-bit signed binary in the buffer memory.

- Data range:-100000 to 100000 (-100.000 to 100.000%)
- \*Restrictions for measured data including resolution and measuring range, refer to section 4.2.1.
- \*The sign of the data is as shown in the following figure.



(b) Unit

×10<sup>-3</sup>% \*Unit is fixed.

(c) Update timing

It will be updated every measuring cycle (500 ms).

6.3.25 CH1 maximum power factor (Un\G720, 721), CH1 minimum power factor (Un\G726, 727)

The max./min. power factors are stored.

### (1) Details of stored data

(a) Storage format

Data are stored as double-word 32-bit signed binary in the buffer memory.

- Data range: -100000 to 100000 (-100.000 to 100.000%)
- \*For the resolution, refer to Section 4.2.1.
- (b) Unit

×10<sup>-3</sup>% \*Unit is fixed.

(c) Update timing

It will be updated every measuring cycle (500 ms).

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6.3.26 Year of time of CH1 max. power factor (Un\G722),

month and day of time of CH1 max. power factor (Un\G723),

hour and minute of time of CH1 max. power factor (Un\G724),

second and day of the week of time of CH1 max. power factor (Un\G725),

year of time of CH1 min. power factor (Un\G728),

month and day of time of CH1 min. power factor (Un\G729),

hour and minute of time of CH1 min. power factor (Un\G730),

second and day of the week of time of CH1 min. power factor (Un\G731)

Stores year, month, day, hour, minute, second, and day of the week of time when CH1 max. power factor (Un\G720, 721) and CH1 min. power factor (Un\G726, 727) were updated.

#### (1) Details of stored data

#### (a) Storage format

As indicated below, data are stored as BCD code in the buffer memory.

Buffer memory address	Storage format
Un\G722 /Un\G728	e.g.)Year 2010 Year
Un\G723 /Un\G729	b15 ~ b12 b11 ~ b8 b7 ~ b4 b3 ~ b0 e.g.) July 30 0730h  Month Day
Un\G724 /Un\G730	e.g.) 10:35  Hour Minute
Un\G725 /Un\G731	Becond  O fixed  Day of the week  Second  Under the week  Unde

#### (b) Update timing

It will be updated every measuring cycle (500 ms) if it exceeds the current max. value or goes under the current min. value.

#### 6.3.27 Multiplier of CH1 frequency (Un\G800)

The multiplier of the frequency is stored.

- (1) Details of stored data
  - (a) Storage format

Data are stored as 16-bit signed binary in the buffer memory.

- Data range: -3 (fixed)
- (b) Update timing

Because it is fixed at -3, there is no update.

#### 6.3.28 CH1 frequency (Un\G802, 803)

Stores the frequency.

- (1) Details of stored data
  - (a) Storage format

Data are stored as double-word 32-bit signed binary in the buffer memory.

- Data range: 0 to 999999 (0 to 999.999 Hz)
- \*Restrictions for measured data including resolution and measuring range, refer to section 4.2.1.
- (b) Unit
  - ×10<sup>-3</sup>% \*Unit is fixed.
- (c) Update timing

It will be updated every measuring cycle (500 ms).

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#### 6.4 Common sections (Un\G4500 to Un\G4999)

#### 6.4.1 Latest error code (Un\G4500)

The latest error code that is detected with this module will be stored. \*For the list of error codes, refer to section 10.1.

- (1) Details of stored data
  - (a) Storage format

Data are stored as 16-bit signed binary in the buffer memory.

- Data range: 0000h (normal), 0001h to FFFFh (error code)
- (b) Update timing

It will be updated at the time of error occurrence and error recovery.

6.4.2 Year of time of the error (Un\G4501), month and day of time of the error (Un\G4502), hour and minute the error (Un\G4503), second and day of the week of time of the error (Un\G4504)

The year, month, day, hour, minute, and day of the week of time of the error will be stored.

- (1) Details of stored data
  - (a) Storage format

As indicated below, data are stored as BCD code in the buffer memory.

Buffer memory address	Storage format
Un\G4501	b15 ~ b12 b11 ~ b8 b7 ~ b4 b3 ~ b0  e.g.) Year 2010  Year
Un\G4502	b15 ~ b12 b11 ~ b8 b7 ~ b4 b3 ~ b0 e.g.) July 30 0730h  Month Day
Un\G4503	b15 ~ b12 b11 ~ b8 b7 ~ b4 b3 ~ b0  e.g.) 10:35  Hour Minute
Un\G4504	Second 0 fixed  Day of the week  Second  Day of the week  Second  Wednesday  Tuesday  Wednesday  Thursday  Friday  Saturday

#### (b) Update timing

It will be updated at the time of error occurrence and error recovery.

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# 6.4.3 State of measuring mode (Un¥G4550)

Store the state of measuring mode.

(a) Storage format

Measuring mode :0
Current measuring mode :1
Test mode :2

(b) Update timing

It will be updated at the time of changing the setting the intelligent function of the module switch.

#### Chapter 7: Current measuring mode

#### 7.1 Measuring functions in the current measuring mode

#### (1) Measured items

By activating the current measuring mode, you can measure only the current data shown below of up to eight circuits.

Each measured item is stored in the buffer memory every 100 ms.

	Measured items
	Details
Current	Current
Current demand	Current demand
	Maximum current demand
	Minimum current demand
	Date/time of the maximum current demand
	Date/time of the minimum current demand

#### (2) Maximum/minimum current demand

The maximum and minimum current demands are obtained as follows:

Maximum current demand: Maximum value obtained since the reset of the maximum and minimum values until now.

Minimum current demand: Minimum value obtained since the reset of the maximum and minimum values until now.

#### (3) Resolution of measured data

The resolution of the current value is same as those listed in 4.2.1 (3).

#### (4) Restrictions on measured data

The restrictions on the current value are same as those described in 4.2.1 (4).

#### 7.2 Selecting the current measuring mode

1) How to use the current measuring mode

You can use the current measuring mode by the intelligent function module switch setting. For GX Works 2, refer to 8.6.2.

For GX Developer, refer to 8.7.2.

# 7.3 List of I/O signals

I/O signals used in the current measuring mode are listed in Table 7.3-1.

Table 7.3-1 List of I/O signals

Innut sign	Input signal (signal direction from QE84WH to CPU Output signal (signal direction from CPU module to						
module)	ai (aignaí dhechon hoith QE04771 to CPU	QE84WH)					
Device #	Signal name	Device #	Signal name				
Xn0	Module ready	Yn0	Use prohibited *1				
Xn1	Data acquisition clock	Yn1	Use prohibited *1				
Xn2	Operating condition setting completion flag	Yn2	Operating condition setting request				
Xn3	Use prohibited *1	Yn3	Use prohibited *1				
Xn4	Max./min. values clear completion flag	Yn4	Max./min. values clear request				
Xn5	Use prohibited *1	Yn5	Use prohibited *1				
Xn6	Use prohibited *1	Yn6	Use prohibited *1				
Xn7	Use prohibited *1	Yn7	Use prohibited *1				
Xn8	Use prohibited *1	Yn8	Use prohibited *1				
Xn9	CH1 alarm 1 flag	Yn9	CH1 alarm 1 reset request				
XnA	CH1 alarm 2 flag	YnA	CH1 alarm 2 reset request				
XnB	CH2 alarm 1 flag	YnB	CH2 alarm 1 reset request				
XnC	CH2 alarm 2 flag	YnC	CH2 alarm 2 reset request				
XnD	CH3 alarm 1 flag	YnD	CH3 alarm 1 reset request				
XnE	CH3 alarm 2 flag	YnE	CH3 alarm 2 reset request				
XnF	CH4 alarm 1 flag	YnF	CH4 alarm 1 reset request				
Xn10	CH4 alarm 2 flag	Yn10	CH4 alarm 2 reset request				
Xn11	CH5 alarm 1 flag	Yn11	CH5 alarm 1 reset request				
Xn12	CH5 alarm 2 flag	Yn12	CH5 alarm 2 reset request				
Xn13	CH6 alarm 1 flag	Yn13	CH6 alarm 1 reset request				
Xn14	CH6 alarm 2 flag	Yn14	CH6 alarm 2 reset request				
Xn15	CH7 alarm 1 flag	Yn15	CH7 alarm 1 reset request				
Xn16	CH7 alarm 2 flag	Yn16	CH7 alarm 2 reset request				
Xn17	CH8 alarm 1 flag	Yn17	CH8 alarm 1 reset request				
Xn18	CH8 alarm 2 flag	Yn18	CH8 alarm 2 reset request				
Xn19	Use prohibited *1	Yn19	Use prohibited *1				
Xn1A	Use prohibited *1	Yn1A	Use prohibited *1				
Xn1B	Use prohibited *1	Yn1B	Use prohibited *1				
Xn1C	Use prohibited *1	Yn1C	Use prohibited *1				
Xn1D	Use prohibited *1	Yn1D	Use prohibited *1				
Xn1E	Use prohibited *1	Yn1E	Use prohibited *1				
Xn1F	Error flag	Yn1F	Error clear request				

Point	
*1 These signal	s cannot be used by the user since they are for system use only.

For details about each I/O signal, refer to Section 5.2.

#### 7.4 Buffer memory

The following describes buffer memory assignment in the current measuring mode.

Table 7.4-1 Buffer memory

	Table 7.4-1 Buffer memory																				
Item			Address(Decimal) Data Description t R/W Back						0	utput va	lue durin	g the te	st mode	<b>'</b> 2							
item	CH1	CH2	CH3	CH4	CH5	CH6	CH7	CH8	Туре	Description	value	IVVV	up*2	CH1	CH2	CH3	CH4	CH5	CH6	CH7	CH8
Setting value	١	4050 to 4052	4100 to 4102	4150 to 4152	4200 to 4202	4250 to 4252	4300 to 4302	4350 to 4352	_	System area	-	1	-				-	-			
				40 40	00				Pr	Output period of data acquisition	0	R/W	0				(	)			
					02				Pr	clock Max./min. value clear target	0	W	_				-	)			
				<del></del> -	02				FI	Max./IIIII. value clear target	- 0	VV					· `	ĺ			
	4003*	4053*	4103*	4153*	4203*	4253*	4303*	4353*	Pr	Primary current	2	R/W	0	521	522	523	524	525	526	527	528
	4004	4054	4104	4154	4204	4254	4304	4354	Pr	Current demand time	120	R/W	0	1010	1020	1030	1040	1050	1060	1070	1080
	4005	4055	4105	4155	4205	4255	4305	4355	Pr	Primary current of CT	0	R/W	0	0	0	0	0	0	0	0	0
	4004 to 4010	4054 to 4060	4104 to 4110	4154 to 4160	4204 to 4210	4254 to 4260	4304 to 4310	4354 to 4360	_	System area	_	_	_	_							
	4011	4061	4111	4161	4211	4261	4311	4361	Pr	Alarm 1 item	0	R/W	0	1	2	1	2	1	2	1	2
	4012 4013	4062 4063	4112 4113	4162 4163	4212 4213	4262 4263	4312 4313	4362 4363	Pr	Alarm 1 value	0	R/W	0	2010	2020	2030	2040	2050	2060	2070	2080
	4014	4064	4114	4164	4214	4264	4314	4364	Pr	Alarm 1 reset method	0	R/W	0	0	1	0	1	0	1	0	1
	4015	4065	4115	4165	4215	4265	4315	4365	Pr	Alarm 1 delay time	0	R/W	0	101	102	103	104	105	106	107	108
	4016 to 4020	4066 to 4070	4116 to 4120	4166 to 4170	4216 to 4220	4266 to 4270	4316 to 4320	4366 to 4370	_	System area	-	_	-				_	_			
	4021	4071	4121	4171	4221	4271	4321	4371	Pr	Alarm 2 item	0	R/W	0	2	1	2	1	2	1	2	1
	4022	4072	4122	4172	4222	4272	4322	4372	Pr						3020	2000	2040	3050	2000	2070	2000
	4023	4073	4123	4173	4223	4273	4323	4373	Pr	Alarm 2 value	0	R/W	0	3010	3020	3030	3040	3050	3060	3070	3080
	4024	4074	4124	4174	4224	4274	4324	4374	Pr	Alarm 2 reset method	0	R/W	0	1	0	1	0	1	0	1	0
	4025	4075	4125	4175	4225	4275	4325	4375	Pr	Alarm 2 delay time	0	R/W	0	201	202	203	204	205	206	207	208
	4026 to 4029	4076 to 4079	4126 to 4129	4176 to 4179	4226 to 4229	4276 to 4279	4326 to 4329	4376 to 4379	_	System area	_	_	_				-	_			
	4030	4080	4130	4180	4230	4280	4330	4380	Md	Multiplier of current	-3	R	_	-3	-3	-3	-3	-3	-3	-3	-3
	4031	4081	4131	4181	4231	4281	4331	4381	ı	System area	_	_	_				-				
	4032	4082	4132	4182	4232	4282	4332	4382	Md	Current	0	R	_	91100	91200	91300	91400	91500	91600	91700	91800
	4033	4083	4133	4183	4233	4283	4333	4383			_										
	4034	4084	4134	4184	4234	4284	4334	4384	Md	Current demand	0	R	_	92100	92200	92300	92400	92500	92600	92700	92800
	4035 4036	4085 4086	4135 4136	4185 4186	4235 4236	4285 4286	4335 4336	4385 4386													
	4030	4087	4137	4187	4230	4287	4337	4387	Md	Maximum current demand	0	R	_	93100	93200	93300	93400	93500	93600	93700	93800
	4038	4088	4138	4188	4238	4288	4338	4388	Md	Year of time of max. current demand	0	R	_	2051h	2052h	2053h	2054h	2055h	2056h	2057h	2058h
										Month and day of time of max.											
	4039	4089	4139	4189	4239	4289	4339	4389	Md	current demand Hour and minute of time of max.	0	R	_	1121h	1122h	1123h	1124h	1125h	1126h	1127h	1128h
	4040	4090	4140	4190	4240	4290	4340	4390	Md	current demand	0	R	-	2041h	2042h	2043h	2044h	2045h	2046h	2047h	2048h
	4041	4091	4141	4191	4241	4291	4341	4391	Md	Second and day of the week of time of max. current demand	0	R	-	2100h	2201h	2302h	2403h	2504h	2605h	2706h	2800h
	4042	4092	4142	4192	4242	4292	4342	4392	Md	Minimum current demand	0	R		94100	94200	94300	94400	94500	94600	94700	94800
	4043	4093	4143	4193	4243	4293	4343	4393													
	4044	4094	4144	4194	4244	4294	4344	4394	Md	Year of time of min. current demand	0	R		2061h	2062h	2063h	2064h	2065h	2066h	2067h	2068h
	4045	4095	4145	4195	4245	4295	4345	4395	Md	Month and day of time of min. current demand	0	R	_	1201h	1202h	1203h	1204h	1205h	1206h	1207h	1208h
	4046	4096	4146	4196	4246	4296	4346	4396	Md	Hour and minute of time of min. current demand	0	R	_	2151h	2152h	2153h	2154h	2155h	2156h	2157h	2158h
	4047	4097	4147	4197	4247	4297	4347	4397	Md	Second and day of the week of time of min. current demand	0	R	_	3101h	3202h	3303h	3404h	3505h	3606h	3700h	3801h
	4048	4098	4148	4198	4248	4298	4348	4398									-				
	to 4049	to 4099	to 4149	to 4199	to 4249	to 4299	to 4349	to 4399	_	System area	_	_	_				-	-			

<sup>\*</sup> Set the primary current to the same value between CH1 and CH2, between CH3 and CH4, between CH5 and CH6, and between CH7 and CH8. If you set the CH2 (or CH4, CH6, or CH8) address to any value that is inconsistent with the value of CH1 (or CH3, CH5, or CH7), the value you set becomes invalid and is replaced with the value of CH1 (or CH3, CH5, or CH7) after the operating conditions are set.

# 7.5Names and functions of LEDs

The following describes names and functions of LEDs in the current measuring mode.

Table 7.5-1 Names and functions of LEDs (in the current measuring mode)

Name	Color	Role	ON/OFF condition
0 LED	Green	Displays the operation	ON: Normal operation
		status of this module.	OFF: Internal power shut-off, hardware error *1
1 LED	Green	Displays CH1 current	ON: CH1 current > 0 A
		measurement status.	OFF: CH1 current = 0 A
2 LED	Green	Displays CH2 current	ON: CH2 current > 0 A
		measurement status.	OFF: CH2 current = 0 A
3 LED	Green	Displays CH3 current	ON: CH3 current > 0 A
		measurement status.	OFF: CH3 current = 0 A
4 LED	Green	Displays CH4 current	ON: CH4 current > 0 A
		measurement status.	OFF: CH4 current = 0 A
5 LED	Green	Displays CH5 current	ON: CH5 current > 0 A
		measurement status.	OFF: CH5 current = 0 A
6 LED	Green	Displays CH6 current	ON: CH6 current > 0 A
		measurement status.	OFF: CH6 current = 0 A
7 LED	-	-	Always OFF.
			·
8 LED	Red	Displays errors and	Flashing: Out-of-range error *1
		conditions of this module.	ON: Hardware error *1
			OFF: Normal operation
9 LED	Green	Displays CH7 current	ON: CH7 current > 0 A
		measurement status.	OFF: CH7 current = 0 A
A LED	Green	Displays CH8 current	ON: CH8 current > 0 A
		measurement status.	OFF: CH8 current = 0 A
B LED	-	-	Always OFF.
C LED	-	-	Always OFF.
			, and, and
D LED	-	-	Always OFF.
E LED	-	-	Always OFF.
<b>_</b>			
F LED	-	-	Always OFF.
<b>_</b>			,
<u> </u>			

<sup>\*1</sup> For details, check with the list of error codes. (Refer to Section 10.1.)

#### 7.6 Names of signals of terminal block

The following describes names of signals of terminal block in the current measuring mode.

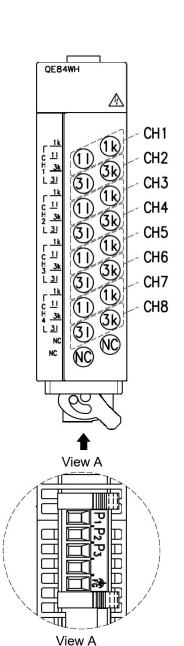


Table 7.6-1 Names of signals of terminal block CH1 1k CH1 current input terminal (power source side) 11 CH1 current input terminal (load side) 3k CH2 current input terminal (power source side) 31 CH2 current input terminal (load side) CH2 1k CH3 current input terminal (power source side) 11 CH3 current input terminal (load side) 3k CH4 current input terminal (power source side) 31 CH4 current input terminal (load side) CH3 1k CH5 current input terminal (power source side) 11 CH5 current input terminal (load side) 3k CH6 current input terminal (power source side) 31 CH6 current input terminal (load side) CH4 1k CH7 current input terminal (power source side) 11 CH7 current input terminal (load side) 3k CH8 current input terminal (power source side) 31 CH8 current input terminal (load side) P1 P2 P3

Figure 7.6-1 Placement of the terminal block

FG

#### 7.7 Wiring

Follow the wiring diagram for external connection in the current measuring mode.

(1) In the case using 5A current sensor.

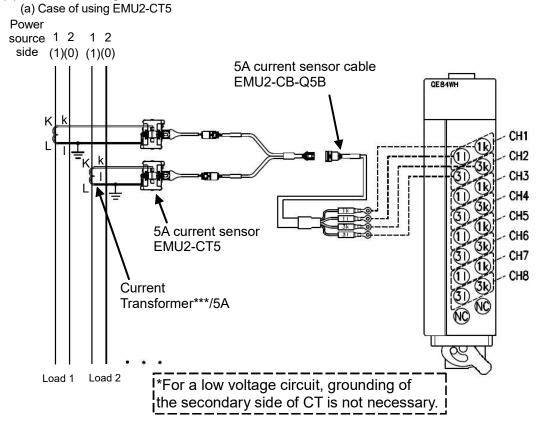


Figure 7.7(1)-(a) Wiring in the using EMU2-CT5 (with the current transformer)

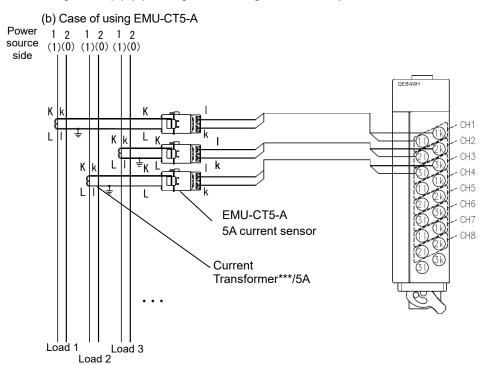


Figure 7.7(1)-(b) Wiring in the using EMU-CT5-A (with the current transformer)

(2) In the case using split-type current sensor.

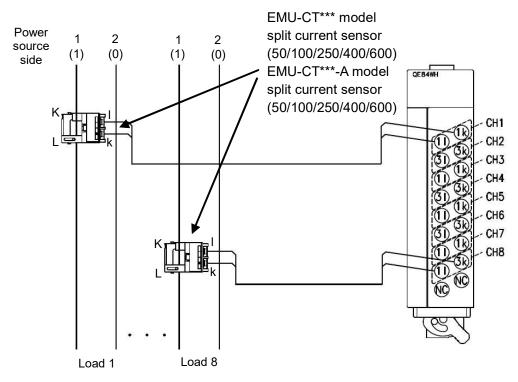


Figure 7.7(2) Wiring in the using split current sensor

#### 7.8 Setting from GX Works2

This section explains setting from GX Works2 necessary to use QE84WH. Before performing this setting, install GX Works2 and connect the Management CPU with the PC using a USB cable. For details, refer to the manual of CPU module.



To addition the unit, enable the switch setting, parameter setting and auto refresh, write the settings to the CPU module, and reset the CPU module or power on the programmable controller again.

#### 7.8.1 Addition the unit

Add the model name of the energy measuring module to use the project.

# (1) Addition procedure

Open the "New Module" window.

Project window→[intelligent Function Module]→Right-click→[New Module...]

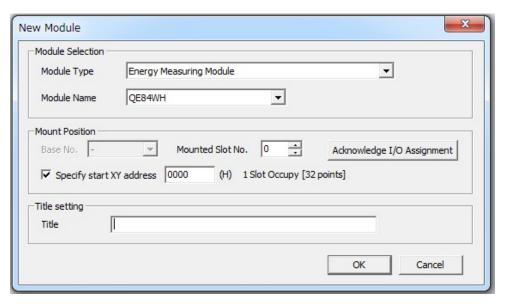


Figure 7.8.1-1 Dialog box of "I/O assignment"

Table 7.8.1-1 Setting items on the "I/O assignment" tab

	9 9							
Ite	em	Description						
Module Selection	Module Type	Set [Energy Measuring module].						
	Module Name	Set the name of the module to mount.						
Mount Position	Base No.	Set the base No. where the module is mounted.						
	Mounted Slot	Set the slot No. where the module is mounted.						
	No.							
	Specify start XY	The start I/O number (hexadecimal) of the target module is set,						
address		according to the mounted slot No. Any start I/O number can be						
		set.						
Title Setting	Title	Set any title.						

#### 7.8.2 Setting the intelligent function of the module switch

Set the operation mode.

#### (1)Setting procedure

Open the "Switch Setting" window.

Project window→[intelligent Function Module]→Module name→[Switch Setting]

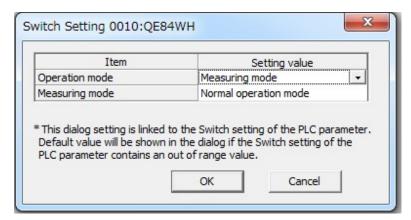


Figure 7.8.2-1 Dialog box to set the intelligent function of the module switch

Table 7.8.2-1 Setting the intelligent function of the module switch

<u> </u>										
Item	Description	Setting value								
Operation mode	Measurement Mode and test mode are changed.	Measuring mode (default) Test mode								
Measuring mode	When set measuring mode above setting, set the kind of measuring mode. When set test mode above setting, this setting disable.	Regular operating mode(default) Current measuring mode								

#### 7.8.3 Parameter Setting

Set the parameters.

Setting parameters on the screen omits the parameter setting in a program.

#### (1)Setting procedure

Open the "Parameter" window.

Project window→[intelligent Function Module]→Module name→[Parameter]

Display Filter • Display All CH1 CH<sub>2</sub> CH3 CH4 CH<sub>5</sub> CH<sub>6</sub> CH7 CH8 Rate setting Set rated value. 2: 100A Primary current 2: 100A Primary current of CT 0 A OA 0 A 0 A 0 A 0 A OA Demand time setting Set demand time. 120 120 120 120 120 120 120 120 Current demand time Seconds Seconds Seconds Seconds Seconds Seconds Seconds Seconds Data acquisition clock function Set data acquisition clock function. Output period of data acquisition dock Alarm 1 monitoring function Set value for Alarm 1 monitoring function. 0: No Alarm 1 item monitoring monitoring monitoring monitoring monitoring monitoring monitoring Alarm 1 value 0 0 0 0 0 0 0 0 0: Alarm 1 reset method Self-retenti Self-retenti Self-retenti Self-retenti Self-retenti Self-retenti Self-retenti Self-retenti on on on on Alarm 1 delay time 0 Seconds Alarm 2 monitoring function Set value for Alarm 2 monitoring function. 0: No 0: No 0: No 0: No Alarm 2 item monitoring monitoring monitoring monitoring monitoring monitoring monitoring monitoring Alarm 2 value 0 0 0 0 0 0 0 0 Alarm 2 reset method Self-retenti Self-retenti Self-retenti Self-retenti Self-retenti Self-retenti Self-retenti 0 Seconds 0 Seconds Alarm 2 delay time 0 Seconds 0 Seconds 0 Seconds 0 Seconds 0 Seconds 0 Seconds (1) Set the item for Alarm 1 to monitor. (2) To validate the setting, ON/OFF the Operating condition setting request is required. E (3) Default value is '0: No monitoring'. (4) To monitor Alarm 1 (if the value for Alarm 1 monitoring item is set from 1 to 2), setting Alarm 1 monitoring value, Alarm 1 reset method, and Alarm 1 delay time is required.

Figure 7.8.3-1 Dialog box to monitor all buffer memories (a case where the module is attached to the slot 0)

- (2)Double-click the item to change the setting, and input the setting value.
  - Items to input from the pull-down list
     Double-click the item to set to display the pull-down list. Select the item.
  - Items to input from the text box
     Double-click the item to set, and input the setting value.
- (3) Setup of CH2 to CH8 is performed by operation of Procedure (2).

Item		Setting value		Reference		
		0:Any setting	516:100/5A			
		1:50A	517:120/5A			
		2:100A	518:150/5A			
		3:250A	519:200/5A			
		4:400A	520:250/5A			
		5:600A	521:300/5A			
		501:5/5A	522:400/5A			
		502:6/5A	523:500/5A			
		503:7.5/5A	524:600/5A			
		504:8/5A	524:000/5A 525:750/5A			
	Primary current	504.6/5A 505:10/5A	526:800/5A	Section 6.2.3		
Rate setting	Filliary current	506:12/5A	520.800/5A 527:1000/5A	Section 6.2.3		
		500:12/5A 507:15/5A				
			528:1200/5A			
		508:20/5A	529:1500/5A			
		509:25/5A	530:1600/5A			
		510:30/5A	531:2000/5A			
		511:40/5A	532:2500/5A			
		512:50/5A	533:3000/5A			
		513:60/5A	534:4000/5A			
		514:75/5A	535:5000/5A			
		515:80/5A	536:6000/5A			
	Primary current of CT	0 to 6000 A	Section 6.2.3			
Demand time setting	Current demand time	0 to 1800 seconds	3	Section 6.2.4		
Data acquisition clock	Output period of data	flag non-use:0		Section 6.2.12		
function	acquisition clock	flag use:1 to 8640	0000 ms	00011011012112		
		0:No monitoring				
	Alarm 1 item	1:Current demand	Section 6.2.6			
		2:Current demand				
Alarm 1 monitoring function	Alarm 1 value	-2147483648 to 2	147483647	Section 6.2.7		
	Alarm 1 reset method	0:Self-retention		Section 6.2.8		
	Alaim Treset metrod	1:Auto reset				
	Alarm 1 delay time	0 to 300 seconds		Section 6.2.9		
		0:No monitoring				
	Alarm 2 item	1:Current demand	• • •	Section 6.2.6		
		2:Current demand				
Alarm 2 monitoring function	Alarm 2 value	-2147483648 to 2	147483647	Section 6.2.7		
	Alarm 2 reset method	0:Self-retention	Section 6.2.8			
	, warm 2 reset method	1:Auto reset	G60ti011 0.2.0			
	Alarm 2 delay time	0 to 300 seconds	Section 6.2.9			

#### 7.8.4 Auto Refresh

This function transfers data in the buffer memory to specified devices.

Programming of reading/writing data is unnecessary.

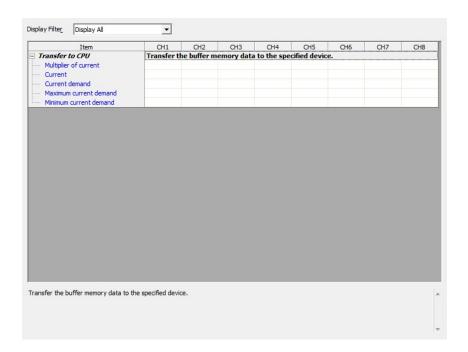
# (1)Setting procedure

1) Start "Auto Refresh".

Project window→[intelligent Function Module]→Module name→[Auto Refresh]

#### 2) Start "Auto Refresh".

Click the item to set, and input the destination device for auto refresh.



#### **Point**

Available devices are X, Y, M, L, B, T, C, ST, D, W, R, and ZR.

When a bit device X, Y, M, L, or B is used, set a number that is divisible by 16 points (example: X10, Y120, M16).

Data in the buffer memory are stored in 16 points of devices starting from the set device No. (Example: When X10 is set, the data are stored in X10 to X1F).

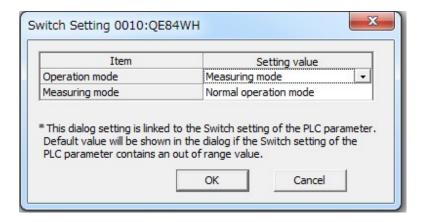
#### 7.8.5 Debugging program

QE84WH provides a test function so that you can debug a program with no input of voltage or current. Pseudo-value can be stored into the buffer memory. For detailed explanation for the test function, refer to 4.2.5.

# --- /t Caution -----

Test function stores pseudo-values for setting value and error information as well as measured value. If you use these data to control the sequence program that controls external devices, there is a chance that erroneous control may occur. For safety of external devices, use this function after disconnecting the device.

- (1) Setting intelligent function of the module switch
  - 1) Configure the operation mode in switch setting as shown below. (Refer to 8.6.2) Test mode transition: Test mode
  - 2) From the "Online" menu, select "Write to PLC" to display the dialog box of Write to PLC, and then execute the writing to PLC parameter. After resetting the CPU module, the value will become effective.



- (2) Starting the test function
  - 1) Reset the CPU module.
  - 2) QE84WH starts in the test function mode. All LEDs are turned on. Pseudo-values are stored in the buffer memory.
- (3) Finishing the test function (Move back to the measuring mode)
  - 1) Following 1) in step (1), Configure the operation mode in switch setting as shown below Test mode transition: Test mode
  - 2) Following 2) in step (1), write the data into PLC.
  - 3) Reset the CPU module, then the operation goes back to the measuring mode.

#### 7.9 Setting from GX Developer

This section explains setting from GX Developer necessary to use QE84WH. Before performing this setting, install GX Developer and connect the Management CPU with the PC using a USB cable. For details, refer to the manual of CPU module.

#### 7.9.1 I/O assignment setting

- (1) Double-click the dialog box of "PLC Parameter" in the GX Developer Project.
- (2) Click "I/O assignment".
- (3) Set the following item to the slot\*1 to which QE84WH has been attached.

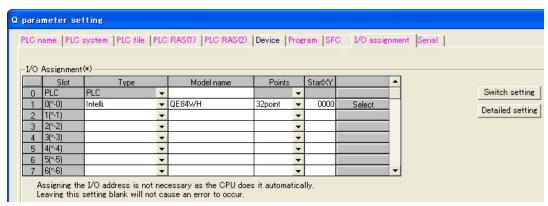


Figure 7.9.1-1 Dialog box of "I/O assignment"

Table 7.9.1-1 Setting items on the "I/O assignment" tab

Item	Descriptions
Туре	Select "Intelli.".
Model name	Enter the model name of the module.
Points	Select 32 points.
Start XY	Enter the initial I/O number of QE84WH.

<sup>\*1</sup> is a case where QE84WH is attached to the slot 0.

#### 7.9.2 Setting the intelligent function of the module switch

- (1) In the "I/O assignment" of 7.9.1, click the Switch setting button to display the dialog box of "I/O module, intelligent function module switch setting".
- (2) The intelligent function module switch setting displays switches 1 to 5; however, only switches 4 and 5 is used for this purpose. Switch setting is configured using 16-bit data. Settings are as shown in Table 7.9.2-1.

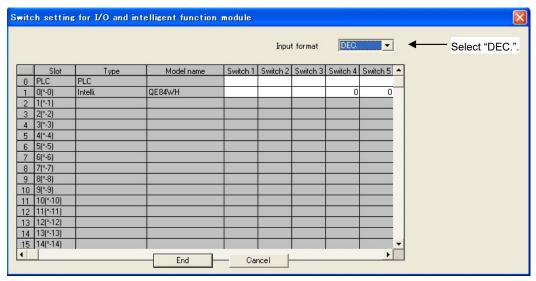


Figure 7.9.2-1 Dialog box to set the intelligent function of the module switch

Swith No.	Switch name	Description
1	Not used	-
2	Not used	-
3	Not used	-
4	Measuring mode selection	0: Regular operating mode 1: Current measuring mode *When switch 5 is set to "1", the test mode is selected.
5	Test mode transition	O: Measuring mode (Even when this switch is not set, the module runs in the measuring mode.)  1: Test mode  * For details of test mode, refer to 4.2.5.

Table 7.9.2-1 Setting the intelligent function of the module switch

- (3) When the setting is completed, click the Complete setting button.
- (4) From the "Online" menu, select "Write to PLC" to display the dialog box of Write to PLC, and then execute the writing to PLC parameter. After resetting the CPU module, the value will become effective.

#### 7.9.3 Initial setting

This section explains the setting of the operating condition for phase wire system, primary voltage, primary current, current demand time, voltage demand time, primary voltage of VT, secondary voltage of VT, and primary current of CT that are required for measurement. Once each value is set, these values will be stored in the nonvolatile memory of the module, so that reconfiguration is not needed. You can also perform the setting using sequence program. In this case, you need to create a program, as referring to Chapter 9.

Follow the procedure below for each setting.

- (1) Check the current setting
- (2) Set the Buffer memory
- (1) Check the current setting
  - From the "Online" menu, select "Monitor" "Buffer memory batch ...". The dialog box to monitor all buffer memories. After setting the address as shown below, click the Start monitoring button to check the current buffer memory status.

Module initial address: Set the initial address of this module.

Buffer memory address: 0

(Display: 16-bit integer, numerical value: check the number in decimal)

2) Check each item. The following shows items for operating condition settings. For specific setting value, see the provided references.

Buffer memory address						Item	Reference		
CH1	CH2	CH3	CH4	CH5	CH6	CH7	CH8	Kom	11010101100
Un\	Un∖	Primary current	Section 6.2.3						
G4003	G4053	G4103	G4153	G4203	G4253	G4303	G4353		0.2.3
Un∖	Un∖	Un∖	Un∖	Un∖	Un∖	Un∖	Un∖	Current demand	Section 6.2.4
G4004	G4054	G4104	G4154	G4204	G4254	G4304	G4354	time	0.2.4
Un∖	Un∖	Un∖	Un∖	Un∖	Un∖	Un∖	Un∖	Primary current of	Section 6.2.3
G4005	G4055	G4105	G4155	G4205	G4255	G4305	G4355	CT	0.2.3

Table 7.9.3-1 List of setting items

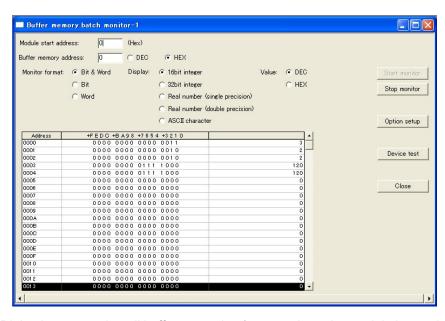


Figure 7.9.3-1 Dialog box to monitor all buffer memories (a case where the module is attached to the slot 0)

- (2) Set the Buffer memory
  - 1) In the dialog box to monitor all buffer memories, click the Device test button to display the Device test dialog box.
  - 2) In the Word device / buffer memory, specify the module initial address and buffer address, and click the Set button to apply the setting.

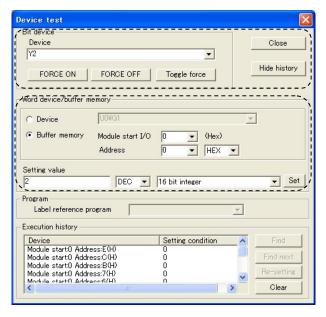


Figure 7.9.3-2 Device test dialog box (a case where this module is attached to the slot 0)

- 3) Change the setting in 2).
- 4) In the section of bit device setting in the device test dialog box, select "Y2"\* and click the FORCE ON button.
- 5) When the setting is completed without any problem, the Device "X2"\* changes to ON. Check this using the procedure as follows:
  - (a) From the "Online" menu, select "Monitor" "Device batch ...". The dialog box to monitor all devices is displayed.
  - (b) Set "X0"\* to the device, and click "Start monitor"
  - (c) Check that Device "X2"\* is in the ON status.

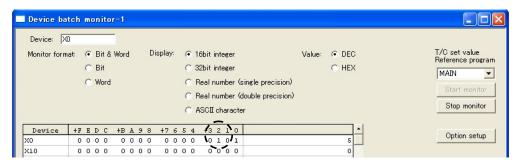


Figure 7.9.3-3 Checking the device "X2"\* in the dialog box to monitor all devices

- 6) After checking that the device "X2"\* is in the ON status, select "Device: "Y2"\* in the dialog box of device test, and then click the FORCE OFF button. Setting is completed.
- 7) If the Device "X2"\* is not in the ON status, this means an error because the set value is out of range (ERR.LED is flashing). Modify the setting, and change the device "Y2" to the OFF status, then change it back to the ON status.

<sup>\*</sup> Indicates a number in the case where the initial I/O number (initial XY) is set to 0.

#### 7.9.4 Debugging program

QE84WH provides a test function so that you can debug a program with no input of voltage or current. Pseudo-value can be stored into the buffer memory. For detailed explanation for the test function, refer to 4.2.5.

#### --- /tৈ Caution ------

Test function stores pseudo-values for setting value and error information as well as measured value. If you use these data to control the sequence program that controls external devices, there is a chance that erroneous control may occur. For safety of external devices, use this function after disconnecting the device.

- (1) Setting intelligent function of the module switch
  - 1) In the "I/O assignment setting" of 7.9.1, click the Switch setting button to display the dialog box of "I/O module, intelligent function module switch setting". (Refer to 7.9.2)
  - 2) The intelligent function module switch setting displays switches 1 to 5; however, use switch 5 when using the test function. Switch setting is configured using 16-bit data. Setting is as follows:

Switch 5: "1"

- 3) When the setting is completed, click the End button.
- 4) From the "Online" menu, select "Write to PLC" to display the dialog box of Write to PLC, and then execute the writing to PLC parameter. After resetting the CPU module, the value will become effective.
- (2) Starting the test function
  - 1) Reset the CPU module.
  - 2) QE84WH starts in the test function mode. All LEDs are turned on. Pseudo-values are stored in the buffer memory.
- (3) Finishing the test function (Move back to the measuring mode)
  - 1) Following 1) and 2) in step (1), configure the intelligent function switch setting as shown below.

Switch 5: "0"

- 2) Following 3) and 4) in step (1), complete the setting and write the data into PLC.
- 3) Reset the CPU module, then the operation goes back to the measuring mode.

#### Chapter 8: Setting and procedure for operation

#### 8.1 Precautions for handling

- (1) Do not drop or apply strong shock to the module case.
- (2) Do not remove the printed-circuit board of the module from the case. Doing so may cause failure.
- (3) Prevent foreign matter such as dust or wire chips from entering the module. Such foreign matter can cause a fire, failure, or malfunction.
- (4) A protective film is attached to the top of the module to prevent foreign matter, such as wire chips, from entering the module during wiring.

Do not remove the film during wiring.

Remove it for heat dissipation before system operation.

- (5) Module fixing screws must be tightened within the specified range as described below. Loose screws may cause short-circuit, failure, or malfunction.
  - \*1 The module can be fixed easily to the base unit, using the hook on top of the module. However, if it is used under a vibrating environment, we strongly recommend that the module be fixed with screws.

Table 8.1-1 Tightening torque

Locations of screws	Torque range	
Module fixing screws (M3 x 12 mm)	0.36 N∙m to 0.48 N∙m	
Terminal screws on the current input	0.42 N∙m to 0.58 N∙m	
terminal block (M3)		
Current input terminal block fixing	0.66 N∙m to 0.89 N∙m	
screws (M3.5)		
Terminal screws on the voltage input	0.4 N∙m to 0.5 N∙m	
terminal block		

(6) To attach the module to the base unit, firmly insert the protruding portions for fixing the module into the holes on the base unit, and make sure the module is securely attached to the module holes as fulcrum points.

Insecure attachment of the module may case malfunction, failure, and a falling.

(7) Before touching the module, make sure that you need to discharge static electricity on your body by touching a metal that is grounded.

Otherwise, it may cause failure or malfunction to the module.

#### 8.2 Procedure for operation

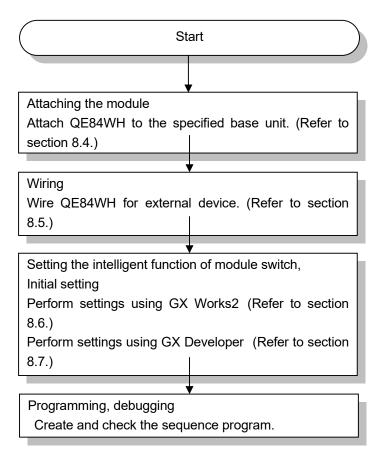


Figure 8.2-1 Procedure for operation

#### 8.3 Name and function of each part

Names and functions of parts of QE84WH are provided below.

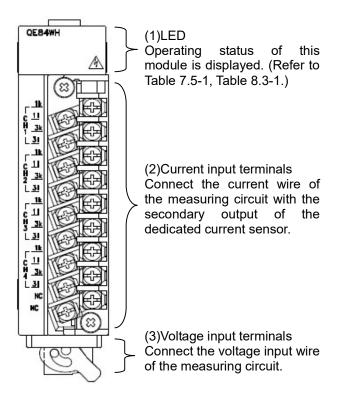


Figure 8.3-1 Appearance of the module

QE84WH

# (1) Names and functions of LEDs

The following describes names and functions of LEDs.

Table 8.3-1 Names and functions of LEDs

Name	Color	Role	ON/OFF condition
0 LED	Green	Displays the operation status of this module.	ON: Normal operation OFF: Internal power shut-off, hardware error *1
1 LED	Green	Displays CH1 measurement status of this module.	Flashing: Measuring electric energy (regeneration) ON: Measuring electric energy (consumption) OFF: Not measuring (No measurement)
2 LED	Green	Displays CH2 measurement status of this module.	Flashing: Measuring electric energy (regeneration) ON: Measuring electric energy (consumption) OFF: Not measuring (No measurement)
3 LED	Green	Displays CH3 measurement status of this module.	Flashing: Measuring electric energy (regeneration) ON: Measuring electric energy (consumption) OFF: Not measuring (No measurement)
4 LED	Green	Displays CH4 measurement status of this module.	Flashing: Measuring electric energy (regeneration) ON: Measuring electric energy (consumption) OFF: Not measuring (No measurement)
5 LED	Green	Displays CH1 3-side measurement status (regeneration) of this module.	ON: Measuring electric energy (regeneration) on side 3 OFF: Other than the above
6 LED	Green	Displays CH2 3-side measurement status (regeneration) of this module.	ON: Measuring electric energy (regeneration) on side 3 OFF: Other than the above
7 LED	-	-	Always OFF.
8 LED	Red	Displays errors and conditions of this module.	Flashing: Out-of-range error *1 ON: Hardware error *1 OFF: Normal operation
9 LED	Green	Displays CH1 1-side measurement status (regeneration) of this module.	ON: Measuring electric energy (regeneration) on side 1 OFF: Other than the above
A LED	Green	Displays CH2 1-side measurement status (regeneration) of this module.	ON: Measuring electric energy (regeneration) on side 1 OFF: Other than the above
B LED	Green	Displays CH3 1-side measurement status (regeneration) of this module.	ON: Measuring electric energy (regeneration) on side 1 OFF: Other than the above
C LED	Green	Displays CH4 1-side measurement status (regeneration) of this module.	ON: Measuring electric energy (regeneration) on side 1 OFF: Other than the above
D LED	Green	Displays CH3 3-side measurement status (regeneration) of this module.	ON: Measuring electric energy (regeneration) on side 3 OFF: Other than the above
E LED	Green	Displays CH4 3-side measurement status (regeneration) of this module.	ON: Measuring electric energy (regeneration) on side 3 OFF: Other than the above
F LED	-	-	Always OFF.

<sup>\*1</sup> For details, check with the list of error codes. (Refer to section 10.1)

# (2) Names of signals of terminal block

The following describes names of signals of terminal block.

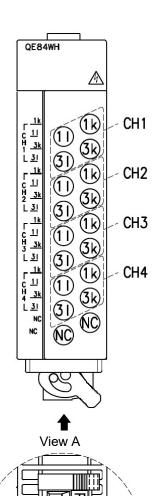


Table8.3-2 Names of signals of terminal block

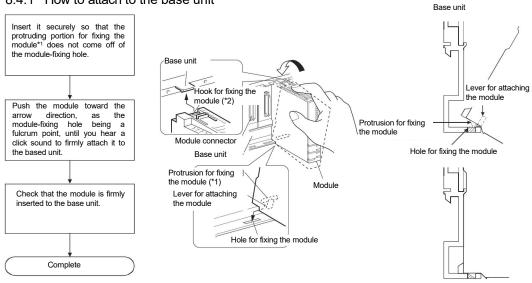
Terminal symbol		Name of terminal
_		
CH1	1k	1-phase current input terminal (power source side)
	11	1-phase current input terminal (load side)
	3k	3-phase current input terminal (power source side)
	31	3-phase current input terminal (load side)
CH2	1k	1-phase current input terminal (power source side)
	11	1-phase current input terminal (load side)
	3k	3-phase current input terminal (power source side)
	31	3-phase current input terminal (load side)
CH3	1k	1-phase current input terminal (power source side)
	11	1-phase current input terminal (load side)
	3k	3-phase current input terminal (power source side)
	31	3-phase current input terminal (load side)
CH4	1k	1-phase current input terminal (power source side)
	11	1-phase current input terminal (load side)
	3k	3-phase current input terminal (power source side)
	31	3-phase current input terminal (load side)
P	1	1-phase voltage input terminal
P2		2-phase voltage input terminal
P3	3	3-phase voltage input terminal
FC	<del>)</del>	Frame GND terminal

Figure 8.3-2 Placement of the terminal block

View A

#### 8.4 Attaching and removing the module

#### 8.4.1 How to attach to the base unit



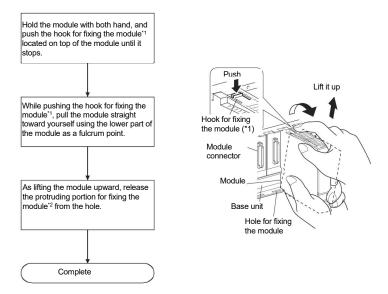
# **!** Caution

- Attach to the base of MELSEC-Q series.
- When attaching the module, make sure to insert the protruding portions for fixing the module
  into the holes on the base unit. In doing so, insert it securely so that the protruding portion of
  the module does not come off of the holes. Do not force to attach the module; otherwise the
  module may break.
- When installing the module at a vibrating area with strong impact, tighten the module to the base unit using screws. Module-fixing screws: M3 x 12 (Prepare them yourself.)

Locations of screws	Torque range
Module-fixing screws	0.36 N•m to 0.48 N•m

 Attaching and detaching the module and the base unit should be performed 50 times or less (to conform to JIS B3502). If the count exceeds 50 times, it may cause a malfunction.

#### 8.4.2 How to detach it from the base unit



 When module-fixing screws are used, make sure to remove the screws for detaching the module first, and then remove the protruding portion for fixing the module from the holes. Do no force to remove the module; it may break the protruding portions for fixing the module.

#### 8.5 Wiring

#### 8.5.1 Precautions for wiring

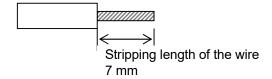
- (1) Connect cables. For connecting voltage transformer and current transformer, refer to the corresponding wiring diagram.
- (2) For wiring, check with the wiring diagram and check phase wire system for the connecting circuit.
- (3) For the current circuit input, Mitsubishi's current sensor is required. (Refer to section 8.5.3)
- (4) If a current sensor is located in a strong magnetic field such as an area nearby a transformer or high-current cable bus bar, the voltage circuit input may be influenced, which in turn affects the measured value. Thus, please ensure sufficient distance between devices.

Condition	Distance
Power line carrying 600 V or lower	300 mm or longer
and 600 A or lower	
Other power lines	600 mm or longer

- (5) For input wiring of the measurement circuit, use separate cables from other external signals in order to prevent from AC surge and induction.
- (6) Keep any object off the cables.
- (7) Protect cable coating from scratch.
- (8) Cable length should be routed in length with a margin, please take care to avoid causing stress to pull the terminal block. (Tensile load: less than 22 N)
- (9) For the actual usage, connect the FG terminal to ground. (D-type ground: Type 3) Connect it directly to the ground terminal.

#### 8.5.2 How to connect wires

- (1) Follow the wiring diagram for external connection to QE84WH.
- (2) Use appropriate electric wires as described below.
  - <Voltage input terminals>
  - 1) Stripping length of the wire to be used has to be 7 mm. Check the stripping length using the strip gauge of QE84WH main module.



Applicable wire	Single wire: AWG24 to AWG12 (φ0.5 mm to 2.0 mm)
(Usable electric wire)	Tightening torque: 0.5 N⋅m to 0.6 N⋅m
	Stranded wire: AWG24 to AWG12 (0.2 mm² to 3.3 mm²)
	Tightening torque: 0.5 N·m to 0.6 N·m

2) When using a stranded wire, strand the wire edges to prevent thin wires from loosening.

#### <Current input terminals>

1) For the connection between the secondary terminal of current sensor (EMU-CT\*\*\*, EMU-CT\*\*\*-A) and current input terminals, use twisted pair cable.

Applicable wire	Stranded wire: AWG22 to AWG18 (0.4 mm² to 0.8 mm²)
(Usable electric wire)	Tightening torque: 0.6 N⋅m to 0.85 N⋅m

2) Use a solderless terminal to prevent thin wires from loosening. No solderless terminal with insulation sleeve can be used.

|--|

3) It is recommended to cover the solderless terminals connecting electric cables with a mark tube or insulating tube.

#### 8.5.3 How to wire

Follow the wiring diagram (Figure 8.5.3(1)-(a) to 8.5.3(2)-(b)) for external connection of QE84WH.

(1) In the case using 5A current sensor. (a) Case of using EMU2-CT5

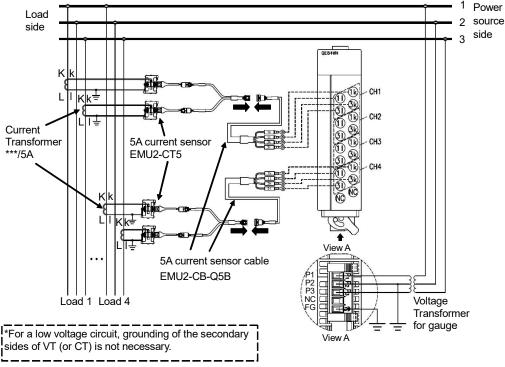


Figure 8.5.3(1)-(a) In the case of Three-Phase 3-wire system (with the voltage transformer for gauge/ current transformer)

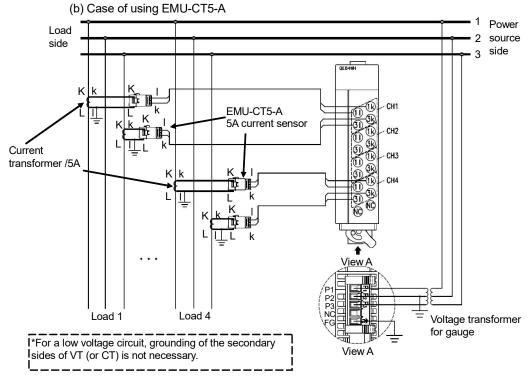


Figure 8.5.3(1)-(b) In the case of Three-phase 3-wire system (with the voltage transformer for gauge/current transformer)

- (2) In the case using split-type current sensor.
  - (a) Case of Three-phase 3-wire system

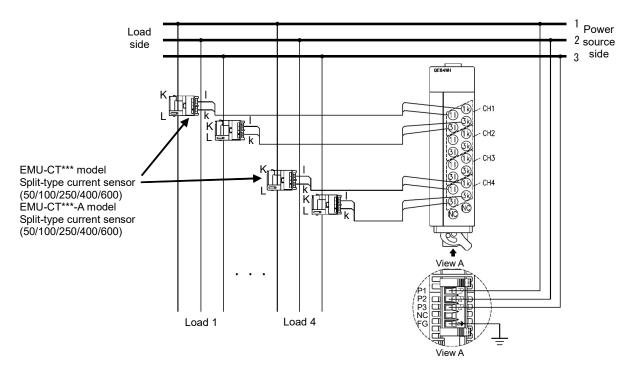


Figure 8.5.3(2)-(a) In the case of Three-Phase 3-wire system

#### (b) Case of Single-phase 2-wire system

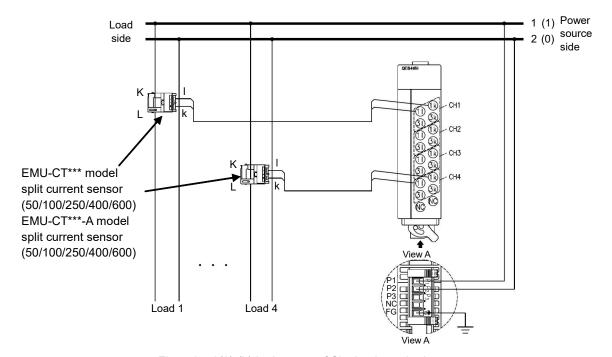


Figure 8.5.3(2)-(b) In the case of Single-phase 2-wire system

# (c) Case of Single-phase 3-wire system

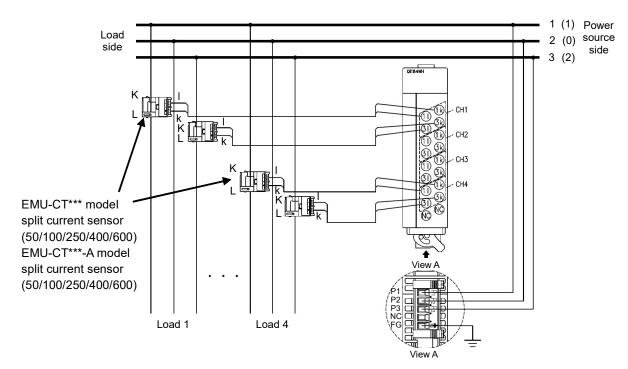


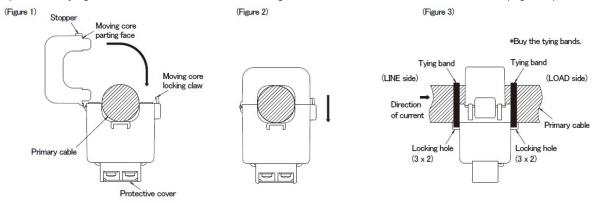
Figure 8.5.3(2)-(c) In the case of Single-phase 3-wire system

#### 8.5.3.1 Current circuit connection

A dedicated current sensor (EMU-CT \*\*\*, EMU-CT \*\*\*-A, EMU2-CT5) is required to connect the current circuit.

#### ■ How to attach EMU-CT5/CT50/CT100/CT250-A

- 1) Press the locking claw of the moving core, please open the moving core by removing the engagement (Figure 1). Before inserting the cable, check the symbols K and L to fit the current sensor in the correct direction. (The direction from the power supply side to the load side is indicated with →.) (Figure 3)
- 2) After checking that the core parting faces are free from dirt, close the moving core. Push down the moving core until the stoppers are securely locked. (Locking claw of the moving core is applied to the stopper, you hear click.) (Figure 2)
- 3) Pass the tying bands into the current sensor locking holes to secure the sensor with the cable. (Figure 3)



# **✓** Supplementary

- Make sure that before connecting the cable, the orientation of the current sensor is correct for attachment. K to L is the correct direction. K: power source side, L: load side.
- Do not bend the moving core in a direction other than the operation direction (shown in Fig. 1). The current sensor may be damaged.

Refer to the table below for appropriate size of electric wires.

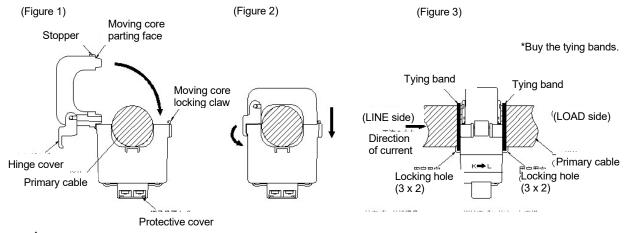
		EMU-CT5-A	EMU-CT50-A	EMU-CT100-A	EMU-CT250-A
Usable wires	IV cable	38 mm <sup>2</sup> or less	38 mm <sup>2</sup> or less	60 mm <sup>2</sup> or less	200 mm <sup>2</sup> or less
size (reference)	CV cable	22 mm <sup>2</sup> or less	22 mm <sup>2</sup> or less	60 mm <sup>2</sup> or less	150 mm <sup>2</sup> or less

Size of electric wires conforms to what is described in the catalog of general PVC insulated wires. Thickness of external PVC insulation is different for different wire. Check with the external dimension diagram of this product and make sure the wire can go through the given space.

#### ■ How to attach EMU-CT400/CT600-A

- Press the locking claw of the moving core, please open the moving core by removing the engagement (Figure

   At this time, the hinge cover opens automatically. Before inserting the cable, check the symbols K and L to
   fit the current sensor in the correct direction. (The direction from the power supply side to the load side is
   indicated with →.) (Figure 3)
- 2) After checking that the core parting faces are free from dirt, close the moving core. Push down the moving core until the stoppers are securely locked. (Locking claw of the moving core is applied to the stopper, you hear click.) After the stopper is securely locked, close the hinge cover. (Figure 2)
- 3) Pass the tying bands into the current sensor locking holes to secure the sensor with the cable. (Figure 3)



### **✓** Supplementary

- Make sure that before connecting the cable, the orientation of the current sensor is correct for attachment. K to L is the correct direction. K: power source side, L: load side.
- Do not bend the moving core in a direction other than the operation direction (shown in Fig. 1). The current sensor may be damaged.
- Refer to the table below for appropriate size of electric wires.

		EMU-CT400-A	EMU-CT600-A	
Usable wires	IV cable	500 mm <sup>2</sup> or less	500 mm <sup>2</sup> or less	
size (reference)	CV cable	400 mm <sup>2</sup> or less	400 mm <sup>2</sup> or less	

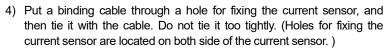
Size of electric wires conforms to what is described in the catalog of general PVC insulated wires. Thickness of external PVC insulation is different for different wire. Check with the external dimension diagram of this product and make sure the wire can go through the given space.

#### ■ How to attach EMU-CT50/CT100/CT250

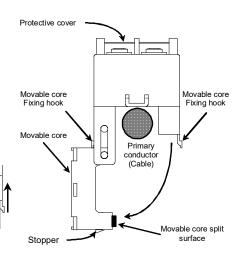
Follow the procedure below to attach to the cable of the target circuit.

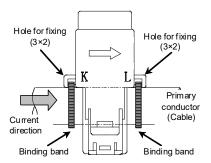
- Open the movable core, as shown in the figure on the right.
   Lift slowly the hooks located on both sides of the movable core, and
   detach them from the stopper. Do not force to open it. You may
   break the hook.
- 2) Do not let the cable touch on the core-spilt surface. Thus, carefully pass the cable from underneath. Before passing the cable, check the direction symbols of K and L, in order to attach the sensor in the correct orientation. (Direction from power source side (K) to load side (L) is indicated with the arrow.)
- on the split-core surface, and after that, close the movable core. Lift the movable core until the stoppers are firmly locked. (When the hooks on both side of movable core are locked to the stoppers, you will hear click sound twice.)

3) Make sure no dust or foreign object is attached



- 5) Cut off the extra portion of binding cable, using a nipper, etc, to avoid interference of the cable.
- 6) Lift a protective cover of the secondary terminal, by holding the center portion of the protective cover, and remove it. And then, connect the given sensor cable. Check the terminal symbols printed on the secondary terminal surface, so that connection is performed correctly.





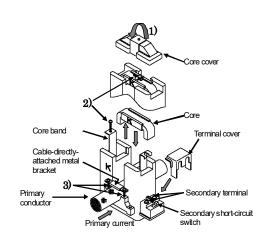
### ✓ Supplementary ----

- When opening the movable core on current sensor, do not widen the hook for fixing the movable core too widely. It may break the hook.
- Refer to the table below for appropriate size of electric wires.

		EMU-CT50	EMU-CT100	EMU-CT250
Usable wires	IV cable	60 mm <sup>2</sup> or less	60 mm <sup>2</sup> or less	150 mm <sup>2</sup> or less
size (reference)	CV cable	38 mm <sup>2</sup> or less	38 mm <sup>2</sup> or less	150 mm <sup>2</sup> or less

Size of electric wires conforms to what is described in the catalog of general PVC insulated wires. Thickness of external PVC insulation is different for different wire. Check with the external dimension diagram of this product and make sure the wire can go through the given space.

- How to attach EMU-CT400/CT600 Follow the procedure below to attach the cable to the target circuit.
- Release the band 1) to the arrow direction (top), and detach the core cover.
- Remove the terminal cover, and shift the secondary short switch into "short".
- Loosen the screw 2), and open the core band to remove the core. Make sure that no dust, etc attaches on the core.
- 4) Loosen the screw 3). Put this module onto the cable, and fix the module by tightening the screw 3) using the metal bracket that is directly attached to the cable. Tighten the screw as tightly as the metal bracket will not bend.
- Align the symbol of "K" on the removed core and the "K" on the module to return the core as in the original location. And then, tighten the core band using the screw 2).
- 6) Attach the core cover and fix it with the band 1).
- 7) Connect the secondary terminal with multiple-circuit power measuring module, turn the secondary short switch into "open", and then attach the terminal cover.



### **✓** Supplementary ---

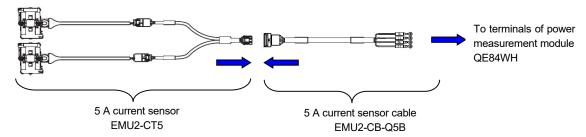
• Refer to the table below for appropriate size of electric wires.

		EMU-CT400		EMU-CT600	
		1 wire	2 wire	1 wire	2 wire
Usable wires	IV cable	5002	2052	5002	2052
size (reference)	CV cable	500 mm <sup>2</sup>	325 mm <sup>2</sup>	500 mm <sup>2</sup>	325 mm <sup>2</sup>

Size of electric wires conforms to what is described in the catalog of general PVC insulated wires. Thickness of external PVC insulation is different for different wire. Check with the external dimension diagram of this product and make sure the wire can go through the given space.

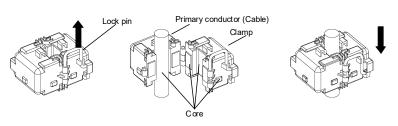
#### ■ How to attach EMU2-CT5

- Transfix EMU2-CT5 current sensor to the secondary-side wire of current transformer (/5A rated). Make sure to use it in a correct combination with 5 A current sensor conversion cable: EMU2-CB-Q5B
- EMU2-CT5 has polarities. Make sure to connect to the right symbol on the terminal. Power source side: (k side), load side: (I side).



Follow the procedure below to attach the cable to the target circuit.

- 1) Slide the lock pin to the arrow direction.
- 2) Put the electric wire through the clamp, and close the clamp again.
- 3) Use your finger to hold the clamp in the full close position, and push the lock pin until it locks.

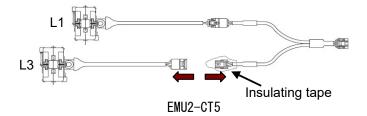


# Caution

- The lock pin is made of metal. If you let it touch electrically charged portions, it may cause electric shock or device failure or fire. Be careful handling the lock pin.
- Physical impact to the core may cause breakage. It may directly influence the performance. Be careful handling the core.
- The mating surface on the core is very sensitive. Even a small foreign object on the surface may affect the measurement performance.
- Excessive force to the core during open clamp may cause breakage. Incorrect direction may cause inaccurate measurement.
- For both the transfixing wire and the binding band for fixing the sensor, use the size of W=2.6 mm or less. To fix them together Put a binding band through a hole for fixing the current sensor, and tie it
  - with the cable. Do not tie it too tightly. (Total four holes for fixing the current sensor exist on both sides of the

#### ■ When wiring single-phase 2-wire circuit

5 A current sensor is not used L3. As shown below, L3 remove connector , and connector with insulating tape.



### ■ Extending the cable of 5 A current sensor

If the cable from current sensor is too short, you can extend it by using an extension cable as shown below. Extension cable (standard)

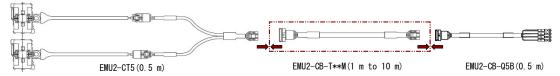
Model name	EMU2-CB-T1M	EMU2-CB-T5M	EMU2-CB-T10M
Cable length	1 m	5 m	10 m

#### Extension cable (separate)

Model name	EMU2-CB-T1MS	EMU2-CB-T5MS	EMU2-CB-T10MS
Cable length	1 m	5 m	10 m

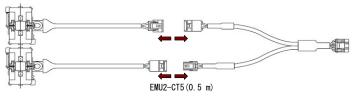
#### Connecting 5 A current sensor and the cable

◆Connecting 5 A current sensor and extension cable (standard)

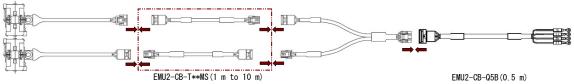


#### ◆Connecting 5 A current sensor and extension cable (separate)

1)Disconnect the connector



2)Connect the extension cable

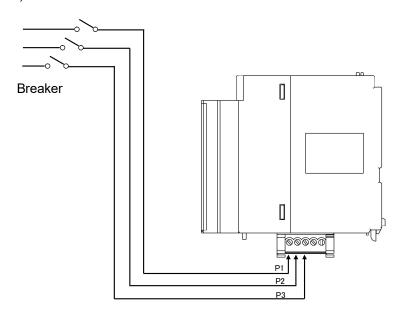


# ✓ Supplementary ------

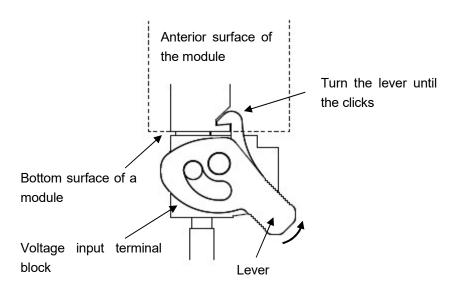
- Cable extension for EMU2-CT5 is 10 m max. (Total cable length is 11 m max.)
- Use extension cable (separate) when 1-phase and 3-phase are set apart.

#### 8.5.3.2 Voltage circuit connection

- If more than 220 V circuit is used, make sure that use a transformer.
- The transformer which has primary voltage of VT less than 6600V and secondary voltage of VT not more than 220 V can be used. For connection to P1 to P3 terminals on QE84WH, connect the secondary of transformer. Make sure that terminal symbols are correct.
- In order to perform maintenance work such as changing the wire layout and replacing equipment, we recommend that you connect protective device (breaker) for the voltage input circuit (P1, P2, and P3 terminals).



- Use the voltage input terminal block to enter the circuit voltage to QE84WH.
   Fix the module by turning the lever until the clicks after inserting the voltage input terminal block.
- When removing a voltage input terminal block from the module, turn the lever in the opposite direction, hold the voltage input terminal part.



### 8.6 Setting from GX Works2

This section explains setting from GX Works2 necessary to use QE84WH. Before performing this setting, install GX Works2 and connect the Management CPU with the PC using a USB cable. For details, refer to the manual of CPU module.

Point

To addition the unit, enable the switch setting, parameter setting and auto refresh, write the settings to the CPU module, and reset the CPU module or power on the programmable controller again.

#### 8.6.1 Addition the unit

Add the model name of the energy measuring module to use the project.

### (1) Addition procedure

Open the "New Module" window.

Project window→[intelligent Function Module]→Right-click→[New Module...]

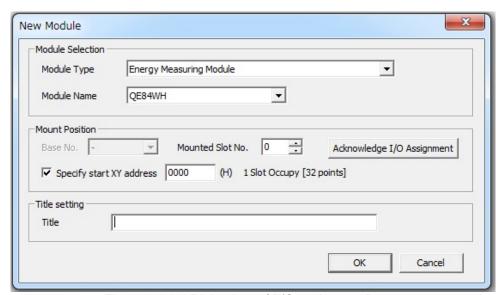


Figure 8.6.1-1 Dialog box of "I/O assignment"

Table 8.6.1-1 Setting items on the "I/O assignment" tab

I abit	Table 6.6.1-1 Setting items on the 1/O assignment tab			
Item		Description		
Module Selection	Module Type	Set [Energy Measuring module].		
	Module Name	Set the name of the module to mount.		
Mount Position Base No.		Set the base No. where the module is mounted.		
Mounted Slot No.		Set the slot No. where the module is mounted.		
	Specify start XY address	The start I/O number (hexadecimal) of the target module is set, according to the mounted slot No. Any start I/O number can be set.		
Title Setting	Title	Set any title.		

### 8.6.2 Setting the intelligent function of the module switch

Set the operation mode.

#### (1)Setting procedure

Open the "Switch Setting" window.

Project window→[intelligent Function Module]→Module name→[Switch Setting]

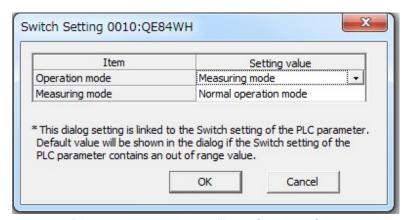


Figure 8.6.2-1 Dialog box to set the intelligent function of the module switch

Table 8.6.2-1 Setting the intelligent function of the module switch

14							
Item	Description	Setting value					
Operation mode	Measurement Mode and test mode are	Measuring mode (default)					
	changed.	Test mode					
Measuring mode	When set measuring mode above setting, set the kind of measuring mode. When set test mode above setting, this setting disable.	Regular operating mode(default) Current measuring mode					

#### 8.6.3 Parameter Setting

Set the parameters.

Setting parameters on the screen omits the parameter setting in a program.

(1)Setting procedure

Open the "Parameter" window.

Project window→[intelligent Function Module]→Module name→[Parameter]

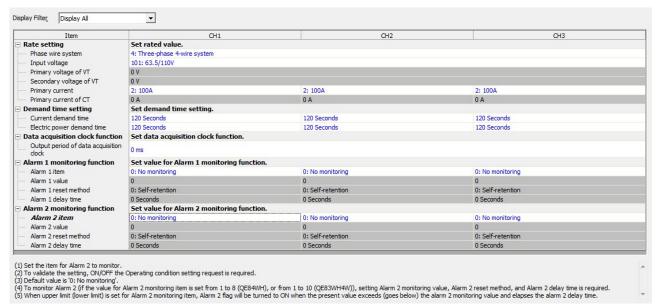


Figure 8.6.3-1 Dialog box to monitor all buffer memories (a case where the module is attached to the slot 0)

(2)Double-click the item to change the setting, and input the setting value.

- Items to input from the pull-down list
   Double-click the item to set to display the pull-down list. Select the item.
- Items to input from the text box
   Double-click the item to set, and input the setting value.
- (3) Setup of CH2 to CH4 is performed by operation of Procedure (2).

ltem		Setting value		Reference
		1:single-phase 2-wire		
	Phase wire system	2:single-phase 3-wire		Section 6.2.1
		3:three-phase 3-wire		
		0:Any setting		
		1:110V		
		2:220V		
		3:220/110V		
	Primary voltage	4:440/110V 5:690/110V		Section 6.2.2
		6:1100/110V		
		7:2200/110V		
		8:3300/110V		
		9:6600/110V		
	Primary voltage of VT	0 V to 6600 V		Section 6.2.2
	Secondary voltage of VT	0 V to 220 V		Section 6.2.2
		0:Any setting	516:100/5A	
		1:50A	517:120/5A	
		2:100A	518:150/5A	
Rate setting		3:250A	519:200/5A	
		4:400A	520:250/5A	
		5:600A	521:300/5A	
		501:5/5A	522:400/5A	
		502:6/5A 503:7.5/5A	523:500/5A 524:600/5A	
		503:7.5/5A 504:8/5A	524:600/5A 525:750/5A	
	Primary current	505:10/5A	526:800/5A	Section 6.2.3
		506:12/5A	527:1000/5A	0.000.000
		507:15/5A	528:1200/5A	
		508:20/5A	529:1500/5A	
		509:25/5A	530:1600/5A	
		510:30/5A	531:2000/5A	
		511:40/5A	532:2500/5A	
		512:50/5A	533:3000/5A	
		513:60/5A 514:75/5A	534:4000/5A 535:5000/5A	
		514.75/5A 515:80/5A	536:6000/5A	
	Primary current of CT	0 A to 6000 A	000.0000/6/1	Section 6.2.3
	Current demand time	0 to 1800 seconds	3	Section 6.2.4
Demand time setting	Electric power demand	0 to 1900 accord		Section 6.2.5
	time	0 to 1800 seconds	5	Section 6.2.5
Data acquisition clock	Output period of data	flag non-use:0		Section 6.2.12
function	acquisition clock	flag use:1 to 8640	0000 ms	
		0:No monitoring		
		1:Current demand upper limit		
		2:Current demand lower limit 3:Voltage upper limit		
	Alarm 1 item	4:Voltage lower lim		Section 6.2.6
		5:Electric power de		
Alarm 1 monitoring function		6:Electric power demand lower limit		
		7:Power factor upper limit		
		8:Power factor lower limit		
	Alarm 1 value	-2147483648 to 21	47483647	Section 6.2.7
	Alarm 1 reset method	0:Self-retention		Section 6.2.8
	Alarm 1 delay time	1:Auto reset 0 to 300 seconds		Section 6.2.9
	rualli i ueldy lillie			36011011 0.2.9
		0:No monitoring 1:Current demand	unner limit	
		2:Current demand	• •	
		3:Voltage upper lim		
	Alarm 2 item	4:Voltage lower lim		Section 6.2.6
		5:Electric power demand upper limit		
Alarm 2 monitoring function		6:Electric power demand lower limit		
,		7:Power factor upper limit		
		8:Power factor lower limit		
	Alarm 2 value	-2147483648 to 21	47483647	Section 6.2.7
	Alarm 2 reset method	0:Self-retention		Section 6.2.8
		1:Auto reset		Section 6.2.9
	µ-varm ∠ deray time	n 2 delay time 0 to 300 seconds		

#### 8.6.4 Auto Refresh

This function transfers data in the buffer memory to specified devices. Programming of reading/writing data is unnecessary.

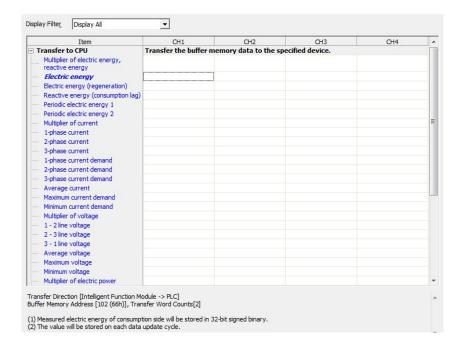
#### (1)Setting procedure

1) Start "Auto Refresh".

Project window→[intelligent Function Module]→Module name→[Auto Refresh]

2) Start "Auto Refresh".

Click the item to set, and input the destination device for auto refresh.



#### Point

Available devices are X, Y, M, L, B, T, C, ST, D, W, R, and ZR.

When a bit device X, Y, M, L, or B is used, set a number that is divisible by 16 points (example: X10, Y120, M16).

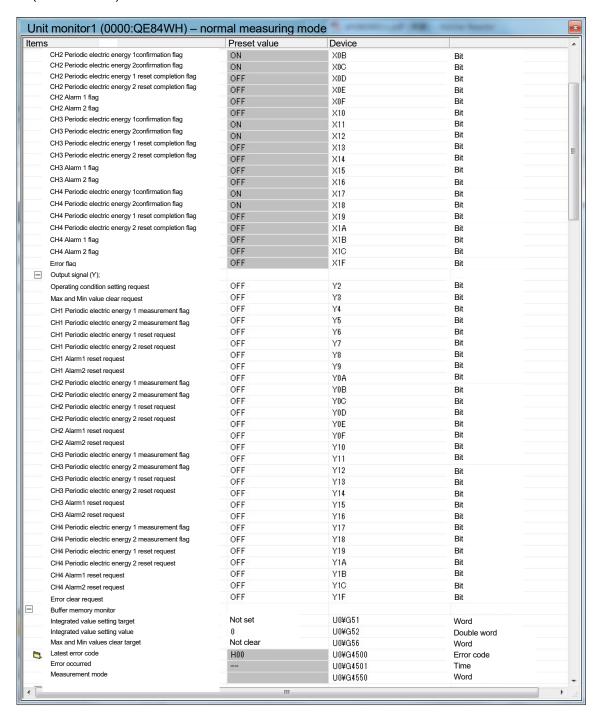
Data in the buffer memory are stored in 16 points of devices starting from the set device No. (Example: When X10 is set, the data are stored in X10 to X1F).

#### 8.6.5 Setting function for integrated value

This function is to set integrated value (electric energy (consumption, regeneration) and reactive energy (consumption lag)) to any value. If you want to clear integrated value, set it to 0.

#### (1)Setting procedure

- Start "Intelligent unit monitor"
  - Project window  $\rightarrow$  [intelligent Function Module]  $\rightarrow$  Module name  $\rightarrow$  Right-Click  $\rightarrow$  [ Intelligent monitor ]
- Set the integrated value setting target(Un¥G51) and integrated value setting value (Un¥G52,3)
- 3) Turn integrated value setting request (Yn3) from OFF to ON to enable the setting. (Refer to 5.2.2).



4) After checking that the Integrated value setting completion flag (Xn3) is in the ON status, turn off the integrated value setting request (Yn3).

The integrated value setting completion flag (Xn3) is OFF, after detect the status is OFF. After detecting Integrated value setting request (Yn3) is in the OFF status, Integrated value setting completion flag (Xn3) turns to OFF.

### (2)Default value

Integrated value setting target (Un¥G51) is set to 0 (No set). Integrated value setting value (Un¥G52,3) is set to 0.

### 8.6.6 Debugging program

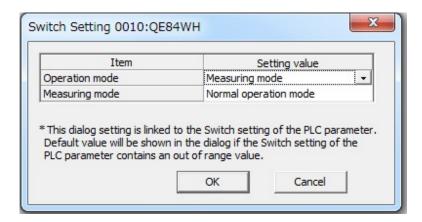
QE84WH provides a test function so that you can debug a program with no input of voltage or current. Pseudo-value can be stored into the buffer memory. For detailed explanation for the test function, refer to 4.2.5.

### --- / Caution

Test function stores pseudo-values for setting value and error information as well as measured value. If you use these data to control the sequence program that controls external devices, there is a chance that erroneous control may occur. For safety of external devices, use this function after disconnecting the device.

-----

- (1) Setting intelligent function of the module switch
  - 1) Configure the operation mode in switch setting as shown below. (Refer to 8.6.2) Test mode transition: Test mode
  - 2) From the "Online" menu, select "Write to PLC" to display the dialog box of Write to PLC, and then execute the writing to PLC parameter. After resetting the CPU module, the value will become effective.



- (2) Starting the test function
  - 1) Reset the CPU module.
  - 2) QE84WH starts in the test function mode. All LEDs are turned on. Pseudo-values are stored in the buffer memory.
- (3) Finishing the test function (Move back to the measuring mode)
  - 1) Following 1) in step (1), Configure the operation mode in switch setting as shown below.

    Test mode transition: Test mode
  - 2) Following 2) in step (1), write the data into PLC.
  - 3) Reset the CPU module, then the operation goes back to the measuring mode.

### 8.7 Setting from GX Developer

This section explains setting from GX Developer necessary to use QE84WH. Before performing this setting, install GX Developer and connect the Management CPU with the PC using a USB cable. For details, refer to the manual of CPU module.

### 8.7.1 I/O assignment setting

- (1) Double-click the dialog box of "PLC Parameter" in the GX Developer Project.
- (2) Click "I/O assignment".
- (3) Set the following item to the slot\*1 to which QE84WH has been attached.

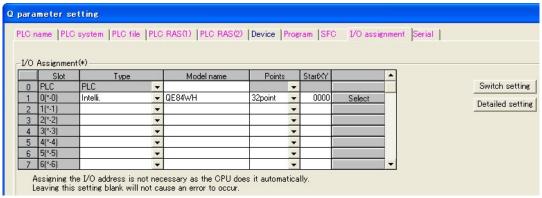


Figure 8.7.1-1 Dialog box of "I/O assignment"

Table 8.7.1-1 Setting items on the "I/O assignment" tab

Item	Descriptions		
Туре	Select "Intelli.".		
Model name	Enter the model name of the module.		
Points	Select 32 points.		
Start XY	Enter the initial I/O number of QE84WH.		

<sup>\*1</sup> is a case where QE84WH is attached to the slot 0.

- 8.7.2 Setting the intelligent function of the module switch
  - (1) In the "I/O assignment" of 8.7.1, click the <u>Switch setting</u> button to display the dialog box of "I/O module, intelligent function module switch setting".
  - (2) The intelligent function module switch setting displays switches 1 to 5; however, only switches 4 and 5 is used for this purpose. Switch setting is configured using 16-bit data. Settings are as shown in Table 8.7.2-1.

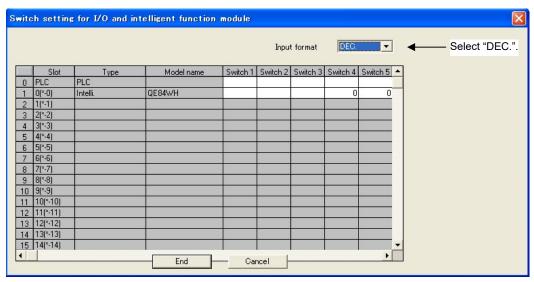


Figure 8.7.2-1 Dialog box to set the intelligent function of the module switch

Table 8.7.2-1 Setting the intelligent function of the module switch

	10.0.0	resumg are intemperation of the medale striten
Swith No.	Switch name	Description
1	Not used	-
2	Not used	-
3	Not used	-
4	Measuring mode selection	O: Regular operating mode 1: Current measuring mode *When switch 5 is set to "1", the test mode is selected.
5	Test mode transition	<ul> <li>0: Measuring mode (Even when this switch is not set, the module runs in the measuring mode.)</li> <li>1: Test mode</li> <li>* For details of test mode, refer to 4.2.5.</li> </ul>

- (3) When the setting is completed, click the Complete setting button.
- (4) From the "Online" menu, select "Write to PLC" to display the dialog box of Write to PLC, and then execute the writing to PLC parameter. After resetting the CPU module, the value will become effective.

#### 8.7.3 Initial setting

This section explains the setting of the operating condition for phase wire system, primary voltage, primary current, current demand time, and voltage demand time, primary voltage of VT, secondary voltage of VT, and primary current of CT that are required for measurement. Once each value is set, these values will be stored in the nonvolatile memory of the module, so that reconfiguration is not needed. You can also perform the setting using sequence program. In this case, you need to create a program, as referring to Chapter 9.

Follow the procedure below for each setting.

- (1) Check the current setting
- (2) Set the Buffer memory
- (1) Check the current setting
  - From the "Online" menu, select "Monitor" "Buffer memory batch ...". The dialog box to monitor all buffer memories. After setting the address as shown below, click the Start monitoring button to check the current buffer memory status.

Module initial address: Set the initial address of this module.

Buffer memory address: 0

(Display: 16-bit integer, numerical value: check the number in decimal)

2) Check each item. The following shows items for operating condition settings. For specific setting value, see the provided references.

Table 8.7.3-1 List of setting items

Buffer memory address			Item	Reference	
CH1	CH2	CH3	CH4		
	Un\G0 (Comm	non to all CHs)		Phase wire system	Section 6.2.1
	Un\G1 (Comm	non to all CHs)		Primary voltage	Section 6.2.2
Un\G2	Un\G1002	Un\G2002	Un\G3002	Primary current	Section 6.2.3
Un\G3	Un\G1003	Un\G2003	Un\G3003	Current demand time	Section 6.2.4
Un\G4	Un\G1004	Un\G2004	Un\G3004	Electric power demand	Section 6.2.5
				time	
Un\G5 (Common to all CHs)			Primary voltage of VT	Section 6.2.2	
Un\G6 (Common to all CHs)			Secondary voltage of VT	Section 6.2.2	
Un\G7	Un\G1007	Un\G2007	Un\G3007	Primary current of CT	Section 6.2.3

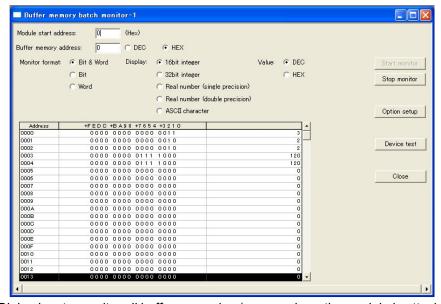


Figure 8.7.3-1 Dialog box to monitor all buffer memories (a case where the module is attached to the slot 0)

- (2) Set the Buffer memory
  - 1) In the dialog box to monitor all buffer memories, click the Device test dialog box.
  - 2) In the Word device / buffer memory, specify the module initial address and buffer address, and click the Set button to apply the setting.

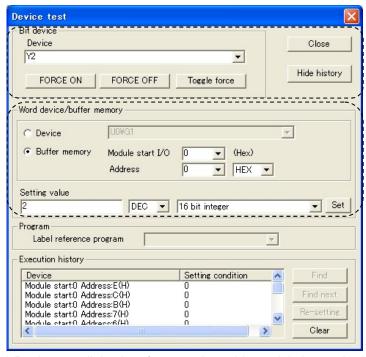


Figure 8.7.3-2 Device test dialog box (a case where this module is attached to the slot 0)

- 3) Change the setting in 2).
- 4) In the section of bit device setting in the device test dialog box, select "Y2"\* and click the FORCE ON button.
- 5) When the setting is completed without any problem, the Device "X2"\* changes to ON. Check this using the procedure as follows:
  - (a) From the "Online" menu, select "Monitor" "Device batch ...". The dialog box to monitor all devices is displayed.
  - (b) Set "X0"\* to the device, and click "Start monitor"
  - (c) Check that Device "X2" is in the ON status.

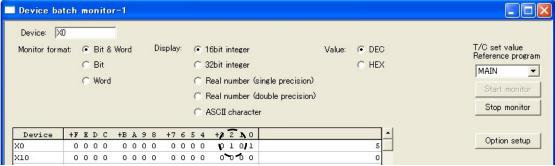


Figure 8.7.3-3 Checking the device "X2"\* in the dialog box to monitor all devices

- 6) After checking that the device "X2"\* is in the ON status, select "Device: "Y2"\* in the dialog box of device test, and then click the FORCE OFF button. Setting is completes.
- 7) If the Device "X2"\* is not in the ON status, this means an error because the set value is out of range (ERR.LED is flashing). Modify the setting, and change the device "Y2" to the OFF status, then change it back to the ON status.

<sup>\*</sup> Indicates a number in the case where the initial I/O number (initial XY) is set to 0.

#### 8.7.4 Integrated value setting

This function is to set integrated value ( electric energy ( consumption, regeneration ) and reactive energy (consumption lag) ) to any value. If you want to clear integrated value, set it to 0.

(1) Check the current setting

1) From the "Online" menu, select "Monitor" – "Entry data monitor". After registering the address as shown below, click the <u>Start monitoring</u> button to check the current buffer memory status.

Table 8.7.4-1 List of setting items

Items	Buffer memory	Display
Integrated value setting target	Un¥G51	16bit
Integrated value setting value	Un¥G52	32bit
Electric energy(consumption)	Un¥G102	16bit
Integrated value set request	YC	16bit
Integrated value set completion flag	XC	16bit

- 2) Check item.
- (a) Set integrated value setting target (Un¥G51) in the buffer memory. Setting range is as follows:

Table 8.7.4-2 List of setting items

Setting value	Description	
0	No set	
1	Electric energy (consumption)	
2	Electric energy (regeneration)	
3	Reactive energy (consumption lag)	

- (b) Set integrated value setting value (Un¥G52, 53) in the buffer memory.
  - Configurable range: 0 to 999999999
  - The unit used for the setting value is the same as that used for the electric energy and reactive energy that are output to the buffer memory.

For details, refer to section 6.3.1.

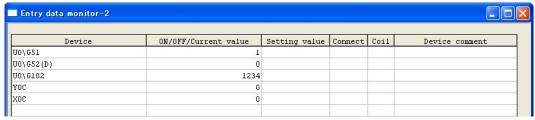


Figure 8.7.4-1 Dialog box to Entry data monitor (a case where the module is attached to the slot 0)

#### (2) Setting function for integrated value

This function is to set integrated value (electric energy (consumption, regeneration) and reactive energy (consumption lag)) to any value. If you want to clear integrated value, set it to 0.

- 1) In the dialog box to monitor all buffer memories, click the Device test dialog box.
- 2) In the Word device / buffer memory, specify the module initial address and buffer address, and click the Set button to apply the setting.

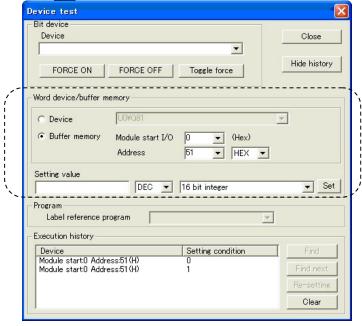


Figure 8.7.4-2 Device test dialog box (a case where this module is attached to the slot 0)

- 3) Change the setting in 2).
- 4) In the section of bit device setting in the device test dialog box, select "YC"\* and click the FORCE ON button.
- 5) When the setting is completed without any problem, the Device "XC"\* changes to ON.

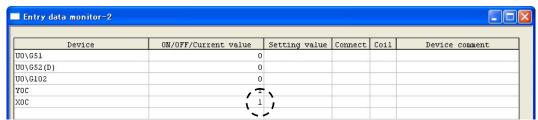


Figure 8.7.4-3 Checking the device "XC"\* in the dialog box to Entry data monitor

- 6) After checking that the device "XC"\* is in the ON status, select "Device: "YC"\* in the dialog box of device test, and then click the FORCE OFF button. Setting is completes.
- \* Indicates a number in the case where the initial I/O number (initial XY) is set to 0.

### 8.7.5 Debugging program

QE84WH provides a test function so that you can debug a program with no input of voltage or current. Pseudo-value can be stored into the buffer memory. For detailed explanation for the test function, refer to 4.2.5.

# r-- /t Caution

Test function stores pseudo-values for setting value and error information as well as measured value. If you use these data to control the sequence program that controls external devices, there is a chance that erroneous control may occur. For safety of external devices, use this function after disconnecting the device.

- (1) Setting intelligent function of the module switch
  - 1) In the "I/O assignment setting" of 8.7.1, click the Switch setting button to display the dialog box of "I/O module, intelligent function module switch setting". (Refer to 8.7.2)
  - 2) The intelligent function module switch setting displays switches 1 to 5; however, use switch 5 when using the test function. Switch setting is configured using 16-bit data. Setting is as follows:

Switch 5: "1"

- 3) When the setting is completed, click the End button.
- 4) From the "Online" menu, select "Write to PLC" to display the dialog box of Write to PLC, and then execute the writing to PLC parameter. After resetting the CPU module, the value will become effective.
- (2) Starting the test function
  - 1) Reset the CPU module.
  - 2) QE84WH starts in the test function mode. All LEDs are turned on. Pseudo-values are stored in the buffer memory.
- (3) Finishing the test function (Move back to the measuring mode)
  - 1) Following 1) and 2) in step (1), configure the intelligent function switch setting as shown below.

Switch 5: "0"

- 2) Following 3) and 4) in step (1), complete the setting and write the data into PLC.
- 3) Reset the CPU module, then the operation goes back to the measuring mode.

9 Programing QE84WH

### Chapter 9: Programming

This chapter explains about programming for QE84WH.

When you apply sample programs introduced in this chapter into the actual system, make sure to verify in advance that there is no problem with the target system control.

Follow the procedure in Figure 9.1-1 to create a sample program using QE84WH.

The default setting allows you to use either GX Works2 (Regular operating mode: refer to 8.6. Current measuring mode: refer to 7.8.), GX Developer (refer to 8.7) or the sequence program to make settings; however, if the setting is made for the first time by using GX Works2 or GX Developer, the program for initial setting can be eliminated, which will reduce time for scanning.

#### 9.1 Programming procedure

Follow the procedure in Figure 9.1-1 to create a program for acquiring the measured data, alarm monitoring, calculating periodical electricity amount using QE84WH.

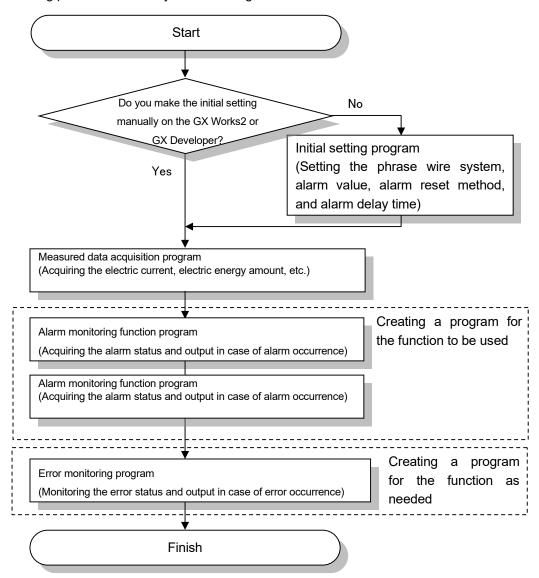


Figure 9.1-1 Programming chart

#### 9.2 System configuration and usage conditions for sample program

A sample program under the following system and the usage condition is shown below.

#### (1) System configuration

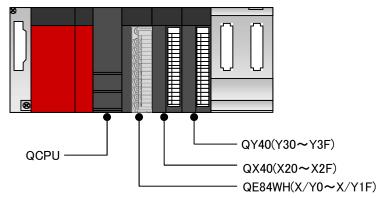


Figure 9.2-1 Sample system configuration using a sample program

(2) Setting conditions for the intelligent function of the module switch Setting is as follows:

Table 9.2-1 Setting the intelligent function of the module switch

Switch No.	Switch name	Description
1	Not used	-
2	Not used	-
3	Not used	-
4	Measuring mode selection	0 (Regular measuring mode)
5	Operation mode	0 (Measuring mode)

#### (3) Programming conditions

(a) Setting the operating conditions

- Phase wire : Three-phase 3-wire- Primary voltage : 220 V

- Primary current : 250 A- Current demand time

Current demand time : 30 sec
Electric power demand time : 30 sec
Primary voltage of VT : 0
Secondary voltage of VT : 0
Primary current of CT : 0

(b) Alarm monitoring setting

- Alarm 1 item : Current demand upper limit

- Alarm 1 value : 100000 (100 A)
 - Alarm 1 reset method : Auto reset
 - Alarm 1 delay time : 5 sec

- Alarm 2 item : Current demand upper limit

- Alarm 2 value : 120000 (120 A)
- Alarm 2 reset method : Self-retention

- Alarm 2 delay time : 5 sec

(c) Data acquisition clock setting

- Output period of data acquisition clock: 1000 (1sec)

(4) Before creating a program

Before creating a program, attach QE84WH to the base unit, and connect it to external devices.

Electric current sensor: EMU-CT250

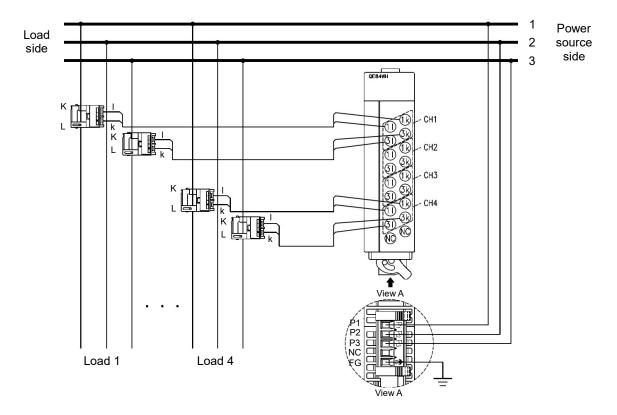


Figure 9.2-2 Example of wiring using a sample program

# 9.2.1 Sample program when make the initial setting using GX Works2 or GX Developer.

# (1) List of devices

Table 9.2.1-1 List of devices

Device	Function			
D30	Device that stores latest error code			
X0	Module ready			
X2	Operating condition setting completion flag			
X9	CH1 Alarm 1 flag			
XA	CH1 Alarm 2 flag	05040411		
XB	CH2 Alarm 1 flag	QE84WH		
XC	CH2 Alarm 2 flag	(X/Y0 to X/Y1F)		
X1F	Error flag			
Y2	Operating condition setting request			
YA	CH1 Alarm 2 reset request			
YC	CH2 Alarm 2 reset request			
X21	Device that the user will turn ON in order to cancel error after CH1 alarm 2 occur	QX40 (X20 to X2F)		
X2E	Device that the user will turn ON in order to support measurement of CH1 periodic electric energy			
X2F	Device that the user will turn ON in order to reset integrated value of CH1			
Y30	Device that turns ON to send an output to the external device when the CH1 alarm 1 occurs	QY40 (Y30 to Y3F)		
Y31	Device that turns ON to send an output to the external device when the CH1 alarm 2 occurs			
Y3F	Device that turns ON to send an output to the external device in the case of an error			

# (2) List of buffer memories to be used

Table 9.2.1-2 List of buffer memories to be used

Device	Description	Setting value	Remarks
U0\G4500	Latest error code	-	Stores latest error code

# (3) Sample program

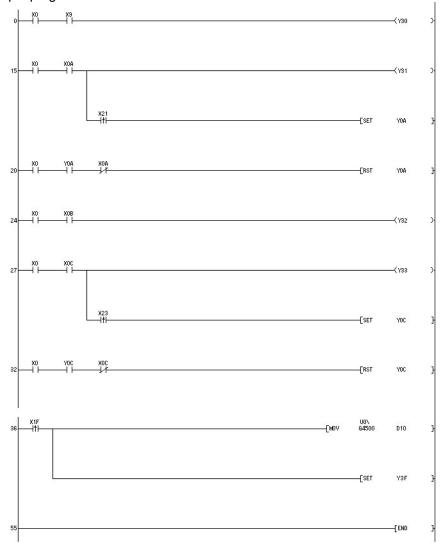


Figure 9.2.1-1 Example of a sample program

# 9.2.2 Sample program when make the initial setting using sequence program.

# (1) List of devices

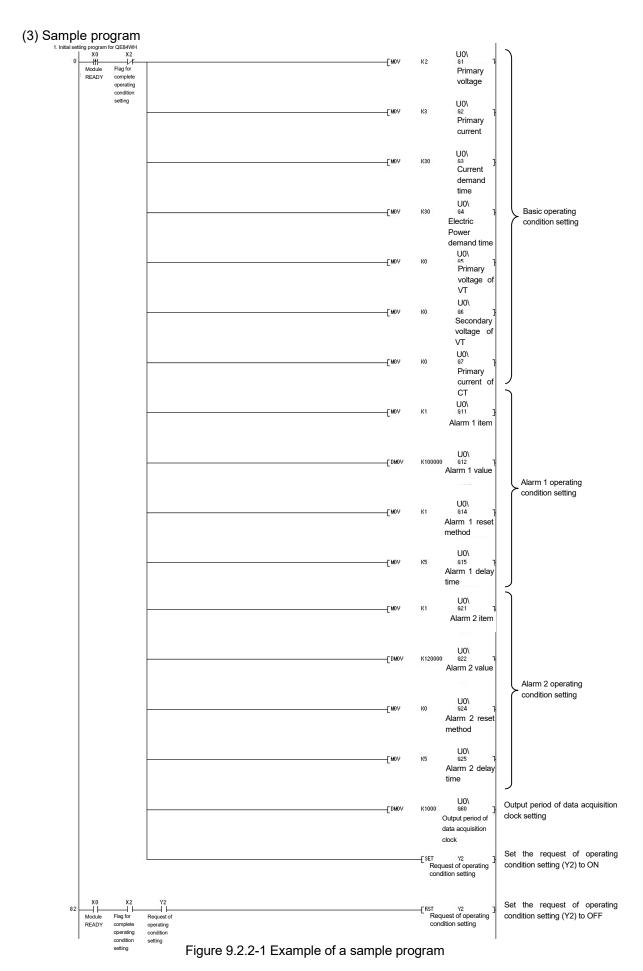
Table 9.2.2-1 List of devices

Device	Function			
D0, D1	Device that stores Multiplier of electric energy			
D2, D3	Device that stores electric energy (consumption)			
D4, D5	Periodic electric energy 1			
D6, D7	Periodic electric energy 2			
D8, D9	Device that stores average current			
D10, D11	Device that stores average voltage			
D12, D13	Device that stores electric power			
D14, D15	Device that stores reactive power			
D16, D17	Device that stores power factor			
D18, D19	Device that stores frequency			
D30	Device that stores latest error code			
X0	Module ready			
X1	Data acquisition clock			
VO	Operating condition setting			
X2	completion flag			
X9	Alarm 1 flag			
XA	Alarm 2 flag	0504)4/1		
X1F	Error flag	QE84WH		
Y2	Operating condition setting request	(X/Y0 to X/Y1F)		
VE	Periodic electric energy 1			
Y5	measurement flag			
VC	Periodic electric energy 2			
Y6	measurement flag			
Y0A	CH1 Alarm 2 reset request			
	Device that the user will turn ON in			
X21	order to cancel error after CH1 alarm			
	2 occur			
	Device that the user will turn ON in	QX40		
X2E	order to support measurement of	(X20 to X2F)		
	CH1 periodic electric energy	(X20 to X21 )		
	Device that the user will turn ON in			
X2F	order to reset integrated value of			
	CH1			
	Device that turns ON to send an			
Y30	output to the external device when			
	the CH1 alarm 1 occurs			
	Device that turns ON to send an	QY40		
Y31	output to the external device when	(Y30 to Y3F)		
	the CH1 alarm 2 occurs	,		
	Device that turns ON to send an			
Y3F	output to the external device in the			
	case of an error			

# (2) List of buffer memories to be used

Table 9.2.2-2 List of buffer memories to be used

Device	Description	Setting value	Remarks	
U0\G0	Phase wire method	3	Three-phase 3-wire	
U0\G1	Primary voltage	2	220 V	
U0\G2	Primary current	3	250 A	
U0\G3	Current demand time	30	30 sec	
U0\G4	Electric power demand time	30	30 sec	
U0\G5	Primary voltage of VT	0	When Primary voltage(U0\G1) is axpect 0	
U0\G6	Secondary voltage of VT	0	When Primary voltage(U0\G1) is axpect 0	
U0\G7	Primary current of CT	0	When Primary current (U0\G2) is axpect 0	
U0\G11	Alarm 1 item	1	Current demand upper limit	
U0\G12, 13	Alarm 1 value	100000	100 A	
U0\G14	Alarm 1 reset method	1	Auto reset	
U0\G15	Alarm 1 delay time	5	5 sec	
U0\G21	Alarm 2 item	1	Current demand upper limit	
U0\G22, 23	Alarm 2 value	120000	120 A	
U0\G24	Alarm 2 reset method	0	Self-retention	
U0\G25	Alarm 2 delay time	5	5 sec	
U0\G60,61	Output period of data acquisition clock	1000	1 sec	
U0\G100	Multiplier of electric energy	-	Stores multiplier of electric energy	
U0\G102, 103	Electric energy (consumption)	-	Stores electric energy	
U0\G114,115	Periodic electric energy 1	-	Stores Periodic electric energy 1	
U0\G116,117	Periodic electric energy 2	-	Stores Periodic electric energy 2	
U0\G218, 219	Average current	-	Stores average current	
U0\G314, 315	Average voltage	-	Stores average voltage	
U0\G402, 403	Electric power	-	Stores Electric power	
U0\G502, 503	Reactive power	-	Stores Reactive power	
U0\G702, 703	Power factor	-	Stores power factor	
U0\G802, 803	Frequency	-	Stores frequency	
U0\G51	Integrated value setting target	19	CH1 Total integrated value	
U0\G52,53	Integrated value setting value	0	0kWh(kvarh)	
U0\G4500	Latest error code	-	Stores latest error code	



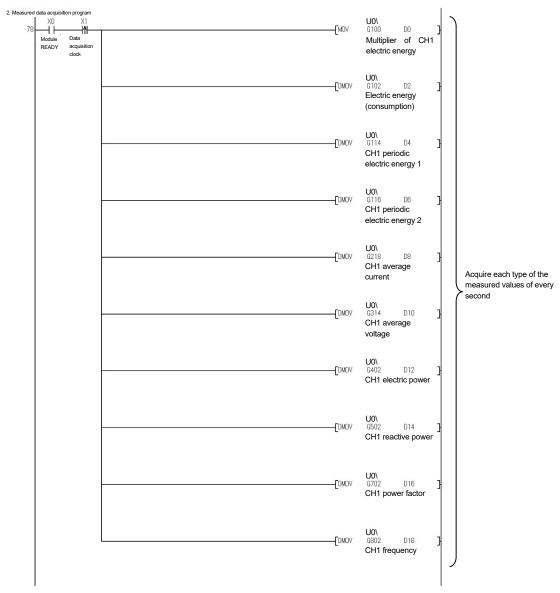


Figure 9.2.2-2 Example of a sample program (continued)

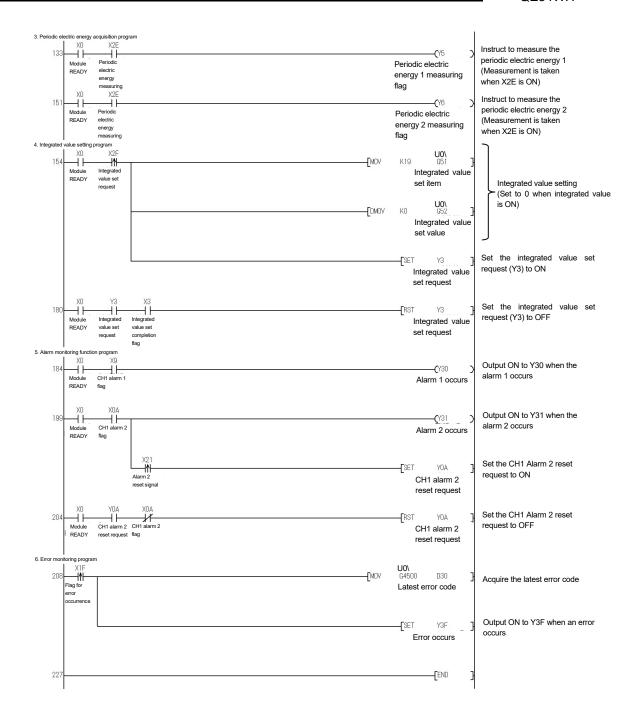


Figure 9.2.2-3 Example of a sample program (continued)

QE84WH

#### 9.3 System configuration and usage conditions for current measuring mode

A sample program is shown below based on the following system and the usage condition.

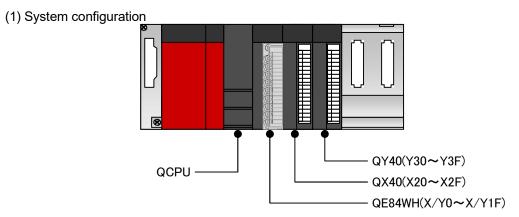


Figure 9.3-1 Sample system configuration using a sample program

(2) Setting conditions for the intelligent function module switch

#### Setting is as follows:

Table 9.3-1 Intelligent function module switch setting

Switch No.	Switch name	Description	
1	Not used	-	
2	Not used	-	
3	Not used	-	
4	Measuring mode selection	1 (Current measuring mode)	
5	Operation mode	0 (Measuring mode)	

#### (3) Programming conditions

(a)Operating condition setting

- Channel to be used : CH1, CH2 - Primary current : 250 A

- CH1 and CH2 current demand time : 30 sec. (Setting the operating conditions)
- Primary current of CT : 0 (When Primary current (U0\G4003) is axpect 0)

#### (b) Alarm monitoring setting

- CH1 and CH2 alarm 1 item : Maximum current demand

- CH1 and CH2 alarm 1 value : 100000 (100 A)
- CH1 and CH2 alarm 1 reset method : Auto reset

- CH1 and CH2 alarm 1 delay time : 5 sec.

- CH1 and CH2 alarm 2 item : Maximum current demand

- CH1 and CH2 alarm 2 value : 120000 (120 A)

- CH1 and CH2 alarm 2 reset method : Self-retention

- CH1 and CH2 alarm 2 delay time : 5 sec.

### (c) Data acquisition clock setting

- Output period of data acquisition clock: 500 (0.5 sec.)

# (4) Before creating a program

Before creating a program, attach QE84WH to the base unit, and connect it to external devices.

Electric current sensor: EMU-CT250 (Split type)

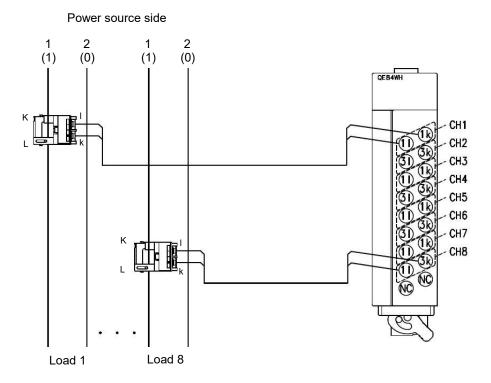


Figure 9.3-2 Example of wiring using a sample program

9.3.1 Sample program when make the initial setting using GX Works2 or GX Developer. A sample program is shown below based on the following system and the usage condition.

# (1) List of devices

Table 9.3.1-1 List of devices

Device	Function		
D0, D1	Device that stores CH1 current		
D4, D5	Device that stores CH2 current		
D10	Device that stores latest error code		
X0	Module ready		
X1	Data acquisition clock		
\ \\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	Operating condition setting		
X2	completion flag		
X9	CH1 alarm 1 flag		
XA	CH1 alarm 2 flag	QE84WH	
ХВ	CH2 alarm 1 flag	(X/Y0 to X/Y1F)	
XC	CH2 alarm 2 flag		
X1F	Error flag		
Y2	Operating condition setting request		
YA	CH1 alarm2 reset request.		
YC	CH2 alarm2 reset request.		
V04	Device that the user will turn ON in order		
X21	to cancel error after CH1 alarm 2 occur	QX40	
V00	Device that the user will turn ON in order	(X20 to X2F)	
X23	to cancel error after CH2 alarm 2 occur		
	Device that turns ON to send an output to		
Y30	the external device when the CH1 alarm		
	1 occurs		
	Device that turns ON to send an output to		
Y31	the external device when the CH1 alarm		
	2 occurs		
	Device that turns ON to send an output to	QY40	
Y32	the external device when the CH2 alarm	(Y30 to Y3F)	
	1 occurs	(100 to 101)	
Y33	Device that turns ON to send an output to		
	the external device when the CH2 alarm		
	2 occurs		
	Device that turns ON to send an		
Y3F	output to the external device in the		
	case of an error		

# (2) List of buffer memories to be used

Table 9.3.1-2 List of buffer memories to be used

Device	Description		Setting value	Remarks
U0\G4003	CH1 and	Primary current	3	250 A
U0\G4004	CH1	Current demand time	30	30 sec.
U0\G4054	CH2	Current demand time	30	30 sec.
U0\G4005	CH1	Primary current of CT	0	When Primary current (U0¥G4003) is axpect 0
U0\G4011	CH1	Alarm 1 item	1	Maximum current demand
U0\G4012, 4013		Alarm 1 value	100000	100 A
U0\G4014		Alarm 1 reset method	1	Auto reset
U0\G4015		Alarm 1 delay time	5	5 sec.
U0\G4021		Alarm 2 item	1	Maximum current demand
U0\G4022, 4023		Alarm 2 value	120000	120 A
U0\G4024		Alarm 2 reset method	0	Self-retention
U0\G4025		Alarm 2 delay time	5	5 sec.
U0\G4061	CH2	Alarm 1 item	1	Maximum current demand
U0\G4062, 4063		Alarm 1 value	1000000	100 A
U0\G4064		Alarm 1 reset method	0	Auto reset
U0\G4065		Alarm 1 delay time	5	5 sec.
U0\G4071		Alarm 2 item	1	Maximum current demand
U0\G4072, 4073		Alarm 2 value	120000	120 A
U0\G4074		Alarm 2 reset method	0	Self-retention
U0\G4075		Alarm 2 delay time	5	5 sec.
U0\G4000, 4001	All CHs	Output period of data acquisition clock	500	0.5 sec.
U0\G4032, 4033	CH1	Current	-	Stores the current measurement.
U0\G4082, 4083	CH2	Current	-	Stores the current measurement.
U0\G4500	Latest erro	or code	-	Stores the latest error code.

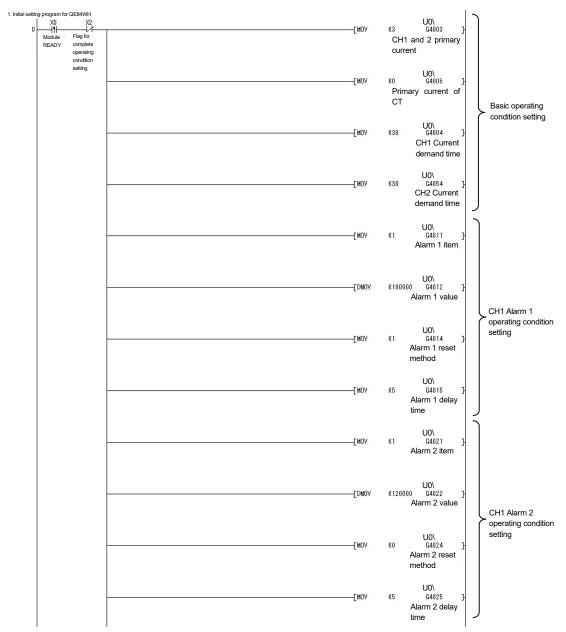


Figure 9.3.1-1 Example of a sample program

QE84WH

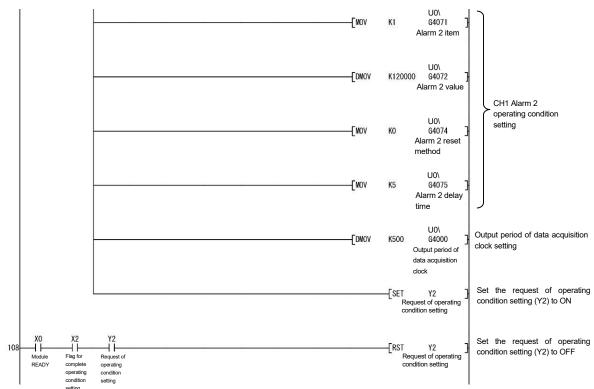


Figure 9.3.1-2 Example of a sample program (continued)

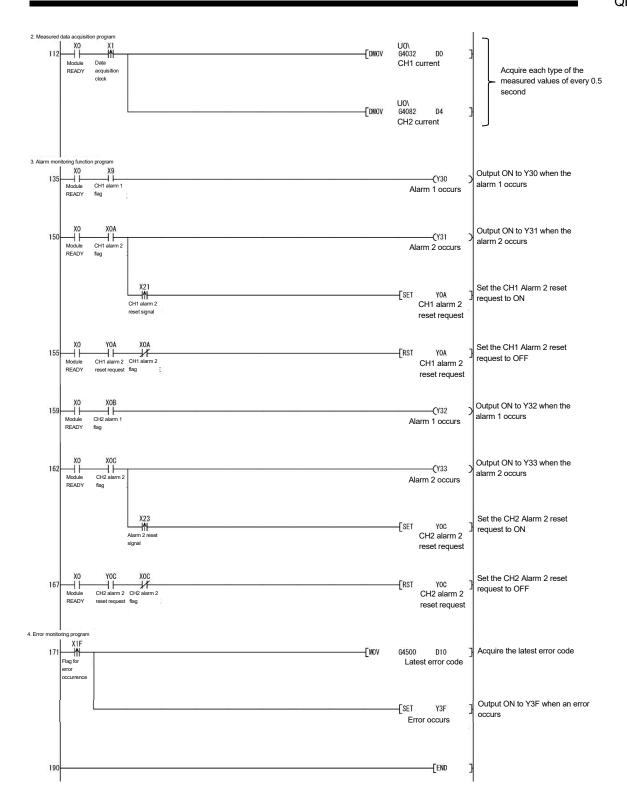


Figure 9.3.1-3 Example of a sample program (continued)

QE84WH

9.3.2 Sample program when make the initial setting using sequence program.

A sample program is shown below based on the following system and the usage condition.

# (1) List of devices

Table 9.3.2-1 List of devices

Device	Function	on				
D0, D1	Device that stores CH1 current					
D4, D5	Device that stores CH2 current					
D10	Device that stores latest error code	Device that stores latest error code				
X0	Module ready					
X1	Data acquisition clock					
¥0	Operating condition setting					
X2	completion flag					
X9	CH1 alarm 1 flag					
XA	CH1 alarm 2 flag	QE84WH				
ХВ	CH2 alarm 1 flag	(X/Y0 to X/Y1F)				
XC	CH2 alarm 2 flag					
X1F	Error flag					
Y2	Operating condition setting request					
YA	CH1 alarm2 reset request.					
YC	CH2 alarm2 reset request.					
V04	Device that the user will turn ON in order					
X21	to cancel error after CH1 alarm 2 occur	QX40				
V00	Device that the user will turn ON in order	(X20 to X2F)				
X23	to cancel error after CH2 alarm 2 occur					
	Device that turns ON to send an output to					
Y30	the external device when the CH1 alarm					
	1 occurs					
	Device that turns ON to send an output to					
Y31	the external device when the CH1 alarm					
	2 occurs					
	Device that turns ON to send an output to	QY40				
Y32	the external device when the CH2 alarm	(Y30 to Y3F)				
	1 occurs	- (130 to 131)				
Y33	Device that turns ON to send an output to					
	the external device when the CH2 alarm					
	2 occurs					
	Device that turns ON to send an					
Y3F	output to the external device in the					
	case of an error					

# (2) List of buffer memories to be used

# Table 9.3.2-2 List of buffer memories to be used

Device	Description		Setting	Remarks
			value	
U0\G4003	CH1 and CH2	Primary current	3	250 A
U0\G4004	CH1	Current demand time	30	30 sec.
U0\G4054	CH2	Current demand time	30	30 sec.
U0\G4005	CH1	Primary current of CT	0	When Primary current (U0¥G4003) is axpect 0
U0\G4011	CH1	Alarm 1 item	1	Maximum current demand
U0\G4012, 4013		Alarm 1 value	100000	100 A
U0\G4014		Alarm 1 reset method	1	Auto reset
U0\G4015		Alarm 1 delay time	5	5 sec.
U0\G4021		Alarm 2 item	1	Maximum current demand
U0\G4022, 4023		Alarm 2 value	120000	120 A
U0\G4024		Alarm 2 reset method	0	Self-retention
U0\G4025		Alarm 2 delay time	5	5 sec.
U0\G4061	CH2	Alarm 1 item	1	Maximum current demand
U0\G4062, 4063		Alarm 1 value	1000000	100 A
U0\G4064		Alarm 1 reset method	0	Auto reset
U0\G4065		Alarm 1 delay time	5	5 sec.
U0\G4071		Alarm 2 item	1	Maximum current demand
U0\G4072, 4073		Alarm 2 value	120000	120 A
U0\G4074		Alarm 2 reset method	0	Self-retention
U0\G4075		Alarm 2 delay time	5	5 sec.
U0\G4000, 4001	All CHs	Output period of data acquisition clock	500	0.5 sec.
U0\G4032, 4033	CH1	Current	-	Stores the current measurement.
U0\G4082, 4083	CH2	Current	-	Stores the current measurement.
U0\G4500	Latest error code		-	Stores the latest error code.

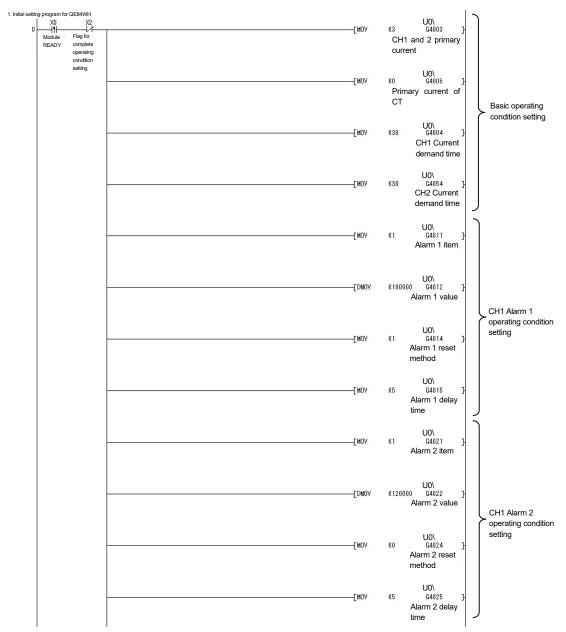


Figure 9.3.2-1 Example of a sample program

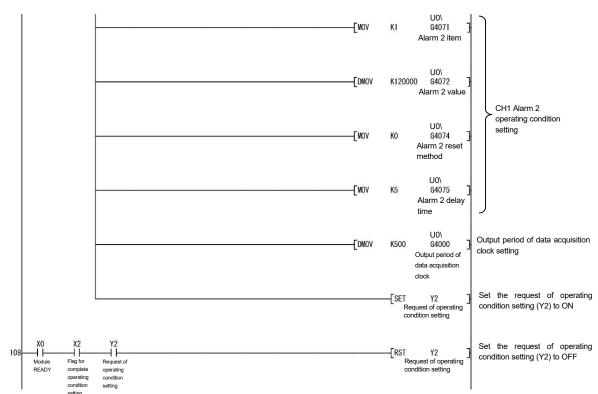


Figure 9.3.2-2 Example of a sample program (continued)

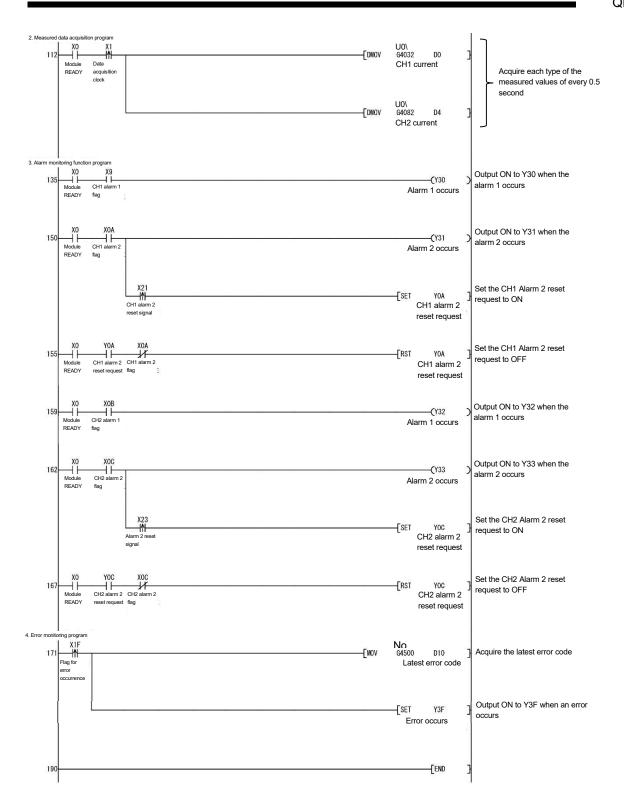


Figure 9.3.2-3 Example of a sample program (continued)

# Chapter 10: Troubleshooting

<b>ACALITION</b>	If abnormal sound, a smell, smoke, and generation of heat occur from this apparatus, please turn off the power immediately and stop use.
ZECAUTION	please turn off the power immediately and stop use.

#### 10.1 List of error codes

When the data are written to the CPU module from this module or when a reading error occurs, error codes will be stored into the following buffer memory.

Table 10.1-1 Latest error code, storage destination upon error occurrence

Latest error code	Time of error occurrence
Un\G4500	Un\G4501 to Un\G4504

Table below shows error codes.

#### Table 10.1-2 List of error codes

Table 10.1-2 List of error codes					
Error code (HEX)	Error level	Measuring mode	Descriptions	Action	Reference
0001h 0002h 0003h	Mid	All modes	Turn the power OFF/ON.  If the error recurs, the module may have a failure. Consult with a nearest sales agent or our company branch for the symptom of the failure.		-
1001h	Low	Regular operating	Phase wire method is set out of range.	Check phase wire method, and set it within 1-3.	Section 6.2.1
1002h	Low	Regular operating	Primary voltage is set out of range.	Set it within 0 to 9 according to the primary voltage.	Section 6.2.2
1003h (CH1), 1013h (CH2) 1023h (CH3), 1033h (CH4)	Low	Regular operating	Primary current is set out of range.	Set it within the range* of 0 to 5, 501 to 536 according to the primary current.	Section 6.2.3
1004h (CH1), 1014h (CH2) 1024h (CH3), 1034h (CH4)	Low	Regular operating	Current demand time is set out of range.	Set current demand time within the range* of 0 to 1800 (seconds).	Section 6.2.4
1005h (CH1), 1015h (CH2) 1025h (CH3), 1035h (CH4)	Low	Regular operating	Electric power demand time is set out of range.	Set electric power demand time within the range* of 0 to 1800 (seconds).	Section 6.2.5
100Dh	Low	Regular operating	Primary voltage of VT is set out of range.	Set primary voltage of VT within the range* of 0 to 6600 (V).  However, this setting cannot set 0 (any setting) when primary voltage (Un¥G1) is 0.	Section 6.2.2
100Eh	Low	Regular operating	Secondary voltage of VT is set out of range.	Set secondary voltage of VT within the range* of 0 to 220 (V). However, this setting cannot set 0(any setting) when primary voltage (Un\G1) is 0.	Section 6.2.2
100Fh (CH1), 101Fh (CH2) 102Fh (CH3), 103Fh (CH4)	Low	Regular operating	Primary current of CT is set out of range.	Set primary current of CT within the range* of 0 to 6000 (A).  However, this setting cannot set 0(any setting) when primary current (Un\G2) is 0	Section 6.2.3
1006h (CH1), 1016h (CH2) 1026h (CH3), 1036h (CH4)	Low	Regular operating	Alarm 1 item is set out of range.	Set alarm 1 item within 1 to 8.	Section 6.2.6
1007h (CH1), 1017h (CH2) 1027h (CH3), 1037h (CH4)	Low	Regular operating	Alarm 2 item is set out of range.	Set alarm 2 item within 1 to 8.	Section 6.2.6
1008h (CH1), 1018h (CH2) 1028h (CH3), 1038h (CH4)	Low	Regular operating	Alarm 1 reset method is set out of range.	Set alarm 1 reset method within 0 to 1.	Section 6.2.8
1009h (CH1), 1019h (CH2) 1029h (CH3), 1039h (CH4)	Low	Regular operating	Alarm 2 reset method is set out of range.	Set alarm 2 reset method within 0 to 1.	Section 6.2.8
100Ah(CH1), 101Ah(CH2) 102Ah(CH3), 103Ah(CH4)	Low	Regular operating	Alarm 1 delay time is set out of range.	Set alarm 1 delay time within the range* of 0 to 300 (seconds).	Section 6.2.9
100Bh(CH1), 101Bh(CH2) 102Bh(CH3), 103Bh(CH4)	Low	Regular operating	Alarm 2 delay time is set out of range.	Set alarm 2 delay time within the range* of 0 to 300 (seconds).	Section 6.2.9
100Ch	Low	Regular operating	Integrated value setting value is set out of range.	Set integrated value setting value within the range* of 0 to 9999999999 in the double word format (32-bit integer).	Section 6.2.10
1041h	Low	Regular operating	Output period of data acquisition clock is set out of range.	Set the output period of data acquisition clock within the range* of 0 to 86400000 in the double word format (32-bit integer).	Section 6.2.12

Error code	Error	Measuring			
(HEX)	level	mode	Descriptions	Action	Reference
2000h	Low	Current measuring	Output period of data acquisition clock is set out of range.	Set the output period of data acquisition clock within the range* of 0 to 86400000 in the double word format (32-bit integer).	Section 6.2.12
2001h(CH1), 2021h(CH3) 2041h(CH5), 2061h(CH7)	Low	Current measuring	Primary current is set out of range.	Set it within the range* of 0 to 5 or 501 to 536 according to the primary current.	Section 6.2.3
2002h(CH1), 2012h(CH2) 2022h(CH3), 2032h(CH4) 2042h(CH5), 2052h(CH6) 2062h(CH7), 2072h(CH8)	Low	Current measuring	Current demand time is set out of range.	Set the current demand time within the range* of 0 to 1800 (seconds).	Section 6.2.4
2003h(CH1), 2013h(CH2) 2023h(CH3), 2033h(CH4) 2043h(CH5), 2053h(CH6) 2063h(CH7), 2073h(CH8)	Low	Current measuring	Alarm 1 item is set out of range.	Set the alarm 1 item within the range of 0 to 2.	Section 6.2.6
2004h(CH1), 2014h(CH2) 2024h(CH3), 2034h(CH4) 2044h(CH5), 2054h(CH6) 2064h(CH7), 2074h(CH8)	Low	Current measuring	Alarm 2 item is set out of range.	Set the alarm 2 item within the range of 0 to 2.	Section 6.2.6
2005h(CH1), 2015h(CH2) 2025h(CH3), 2035h(CH4) 2045h(CH5), 2055h(CH6) 2065h(CH7), 2075h(CH8)	Low	Current measuring	Alarm 1 reset method is set out of range.	Set the alarm 1 reset method within the range of 0 to 1.	Section 6.2.8
2006h(CH1), 2016h(CH2) 2026h(CH3), 2036h(CH4) 2046h(CH5), 2056h(CH6) 2066h(CH7), 2076h(CH8)	Low	Current measuring	Alarm 2 reset method is set out of range.	Set the alarm 2 reset method within the range of 0 to 1.	Section 6.2.8
2007h(CH1), 2017h(CH2) 2027h(CH3), 2037h(CH4) 2047h(CH5), 2057h(CH6) 2067h(CH7), 2077h(CH8)	Low	Current measuring	Alarm 1 delay time is set out of range.	Set the alarm 1 delay time within the range* of 0 to 300 (seconds).	Section 6.2.9
2008h(CH1), 2018h(CH2) 2028h(CH3), 2038h(CH4) 2048h(CH5), 2058h(CH6) 2068h(CH7), 2078h(CH8)	Low	Current measuring	Alarm 2 delay time is set out of range.	Set the alarm 2 delay time within the range* of 0 to 300 (seconds).	Section 6.2.9
2009h(CH1), 2029h(CH3), 2049h(CH5), 2069h(CH7),	Low	Current measuring	Primary current of CT is set out of range.	Set primary current of CT within the range* of 0 to 6000 (A).  However, this setting cannot set 0(any setting) when primary current (Un\G2) is 0	Section 6.2.3
0000h	-	All mode	Normal	-	

<sup>\*</sup> Also check that it is set in decimal.

# 10.2 Troubleshooting

# 10.2.1 When "0" LED (RUN) is turned off

#### Table 10.2.1-1 When "0" LED is turned off

Check item	Action	Reference
Is power source is supplied?	Check that supply voltage of the power source is within the rating.	-
Is capacity of the power source module sufficient?	Calculate the consumption current of CPU module, I/O module, and intelligent function module attached to the base unit, and check that the power capacity is sufficient.	1
Is the watchdog time an error?	Reset CPU module, and check whether it is turned on.  If RUN LED is not turned on even after doing the above, the module may have a failure. Consult with a nearest sales agent or our company branch for the symptom of the failure.	-
Is the module properly attached to the base unit?	Check the module attachment status.	Section 8.4
Is the slot type set to "empty" in the I/O assignment setting of the PC parameter at GX Developer?	Set the slot type to "Intelligent".	Section 8.7.1

# 10.2.2 When "8" LED (ERR) is turned on or flashing

# (1) If it is ON

# Table 10.2.2-1 When "8" LED is turned on

Check item	Action	Reference
	Check latest error code (Un\G4500), and take a corrective	
	action as described in section 10.1. After that, reset CPU	
Did only owner occur?	module, and check whether it is turned on.	Section
Did any error occur?	If "8" LED is turned on even after doing the above, the	10.1
	module may have a failure. Consult with a nearest sales	
	agent or our company branch for the symptom of the failure.	

# (2) If it is flashing

#### Table 10.2.2-2 When "8" LED is flashing

Check item	Action	Reference
Did any error occur?	The set value may be out of range. Check that the operating condition settings and the integrated value are correct.  Correct configuration or turning Error clear request (Y1F*) ON will clear the error. When the error is cleared by Error clear request (Y1F*), the operation continues according to the previous settings.  * In the case where the initial I/O number of this module is 0	Section 5.2.2 Chapter 6 Section 8.6.3 Section 8.7.3

# 10.2.3 If electric energy cannot be measured

The following check has to be performed while current is flowing from the power source side to the load side.

Note that electric energy is not measured in the current measuring mode.

Table 10.2.3-1 If electric energy cannot be measured

Check	item			Action	Reference
		"9" LED is	"5" LED is	1) The type of current sensor may be	
CH1	"1" LED is OFF.	OFF.	OFF.	incorrect. In addition, if the rating of the sensor	
01.10		"A" LED is	"6" LED is	in use is different from the primary current,	
CH2	"2" LED is OFF.	OFF.	OFF.	measurement cannot be taken correctly.	
01.10	"0"   ED :- OFF	"B" LED is	"D" LED is	2) Wiring is not done or wrong. Refer to	
CH3	"3" LED is OFF.	OFF.	OFF.	Section 8.5 to check the wiring.	
CLIA	"4" I ED :- OFF	"C" LED is	"E" LED is	3) Voltage wiring may be incorrect. Check	
CH4	"4" LED is OFF.	OFF.	OFF.	connection of P1, P2, and P3.	
CH1	"1" LED is	"9" LED is	"5" LED is		
CITI	flashing.	OFF.	ON.	1) Current sensors on side 1 and side 3 may	
CH2	"2" LED is	"A" LED is	"6" LED is	be installed in the reverse order or current	
0112	flashing.	OFF.	ON.	sensors on side 1 and side 3 may be	
CH3	"3" LED is	"B" LED is	"D" LED is	swapped. Check the connection.	
0110	flashing.	OFF.	ON.	2) Voltage wiring may be incorrect. Check	
CH4	"4" LED is	"C" LED is	"E" LED is	connection of P1, P2, and P3.	Section 8.5
0114	flashing.	OFF.	ON.		
CH1	"1" LED is ON,	'LED is ON, "9" LED is ON.	"5" LED is	in the reverse order. Check the connection. 2) Voltage wiring may be incorrect. Check	
	flashing, or OFF.		OFF.		
CH2	"2" LED is ON,	·	"6" LED is		
	flashing, or OFF.	ON.	OFF.	connection of P1, P2, and P3.	
CH3	"3" LED is ON,	"B" LED is	"D" LED is		
	flashing, or OFF.	ON.	OFF.	-	
CH4	"4" LED is ON,	"C" LED is	"E" LED is		
	flashing, or OFF.	ON.	OFF.		
CH1	"1" LED is ON,	"9" LED is ON.	"5" LED is	1) Current sensor on side 3 may be installed	
	flashing, or OFF.		ON.	in the reverse order. Check the connection.	
CH2	"2" LED is ON,	"A" LED is	"6" LED is	2) Voltage wiring may be incorrect. Check	
	flashing, or OFF.	ON.	ON.	connection of P1, P2, and P3.	
CH3	"3" LED is ON,	"B" LED is	"D" LED is		
	flashing, or OFF.	ON.	ON.	-	
CH4	"4" LED is ON,	"C" LED is	"E" LED is		
	flashing, or OFF.	ON.	ON.	1) Magaurament in taken namedly. Ohradi fire	
CH1	"1" LED is ON.	"9" LED is	"5" LED is	Measurement is taken normally. Check for the correct buffer memory address and data	
		OFF. "A" LED is	OFF. "6" LED is	format (double word: 32-bit integer).	
CH2	"2" LED is ON.	OFF.	OFF.	Tomat (double word, 52-bit litteger).	Oh +
		"B" LED is	"D" LED is	-	Chapter
CH3	"3" LED is ON.	OFF.	OFF.		6
		"C" LED is	"E" LED is	-	
CH4	"4" LED is ON.	OFF.	OFF.		
	1	J 011.	J 011.		I

10.2.4 If the electric current and voltage that are measured using this module do not match with the ones measured with other gauge

Table 10.2.4-1 If current and voltage that are measured using this module do not match with the ones measured with other gauge

Check item	Action	Reference
Are phase wire method, primary current, and primary voltage correct?	Check the value in the buffer memory for checking the phase wire method, primary current and primary voltage. When the value in the buffer memory is changed, you need to turn the request	Section 6.1
	for operating condition setting into ON. Otherwise, it will not be applied to the measurement.	
Does the compared gauge measure the effective value correctly?	This module stores the effective value into the buffer memory. If the compared device uses the average value instead of the effective value, the resulted value may largely differ when there is current distortion in the measurement circuit.	-
Is the secondary of CT short-circuited?	Make sure that the secondary of CT is not short-circuited. If it is connected to Mitsubishi's current transformer CW-5S(L), check that the secondary switch is not short-circuited.	-
Are you using other current sensor than recommended ones?	Only the dedicated current sensors can be connected to this module. Check that other company's sensor is not being used.	-

#### 10.3 Q&A

#### 10.3.1 General

# To what degree is the module durable against overvoltage and overcurrent? Is external protective circuit required?

Momentary\*: Up to 2 times as high as rated voltage and 20 times as high as rated current.

Continuous: Up to 1.1 times as high as rated voltage and rated current.

\* Momentary means: Energizing 9 times for 0.5 seconds at 1-minute intervals, and then 1 time for 5 seconds.

External protective circuit is not required.

#### Q Can the module be used as an electric energy meter?

This module can be used to measure the electric energy and to manage the use of electric energy.

However, it cannot be used for deal and proof of electric energy measurement stipulated in the measurement law.

#### Are errors in wiring verifiable easily?

They are verifiable by the illuminating condition of the LEDs on the front of the module. Refer to Section 10.2.3 for details.

#### **Q** Is it OK to open the secondary terminals of the current sensor?

The secondary side of the models EMU2-CT5, EMU-CT50, EMU-CT100, EMU-CT250, EMU-CT5-A, EMU-CT50-A, EMU-CT100-A, EMU-CT250-A, EMU-CT400-A, and EMU-CT600-A is equipped with the protective circuit against opening of secondary terminals. Opening them during the wiring work causes no problems. However, for safety, please do not continuously energize the module with the terminals open. The secondary side of the models EMU-CT400 and EMU-CT600 is equipped with the protective circuit against opening of secondary terminals. However, during the wiring work, be sure to turn the secondary side short-circuit switch to short. After completion of work, be sure to turn the secondary short-circuit switch to open. Note that failing to turn the switch open results in an inaccurate measurement.

#### Q Is measurement of inverter circuit possible?

Measuring the secondary side of the inverter is impossible due to the large fluctuation of frequency.

Make measurement on the primary side of the inverter. However, since a current waveform on the primary side of the inverter has a distortion containing the harmonic components, a slight error occurs.

# If a load such as welding equipment exists, a current flows only for a short period (e.g. 2-cycle waveform of commercial frequency (50 Hz: 40 ms, 60 Hz: 33 ms)). Is accurate measurement possible?

This module makes measurement with a sampling period of 4340 Hz (for both 50 Hz and 60 Hz). However, measuring part of buffer memory data is updated every 500 ms. The electrical amount such as current, voltage, electric power, power factor, and frequency is measured in a cycle of 500 ms period.

The amount of electricity and reactive power amount are measured separately from the momentary data described above, using a sampling period of 4340 Hz continuously without intermittence. Therefore, measuring the load for a short period is possible.

#### Q Obtained values may be different from other measuring instruments. Why is it so?

There are various possible causes. Check the following first, please:

- [1] Check for wiring errors (polarity of current sensors, connections of current circuits, and connections of voltage circuits, in particular).
- [2] On the split-type current sensor, check for the poor engagement or separation of fitting surfaces.
- [3] On the split-type current sensor, check for pinching of foreign object between fitting surfaces.
- [4] Check that the measuring instrument used for comparison indicates a correct RMS value.
- [5] If the measuring instrument used for comparison measures an average value instead of rms value, distortion in the current of the circuit to be measured causes a significant difference of values. This module measures an rms value.
- [6] Check for the short-circuit on the secondary side of the current transformer (CT).
- [7] Current sensor connectable to the module is the dedicated current sensor only. Check that the proper current sensor is connected or not.

#### 10.3.2 Q&A about Specifications

#### Q What accuracy does "measuring accuracy" mean?

In terms of the amount of electricity, it means a range of tolerances in reading values. For example, when the reading value is "10 kWh," a tolerance is  $\pm 0.2$  kWh.

In terms of measuring elements other than the amount of electricity, it means tolerance for the rated input. For a current, when a rated current is set to 250 A,  $\pm 1\%$  of 250 A is a tolerance.

#### Q Is accuracy of a current sensor included?

Accuracy of a current sensor is not included in accuracy of the module.

A maximum value of tolerance is obtained by summing tolerance of the module and that of a current sensor.

#### Q To what degree an area of microcurrent is measured?

A current value is measured from the area exceeding 0.4 % of the rated current. In an area below 0.4 %, measurement result is indicated as "0" (zero).

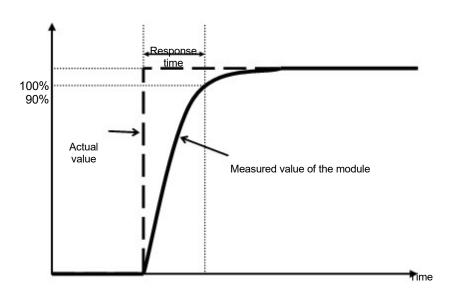
However, in that case, still, the amount of electricity is being measured. Even if the indicated value is "0," measurement value will increase in continuing measurement for a long time.

The amount of electricity is measured with a load that is about 0.4 % or more of all load power.

A

#### Q What kind of time is "response time"?

"Response time" is a period of time between a point of sudden change of voltage or current input and a point that an output (computation result) follows up to within± 10% of input.



#### 10.3.3 Q&A about Installing

#### What is wire diameter that allows installing a current sensor?

The following lists the nominal cross-sectional areas of the conductor of 600-V vinyl coated wires that can penetrate (values for reference).

IV wire (600-V vinyl insulated wire)

38 mm<sup>2</sup> (EMU-CT50-A), 60 mm<sup>2</sup> (EMU-CT50/CT100, EMU-CT100-A),

150 mm<sup>2</sup> (EMU-CT250), 200 mm<sup>2</sup> (EMU-CT250-A),

 $500 \text{ mm}^2 \times 1 \text{ wire}, 325 \text{ mm}^2 \times 2 \text{ wires (EMU-CT400/CT600)},$ 

500 mm<sup>2</sup> (EMU-CT400/CT600-A)

CV wire (600-V vinyl insulated wire)

22 mm<sup>2</sup> (EMU-CT50-A), 38 mm<sup>2</sup> (EMU-CT50/CT100), 60 mm<sup>2</sup> (EMU-CT100-A),

150 mm<sup>2</sup> (EMU-CT250 (100 mm<sup>2</sup> is recommended), EMU-CT250-A),

400 mm<sup>2</sup> (EMU-CT400/CT600-A),

500 mm<sup>2</sup> × 1 wire, 325 mm<sup>2</sup> × 2 wires (EMU-CT400/CT600)

The above shows the standard nominal cross-sectional areas. Due to the outer difference of finished vinyl insulation and deformation (bending) depending on manufacturers, a wire may not penetrate.

Make verification on site.

#### What are the points when installing a current sensor?

Models EMU2-CT5, EMU-CT\*\*\* and EMU-CT\*\*\*-A are split-type. If split surfaces are not engaged sufficiently or a foreign object exists between the split surfaces, adequate performances are not obtained. Pay attention in installation.

#### 10.3.4 Q&A about Connection

#### Q Does polarity exist in connection between a current sensor and the module?

Yes, it does.

Make connections so that secondary terminals of current sensor (k, l) and terminal symbols of module agree with each other.

If polarity is incorrect, the current value is measurable, but the electric power and the electrical energy can not be measured correctly.

#### Q Are there any key points in avoiding errors in wiring?

Check polarity of current sensor on the primary current side.

Power supply side of the circuit is indicated as "K," and the load is indicated as "L." An arrow indicates the direction from K to L.

For a 3-wire circuit, check that the current sensor and the module are connected correctly for the 1-side circuit and 3-side circuit.

Besides, check that voltage inputs are connected correctly among P1, P2, and P3.

#### Q How do wires extend between a current sensor and the module?

Model EMU-CT\*\*\*, EMU-CT\*\*\*-A are extendable up to 50 m.

Model EMU2-CT5 is extendable up to 11 m, using together with extension cable. To extend the wire further, use the current transformer CW-5S(L) for split-type instrument in combination, extending the secondary wiring on CW-5S(L) side.

#### 10.3.5 Q&A about Setting

#### Q Is the setting required?

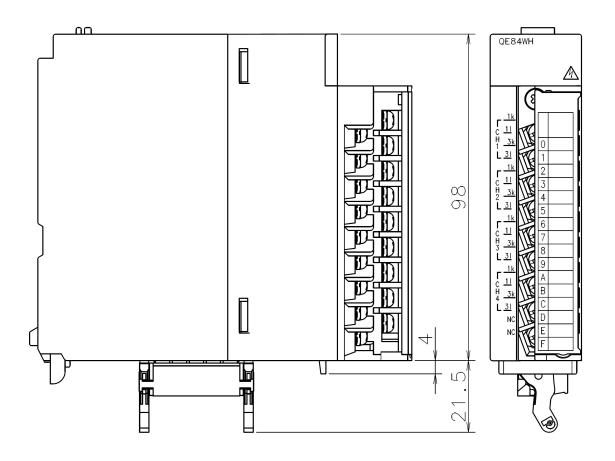
At least, settings of phase wires, primary current and primary voltage are required. Specify settings in accordance with a circuit to be connected.

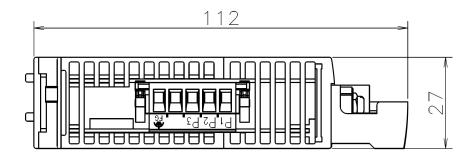
# If a primary current setting value is different from that of rated current on a connected current sensor, does it cause a breakdown?

A It does not cause breakdown or burning. However, measurement values will be totally incorrect.

# Appendix

Appendix 1: External dimensions





Unit [mm]

#### Appendix 2: Optional devices

# ■ Split type current sensor

Item			Specifications	3	
Model	EMU-CT50	EMU-CT100	EMU-CT250	EMU-CT400	EMU-CT600
Rated primary current	50 A AC	100 A AC	250 A AC	400 A AC	600 A AC
Rated secondary current	16.66 mA	33.33 mA	66.66 mA	66.66 mA	66.66 mA
Rated burden			0.1 VA		
Maximum voltage (voltage to ground ∕ line voltage)			460 V AC		
Ratio error	±1 %(5 % to 100 % of rating, RL≦10 Ω)				
Phase displacement	±30 min. (5 % to 100 % of rating, RL≦10 Ω)				
Measurement(installation)category					
Pollution degree			2		
Working temperature range	-5 °C	C to +55 °C (dai	ly mean tempe	rature: +35 °C o	or less)
Working humidity range		5 % to 9	5 %RH (no con	densation)	
CE marking conformity standard			EN61010-2-03	2	
CE marking conformity standard Maximum voltage (voltage to ground ∕ line voltage)	460 V AC				
Weight (per one)	0.1 kg 0.7 kg			kg	

<sup>\*</sup>Use an electric wire of the size of penetrating this current sensor for a primary side cable, do not use a non-insulation electric wire or a metal for a primary cable.
\*EMU-CT400 and EMU-CT600 are stopped.

Item	Specifications					
Model	EMU-CT50-A	EMU-CT100-A	EMU-CT250-A	EMU-CT400-A	EMU-CT600-A	
Rated primary current	50 A AC	100 A AC	250 A AC	400 A AC	600 A AC	
Rated secondary current	16.66 mA	33.33 mA	66.66 mA	66.66 mA	66.66 mA	
Rated burden	0.1 VA					
Maximum voltage (voltage to ground ∕ line voltage)	460 V AC					
Ratio error		±1 %(5 % to 100 % of rating, RL≦10 Ω)				
Phase displacement	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$		±40 min. (5 % to 100 % of rating, RL≦10 Ω)			
Measurement(installation)category		-		III		
Pollution degree		-		2	2	
Working temperature range	-5	°C to +55 °C (da	ily mean tempera	ture: +35 °C or le	ss)	
Working humidity range		30 % to 8	35 %RH (no cond	ensation)		
CE marking conformity standard	-			EN61010-2-032		
CE marking conformity standard Maximum voltage (voltage to ground / line voltage)	-		460 \	/ AC		
Weight (per one)	0.1 kg	0.1 kg	0.2 kg	0.3 kg	0.4 kg	

<sup>\*</sup>Use an electric wire of the size of penetrating this current sensor for a primary side cable, do not use a non-insulation electric wire or a metal for a primary cable.

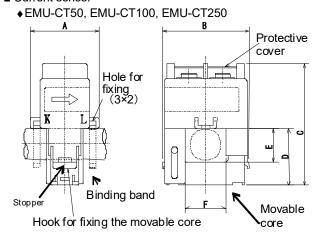
#### ■ 5A current sensor

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Item	Specifications				
Model	EMU2-CT5	EMU-CT5-A			
Rated primary current	5 A	AC			
Rated secondary current	1.66	S mA			
Rated burden	0.1	VA			
Maximum voltage (voltage to ground ∕ line voltage)	260 V AC	260 V AC			
Ratio error	±1 % (5 % to 100 % of rating, $R_L \le 10 \Omega$ )	$\pm 1$ %(5 % to 100 % of rating, R <sub>L</sub> $\leq 10$ Ω)			
Phase displacement	±30 min. (5 % to 100 % of rating, R <sub>L</sub> ≦10 Ω)	$\pm 45$ min. or less (10 % to 100 % of rating, RL=10 Ω) $\pm 60$ min. or less (5 % of rating, RL=10Ω)			
Measurement(installation)category	III	-			
Pollution degree	2	-			
Working temperature range	−5 °C to +55 °C (daily mean temperature: +35 °C or less)	-5 °C to +55 °C (daily mean temperature: +35 °C or less)			
Working humidity range	5 % to 95 %RH (no condensation)	30 % to 85 %RH (no condensation)			
CE marking conformity standard	EN61010-2-032	-			
CE marking conformity standard Maximum voltage	260 V AC	-			
Weight (per one)	0.1 kg	0.1 kg			

<sup>\*</sup>Use an electric wire of the size of penetrating this current sensor for a primary side cable, do not use a non-insulation electric wire or a metal for a primary cable.

#### Appendix 3: Optional devices

#### ■ Current sensor



Model	Α	В	С	D	E	F
EMU-CT50/CT100	31.5	39.6	55.2	25.7	15.2	18.8
EMU-CT250	36.5	44.8	66	32.5	22	24

◆EMU-CT400, EMU-CT600

Core cover

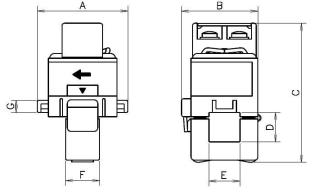
M4 screw
Split metal core surface Secondary terminal M4 screw
Secondary terminal short-circuit switch

Terminal

Unit [mm]

Unit [mm]

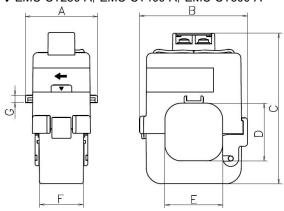
♦ EMU-CT5-A, EMU-CT50-A, EMU-CT100-A



Model	Α	В	С	D	E	F	G
EMU-CT5-A EMU-CT50-A	37.4	31.6	57.5	12.2	12.8	14	5
EMU-CT100-A	43.6	33.6	65	16.2	16.2	19	5

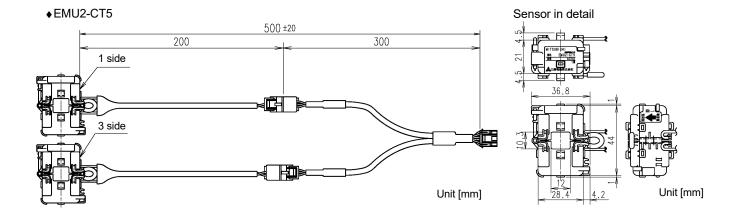
Unit [mm]

♦ EMU-CT250-A, EMU-CT400-A, EMU-CT600-A

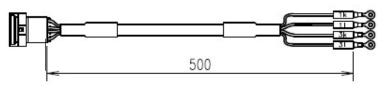


Model	Α	В	С	D	Е	F	G
EMU-CT250-A	42.6	49.4	74.5	24	24	25.2	4.5
EMU-CT400-A EMU-CT600-A	44.9	67.2	94	36	36	27	4.5

Unit [mm]



- Dedicated cable
- ♦5A current sensor cable EMU2-CB-Q5B



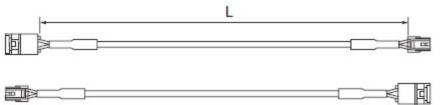
Unit[mm]

♦Extension cable(standard) EMU2-CB-T\*\*M



Model	EMU2-CB-T1M	EMU2-CB-T5M	EMU2-CB-T10M
Length	1000 mm	5000 mm	10000 mm

♦ Extension cable(separate) EMU2-CB-T\*\*MS



Model	EMU2-CB-T1MS	EMU2-CB-T5MS	EMU2-CB-T10MS
Length	1000 mm	5000 mm	10000 mm

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# **Warranty**

For using this product, please thoroughly read the following product warranty descriptions.

#### 1. Gratis Warranty Period and Gratis Warranty Coverage

If any failure or defect (hereinafter collectively called "failures") for which our company is held responsible occurs on the product during the gratis warranty period, our company shall replace the product for free through the distributor at which you purchased the product or our service company.

However, if an international travel is required for replacement, or a travel to an isolated island or remote location equivalent is required for replacement, the actual cost incurred to send an engineer(s) shall be charged. [Gratis Warranty Period]

The gratis warranty term of the product shall be for one year after the date of purchase or delivery to a designated place

Note that after manufacture and shipment from Mitsubishi, the maximum distribution period shall be six (6) months, and the longest gratis warranty term after manufacturing shall be eighteen (18) months. The gratis warranty term of repair parts shall not exceed the gratis warranty term before repairs.

#### [Gratis Warranty Coverage]

- (1) The gratis warranty shall apply only if the product is being used properly in the conditions, with the methods and under the environments in accordance with the terms and precautions described in the instruction manual, user's manual, caution label on the product, etc.
- (2) Replacement shall be charged for the following cases even during the gratis warranty period.
  - 1) Failures occurring due to your improper storage or handling, carelessness or fault, and failures arising from the design contents of hardware or software you use.
  - 2) Failures arising from modification you performed on the product without prior consent of our company.
  - 3) Failures occurring in the event that the product is assembled into the device you use and that are acknowledged as avoidable if the device is equipped with a safety mechanism that comply with the legal regulations applicable to the device or with functions/architecture which are considered as necessary to be equipped under conventions of the industry.
  - 4) Failures due to accidental force such as a fire, abnormal voltage, etc. and force majeure such as an earthquake, thunderstorm, wind, flood, etc.
  - 5) Failures due to matters unpredictable based on the level of science technology at the time of product
  - 6) Other failures which are beyond responsibility of our company or which you admit that our company is not held responsible for.

#### 2. Fare-Paying Repair Period after Production Discontinued

- (1) The period our company may accept product replacement with charge shall be seven (7) years after production of the product is discontinued.
  - Production stoppage shall be announced in the technical news, etc. of our company.
- (2) The product (including spare) cannot be supplied after production is discontinued.

#### 3. Exemption of Compensation Liability for Opportunity Loss, Secondary Loss, etc.

Our company shall not be liable to compensate for any loss arising from events not attributable to our company, opportunity loss and lost earning of the customer due to failure of the product, and loss, secondary loss, accident compensation, damage to other products besides our products and other operations caused by a special reason regardless of our company's predictability in both within and beyond the gratis warranty period.

#### 4. Change of Product Specifications

Please be advised in advance that the specifications described in catalogs, manuals or technical materials are subject to change without notice.

#### 5. Application of Products

- (1) For use of our general-purpose sequencer MELSEC-Q series and Energy Measuring Unit QE84WH, they shall be used for a purpose which shall not lead to a material accident even when a failure or malfunction of the sequencer occurs, and a backup or fail-safe function shall be implemented systematically at external of the device in the event of a failure or malfunction.
- (2) Our general-purpose sequencers are designed and manufactured as general-purpose products which are targeted for general industry applications. Therefore, use of the sequencer for purposes in nuclear power plants and other power plants of each electric power company which greatly affect public, or for purposes in each JR company and the Defense Agency requiring a special quality assurance system shall be excluded from its applications.

However, the sequencer may be used for such purposes if the customer acknowledges that it should be used for limited purpose only and agrees not to require special quality.

Also, if you are considering to use this device for purposes that are expected to greatly affect human life or property and require high reliability especially in safety or control system such as aviation, medical care, railroad, combustion/fuel device, manned carrier device, entertainment machine, safety equipment, please consult with our service representative to exchange necessary specifications.

# **Energy Measuring Module**

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